SysAcq_Pertuet_Schini

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3.2 Stm32g4xx_system

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- #define HSE_VALUE 24000000U
- #define HSI_VALUE 16000000U

3.3.1 Detailed Description

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3.3.2.1 HSE_VALUE

```
#define HSE_VALUE 24000000U
```

Value of the External oscillator in Hz

3.3.2.2 HSI_VALUE

```
#define HSI_VALUE 16000000U
```

Value of the Internal oscillator in Hz

3.4 STM32G4xx_System_Private_TypesDefinitions

3.5 STM32G4xx_System_Private_Defines

3.6 STM32G4xx_System_Private_Macros

3.7 STM32G4xx_System_Private_Variables

Variables

- uint32_t **SystemCoreClock** = HSI_VALUE
- const uint8_t **AHBPrescTable** [16] = {0U, 0U, 0U, 0U, 0U, 0U, 0U, 0U, 1U, 2U, 3U, 4U, 6U, 7U, 8U, 9U}
- const uint8_t **APBPrescTable** [8] = {0U, 0U, 0U, 0U, 1U, 2U, 3U, 4U}

3.7.1 Detailed Description

3.8 STM32G4xx_System_Private_FunctionPrototypes

3.9 STM32G4xx_System_Private_Functions

Functions

- void SystemInit (void)

  Setup the microcontroller system.
- void SystemCoreClockUpdate (void)

  Update SystemCoreClock variable according to Clock Register Values. The SystemCoreClock variable contains the core clock (HCLK), it can be used by the user application to setup the SysTick timer or configure other parameters.

3.9.1 Detailed Description

3.9.2 Function Documentation

3.9.2.1 SystemCoreClockUpdate()

```
void SystemCoreClockUpdate (
             void   )
```

Update SystemCoreClock variable according to Clock Register Values. The SystemCoreClock variable contains the core clock (HCLK), it can be used by the user application to setup the SysTick timer or configure other parameters.

Note

Each time the core clock (HCLK) changes, this function must be called to update SystemCoreClock variable value. Otherwise, any configuration based on this variable will be incorrect.

- The system frequency computed by this function is not the real frequency in the chip. It is calculated based on the predefined constant and the selected clock source:

- If SYSCLK source is HSI, SystemCoreClock will contain the HSI_VALUE(∗∗)
- If SYSCLK source is HSE, SystemCoreClock will contain the HSE_VALUE(∗∗∗)
- If SYSCLK source is PLL, SystemCoreClock will contain the HSE_VALUE(∗∗∗) or HSI_VALUE(∗) multiplied/divided by the PLL factors.

(∗∗) HSI_VALUE is a constant defined in stm32g4xx_hal.h file (default value 16 MHz) but the real value may vary depending on the variations in voltage and temperature.

(∗∗∗) HSE_VALUE is a constant defined in stm32g4xx_hal.h file (default value 24 MHz), user has to ensure that HSE_VALUE is same as the real frequency of the crystal used. Otherwise, this function may have wrong result.

- The result of this function could be not correct when using fractional value for HSE crystal.

Parameters

None	

Return values

None	

3.9.2.2 SystemInit()

```
void SystemInit (
            void )
```

Setup the microcontroller system.

Parameters

None	

Return values

None	

Chapter 4

File Documentation

4.1 main.c File Reference

: Main program body

```
#include "main.h"
#include "corrPI.h"
#include "commandeMCC.h"
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
```

Macros

- #define **UART_TX_BUFFER_SIZE** 64
- #define **UART_RX_BUFFER_SIZE** 1
- #define **CMD_BUFFER_SIZE** 64
- #define **MAX_ARGS** 9
- #define **ASCII_LF** 0x0A
- #define **ASCII_CR** 0x0D
- #define **ASCII_DEL** 0x7F
- #define **ARR_VAL** 1024
- #define **ALPHA** 600 /** Rapport cyclique permettant de gérer les PWM entre 0 et 1023 */
- #define **KP_ALPHA** 0.10
- #define **KI_ALPHA** 0.8
- #define **ALPHA_OUT_MAX_VALUE** 0.99
- #define **ALPHA_OUT_MIN_VALUE** 0.01
- #define **TIM1_PERIOD** 0.0000625
- #define **KP_CURRENT** 0.1
- #define **KI_CURRENT** 2.0
- #define **CURRENT_OUT_MAX_VALUE** 2.0
- #define **TIM3_PERIOD** 0.1
- #define **TIM4_PERIOD** 0.0064
- #define **TICK2SPEED_TIM3** 0.0146
- #define **TICK2SPEED_TIM4** (60.0/4096.0)/TIM4_PERIOD

Functions

- void SystemClock_Config (void)

  System Clock Configuration.
- void **newcom** (void)
- void delete (void)
- void new_carac (void)
- void **get** (void)
- void **set** (void)
- void help (void)

  Présente les fonctions et leur utilités dans la console.
- void start (void)

  Initialise le hacheur et lance les PWM avec alpha = 50%.
- void stop (void)

  Arrête les moteurs.
- void speed (void)

  Règle le rapport cyclique des PWM, avec une valeur entre 0 et 100%.
- void **changeSpeed** (int a)
- void HAL_ADC_ConvCpltCallback (ADC_HandleTypeDef ∗hadc)

  Permet de réinitialiser le flag adcDmaFlag après l'éxecution automatique de l'interruption dans le shell.
- int main (void)

  Lance le Shell et initialise les périphériques.
- void **HAL_UART_RxCpltCallback** (UART_HandleTypeDef ∗huart)
- void Error_Handler (void)

  This function is executed in case of error occurrence.

Variables

- ADC_HandleTypeDef **hadc1**
- DMA_HandleTypeDef **hdma_adc1**
- TIM_HandleTypeDef **htim1**
- TIM_HandleTypeDef **htim2**
- TIM_HandleTypeDef **htim3**
- UART_HandleTypeDef **huart2**
- uint8_t **adcDmaFlag** = 0
- uint32_t **adcRawValue** [1]
- uint8_t **prompt** [ ] ="user@Nucleo-STM32G474>>"
- uint8_t started [ ]
- uint8_t **newline** [ ] ="\r\n"
- uint8_t **cmdNotFound** [ ] ="Command not found\r\n"
- uint32_t **uartRxReceived**
- uint8_t **uartRxBuffer** [UART_RX_BUFFER_SIZE]
- uint8_t **uartTxBuffer** [UART_TX_BUFFER_SIZE]
- uint8_t **powerOn** [ ] ="Allumage du moteur\r\n"
- uint8_t **powerOff** [ ] ="Extinction du moteur\r\n"
- int **a**
- int **adcValue**
- long vitesse
- int **PIFlag**
- int **PIUpdateFlag**
- float **i_n** [2]
- float **w_n** [2]

- float **i_consigne**
- float **v_consigne**
- uint16_t **AD_RES** = 0
- char **cmdBuffer** [CMD_BUFFER_SIZE]
- int **idx_cmd**
- char ∗ **argv** [MAX_ARGS]
- int **argc** = 0
- char ∗ **token**
- int **newCmdReady** = 0

4.1.1 Detailed Description

: Main program body

Attention

4.1.2 Function Documentation

4.1.2.1 delete()

```
void delete (
             void  )
```

Supprime le dernier caractère après avoir appuyé sur BackSpace

4.1.2.2 Error_Handler()

```
void Error_Handler (
             void  )
```

This function is executed in case of error occurrence.

Return values

None	

4.1.2.3 HAL_ADC_ConvCpltCallback()

```
void HAL_ADC_ConvCpltCallback (
            ADC_HandleTypeDef * hadc )
```

Permet de réinitialiser le flag adcDmaFlag après l'éxecution automatique de l'interruption dans le shell.

Parameters

hadc	

4.1.2.4 help()

```
void help (
            void )
```

Présente les fonctions et leur utilités dans la console.

4.1.2.5 main()

```
int main (
            void )
```

Lance le Shell et initialise les périphériques.

4.1.2.6 new_carac()

```
void new_carac (
            void )
```

Ecrit le caractère tapé dans la console

4.1.2.7 speed()

```
void speed (
            void )
```

Règle le rapport cyclique des PWM, avec une valeur entre 0 et 100%.

4.1.2.8 start()

```
void start (
            void )
```

Initialise le hacheur et lance les PWM avec alpha = 50%.

4.1.2.9 stop()

```
void stop (
            void )
```

Arrête les moteurs.

4.1.2.10 SystemClock_Config()

```
void SystemClock_Config (
            void )
```

System Clock Configuration.

Return values

None	

Configure the main internal regulator output voltage

Initializes the RCC Oscillators according to the specified parameters in the RCC_OscInitTypeDef structure.

Initializes the CPU, AHB and APB buses clocks

4.1.3 Variable Documentation

4.1.3.1 started

```
uint8_t started[]
```

Initial value:

```
=
       "\r\n*-----------------------------*"
       "\r\n| Welcome on Nucleo-STM32G474 |"
       "\r\n*-----------------------------*"
       "\r\n"
```

4.1.3.2 vitesse

```
long vitesse
```

Valeure de courant relevée après convertion en ampères

4.2 stm32g4xx_hal_msp.c File Reference

This file provides code for the MSP Initialization and de-Initialization codes.

```
#include "main.h"
```

Functions

- void HAL_TIM_MspPostInit (TIM_HandleTypeDef ∗htim)
- void HAL_MspInit (void)
- void HAL_ADC_MspInit (ADC_HandleTypeDef ∗hadc)

  ADC MSP Initialization This function configures the hardware resources used in this example.
- void HAL_ADC_MspDeInit (ADC_HandleTypeDef ∗hadc)

  ADC MSP De-Initialization This function freeze the hardware resources used in this example.
- void HAL_TIM_Base_MspInit (TIM_HandleTypeDef ∗htim_base)

  TIM_Base MSP Initialization This function configures the hardware resources used in this example.
- void HAL_TIM_Encoder_MspInit (TIM_HandleTypeDef ∗htim_encoder)

  TIM_Encoder MSP Initialization This function configures the hardware resources used in this example.
- void HAL_TIM_Base_MspDeInit (TIM_HandleTypeDef ∗htim_base)

  TIM_Base MSP De-Initialization This function freeze the hardware resources used in this example.
- void HAL_TIM_Encoder_MspDeInit (TIM_HandleTypeDef ∗htim_encoder)

  TIM_Encoder MSP De-Initialization This function freeze the hardware resources used in this example.
- void HAL_UART_MspInit (UART_HandleTypeDef ∗huart)

  UART MSP Initialization This function configures the hardware resources used in this example.
- void HAL_UART_MspDeInit (UART_HandleTypeDef ∗huart)

  UART MSP De-Initialization This function freeze the hardware resources used in this example.

Variables

- DMA_HandleTypeDef **hdma_adc1**

4.2.1 Detailed Description

This file provides code for the MSP Initialization and de-Initialization codes.

Attention

4.2.2 Function Documentation

4.2.2.1 HAL_ADC_MspDeInit()

```
void HAL_ADC_MspDeInit (
            ADC_HandleTypeDef * hadc )
```

ADC MSP De-Initialization This function freeze the hardware resources used in this example.

Parameters

hadc	ADC handle pointer

Return values

None	

ADC1 GPIO Configuration PA0 ----—> ADC1_IN1

4.2.2.2 HAL_ADC_MspInit()

```
void HAL_ADC_MspInit (
            ADC_HandleTypeDef * hadc )
```

ADC MSP Initialization This function configures the hardware resources used in this example.

Parameters

hadc	ADC handle pointer

Return values

None	

Initializes the peripherals clocks

ADC1 GPIO Configuration PA0 ----—> ADC1_IN1

4.2.2.3 HAL_MspInit()

```
void HAL_MspInit (
            void )
```

Initializes the Global MSP. Disable the internal Pull-Up in Dead Battery pins of UCPD peripheral

4.2.2.4 HAL_TIM_Base_MspDeInit()

```
void HAL_TIM_Base_MspDeInit (
            TIM_HandleTypeDef * htim_base )
```

TIM_Base MSP De-Initialization This function freeze the hardware resources used in this example.

Parameters

htim_base	TIM_Base handle pointer

Return values

None	

4.2.2.5 HAL_TIM_Base_MspInit()

```
void HAL_TIM_Base_MspInit (
            TIM_HandleTypeDef * htim_base )
```

TIM_Base MSP Initialization This function configures the hardware resources used in this example.

Parameters

htim_base	TIM_Base handle pointer

Return values

None	

4.2.2.6 HAL_TIM_Encoder_MspDeInit()

```
void HAL_TIM_Encoder_MspDeInit (
            TIM_HandleTypeDef * htim_encoder )
```

TIM_Encoder MSP De-Initialization This function freeze the hardware resources used in this example.

Parameters

htim_encoder	TIM_Encoder handle pointer

Return values

None	

TIM2 GPIO Configuration PA1 ---—> TIM2_CH2 PA15 ---—> TIM2_CH1

4.2.2.7 HAL_TIM_Encoder_MspInit()

```
void HAL_TIM_Encoder_MspInit (
            TIM_HandleTypeDef * htim_encoder )
```

TIM_Encoder MSP Initialization This function configures the hardware resources used in this example.

Parameters

htim_encoder	TIM_Encoder handle pointer

Return values

None	

TIM2 GPIO Configuration PA1 ---—> TIM2_CH2 PA15 ---—> TIM2_CH1

4.2.2.8 HAL_TIM_MspPostInit()

```
void HAL_TIM_MspPostInit (
            TIM_HandleTypeDef * htim )
```

TIM1 GPIO Configuration PA8 ---—> TIM1_CH1 PA9 ---—> TIM1_CH2 PA11 ---—> TIM1_CH1N PA12 ---—> TIM1_CH2N

4.2.2.9 HAL_UART_MspDeInit()

```
void HAL_UART_MspDeInit (
            UART_HandleTypeDef * huart )
```

UART MSP De-Initialization This function freeze the hardware resources used in this example.

Parameters

huart	UART handle pointer

Return values

None	

USART2 GPIO Configuration PA2 ---—> USART2_TX PA3 ---—> USART2_RX

4.2.2.10 HAL_UART_MspInit()

```
void HAL_UART_MspInit (
            UART_HandleTypeDef * huart )
```

UART MSP Initialization This function configures the hardware resources used in this example.

Parameters

huart	UART handle pointer

Return values

None	

Initializes the peripherals clocks

USART2 GPIO Configuration PA2 ------> USART2_TX PA3 ------> USART2_RX

4.3 stm32g4xx_it.c File Reference

Interrupt Service Routines.

```
#include "main.h"
#include "stm32g4xx_it.h"
```

Functions

- void **NMI_Handler** (void)

  This function handles Non maskable interrupt.
- void **HardFault_Handler** (void)

  This function handles Hard fault interrupt.
- void **MemManage_Handler** (void)

  This function handles Memory management fault.
- void **BusFault_Handler** (void)

  This function handles Prefetch fault, memory access fault.
- void **UsageFault_Handler** (void)

  This function handles Undefined instruction or illegal state.
- void **SVC_Handler** (void)

  This function handles System service call via SWI instruction.
- void **DebugMon_Handler** (void)

  This function handles Debug monitor.
- void **PendSV_Handler** (void)

  This function handles Pendable request for system service.
- void **SysTick_Handler** (void)

  This function handles System tick timer.
- void **DMA1_Channel1_IRQHandler** (void)

  This function handles DMA1 channel1 global interrupt.
- void **TIM2_IRQHandler** (void)

  This function handles TIM2 global interrupt.
- void **TIM3_IRQHandler** (void)

  This function handles TIM3 global interrupt.
- void **USART2_IRQHandler** (void)

  This function handles USART2 global interrupt / USART2 wake-up interrupt through EXTI line 26.
- void **EXTI15_10_IRQHandler** (void)

  This function handles EXTI line[15:10] interrupts.

Variables

- int **PIFlag**
- uint32_t vitesse
- int **speedFlag**
- DMA_HandleTypeDef **hdma_adc1**
- TIM_HandleTypeDef **htim2**
- TIM_HandleTypeDef **htim3**
- UART_HandleTypeDef **huart2**

4.3.1 Detailed Description

Interrupt Service Routines.

Attention

4.3.2 Variable Documentation

4.3.2.1 vitesse

```
uint32_t vitesse  [extern]
```

Valeure de courant relevée après convertion en ampères

4.4 syscalls.c File Reference

STM32CubeIDE Minimal System calls file.

```
#include <sys/stat.h>
#include <stdlib.h>
#include <errno.h>
#include <stdio.h>
#include <signal.h>
#include <time.h>
#include <sys/time.h>
#include <sys/times.h>
```

Functions

- int **__io_putchar** (int ch) __attribute__((weak))
- int **__io_getchar** (void)
- void **initialise_monitor_handles** ()
- int **_getpid** (void)
- int **_kill** (int pid, int sig)
- void **_exit** (int status)
- **__attribute__** ((weak))
- int **_close** (int file)
- int **_fstat** (int file, struct stat ∗st)
- int **_isatty** (int file)
- int **_lseek** (int file, int ptr, int dir)
- int **_open** (char ∗path, int flags,...)
- int **_wait** (int ∗status)
- int **_unlink** (char ∗name)
- int **_times** (struct tms ∗buf)
- int **_stat** (char ∗file, struct stat ∗st)
- int **_link** (char ∗old, char ∗new)
- int **_fork** (void)
- int **_execve** (char ∗name, char ∗∗argv, char ∗∗env)

Variables

- char ∗∗ **environ** = __env

4.4.1 Detailed Description

STM32CubeIDE Minimal System calls file.

Author

Auto-generated by STM32CubeIDE

```
For more information about which c-functions
need which of these lowlevel functions
please consult the Newlib libc-manual
```

Attention

4.5 sysmem.c File Reference

STM32CubeIDE System Memory calls file.

```
#include <errno.h>
#include <stdint.h>
```

Functions

- void ∗ _sbrk (ptrdiff_t incr)

    _sbrk() allocates memory to the newlib heap and is used by malloc and others from the C library

4.5.1 Detailed Description

STM32CubeIDE System Memory calls file.

Author

Generated by STM32CubeIDE

```
For more information about which C functions
need which of these lowlevel functions
please consult the newlib libc manual
```

Attention

4.5.2 Function Documentation

4.5.2.1 _sbrk()

```
void * _sbrk (
             ptrdiff_t incr )
```

_sbrk() allocates memory to the newlib heap and is used by malloc and others from the C library

```
* ############################################################################
* #  .data  #  .bss  #       newlib heap       #          MSP stack          #
* #         #        #                         # Reserved by _Min_Stack_Size #
* ############################################################################
* ^-- RAM start      ^-- _end                             _estack, RAM end --^
*
```

This implementation starts allocating at the '_end' linker symbol The '_Min_Stack_Size' linker symbol reserves a memory for the MSP stack The implementation considers '_estack' linker symbol to be RAM end NOTE: If the MSP stack, at any point during execution, grows larger than the reserved size, please increase the '_Min_Stack_Size'.

Parameters

incr	Memory size

Returns

Pointer to allocated memory

4.6 system_stm32g4xx.c File Reference

CMSIS Cortex-M4 Device Peripheral Access Layer System Source File.

```
#include "stm32g4xx.h"
```

Macros

- #define HSE_VALUE 24000000U
- #define HSI_VALUE 16000000U

Functions

- void SystemInit (void)

  Setup the microcontroller system.
- void SystemCoreClockUpdate (void)

  Update SystemCoreClock variable according to Clock Register Values. The SystemCoreClock variable contains the core clock (HCLK), it can be used by the user application to setup the SysTick timer or configure other parameters.

Variables

- uint32_t **SystemCoreClock** = HSI_VALUE
- const uint8_t **AHBPrescTable** [16] = {0U, 0U, 0U, 0U, 0U, 0U, 0U, 0U, 1U, 2U, 3U, 4U, 6U, 7U, 8U, 9U}
- const uint8_t **APBPrescTable** [8] = {0U, 0U, 0U, 0U, 1U, 2U, 3U, 4U}

4.6.1 Detailed Description

CMSIS Cortex-M4 Device Peripheral Access Layer System Source File.

Author

MCD Application Team

This file provides two functions and one global variable to be called from user application:

- SystemInit(): This function is called at startup just after reset and before branch to main program. This call is made inside the "startup_stm32g4xx.s" file.
- SystemCoreClock variable: Contains the core clock (HCLK), it can be used by the user application to setup the SysTick timer or configure other parameters.
- SystemCoreClockUpdate(): Updates the variable SystemCoreClock and must be called whenever the core clock is changed during program execution.

After each device reset the HSI (16 MHz) is used as system clock source. Then SystemInit() function is called, in "startup_stm32g4xx.s" file, to configure the system clock before to branch to main program.

4.6.2 This file configures the system clock as follows:

4.6.2.1 System Clock source | HSI

4.6.2.2 SYSCLK(Hz) | 16000000

4.6.2.3 HCLK(Hz) | 16000000

4.6.2.4 AHB Prescaler | 1

4.6.2.5 APB1 Prescaler | 1

4.6.2.6 APB2 Prescaler | 1

4.6.2.7 PLL_M | 1

4.6.2.8 PLL_N | 16

4.6.2.9 PLL_P | 7

4.6.2.10 PLL_Q | 2

4.6.2.11 PLL_R | 2

4.6.2.12 Require 48MHz for RNG | Disabled

===

Attention

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