

Universität Stuttgart
Master of Science

Distributed Systems Models

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Distributed System Definition

from Coulouris et al.

A system model is necessary to precisely and uniquely specify the relationship between different components of a distributed system and its behaviour as a whole. Different aspects of a distributed system need modeling:

- *Computation state* (e.g, consistency)
- *Architecture* (e.g., client-server)
- *Interaction* (e.g., asynchronous messages)
- *Failure* (e.g., types of channel exceptions)
- *Security* (e.g., types of attacks to a host)

Modelling the state of the computation

- State machine to model a system who's output depends on the current state and input (e.g., incoming messages)
- Finite State Machine (FSM):
 - S is a finite non-empty set of states;
 - $s_0 \in S$ is the initial state;
 - I is a set of input messages
 - O is a set of output messages
 - $\delta : S \times I \rightarrow S \times O$ is the state transition function

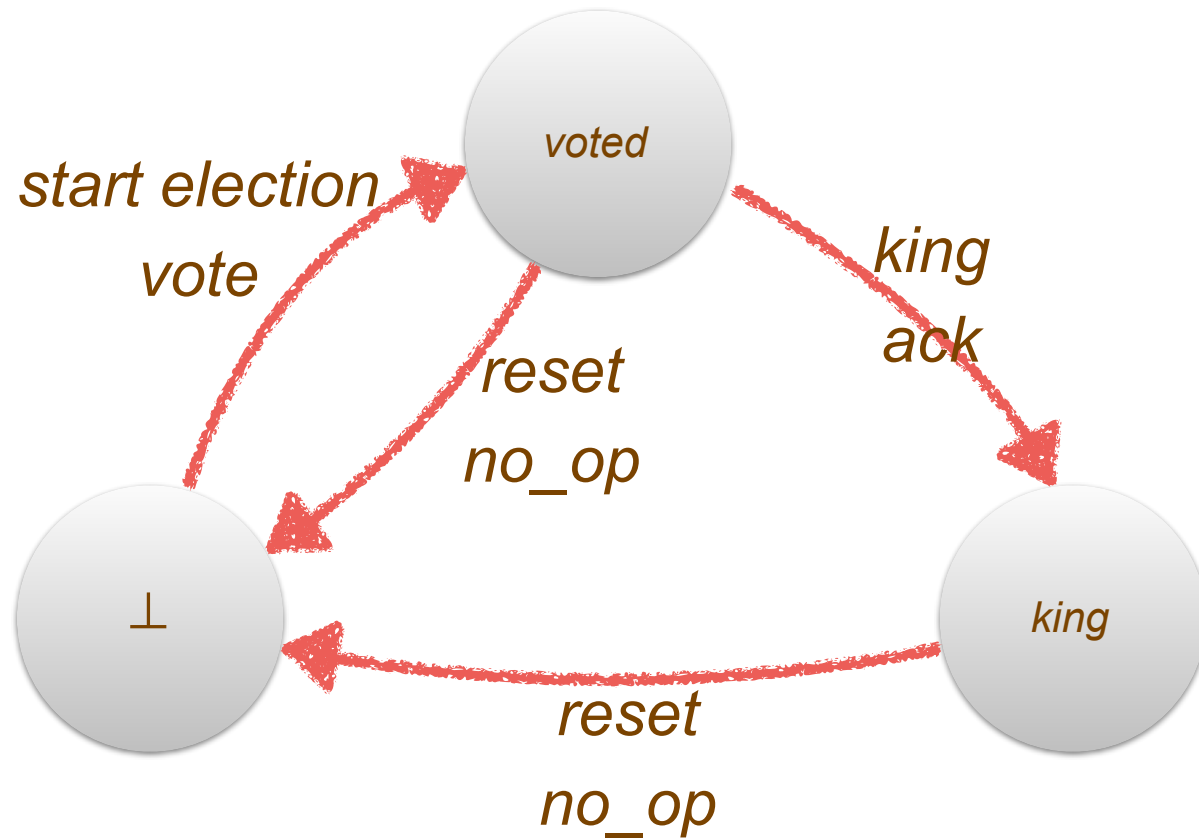
Finite State Machine

Example

- $S = \{\perp, \text{voted}, \text{king}\}$
- $s_0 = \perp$
- $I = \{\text{start election}, \text{king}, \text{reset}\}$
- $O = \{\text{vote}, \text{ack}, \text{no_op}\}$
- Next state function:
 - $(\perp, \text{start election}) \rightarrow (\text{voted}, \text{vote})$
 - $(\text{voted}, \text{king}) \rightarrow (\text{voted}, \text{ack})$
 - $(\text{voted}, \text{reset}) \rightarrow (\perp, \text{no_op})$
 - $(\text{king}, \text{reset}) \rightarrow (\perp, \text{no_op})$

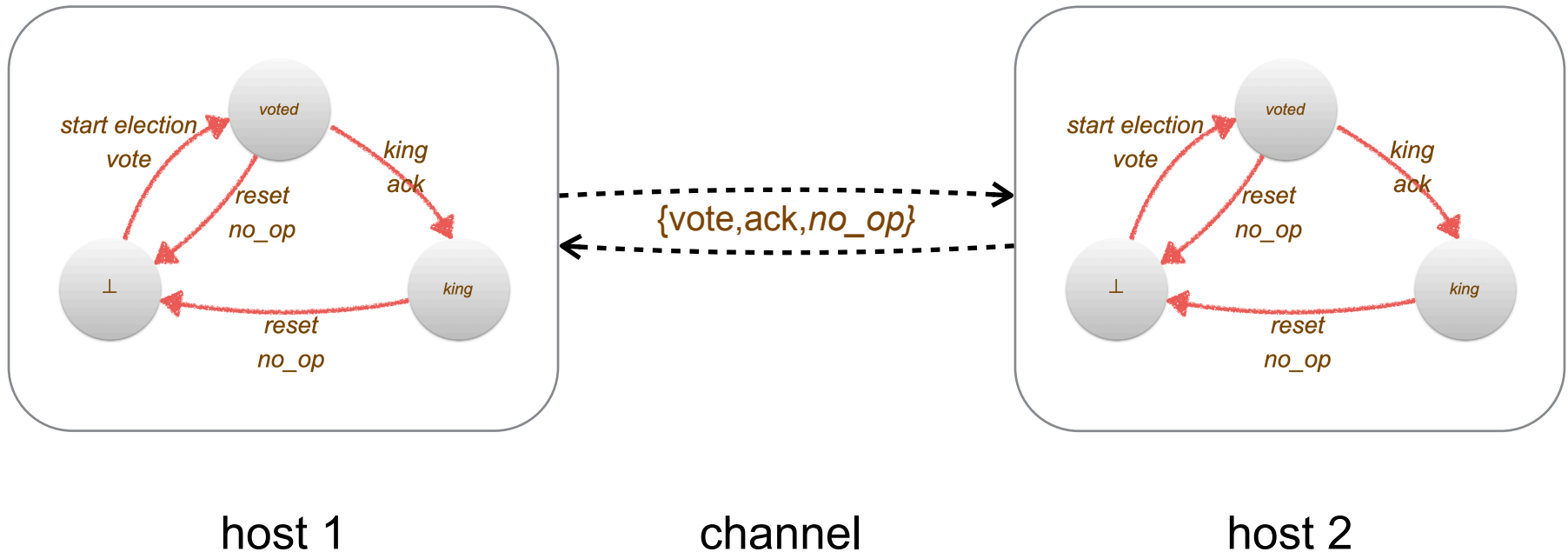
Finite State Machine

Example schema



State of a Distributed System

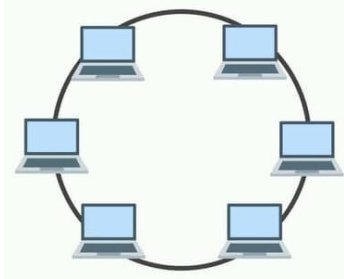
- A distributed system is modelled by the set of states of its components and of its channels



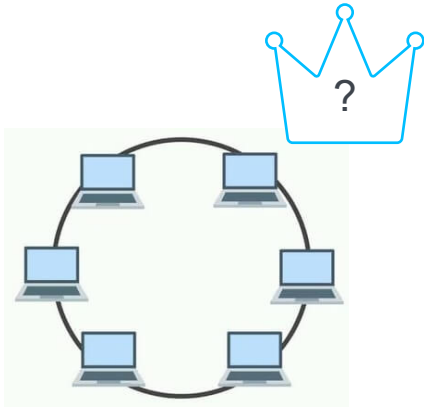
Some important (negative) results

- No leader election in anonymous rings
- No consensus in asynchronous systems
- Byzantine fault tolerance with at most $\lceil \frac{1}{3}n - 1 \rceil$
- CAP theorem (Consistency, Availability, Partitioning Tolerance)

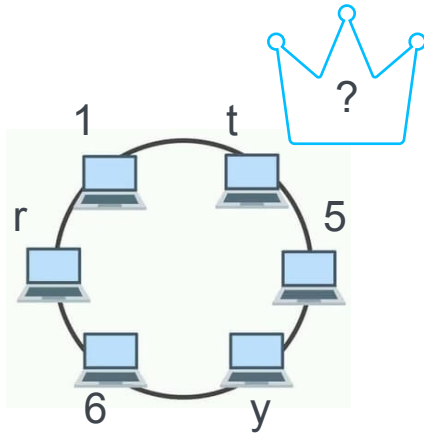
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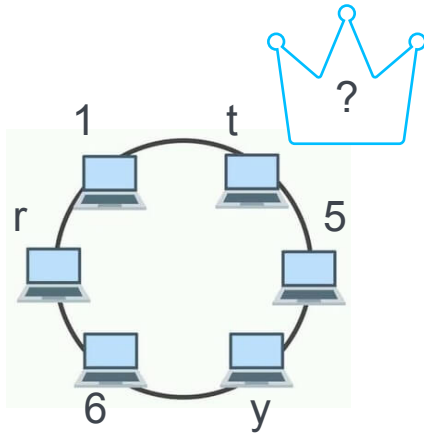
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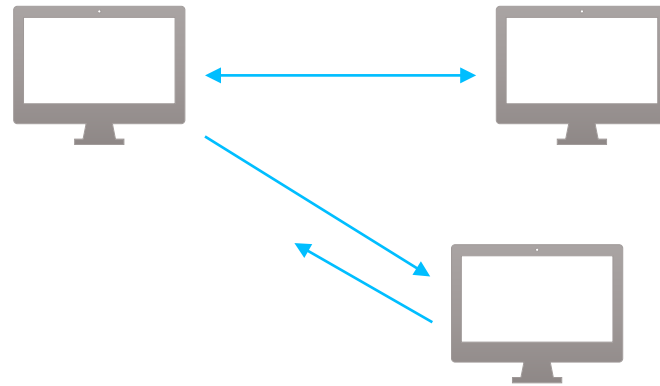
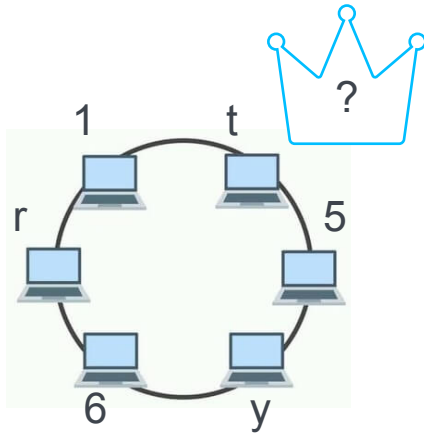
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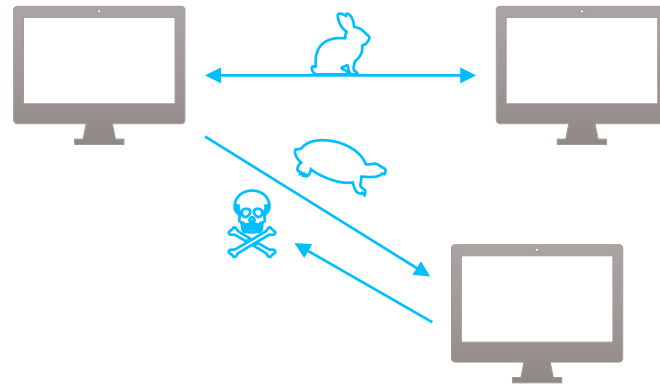
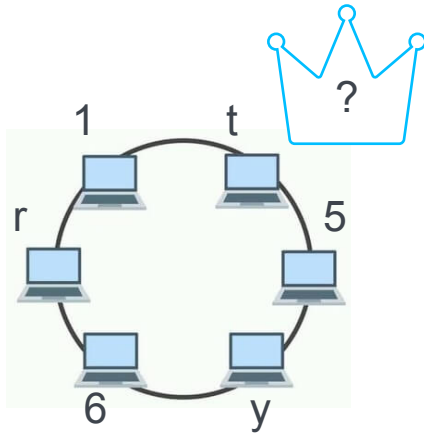
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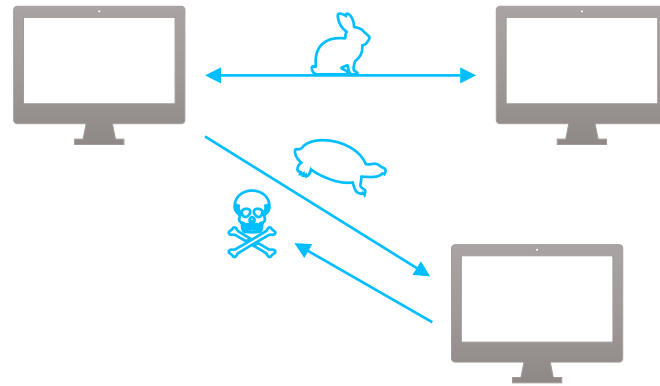
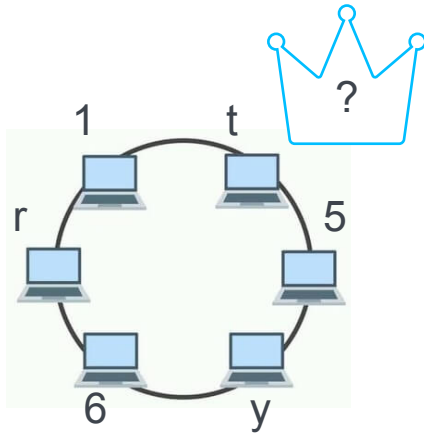
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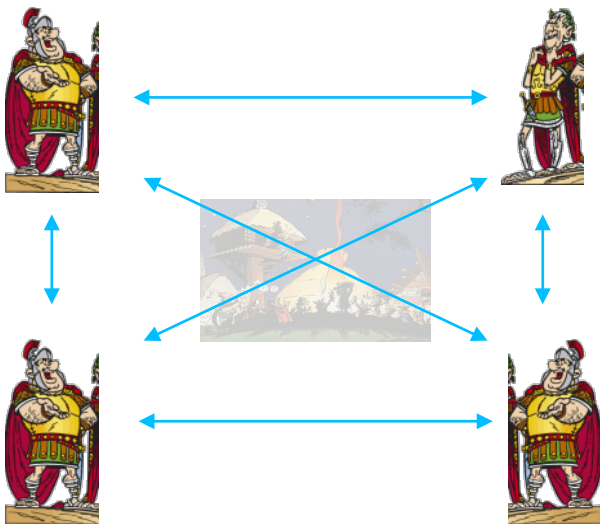
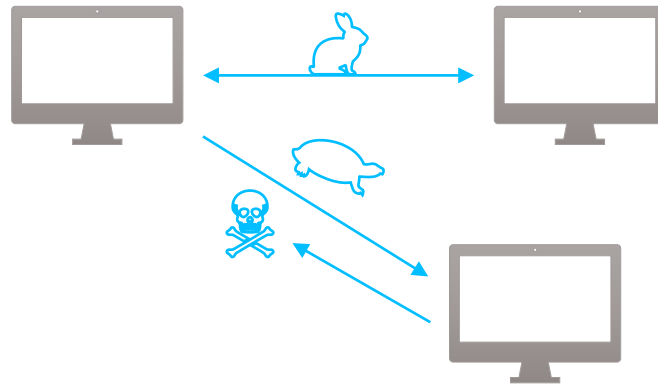
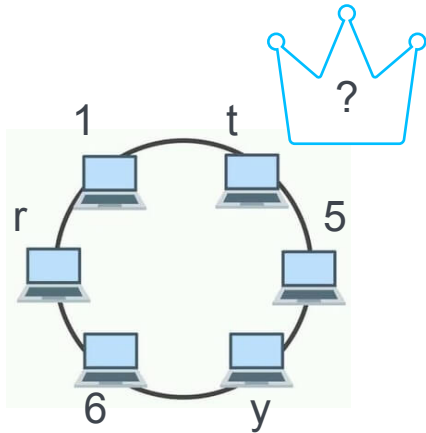
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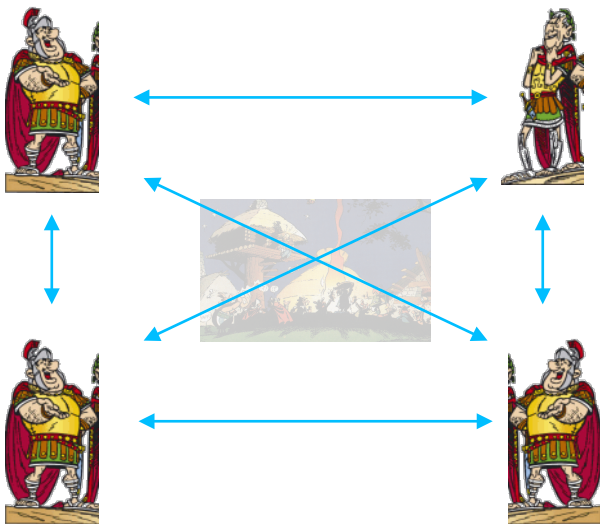
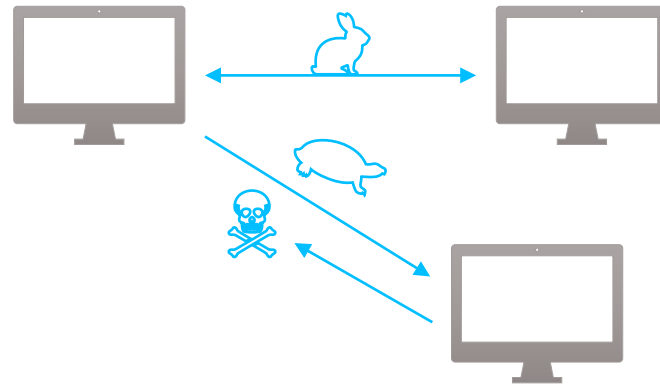
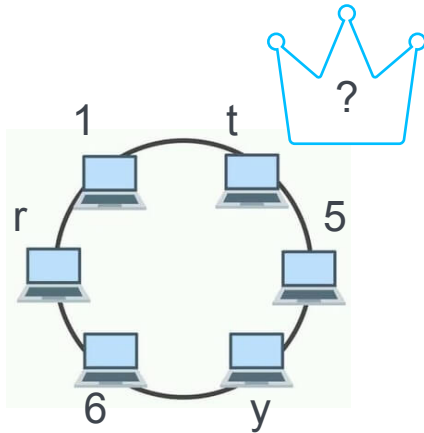
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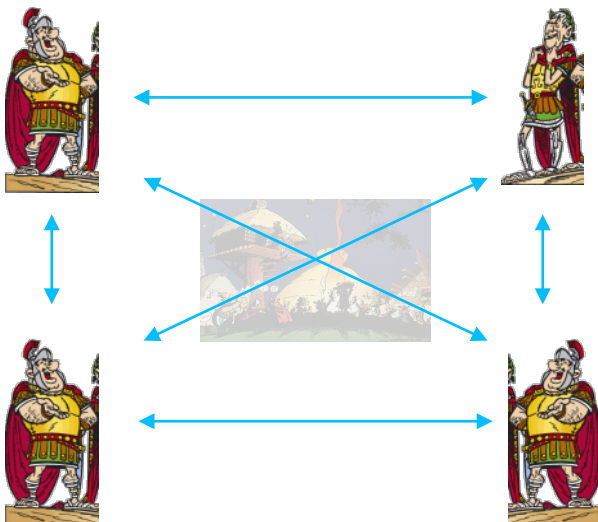
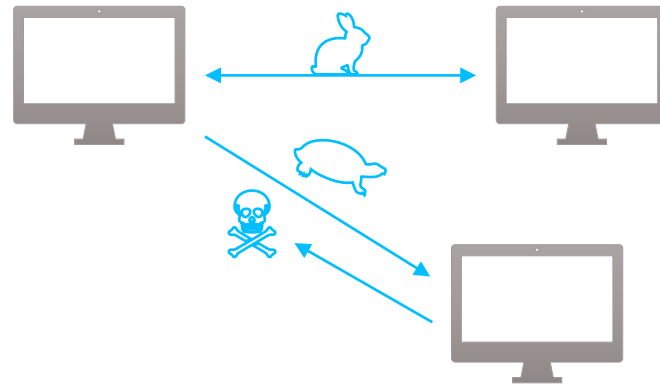
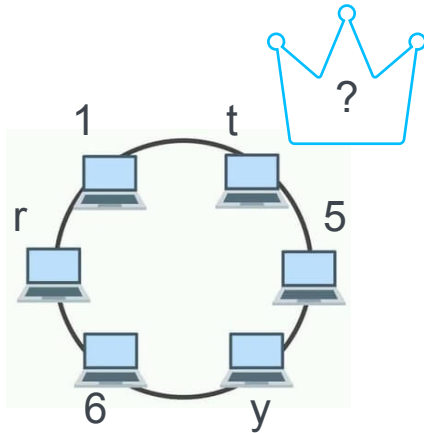
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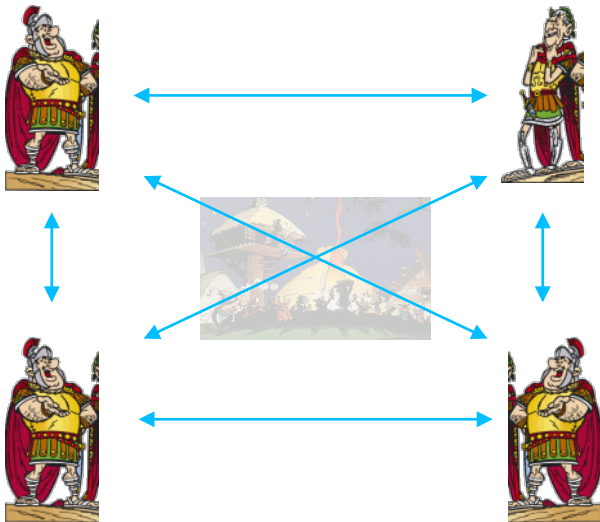
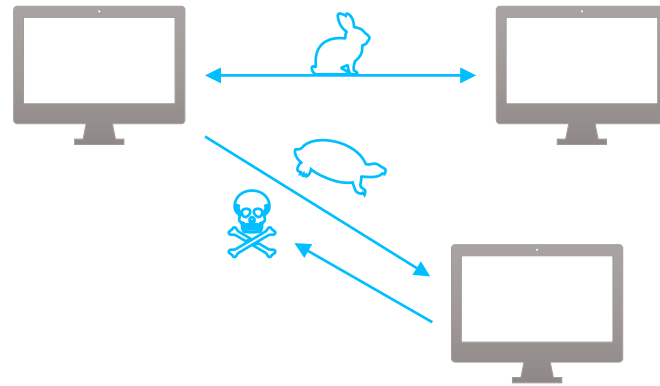
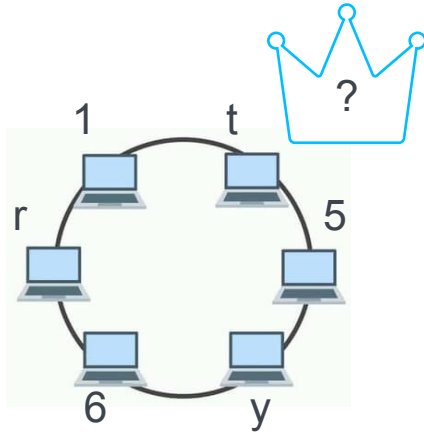
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Architectural Models

- **Client-server**

- *Architectural variations:*

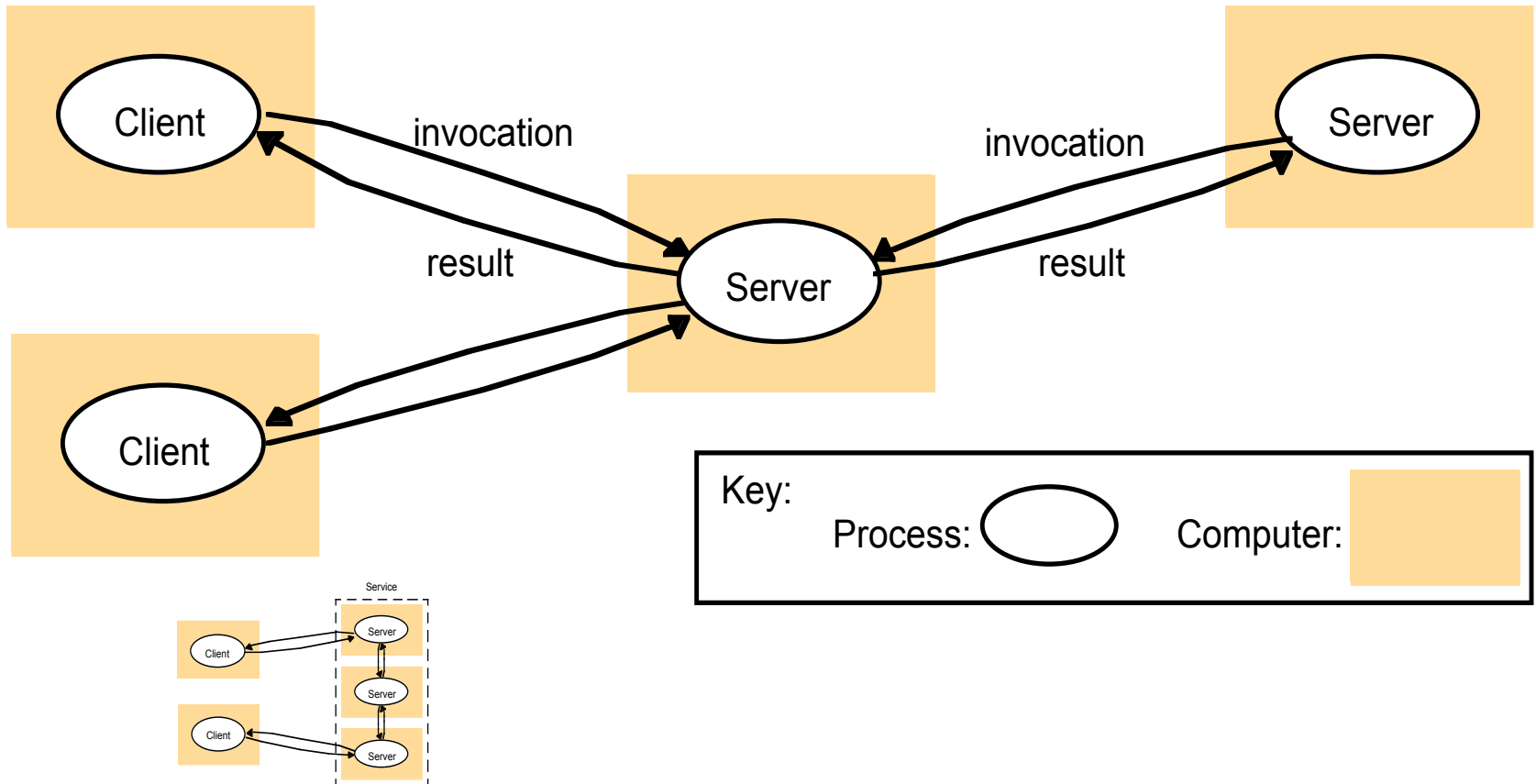
- One server-many clients
 - Many servers-many clients
 - Intermediaries: proxies, load balancing mediators

- *Computational load variations*

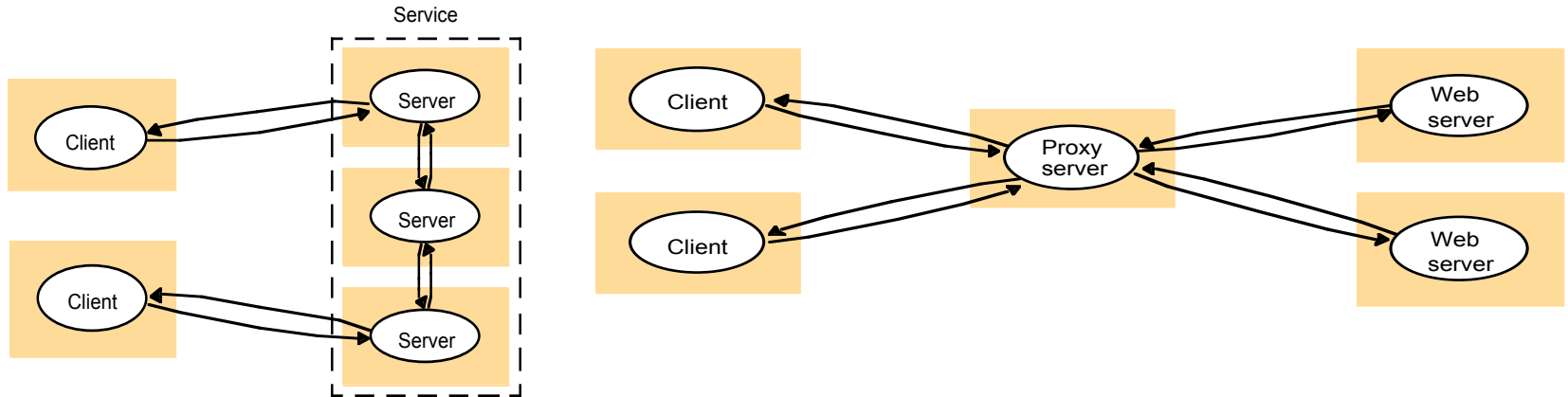
- Mobile code (applets, scripts)
 - Mobile agents
 - Network computers
 - Thin clients

- **Peer-to-peer**

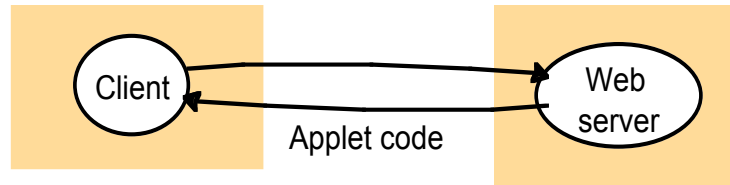
Client Server



Client Server Variations



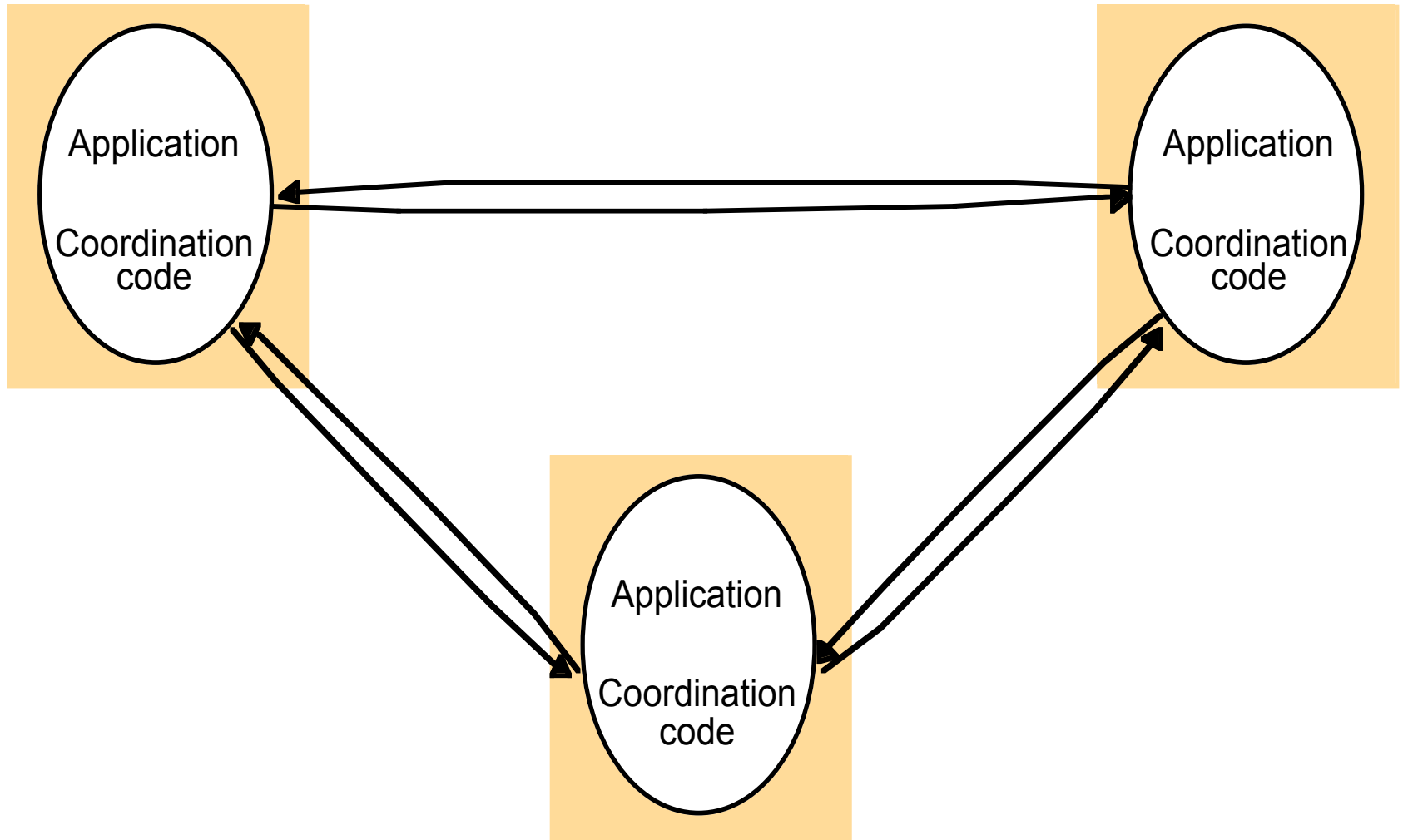
a) client request results in the downloading of applet code



b) client interacts with the applet



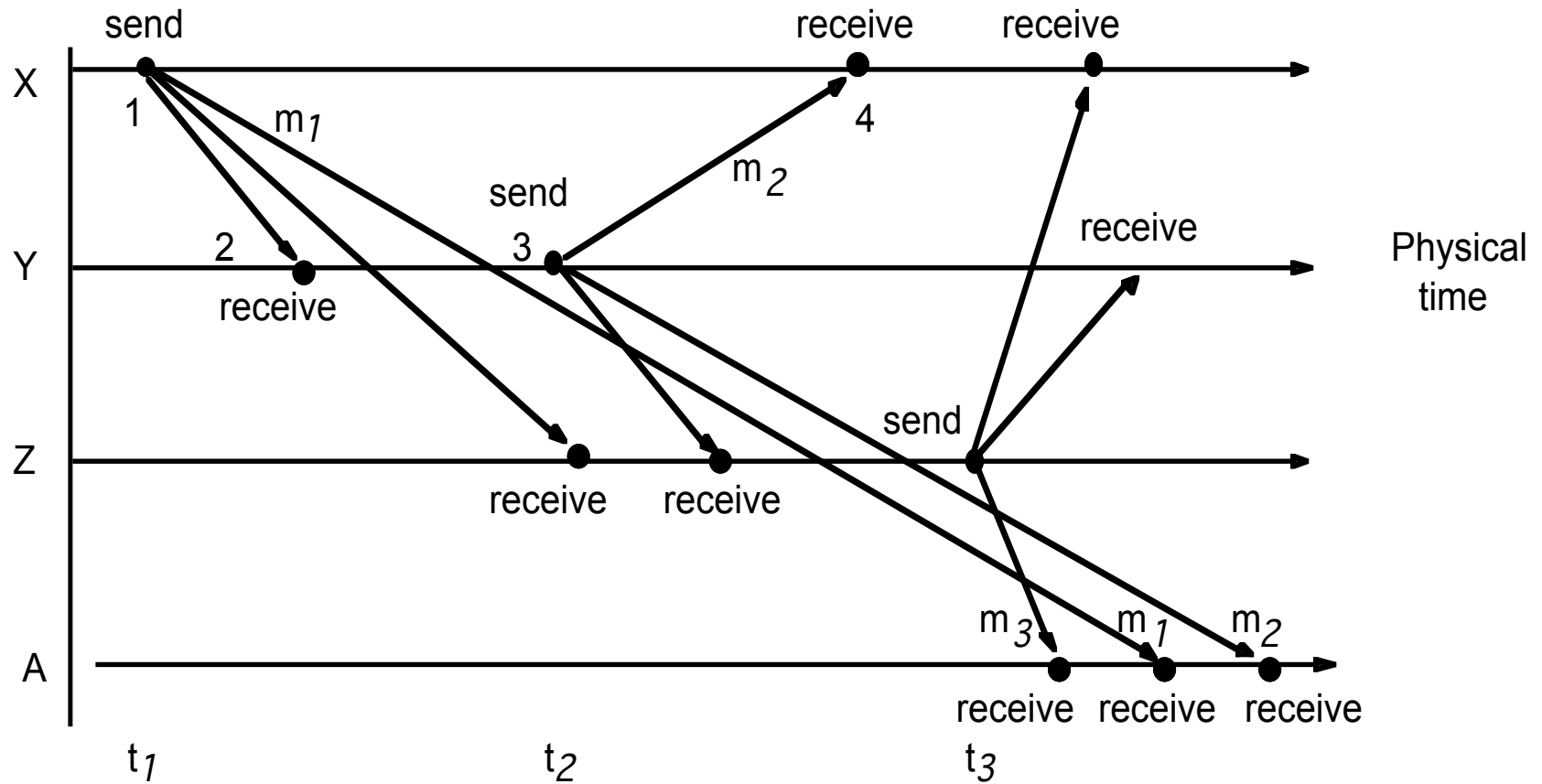
Peer-to-peer



Interaction model

- **Synchronous** distributed system
 - Time to execute a step has lower and upper bounds
 - Each message is received within a given time
 - Each process has a local clock with a given max drift
- **Asynchronous** distributed system
 - No bounds on process execution time
 - No bounds on message receival time
 - Arbitrary clock drifts

Example: eMail

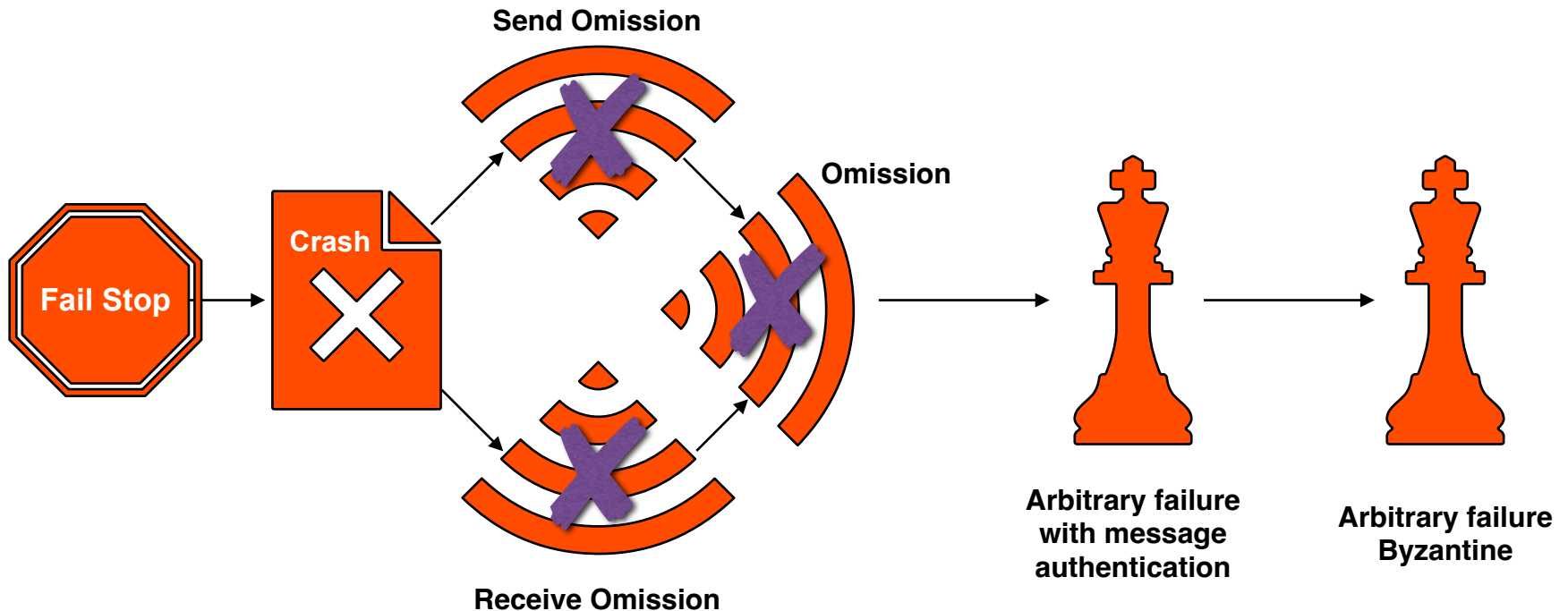


Interaction model

- Performance
 - *Latency*: Δ time transmission begins and beginning of receipt
 - *Bandwidth*: amount of information that can be transmitted over a channel in the unit of time
 - *Jitter*: difference in time needed to transmit a series of messages
- Clock drift rate: timing events (GPS)
- Event ordering

Failure model

- Defines how failures can occur in order to detect and mask them, thus establishing the level of fault tolerance of the system.



Security Models

- Model the enemy's attacks
 - list type of attacks, to which components, for which users and processes
- Goal:
 - To protect objects, processes, communication, data integrity and privacy
- Solutions:
 - Cryptography
 - Authentication
 - Secure channels
 - Data mixing and obfuscation