# Characterization of Distributed Systems

#### **Marco Aiello**

(based on <a href="http://www.cdk4.net">http://www.cdk4.net</a>)

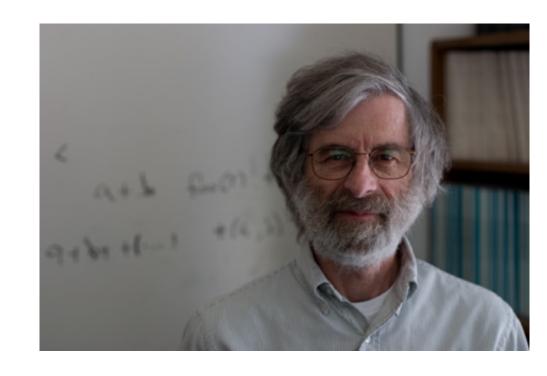
# What is a distributed system?

A distributed system is a collection of autonomous hosts that are connected through a computer network. Each host executes computations and operates a distribution middleware, which enables the components to coordinate their activities via message-passing in such a way that users perceive the system as a single, integrated computing facility.

#### or better said

"A distributed system is one in which the failure of a machine you have never heard of can cause your own machine to become unusable"

Leslie Lamport

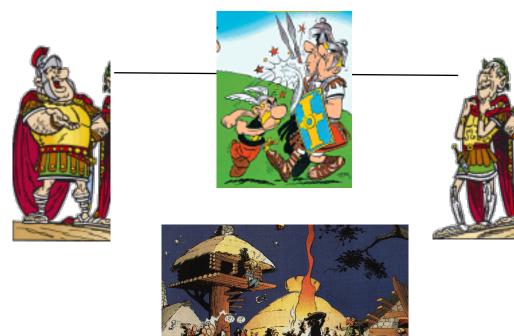


#### **How to think in Distributed Systems Terms**

- Verify correctness of protocols
- Verify efficiency of protocols
- Hosts are independent state machines
- Deal with concurrency, consistency, replication

#### Two generals problem

- Two Generals need to coordinate an attack against an enemy. If they attack individually, they will loose, if they attack together they will win.
- But the enemy lies in the middle and can intercept the coordination messages and avoid delivery
- Can the generals defeat the enemy?



#### Two generals problem

#### Proof sketch

- **Theorem:** there is no non-trivial protocol that guarantees that the generals will always attack simultaneously
- **Proof:** Ab absurdum, suppose there is one such protocol that does the job in the minimum number of steps n>0.
- Consider the last message sent, the n-th. The state of the sender cannot depend on its receipt, the state of the receiver cannot depend on its arrival, so they both do not need the n-th message. So we would have a protocol with n-1 messages. But that contradict the hypothesis
- Fact: A solution requires reliable message delivery.

#### Modelling the state of the computation

- State machine to model a system who's output depends on the current state and input (e.g., incoming messages)
- Finite State Machine (FSM):
  - Finite set of states S ⊇ {initial state s0}
  - Set of inputs messages I
  - Set of outputs messages O
  - Next state function: f: S × I → S × O

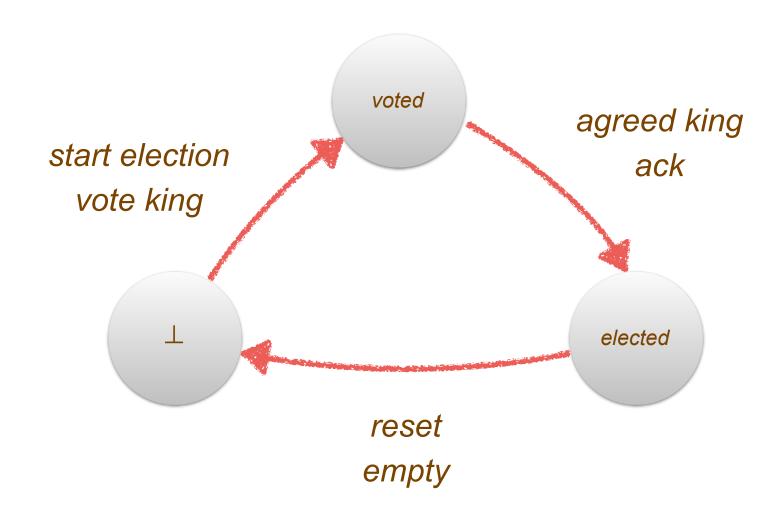
#### **Finite State Machine**

#### Example

- S={⊥,voted,elected}
- $s0 = \bot$
- I = {start election, agreed king, reset}
- O = {vote king, ack, empty}
- Next state function:
  - (⊥,start election) -> (voted,vote king)
  - (voted,agreed king) -> (elected,ack)
  - (elected,reset) -> (⊥,empty)
  - any other combination > (⊥,empty)

#### **Finite State Machine**

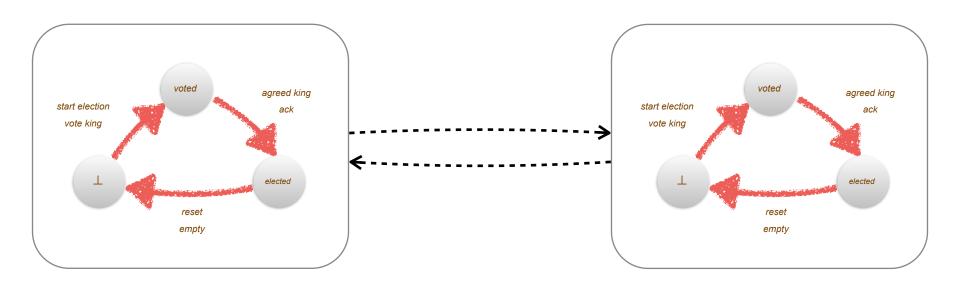
#### Example schema



#### State of a Distributed System

host 1

 A distributed system is modelled by the set of states of its components and of its channels



channel

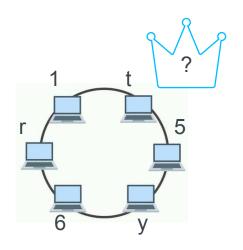
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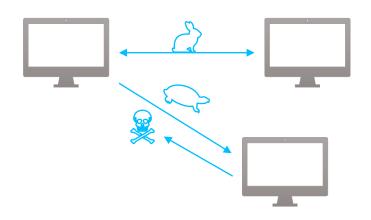
host 2

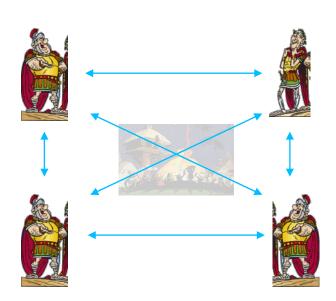
#### Some important (negative) results

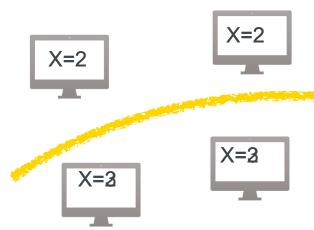
- No leader election in anonymous rings
- No consensus in asynchronous systems
- Byzantine fault tolerance with at most  $\lceil \frac{1}{3}n 1 \rceil$
- CAP theorem (Consistency, Availability, Partitioning Tolerance)

## In pictures

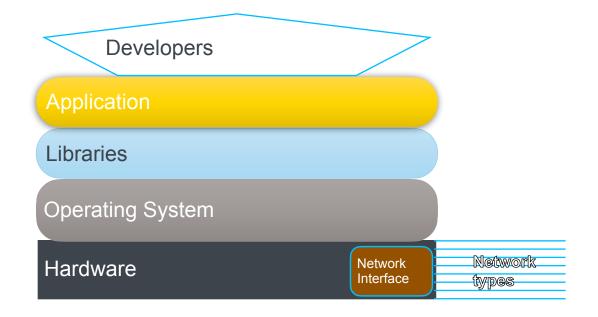




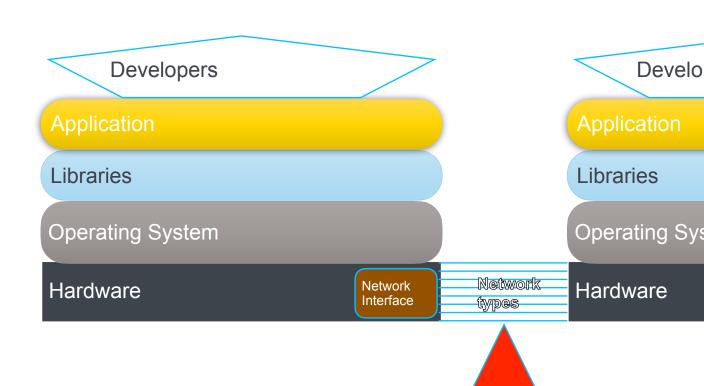




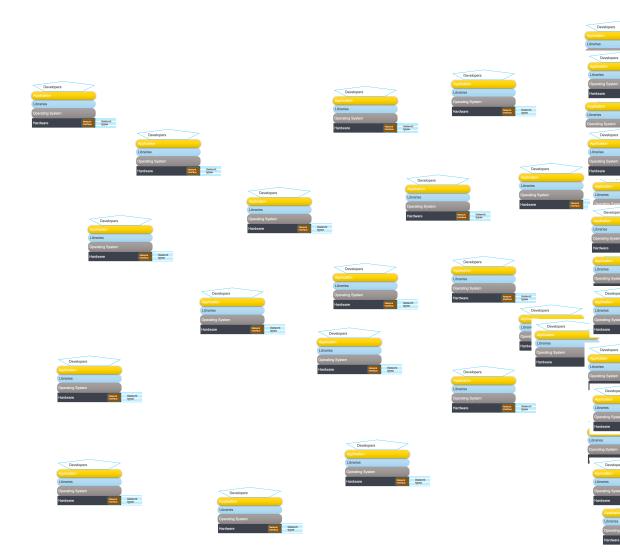
- Heterogeneity
  - Openness
  - Security
  - Scalability
  - Failure handling
  - Consistency
  - Concurrency
  - Transparency



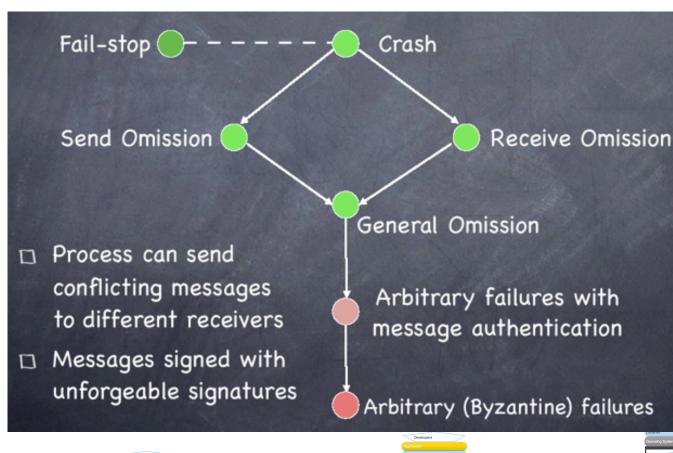
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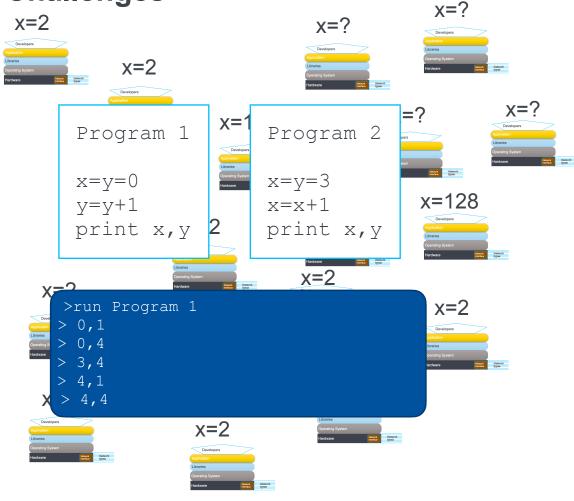






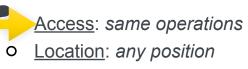


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Eventual	Consistent Prefix	Session .	Causal	Bounded	Strong	
	Read	Read Your Own Write		Staleness	Sequential	
		Monotonic Read			Linearizable	
		Write Follows Read			Strict	
Weaker Consistency		Monotonic Write			Stronger Consistency	_

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- Mobility: dynamic
- O Replication: any copy
- o Failure: tolerance
- Scaling: any number of nodes

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