

Solving recurrences

Recap

MergeSort($A[p..r]$)

IF $p < r$

$q = \lfloor (p + r) / 2 \rfloor$

MergeSort($A[p..q]$)

MergeSort($A[q + 1..r]$)

Merge(A, p, q, r)

$T(n/2)$


$T(n/2)$

$\Theta(n)$

$$T(n) = \begin{cases} \Theta(1) & \text{if } n = 1 \\ 2T(n/2) + \Theta(n) & \text{if } n > 1 \end{cases}$$

How about apply iteration?

$$\begin{aligned}T(n) &= 2T\left(\frac{n}{2}\right) + \Theta(n) \\&= 2^2T(2^{k-2}) + c2^k + c2^k \\&\dots\dots\dots \\&= 2^kT(1) + c(k2^k) \\&= O(n \lg n)\end{aligned}$$

 assume $n = 2^k$

It can be difficult to compute sometime.

Solving recurrences

1. Substitution method
2. Recursion tree
3. Master theorem

Substitution method

The most general method:

- 1. Guess* the form of the solution.
- 2. Verify* by induction.
- 3. Solve* for constants.

Substitution method

The most general method:


1. **Guess** the form of the solution.
2. **Verify** by induction.
3. **Solve** for constants.

EXAMPLE: $T(n) = 4T(n/2) + n$

- [Assume that $T(1) = \Theta(1)$.]
- Guess $O(n^3)$.
- Assume that $T(k) \leq ck^3$ for $k < n$.
- Prove $T(n) \leq cn^3$ by induction.

Example of substitution

$$\begin{aligned}T(n) &= 4T(n/2) + n \\&\leq 4c(n/2)^3 + n \\&= (c/2)n^3 + n \\&= cn^3 - ((c/2)n^3 - n) \leftarrow \textit{desired} - \textit{residual} \\&\leq cn^3 \leftarrow \textit{desired}\end{aligned}$$

whenever $(c/2)n^3 - n \geq 0$, for example,
if $c \geq 2$ and $n \geq 1$. 

residual

Example (continued)

- We must also handle the initial conditions, that is, ground the induction with base cases.
- **Base:** $T(n) = \Theta(1)$ for all $n < n_0$, where n_0 is a suitable constant.
- For $1 \leq n < n_0$, we have “ $\Theta(1)$ ” $\leq cn^3$, if we pick c big enough.

Example (continued)

- We must also handle the initial conditions, that is, ground the induction with base cases.
- **Base:** $T(n) = \Theta(1)$ for all $n < n_0$, where n_0 is a suitable constant.
- For $1 \leq n < n_0$, we have “ $\Theta(1)$ ” $\leq cn^3$, if we pick c big enough.

This bound is not tight!

A tighter upper bound?

We shall prove that $T(n) = O(n^2)$.

A tighter upper bound?

We shall prove that $T(n) = O(n^2)$.

Assume that $T(k) \leq ck^2$ for $k < n$:

$$\begin{aligned} T(n) &= 4T(n/2) + n \\ &\leq 4c(n/2)^2 + n \\ &= cn^2 + n \\ &= O(n^2) \end{aligned}$$

A tighter upper bound?

We shall prove that $T(n) = O(n^2)$.

Assume that $T(k) \leq ck^2$ for $k < n$:

$$\begin{aligned} T(n) &= 4T(n/2) + n \\ &\leq 4c(n/2)^2 + n \\ &= cn^2 + n \end{aligned}$$

~~$= O(n^2)$~~ **Wrong!** We must prove the I.H.



A tighter upper bound?

We shall prove that $T(n) = O(n^2)$.

Assume that $T(k) \leq ck^2$ for $k < n$:

$$\begin{aligned} T(n) &= 4T(n/2) + n \\ &\leq 4c(n/2)^2 + n \\ &= cn^2 + n \end{aligned}$$

~~$= O(n^2)$~~ **Wrong!** We must prove the I.H.

$$= cn^2 - (-n) \quad [\text{desired} - \text{residual}]$$

$\leq cn^2$ for **no** choice of $c > 0$. Lose!

A tighter upper bound!

IDEA: Strengthen the inductive hypothesis.

- *Subtract* a low-order term.

Inductive hypothesis: $T(k) \leq c_1 k^2 - c_2 k$ for $k < n$.

A tighter upper bound!

IDEA: Strengthen the inductive hypothesis.

- *Subtract* a low-order term.

Inductive hypothesis: $T(k) \leq c_1 k^2 - c_2 k$ for $k < n$.

$$\begin{aligned} T(n) &= 4T(n/2) + n \\ &= 4(c_1(n/2)^2 - c_2(n/2)) + n \\ &= c_1 n^2 - 2c_2 n + n \\ &= c_1 n^2 - c_2 n - (c_2 n - n) \\ &\leq c_1 n^2 - c_2 n \quad \text{if } c_2 \geq 1. \end{aligned}$$

A tighter upper bound!

IDEA: Strengthen the inductive hypothesis.

- *Subtract* a low-order term.

Inductive hypothesis: $T(k) \leq c_1 k^2 - c_2 k$ for $k < n$.

$$\begin{aligned} T(n) &= 4T(n/2) + n \\ &= 4(c_1(n/2)^2 - c_2(n/2)) + n \\ &= c_1 n^2 - 2c_2 n + n \\ &= c_1 n^2 - c_2 n - (c_2 n - n) \\ &\leq c_1 n^2 - c_2 n \text{ if } c_2 \geq 1. \end{aligned}$$

Pick c_1 big enough to handle the initial conditions.

Example of recursion tree

Solve $T(n) = T(n/4) + T(n/2) + n^2$:

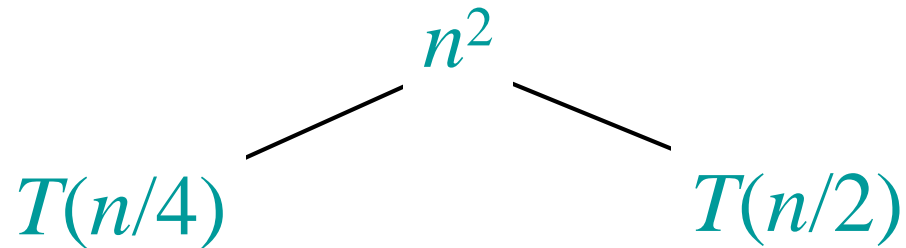
Example of recursion tree

Solve $T(n) = T(n/4) + T(n/2) + n^2$:

$$T(n)$$

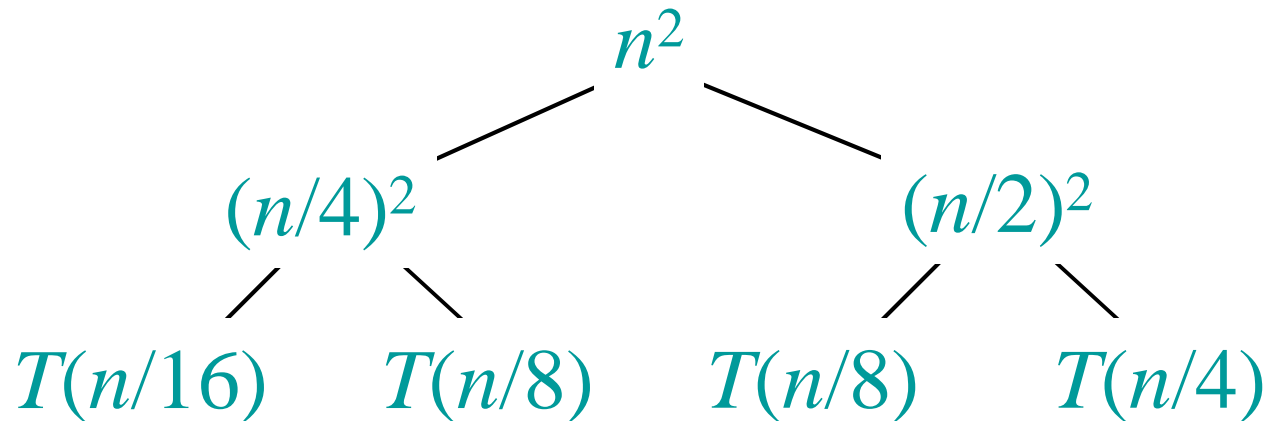
Example of recursion tree

Solve $T(n) = T(n/4) + T(n/2) + n^2$:



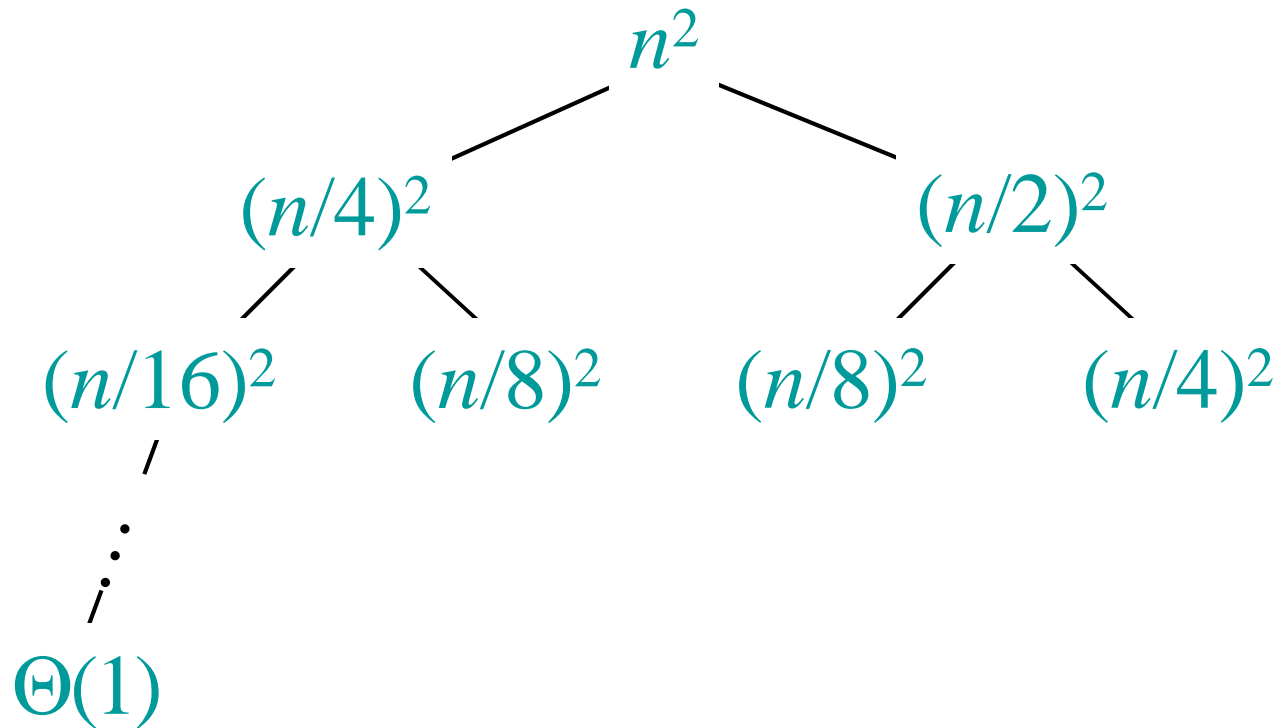
Example of recursion tree

Solve $T(n) = T(n/4) + T(n/2) + n^2$:



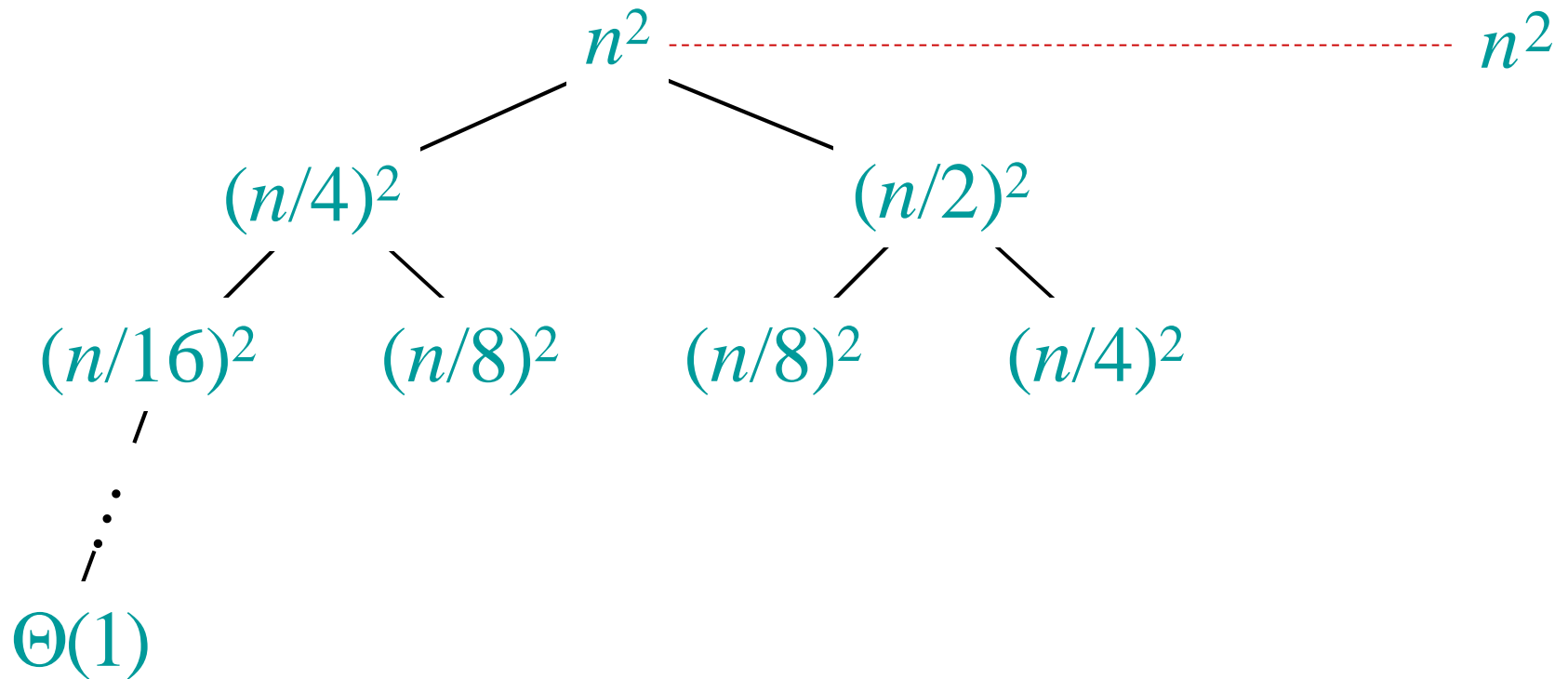
Example of recursion tree

Solve $T(n) = T(n/4) + T(n/2) + n^2$:



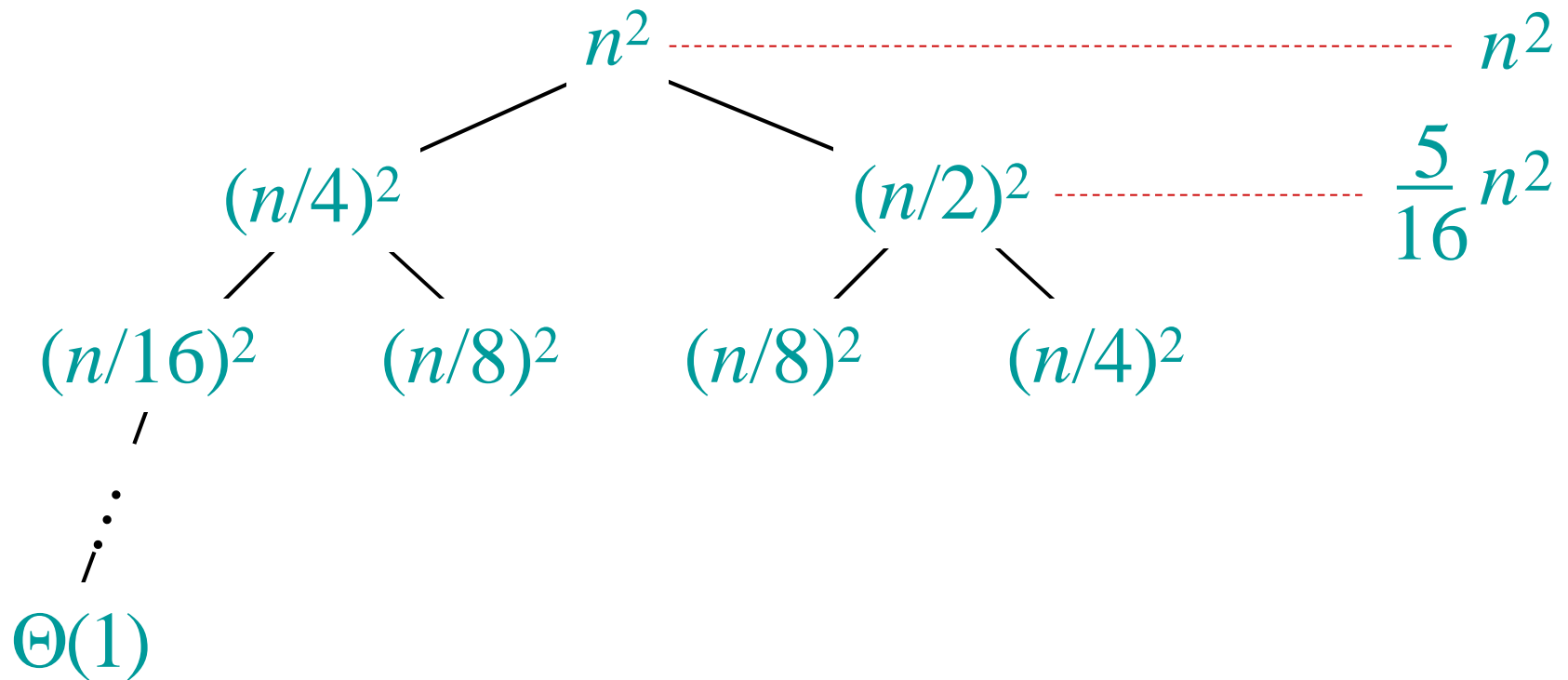
Example of recursion tree

Solve $T(n) = T(n/4) + T(n/2) + n^2$:



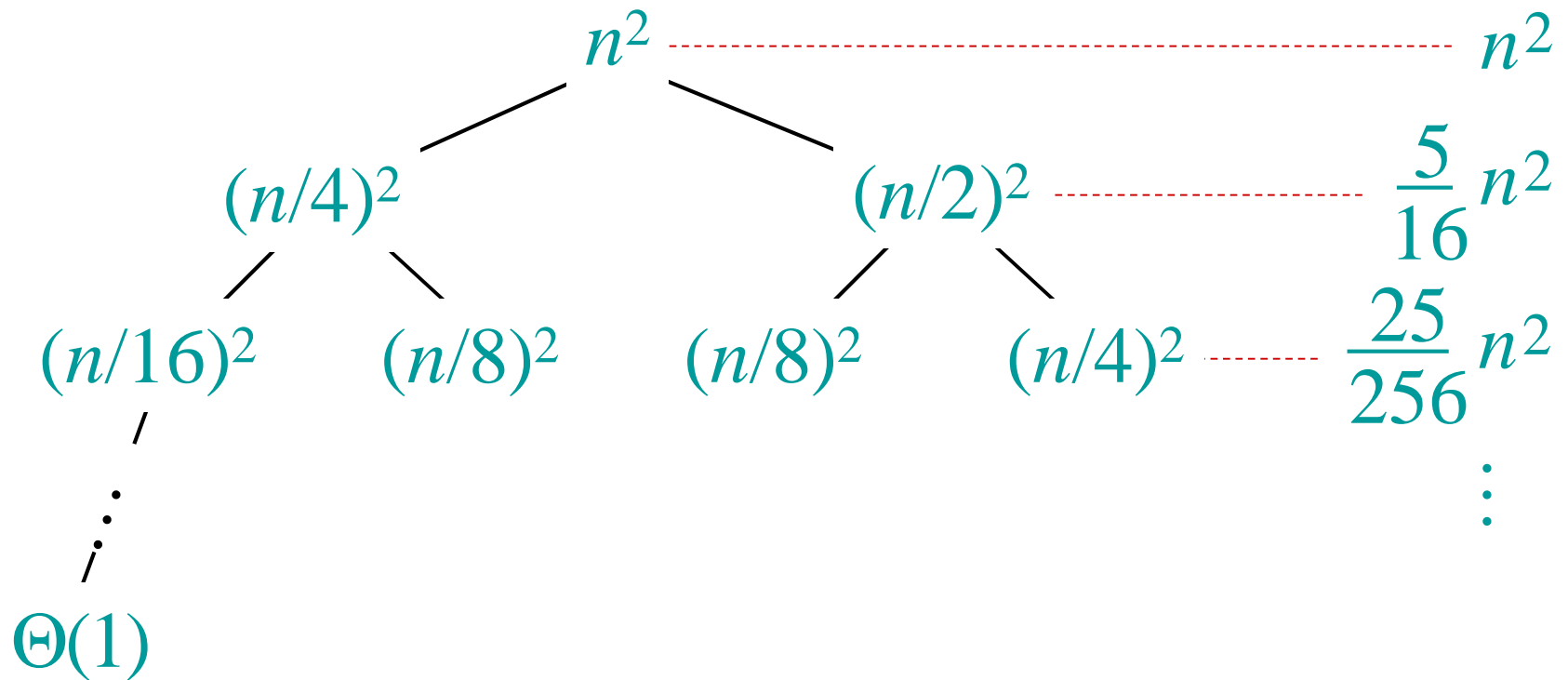
Example of recursion tree

Solve $T(n) = T(n/4) + T(n/2) + n^2$:



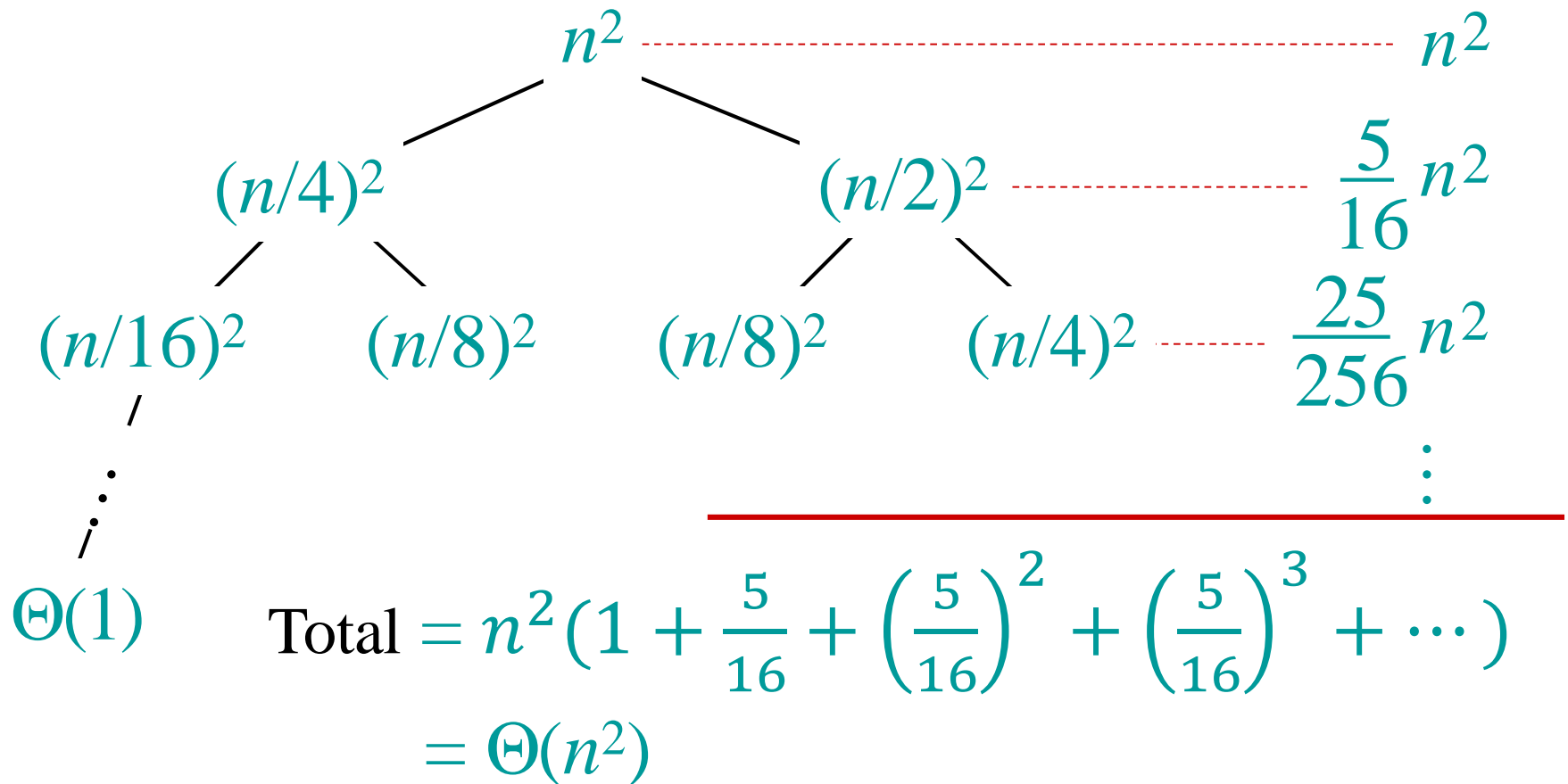
Example of recursion tree

Solve $T(n) = T(n/4) + T(n/2) + n^2$:



Example of recursion tree

Solve $T(n) = T(n/4) + T(n/2) + n^2$:



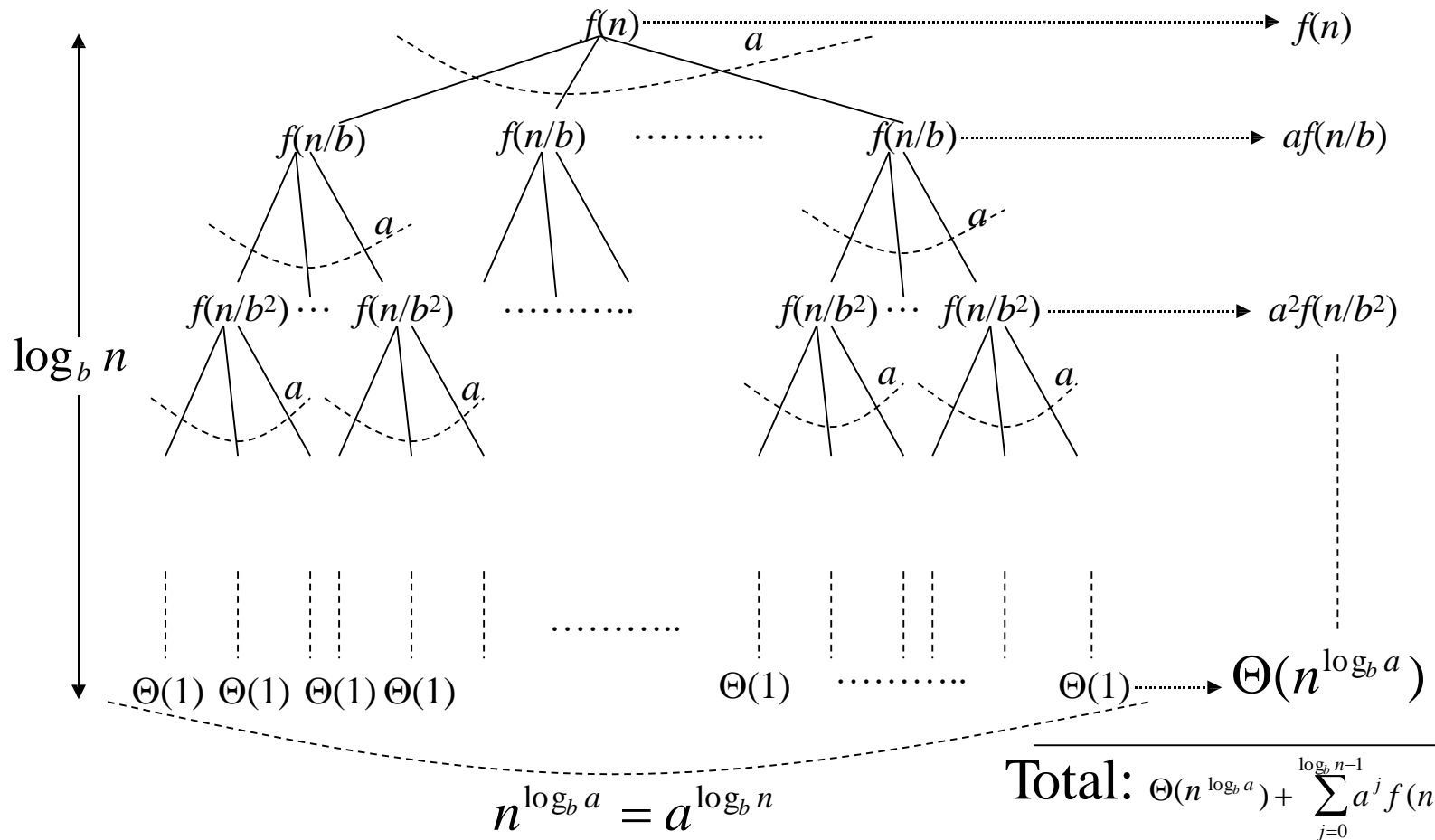
The master method

The master method applies to recurrences of the form

$$T(n) = aT(n/b) + f(n) ,$$

where $a \geq 1$, $b > 1$, and f is asymptotically positive.

The recursion tree of $T(n)$



Three common cases

The running time $T(n)$

- Dominated by cost at leaves (for solving the minimum subproblems)
- Evenly distributed throughout the tree
- Dominated by cost at the root (for dividing the problem and combining the results)

Solving recurrences amounts to characterizing the dominant term in each case.

Three common cases

Compare $f(n)$ with $n^{\log_b a}$:

1. $f(n) = O(n^{\log_b a - \varepsilon})$ for some constant $\varepsilon > 0$.
 - $f(n)$ grows *polynomially slower* than $n^{\log_b a}$ (by an n^ε factor).

Solution: $T(n) = \Theta(n^{\log_b a})$.

Three common cases

Compare $f(n)$ with $n^{\log_b a}$:

1. $f(n) = O(n^{\log_b a - \varepsilon})$ for some constant $\varepsilon > 0$.

- $f(n)$ grows *polynomially slower* than $n^{\log_b a}$ (by an n^ε factor).

Solution: $T(n) = \Theta(n^{\log_b a})$.

2. $f(n) = \Theta(n^{\log_b a} \lg^k n)$ for some constant $k \geq 0$.

- $f(n)$ and $n^{\log_b a}$ grow at similar rates (within a logarithmic factor to some power).

Solution: $T(n) = \Theta(n^{\log_b a} \lg^{k+1} n)$.

Three common cases (cont.)

Compare $f(n)$ with $n^{\log_b a}$:

3. $f(n) = \Omega(n^{\log_b a + \varepsilon})$ for some constant $\varepsilon > 0$.

- $f(n)$ grows *polynomially faster* than $n^{\log_b a}$ (by an n^ε factor),

and $f(n)$ satisfies the *regularity condition* that $af(n/b) \leq cf(n)$ for some constant $c < 1$ and big enough n .

Solution: $T(n) = \Theta(f(n))$.

Examples

Ex. $T(n) = 4T(n/2) + n$
 $a = 4, b = 2 \Rightarrow n^{\log_b a} = n^2; f(n) = n.$
CASE 1: $f(n) = O(n^{2-\varepsilon})$ for $\varepsilon = 1.$
 $\therefore T(n) = \Theta(n^2).$

Examples

Ex. $T(n) = 4T(n/2) + n$
 $a = 4, b = 2 \Rightarrow n^{\log_b a} = n^2; f(n) = n.$
CASE 1: $f(n) = O(n^{2-\varepsilon})$ for $\varepsilon = 1$.
 $\therefore T(n) = \Theta(n^2).$

Ex. $T(n) = 4T(n/2) + n^2$
 $a = 4, b = 2 \Rightarrow n^{\log_b a} = n^2; f(n) = n^2.$
CASE 2: $f(n) = \Theta(n^2 \lg^0 n)$, that is, $k = 0$.
 $\therefore T(n) = \Theta(n^2 \lg n).$

Examples

Ex. $T(n) = 4T(n/2) + n^3$

$a = 4, b = 2 \Rightarrow n^{\log_b a} = n^2; f(n) = n^3.$

CASE 3: $f(n) = \Omega(n^{2+\varepsilon})$ for $\varepsilon = 1$

and $4(n/2)^3 \leq cn^3$ (reg. cond.) for $c = 1/2.$

$\therefore T(n) = \Theta(n^3).$

Examples

Ex. $T(n) = 4T(n/2) + n^3$

$$a = 4, b = 2 \Rightarrow n^{\log_b a} = n^2; f(n) = n^3.$$

CASE 3: $f(n) = \Omega(n^{2+\varepsilon})$ for $\varepsilon = 1$

and $4(n/2)^3 \leq cn^3$ (reg. cond.) for $c = 1/2$.

$$\therefore T(n) = \Theta(n^3).$$

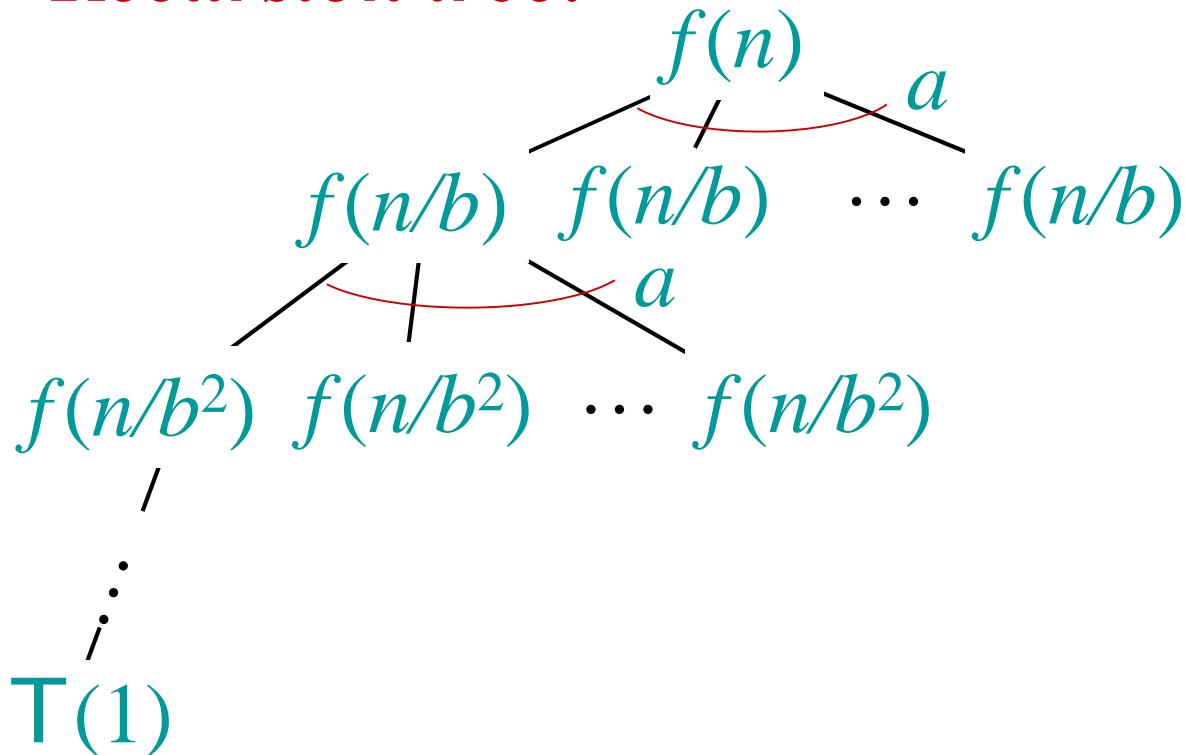
Ex. $T(n) = 4T(n/2) + n^2/\lg n$

$$a = 4, b = 2 \Rightarrow n^{\log_b a} = n^2; f(n) = n^2/\lg n.$$

Master method does not apply. In particular, for every constant $\varepsilon > 0$, we have $n^\varepsilon = \omega(\lg n)$.

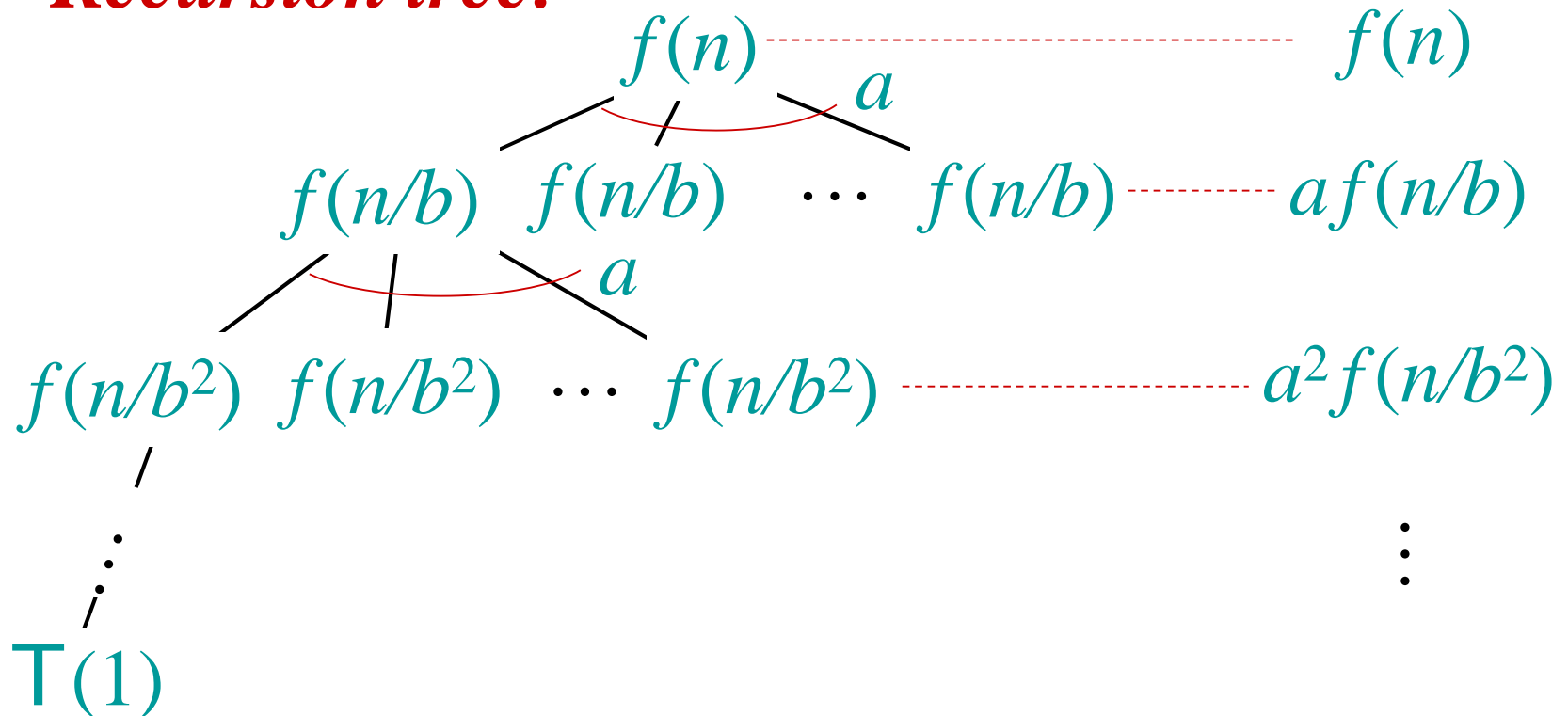
Idea of master theorem

Recursion tree:



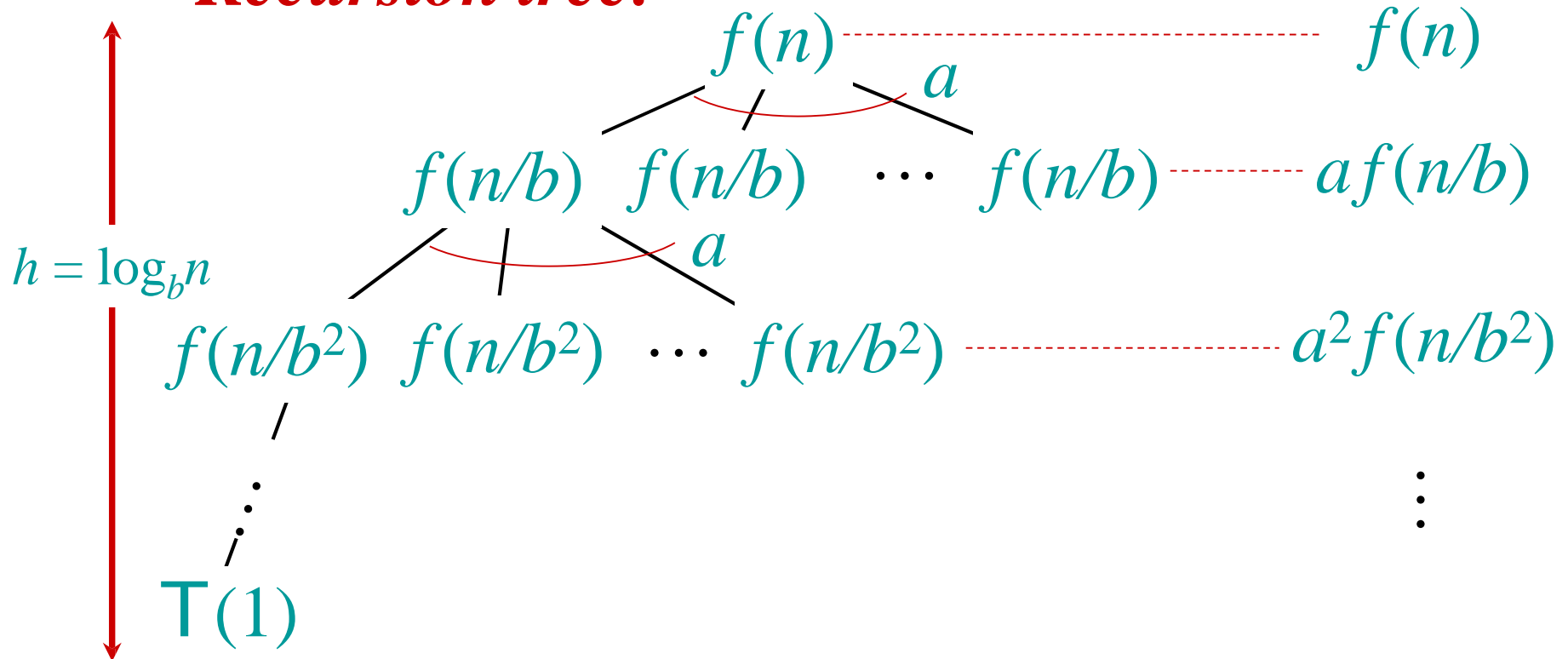
Idea of master theorem

Recursion tree:



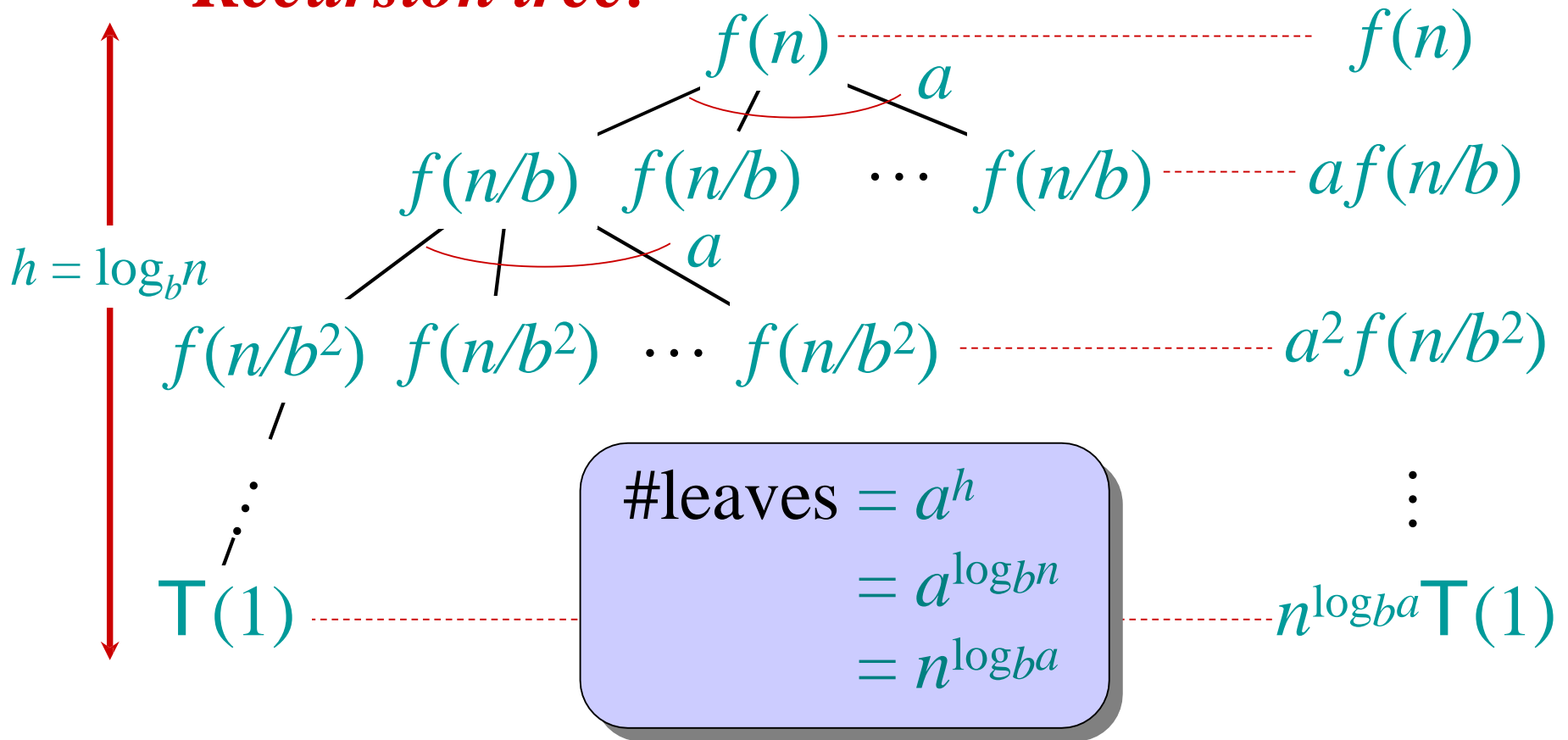
Idea of master theorem

Recursion tree:



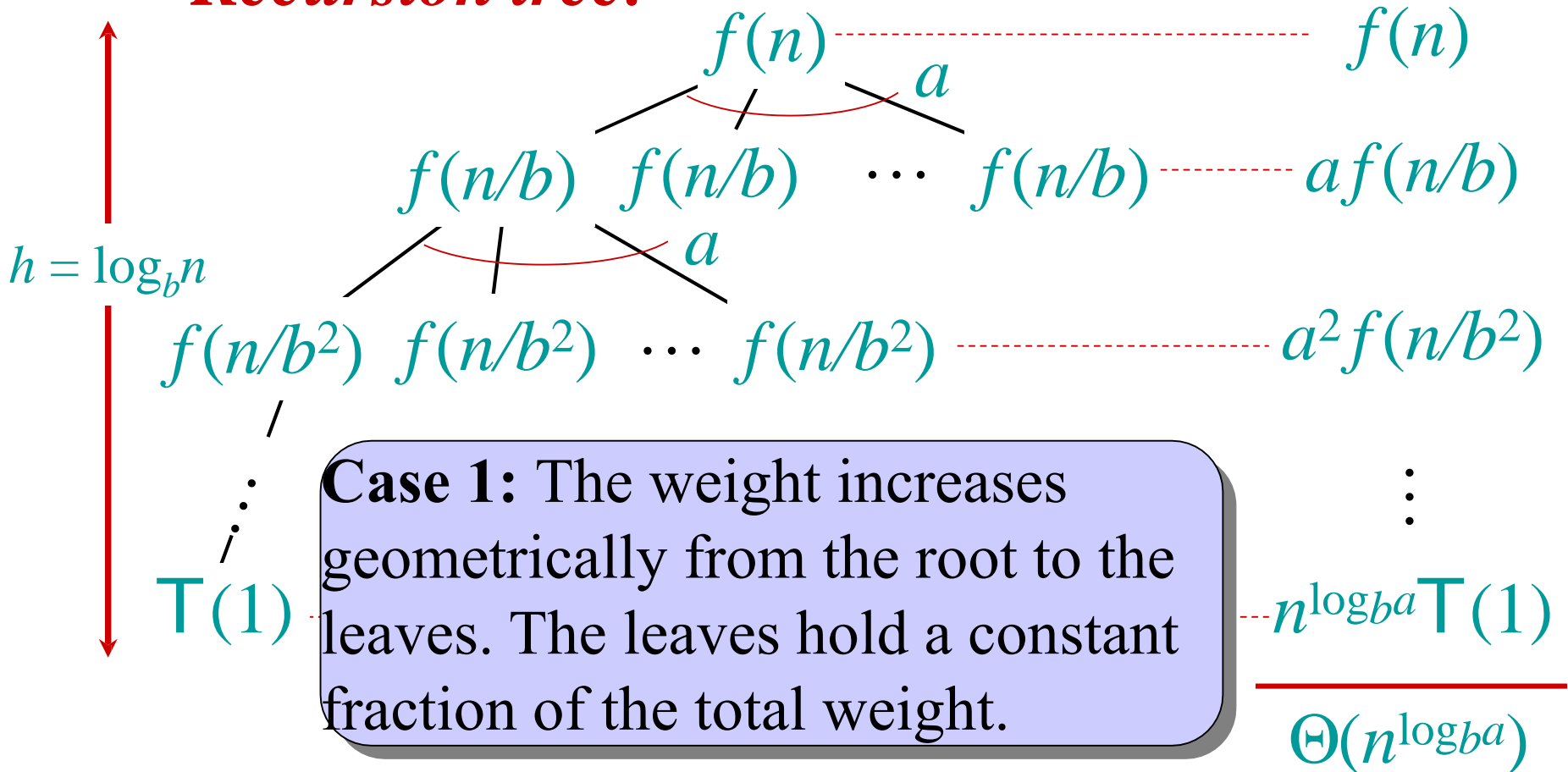
Idea of master theorem

Recursion tree:



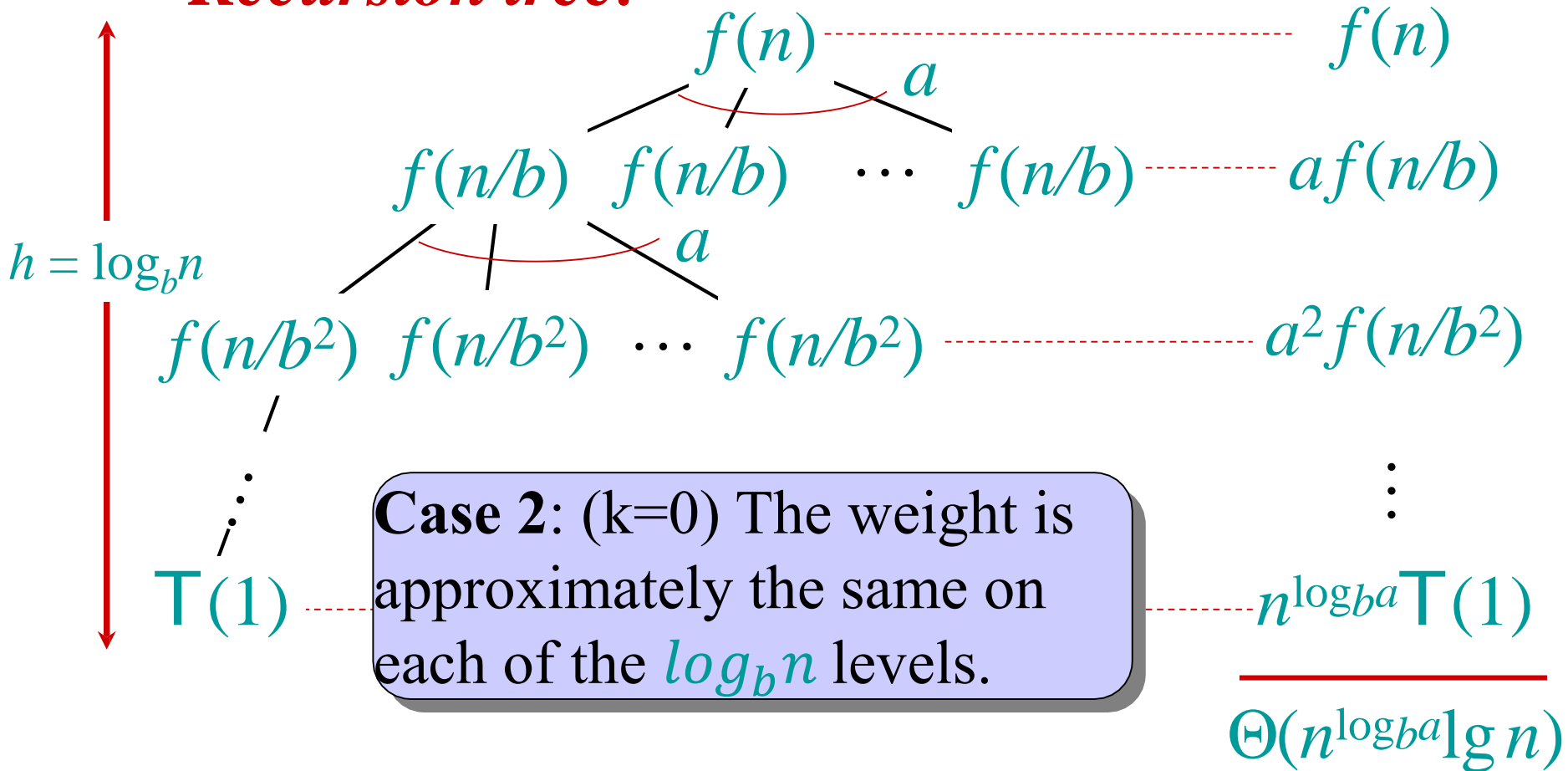
Idea of master theorem

Recursion tree:



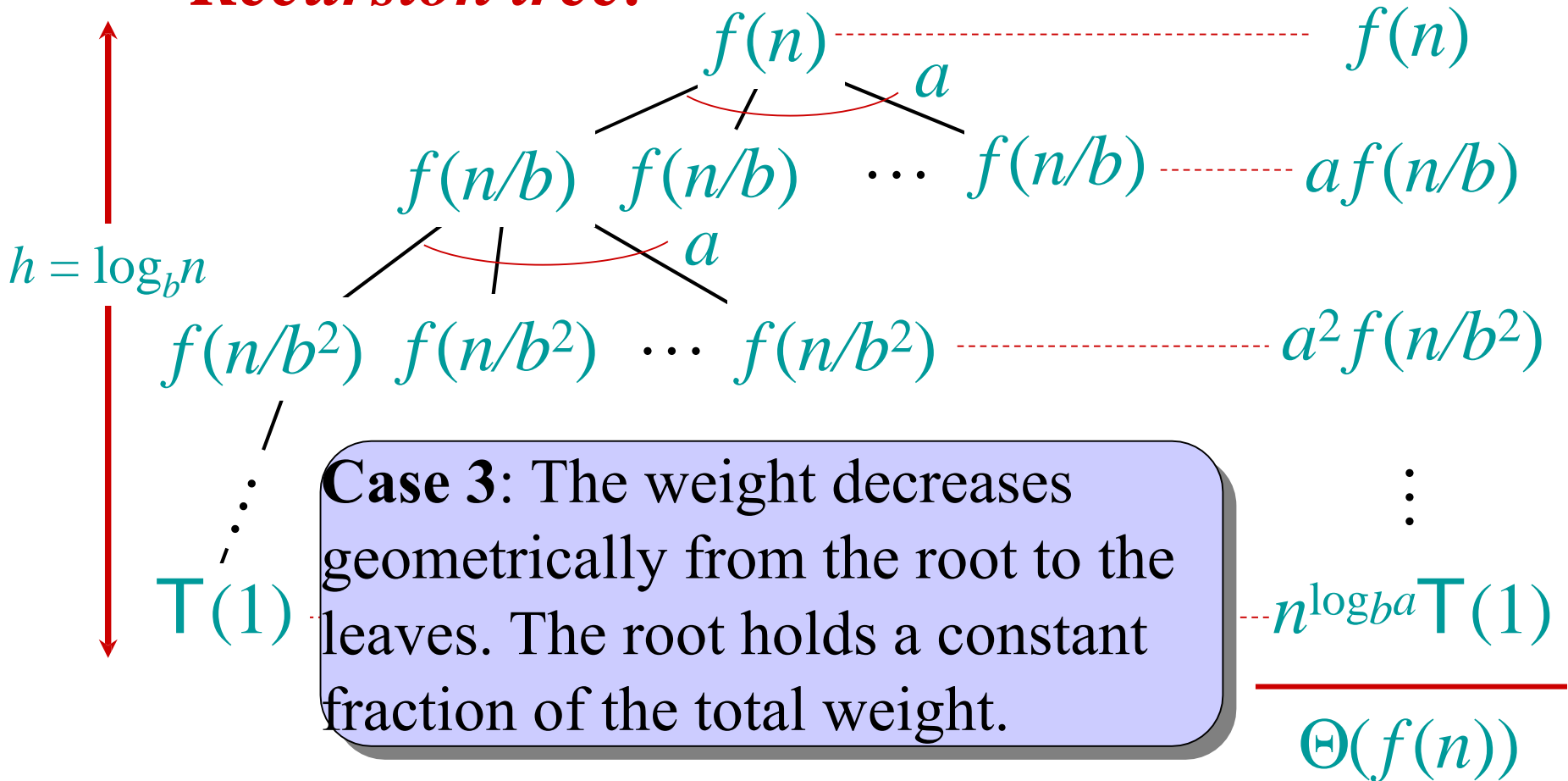
Idea of master theorem

Recursion tree:



Idea of master theorem

Recursion tree:



Some advanced sorting algorithms

Recap sorting

Sorting algorithms	Average case	Worst case	Space	Stability	Complexity
Insertion Sort	$O(n^2)$	$O(n^2)$	$O(1)$	Stable	Simple
Bubble Sort	$O(n^2)$	$O(n^2)$	$O(1)$	Stable	Simple
Selection Sort	$O(n^2)$	$O(n^2)$	$O(1)$	Unstable	Simple
Quicksort	$O(n \log n)$	$O(n^2)$	$O(\log n)$	Unstable	Complex
Heapsort	$O(n \log n)$	$O(n \log n)$	$O(1)$	Unstable	Complex
Mergesort	$O(n \log n)$	$O(n \log n)$	$O(n)$	Stable	Complex

Heapsort

Use data structure *heap* to manage information

Combine the better attributes of insertion sort and merge sort

- $O(n \lg n)$ – like merge sort, unlike insertion sort
- Sorts in place – like insertion, unlike merge sort

Data Structure: Heaps

A *binary* heap data structure A

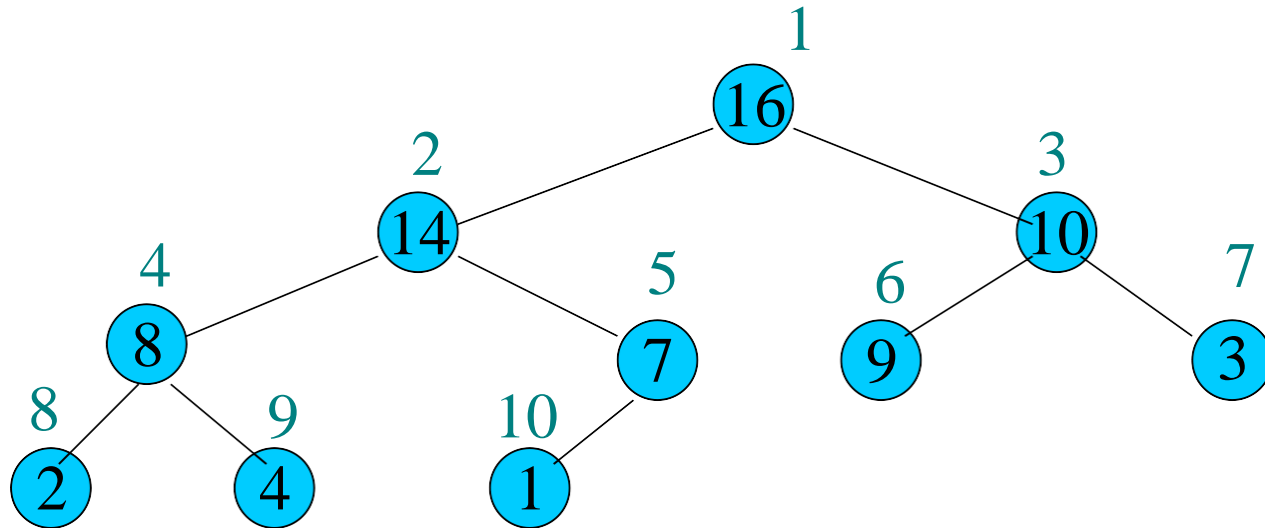
- Simple array
- Viewed as a nearly complete binary tree
- **Max-heap property**

$$A[\text{parent}(x)] \geq A[x]$$

It means that *the value of a node is at most the value of its parent.*

There are also min-heaps and k -ary heaps.

Example of heaps



- Notice the implicit tree links: Children of node i are $2i$ and $2i+1$
- Quickly computed by shifting the binary representation of i left by one bit position and adding 1 as the low-order bit
- Height is $\Theta(\lg n)$ for a heap of size n

Heaps: Extract-Max

Heap-Extract-Max(A)

1. //Removes and returns largest element of A
2. $max \leftarrow A[1]$
3. $A[1] \leftarrow A[n]$
4. $n \leftarrow n-1$
5. Max-Heapify($A, 1$) //Remakes heap
6. **return** max

Running time? $\Theta(1) + \text{Heapify time.}$

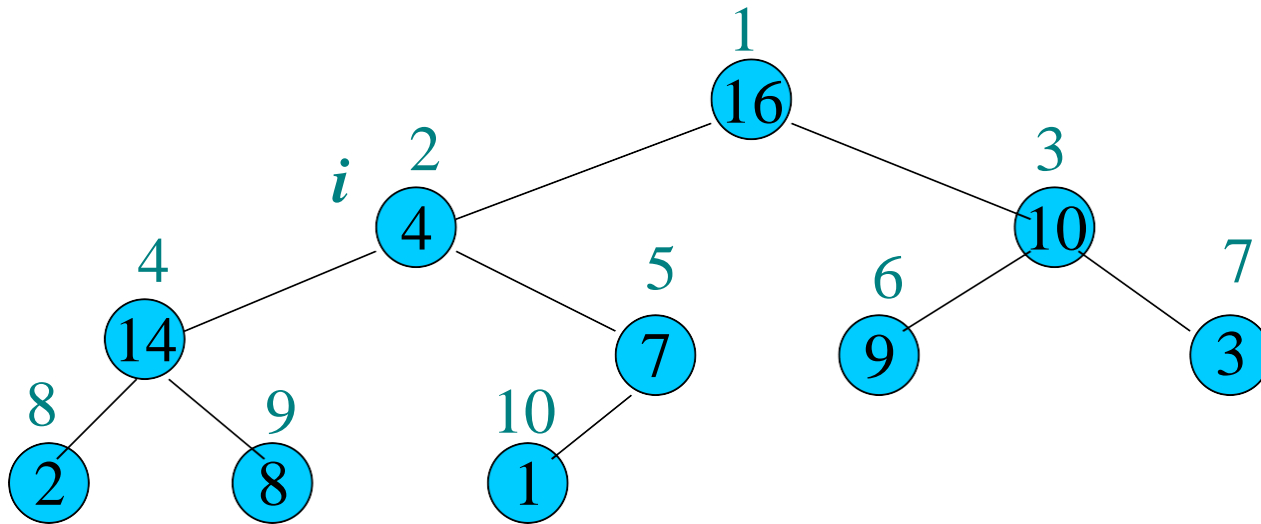
Heaps: Heapify

Max-Heapify (A, i)

- i is index into array A .
- Both binary trees rooted at $\text{Left}(i)$ and $\text{Right}(i)$ are max-heaps.
- But, $A[i]$ may be smaller than its children, thus violating the heap property.
- Heapify makes A a heap once more by “floating down” $A[i]$ in max-heap so that the subtree rooted at i obeys the max-heap property.

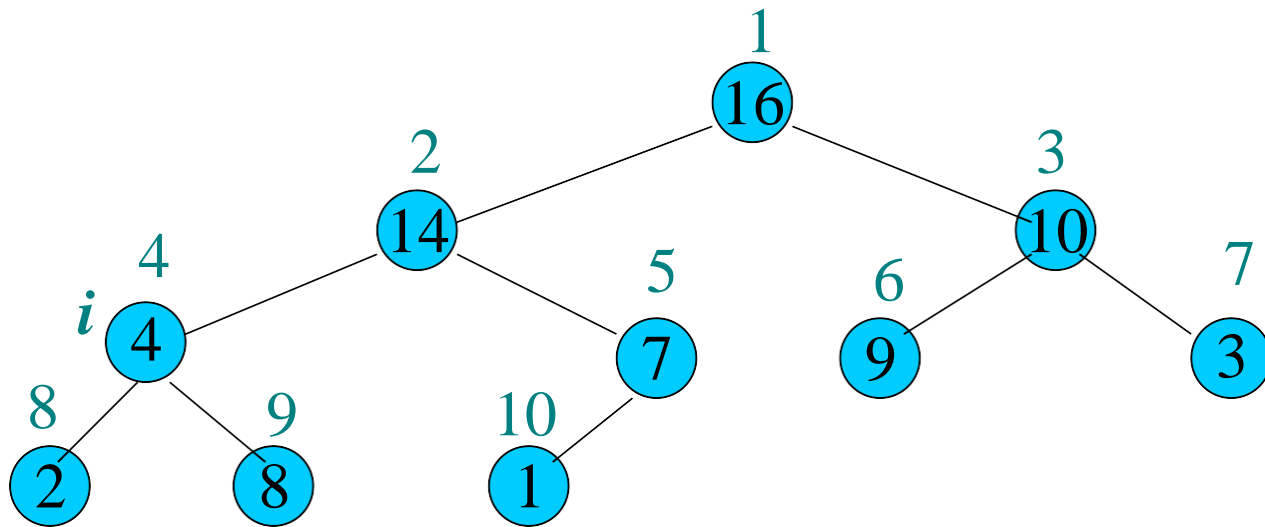
Heaps: Heapify Example

1. Call Heapify($A, 2$)



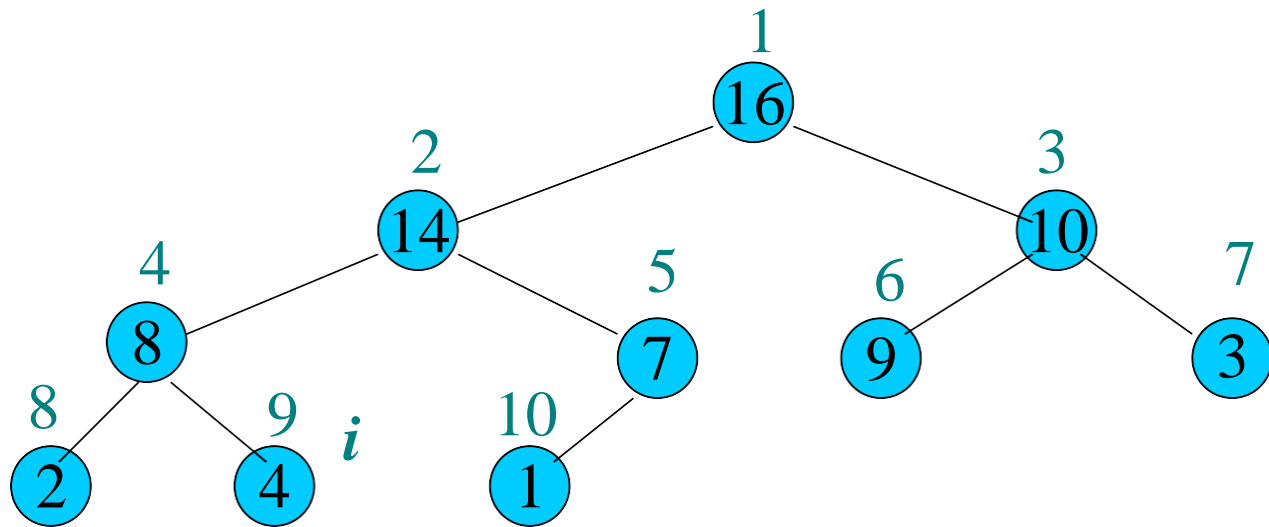
Heaps: Heapify Example (cont.)

2. Exchange $A[2]$ with $A[4]$ and recursively call $\text{Heapify}(A, 4)$



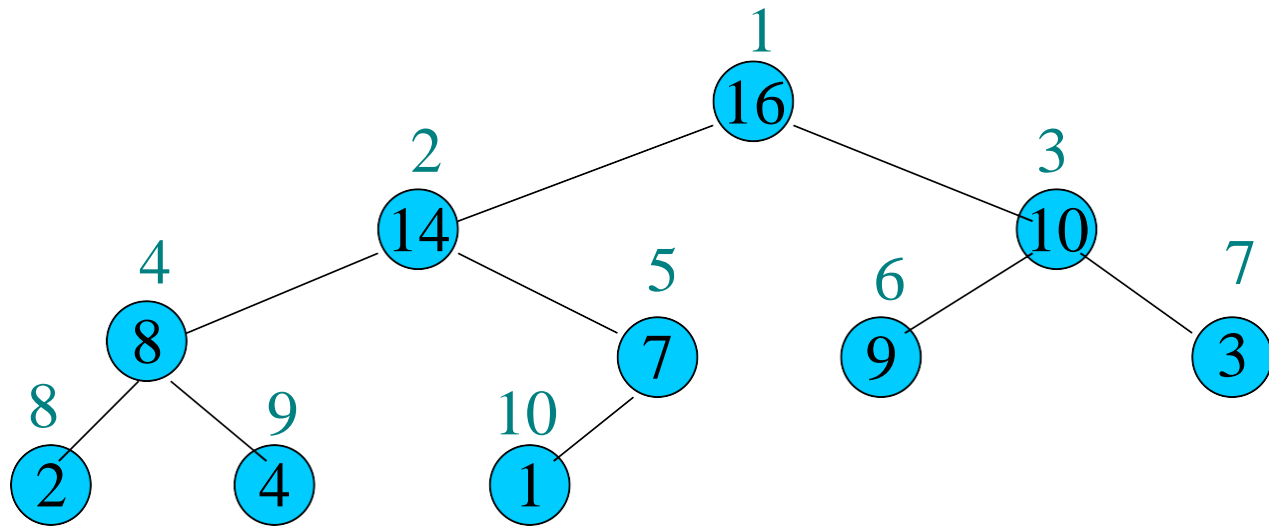
Heaps: Heapify Example (cont.)

3. Exchange $A[4]$ with $A[9]$ and recursively call $\text{Heapify}(A, 9)$



Heaps: Heapify Example (cont.)

4. Node 9 has no children, so we are done.



Heaps: Heapify

```
MAX-HEAPIFY( $A, i$ )
1   $l = \text{LEFT}(i)$ 
2   $r = \text{RIGHT}(i)$ 
3  if  $l \leq A.\text{heap-size}$  and  $A[l] > A[i]$ 
4       $\text{largest} = l$ 
5  else  $\text{largest} = i$ 
6  if  $r \leq A.\text{heap-size}$  and  $A[r] > A[\text{largest}]$ 
7       $\text{largest} = r$ 
8  if  $\text{largest} \neq i$ 
9      exchange  $A[i]$  with  $A[\text{largest}]$ 
10     MAX-HEAPIFY( $A, \text{largest}$ )
```

- Correctness: induction on the height of i
- The worst-case running time is proportional to the height of $i = O(\lg n)$

Heapsort

Heapsort(A)

1. Build-Max-Heap(A)
2. **for** $i \leftarrow n$ **downto** 2
3. **do** exchange $A[1] \leftrightarrow A[i]$
4. $n \leftarrow n - 1$
5. Heapify($A, 1$)

Analysis

??

n times

$O(1)$

$O(1)$

$O(\lg n)$

Total Running time:

$O(n \lg n)$ + Build-Heap(A) time

Heapsort: Building a heap

Convert an array $A[1..n]$ where $n = \text{length}[A]$, into a heap.

Notice that the elements in the subarray $A[(\lfloor n/2 \rfloor + 1)..n]$ are leaves and already 1-element heaps to begin with.

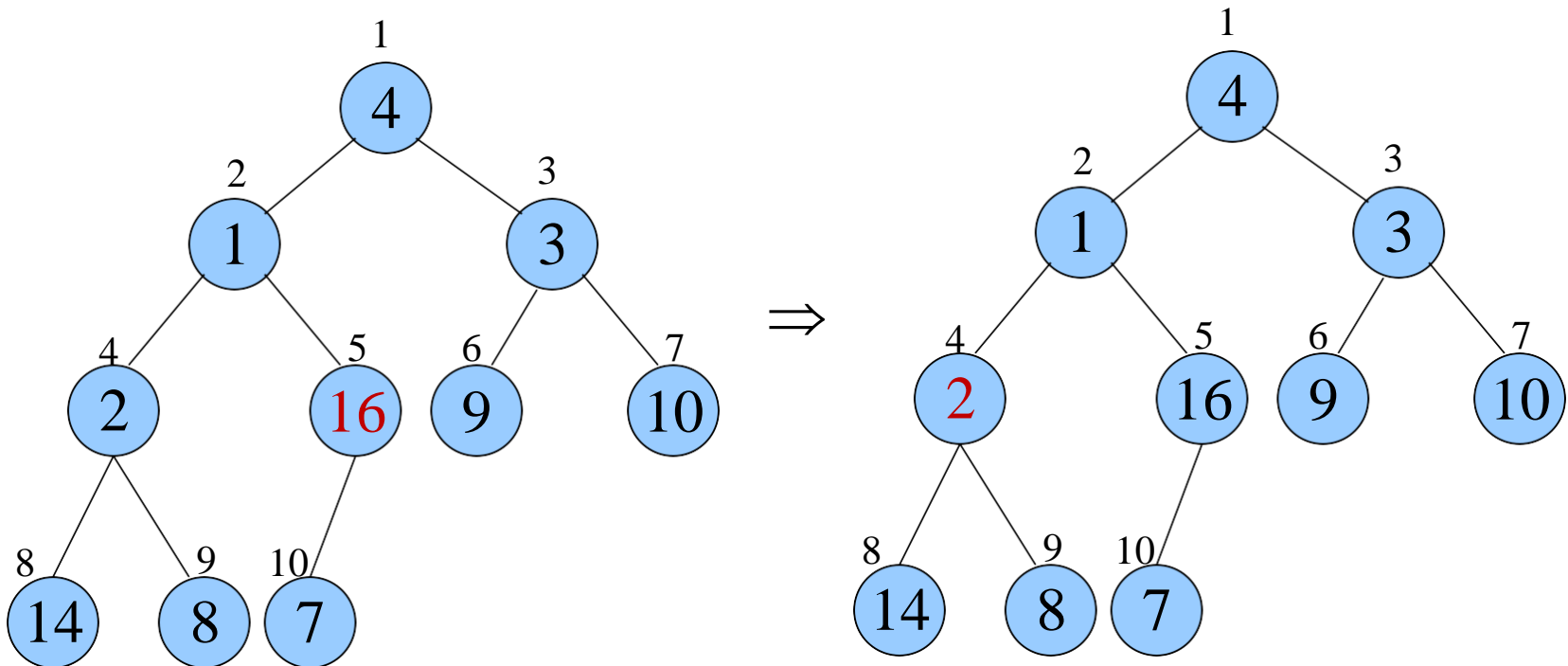
Build-Max-Heap(A)

1. **for** $i \leftarrow \lfloor n/2 \rfloor$ **downto** 1
2. **do** Max-Heapify(A, i)

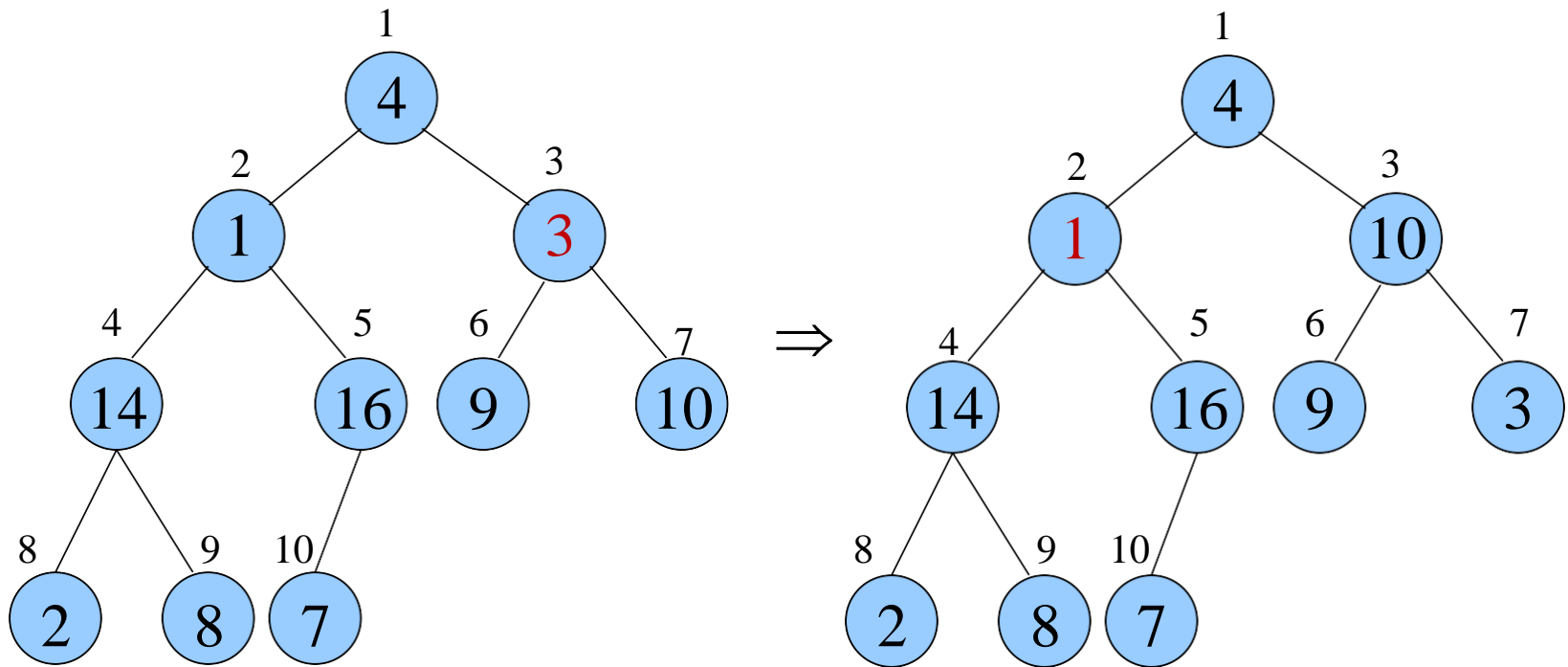
Build-Max-Heap: Example

A

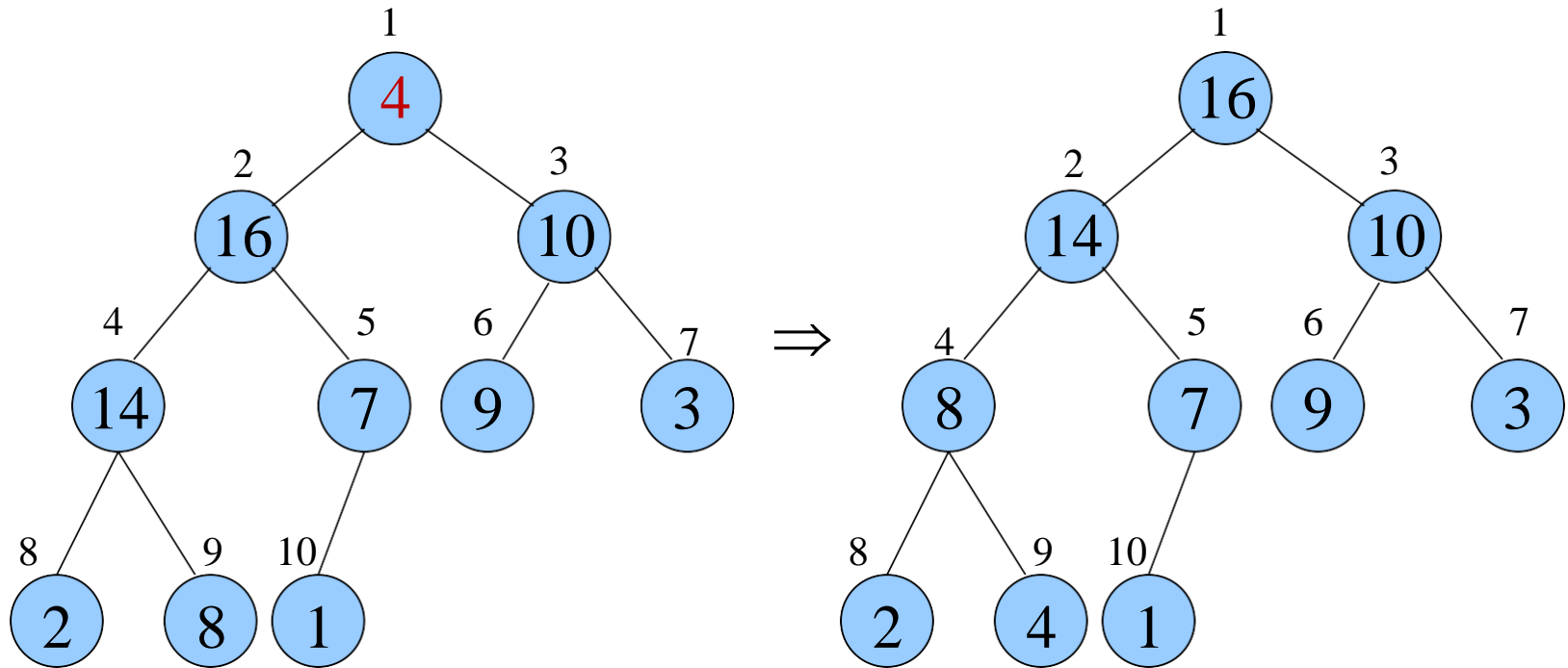
4	1	3	2	16	9	10	14	8	7
---	---	---	---	----	---	----	----	---	---



Build-Max-Heap: Example (cont.)



Build-Max-Heap: Example (cont.)



Build-Max-Heap: a simple upper bound

- Correctness: induction on i , all trees rooted at $m > i$ are heaps.
- Running time: makes $O(n)$ calls to Max-Heapify = $O(n \lg n)$
- This is good enough for an $O(n \lg n)$ bound on Heapsort, but sometimes we build heaps for other reasons

Build-max-Heap: a tighter analysis

Time of Heapify = $O(\text{height of subtree rooted at } i)$

An n -element heap has height $\lfloor \lg n \rfloor$ and at most $\lfloor n/2^{h+1} \rfloor$ nodes of any height h

$$\sum_{h=0}^{\lfloor \lg n \rfloor} \left\lfloor \frac{n}{2^{h+1}} \right\rfloor O(h) = O \left(n \sum_{h=0}^{\lfloor \lg n \rfloor} \frac{h}{2^h} \right)$$

$$\boxed{\sum_{h=0}^{\infty} \frac{h}{2^h} = \frac{1/2}{(1 - 1/2)^2} = 2} \rightarrow = O \left(n \sum_{h=0}^{\infty} \frac{h}{2^h} \right) = O(n) .$$

Quicksort

- Proposed by C.A.R. Hoare in 1962.
- Divide-and-conquer algorithm.
- Sorts “in place” (like insertion sort, but not like merge sort).
- Very practical (with tuning).
- Remarkably efficient on the average: its expected running time is $\Theta(n \lg n)$

Divide and conquer

Quicksort an n -element array:

- 1. Divide:** Partition the array into two subarrays around a **pivot** x such that elements in lower subarray $\leq x \leq$ elements in upper subarray.



- 2. Conquer:** Recursively sort the two subarrays.
- 3. Combine:** Trivial.

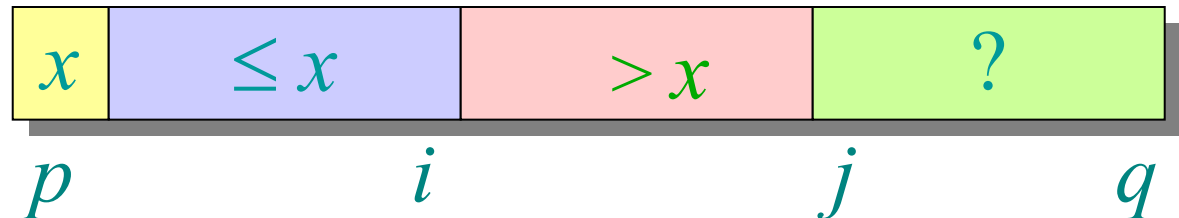
Key: *Linear-time partitioning subroutine.*

Partitioning subroutine

```
PARTITION( $A, p, q$ )  $\triangleright A[p \dots q]$   
   $x \leftarrow A[p]$   $\triangleright$  pivot =  $A[p]$   
   $i \leftarrow p$   
  for  $j \leftarrow p + 1$  to  $q$   
    do if  $A[j] \leq x$   
      then  $i \leftarrow i + 1$   
           exchange  $A[i] \leftrightarrow A[j]$   
  exchange  $A[p] \leftrightarrow A[i]$   
  return  $i$ 
```

Running time
= $O(n)$ for n
elements.

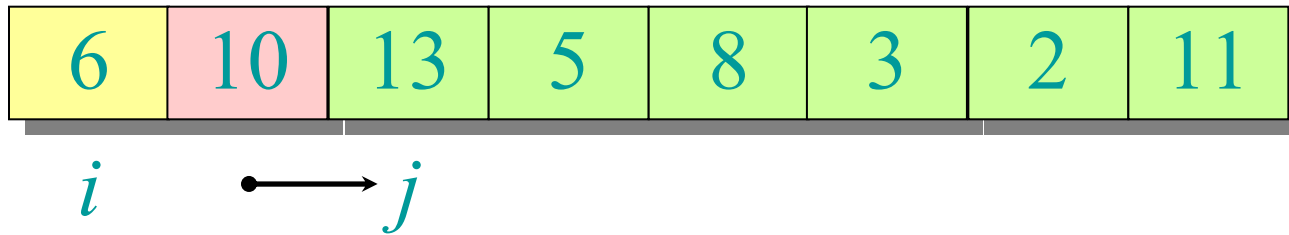
Invariant:



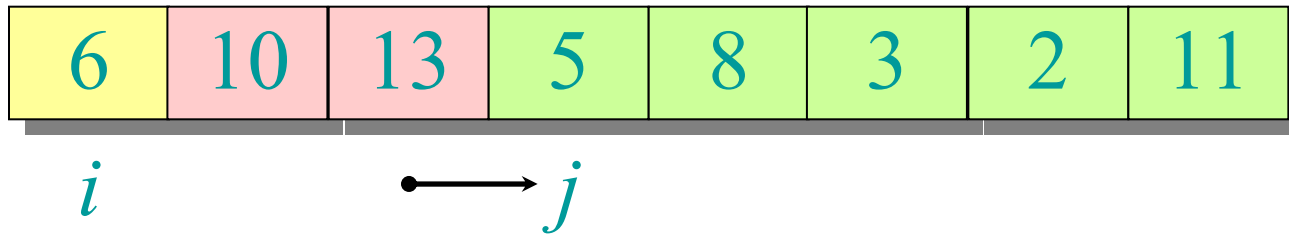
Example of partitioning

6	10	13	5	8	3	2	11
i	j						

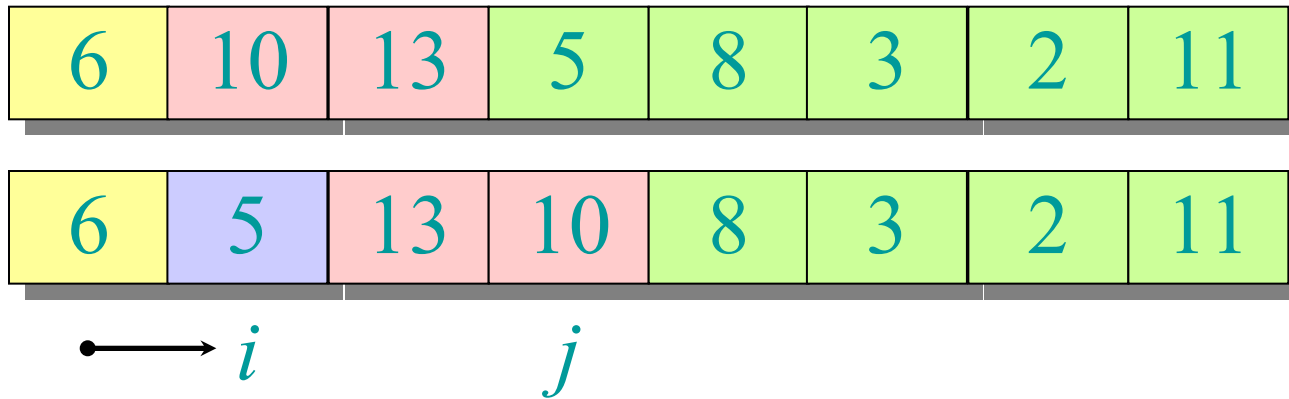
Example of partitioning



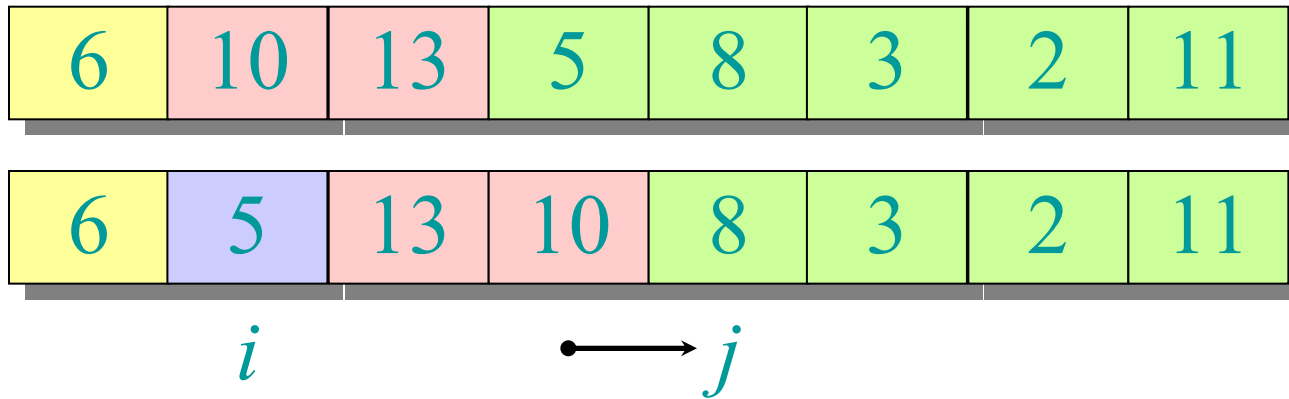
Example of partitioning



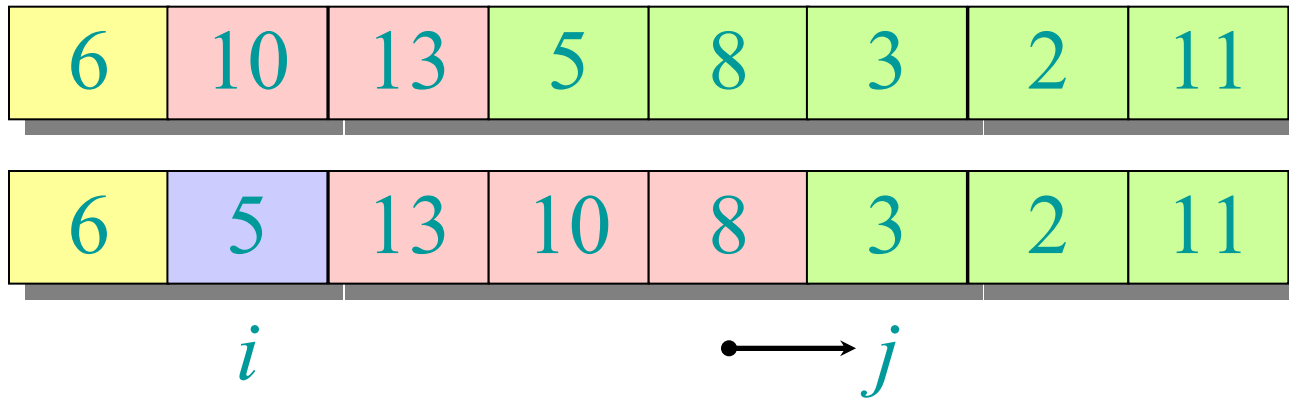
Example of partitioning



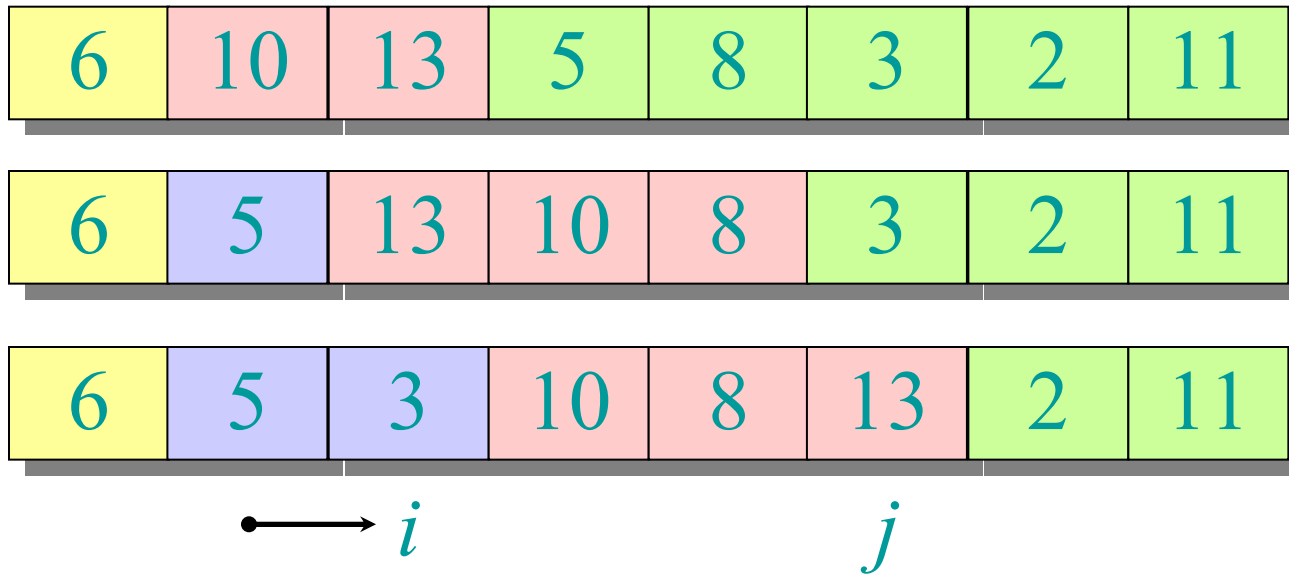
Example of partitioning



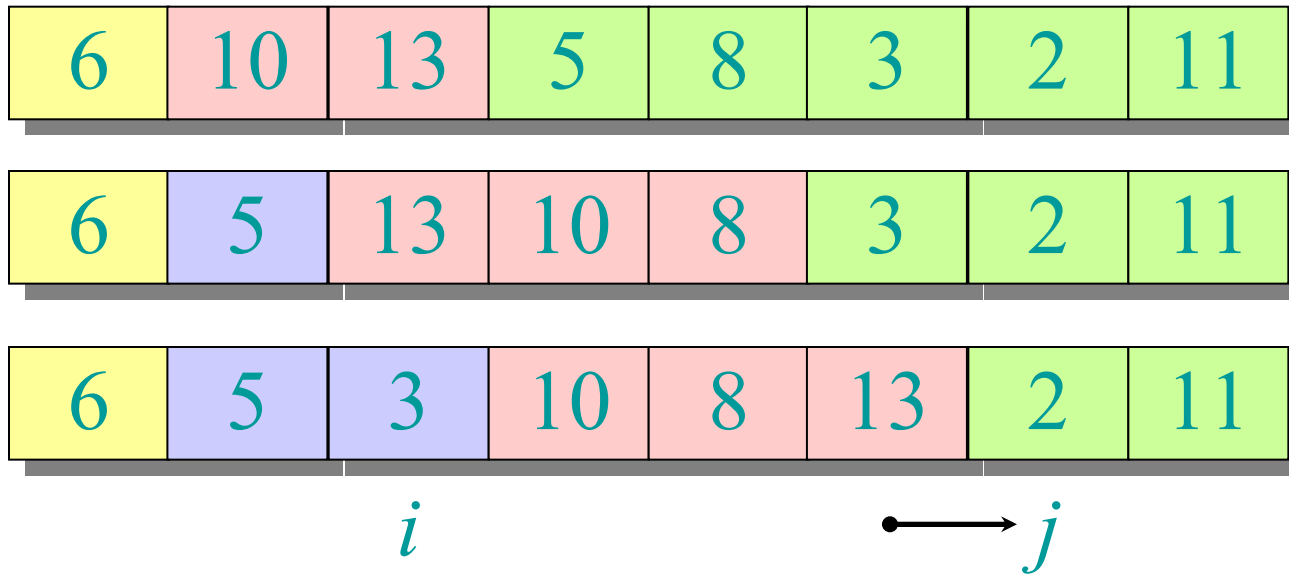
Example of partitioning



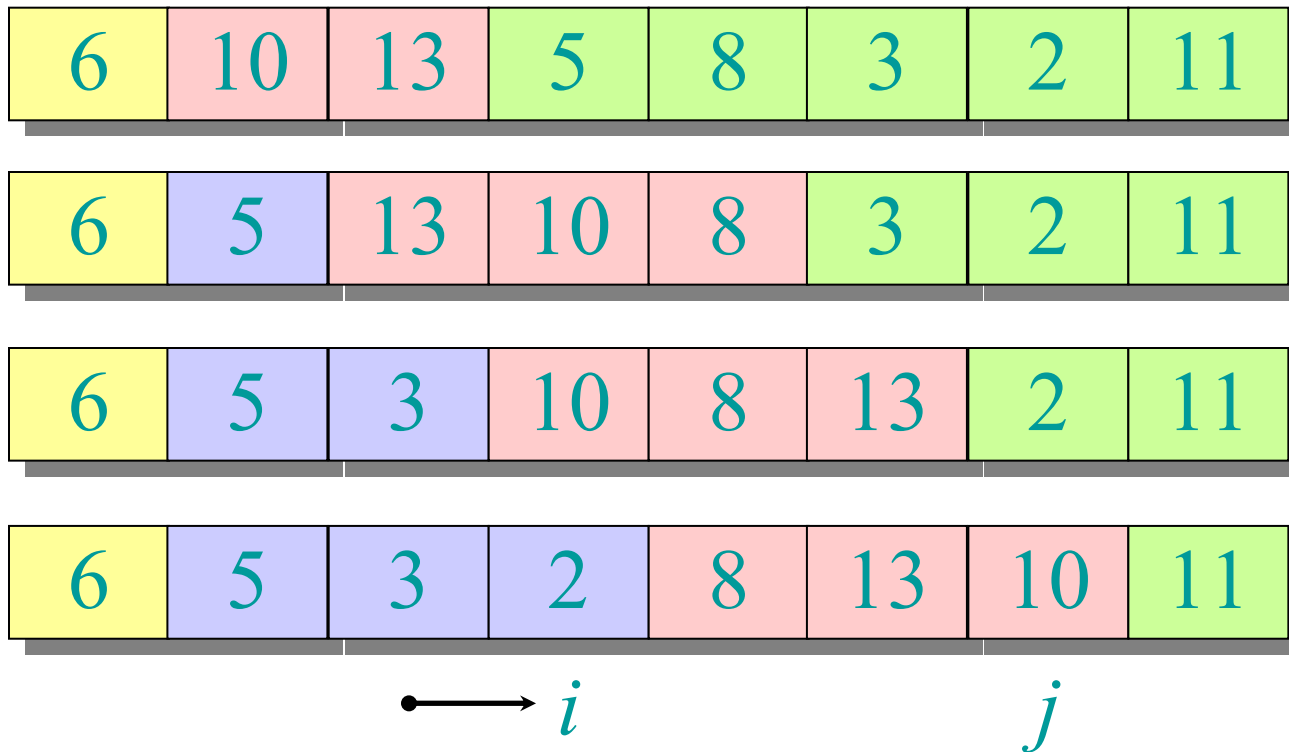
Example of partitioning



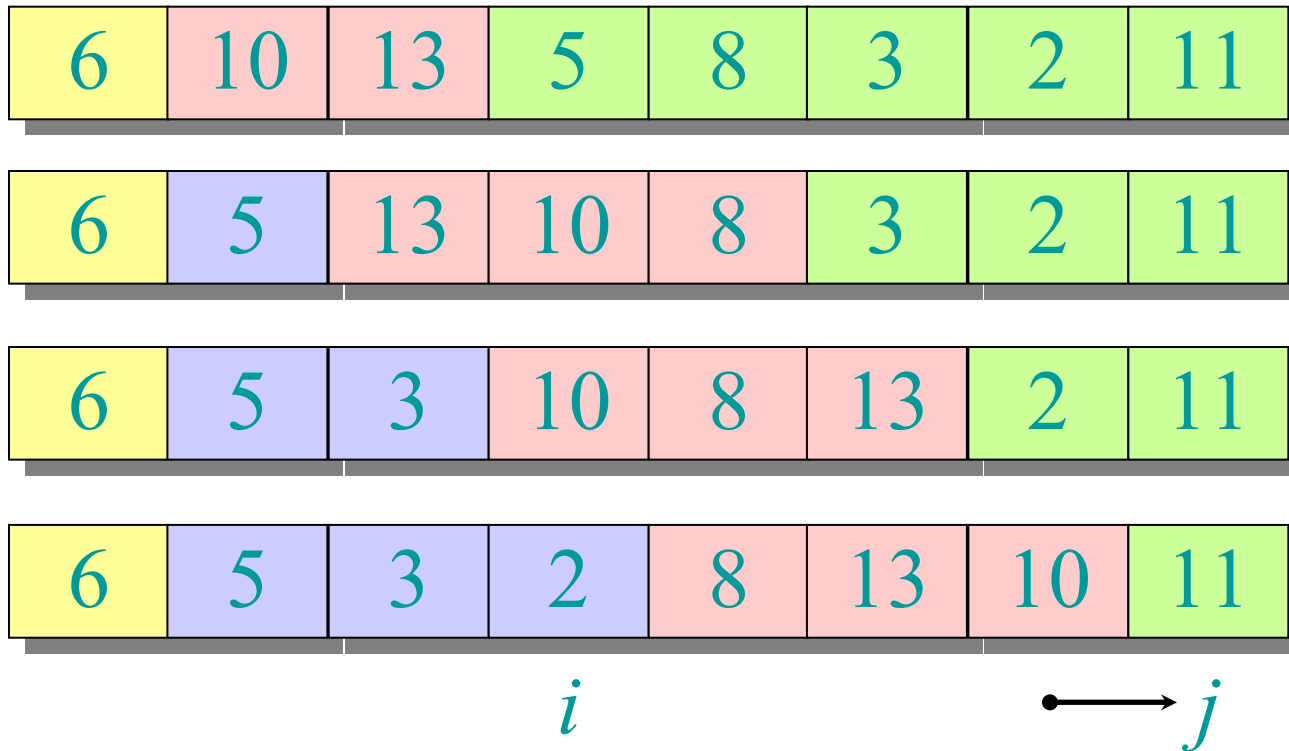
Example of partitioning



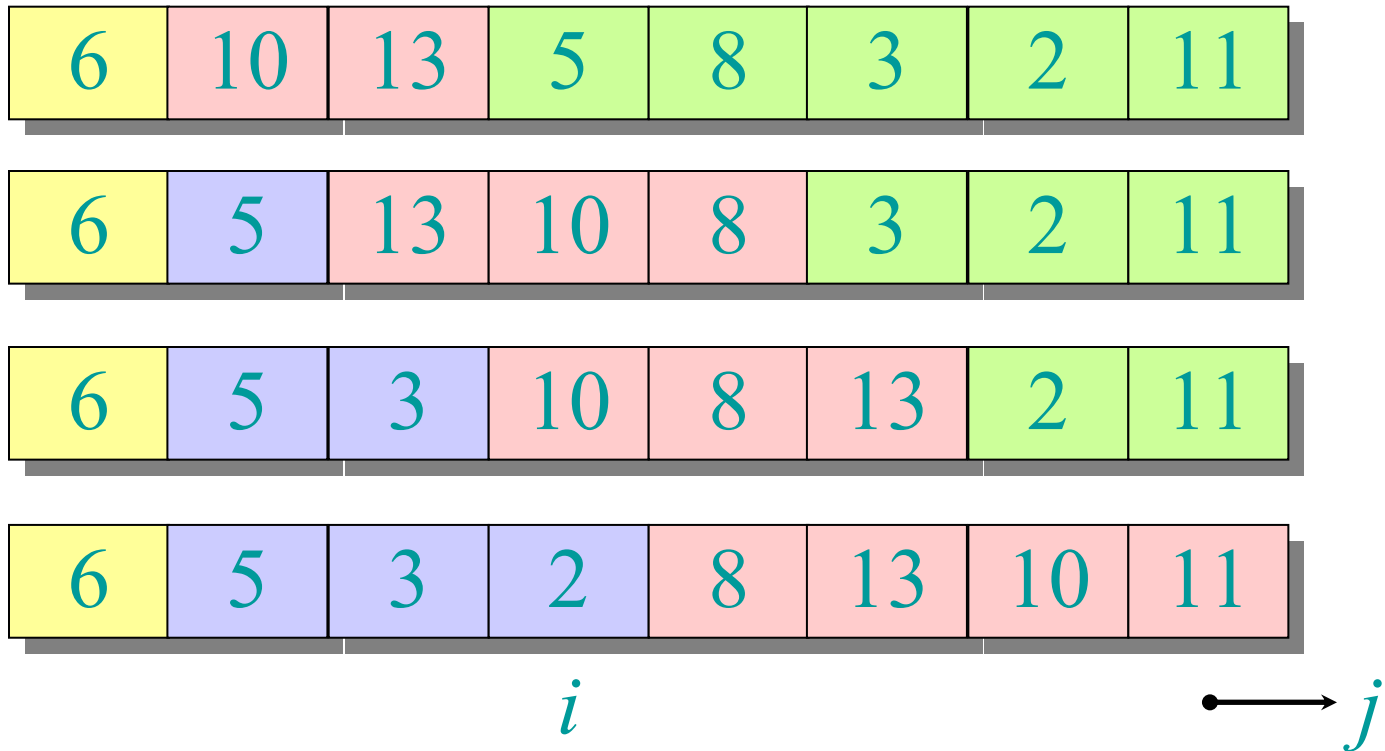
Example of partitioning



Example of partitioning



Example of partitioning



Example of partitioning

6	10	13	5	8	3	2	11
---	----	----	---	---	---	---	----

6	5	13	10	8	3	2	11
---	---	----	----	---	---	---	----

6	5	3	10	8	13	2	11
---	---	---	----	---	----	---	----

6	5	3	2	8	13	10	11
---	---	---	---	---	----	----	----

2	5	3	6	8	13	10	11
---	---	---	---	---	----	----	----

i

Pseudocode for quicksort

QUICKSORT(A, p, r)

if $p < r$

then $q \leftarrow \text{PARTITION}(A, p, r)$

 QUICKSORT($A, p, q-1$)

 QUICKSORT($A, q+1, r$)

Initial call: QUICKSORT($A, 1, n$)

Analysis of quicksort

- Assume all input elements are distinct.
- In practice, there are better partitioning algorithms for when duplicate input elements may exist.
- Let $T(n)$ = worst-case running time on an array of n elements.

Worst-case of quicksort

- Input sorted or reverse sorted.
- Partition around min or max element.
- One side of partition always has no elements.

$$T(n) = T(0) + T(n-1) + \Theta(n)$$

$$= \Theta(1) + T(n-1) + \Theta(n)$$

$$= T(n-1) + \Theta(n)$$

$$= \Theta(n^2) \quad (\textit{arithmetic series})$$

Worst-case recursion tree

$$T(n) = T(0) + T(n-1) + cn$$

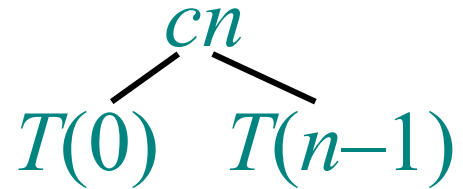
Worst-case recursion tree

$$T(n) = T(0) + T(n-1) + cn$$

$$T(n)$$

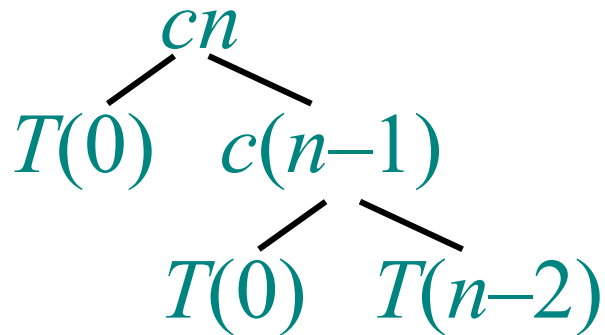
Worst-case recursion tree

$$T(n) = T(0) + T(n-1) + cn$$



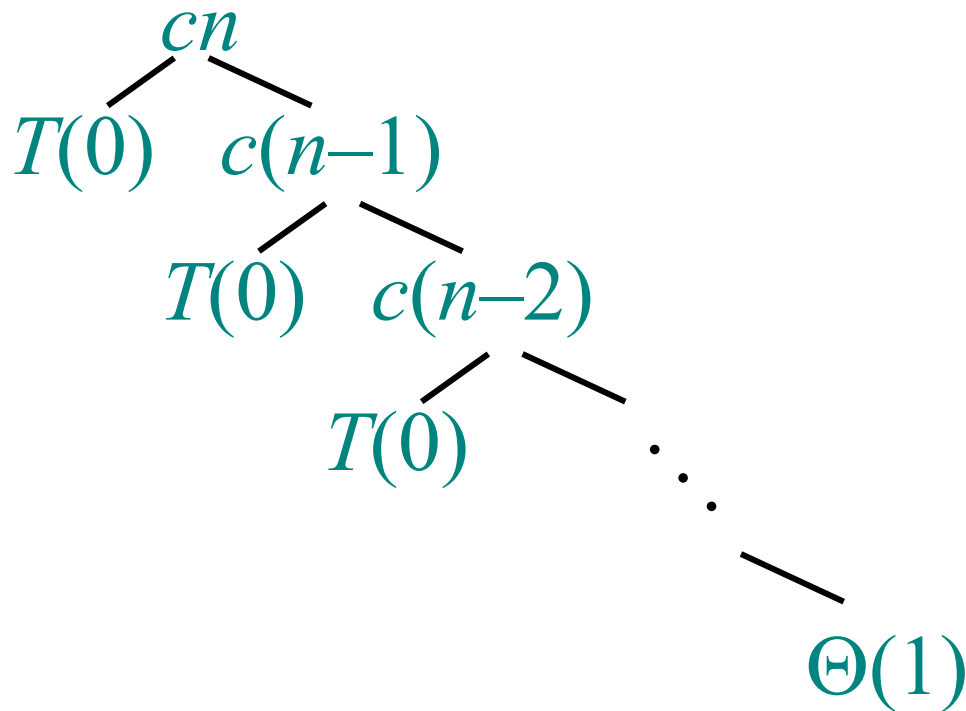
Worst-case recursion tree

$$T(n) = T(0) + T(n-1) + cn$$



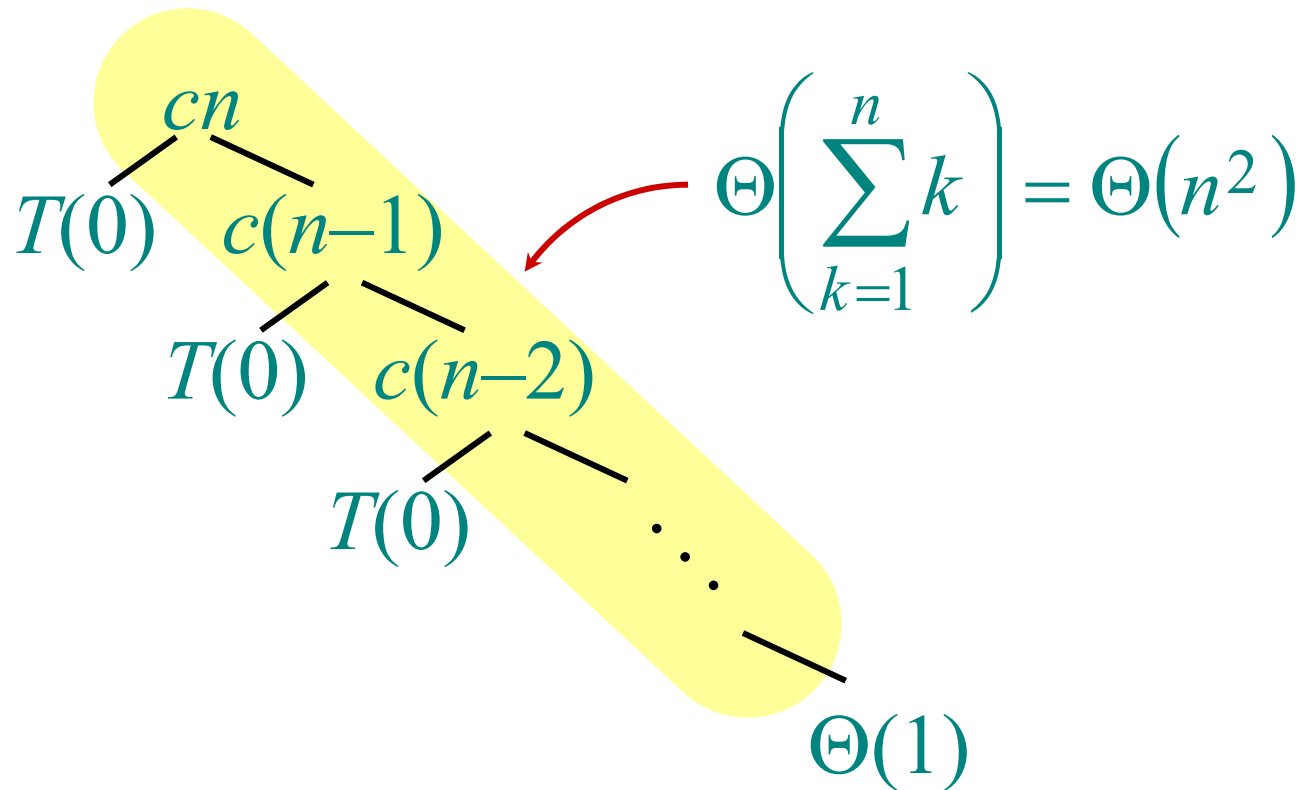
Worst-case recursion tree

$$T(n) = T(0) + T(n-1) + cn$$



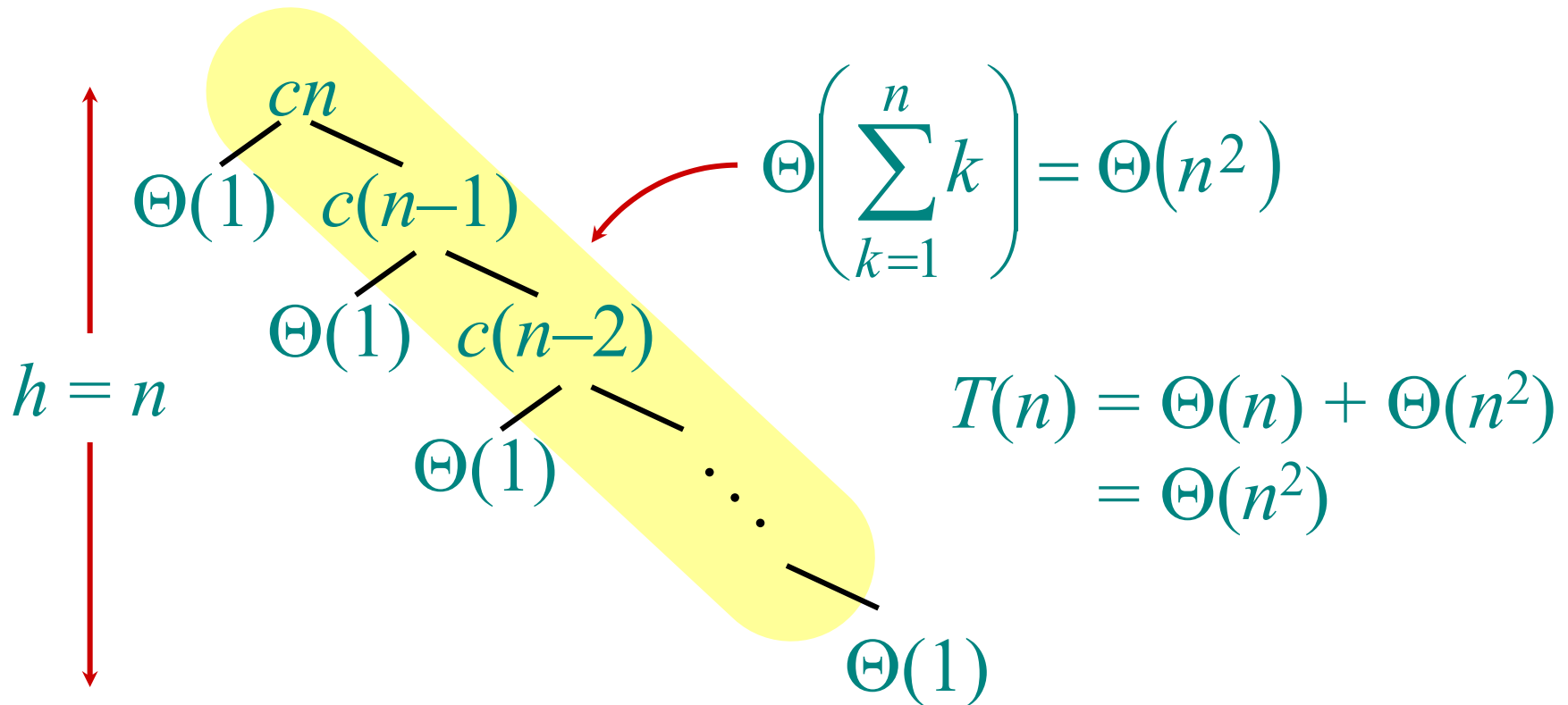
Worst-case recursion tree

$$T(n) = T(0) + T(n-1) + cn$$



Worst-case recursion tree

$$T(n) = T(0) + T(n-1) + cn$$



Best-case analysis

(For intuition only!)

If we're lucky, PARTITION splits the array evenly:

$$\begin{aligned} T(n) &= 2T(n/2) + \Theta(n) \\ &= \Theta(n \lg n) \quad (\text{same as merge sort}) \end{aligned}$$

What if the split is always $\frac{1}{10} : \frac{9}{10}$?

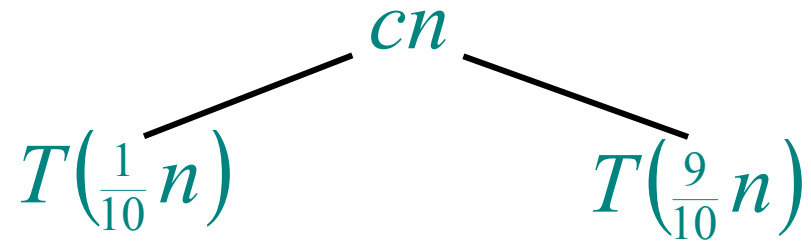
$$T(n) = T\left(\frac{1}{10}n\right) + T\left(\frac{9}{10}n\right) + \Theta(n)$$

What is the solution to this recurrence?

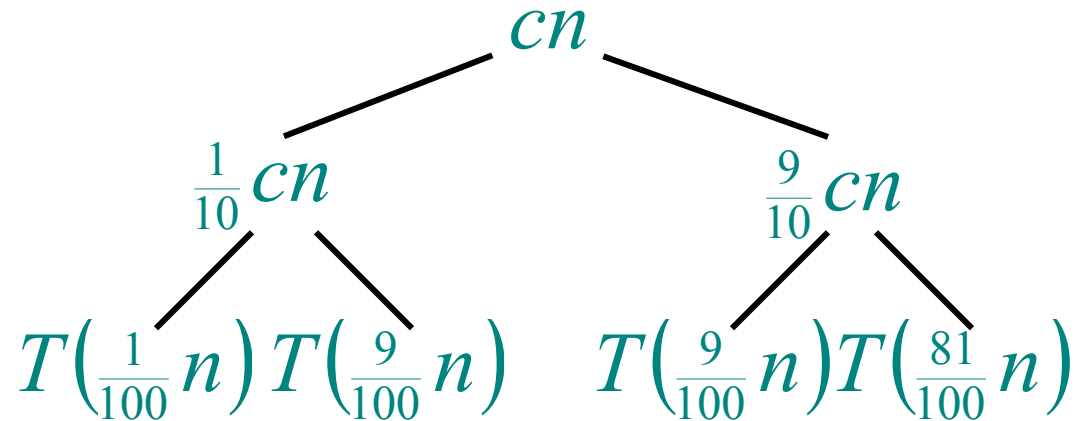
Analysis of “almost-best” case

$$T(n)$$

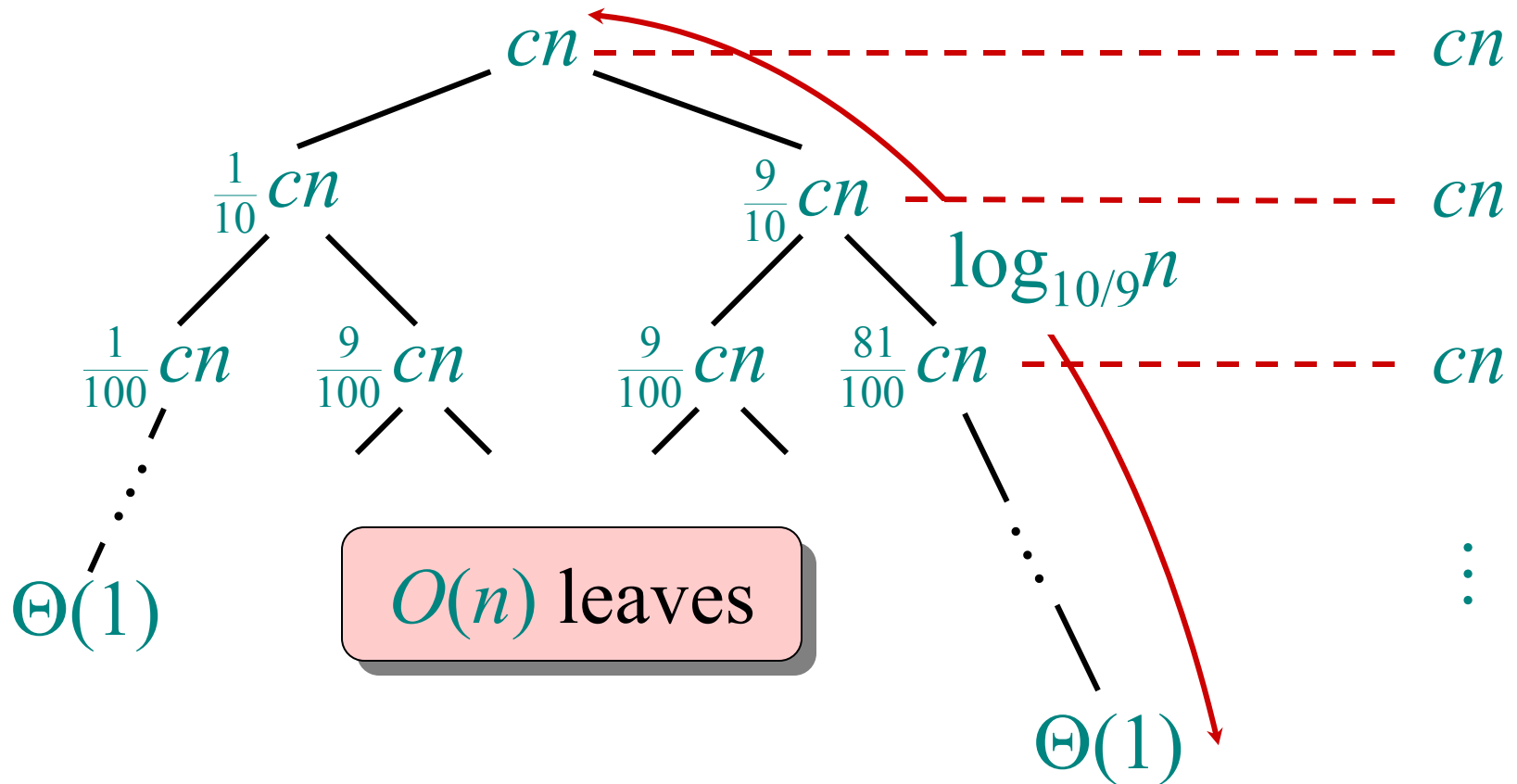
Analysis of “almost-best” case



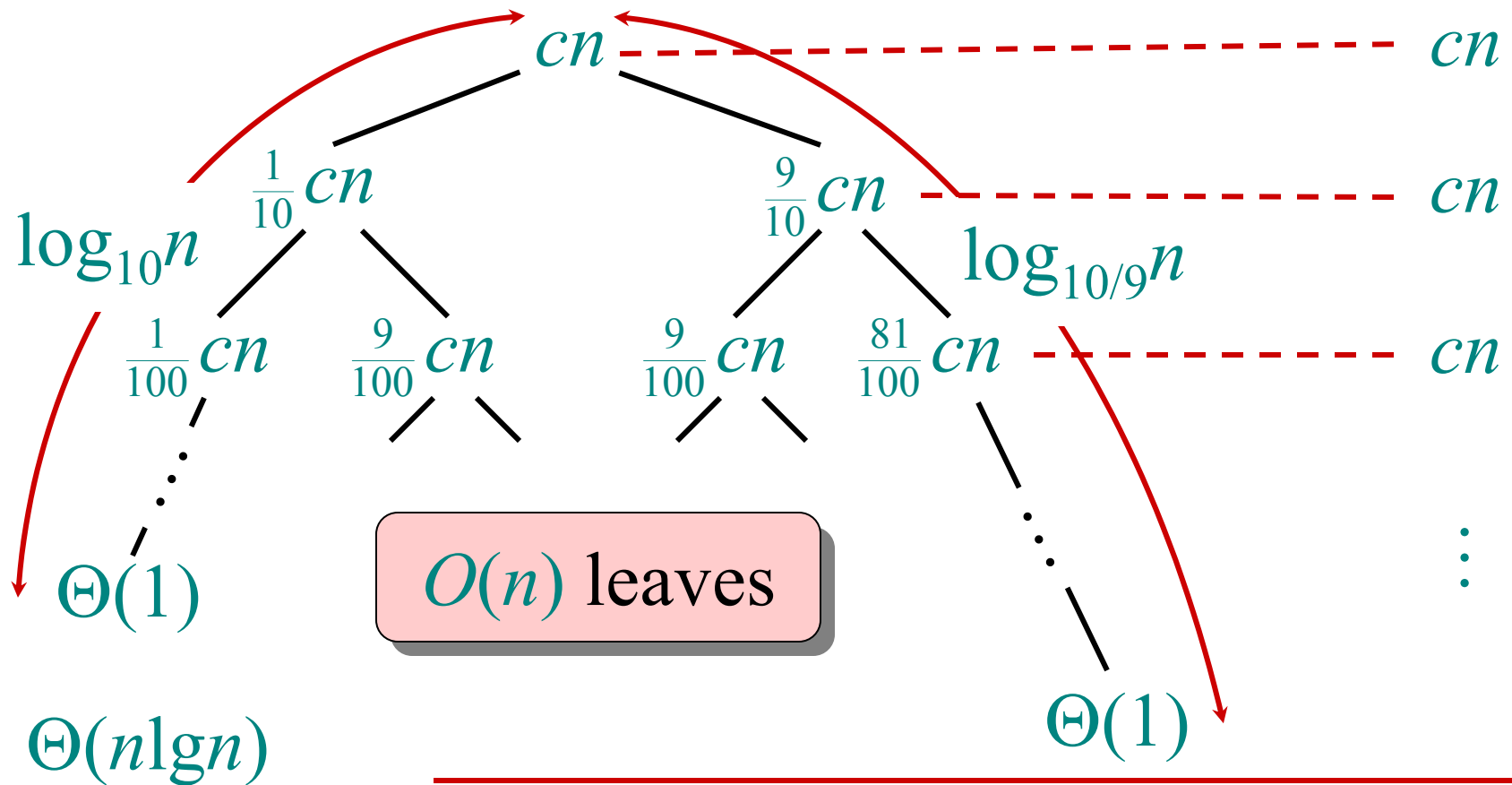
Analysis of “almost-best” case



Analysis of “almost-best” case



Analysis of “almost-best” case



$$cn \log_{10} n \leq T(n) \leq cn \log_{10/9} n + O(n)$$

More intuition

Suppose we alternate lucky, unlucky, lucky, unlucky, lucky,

$$L(n) = 2U(n/2) + \Theta(n) \quad \textit{lucky}$$

$$U(n) = L(n-1) + \Theta(n) \quad \textit{unlucky}$$

Solving:

$$\begin{aligned} L(n) &= 2(L(n/2 - 1) + \Theta(n/2)) + \Theta(n) \\ &= 2L(n/2 - 1) + \Theta(n) \\ &= \Theta(n \lg n) \end{aligned}$$

How can we make sure we are usually lucky?

Randomized quicksort

IDEA: Partition around a *random* element.

- Running time is independent of the input order.
- No assumptions need to be made about the input distribution.
- No specific input elicits the worst-case behavior.
- The worst case is determined only by the output of a random-number generator.

Randomized Quicksort

New “randomized” partitioning: swap before actually partitioning.

Randomized-Partition(A, p, r)

1. $i \leftarrow \text{Random}(p, r)$
2. exchange $A[p] \leftrightarrow A[i]$
3. return Partition(A, p, r)

Randomized-Quicksort(A, p, r)

1. **if** $p < r$
2. **then** $q \leftarrow \text{Randomized-Partition}(A, p, r)$
3. Randomized-Quicksort($A, p, q-1$)
4. Randomized-Quicksort($A, q+1, r$)

Randomized quicksort analysis

Let $T(n)$ = the random variable for the running time of randomized quicksort on an input of size n , assuming random numbers are independent.

For $k = 0, 1, \dots, n-1$, define the *indicator random variable*

$$X_k = \begin{cases} 1 & \text{if PARTITION generates a } k : n-k-1 \text{ split,} \\ 0 & \text{otherwise.} \end{cases}$$

$E[X_k] = \Pr\{X_k = 1\} = 1/n$, since all splits are equally likely, assuming elements are distinct.

Analysis (continued)

$$T(n) = \begin{cases} T(0) + T(n-1) + \Theta(n) & \text{if } 0 : n-1 \text{ split,} \\ T(1) + T(n-2) + \Theta(n) & \text{if } 1 : n-2 \text{ split,} \\ \vdots & \\ T(n-1) + T(0) + \Theta(n) & \text{if } n-1 : 0 \text{ split,} \end{cases}$$
$$= \sum_{k=0}^{n-1} X_k (T(k) + T(n-k-1) + \Theta(n)).$$

Calculating expectation

$$E[T(n)] = E\left[\sum_{k=0}^{n-1} X_k (T(k) + T(n-k-1) + \Theta(n))\right]$$

Take expectations of both sides.

Calculating expectation

$$\begin{aligned} E[T(n)] &= E\left[\sum_{k=0}^{n-1} X_k (T(k) + T(n-k-1) + \Theta(n))\right] \\ &= \sum_{k=0}^{n-1} E[X_k (T(k) + T(n-k-1) + \Theta(n))] \end{aligned}$$

Linearity of expectation.

Calculating expectation

$$\begin{aligned} E[T(n)] &= E\left[\sum_{k=0}^{n-1} X_k (T(k) + T(n-k-1) + \Theta(n))\right] \\ &= \sum_{k=0}^{n-1} E[X_k (T(k) + T(n-k-1) + \Theta(n))] \\ &= \sum_{k=0}^{n-1} E[X_k] \cdot E[T(k) + T(n-k-1) + \Theta(n)] \end{aligned}$$

Independence of X_k from other random choices.

Calculating expectation

$$\begin{aligned} E[T(n)] &= E\left[\sum_{k=0}^{n-1} X_k (T(k) + T(n-k-1) + \Theta(n))\right] \\ &= \sum_{k=0}^{n-1} E[X_k (T(k) + T(n-k-1) + \Theta(n))] \\ &= \sum_{k=0}^{n-1} E[X_k] \cdot E[T(k) + T(n-k-1) + \Theta(n)] \\ &= \frac{1}{n} \sum_{k=0}^{n-1} E[T(k)] + \frac{1}{n} \sum_{k=0}^{n-1} E[T(n-k-1)] + \frac{1}{n} \sum_{k=0}^{n-1} \Theta(n) \end{aligned}$$

Linearity of expectation; $E[X_k] = 1/n$.

Calculating expectation

$$\begin{aligned} E[T(n)] &= E\left[\sum_{k=0}^{n-1} X_k (T(k) + T(n-k-1) + \Theta(n))\right] \\ &= \sum_{k=0}^{n-1} E[X_k (T(k) + T(n-k-1) + \Theta(n))] \\ &= \sum_{k=0}^{n-1} E[X_k] \cdot E[T(k) + T(n-k-1) + \Theta(n)] \\ &= \frac{1}{n} \sum_{k=0}^{n-1} E[T(k)] + \frac{1}{n} \sum_{k=0}^{n-1} E[T(n-k-1)] + \frac{1}{n} \sum_{k=0}^{n-1} \Theta(n) \\ &= \frac{2}{n} \sum_{k=1}^{n-1} E[T(k)] + \Theta(n) \end{aligned}$$

Summations have identical terms.

Hairy recurrence

$$E[T(n)] = \frac{2}{n} \sum_{k=2}^{n-1} E[T(k)] + \Theta(n)$$

(The $k = 0, 1$ terms can be absorbed in the $\Theta(n)$.)

Prove: $E[T(n)] \leq an \lg n$ for constant $a > 0$.

- Choose a large enough so that $an \lg n$ dominates $E[T(n)]$ for sufficiently small $n \geq 2$.

Use fact: $\sum_{k=2}^{n-1} k \lg k \leq \frac{1}{2} n^2 \lg n - \frac{1}{8} n^2$ (exercise).

Substitution method

$$E[T(n)] \leq \frac{2}{n} \sum_{k=2}^{n-1} ak \lg k + \Theta(n)$$

Substitute inductive hypothesis.

Substitution method

$$\begin{aligned} E[T(n)] &\leq \frac{2}{n} \sum_{k=2}^{n-1} ak \lg k + \Theta(n) \\ &\leq \frac{2a}{n} \left(\frac{1}{2} n^2 \lg n - \frac{1}{8} n^2 \right) + \Theta(n) \end{aligned}$$

Use fact.

Substitution method

$$\begin{aligned} E[T(n)] &\leq \frac{2}{n} \sum_{k=2}^{n-1} ak \lg k + \Theta(n) \\ &\leq \frac{2a}{n} \left(\frac{1}{2} n^2 \lg n - \frac{1}{8} n^2 \right) + \Theta(n) \\ &= an \lg n - \left(\frac{an}{4} - \Theta(n) \right) \end{aligned}$$

Express as *desired – residual*.

Substitution method

$$\begin{aligned} E[T(n)] &\leq \frac{2}{n} \sum_{k=2}^{n-1} ak \lg k + \Theta(n) \\ &= \frac{2a}{n} \left(\frac{1}{2} n^2 \lg n - \frac{1}{8} n^2 \right) + \Theta(n) \\ &= an \lg n - \left(\frac{an}{4} - \Theta(n) \right) \\ &\leq an \lg n, \end{aligned}$$

if a is chosen large enough so that $an/4$ dominates the $\Theta(n)$.

Quicksort in practice

- Quicksort is a great general-purpose sorting algorithm.
- Quicksort is typically over twice as fast as merge sort.
- Quicksort can benefit substantially from *code tuning*.
- Quicksort behaves well even with caching and virtual memory.

How fast can we sort?

All the sorting algorithms we have seen so far are *comparison sorts*: only use comparisons to determine the relative order of elements.

- *E.g.*, insertion sort, merge sort, quicksort, heapsort.

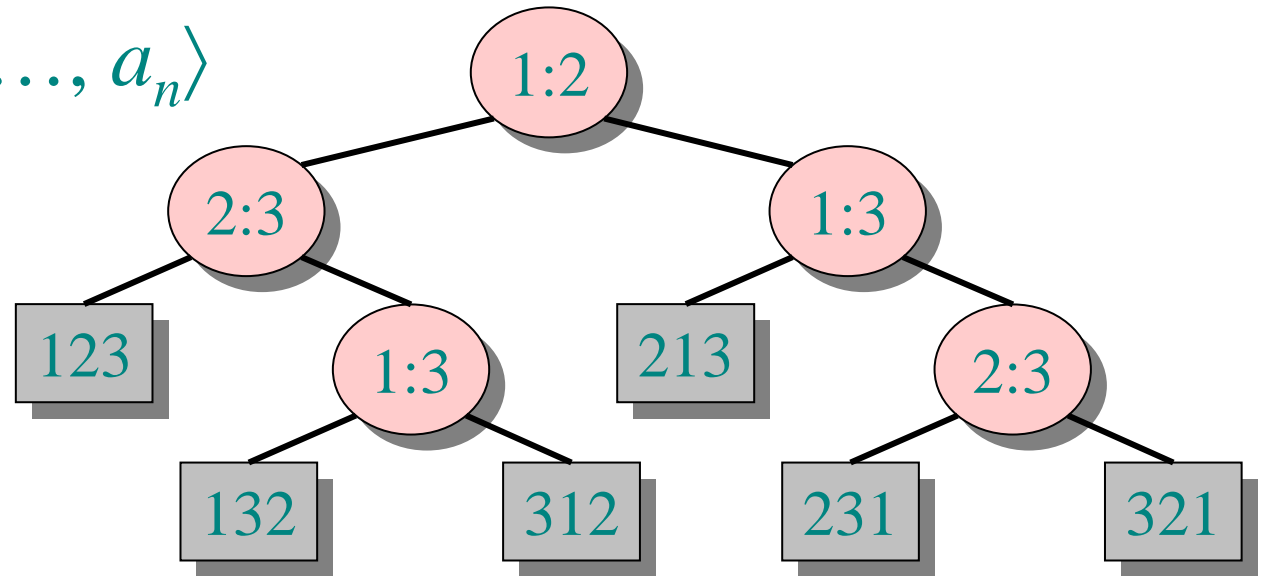
The best worst-case running time that we've seen for comparison sorting is $O(n \lg n)$.

Is $O(n \lg n)$ the best we can do?

Decision trees can help us answer this question.

Decision-tree example

Sort $\langle a_1, a_2, \dots, a_n \rangle$

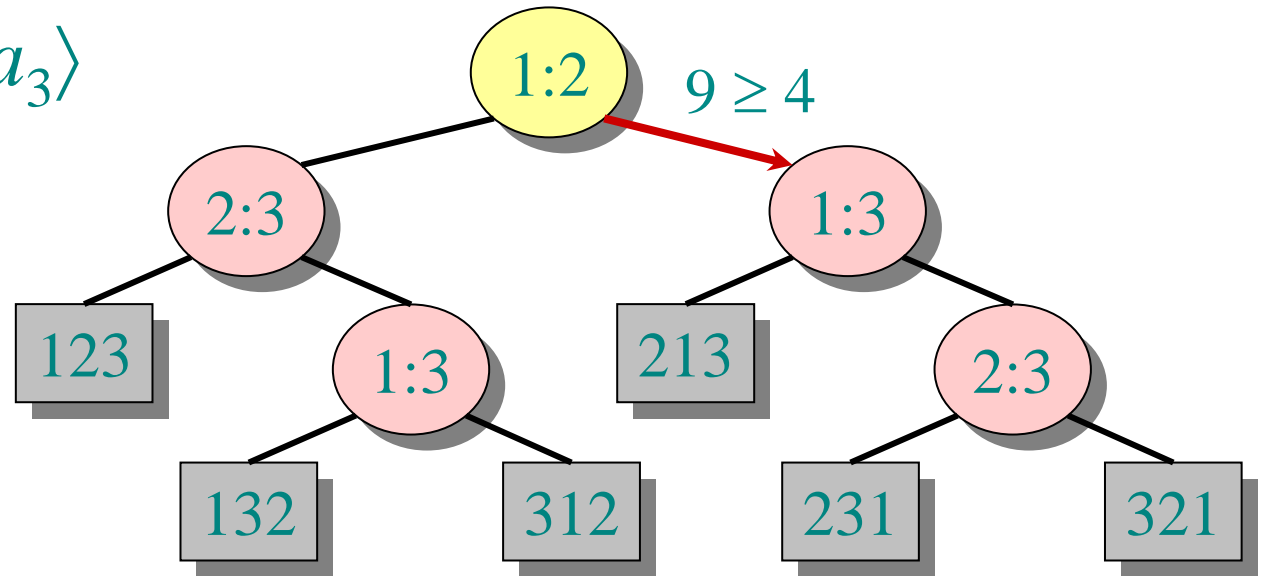


Each internal node is labeled $i:j$ for $i, j \in \{1, 2, \dots, n\}$.

- The left subtree shows subsequent comparisons if $a_i \leq a_j$.
- The right subtree shows subsequent comparisons if $a_i \geq a_j$.

Decision-tree example

Sort $\langle a_1, a_2, a_3 \rangle$
 $= \langle 9, 4, 6 \rangle$:

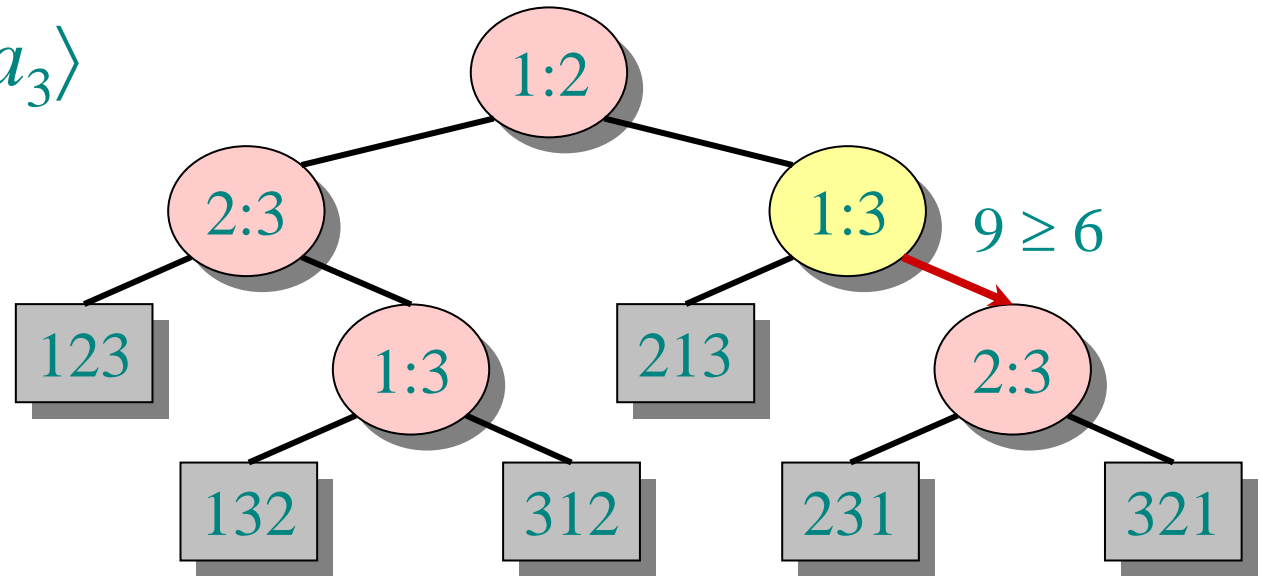


Each internal node is labeled $i:j$ for $i, j \in \{1, 2, \dots, n\}$.

- The left subtree shows subsequent comparisons if $a_i \leq a_j$.
- The right subtree shows subsequent comparisons if $a_i \geq a_j$.

Decision-tree example

Sort $\langle a_1, a_2, a_3 \rangle$
 $= \langle 9, 4, 6 \rangle$:

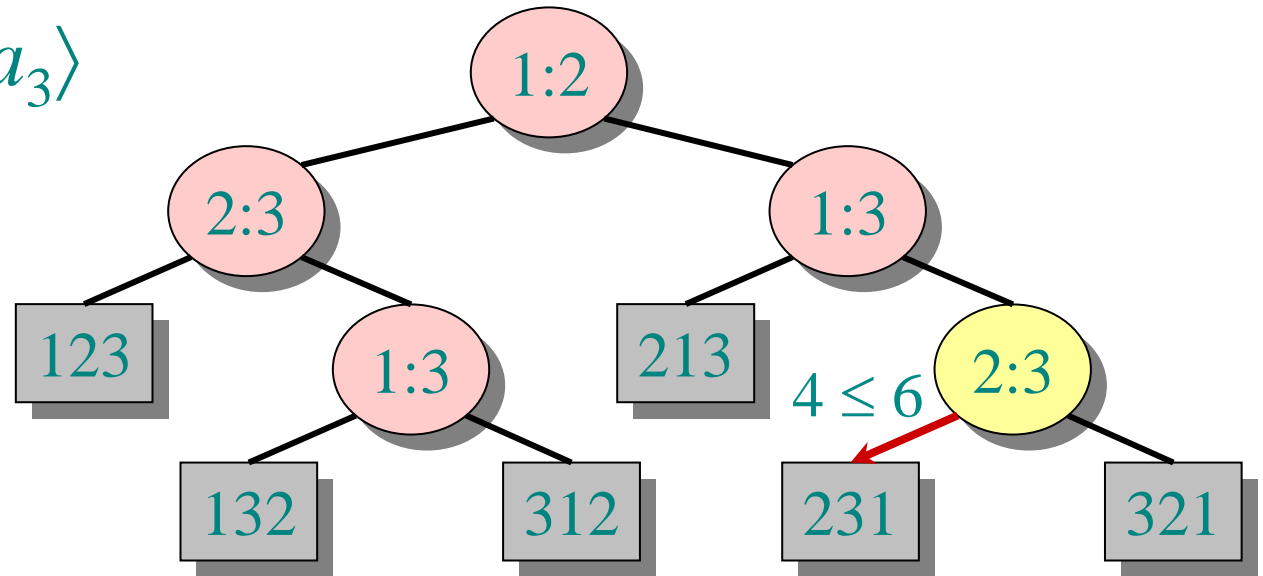


Each internal node is labeled $i:j$ for $i, j \in \{1, 2, \dots, n\}$.

- The left subtree shows subsequent comparisons if $a_i \leq a_j$.
- The right subtree shows subsequent comparisons if $a_i \geq a_j$.

Decision-tree example

Sort $\langle a_1, a_2, a_3 \rangle$
 $= \langle 9, 4, 6 \rangle$:

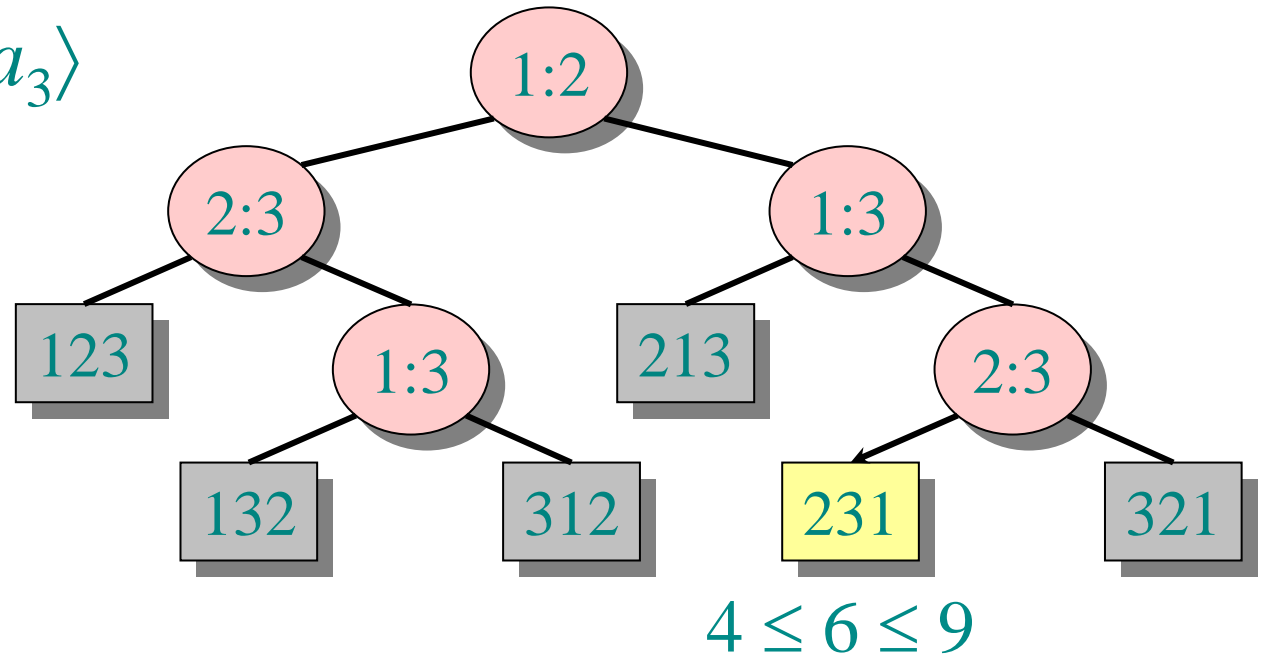


Each internal node is labeled $i:j$ for $i, j \in \{1, 2, \dots, n\}$.

- The left subtree shows subsequent comparisons if $a_i \leq a_j$.
- The right subtree shows subsequent comparisons if $a_i \geq a_j$.

Decision-tree example

Sort $\langle a_1, a_2, a_3 \rangle$
 $= \langle 9, 4, 6 \rangle$:



Each leaf contains a permutation $\langle \pi(1), \pi(2), \dots, \pi(n) \rangle$ to indicate that the ordering $a_{\pi(1)} \leq a_{\pi(2)} \leq \dots \leq a_{\pi(n)}$ has been established.

Decision-tree model

A decision tree can model the execution of any comparison sort:

- One tree for each input size n .
- View the algorithm as splitting whenever it compares two elements.
- The tree contains the comparisons along all possible instruction traces.
- The running time of the algorithm = the length of the path taken.
- Worst-case running time = height of tree.


Lower bound for decision-tree sorting

Theorem. Any decision tree that can sort n elements must have height $\Omega(n \lg n)$.

Proof. The tree must contain $\geq n!$ leaves, since there are $n!$ possible permutations. A height- h binary tree has $\leq 2^h$ leaves. Thus, $n! \leq 2^h$.

$$\begin{aligned} \therefore h &\geq \lg(n!) && (\lg \text{ is mono. increasing}) \\ &\geq \lg((n/e)^n) && (\text{Stirling's formula}) \\ &= n \lg n - n \lg e \\ &= \Omega(n \lg n). \quad \square \end{aligned}$$

Lower bound for comparison sorting

Corollary. Heapsort and merge sort are asymptotically optimal comparison sorting algorithms. 

Sorting in linear time

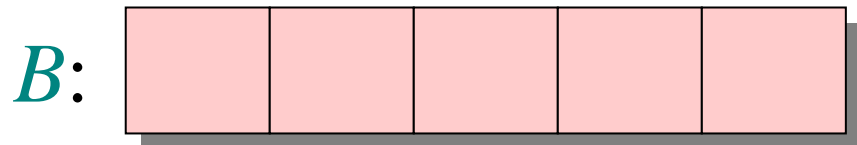
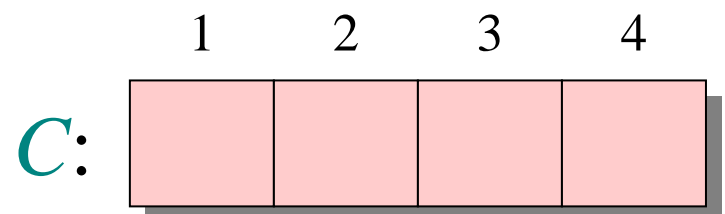
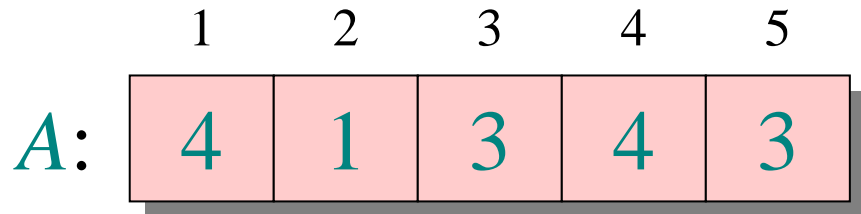
Counting sort: No comparisons between elements.

- *Input:* $A[1 \dots n]$, where $A[j] \in \{1, 2, \dots, k\}$.
- *Output:* $B[1 \dots n]$, sorted.
- *Auxiliary storage:* $C[1 \dots k]$.

Counting sort

```
for  $i \leftarrow 1$  to  $k$   
    do  $C[i] \leftarrow 0$   
for  $j \leftarrow 1$  to  $n$   
    do  $C[A[j]] \leftarrow C[A[j]] + 1$      $\triangleright C[i] = |\{\text{key} = i\}|$   
for  $i \leftarrow 2$  to  $k$   
    do  $C[i] \leftarrow C[i] + C[i-1]$      $\triangleright C[i] = |\{\text{key} \leq i\}|$   
for  $j \leftarrow n$  downto  $1$   
    do  $B[C[A[j]]] \leftarrow A[j]$   
         $C[A[j]] \leftarrow C[A[j]] - 1$ 
```

Counting-sort example



Loop 1

	1	2	3	4	5
<i>A</i> :	4	1	3	4	3

	1	2	3	4
<i>C</i> :	0	0	0	0

<i>B</i> :					
------------	--	--	--	--	--

for $i \leftarrow 1$ **to** k
 do $C[i] \leftarrow 0$

Loop 2

	1	2	3	4	5
<i>A</i> :	4	1	3	4	3

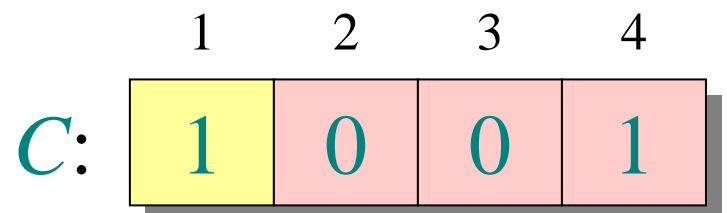
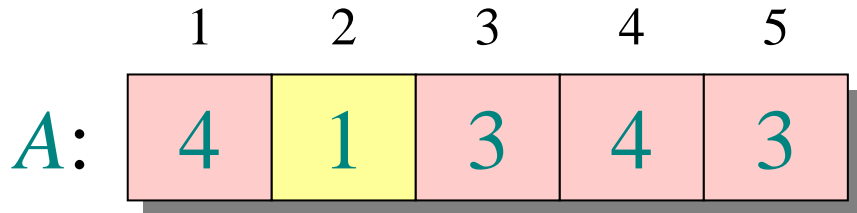
	1	2	3	4
<i>C</i> :	0	0	0	1

<i>B</i> :					
------------	--	--	--	--	--

for $j \leftarrow 1$ **to** n

do $C[A[j]] \leftarrow C[A[j]] + 1$ $\triangleright C[i] = |\{\text{key} = i\}|$

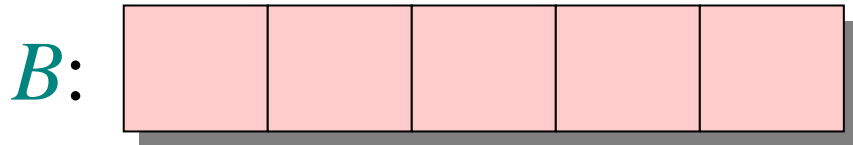
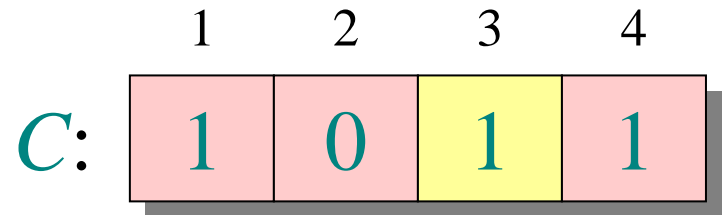
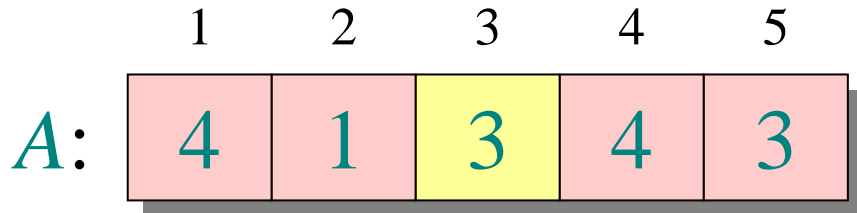
Loop 2



for $j \leftarrow 1$ **to** n

do $C[A[j]] \leftarrow C[A[j]] + 1 \quad \triangleright C[i] = |\{\text{key} = i\}|$

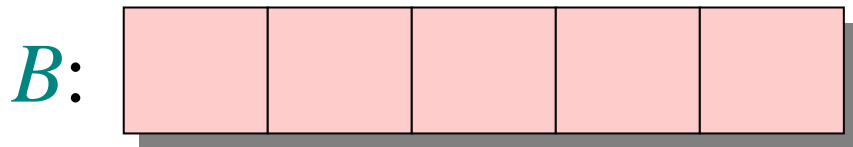
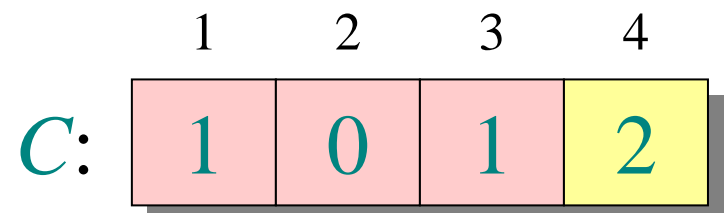
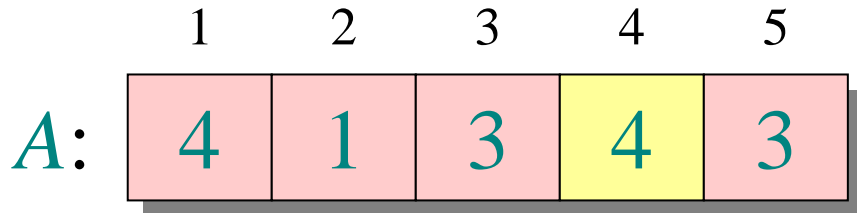
Loop 2



for $j \leftarrow 1$ **to** n

do $C[A[j]] \leftarrow C[A[j]] + 1$ $\triangleright C[i] = |\{\text{key} = i\}|$

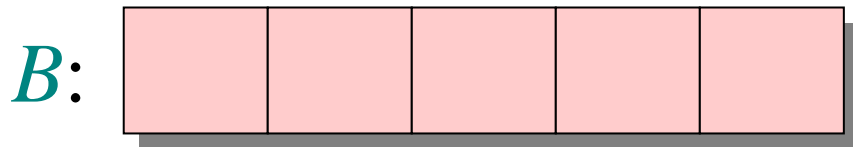
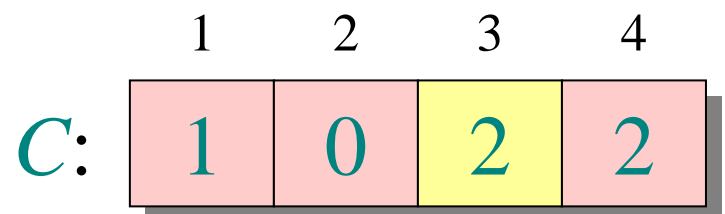
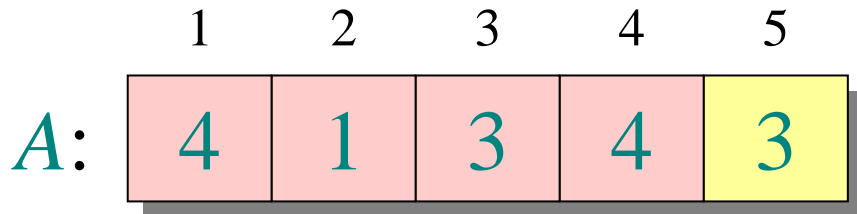
Loop 2



for $j \leftarrow 1$ **to** n

do $C[A[j]] \leftarrow C[A[j]] + 1$ $\triangleright C[i] = |\{\text{key} = i\}|$

Loop 2



for $j \leftarrow 1$ **to** n

do $C[A[j]] \leftarrow C[A[j]] + 1$ $\triangleright C[i] = |\{\text{key} = i\}|$

Loop 3

	1	2	3	4	5
<i>A</i> :	4	1	3	4	3

	1	2	3	4
<i>C</i> :	1	0	2	2

<i>B</i> :					
------------	--	--	--	--	--

<i>C'</i> :	1	1	2	2
-------------	---	---	---	---

for $i \leftarrow 2$ **to** k

do $C[i] \leftarrow C[i] + C[i-1]$

$\triangleright C[i] = |\{\text{key} \leq i\}|$

Loop 3

	1	2	3	4	5
<i>A</i> :	4	1	3	4	3

	1	2	3	4
<i>C</i> :	1	0	2	2

<i>B</i> :					
------------	--	--	--	--	--

<i>C'</i> :	1	1	3	2
-------------	---	---	---	---

for $i \leftarrow 2$ **to** k

do $C[i] \leftarrow C[i] + C[i-1]$

$\triangleright C[i] = |\{\text{key} \leq i\}|$

Loop 3

	1	2	3	4	5
<i>A</i> :	4	1	3	4	3

	1	2	3	4
<i>C</i> :	1	0	2	2

<i>B</i> :					
------------	--	--	--	--	--

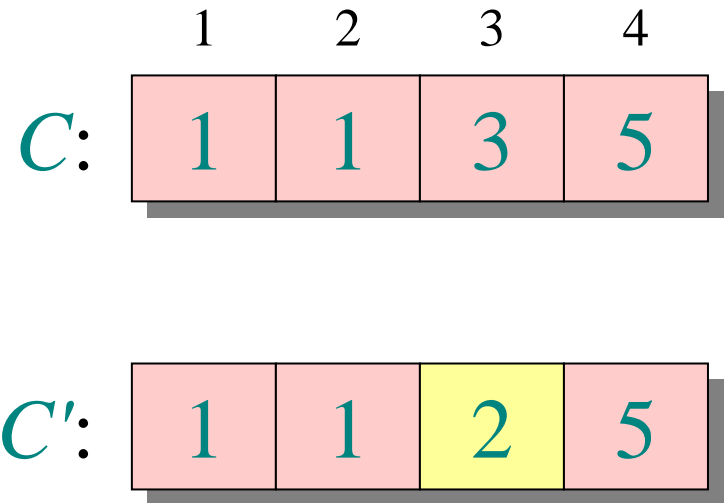
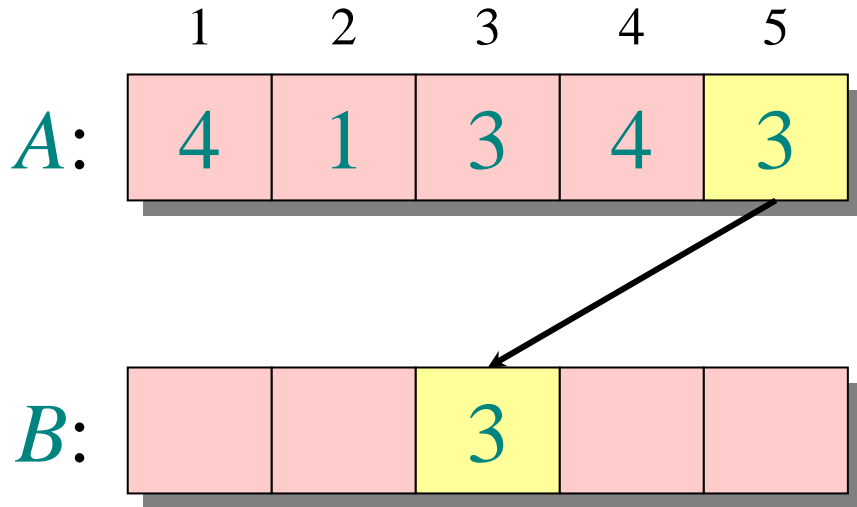
<i>C'</i> :	1	1	3	5
-------------	---	---	---	---

for $i \leftarrow 2$ **to** k

do $C[i] \leftarrow C[i] + C[i-1]$

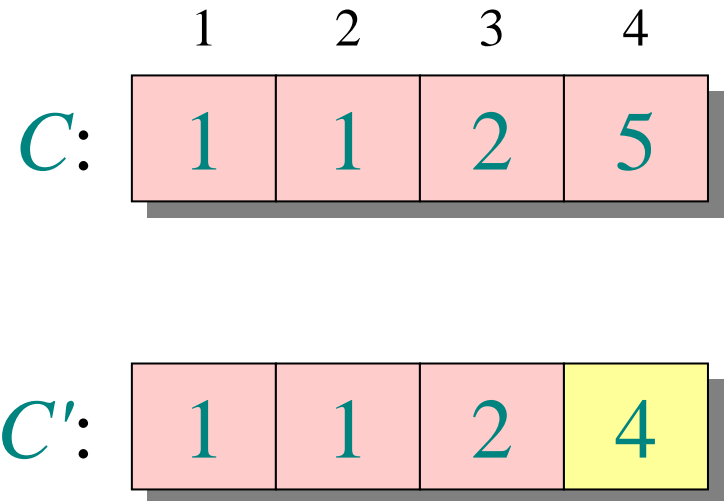
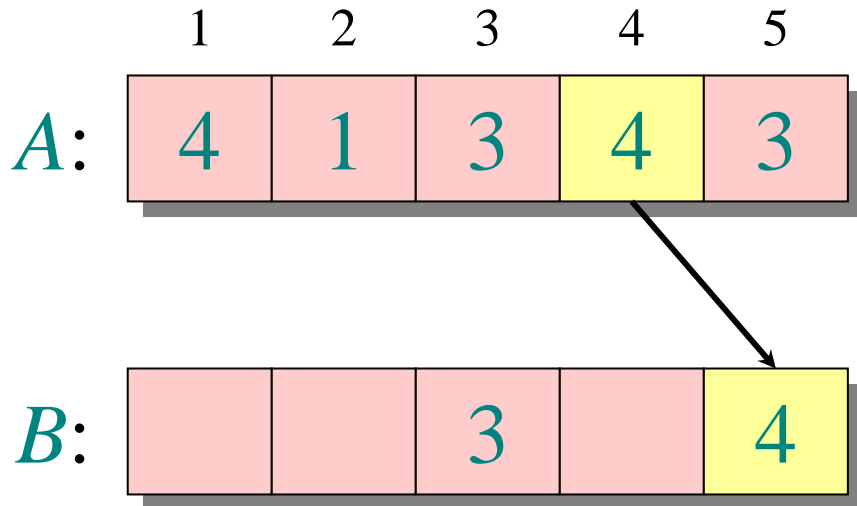
$\triangleright C[i] = |\{\text{key} \leq i\}|$

Loop 4



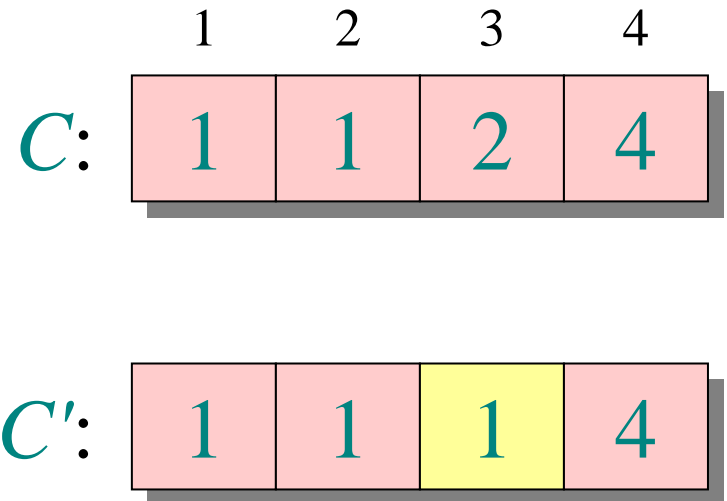
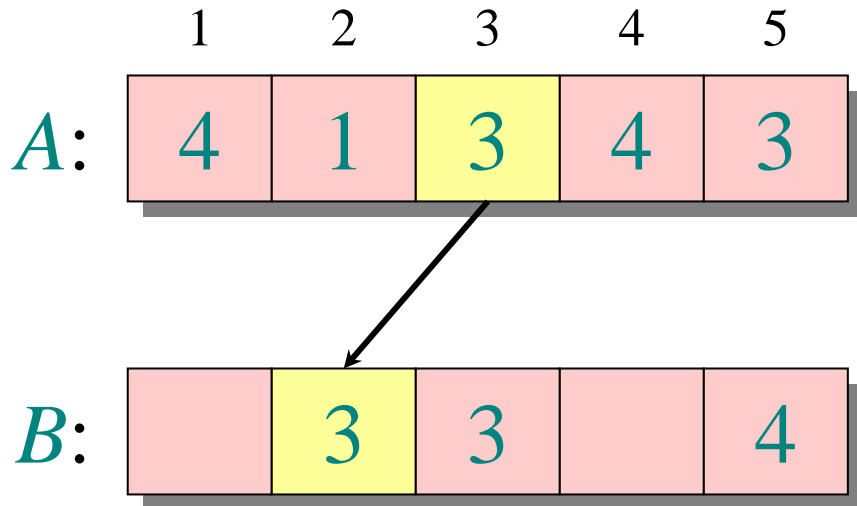
```
for  $j \leftarrow n$  downto 1  
  do  $B[C[A[j]]] \leftarrow A[j]$   
      $C[A[j]] \leftarrow C[A[j]] - 1$ 
```

Loop 4



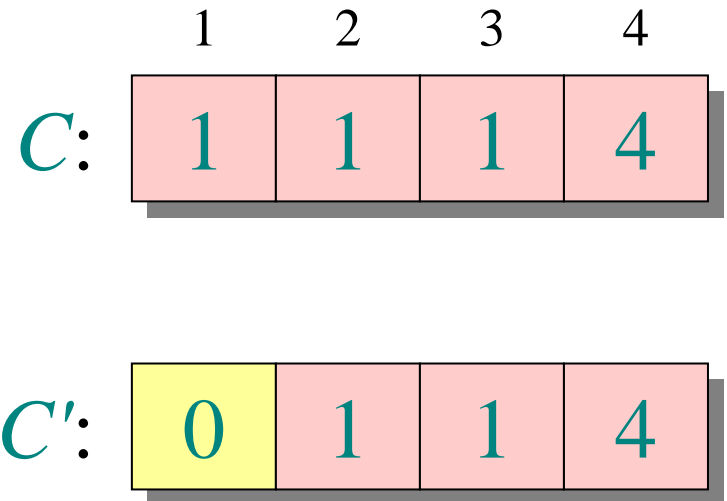
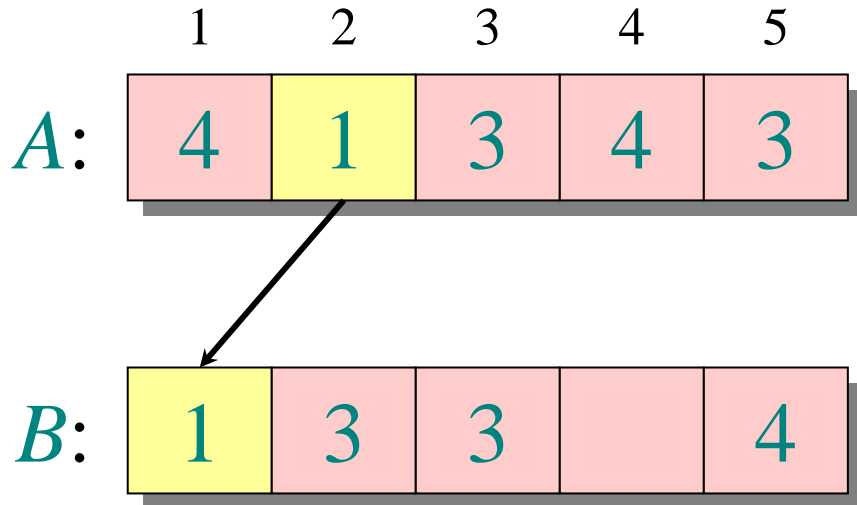
```
for  $j \leftarrow n$  downto 1  
  do  $B[C[A[j]]] \leftarrow A[j]$   
      $C[A[j]] \leftarrow C[A[j]] - 1$ 
```

Loop 4



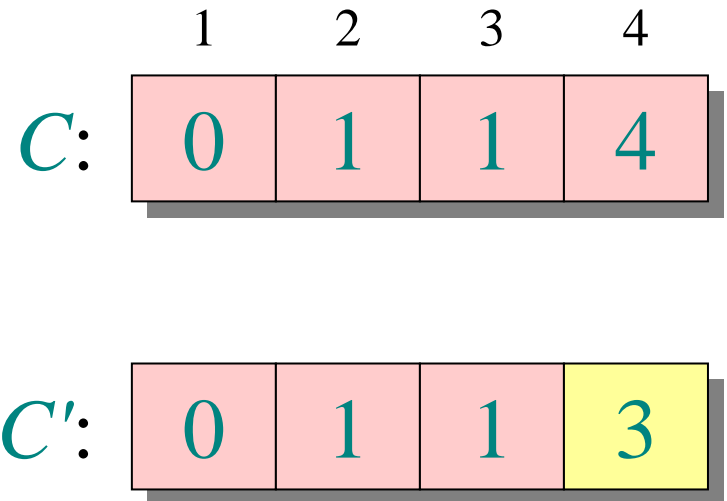
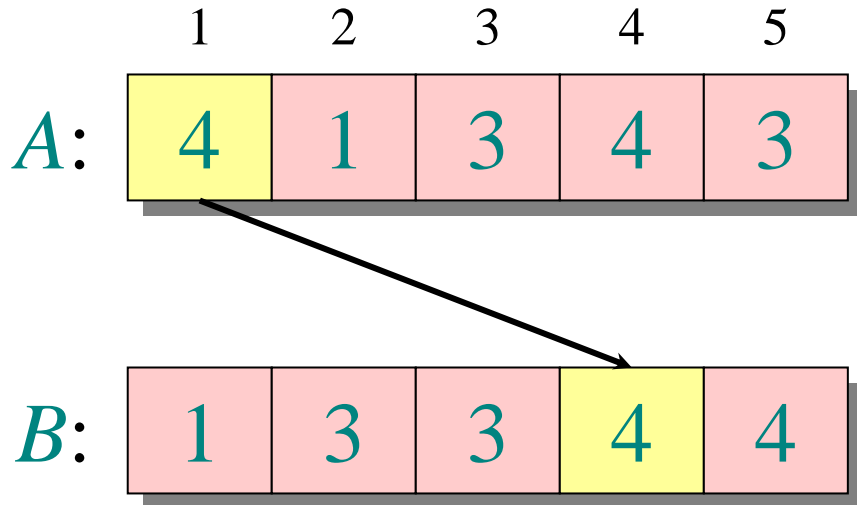
```
for  $j \leftarrow n$  downto 1  
  do  $B[C[A[j]]] \leftarrow A[j]$   
      $C[A[j]] \leftarrow C[A[j]] - 1$ 
```

Loop 4



```
for  $j \leftarrow n$  downto 1  
  do  $B[C[A[j]]] \leftarrow A[j]$   
      $C[A[j]] \leftarrow C[A[j]] - 1$ 
```

Loop 4



```
for  $j \leftarrow n$  downto 1  
  do  $B[C[A[j]]] \leftarrow A[j]$   
      $C[A[j]] \leftarrow C[A[j]] - 1$ 
```

Analysis

$\Theta(k)$ { **for** $i \leftarrow 1$ **to** k
 do $C[i] \leftarrow 0$

$\Theta(n)$ { **for** $j \leftarrow 1$ **to** n
 do $C[A[j]] \leftarrow C[A[j]] + 1$

$\Theta(k)$ { **for** $i \leftarrow 2$ **to** k
 do $C[i] \leftarrow C[i] + C[i-1]$

$\Theta(n)$ { **for** $j \leftarrow n$ **downto** 1
 do $B[C[A[j]]] \leftarrow A[j]$
 $C[A[j]] \leftarrow C[A[j]] - 1$

$\Theta(n + k)$

Running time

If $k = O(n)$, then counting sort takes $\Theta(n)$ time.

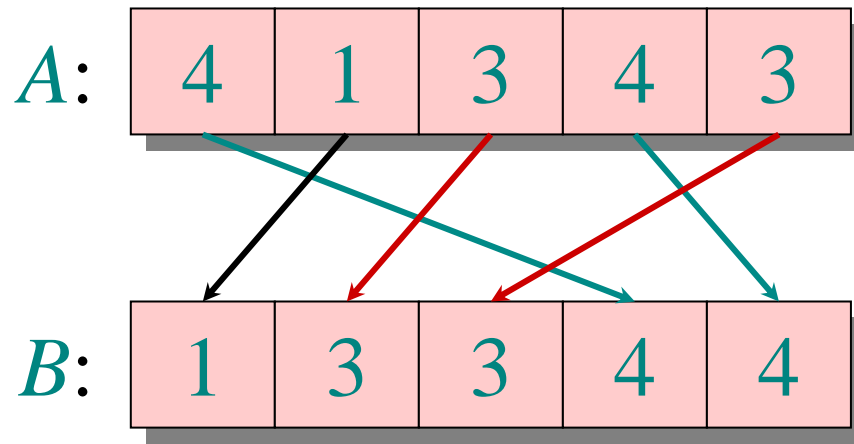
- But, sorting takes $\Omega(n \lg n)$ time!
- Where's the fallacy?

Answer:

- *Comparison sorting* takes $\Omega(n \lg n)$ time.
- Counting sort is not a *comparison sort*.
- In fact, not a single comparison between elements occurs!

Stable sorting

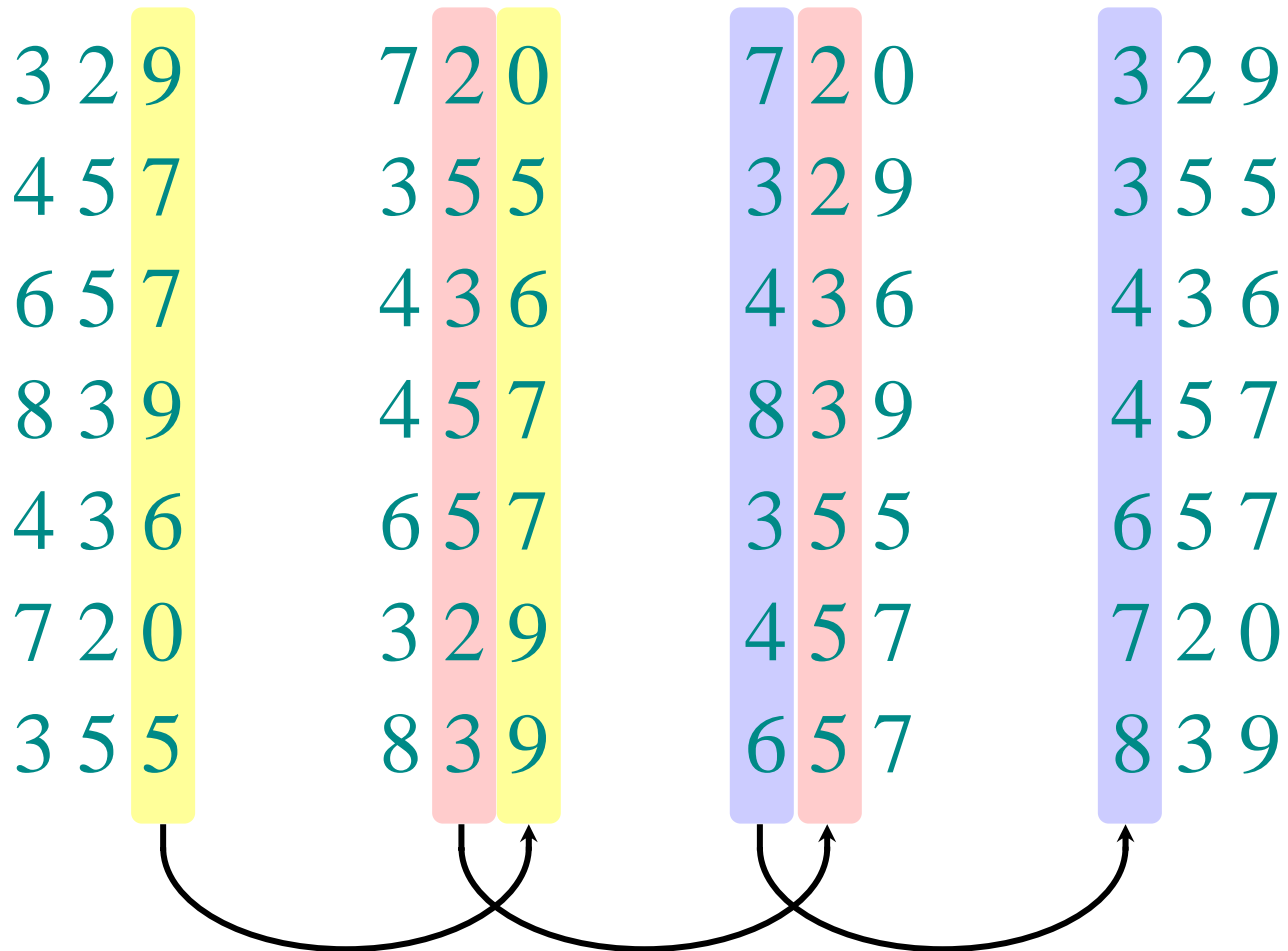
Counting sort is a *stable* sort: it preserves the input order among equal elements.



Radix sort

- *Origin*: Herman Hollerith's card-sorting machine for the 1890 U.S. Census. (See Appendix.)
- Digit-by-digit sort.
- Hollerith's original (bad) idea: sort on most-significant digit first.
- Good idea: Sort on *least-significant digit first* with auxiliary *stable* sort.

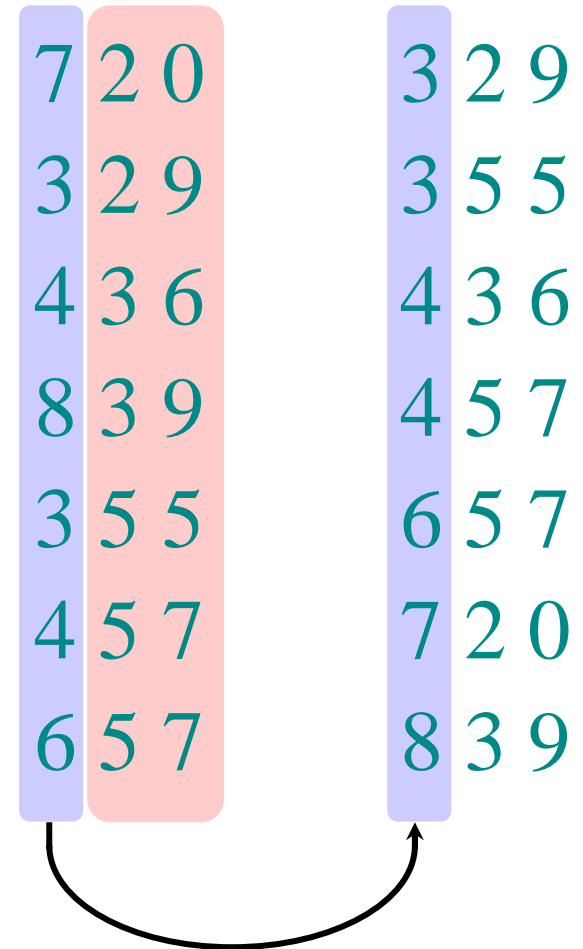
Operation of radix sort



Correctness of radix sort

Induction on digit position

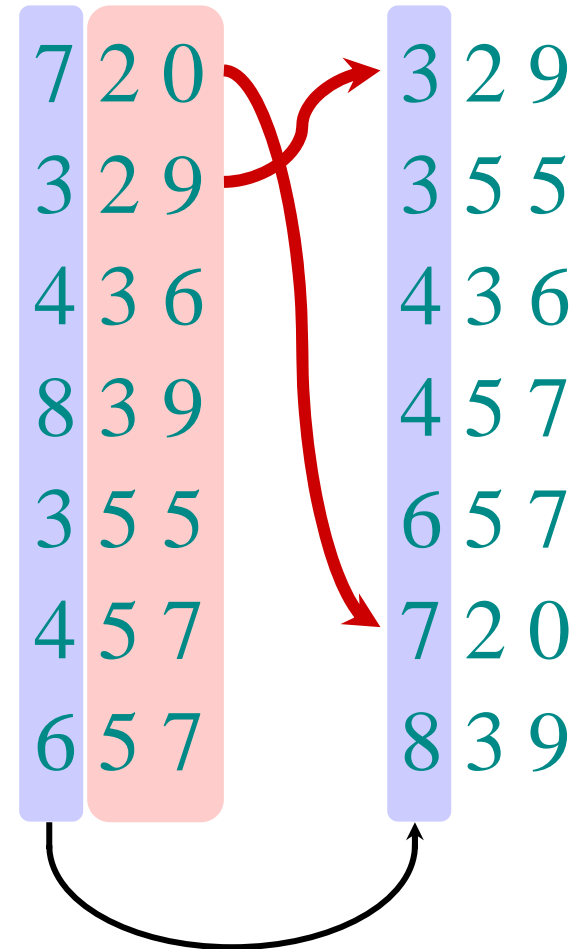
- Assume that the numbers are sorted by their low-order $t - 1$ digits.
- Sort on digit t



Correctness of radix sort

Induction on digit position

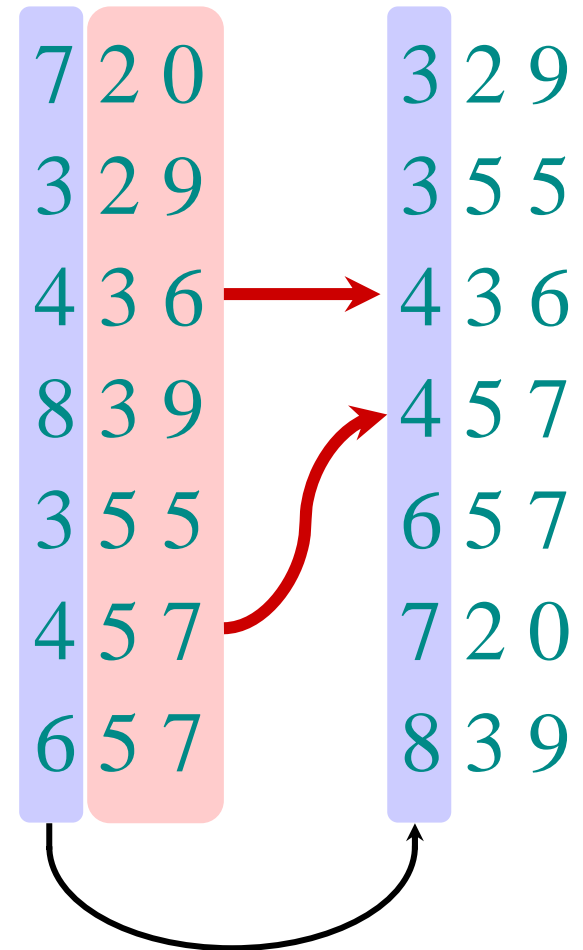
- Assume that the numbers are sorted by their low-order $t - 1$ digits.
- Sort on digit t
 - Two numbers that differ in digit t are correctly sorted.



Correctness of radix sort

Induction on digit position

- Assume that the numbers are sorted by their low-order $t - 1$ digits.
- Sort on digit t
 - Two numbers that differ in digit t are correctly sorted.
 - Two numbers equal in digit t are put in the same order as the input \Rightarrow correct order.



Analysis of radix sort

- Assume counting sort is the auxiliary stable sort.
- Sort n computer words of b bits each.
- Each word can be viewed as having b/r base- 2^r digits.

Example: 32-bit word 

$r = 8 \Rightarrow b/r = 4$ passes of counting sort on base- 2^8 digits; or $r = 16 \Rightarrow b/r = 2$ passes of counting sort on base- 2^{16} digits.

How many passes should we make?

Analysis (continued)

Recall: Counting sort takes $\Theta(n + k)$ time to sort n numbers in the range from 0 to $k - 1$.

If each b -bit word is broken into r -bit pieces, each pass of counting sort takes $\Theta(n + 2^r)$ time. Since there are b/r passes, we have

$$T(n, b) = \Theta\left(\frac{b}{r}(n + 2^r)\right).$$

Choose r to minimize $T(n, b)$:

- Increasing r means fewer passes, but as $r \gg \lg n$, the time grows exponentially.

Conclusions

In practice, radix sort is fast for large inputs, as well as simple to code and maintain.

Downside: Unlike quicksort, radix sort displays little locality of reference, and thus a well-tuned quicksort fares better on modern processors, which feature steep memory hierarchies.