SPIKE PRIME LESSONS

By the Creators of EV3Lessons



VARIABLES

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LESSON OBJECTIVES

- 1. Learn about different types of variables
- 2. Learn how to read and write to variables

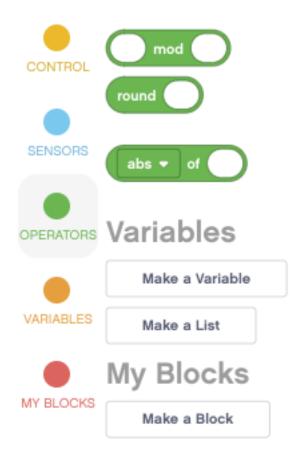
VARIABLES

- What is a variable? Ans. A variable stores a value that you can use later in your program. Think of it like a notepad or a box that holds a value for you.
- You can name the variable whatever you want
- You can define the type of variable:
 - Variable (Holds a number)
 - List (Holds a set of numbers ... 1,2,3,10,55)
- You can either....
 - Write put a value into the variable
 - Read retrieve the last value written to the variable

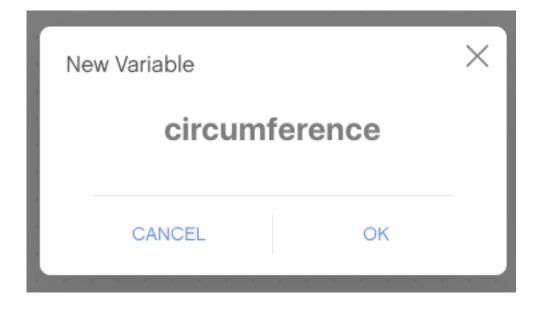
WHY VARIABLES?

- Variables are an easy way to transfer data across code
- You can also use variables to transfer data into a My Block without an input (eg. A variable for wheel size in Move Inches You probably do not want this to be an input since it rarely changes. You may also use the value in other locations and want to change it just in one spot.)
- List variables can store multiple data items and make it easy to process all of them. We will cover list variables in a separate lesson in the advanced section.

CREATING A VARIABLE



- To create a variable, scroll down to the Variables section
- Select Make a Variable and Name it.
- In the example below, a variable called "circumference" has been made



WRITING TO A VARIABLE

Once you have created the variable, it will appear in the menu bar.

Variables Make a Variable circumference circumference set circumference change Make a List My Blocks Make a Block

In the example below, Circumference is set to the circumference of the EV3 Educator robot wheel in centimeters.

Circumference = Pi X Wheel Diameter

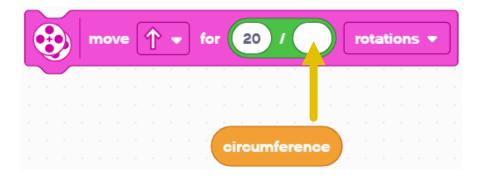
Circumference = 3.14×5.6

This can be calculated using a Math Block



READING A VARIABLE

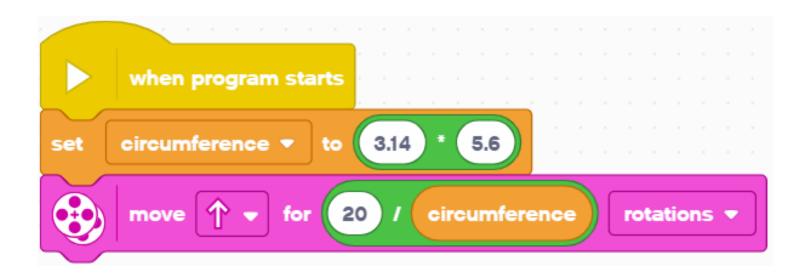
- The variable can now be used in any block with an oval shape operator where you would normally type in a value
- In the example on the right, the circumference is used to move the robot forward 20 centimeters (20 CM/Centimeters in a Circumference)
- For example, if the circumference was 10CM, the robot would have to move 2 rotations to move 20CM.





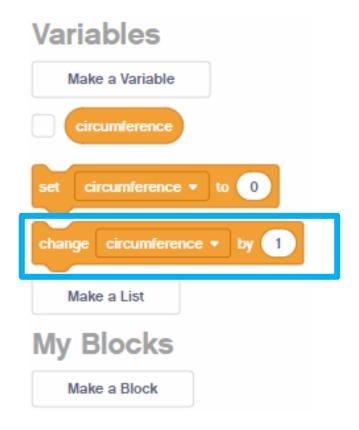
PUTTING IT ALL TOGETHER

- In this example, the program moves 20CM
- First set the variable "circumference" before using it in the program
- Use the variable in the movement block



CHANGING VARIABLES

Once you have created the variable, it will appear in the menu bar.



In the example below, counter is initialized to 1. The change by 2 will add 2 to the counter.

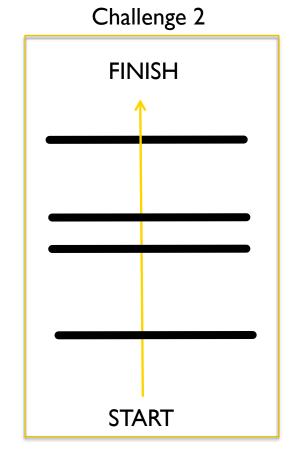
The display block will show a 3 on the screen since I + 2 = 3

Note that you can change by a negative number as well – this will subtract from the variable.

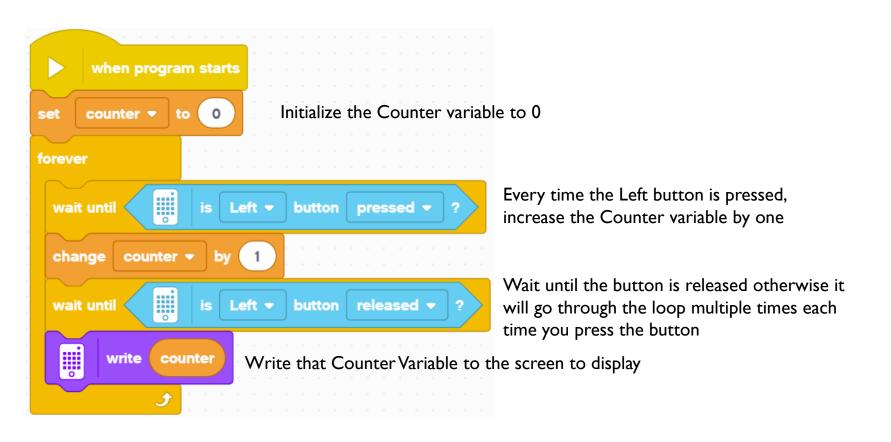


CHALLENGES

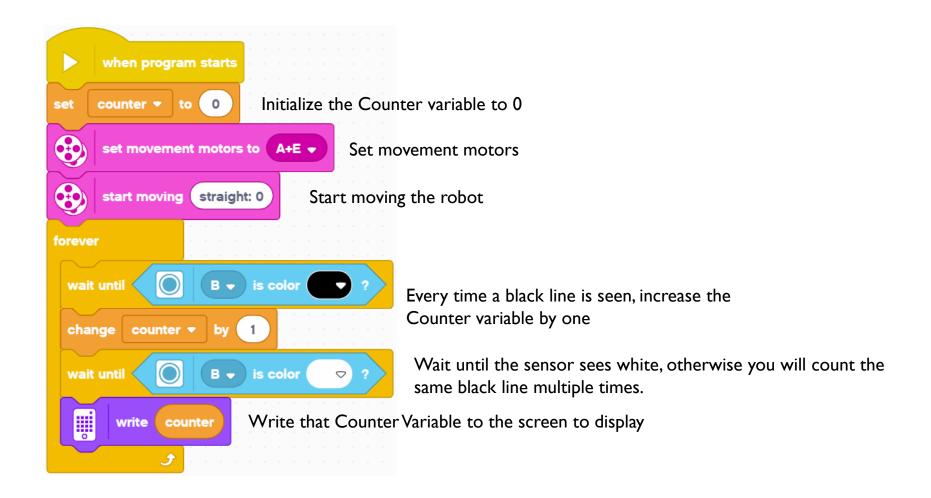
- Challenge 1:
 - Can you make a program that displays the number of times that you have pressed the left button?
- Challenge 2:
 - Can you write a program that counts the number of black lines you have crossed?



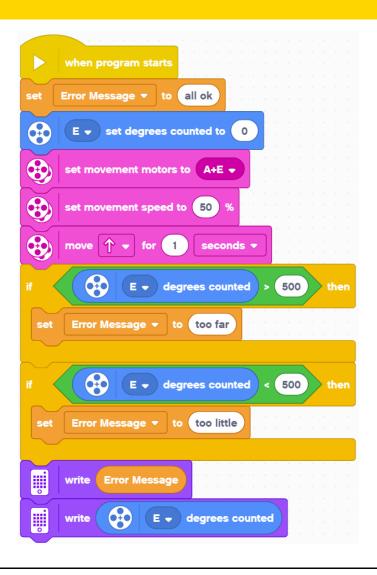
SOLUTION: COUNT CLICKS



SOLUTION: COUNT THE LINES



NON-NUMERIC VARIABLES



- Variables can also store text.
- In the example on the left, we use the "Error Message" variable to store text that describes what went wrong
- The program lets the user know if the robot travelled too far or too little if the goal was to move 500 degrees.
- Note: Isec at 50 % speed should move 500 degrees

CREDITS

- This lesson was created by Sanjay Seshan and Arvind Seshan for SPIKE Prime Lessons
- More lessons are available at www.primelessons.org



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