



The Pseudospectral Fourier Method

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Motivation of the Pseudospectral Method

- Better operators for the spatial derivatives were required. PS is exact up to machine precision in space.
- FD is very memory consuming and PS overcomes this problem by using less spatial grid points.
- ullet First method to be exact at grid points o basis for later methods.





History

- The development started in the early 1980s.
- As a method with global communication, it was well suited for serial processing, which was common in HPC at this time.
- Advance from acoustic wave equation to elastic wave equation and complex 3D structures.
- Boundary conditions could be implemented with Chebychev polynomials.
- Grid stretching for better incorporation of topography and internal curves.
- Optimization for parallel computing by mixing FD and PS in different spatial directions.

Problem: Solving the acoustic wave equation

$$\underbrace{\frac{p(x,t+\mathrm{d}t)-2p(x,t)+p(x,t-\mathrm{d}t)}{\mathrm{d}t^2}}_{} = c(x)^2 \underbrace{\partial_x^2 p(x,t)}_{} + s(x,t)$$

Finite differences for temporal derivatives

Pseudospectral method for spatial derivative

Fourier Series

 Approximate function by a sum over N weighted orthogonal basis functions

$$f(x) \approx g_N(x) = \sum_{i=1}^N a_i \Phi_i(x)$$

ullet Chose trigonometric basis functions in the interval $[-\pi,\pi]$

$$cos(nx)$$
 $n = 0, 1, ..., \infty$
 $sin(nx)$ $n = 0, 1, ..., \infty$

• Approximation of 2π -periodic function on $[-\pi,\pi]$

$$f(x) \approx g_n(x) = \frac{1}{2}a_0 + \sum_{k=1}^n a_k \cos(kx) + b_k \sin(kx)$$



• Apply least squares problem to find coefficients a_k , b_k

$$||f(x) - g_N(x)||_{L^2} = \left[\int_a^b \{f(x) - g_N(x)\}^2 dx\right]^{\frac{1}{2}} = Min$$



• For discrete set of points
$$x_i = \frac{2\pi}{N}i$$
, $i = 0, ..., N$

$$a_k^* = \frac{2}{N} \sum_{j=1}^N f(x_j) \cos(kx_j)$$
 $k = 0, 1, ..., n$
 $b_k^* = \frac{2}{N} \sum_{j=1}^N f(x_j) \sin(kx_j)$ $k = 0, 1, ..., n$

$$\to g_n^* := \frac{1}{2}a_0^* + \sum_{k=1}^{n-1} \{a_k^* \cos(kx) - b_k^* \sin(kx)\} + \frac{1}{2}a_n^* \cos(nx)$$

Exact interpolation at collocation points

$$g_n^*(x_i) = f(x_i)$$



Fourier Transform

Continuous

$$F(k) = \mathscr{F}[f(x)] = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} f(x)e^{ikx}dx$$

$$f(x) = \mathscr{F}^{-1}[F(k)] = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} F(k)e^{-ikx}dk$$

Discrete

$$F_k = \sum_{j=0}^{N-1} f_j e^{i2\pi jk/N}, \ k = 0, ..., N$$

$$f_j = \frac{1}{N} \sum_{k=0}^{N-1} F_k e^{-i2\pi jk/N}, \ j = 0, ..., N$$

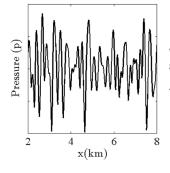


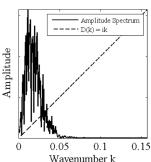
Exploited property for Pseudospectral Method

$$F^{(n)}(k) = (ik)^n F(k)$$

$$\to f^{(n)}(x) = \mathscr{F}^{-1}[(ik)^n F(k)]$$

$$\to \partial_x^n f_j = \mathscr{F}^{-1}[(ik)^n F_k]$$





Igel, unpublished

Comparison PS - FD

Pros

- Exact spatial derivative (up to machine precision)
- Only two grid points per wavelength required
- No grid staggering required
- Memory efficient

Cons

- Computational more expensive (more FLOPS per spatial derivative required)
- Global communication required

 → does not allow parallel
 computing
- Assumes periodicity of function
 → boundary conditions
 difficult to implement