Lecture 14: Deep Learning

Course: Biomedical Data Science
Parisa Rashidi
Fall 2018

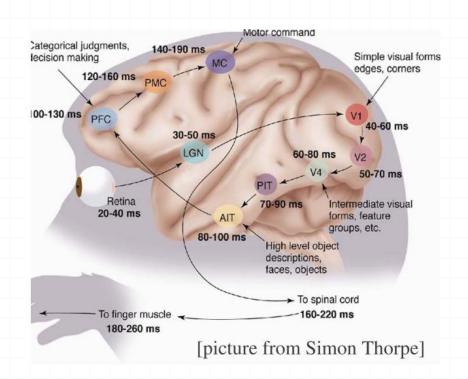
Deep Neural Network

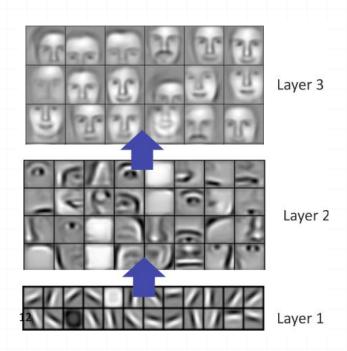
Material partially based on:

- -Raschka, Sebastian. Python Machine Learning (p. 18). Packt Publishing.
- -Stanford CS231n: Convolutional Neural Networks for Visual Recognition, 2017.

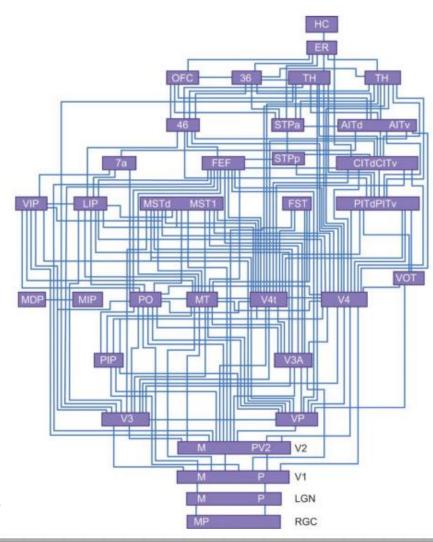
Learning Features instead of Feature Engineering

- The visual system is deep (around 10 layers)
- What is the learning algorithm of the neo-cortex?



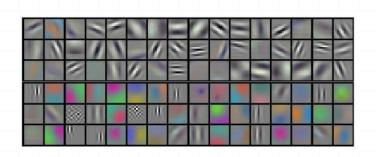


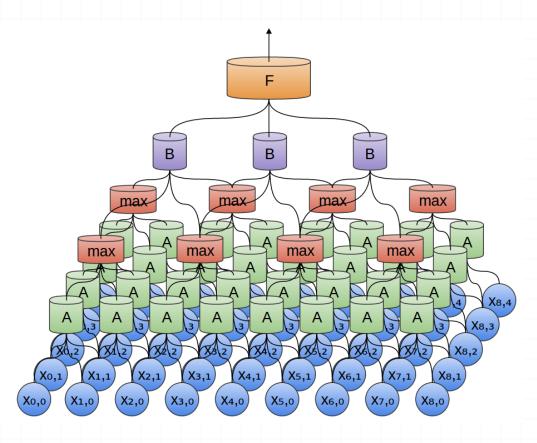
Visual Pathway is Complex!



Banich, Marie T.; Compton, Rebecca J.. Cognitive Neuroscience (Kindle Location 7070). Cambridge University Press.

Convolutional NN





Why Deep Learning Works

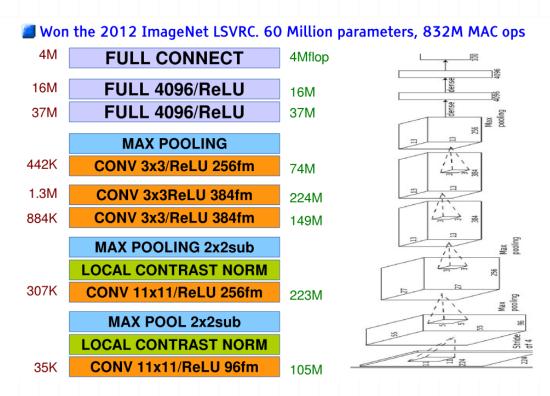
- Some tricks
 - GPU utilization
 - Dropout
 - Pre-training each layer (not popular anymore)

Notable Architectures

ImageNet Challenge: 1000 classes, 1.5M training images

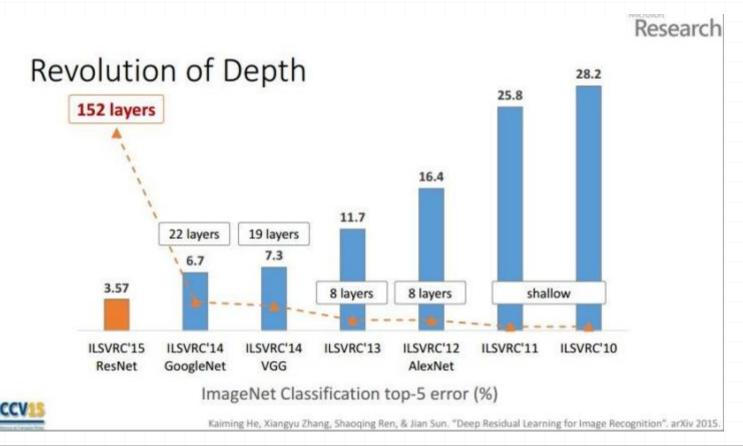
AlexNet by Krizhevsky et al. 2012

- 650K neurons, 832M synapses, 60M parameters
- Error rate 15%

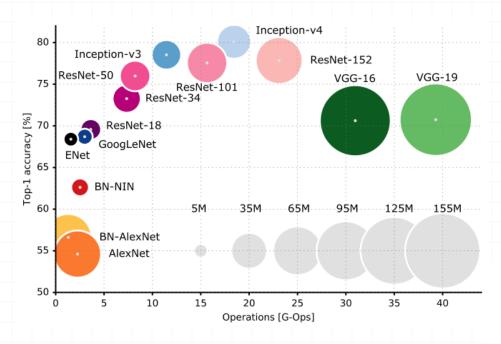


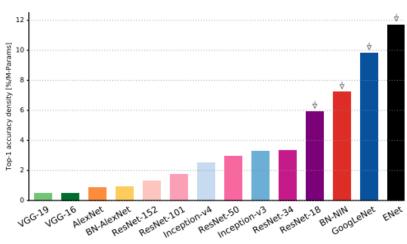
Improvement Over Time

ResNet: 152 layers, 2015



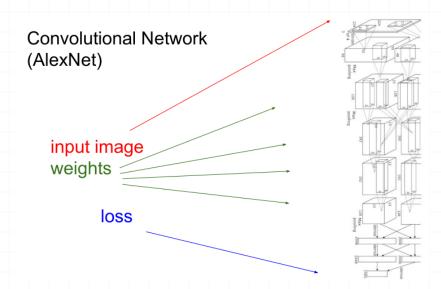
Improvement over Time





Big Picture

- Remember the 4 steps (sample, forward, backprop, update)
 - Learning rate
 - Activation function



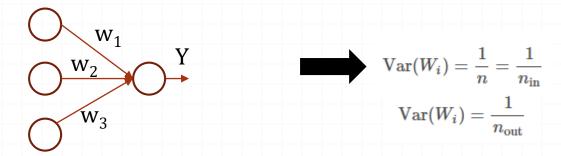
Weight Initialization

- All set to zero?
 - No asymmetry
- Random numbers?
 - Variance is important
 - If the weights are initialized to be too small, then the output from each layer gets smaller and smaller.
 - If the weights are initialized to be too large, then output from each layer gets larger and larger.

Weight Initialization

- The variance of the output from a randomly initialized neuron grows with the number of inputs.
 - Fine for small networks, it can lead to nonhomogeneous distributions of activations across the layers of a network.

$$\operatorname{Var}(Y) = \operatorname{Var}(W_1X_1 + W_2X_2 + \dots + W_nX_n) = n\operatorname{Var}(W_i)\operatorname{Var}(X_i)$$



Weight Initialization

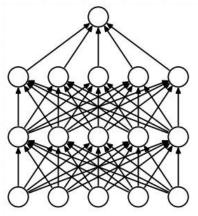
- Use a more sophisticated approach
 - He initialization
 - Xavier (or Glorot) initialization
 - Or use batch normalization after every layer (an advanced topic)

Regularization

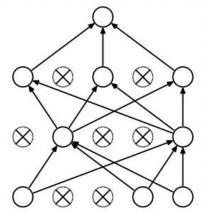
- Minimize ($Loss + \lambda Penalty$)
- L2 regularization is the most common form of regularization.
 - encouraging the network to use all of its inputs a little rather that some of its inputs a lot (diffused weights)
- L1 regularization allows the weight vectors to become sparse.
- In practice, if you are not concerned with explicit feature selection, use L2 regularization.

Dropout

 Randomly set some neurons to zero in each forward pass



(a) Standard Neural Net



(b) After applying dropout.

Convolutional Filters

- A group operator
 - Goes back to conventional vision techniques

1,	1 _{×0}	1,	0	0
0×0	1,	1,0	1	0
0,	O _{×0}	1,	1	1
0	0	1	1	0
0	1	1	0	0

Image

4	

Convolved Feature

Convolutional Filters

• Example: edge detection

Operation	Kernel	Image result
Identity	$\begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$	
	$\begin{bmatrix} 1 & 0 & -1 \\ 0 & 0 & 0 \\ -1 & 0 & 1 \end{bmatrix}$	
Edge detection	$\begin{bmatrix} 0 & 1 & 0 \\ 1 & -4 & 1 \\ 0 & 1 & 0 \end{bmatrix}$	
	$\begin{bmatrix} -1 & -1 & -1 \\ -1 & 8 & -1 \\ -1 & -1 & -1 \end{bmatrix}$	
Sharpen	$\begin{bmatrix} 0 & -1 & 0 \\ -1 & 5 & -1 \\ 0 & -1 & 0 \end{bmatrix}$	
Box blur (normalized)	$\frac{1}{9} \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$	

Transfer Learning

Transfer Learning with CNNs



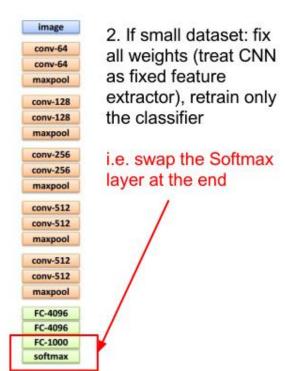


image 3. If you have medium sized conv-64 dataset, "finetune" instead: conv-64 use the old weights as maxpool initialization, train the full conv-128 network or only some of the conv-128 higher layers maxpool conv-256 conv-256 retrain bigger portion of the

network, or even all of it.

maxpool

conv-512

conv-512

maxpool

conv-512

conv-512

maxpool

FC-4096

FC-4096

FC-1000

softmax

More

We will teach the rest of the material using slides <u>here</u>