Programming assignment 4 – Consensus

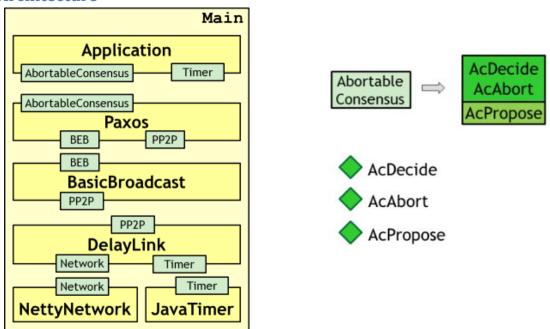
Introduction

In this programming assignment you shall implement the Paxos component that provides the Abortable Consensus service. The algorithm is available at the end of this document, and it is the algorithm described in the "Paxos Made Simple" paper (the algorithm is not available in the textbook).

Installation

Download id2203-ass4-consensus.zip from the course website, unpack and import into Eclipse in the same way as for previous assignments.

Architecture



The AbortableConsensus port is defined in se.kth.ict.id2203.ports.ac.

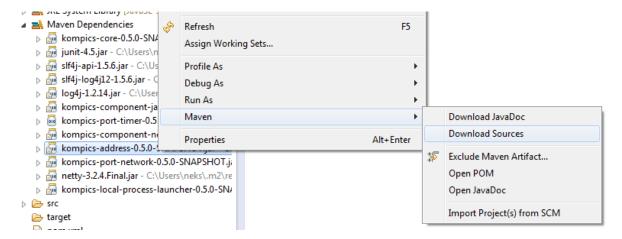
Code to write

The component shall be implemented in the Paxos.java file in the se.kth.ict.id2203.components.paxos package. You will have to add files for internal events as you see fit.

Various notes

- You need to add the following messages (events) in the component's package:
 - o PrepareMessage ⊆ BebDeliver
 - o PrepareAckMessage ⊆ Pp2pDeliver
 - o NackMessage ⊆ Pp2pDeliver
 - o AcceptMessage ⊆ BebDeliver

- o AcceptAckMessage ⊆ Pp2pDeliver
- Remember that you can download the source code for the Kompics classes if you wonder how something in Kompics works. This can easily be done inside Eclipse using Maven:



- The se.sics.kompics.address.Address class has well-defined equals, hashCode and compareTo methods, and an object of this class can therefore be used as a key in both a HashMap and a TreeMap.
- It is a good idea to insert logging statements in the code to be able to trace the execution. For example, in the handler for the PrepareMessage event, you might write:

• The algorithm maintains logical clocks. They are used to come up with new, and successively higher, proposal numbers.

Exploration

The Application has two commands for invoking Abortable Consensus:

- Pn Propose value n. The attempt to reach consensus might fail, resulting in an abort, or a value might be decided.
- Cn Propose value n, and if the attempt fails then the application will automatically try to propose again until a value is decided. Please have a look at the handleAbort method in Application.java to see how this is implemented.

You shall do the following:

- In Executor.java there are three scenarios (one should be uncommented at a time), and you should run each of them.
 - In the first scenario, process 1 will propose value 1 alone, and should succeed and get a decision with value 1.
 - In scenario 2, all three processes will propose the values 1, 2 and 3 using command
 'P'. Only one process should succeed and get a decision, and the others should abort.
 - In scenario 3, all three processes will propose the values 1, 2 and 3 using the 'C'
 command. Processes will content and they will abort each other. After a process has

aborted, it will wait for a random time in the interval [0, 100] ms before proposing the same value again. After some time it is likely that processes will decide.

- Try to change this time interval (line 123 of Application.java) to see how that will affect the time it takes until processes decide.
- For each scenario, make sure that the agreement property is never violated.

Automatic correction

When everything is working you run the AutomaticCorrection.java file to test the component and submit the assignment to the http://cloud7.sics.se:11700/ server. Remember to change the email and password strings before running.

Algorithm 1 Paxos: Prepare Phase

Implements:

AbortableConsensus, instance ac.

Uses:

BestEffortBroadcast, **instance** beb; PerfectPointToPointLinks, **instance** pp2p.

```
1: upon event \langle ac, Init \rangle do
        t := 0;
                                                                                                         ⊳ logical clock
 2:
        prepts := 0;
                                                                                                ▷ prepared timestamp
 3:
        (ats, av) := (0, \bot);

    b timestamp and value accepted

 4:
        (pts, pv) := (0, \perp);
                                                                                  ▷ proposer's timestamp and value
 5:
        readlist := [\bot]^N;
 6:
        acks := 0;
 7:
 8: upon event \langle ac, Propose \mid v \rangle do
 9:
        t := t + 1;
        pts := t \times N + rank(self);
10:
        pv := v;
11:
        readlist := [\bot]^N;
12:
13:
        acks := 0;
        trigger \langle beb, Broadcast \mid [PREPARE, pts, t] \rangle;
14:
15: upon event \langle beb, Deliver \mid q, [Prepare, ts, t'] \rangle do
16:
        t := max(t, t') + 1;
        if ts < prepts then
17:
            trigger \langle pp2p, Send \mid q, [NACK, ts, t] \rangle;
18:
19:
        else
20:
            prepts := ts;
21:
            trigger \langle pp2p, Send \mid q, [PREPAREACK, ats, av, ts, t] \rangle;
```

Algorithm 2 Paxos: Accept Phase 22: **upon event** $\langle pp2p, Deliver \mid q, [NACK, pts', t'] \rangle$ **do** t := max(t, t') + 1;23: if pts' = pts then 24: pts := 0;25: **trigger** $\langle ac, Abort \rangle$ 26: 27: **upon event** $\langle pp2p, Deliver \mid q, [PrepareAck, ts, v, pts', t'] \rangle$ **do** 28: t := max(t, t') + 1;if pts' = pts then 29: readlist[q] := (ts, v);30: if #(readlist) > N/2 then 31: (ts, v) := highest(readlist);32: ▶ pair with greatest timestamp 33: if $ts \neq 0$ then pv := v;34: $readlist := [\bot]^N;$ 35: **trigger** $\langle beb, Broadcast \mid [Accept, pts, pv, t] \rangle$; 36: 37: **upon event** $\langle beb, Deliver \mid q, [Accept, ts, v, t'] \rangle$ **do** t := max(t, t') + 1;38: if ts < prepts then 39: **trigger** $\langle pp2p, Send \mid q, [NACK, ts, t] \rangle$; 40: 41: else 42: ats := prepts := ts;av := v;43: **trigger** $\langle pp2p, Send \mid q, [ACCEPTACK, ts, t] \rangle$; 44: 45: **upon event** $\langle pp2p, Deliver \mid q, [AcceptAck, pts', t'] \rangle$ **do** t := max(t, t') + 1;46: if pts' = pts then 47: acks := acks + 1;48: if acks > N/2 then 49: pts := 0;50:

trigger $\langle ac, Return \mid pv \rangle$;

51: