

Chapter 3

Maximum-Likelihood and Bayesian Parameter Estimation

Bayes Theorem for Classification

$$P(\omega_j|\mathbf{x}) = \frac{p(\mathbf{x}|\omega_j) \cdot P(\omega_j)}{p(\mathbf{x})} \quad (1 \leq j \leq c) \quad (\text{Bayes Formula})$$

To compute posterior probability $P(\omega_j|\mathbf{x})$, we need to know:

Prior probability: $P(\omega_j)$

Likelihood: $p(\mathbf{x}|\omega_j)$

The collection of training examples is composed of c data sets

□ Each example in \mathcal{D}_j is drawn according to the class-conditional pdf, i.e. $p(\mathbf{x}|\omega_j)$

$\mathcal{D}_j \quad (1 \leq j \leq c)$

□ Examples in \mathcal{D}_j are *i.i.d.* random variables, i.e.

independent and identically distributed (独立同分布)


Bayes Theorem for Classification (Cont.)

For prior probability:  no difficulty

$$P(\omega_j) = \frac{|\mathcal{D}_j|}{\sum_{i=1}^c |\mathcal{D}_i|}$$

(Here, $|\cdot|$ returns the **cardinality**,
i.e. number of elements, of a set)


For class-conditional pdf:

Ch. 3  **Case I:** $p(\mathbf{x}|\omega_j)$ has certain **parametric form**

$$p(\mathbf{x}|\omega_j) \quad \left[\begin{array}{l} \text{e.g.: } p(\mathbf{x}|\omega_j) \sim N(\boldsymbol{\mu}_j, \boldsymbol{\Sigma}_j) \quad (\text{parameters: } \boldsymbol{\theta}_j = \{\boldsymbol{\mu}_j, \boldsymbol{\Sigma}_j\}) \\ \mathbf{x} \in \mathbf{R}^d \xrightarrow{\text{yellow arrow}} \boldsymbol{\theta}_j \text{ contains } "d + d(d + 1)/2" \text{ free parameters} \end{array} \right]$$

To show the dependence of
 $p(\mathbf{x}|\omega_j)$ on $\boldsymbol{\theta}_j$ **explicitly:**

$$p(\mathbf{x}|\omega_j) \xrightarrow{\text{yellow arrow}} p(\mathbf{x}|\omega_j, \boldsymbol{\theta}_j)$$

Ch. 4  **Case II:** $p(\mathbf{x}|\omega_j)$ doesn't have **parametric form**

Estimation Under Parametric Form

Parametric class-conditional pdf: $p(\mathbf{x}|\omega_j, \boldsymbol{\theta}_j) \quad (1 \leq j \leq c)$

□ Assumption I: Maximum-Likelihood (ML) estimation (极大似然估计)

View parameters as quantities whose values are **fixed but unknown**



Estimate parameter values by **maximizing the likelihood** (probability) of observing the actual training examples

□ Assumption II: Bayesian estimation (贝叶斯估计)

View parameters as **random variables** having some known prior distribution



Observation of the actual training examples transforms parameters' **prior distribution into posterior distribution** (via Bayes theorem)

Maximum-Likelihood Estimation

Settings

Likelihood function for each category is governed by some **fixed but unknown** parameters, i.e. $p(\mathbf{x}|\omega_j, \boldsymbol{\theta}_j)$ ($1 \leq j \leq c$)

Task: Estimate $\{\boldsymbol{\theta}_j\}_{j=1}^c$ from $\{\mathcal{D}_j\}_{j=1}^c$

A simplified treatment

Examples in \mathcal{D}_j gives no information about $\boldsymbol{\theta}_i$ if $i \neq j$



Work with each category **separately** and therefore simplify the notations by dropping subscripts w.r.t. categories

without loss of generality: $\mathcal{D}_j \longrightarrow \mathcal{D}$; $\boldsymbol{\theta}_j \longrightarrow \boldsymbol{\theta}$

Maximum-Likelihood Estimation (Cont.)

$$\mathbf{x}_k \sim p(\mathbf{x}|\boldsymbol{\theta})$$

$$(k = 1, \dots, n)$$

$\boldsymbol{\theta}$: Parameters to be estimated

\mathcal{D} : A set of *i.i.d.* examples $\{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n\}$

The objective function

$$p(\mathcal{D}|\boldsymbol{\theta}) = \prod_{k=1}^n p(\mathbf{x}_k|\boldsymbol{\theta})$$



The likelihood of $\boldsymbol{\theta}$ w.r.t. the set of observed examples

The maximum-likelihood estimation

$$\hat{\boldsymbol{\theta}} = \arg \max_{\boldsymbol{\theta}} p(\mathcal{D}|\boldsymbol{\theta})$$

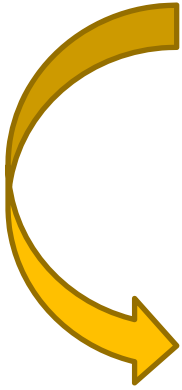


Intuitively, $\hat{\boldsymbol{\theta}}$ best agrees with the actually observed examples

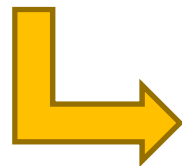
Maximum-Likelihood Estimation (Cont.)

Gradient Operator (梯度算子)

- ✓ Let $\boldsymbol{\theta} = (\theta_1, \dots, \theta_p)^t \in \mathbf{R}^p$ be a p -dimensional vector
- ✓ Let $f : \mathbf{R}^p \rightarrow \mathbf{R}$ be p -variate real-valued function over $\boldsymbol{\theta}$


$$\nabla_{\boldsymbol{\theta}} \equiv \begin{bmatrix} \frac{\partial}{\partial \theta_1} \\ \vdots \\ \frac{\partial}{\partial \theta_p} \end{bmatrix}$$

$$f(\boldsymbol{\theta}) = \theta_1^2 + 3\theta_1\theta_2$$



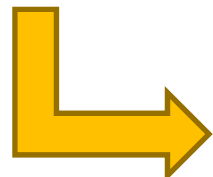
$$\nabla_{\boldsymbol{\theta}} f = \begin{bmatrix} \frac{\partial f}{\partial \theta_1} \\ \frac{\partial f}{\partial \theta_2} \end{bmatrix} = \begin{bmatrix} 2\theta_1 + 3\theta_2 \\ 3\theta_1 \end{bmatrix}$$

$l(\boldsymbol{\theta}) = \ln p(\mathcal{D}|\boldsymbol{\theta})$ is named as the **log-likelihood function**

$$\hat{\boldsymbol{\theta}} = \arg \max_{\boldsymbol{\theta}} p(\mathcal{D}|\boldsymbol{\theta}) \longleftrightarrow \hat{\boldsymbol{\theta}} = \arg \max_{\boldsymbol{\theta}} l(\boldsymbol{\theta})$$

Maximum-Likelihood Estimation (Cont.)

$$l(\boldsymbol{\theta}) = \ln p(\mathcal{D}|\boldsymbol{\theta}) = \sum_{k=1}^n \ln p(\mathbf{x}_k|\boldsymbol{\theta})$$


$$\underline{\underline{\nabla_{\boldsymbol{\theta}} l}} = \nabla_{\boldsymbol{\theta}} \left(\sum_{k=1}^n \ln p(\mathbf{x}_k|\boldsymbol{\theta}) \right) = \sum_{k=1}^n \nabla_{\boldsymbol{\theta}} \underline{\underline{\ln p(\mathbf{x}_k|\boldsymbol{\theta})}}$$

$\nabla_{\boldsymbol{\theta}} l$
 p -dimensional vector with
each component being a
function over $\boldsymbol{\theta}$

$\ln p(\mathbf{x}_k|\boldsymbol{\theta})$
 p -variate real-valued
function over $\boldsymbol{\theta}$ (not
over \mathbf{x}_k)

Necessary conditions for ML estimate $\hat{\boldsymbol{\theta}}$

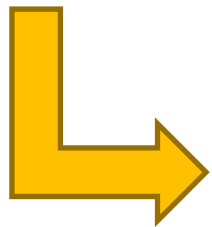
$$\nabla_{\boldsymbol{\theta}} l \big|_{\boldsymbol{\theta}=\hat{\boldsymbol{\theta}}} = \mathbf{0} \text{ (a set of } p \text{ equations)}$$

The Gaussian Case: Unknown μ

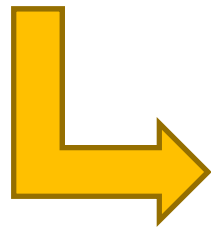
$$\mathbf{x}_k \sim N(\mu, \Sigma) \\ (k = 1, \dots, n)$$

suppose Σ is known  $\theta = \{\mu\}$

$$p(\mathbf{x}_k | \mu) = \frac{1}{(2\pi)^{d/2} |\Sigma|^{1/2}} \exp \left[-\frac{1}{2} (\mathbf{x}_k - \mu)^t \Sigma^{-1} (\mathbf{x}_k - \mu) \right]$$



$$\begin{aligned} \ln p(\mathbf{x}_k | \mu) &= -\frac{1}{2} \ln [(2\pi)^d |\Sigma|] - \frac{1}{2} (\mathbf{x}_k - \mu)^t \Sigma^{-1} (\mathbf{x}_k - \mu) \\ &= -\frac{1}{2} \ln [(2\pi)^d |\Sigma|] - \frac{1}{2} \mathbf{x}_k^t \Sigma^{-1} \mathbf{x}_k + \mu^t \Sigma^{-1} \mathbf{x}_k - \frac{1}{2} \mu^t \Sigma^{-1} \mu \end{aligned}$$



$$\nabla_{\mu} \ln p(\mathbf{x}_k | \mu) = \Sigma^{-1} (\mathbf{x}_k - \mu)$$

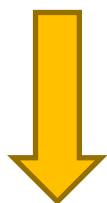
The Gaussian Case: Unknown μ

(Cont.)

$$l(\mu) = \sum_{k=1}^n \ln p(\mathbf{x}_k | \mu)$$

Intuitive result

ML estimate for the unknown μ
is just the arithmetic average of
training samples – **sample mean**


$$\nabla_{\mu} \ln p(\mathbf{x}_k | \mu) = \Sigma^{-1}(\mathbf{x}_k - \mu)$$

$$\nabla_{\mu} l = \sum_{k=1}^n \Sigma^{-1}(\mathbf{x}_k - \mu)$$


$$\nabla_{\mu} l = \mathbf{0} \text{ (necessary condition}$$

for ML estimate $\hat{\mu}$)

$$\hat{\mu} = \frac{1}{n} \sum_{k=1}^n \mathbf{x}_k$$

Multiply Σ on
both sides

$$\sum_{k=1}^n \Sigma^{-1}(\mathbf{x}_k - \hat{\mu}) = \mathbf{0}$$

$$\sum_{k=1}^n (\mathbf{x}_k - \hat{\mu}) = \mathbf{0}$$

The Gaussian Case: Unknown μ and Σ

$$\mathbf{x}_k \sim N(\boldsymbol{\mu}, \boldsymbol{\Sigma})$$
$$(k = 1, \dots, n)$$

$\boldsymbol{\mu}$ and $\boldsymbol{\Sigma}$ unknown $\longrightarrow \boldsymbol{\theta} = \{\boldsymbol{\mu}, \boldsymbol{\Sigma}\}$

Consider *univariate* case

$$p(x_k | \boldsymbol{\theta}) = \frac{1}{\sqrt{2\pi}\sigma} \exp \left[-\frac{(x - \mu)^2}{2\sigma^2} \right] \quad \left(\boldsymbol{\theta} = \begin{bmatrix} \theta_1 \\ \theta_2 \end{bmatrix} = \begin{bmatrix} \mu \\ \sigma^2 \end{bmatrix} \right)$$

$$\ln p(x_k | \boldsymbol{\theta}) = -\frac{1}{2} \ln 2\pi\theta_2 - \frac{1}{2\theta_2} (x_k - \theta_1)^2$$

$$\nabla_{\boldsymbol{\theta}} \ln p(x_k | \boldsymbol{\theta}) = \begin{bmatrix} \frac{1}{\theta_2} (x_k - \theta_1) \\ -\frac{1}{2\theta_2} + \frac{(x_k - \theta_1)^2}{2\theta_2^2} \end{bmatrix}$$

The Gaussian Case: Unknown μ and Σ (Cont.)

$$l(\boldsymbol{\theta}) = \sum_{k=1}^n \ln p(x_k | \boldsymbol{\theta})$$

$$\nabla_{\boldsymbol{\theta}} \ln p(x_k | \boldsymbol{\theta}) =$$

$$\begin{bmatrix} \frac{1}{\theta_2} (x_k - \theta_1) \\ -\frac{1}{2\theta_2} + \frac{(x_k - \theta_1)^2}{2\theta_2^2} \end{bmatrix}$$

$$\nabla_{\boldsymbol{\theta}} l = \begin{bmatrix} \sum_{k=1}^n \frac{1}{\theta_2} (x_k - \theta_1) \\ \sum_{k=1}^n \left(-\frac{1}{2\theta_2} + \frac{(x_k - \theta_1)^2}{2\theta_2^2} \right) \end{bmatrix}$$

$$\sum_{k=1}^n \frac{1}{\hat{\theta}_2} (x_k - \hat{\theta}_1) = 0$$

$$-\sum_{k=1}^n \frac{1}{\hat{\theta}_2} + \sum_{k=1}^n \frac{(x_k - \hat{\theta}_1)^2}{\hat{\theta}_2^2} = 0$$

$\nabla_{\boldsymbol{\theta}} l = 0$ (necessary condition for ML estimate $\hat{\theta}_1$ and $\hat{\theta}_2$)

The Gaussian Case: Unknown μ and Σ (Cont.)

$$\sum_{k=1}^n \frac{1}{\hat{\theta}_2} (x_k - \hat{\theta}_1) = 0 \quad \Rightarrow \quad \sum_{k=1}^n (x_k - \hat{\theta}_1) = 0 \quad \Rightarrow \quad \hat{\theta}_1 = \frac{1}{n} \sum_{k=1}^n x_k$$

$$-\sum_{k=1}^n \frac{1}{\hat{\theta}_2} + \sum_{k=1}^n \frac{(x_k - \hat{\theta}_1)^2}{\hat{\theta}_2^2} = 0 \quad \Rightarrow \quad \hat{\theta}_2 = \frac{1}{n} \sum_{k=1}^n (x_k - \hat{\theta}_1)^2$$

ML estimate in univariate case

$$\hat{\mu} = \frac{1}{n} \sum_{k=1}^n x_k \quad \hat{\sigma}^2 = \frac{1}{n} \sum_{k=1}^n (x_k - \hat{\mu})^2$$

The Gaussian Case: Unknown μ and Σ (Cont.)

ML estimate in *multivariate* case

Intuitive
result as well!

$$\hat{\mu} = \frac{1}{n} \sum_{k=1}^n \mathbf{x}_k \quad \longrightarrow \quad \text{Arithmetic average of } n \text{ vectors } \mathbf{x}_k$$

$$\hat{\Sigma} = \frac{1}{n} \sum_{k=1}^n (\mathbf{x}_k - \hat{\mu})(\mathbf{x}_k - \hat{\mu})^t \quad \longrightarrow \quad \begin{array}{l} \text{Arithmetic average} \\ \text{of } n \text{ matrices} \\ (\mathbf{x}_k - \hat{\mu})(\mathbf{x}_k - \hat{\mu})^t \end{array}$$

Bayesian Estimation

Settings

- ❑ The **parametric form** of the likelihood function for each category is known $p(\mathbf{x}|\omega_j, \boldsymbol{\theta}_j)$ ($1 \leq j \leq c$)
- ❑ However, $\boldsymbol{\theta}_j$ is considered to be **random variables** instead of being fixed (but unknown) values

In this case, we can no longer make a single ML estimate $\hat{\boldsymbol{\theta}}_j$ and then infer $P(\omega_j|\mathbf{x})$ based on $P(\omega_j)$ and $p(\mathbf{x}|\omega_j, \hat{\boldsymbol{\theta}}_j)$



How can we
proceed under
this situation

Fully exploit training examples!

$$P(\omega_j|\mathbf{x}) \longrightarrow P(\omega_j|\mathbf{x}, \mathcal{D}^*)$$

$$(\mathcal{D}^* = \mathcal{D}_1 \cup \mathcal{D}_2 \cup \dots \cup \mathcal{D}_c)$$

Bayesian Estimation (Cont.)

$$P(\omega_j|\mathbf{x}, \mathcal{D}^*) = \frac{p(\omega_j, \mathbf{x}, \mathcal{D}^*)}{p(\mathbf{x}, \mathcal{D}^*)} = \frac{p(\omega_j, \mathbf{x}, \mathcal{D}^*)}{\sum_{i=1}^c p(\omega_i, \mathbf{x}, \mathcal{D}^*)}$$

$$p(\omega_j, \mathbf{x}, \mathcal{D}^*) = p(\mathcal{D}^*) \cdot p(\omega_j, \mathbf{x}|\mathcal{D}^*) = p(\mathcal{D}^*) \cdot P(\omega_j|\mathcal{D}^*) \cdot p(\mathbf{x}|\omega_j, \mathcal{D}^*)$$

$$P(\omega_j|\mathbf{x}, \mathcal{D}^*) = \frac{p(\mathcal{D}^*) \cdot P(\omega_j|\mathcal{D}^*) \cdot p(\mathbf{x}|\omega_j, \mathcal{D}^*)}{p(\mathcal{D}^*) \cdot \sum_{i=1}^c P(\omega_i|\mathcal{D}^*) \cdot p(\mathbf{x}|\omega_i, \mathcal{D}^*)}$$

Two assumptions

$$P(\omega_j|\mathcal{D}^*) = P(\omega_j)$$

$$p(\mathbf{x}|\omega_j, \mathcal{D}^*) = p(\mathbf{x}|\omega_j, \mathcal{D}_j)$$

$$= \frac{P(\omega_j|\mathcal{D}^*) \cdot p(\mathbf{x}|\omega_j, \mathcal{D}^*)}{\sum_{i=1}^c P(\omega_i|\mathcal{D}^*) \cdot p(\mathbf{x}|\omega_i, \mathcal{D}^*)}$$

Eq.22 [pp.91]

$$= \frac{P(\omega_j) \cdot p(\mathbf{x}|\omega_j, \mathcal{D}_j)}{\sum_{i=1}^c P(\omega_i) \cdot p(\mathbf{x}|\omega_i, \mathcal{D}_i)}$$

Eq.23 [pp.91]

Bayesian Estimation (Cont.)

$$P(\omega_j | \mathbf{x}, \mathcal{D}^*) = \frac{P(\omega_j) \cdot p(\mathbf{x} | \omega_j, \mathcal{D}_j)}{\sum_{i=1}^c P(\omega_i) \cdot p(\mathbf{x} | \omega_i, \mathcal{D}_i)}$$

Key problem

Determine $p(\mathbf{x} | \omega_j, \mathcal{D}_j)$

Treat each class
independently

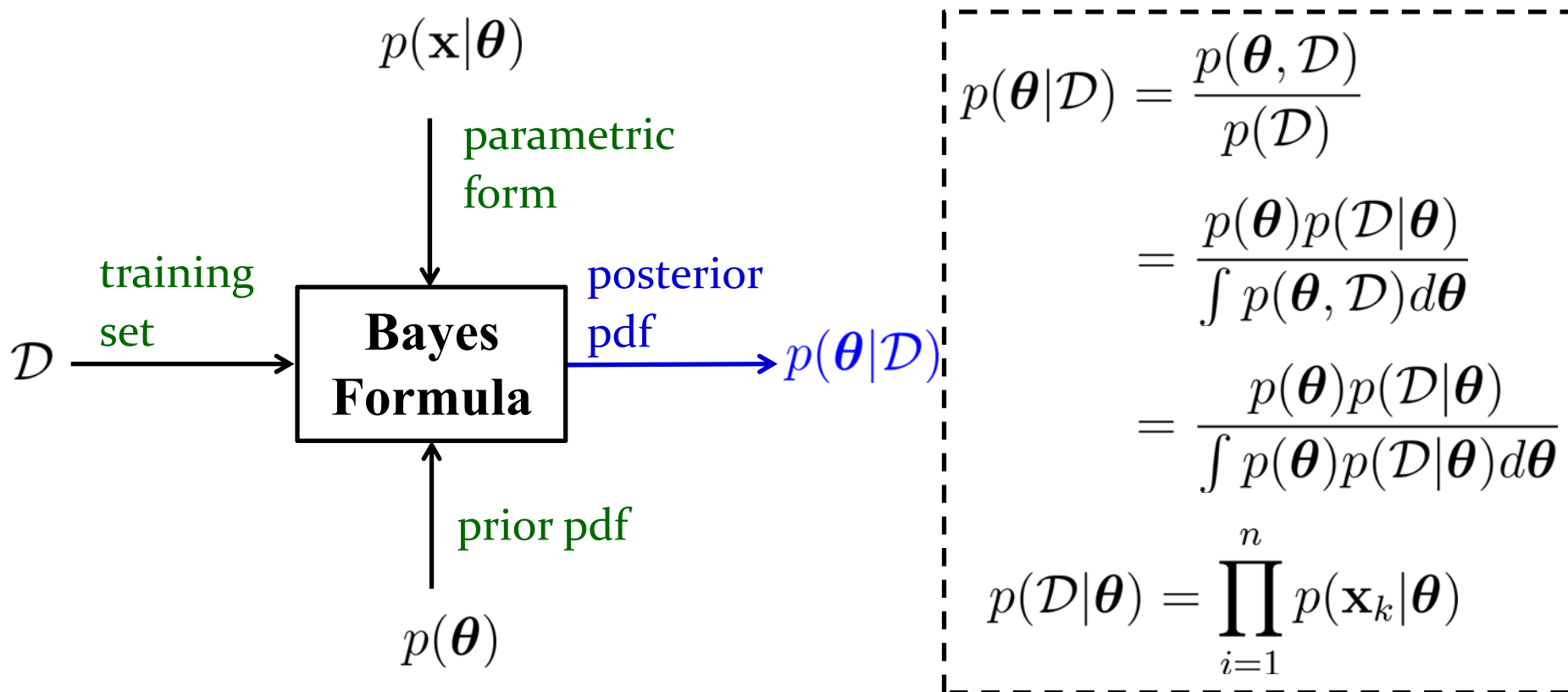


Simplify the *class-conditional pdf*
notation $p(\mathbf{x} | \omega_j, \mathcal{D}_j)$ as $p(\mathbf{x} | \mathcal{D})$

$$\begin{aligned} p(\mathbf{x} | \mathcal{D}) &= \int p(\mathbf{x}, \boldsymbol{\theta} | \mathcal{D}) d\boldsymbol{\theta} \quad (\boldsymbol{\theta} : \text{random variables w.r.t. parametric form}) \\ &= \int p(\mathbf{x} | \boldsymbol{\theta}, \mathcal{D}) p(\boldsymbol{\theta} | \mathcal{D}) d\boldsymbol{\theta} \\ &= \int p(\mathbf{x} | \boldsymbol{\theta}) p(\boldsymbol{\theta} | \mathcal{D}) d\boldsymbol{\theta} \quad (\mathbf{x} \text{ is independent of } \mathcal{D} \text{ given } \boldsymbol{\theta}) \end{aligned}$$

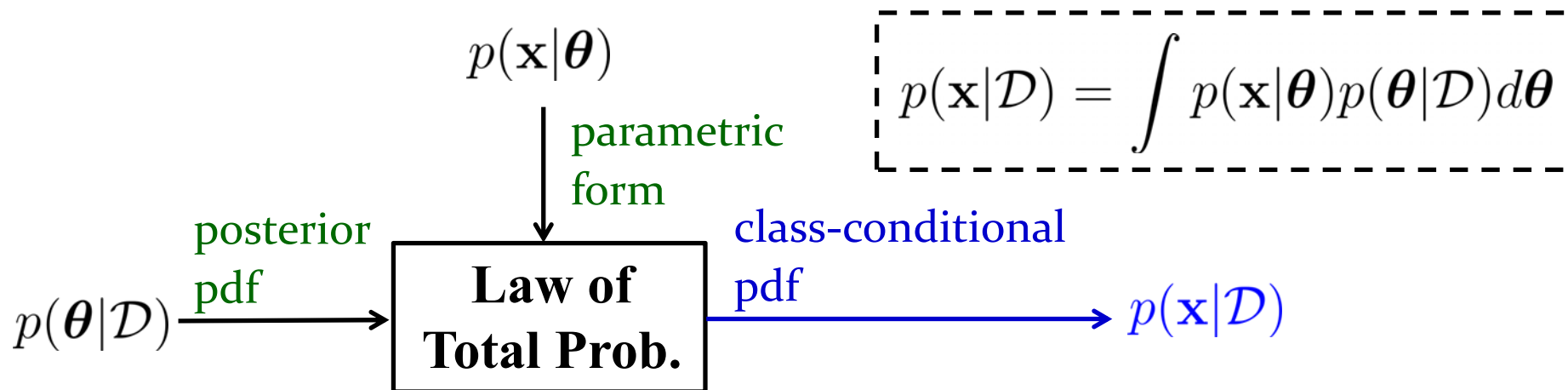
Bayesian Estimation: The General Procedure

Phase I: *prior pdf* \Rightarrow *posterior pdf* (for θ)



Bayesian Estimation: The General Procedure

Phase II: *posterior pdf (for θ)* \rightarrow *class-conditional pdf (for \mathbf{x})*

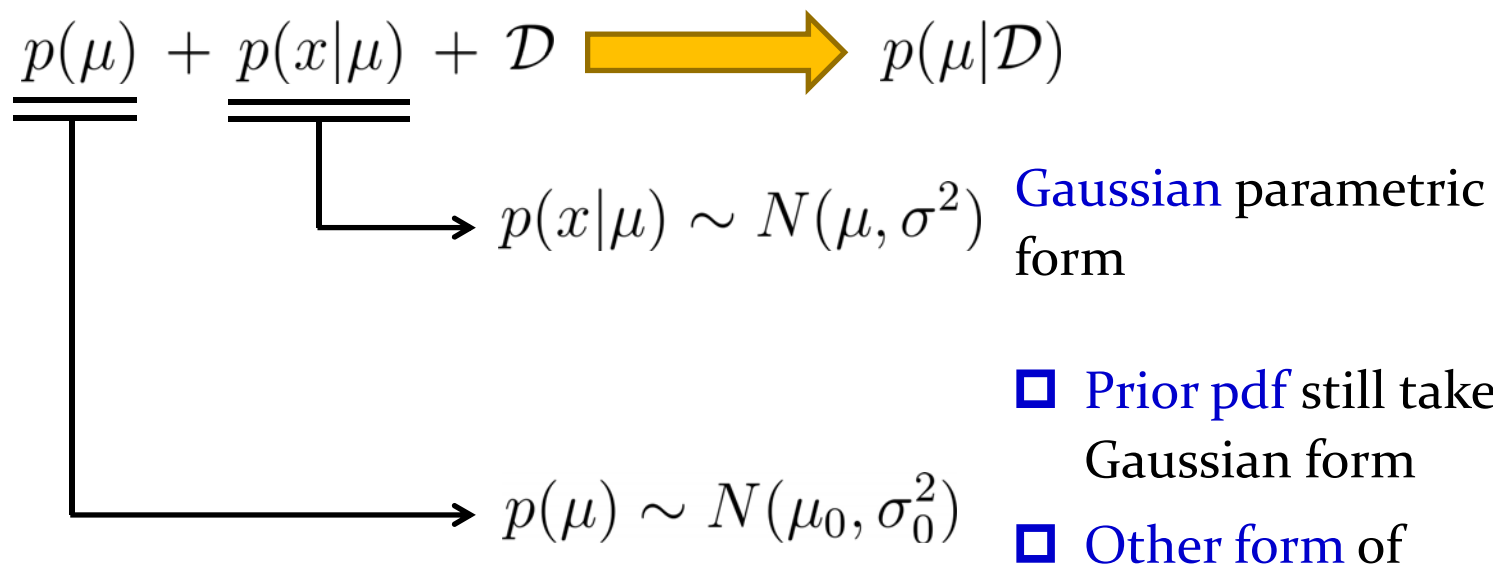


Phase III:
$$P(\omega_j|\mathbf{x}, \mathcal{D}^*) = \frac{P(\omega_j) \cdot p(\mathbf{x}|\omega_j, \mathcal{D}_j)}{\sum_{i=1}^c P(\omega_i) \cdot p(\mathbf{x}|\omega_i, \mathcal{D}_i)}$$

The Gaussian Case: Unknown μ

Consider univariate case: $\theta = \{\mu\}$ (σ^2 is known)

Phase I: prior pdf \Rightarrow posterior pdf (for θ)



- Prior pdf still takes Gaussian form
- Other form of prior pdf could be assumed as well

How would $p(\mu|\mathcal{D})$ look like in this case?

The Gaussian Case: Unknown μ

(Cont.)

$$p(\mu|\mathcal{D}) = \frac{p(\mu, \mathcal{D})}{p(\mathcal{D})} = \frac{p(\mu)p(\mathcal{D}|\mu)}{\int p(\mu)p(\mathcal{D}|\mu) d\mu}$$

$$= \alpha p(\mu) p(\mathcal{D}|\mu)$$

($\int p(\mu)p(\mathcal{D}|\mu) d\mu$ is a **constant** not related to μ)

$$= \alpha p(\mu) \prod_{k=1}^n p(x_k|\mu) \quad (\text{examples in } \mathcal{D} \text{ are } \textit{i.i.d.})$$

$$p(\mu) \sim N(\mu_0, \sigma_0^2)$$

$$p(x|\mu) \sim N(\mu, \sigma^2)$$

$$p(\mu) = \frac{1}{\sqrt{2\pi}\sigma_0} \exp \left[-\frac{1}{2} \left(\frac{\mu - \mu_0}{\sigma_0} \right)^2 \right]$$

$$p(x_k|\mu) = \frac{1}{\sqrt{2\pi}\sigma} \exp \left[-\frac{1}{2} \left(\frac{x_k - \mu}{\sigma} \right)^2 \right]$$

The Gaussian Case: Unknown μ

(Cont.)

$$p(\mu|\mathcal{D}) = \alpha p(\mu) \prod_{k=1}^n p(x_k|\mu)$$

$p(\mu|\mathcal{D})$ is an exponential
function of a quadratic
function of μ



$p(\mu|\mathcal{D})$ is a
normal pdf
as well

$$= \alpha \cdot \frac{1}{\sqrt{2\pi}\sigma_0} \exp \left[-\frac{1}{2} \left(\frac{\mu - \mu_0}{\sigma_0} \right)^2 \right] \cdot \prod_{k=1}^n \frac{1}{\sqrt{2\pi}\sigma} \exp \left[-\frac{1}{2} \left(\frac{x_k - \mu}{\sigma} \right)^2 \right]$$

$$= \alpha' \cdot \exp \left[-\frac{1}{2} \left(\left(\frac{\mu - \mu_0}{\sigma_0} \right)^2 + \sum_{k=1}^n \left(\frac{\mu - x_k}{\sigma} \right)^2 \right) \right]$$

$$p(\mu|\mathcal{D}) \sim N(\mu_n, \sigma_n^2)$$

$$= \alpha'' \cdot \exp \left[-\frac{1}{2} \left[\left(\frac{n}{\sigma^2} + \frac{1}{\sigma_0^2} \right) \mu^2 - 2 \left(\frac{1}{\sigma^2} \sum_{k=1}^n x_k + \frac{\mu_0}{\sigma_0^2} \right) \mu \right] \right]$$

The Gaussian Case: Unknown μ

(Cont.)

$$p(\mu|\mathcal{D}) = \alpha'' \cdot \exp \left[-\frac{1}{2} \left[\left(\frac{n}{\sigma^2} + \frac{1}{\sigma_0^2} \right) \mu^2 - 2 \left(\frac{1}{\sigma^2} \sum_{k=1}^n x_k + \frac{\mu_0}{\sigma_0^2} \right) \mu \right] \right]$$

$$p(\mu|\mathcal{D}) = \frac{1}{\sqrt{2\pi}\sigma_n} \exp \left[-\frac{1}{2} \left(\frac{\mu - \mu_n}{\sigma_n} \right)^2 \right] = \alpha'' \cdot \exp \left[-\frac{1}{2} \left[\frac{1}{\sigma_n^2} \mu^2 - 2 \frac{\mu_n}{\sigma_n^2} \mu \right] \right]$$

Equating the
coefficients in
both form:

$$\frac{1}{\sigma_n^2} = \frac{n}{\sigma^2} + \frac{1}{\sigma_0^2}$$

$$\frac{\mu_n}{\sigma_n^2} = \frac{1}{\sigma^2} \sum_{k=1}^n x_k + \frac{\mu_0}{\sigma_0^2}$$



$$\sigma_n^2 = \frac{\sigma^2 \sigma_0^2}{n \sigma_0^2 + \sigma^2}$$

$$\mu_n = \frac{\sigma_n^2}{\sigma^2} \sum_{k=1}^n x_k + \frac{\sigma_n^2}{\sigma_0^2} \mu_0$$

The Gaussian Case: Unknown μ

(Cont.)

Phase II: *posterior pdf (for θ)* \rightarrow *class-conditional pdf (for \mathbf{x})*

$$\underbrace{p(\mu|\mathcal{D})}_{\text{posterior pdf (for } \theta\text{)}} + \underbrace{p(x|\mu)}_{\text{class-conditional pdf (for } \mathbf{x}\text{)}} \xrightarrow{\text{yellow arrow}} p(x|\mathcal{D})$$

$p(x|\mu) \sim N(\mu, \sigma^2)$

$p(\mu|\mathcal{D}) \sim N(\mu_n, \sigma_n^2)$

How would $p(x|\mathcal{D})$ look
like in this case?

$$\sigma_n^2 = \frac{\sigma^2 \sigma_0^2}{n\sigma_0^2 + \sigma^2}$$
$$\mu_n = \frac{\sigma_n^2}{\sigma^2} \sum_{k=1}^n x_k + \frac{\sigma_n^2}{\sigma_0^2} \mu_0$$

The Gaussian Case: Unknown μ

(Cont.)

Then, phase III
follows naturally
for prediction

$$p(x|\mathcal{D}) = \int p(x|\mu)p(\mu|\mathcal{D})d\mu \quad \text{Eq.25 [pp.92]}$$
$$= \int \frac{1}{\sqrt{2\pi}\sigma} \exp \left[-\frac{1}{2} \left(\frac{x - \mu}{\sigma} \right)^2 \right] \frac{1}{\sqrt{2\pi}\sigma_n} \exp \left[-\frac{1}{2} \left(\frac{\mu - \mu_n}{\sigma_n} \right)^2 \right] d\mu$$
$$= \beta \cdot \exp \left[-\frac{1}{2} \frac{(x - \mu_n)^2}{\sigma^2 + \sigma_n^2} \right] \quad \text{Eq.36 [pp.95]}$$

$p(x|\mathcal{D})$ is an exponential
function of a quadratic
function of x  $p(x|\mathcal{D})$ is a
normal pdf
as well

$$p(x|\mathcal{D}) \sim N(\mu_n, \sigma^2 + \sigma_n^2)$$

The Gaussian Case: Unknown μ (Multivariate)

$$\theta = \{\mu\} \text{ (} \Sigma \text{ is known)}$$



$$p(\mathbf{x}|\mu) \sim N(\mu, \Sigma)$$

$$p(\mu) \sim N(\mu_0, \Sigma_0)$$

$$p(\mu|\mathcal{D}) \sim N(\mu_n, \Sigma_n)$$

$$p(\mathbf{x}|\mathcal{D}) \sim N(\mu_n, \Sigma + \Sigma_n)$$

$$\mu_n = \Sigma_0 \left(\Sigma_0 + \frac{1}{n} \Sigma \right)^{-1} \frac{1}{n} \sum_{k=1}^n \mathbf{x}_k + \frac{1}{n} \Sigma \left(\Sigma_0 + \frac{1}{n} \Sigma \right)^{-1} \mu_0$$

$$\Sigma_n = \Sigma_0 \left(\Sigma_0 + \frac{1}{n} \Sigma \right)^{-1} \frac{1}{n} \Sigma$$

Summary

- Key issue for PR
 - Estimate prior and class-conditional pdf from training set
 - Basic assumption on training examples: *i.i.d.*
- Two strategies to the key issue
 - **Parametric form** for class-conditional pdf
 - Maximum likelihood (ML) estimation
 - Bayesian estimation
 - No parametric form for class-conditional pdf

Summary (Cont.)

- Maximum likelihood estimation
 - Settings: parameters as fixed but unknown values
 - The objective function: Log-likelihood function
 - Necessary conditions for ML estimation: gradient for the objective function should be zero vector
 - The Gaussian case
 - Unknown μ
 - Unknown μ and Σ

Summary (Cont.)

- Bayesian estimation

- Settings: **parameters as random variables**

- The general procedure

- Phase I: *prior pdf* \rightarrow *posterior pdf* (for θ)

- Phase II: *posterior pdf* (for θ) \rightarrow *class-conditional pdf* (for \mathbf{x})

- Phase III: *prediction* (Eq.22 [pp.91])

- The Gaussian case

- Unknown μ : univariate and multivariate