

Machine Learning: Business Applications

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ESAN Graduate School of Business

Datos Generales del Curso

Asignatura: Machine Learning: Aplicaciones en los Negocios

Área académica: Programa de Especialización para Ejecutivos

Año y semestre: 2019 – I

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Sumilla

- Este curso presenta métodos de machine learning con énfasis en problemas de clasificación y regresión de aprendizaje supervisado.
- El curso contiene sesiones de fundamentos matemáticos; sesiones de desarrollo metodológico y de aplicaciones.
- Se usará el software R para la resolución de casos de estudio.

Objetivos de la Asignatura

- Mejorar las capacidades cuantitativas de analistas y gerentes para interpretar los resultados de métodos que aprenden de los datos.
- Utilizar adecuadamente conceptos matemáticos básicos involucrados en los métodos de aprendizaje supervisado de Machine Learning.
- Utilizar el software R y sus librerías especializadas para es desarrollo de implementaciones propias o de terceros.

Programación de Contenidos

- Estadística básica:
 - Sesión 1: Introducción
 - Sesión 2: Software R
 - Sesión 3: Regresión lineal
- 2 Métodos Lineales:
 - Sesión 4: Modelos de Clasificación
 - Sesión 5: Métodos de Resampleo
 - Sesión 6: Regularización
 - Sesión 7: Reducción dimensional
 - Sesión 8: Taller
- Métodos No-Lineales:
 - Sesión 9: Splines
 - Sesión 10: GAMs
 - Sesión 11, 12: Árboles de decisión
 - Sesión 13, 14: Support Vector Machines
 - Sesión 15: Evaluación Final

Metodología

Las exposiciones del profesor se complementarán con actividades que harán los alumnos en el salón de clase, y fuera de él:

- Participar en clase.
- Leer la bibliografía indicada en el programa.
- Hacer las tareas.
- Rendir las evaluaciones programadas.

Evaluación

Nota Final = seis tareas (60%) + un examen final (40%).

- Las tareas se podrán realizar de manera individual o en parejas.
- El examen final es individual.
- El examen final es obligatorio, y se rendirá el día 23.05.19.

Fuentes de Información

- [EH06] Everitt, B. and T. Hothorn. A handbook of statistical analyses using R. Chapman & Hall/CRC, 2006.
- [JO13] James, G. et. al. (2013). An Introduction to Statistical Learning with Applications in R. Springer Series in Statistics.
- [HT09] Hastie, T., R. Tibshirani and J. Friedman (2009). The Elements of Statistical Learning: Data Mining, Inference and Prediction. Springer Series in Statistics.
- [RS05] Ramsay, J.O. and B.W. Silverman (2006). Functional Data Analysis. Springer Series in Statistics.
- [RO03] Ruppert, D., M. Wand and R. Carrol (2003).
 Semiparametric Regression. Cambridge Series in Statistical and Probabilistic Mathematics.
- [W06] Wood, S. (2006). Generalized Additive Models: An Introduction with R. Chapman & Hall/CRC.

Docente

Educación:

- Doctor. Matemáticas y Ciencia Comp. Universidad de Göttingen.
- Magister. Matemáticas Ap. y Estadística. SUNY Stony Brook.
- Magister. Matemáticas. PUCP.
- Licenciado y Bachiller. Economía. UP.

Experiencia:

- 2019: Profesor Investigador. TI. U. ESAN.
- 2018: Gerente. Financial Services Office. EY Perú.
- 2017: Profesor investigador. Finanzas. U. del Pacífico.
- 2011–2016: Investigador asociado. IMS. U. Göttingen.
- 2005–2008: Científico Investigador. CGIAR. CIP.

Asistentes

- Expectativa: analista, gerente, etc.
- Sectores: banca, seguros, reguladores, etc.
- Lenguajes: Python, R, C++, Matlab, etc.

Materiales

Desde un celular:



Desde un navegador:

https://github.com/LFRM/Lectures

Introduction

Overview

- Machine Learning: is a toolbox to understand data using statistics
- Objectives
 - Prediction / to predict something
 - 2 Inference / to explain something
- Problems
 - **1** Supervised learning: "input \Rightarrow output" structure.
 - 2 Unsupervised learning: only "input" structure.
- Methods
 - 1 Regression
 - 2 Classification
 - 3 Clustering

Basics

The general model follows:

$$Y = f(X) + \epsilon, \quad X = \{X_1, \dots, X_p\}$$

where

- *Y* is called response / dependent variable
- X are called features / independent variables / predictors
- f is a non-random function
- lacksquare is a random error term, independent of X, and with zero mean.

In this course: we find f to predict / explain.

Basics

Usual Steps:

- \blacksquare We observe predictors X and response Y.
- 2 We characterize their relationship

$$Y = f(X) + \epsilon. \tag{1}$$

- **3** We estimate \hat{f} "somehow".
- 4 We use \hat{f} in X to make prediction \hat{Y}

$$\hat{Y} = \hat{f}(X). \tag{2}$$

Focus depends on Goals:

- Prediction: we care mostly about \hat{Y} .
- Inference: we care mostly about \hat{f} .

Estimation Error

Proposition 1

$$\mathbb{E}[(Y - \hat{Y})^2] = \underbrace{\mathbb{E}[(f(X) - \hat{f}(X))^2]}_{Reducible} + \underbrace{Var[\epsilon]}_{Irreducible} . \tag{3}$$

Proof. Trivial. Direct substitution from (1) and (2).

Interpretation of proposition 1:

- The magnitude of the estimation error has a reducible and an irreducible component.
- We cannot reduce the estimation error below $Var[\epsilon]$.

Estimation of *f*: Parametric vs. Non-Parametric

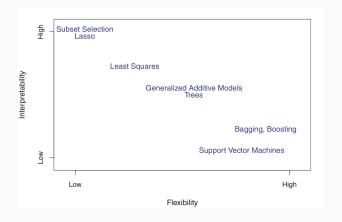
Parametric Methods:

- Impose rigid structure on f, e.g. f is linear.
- Trade-off: easy to interpret vs. bad accuracy.

Non-Parametric Methods:

- Impose flexible structure on f, e.g. f is a piecewise polynomial.
- Trade-off: difficult to interpret vs. good accuracy.

Estimation of f: Parametric vs. Non-Parametric



Source: [JO13]

Estimation of f: Regression vs. Classification

- Discrete response \Rightarrow classification / cont. response \Rightarrow regression.
- Specific methods for regression or classification.
- Some methods deal with both, e.g. K-nearest neighbors, boosting.

Estimation of *f***: Assessing Model Accuracy**

Definition 1.1 (Mean Squared Error)

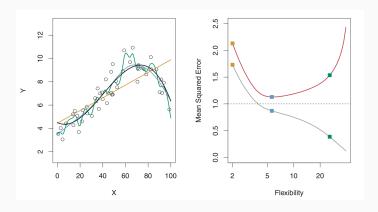
The Mean Squared Error (MSE) is defined as

MSE :=
$$Ave\{(y_i - \hat{f}(x_i))^2\}$$
 (4)
= $\frac{1}{n}\sum_{i=1}^{n}(y_i - \hat{f}(x_i))^2$.

We call it "train" MSE if we compute it with training data (X, Y) and "test" MSE if we compute it with "test" data (X_0, Y_0) .

- Train MSE can be reduced arbitrarily (overfitting).
- Test MSE cannot be reduced arbitrarily.
- Test MSE is used for model selection.

Estimation of *f***: Assessing Model Accuracy**



Left: data (circles), true function (black), linear fit (orange), spline fit 1 (blue), spline fit 2 (green). Right: train MSE (gray), test MSE (red).

Source: [JO13]

Estimation of *f*: **Bias** - **Variance Trade-off**

Proposition 2

Given x_0 , the expected test MSE can be decomposed into the sum of three quantities: the variance of $\hat{f}(x_0)$, the squared bias of $\hat{f}(x_0)$ and the variance of the error term.

Proof. From proposition 1 we known that

$$\mathbb{E}[(y_0 - \hat{f}(x_0))^2] = \mathbb{E}[(f(x_0) - \hat{f}(x_0))^2] + \text{Var}[\epsilon]$$

$$= \mathbb{E}[(\{f(x_0) - \mathbb{E}[\hat{f}(x_0)]\} - \{\hat{f}(x_0) - \mathbb{E}[\hat{f}(x_0)]\})^2] + \text{Var}[\epsilon],$$

Thus,

$$\mathbb{E}[(y_0 - \hat{f}(x_0))^2] = \underbrace{\mathbb{E}[(f(x_0) - \mathbb{E}[\hat{f}(x_0)])^2]}_{\text{Squared Bias of } \hat{f}} + \underbrace{\mathbb{E}[(\hat{f}(x_0) - \mathbb{E}[\hat{f}(x_0)])^2]}_{\text{Variance of } \hat{f}}$$

$$+ \underbrace{\text{Var}[\epsilon]}_{\text{Variance of error}}$$

Estimation of *f***: Bias - Variance Trade-off**

Interpretation of proposition 2:

- The reducible error is a mixture of bias and variance.
- To minimize the expected test MSE we need a method that minimizes both Bias and Variance.

Methods:

- More flexible methods: ↓ bias and ↑ variance.
- Less flexible methods: ↑ bias and ↓ variance.
- The adequacy of the method depends on the data.

Estimation of *f*: Classification Setting

Definition 1.2 (Training Error Rate)

The training error rate (TER) is the proportion of mistakes that the classifier makes in the training set

TER: =
$$Ave\{\mathcal{I}_{\hat{y}_i \neq y_i}\}$$
 (5)
= $\frac{1}{n} \sum_{i=1}^{n} \mathcal{I}_{\hat{y}_i \neq y_i},$

Definition 1.3 (Bayes Classifier)

The Bayes classifier minimizes (5), by selecting the value of j such that

$$max_{j}\mathbb{P}[Y=j|X=x_{0}], \tag{6}$$

for each x_0 in the test data set.

Estimation of *f***: Classification Setting**

Note that the Bayes classifier:

- Is theoretical, i.e. the conditional probability in (6) is unknown.
- Provides a lower bound on TER,

$$\mathsf{TER} \geq 1 - \mathbb{E}\left[\mathsf{max}_j\mathbb{P}[Y=j|X=x_0]\right]$$

Estimation of *f*: Classification Setting

Definition 1.4 (*K***-Nearest Neighbors)**

K-Nearest Neighbors (KNN) is a classification method that requires a positive integer K. For a test observation x_0 , it identifies K points near x_0 , called \mathcal{N}_0 , and estimates the conditional probability for class j as:

$$\hat{\mathbb{P}}[Y=j|X=x_0]=\frac{1}{K}\sum_{i\in\mathcal{N}_0}\mathcal{I}_{y_i=j},$$

i.e. as the fraction of the points in \mathcal{N}_0 whose response values equal j.

Note that:

- *K* has a strong effect on the classification obtained by KNN.
- Small K: \downarrow bias and \uparrow variance.
- Large K: ↑ bias and \downarrow variance.

R Software

The R Project for Statistical Computing

- This is an extremely short introduction to R.
- Click here to download the software.
- For more information look at my lecture notes in Applied Statistics.

For now, lets run R online:



- The call for the function is function is function (arg1, arg2), where arg1 and arg2 are args. of the function.
 - 1 What does c() evaluated in the arguments 1 and 2 does?
 - 2 Does the order of the arguments matter?
- We can store values using "<-" or "=".

$$> x < -c(1,2)$$

$$> y = c(4,-1)$$

$$> x + y$$

Let
$$z1 = 1000$$
 and $z2 = rep(1000, 3)$. Compute

- 1 x + z1
- 2 x + z2

- To ask for help on function funcname use ?funcname
- To list all the objects in the workspace use ls().
- To delete object obj from the workspace use rm(obj).
- To delete every object use rm(list = ls())

■ To create a matrix use matrix

■ Compute

■ To create a realization of a normal random variable use rnorm. To specify the mean, use mean and, to specify the standard deviation, use sd

```
> x <- rnorm(10000)
> y <- rnorm(10000, mean = 50, sd = 0.1)
```

■ To compute the correlation between two r.v.s use cor.

```
> z <- x + y
> cor(x, z)
[1] 0.9951
```

■ To reproduce the exact same random number use set.seed() with an arbitrar integer argument, e.g. set.seed(123)

```
> set.seed(123)
> rnorm(5)
[1] -0.56047565 -0.23017749 1.55870831 ...
```

Graphics

■ There are various functions for plotting. See ?plot

```
> x = rnorm(100) + 1:100
 > y = rnorm(100) + seq(-1, -100, length = 100)
 > plot(x, y)
 > plot(x, y, xlab = "this is my x-axis",
   ylab = "this is my y lab", main = "Plot x vs y")
■ To save the output use pdf(), or jpeg()
 > pdf("myfgure.pdf")
 > plot(x, y, color = 2, lwd = 3)
 > dev.off()
 null device
```

Graphics

```
Let f: \mathbb{R}^2 \to \mathbb{R},
```

 \blacksquare To plot the contour of f use contour or image.

```
> x = 1:10
> y = x
> f = outer( x, y, function (x, y) cos(y) / (1 + x ^ 2) )
> contour(x, y, f)
> contour(x, y, f, nlevels = 45)
> fa = ( f - t(f) ) / 2
> contour( x, y, fa, nlevels = 15)
> image(x, y, fa)
```

■ To plot *f* in three dimensions use persp.

```
> persp(x, y, fa)
> persp(x, y, fa, theta = 30, phi = 20)
> persp(x, y, fa, theta = 30, phi = 40)
```

Indexing Matrix Data

Extracting part of a data set can be done in different ways:

Compute

- 1 A[2,3]
- 2 A[1,]
- 3 A[1:3, c(2,4)]
- 4 A[,-4]
- 5 dim(A)

Loading Data

■ To import data use read.table() or read.csv(); and to visualize the imported data use fix().

```
> Auto = read.csv("Auto.csv", header = T, sep=" ")
> fix(Auto)
> dim(Auto)
[1] 392 9
```

■ To list the variable names in the data set use names().

```
> names(Auto)
[1] "mpg" "cylinders" "displacement" "horsepower"
[5] "weight" "acceleration" "year" "origin"
[9] "name"
```

■ To export data use write.table()

Additional Graphical and Numerical Summaries

- To access a variable cylinders in data frame Auto, we use
 - > Auto\$cylinders
- To avoid using the dollar symbol, we can simply attach the data, so that all the variables in the data frame are added to the workspace.
 - > attach(Auto)
 - > plot(cylinders, mpg)
- Plot the following:
 - 1 mpg vs. cylinders using red circles
 - 2 mpg vs. cylinders using a red circles, with axis labels "mpg" and "cylinders" resp.

Additional Graphical and Numerical Summaries

- To plot a histogram use hist()
 - > hist(mpg)
 - > hist(mpg, col = 2)
- To create a scatterplot matrix use pairs()
 - > pairs(Auto)
 - > pairs(~ mpg + displacement + horsepower
 - + weight + acceleration, Auto)
- To print a summary of a given variable or data frame, use summary()
 - > summary(mpg)
 - > summary(Auto)

Homework

Exercises 2, 3, 4, 6, 7, 9, 10 from [JO13].

Linear Regression

Motivation

What?

Supervised learning method for continuous response.

Why?

- Well document starting point.
- Recall: not flexible, tipically \uparrow bias and \downarrow variance.
- Fancy approaches are extensions/generalizations of linear regression.

Simple Linear Regression

Model:

$$Y = f(X) + \epsilon, \quad f(X) = \beta_0 + \beta_1 X, \tag{7}$$

where ϵ is a centered random noise, uncorrelated to X.

Estimation

■ Idea: estimate f(X) via

$$\hat{f}(X) = \hat{\beta}_0 + \hat{\beta}_1 X,\tag{8}$$

e.g. identifying $\hat{\beta}_0$, $\hat{\beta}_1$ that fulfills the least squares criteria.

■ Least Squares Criteria:

$$(\hat{\beta}_0, \hat{\beta}_1) = \operatorname{argmin}_{\hat{\beta}_0, \hat{\beta}_1} RSS$$
 (9)

where the minimized quantity:

RSS :=
$$\sum_{i=1}^{n} e_i^2$$
, $e_i := y_i - \hat{y}_i$, (10)

is the "Residual Sum of Squares" (RSS) of the model.

Estimation

■ FOC:

$$\frac{\partial RSS}{\partial \hat{\beta}_0} = \hat{\beta}_0 + \hat{\beta}_1 \bar{x} - \bar{y} = 0, \tag{11}$$

$$\frac{\partial RSS}{\partial \hat{\beta}_1} = \hat{\beta}_0 \sum_{i=1}^n x_i + \hat{\beta}_1 \sum_{i=1}^n x_i^2 - \sum_{i=1}^n x_i y_i = 0.$$
 (12)

with solution

$$\hat{\beta}_0 = \bar{y} - \hat{\beta}_1 \bar{x}, \tag{13}$$

$$\hat{\beta}_1 = \frac{\sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y})}{\sum_{i=1}^n (x_i - \bar{x})^2}.$$
 (14)

RSS is convex, thus the SOC is fullfilled.

Unbiasedness

Recall:

- Let $Z \sim (\mu, \sigma)$, where mean μ and s.d. σ are unknown.
- Sample mean estimator: Collect n random samples of Z, and estimate μ by $\hat{\mu} = \frac{1}{n} \sum_{i=1}^{n} z_i$. Repeat the previous m times with different samples of size n: $\{\hat{\mu}^{(1)}, \hat{\mu}^{(2)}, \dots, \hat{\mu}^{(m)}\}$.
- lacksquare Unbiasedness: We say $\hat{\mu}$ is an unbiased estimator of μ if

$$\frac{1}{m} \sum_{k=1}^{m} \hat{\mu}^{(k)} \to \mu \quad \text{as} \quad k \to \infty.$$

■ Variance: The precision of the sample mean estimator is

$$Var[\hat{\mu}] = SE(\hat{\mu})^2 = \frac{\sigma^2}{n}.$$

Linear regression:

- \blacksquare β_0 and β_1 are r.v.s, and given some data we estimate them by $\hat{\beta}_0$ and $\hat{\beta}_1$, but the estimators vary according to the random sample.
- Unbiasedness: if we consider m random samples, we obtain $\hat{\beta}_0^{(k)}$ and $\hat{\beta}_{1}^{(k)}$, for $k=1,\ldots,m$. It can be shown that

$$\frac{1}{m}\sum_{k=1}^m \hat{\beta}_0^{(k)} \to \beta_0 \quad \text{and} \quad \frac{1}{m}\sum_{k=1}^m \hat{\beta}_1^{(k)} \to \beta_1 \quad \text{as} \quad k \to \infty,$$

thus $\hat{f}(X)$ is an unbiased estimator of f(X).

■ Variance: The precision of the estimators follow:

$$Var[\hat{\beta}_{0}] = \sigma^{2} \left[\frac{1}{n} + \frac{\bar{x}^{2}}{\sum_{i=1}^{n} (x_{i} - \bar{x})^{2}} \right],$$

$$Var[\hat{\beta}_{1}] = \frac{\sigma^{2}}{\sum_{i=1}^{n} (x_{i} - \bar{x})^{2}}.$$
(15)

$$Var[\hat{\beta}_{1}] = \frac{\sigma^{2}}{\sum_{i=1}^{n} (x_{i} - \bar{x})^{2}}.$$
 (16)