

Calibration results

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Camera-system parameters:

cam0 (/image_raw):

type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>

distortion: [0.00230827 0.03159201 -0.00067236 0.00378966] +- [0.00322197 0.00878667 0.00041228 0.00048088]

projection: [937.78627253 936.05546548 492.14983865 370.77383202] +- [2.04068173 2.0259555 1.42284356 1.33676124]

reprojection error: [-0.000000, -0.000000] +- [0.586178, 0.547866]

Target configuration

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Type: aprilgrid

Tags:

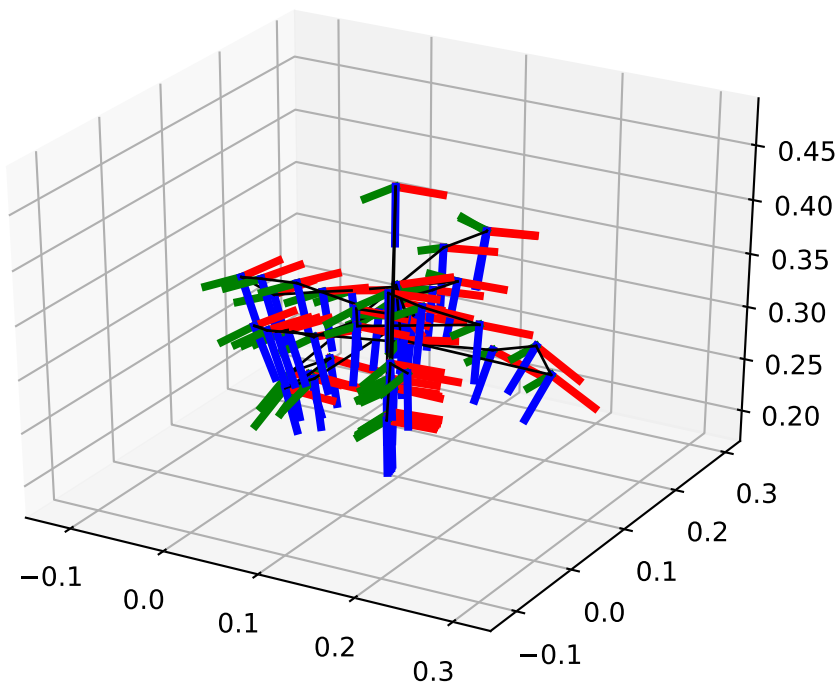
Rows: 6

Cols: 6

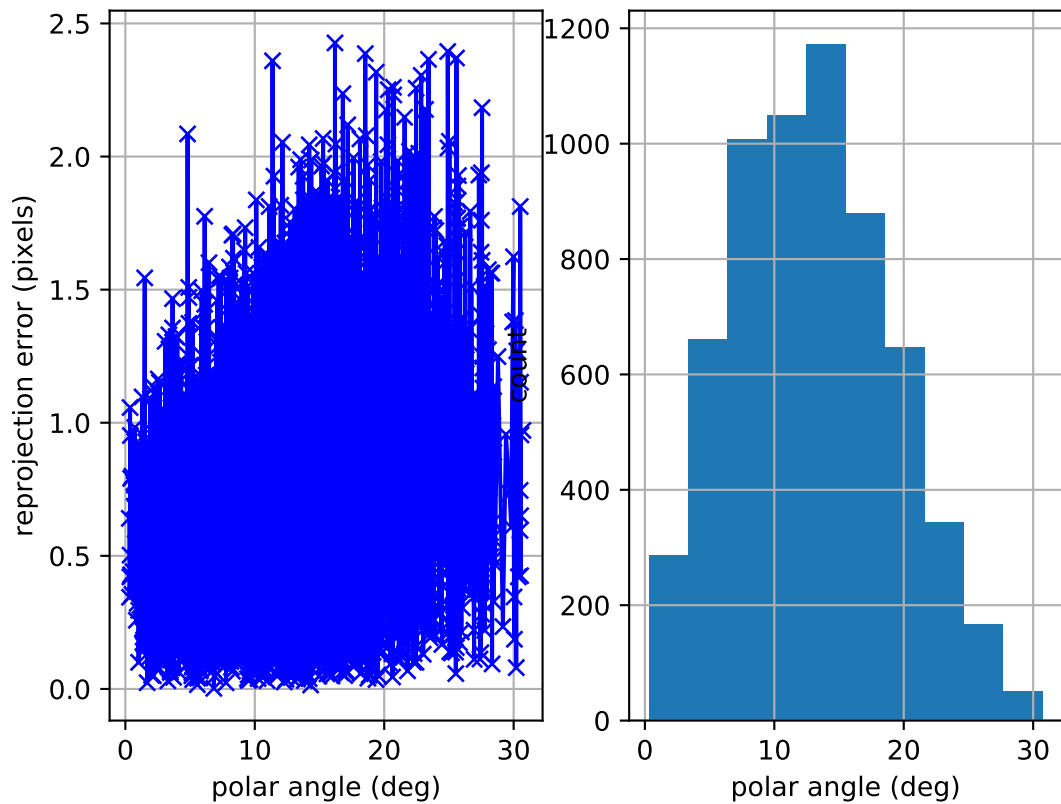
Size: 0.021 [m]

Spacing 0.0063 [m]

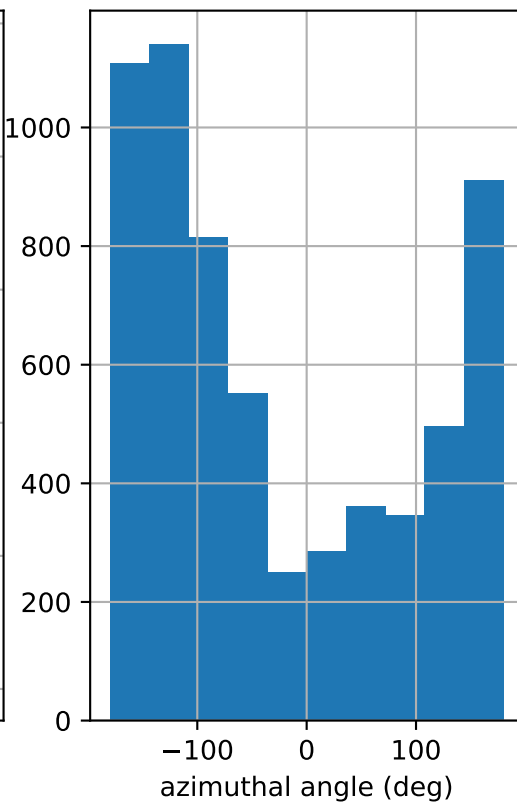
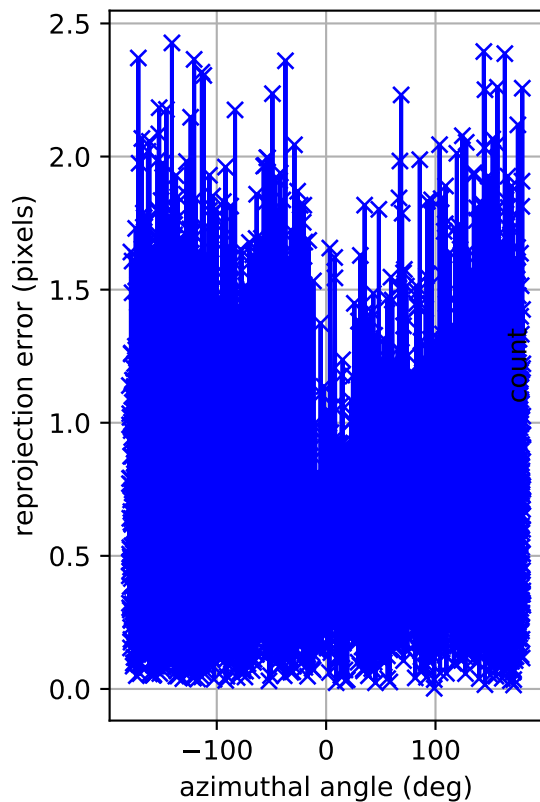
cam0: estimated poses



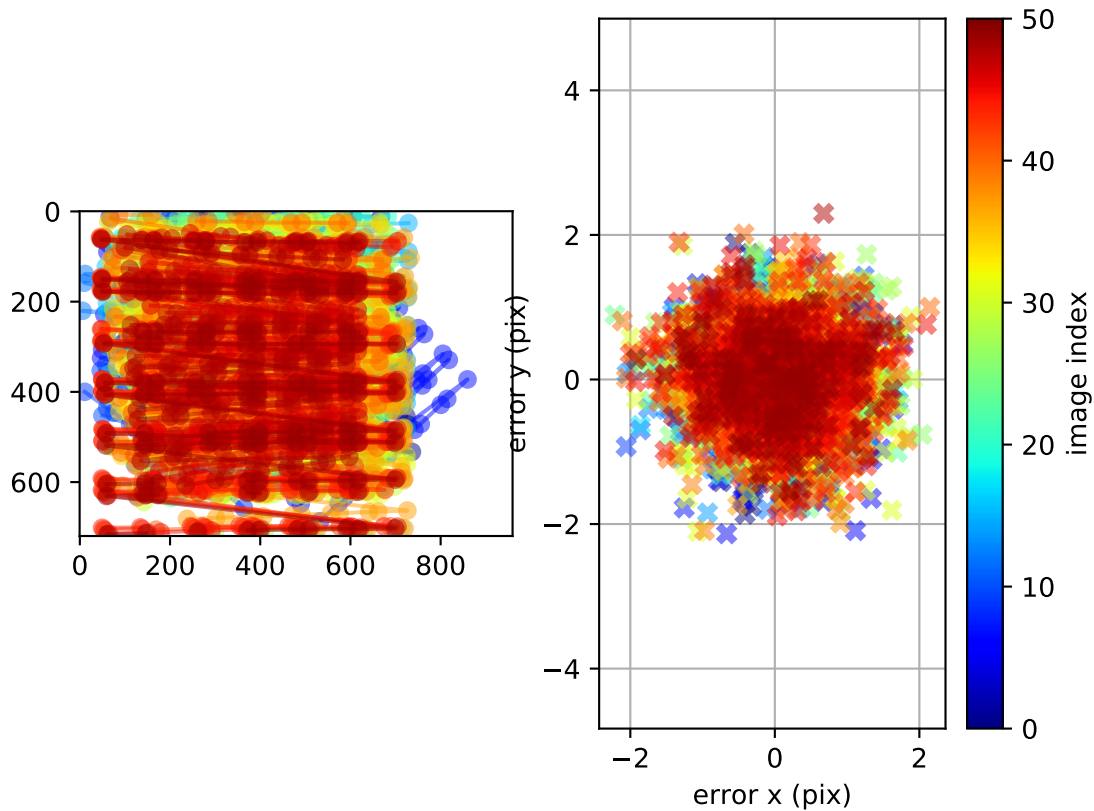
cam0: polar error



cam0: azimuthal error



cam0: reprojection errors



Location of removed outlier corners

