

SVM-KKT

SVM을 최적화 하기 위해선 KKT 조건을 활용한다.

SVM의 제약조건은 릿지회귀에서 보다 더 복잡하므로 KKT 조건을 사용하여 최적화를 진행한다.

$$\text{목적함수} \quad \min \frac{1}{2} \|w\|^2$$

$$\text{제약조건} \quad y_i(w^T x_i + b) \geq 1$$

라그랑주 함수 정의

$$L(w, b, \alpha) = \frac{1}{2} \|w\|^2 - \sum_{i=1}^n \alpha_i \{ y_i (w^T x_i + b) - 1 \}$$

KKT 조건

① stationarity

$$\nabla L(w, b, \alpha) = 0$$

② primal feasibility

$$y_i (w^T x_i + b) \geq 1$$

③ dual feasibility

$$\alpha_i \geq 0$$

④ complementary slackness

$$\alpha_i \{ y_i (w^T x_i + b) - 1 \} = 0$$

stationarity

$\nabla L(w, b, \alpha)$ 를 계산해보겠다.

$$L(w, b, \alpha) = \frac{1}{2} \|w\|^2 - \sum_{i=1}^n \alpha_i \{y_i (w^T x_i + b) - 1\}$$

$$\frac{d}{dw} L(w, b, \alpha) = w - \sum_{i=1}^n \alpha_i y_i x_i = 0$$

$$w = \sum_{i=1}^n \alpha_i y_i x_i$$

$$\frac{d}{db} L(w, b, \alpha) = - \sum_{i=1}^n \alpha_i y_i = 0$$

$$\sum_{i=1}^n \alpha_i y_i = 0$$

종합해보면, 다음 2가지 결과를 얻었다

$$w^* = \sum_{i=1}^n \alpha_i y_i x_i$$

$$\sum_{i=1}^n \alpha_i y_i = 0$$

$L(w, b, \alpha)$ 를 $w^* = \sum_{i=1}^n \alpha_i y_i x_i$ 를 이용하여

dual 문제 $L(w^*, b^*, \alpha)$ 의 해를 찾아 보겠다.

$$\frac{1}{2} \|w^*\|^2 = \frac{1}{2} w^{*T} w^*$$

$$= \frac{1}{2} w^{*T} \sum_{i=1}^n \alpha_i y_i x_i$$

$$= \frac{1}{2} \sum_{i=1}^n \alpha_i y_i (w^{*T} x_i)$$

$$w^{*T} = \sum_{j=1}^n \alpha_j y_j x_j^T$$

$$= \frac{1}{2} \sum_{i=1}^n \alpha_i y_i \sum_{j=1}^n \alpha_j y_j x_j^T x_i$$

$$= \frac{1}{2} \sum_{i=1}^n \sum_{j=1}^n \alpha_i \alpha_j y_i y_j x_j^T x_i$$

$$\begin{aligned}
& \sum_{i=1}^n \alpha_i \left\{ y_i (w^T x_i + b) - 1 \right\} \\
&= \sum_{i=1}^n \alpha_i y_i (w^T x_i + b) - \sum_{i=1}^n \alpha_i \\
&= \sum_{i=1}^n \alpha_i y_i w^T x_i + b \sum_{i=1}^n \alpha_i y_i - \sum_{i=1}^n \alpha_i \\
&\quad \sum_{i=1}^n \alpha_i y_i = 0 \\
&\quad \sum_{i=1}^n \alpha_i y_i w^T x_i = \|w^*\|^2 \\
&= \sum_{i=1}^n \sum_{j=1}^n \alpha_i \alpha_j y_i y_j x_j^T x_i - \sum_{i=1}^n \alpha_i
\end{aligned}$$

이를 통해서 $L(w^*, b^*, \alpha) = \sum_{i=1}^n \alpha_i - \sum_{i=1}^n \sum_{j=1}^n \alpha_i \alpha_j y_i y_j x_j^T x_i$

원래 라그랑주 함수는 $L(w, b, \alpha) = \frac{1}{2} \|w\|^2 - \sum_{i=1}^n \alpha_i \{y_i (w^T x_i + b) - 1\}$

목적함수인 $\frac{1}{2} \|w\|^2$ 를 최소화하려면 α 를 최대화 해야 한다.

$L(w^*, b^*, \alpha)$ 를 $L_{dual}(\alpha)$ 라 둔다면 α 를 최대화 해야 한다.

정리해하면,

$$\text{maximize } L_{dual}(\alpha) = \sum_{i=1}^n \alpha_i - \sum_{i=1}^n \sum_{j=1}^n \alpha_i \alpha_j y_i y_j x_j^T x_i$$

$$\text{subject to } \begin{cases} \sum_{i=1}^n \alpha_i y_i = 0 \\ \alpha_i \geq 0 \end{cases}$$