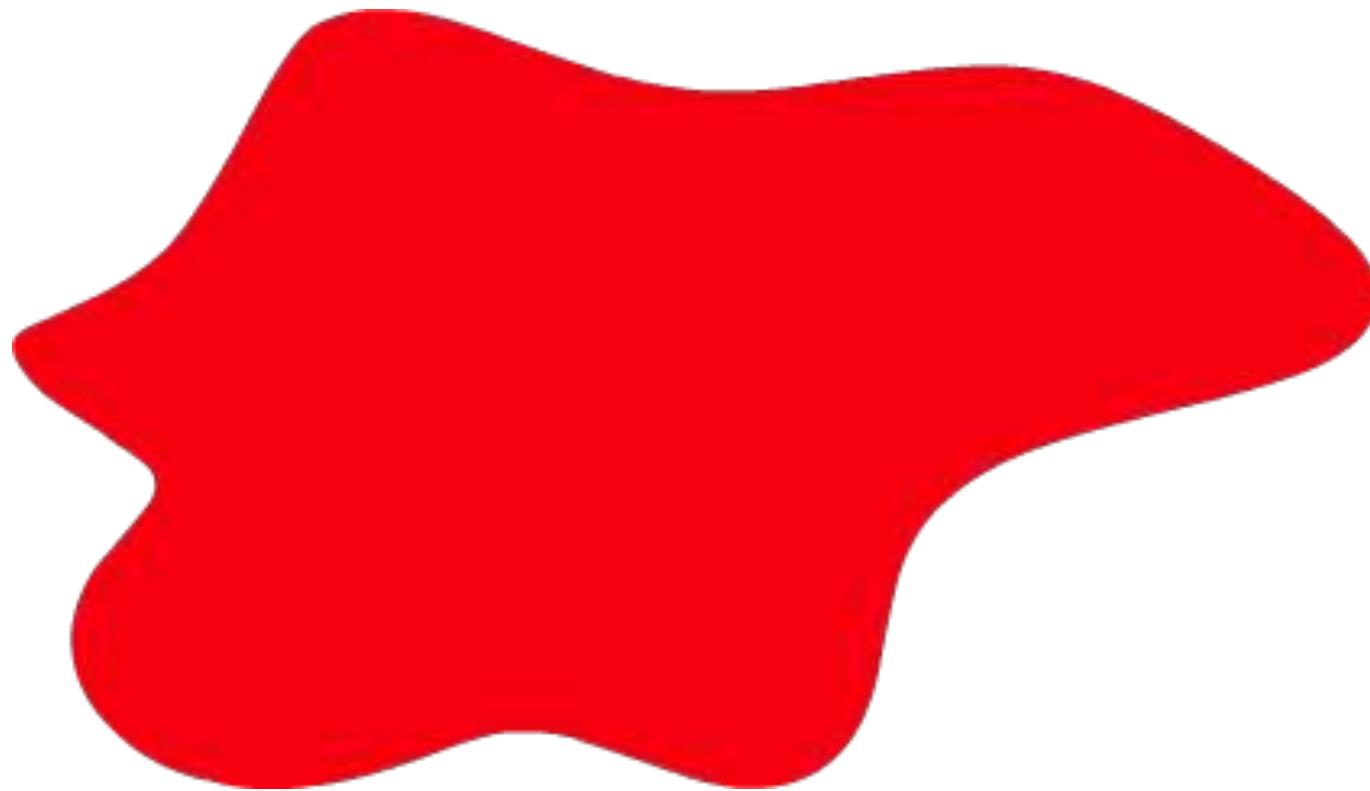


Constrained CNNs

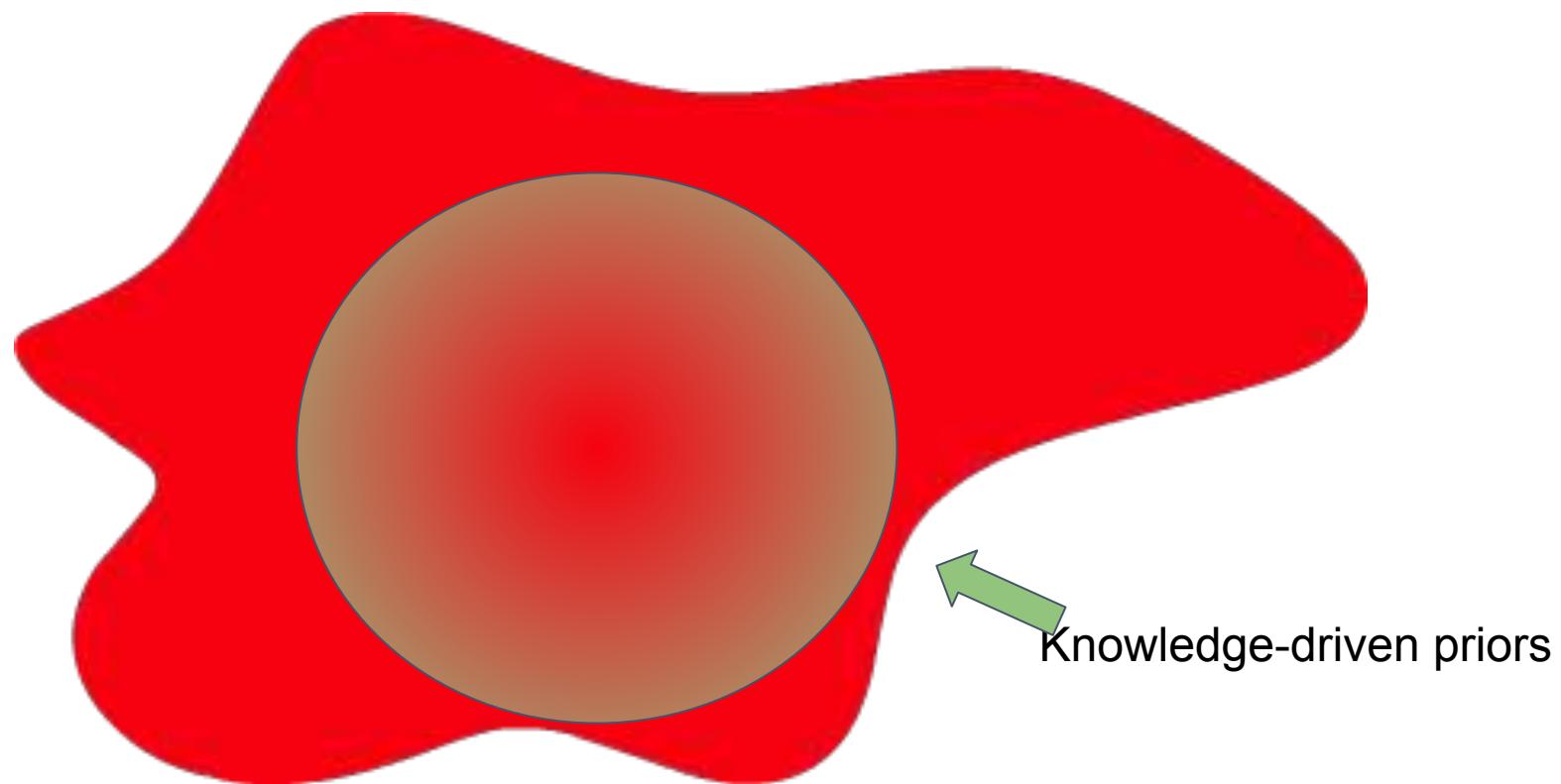
Constrained optimization (in CNNs)

Knowledge vs data driven priors



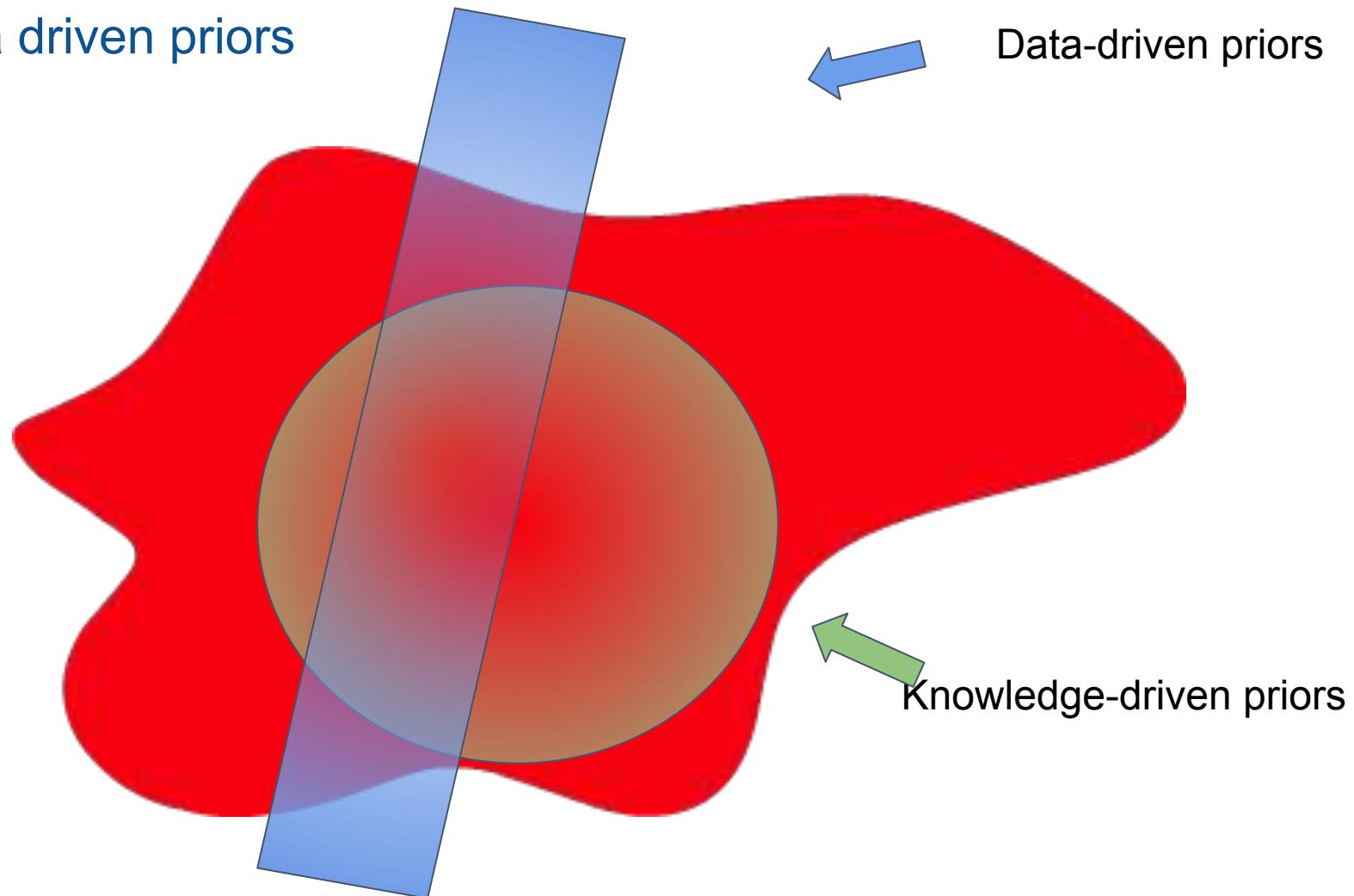
Constrained optimization (in CNNs)

Knowledge vs data driven priors



Constrained optimization (in CNNs)

Knowledge vs data driven priors

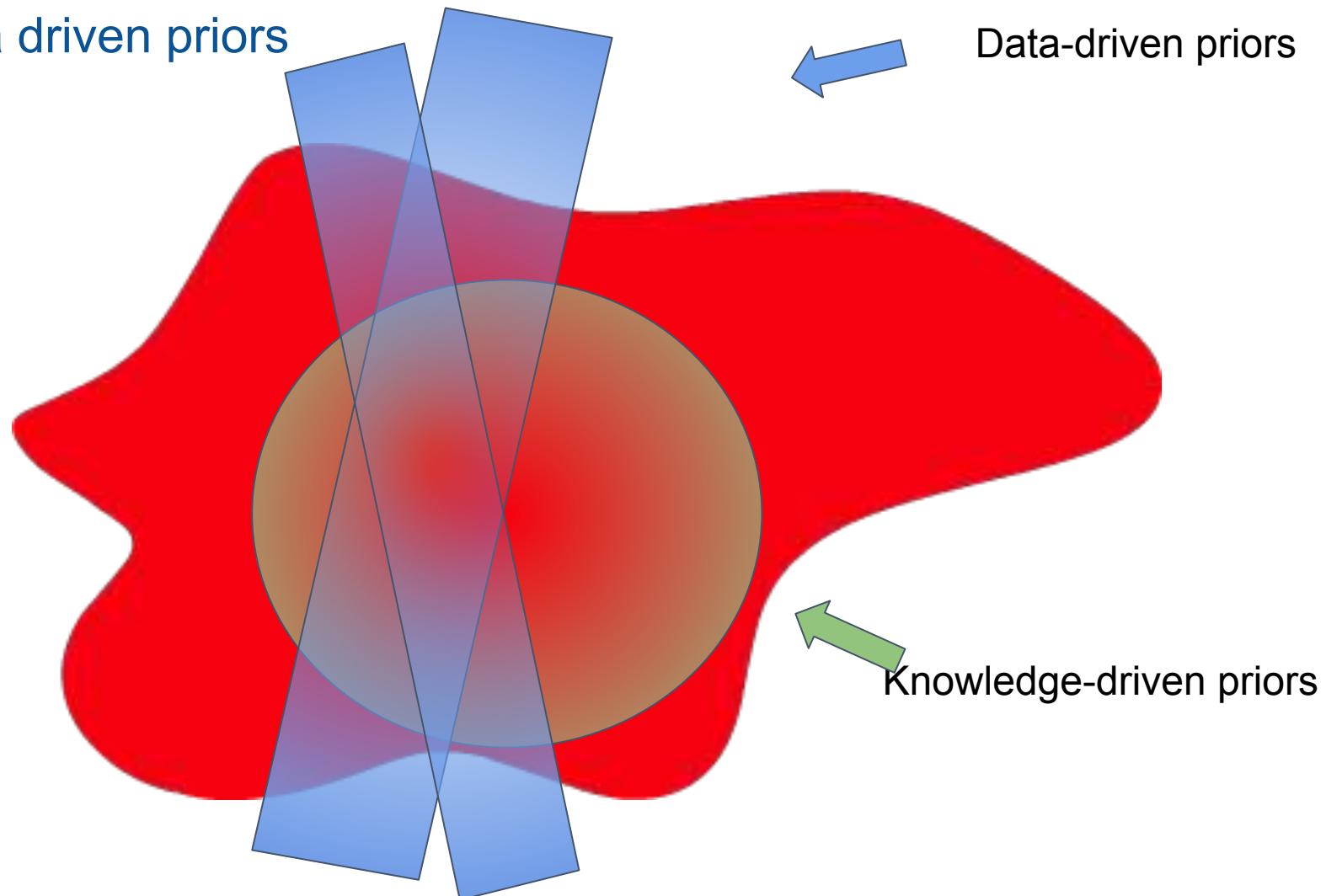


Data-driven priors

Knowledge-driven priors

Constrained optimization (in CNNs)

Knowledge vs data driven priors



Data-driven priors

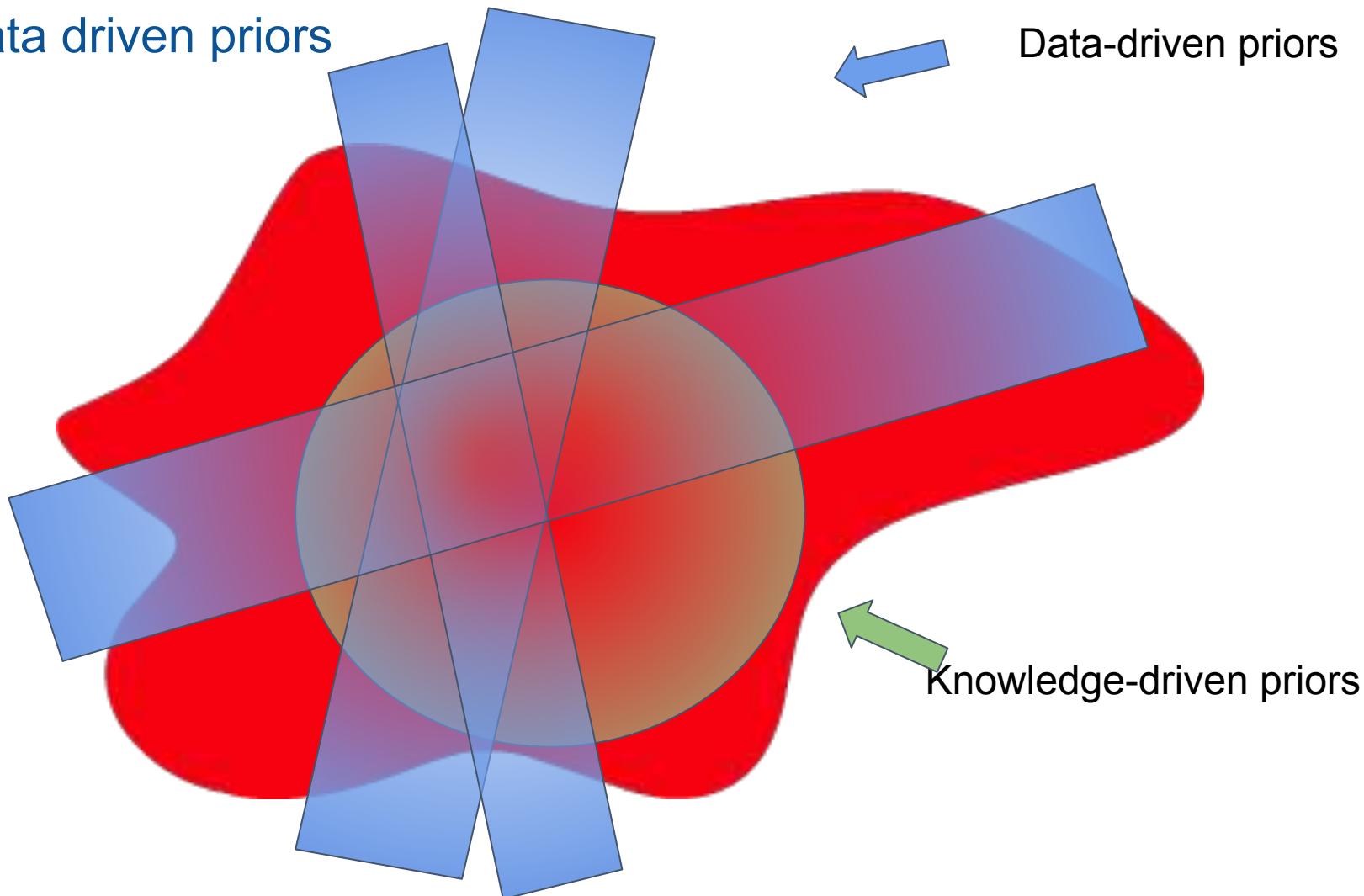
Knowledge-driven priors

Constrained optimization (in CNNs)

Knowledge vs data driven priors

Data-driven priors

Knowledge-driven priors



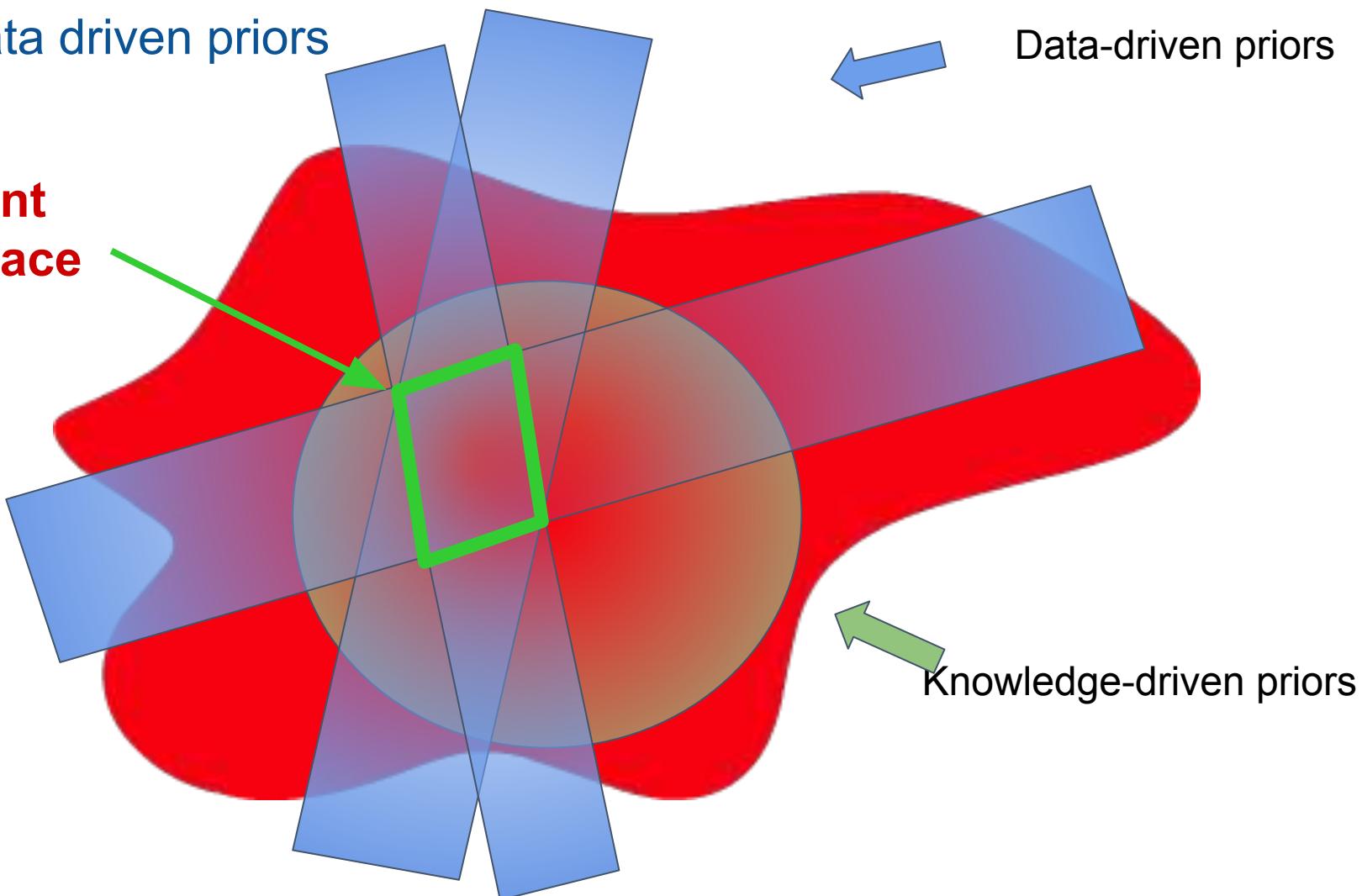
Constrained optimization (in CNNs)

Knowledge vs data driven priors



Data-driven priors

Both constraint
the search space



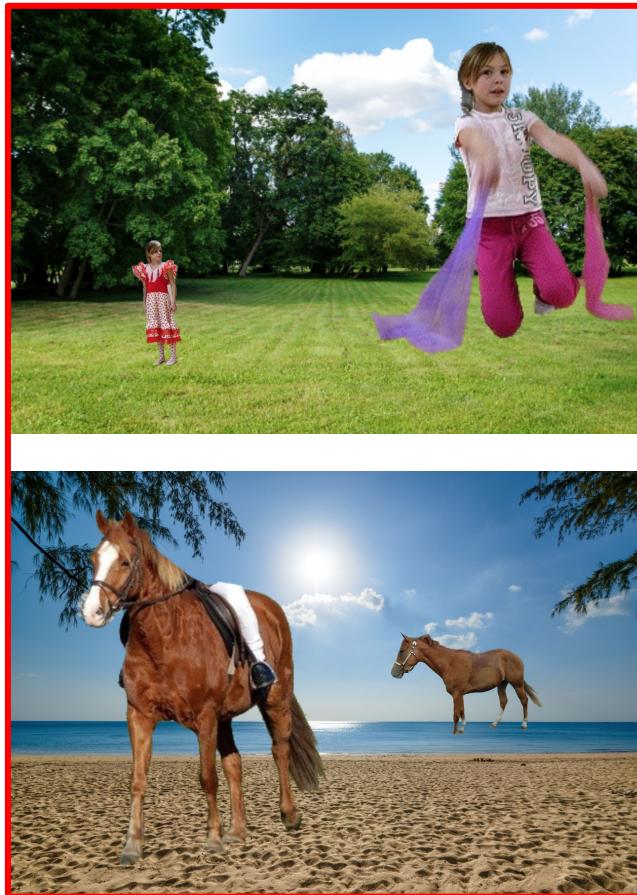
Knowledge-driven priors

Constrained optimization (in CNNs)

Knowledge-driven priors

Common priors in natural images

Target Size



- Pathak et al., Constrained convolutional neural networks for weakly supervised segmentation, ICCV 2015
- Xu et al., Learning to Segment Under Various Forms of Weak Supervision, CVPR 2015
- Zhang et al., Curriculum Domain Adaptation for Semantic Segmentation of Urban Scenes. ICCV'17

Constrained optimization (in CNNs)

Knowledge-driven priors

Common priors in natural images

Target Location



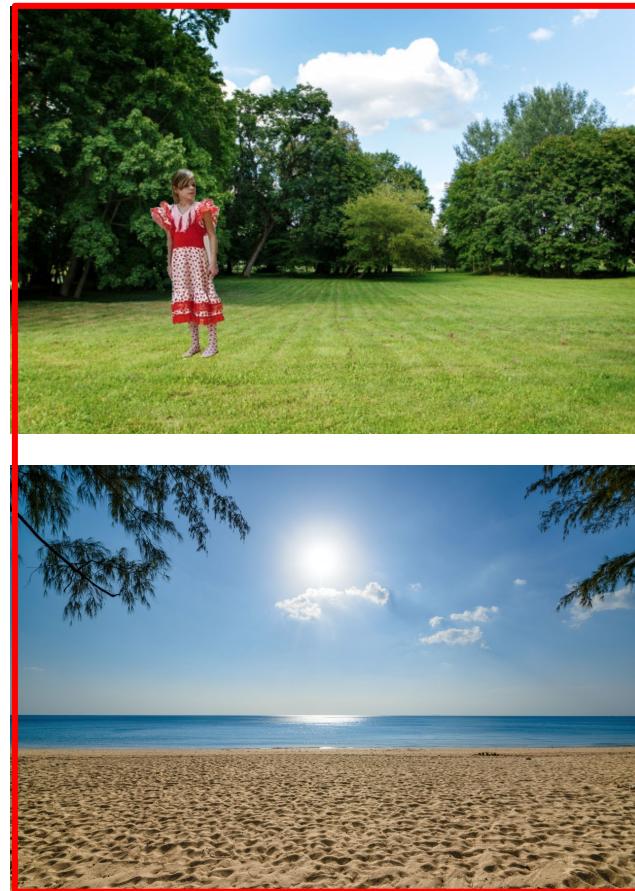
- Remez et al. Learning to segment via cut-and-paste. ECCV 2018
- Georgakis et al Synthesizing training data for object detection in indoor scenes. RSS 2017

Constrained optimization (in CNNs)

Knowledge-driven priors

Common priors in natural images

Number of instances



- Deselaers et al. Localizing objects while learning their appearance. ECCV 2010

Constrained optimization (in CNNs)

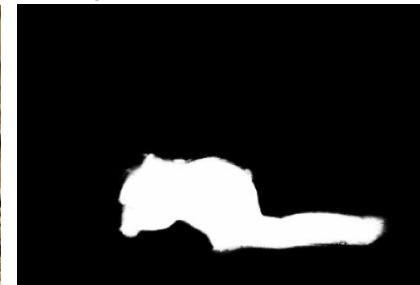
Knowledge-driven priors

Common priors in natural images

Contrast
Foreground/Background



Saliency



Images from Hou et al, CVPR'17

- Hou et al. Deeply supervised salient object detection with short connections. CVPR 2017
- Li et al. Instance-level salient object segmentation. CVPR 2017

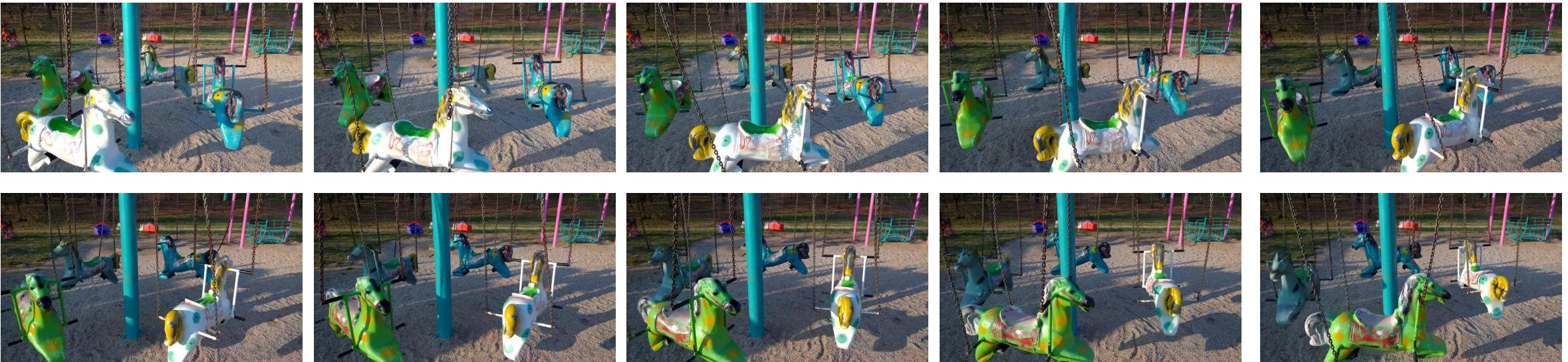
Constrained optimization (in CNNs)

Knowledge-driven priors

Common priors in natural images

Motion

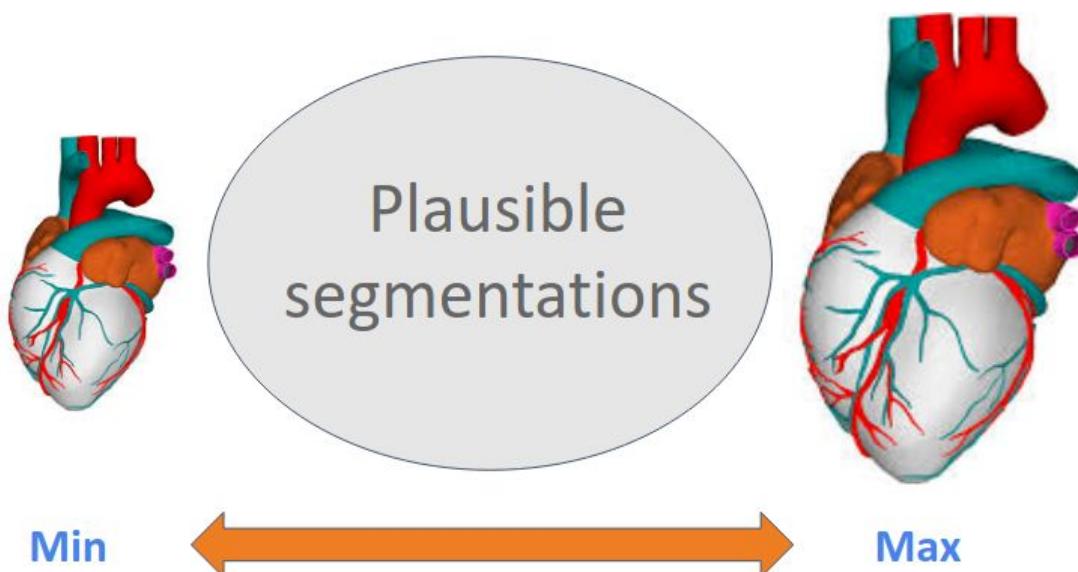
Images from the DAVIS Challenge Dataset



- Tokmakov et al. Weakly-supervised semantic segmentation using motion cues. ECCV 2016
- Pathak et al. Learning features by watching objects move. CVPR 2017

Constrained optimization (in CNNs)

Knowledge-driven priors



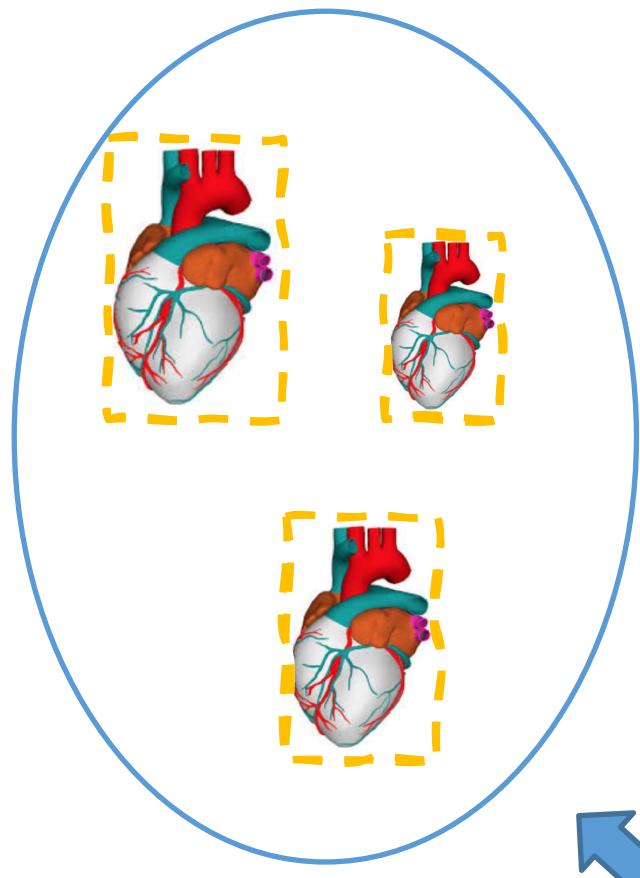
What about priors in the medical domain?



Partial labeled data
(exploit target relationships)

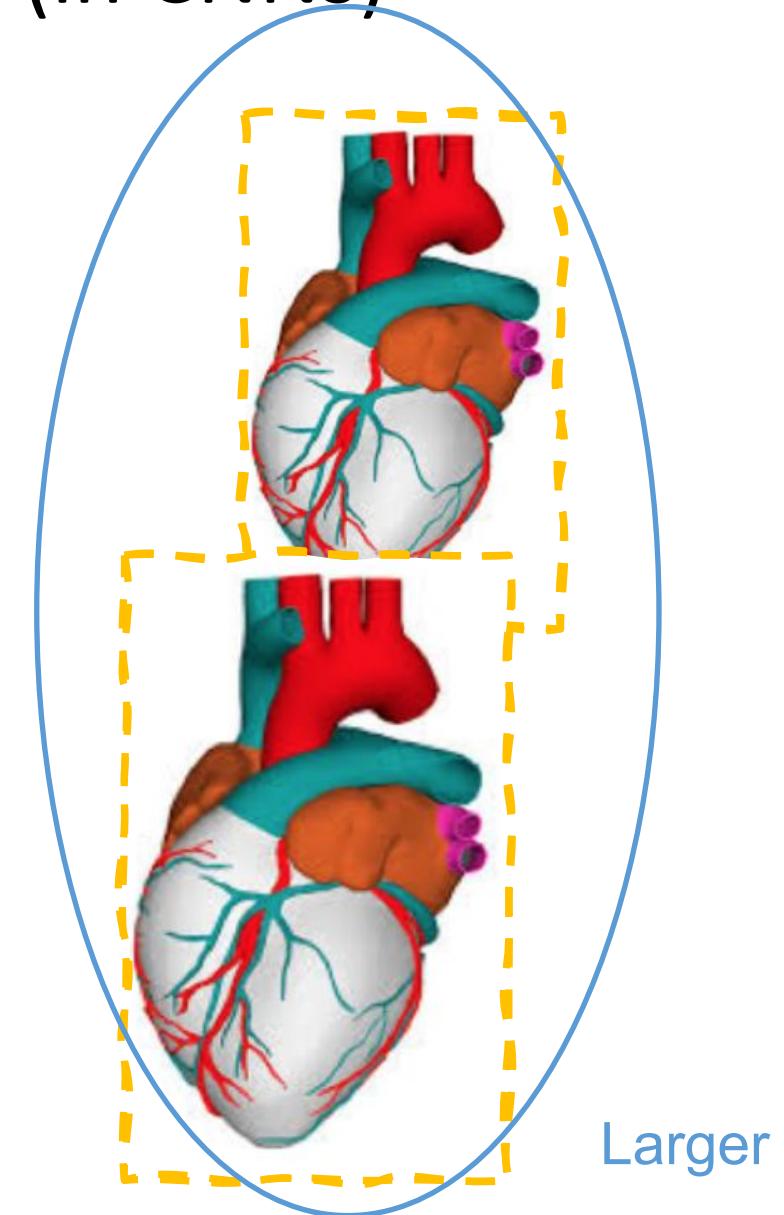
Constrained optimization (in CNNs)

Equality constraints



Known size

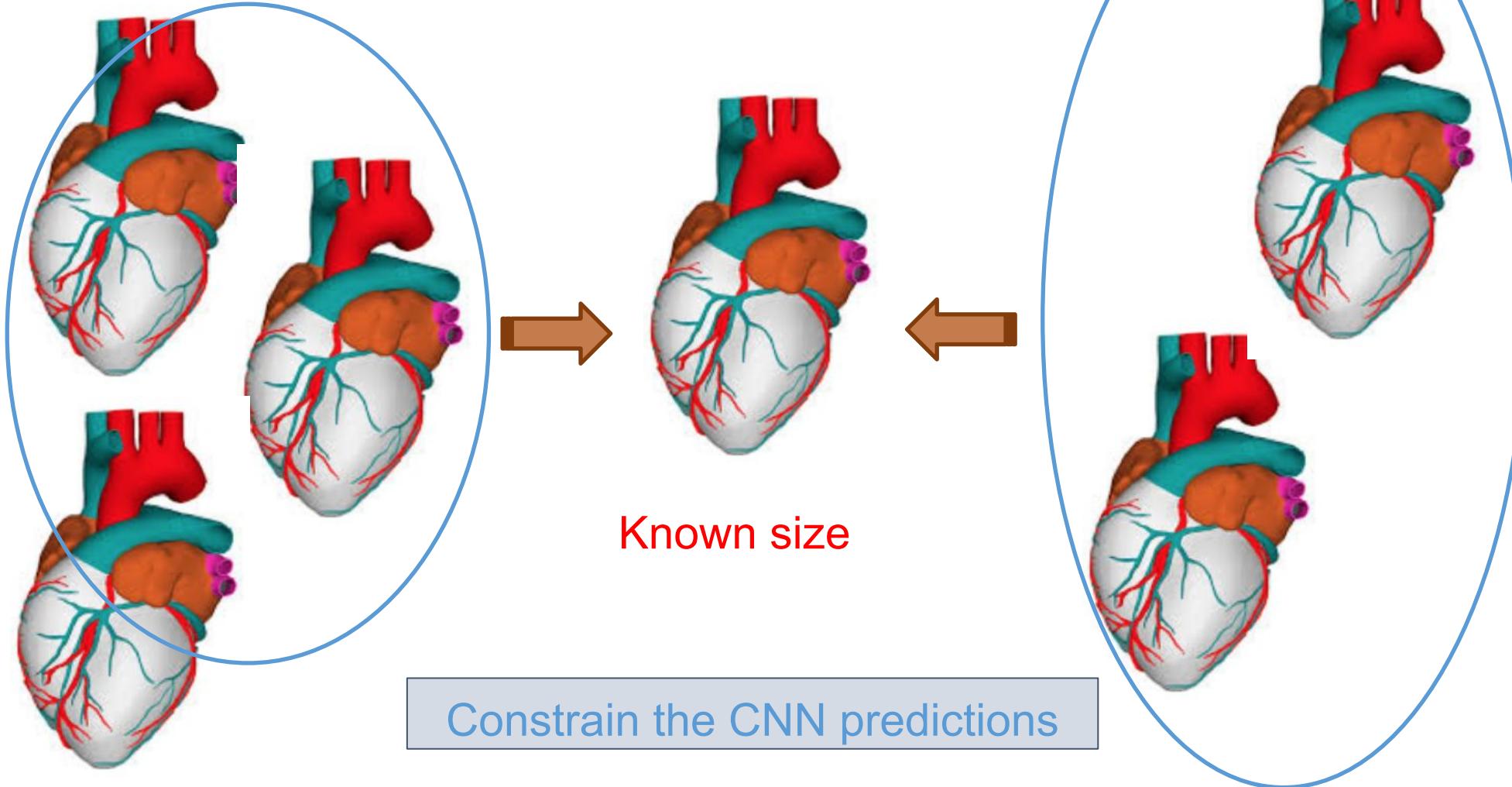
CNN predictions



Larger

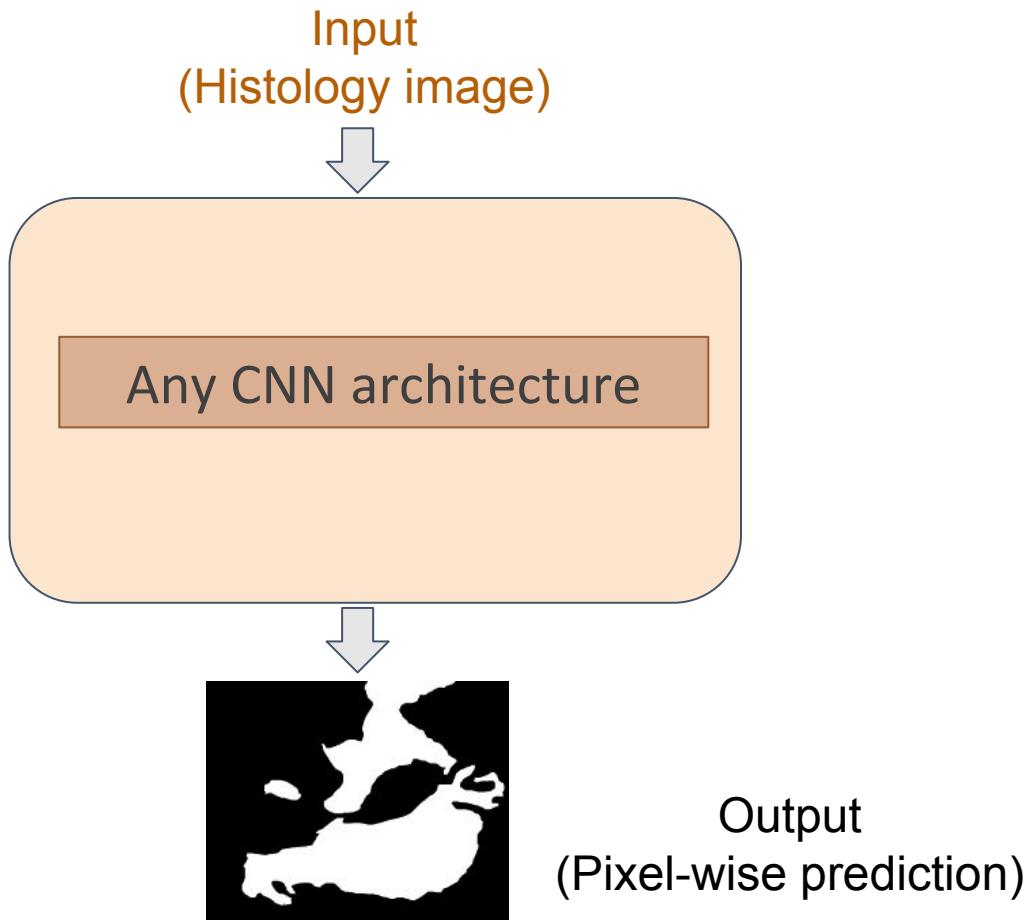
Constrained optimization (in CNNs)

Equality constraints



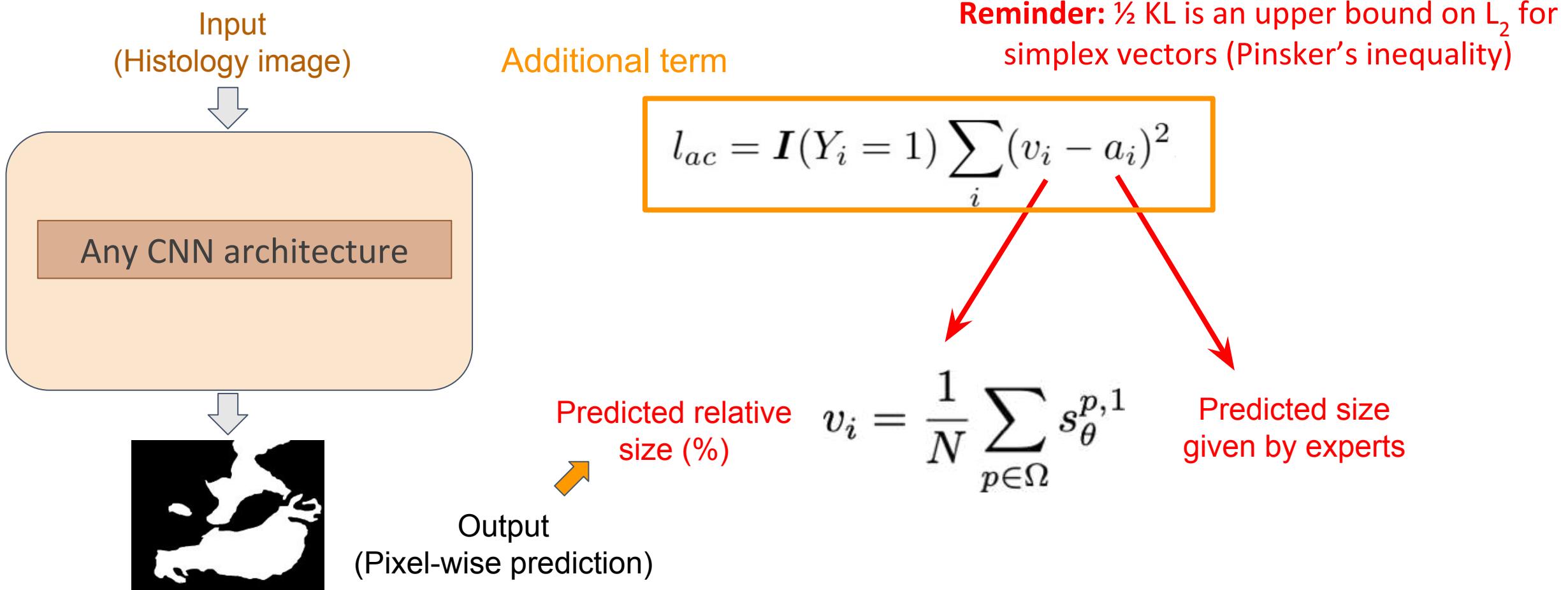
Constrained optimization (in CNNs)

Equality constraints (e.g, L2 penalty)



Constrained optimization (in CNNs)

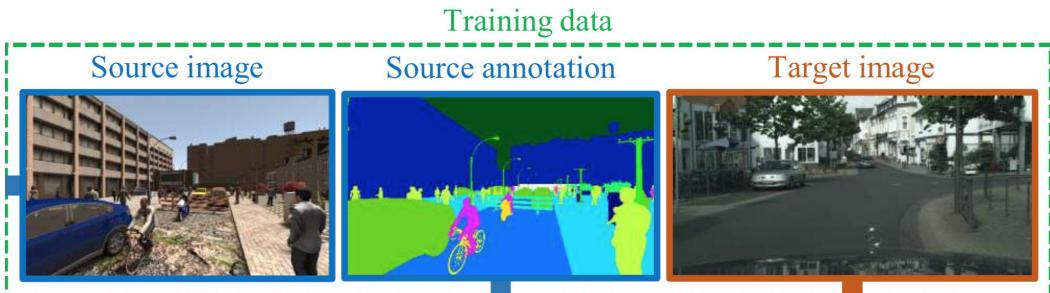
Equality constraints (e.g, L2 penalty)



Constrained optimization (in CNNs)

Equality constraints (e.g, KL)

Unsupervised domain
adaptation

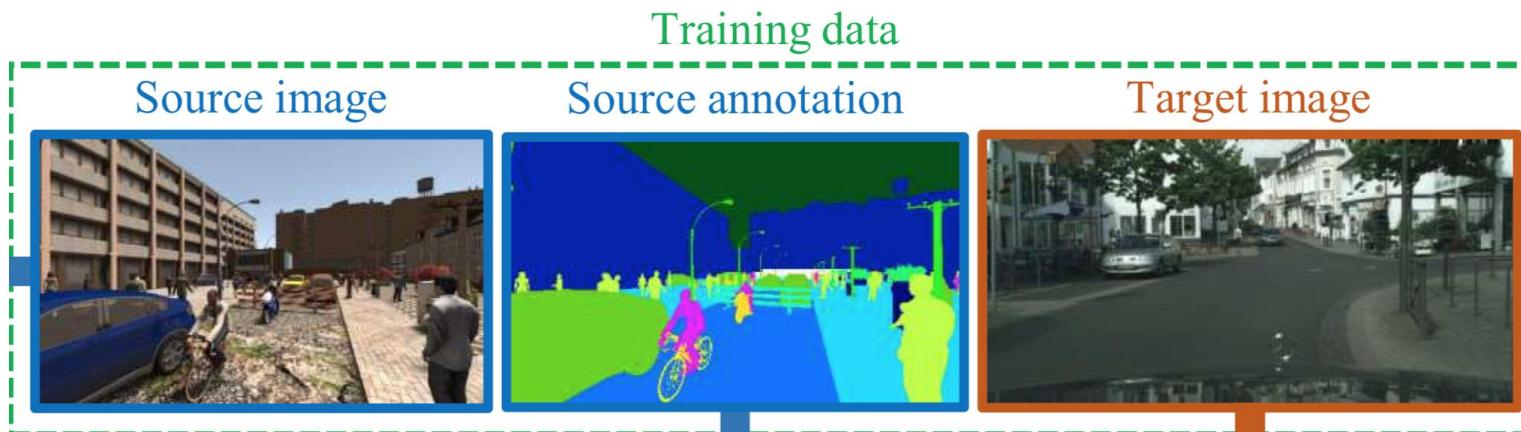


Partially labeled data



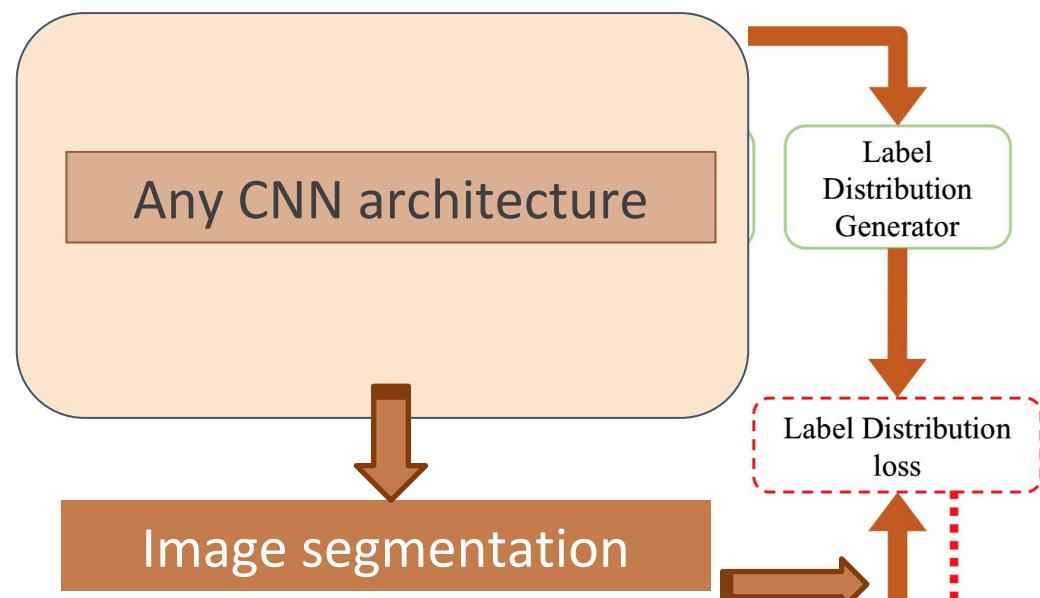
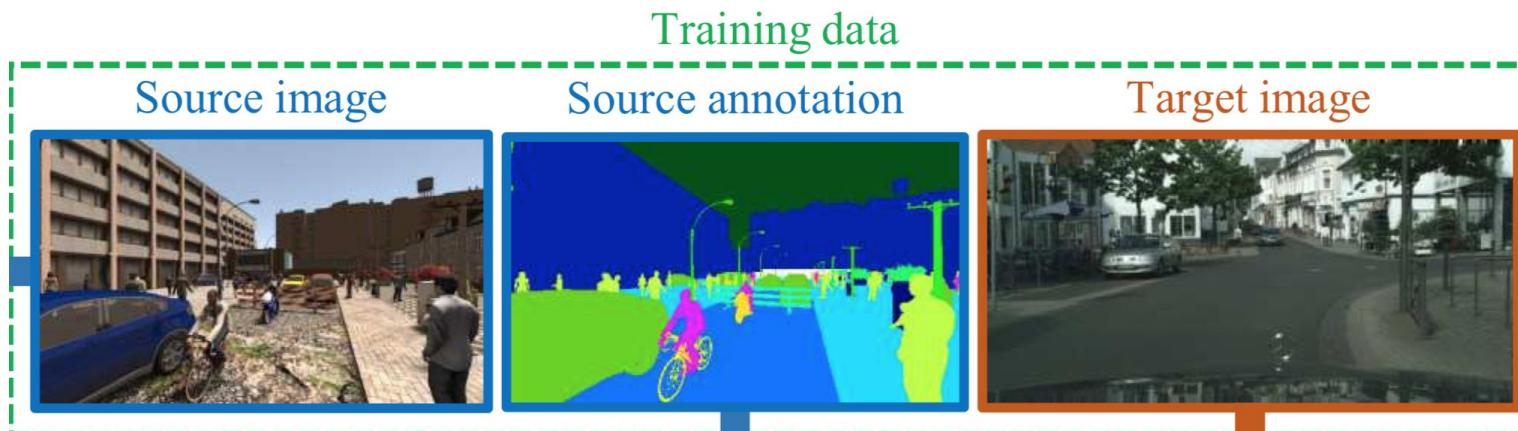
Constrained optimization (in CNNs)

Equality constraints (e.g, KL): Curriculum DA



Constrained optimization (in CNNs)

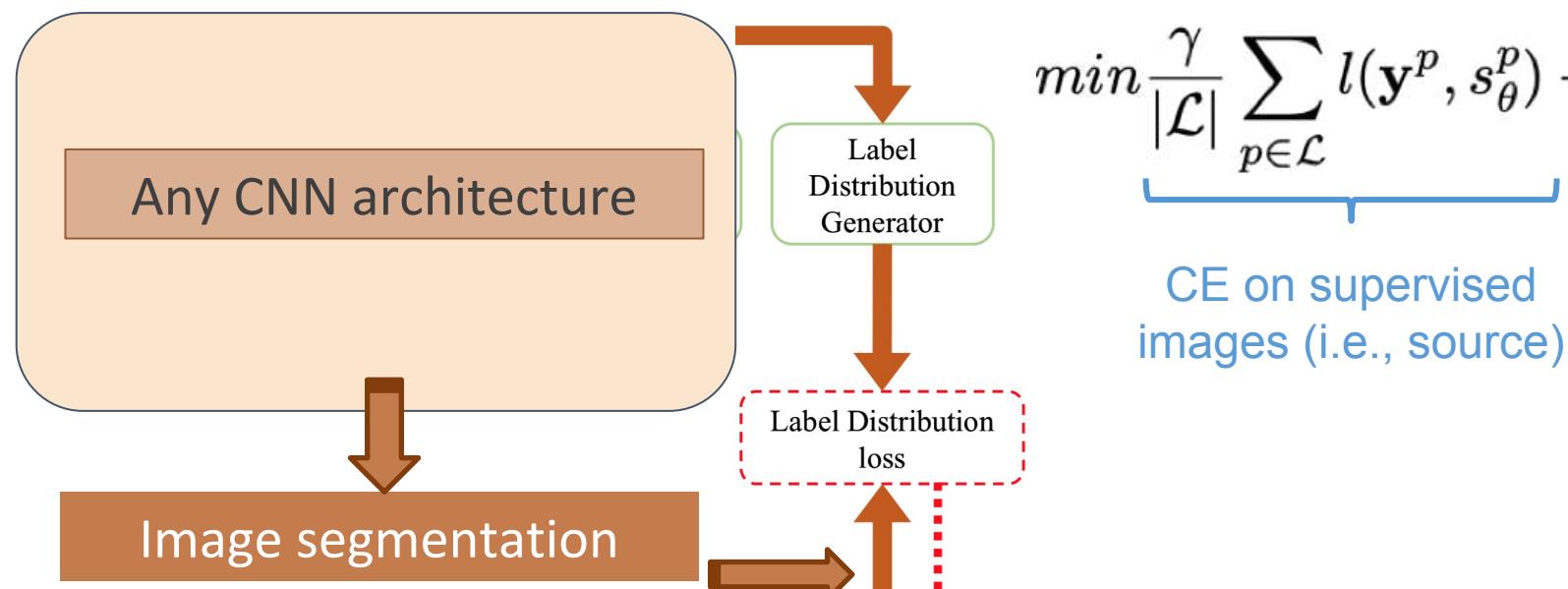
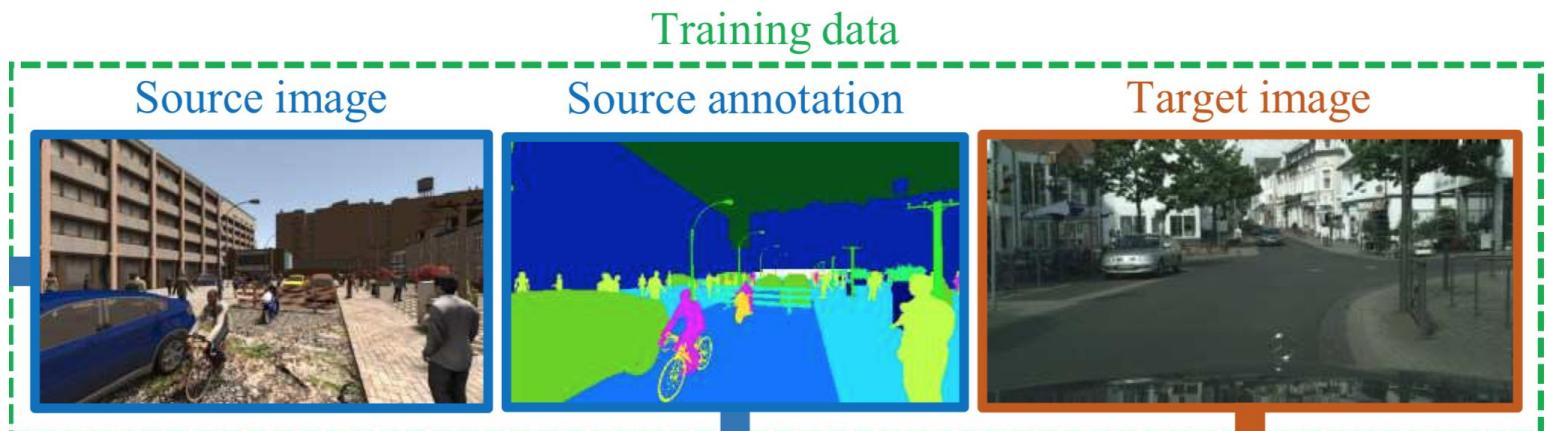
Equality constraints (e.g, KL): Curriculum DA



$$\min \frac{\gamma}{|\mathcal{L}|} \sum_{p \in \mathcal{L}} l(\mathbf{y}^p, s_\theta^p) + \frac{1 - \gamma}{|\mathcal{U}|} \sum_{q \in \mathcal{U}} \sum_k \mathbf{C}(a^{q,k}, \hat{a}^{q,k})$$

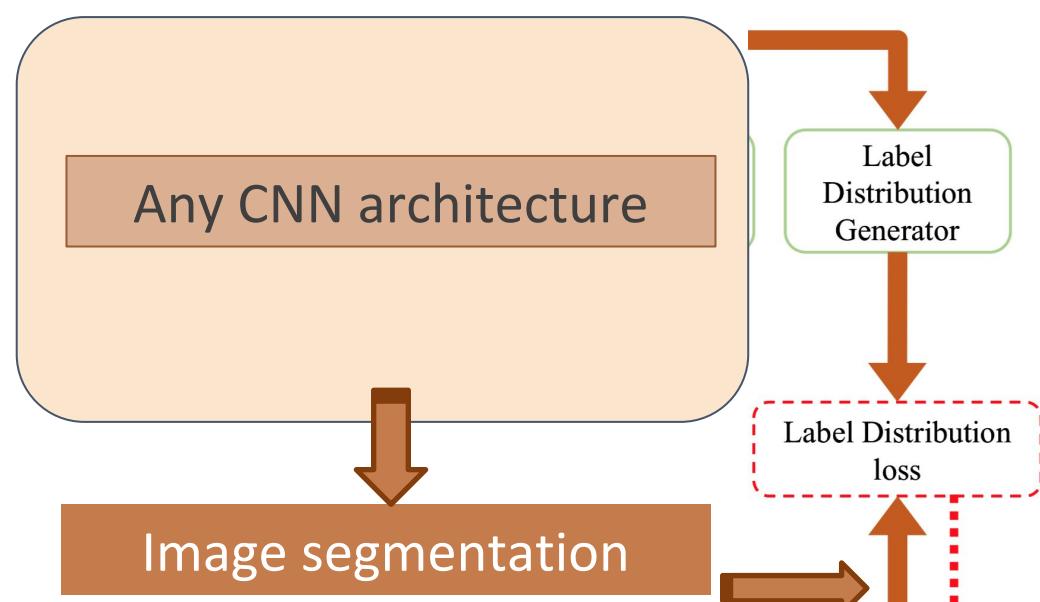
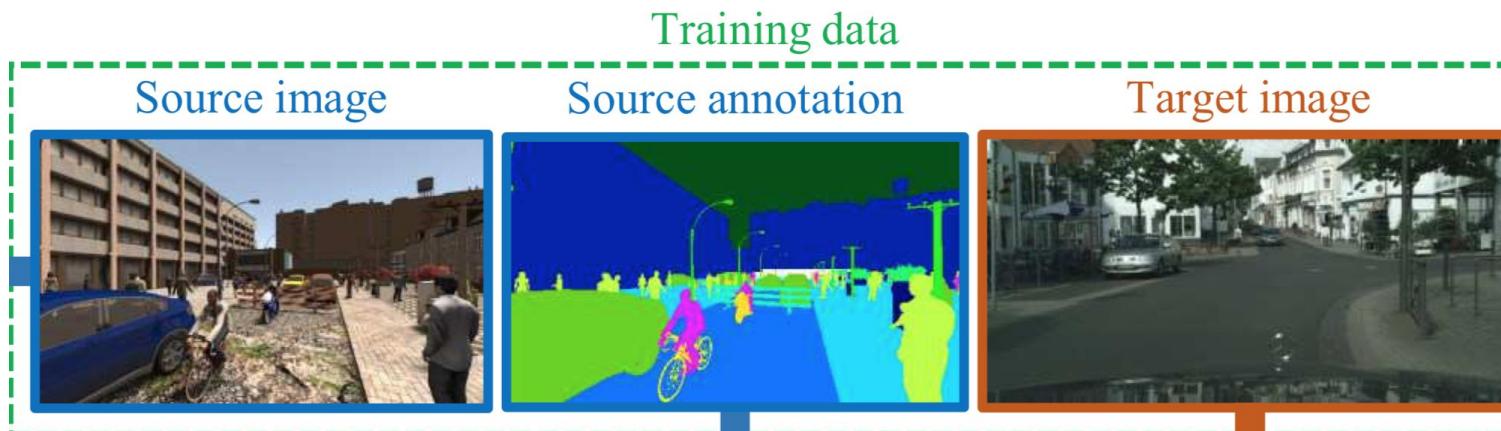
Constrained optimization (in CNNs)

Equality constraints (e.g, KL): Curriculum DA



Constrained optimization (in CNNs)

Equality constraints (e.g, KL): Curriculum DA



$$\min \frac{\gamma}{|\mathcal{L}|} \sum_{p \in \mathcal{L}} l(\mathbf{y}^p, s_\theta^p) + \underbrace{\frac{1 - \gamma}{|\mathcal{U}|} \sum_{q \in \mathcal{U}} \sum_k \mathbf{C}(a^{q,k}, \hat{a}^{q,k})}_{\text{CE on supervised images (i.e., source)}}$$

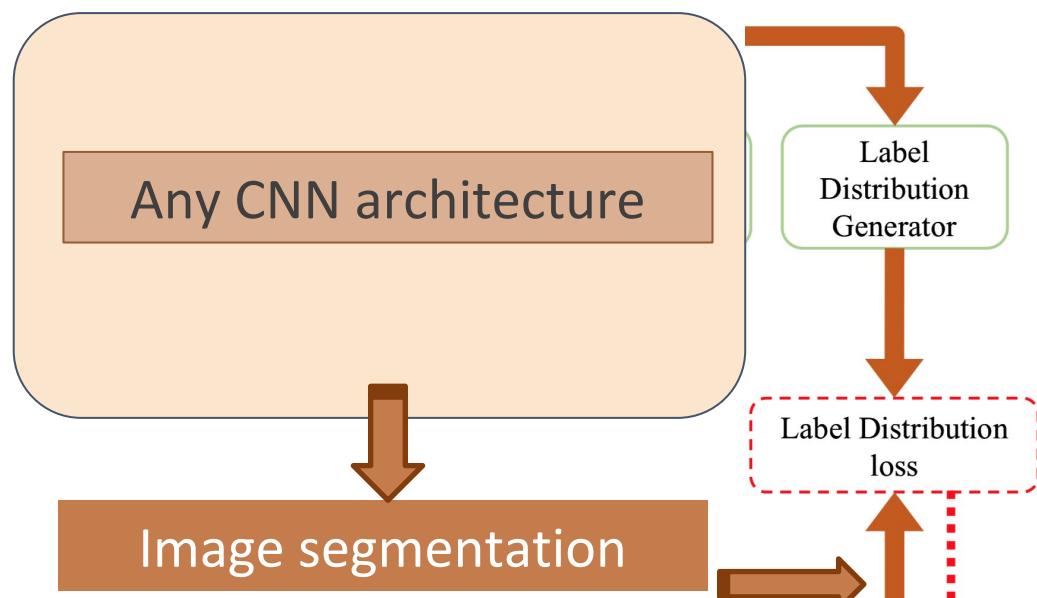
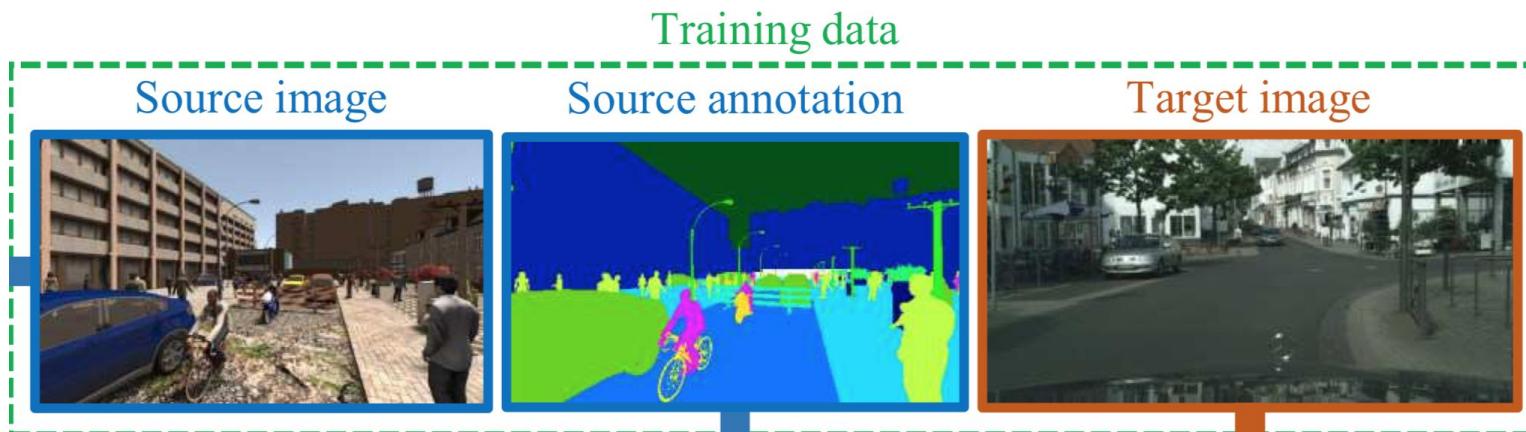
Additional term

$$\frac{1 - \gamma}{|\mathcal{U}|} \sum_{q \in \mathcal{U}} \sum_k \mathbf{C}(a^{q,k}, \hat{a}^{q,k})$$

CE on supervised
images (i.e., source)

Constrained optimization (in CNNs)

Equality constraints (e.g, KL): Curriculum DA



$$\min \frac{\gamma}{|\mathcal{L}|} \sum_{p \in \mathcal{L}} l(\mathbf{y}^p, s_\theta^p) + \underbrace{\frac{1 - \gamma}{|\mathcal{U}|} \sum_{q \in \mathcal{U}} \sum_k \mathbf{C}(a^{q,k}, \hat{a}^{q,k})}_{\text{CE on supervised images (i.e., source)}}$$

CE on supervised
images (i.e., source)

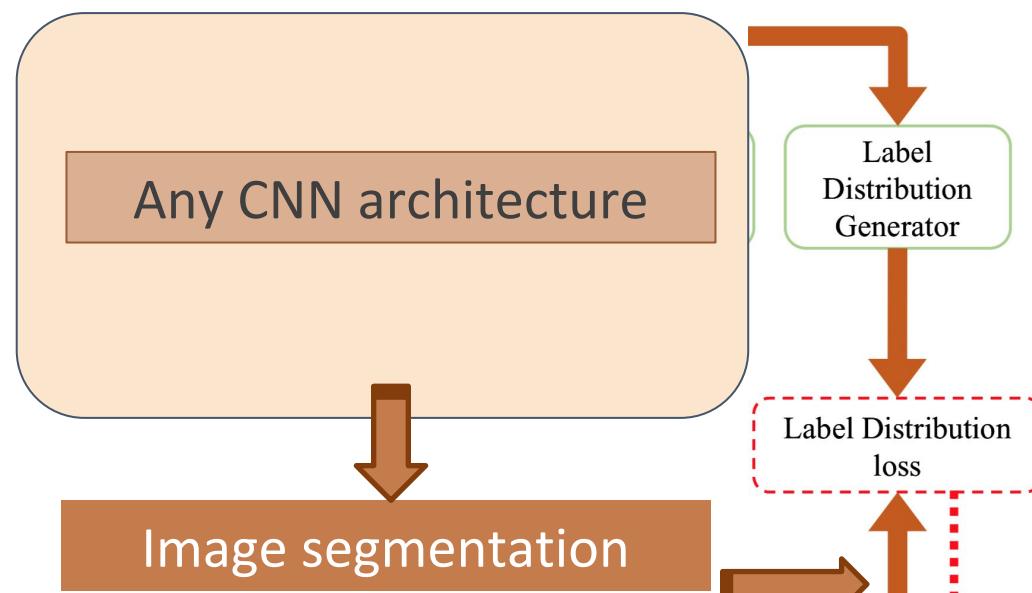
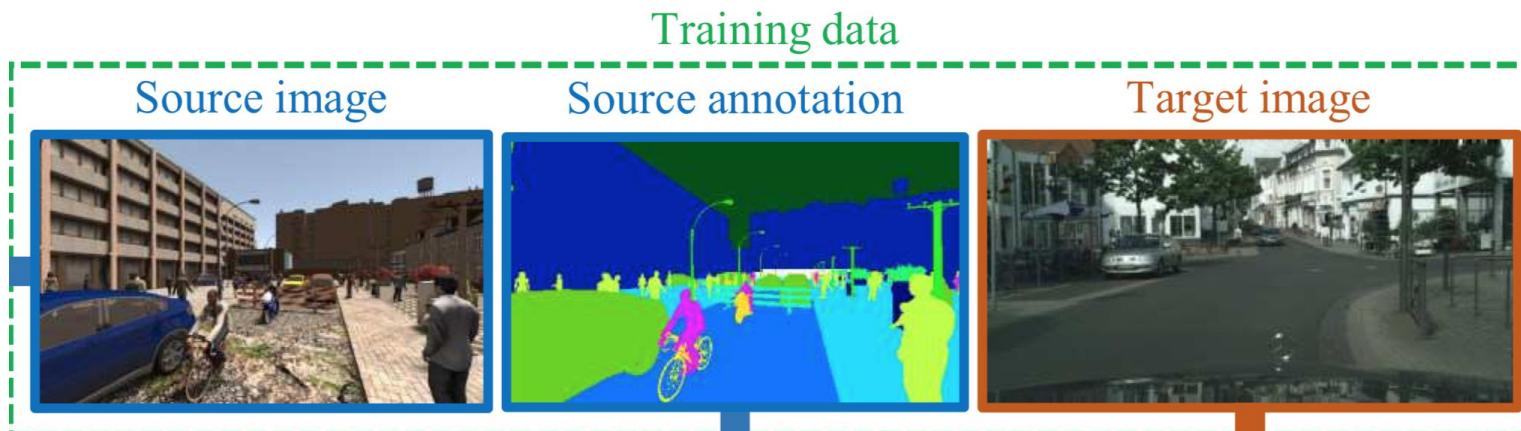
$$\mathbf{C}(\mathbf{a}^q, \hat{\mathbf{a}}^q) = H(\mathbf{a}^q) + KL(\mathbf{a}^q, \hat{\mathbf{a}}^q)$$

Additional term

$$\frac{1 - \gamma}{|\mathcal{U}|} \sum_{q \in \mathcal{U}} \sum_k \mathbf{C}(a^{q,k}, \hat{a}^{q,k})$$

Constrained optimization (in CNNs)

Equality constraints (e.g, KL): Curriculum DA



$$\min \frac{\gamma}{|\mathcal{L}|} \sum_{p \in \mathcal{L}} l(\mathbf{y}^p, s_\theta^p) + \underbrace{\frac{1 - \gamma}{|\mathcal{U}|} \sum_{q \in \mathcal{U}} \sum_k \mathbf{C}(a^{q,k}, \hat{a}^{q,k})}_{\text{CE on supervised images (i.e., source)}}$$

Additional term

CE on supervised
images (i.e., source)

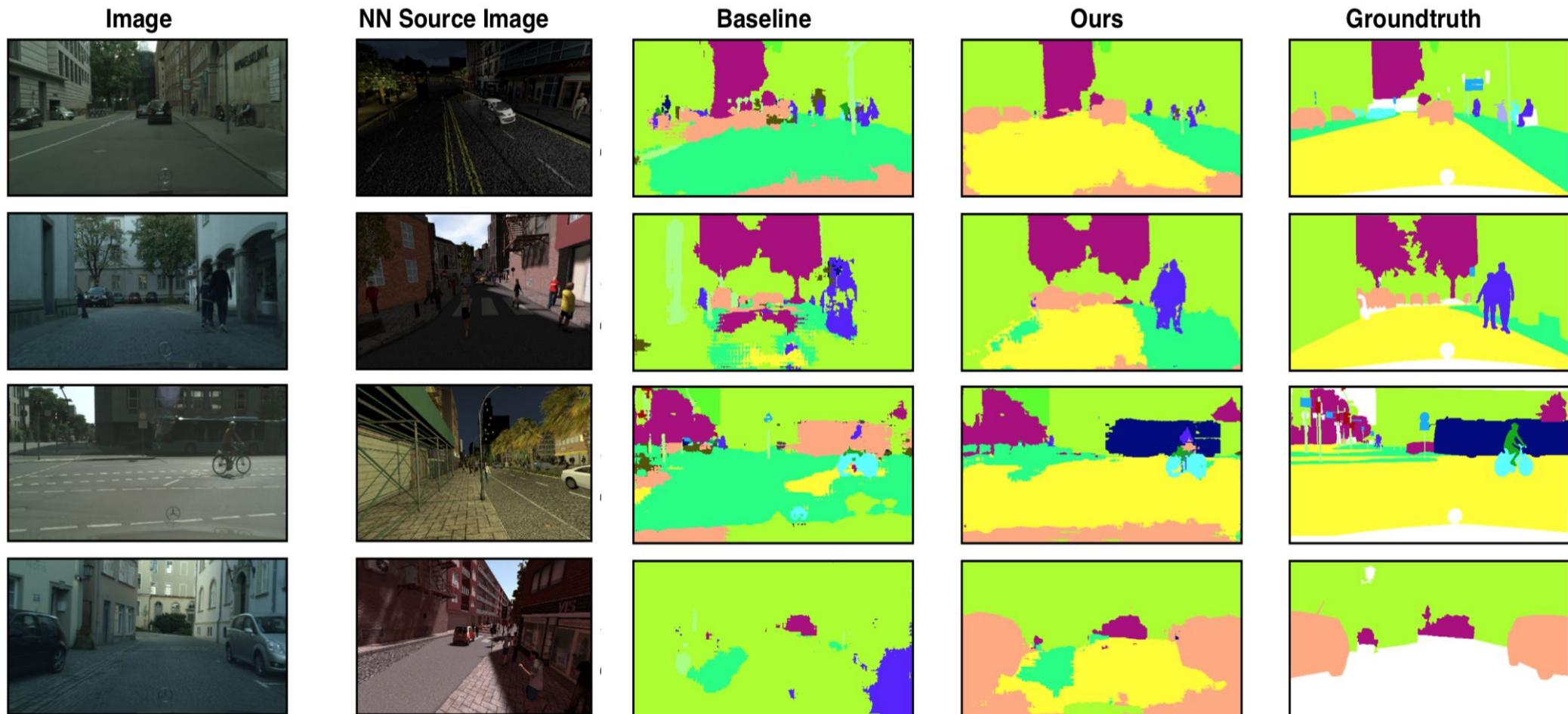
$$\mathbf{C}(\mathbf{a}^q, \hat{\mathbf{a}}^q) = H(\mathbf{a}^q) + KL(\mathbf{a}^q, \hat{\mathbf{a}}^q)$$

Predicted size

From predicted image

Constrained optimization (in CNNs)

Equality constraints (e.g, KL): Curriculum DA



Constrained optimization (in CNNs)

Equality constraints (e.g, KL): Partial annotations



Constrained optimization (in CNNs)

Equality constraints (e.g, KL): Partial annotations

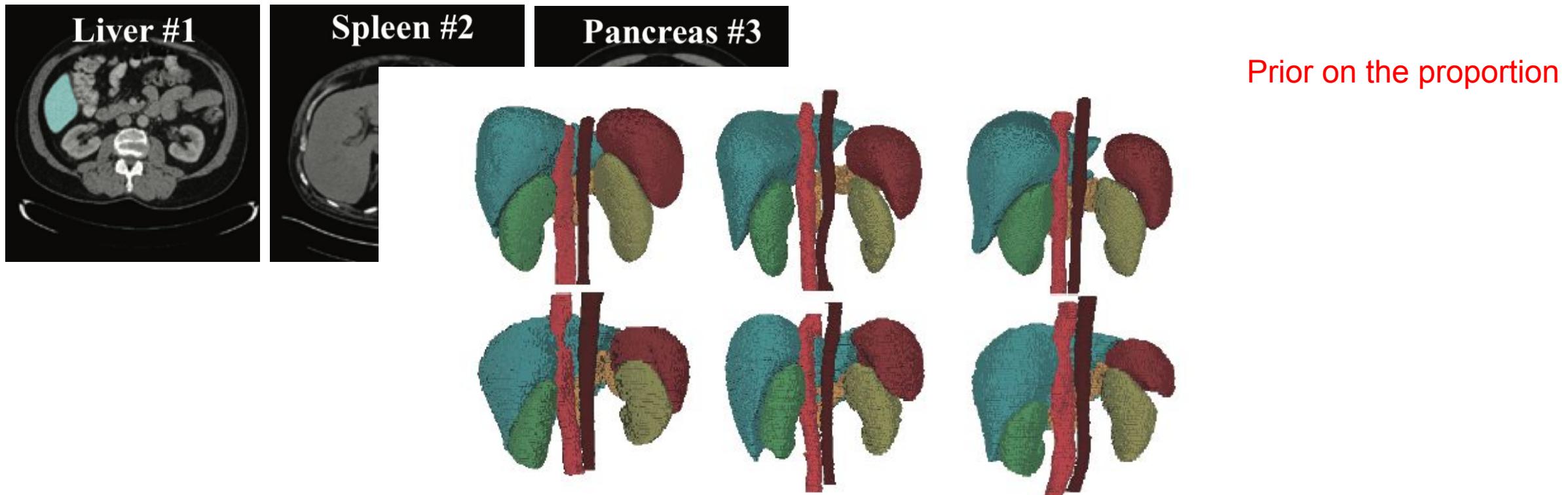
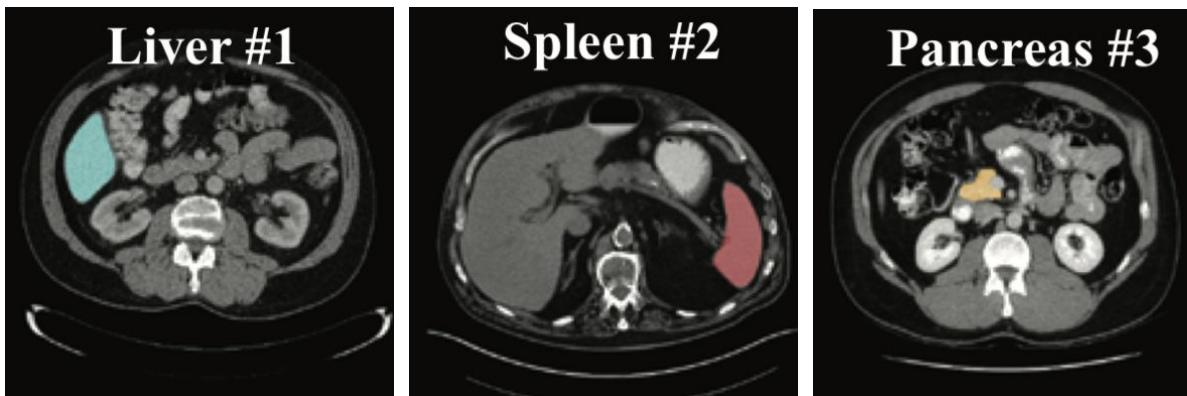


Figure 1. 3D Visualization of several abdominal organs (liver, spleen, left kidney, right kidney, aorta, inferior vena cava) to show the similarity of patient-wise abdominal organ size distributions.

Constrained optimization (in CNNs)

Equality constraints (e.g, KL): Partial annotations



Main objective:

$$\min \frac{1}{|\mathcal{L}|} \sum_{p \in \mathcal{L}} l(\mathbf{y}^p, \mathbf{s}_\theta^p) + \lambda_1 \frac{1}{|\mathcal{P}|} \sum_{q \in \mathcal{P}} l(\mathbf{y}^q, \mathbf{s}_\theta^q) + \lambda_2 \mathcal{J}(\theta)$$

Fully labeled images

Partially labeled images

Prior-aware loss

Constrained optimization (in CNNs)

Equality constraints (e.g, KL): Partial annotations



Prior-aware loss

Averaged predicted distribution

$$\hat{\mathbf{p}} = \frac{1}{N} \sum_{p \in \mathcal{P}} \mathbf{s}_{\theta}^p$$

[$s_{\theta}^{p,0}, s_{\theta}^{p,1}, \dots, s_{\theta}^{p,|K|}$]

On partially labeled images

Constrained optimization (in CNNs)

Equality constraints (e.g, KL): Partial annotations



Prior-aware loss

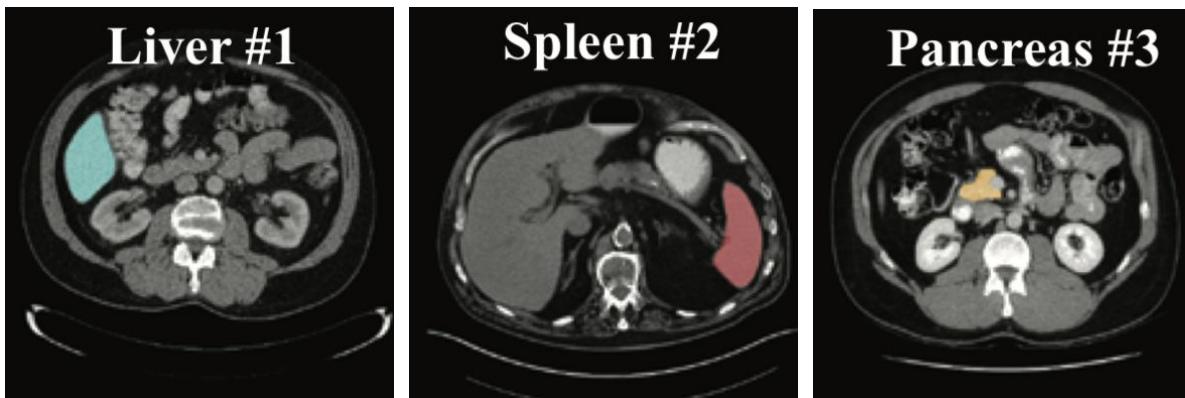
Embed prior knowledge

$$KL(\mathbf{q}|\hat{\mathbf{p}})$$

Real label distribution Average predicted distribution

Constrained optimization (in CNNs)

Equality constraints (e.g, KL): Partial annotations



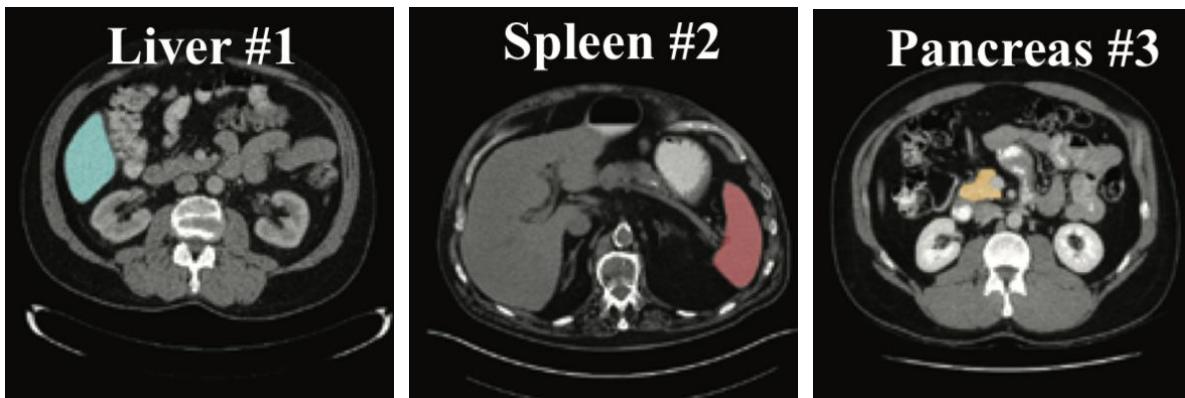
Prior-aware loss

KL can be expanded

$$-\sum_{c=0}^{|K|}\{q^c \log \frac{1}{N} \sum_{p \in \mathcal{P}} \mathbf{s}_\theta^{p,c} + (1 - q^c) \log(1 - \frac{1}{N} \sum_{p \in \mathcal{P}} \mathbf{s}_\theta^{p,c})\} + const$$

Constrained optimization (in CNNs)

Equality constraints (e.g, KL): Partial annotations



Prior-aware loss

$$-\sum_{c=0}^{|K|} \left\{ q^c \log \frac{1}{N} \sum_{p \in \mathcal{P}} \mathbf{s}_{\theta}^{p,c} + (1 - q^c) \log \left(1 - \frac{1}{N} \sum_{p \in \mathcal{P}} \mathbf{s}_{\theta}^{p,c} \right) \right\} + const$$

KL can be expanded

This is problematic (average distribution of \hat{p} organ sizes inside log!!)

Constrained optimization (in CNNs)

Equality constraints (e.g, KL): Partial annotations



Stochastic primal-dual gradient
(split terms updated independently)

Prior-aware loss

$$-\sum_{c=0}^{|K|} \left\{ q^c \log \frac{1}{N} \sum_{p \in \mathcal{P}} \mathbf{s}_\theta^{p,c} + (1 - q^c) \log \left(1 - \frac{1}{N} \sum_{p \in \mathcal{P}} \mathbf{s}_\theta^{p,c} \right) \right\} + const$$

KL can be expanded

This is problematic (average distribution of \hat{p} organ sizes inside log!!)

Constrained optimization (in CNNs)

Equality constraints (e.g, KL): Partial annotations



Prior-aware loss

$$-\sum_{c=0}^{|K|} \left\{ q^c \log \frac{1}{N} \sum_{p \in \mathcal{P}} \mathbf{s}_{\theta}^{p,c} + (1 - q^c) \log \left(1 - \frac{1}{N} \sum_{p \in \mathcal{P}} \mathbf{s}_{\theta}^{p,c} \right) \right\} + const$$

KL can be expanded

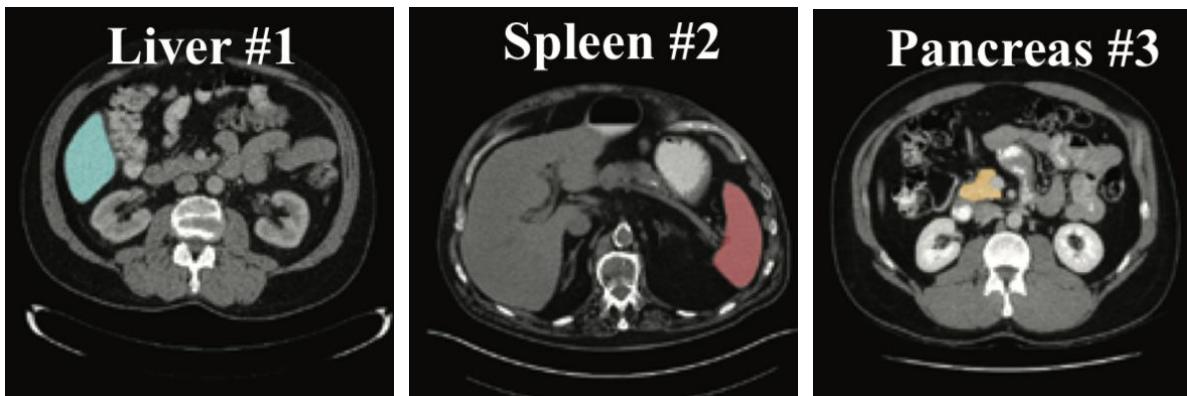
This is problematic (average distribution of \hat{p} organ sizes inside log!!)

$$-\log \alpha = \max_{\beta} (\alpha \beta + 1 + \log(-\beta))$$

Stochastic primal-dual gradient (split terms updated independently)

Constrained optimization (in CNNs)

Equality constraints (e.g, KL): Partial annotations



$$-\log \bar{p}^l = \max_{\nu^l} \left(\bar{p}^l \nu^l + 1 + \log(-\nu^l) \right)$$

$$-\log(1 - \bar{p}^l) = \max_{\mu^l} \left((1 - \bar{p}^l) \mu^l + 1 + \log(-\mu^l) \right),$$

Stochastic primal-dual gradient
(split terms updated independently)

Prior-aware loss

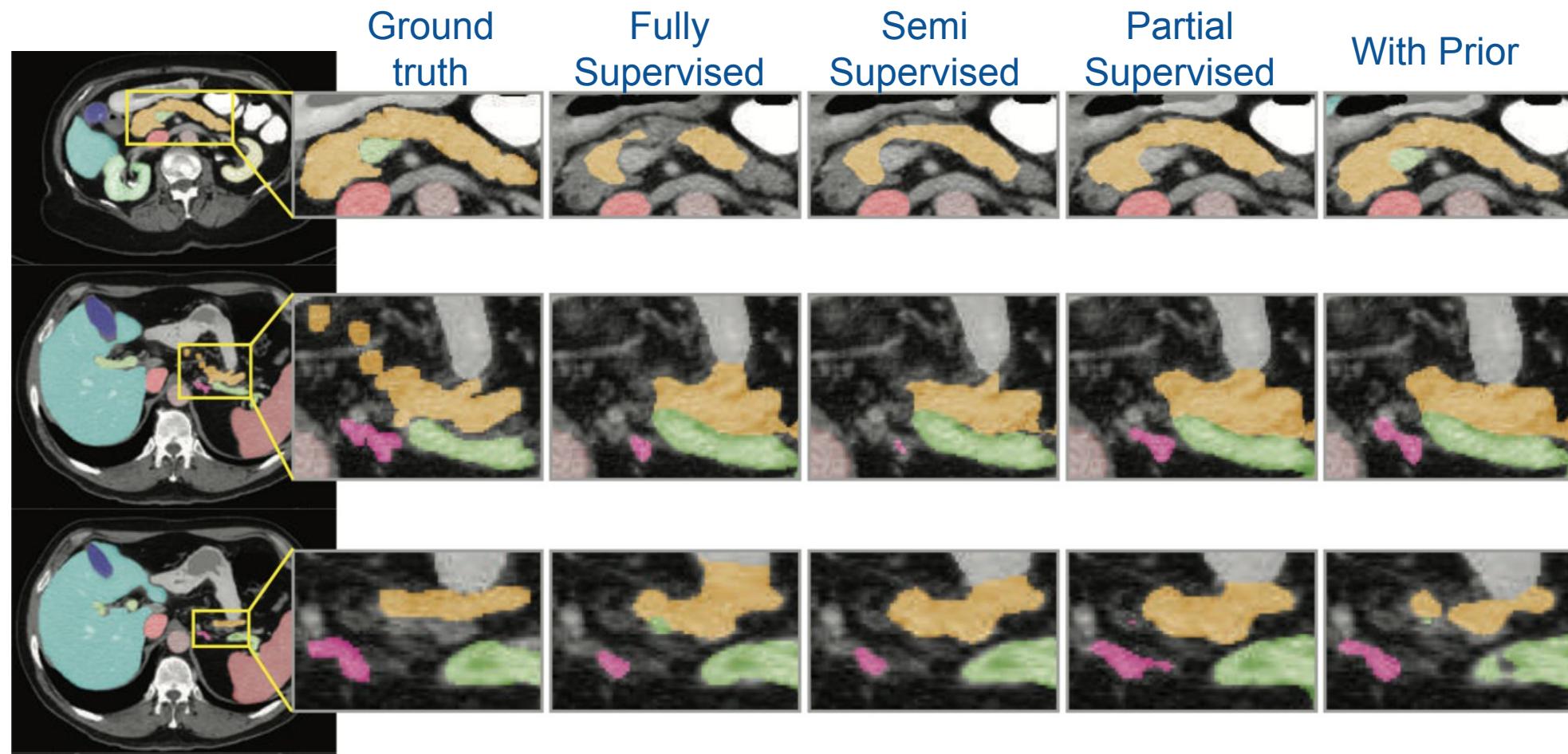
$$-\sum_{c=0}^{|K|} \left\{ q^c \log \frac{1}{N} \sum_{p \in \mathcal{P}} \mathbf{s}_{\theta}^{p,c} + (1 - q^c) \log \left(1 - \frac{1}{N} \sum_{p \in \mathcal{P}} \mathbf{s}_{\theta}^{p,c} \right) \right\} + const$$

KL can be expanded

This is problematic (average distribution of \hat{p} organ sizes inside log!!)

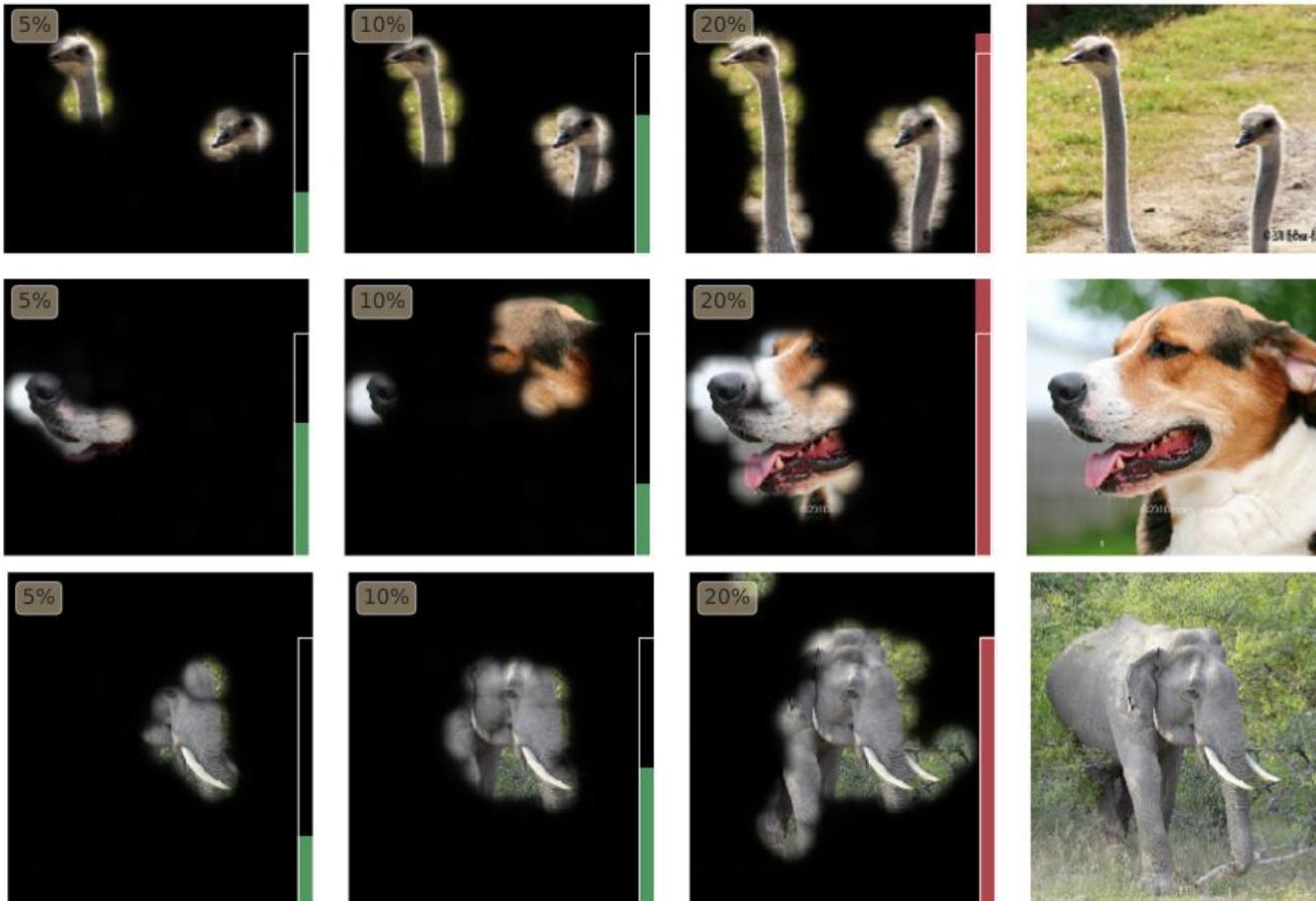
Constrained optimization (in CNNs)

Equality constraints (e.g, KL): Partial annotations



Constrained optimization (in CNNs)

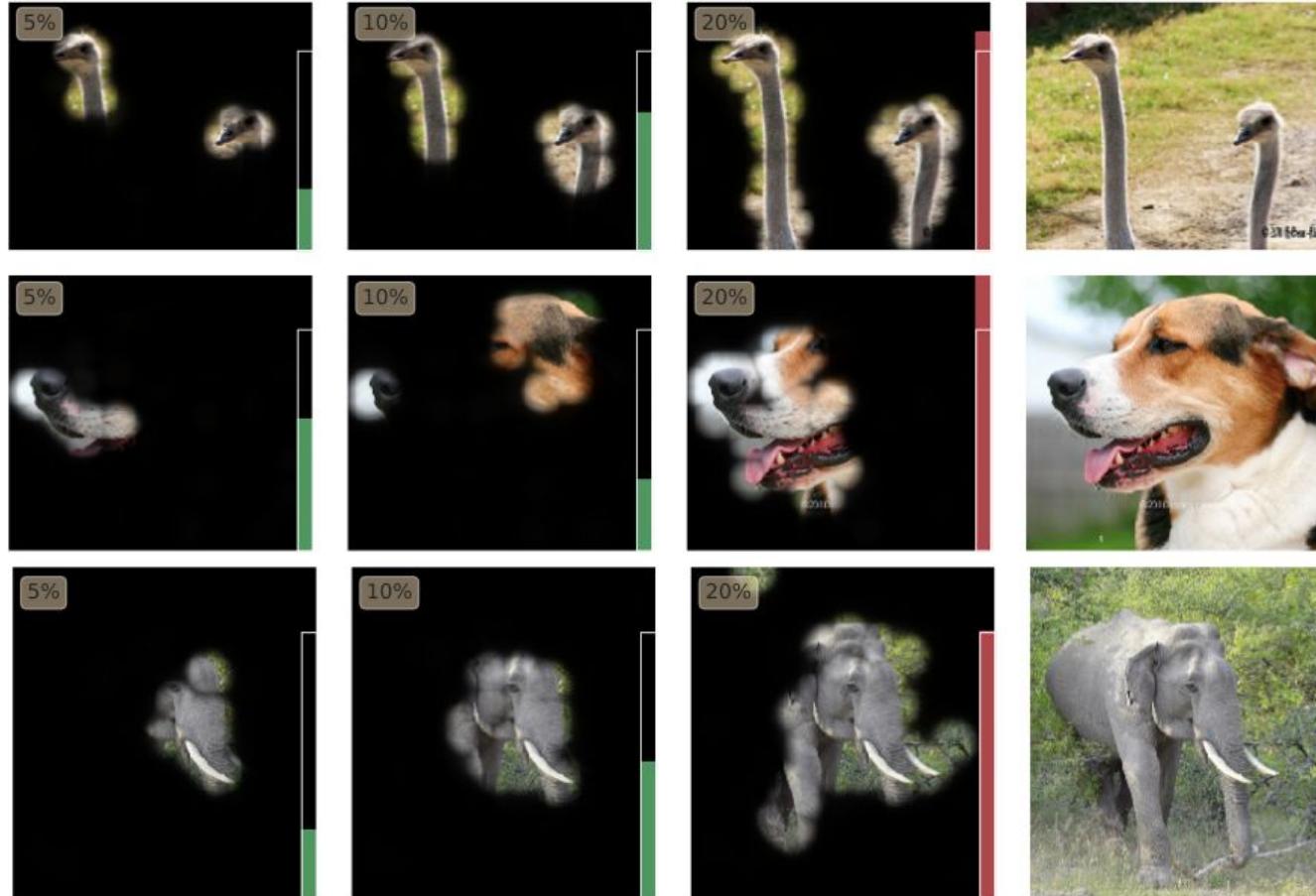
Equality constraints



Extremal perturbations

Constrained optimization (in CNNs)

Equality constraints



Extremal perturbations

1 - Relax the mask

$$\mathbf{m} \in [0, 1]^{|\Omega|}$$

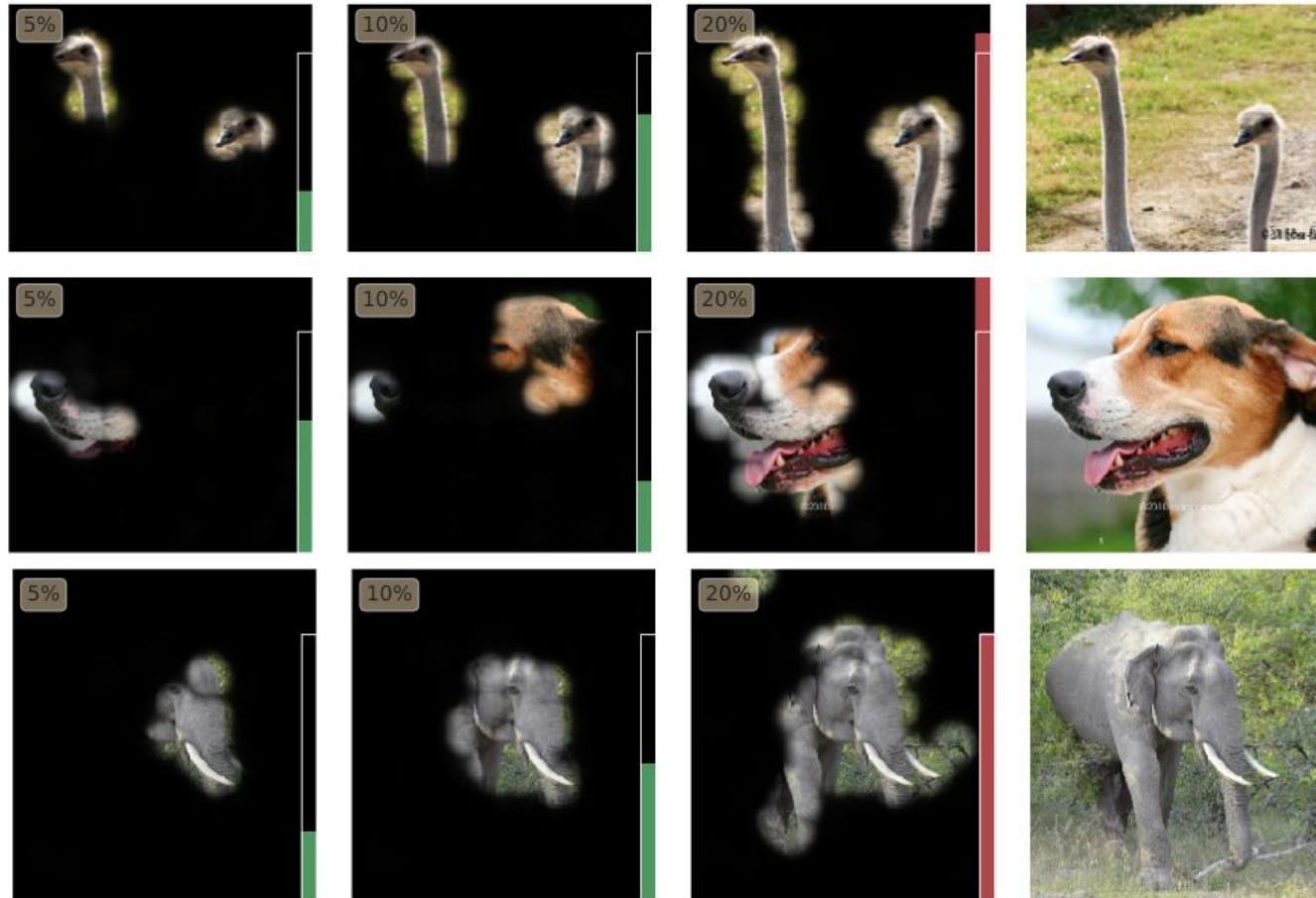
2 - Vectorize and sort \mathbf{m}
(non-decreasing order)

3 - If \mathbf{m} satisfies the area
constraints (a) **exactly**

$$\mathbf{r}_a \in [0, 1]^{|\Omega|} = \underbrace{[0, 0, \dots, 0]}_{(1-a)|\Omega|} \underbrace{[1, 1, \dots, 1]}_{(a)|\Omega|}$$

Constrained optimization (in CNNs)

Equality constraints



Extremal perturbations

1 - Relax the mask

$$\mathbf{m} \in [0, 1]^{|\Omega|}$$

2 - Vectorize and sort \mathbf{m}
(non-decreasing order)

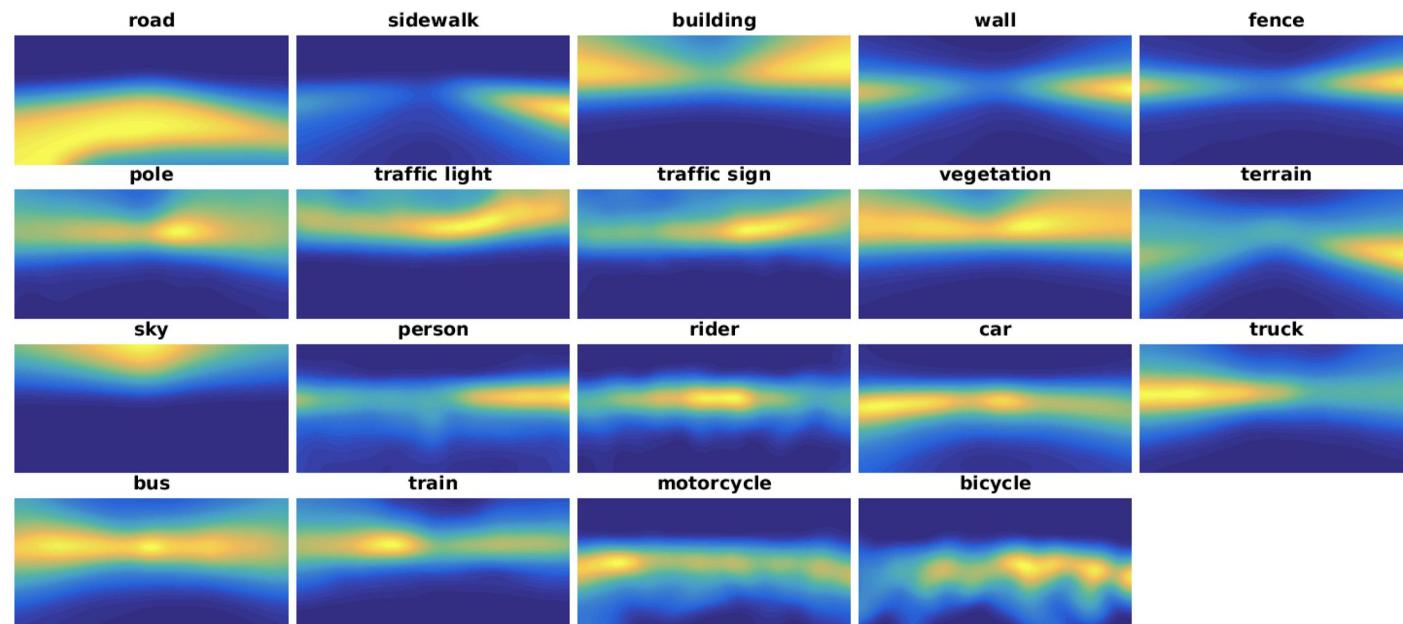
3 - If \mathbf{m} satisfies the area
constraints (a) **exactly**

$$\mathbf{r}_a \in [0, 1]^{|\Omega|} = [\underbrace{0, 0, \dots, 0}_{(1-a)|\Omega|}, \underbrace{1, 1, \dots, 1}_{(a)|\Omega|}]$$

$$R_a(\mathbf{m}) = \|vecsorth(\mathbf{m}) - \mathbf{r}_a\|^2$$

Constrained optimization (in CNNs)

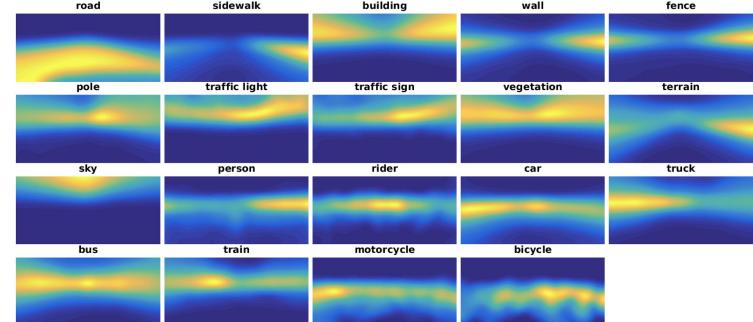
Equality constraints (at pixel-level)



Spatial priors on GTA5

Constrained optimization (in CNNs)

Equality constraints (at pixel-level)

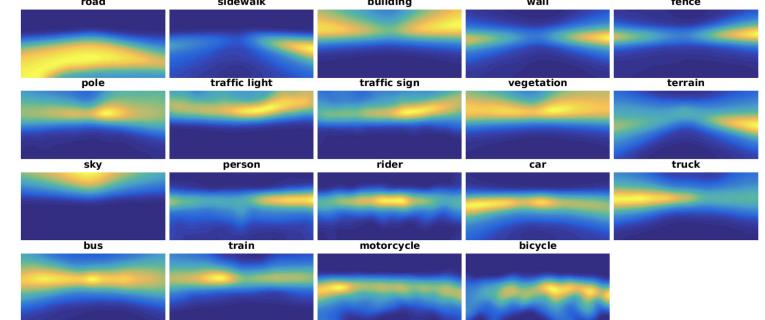
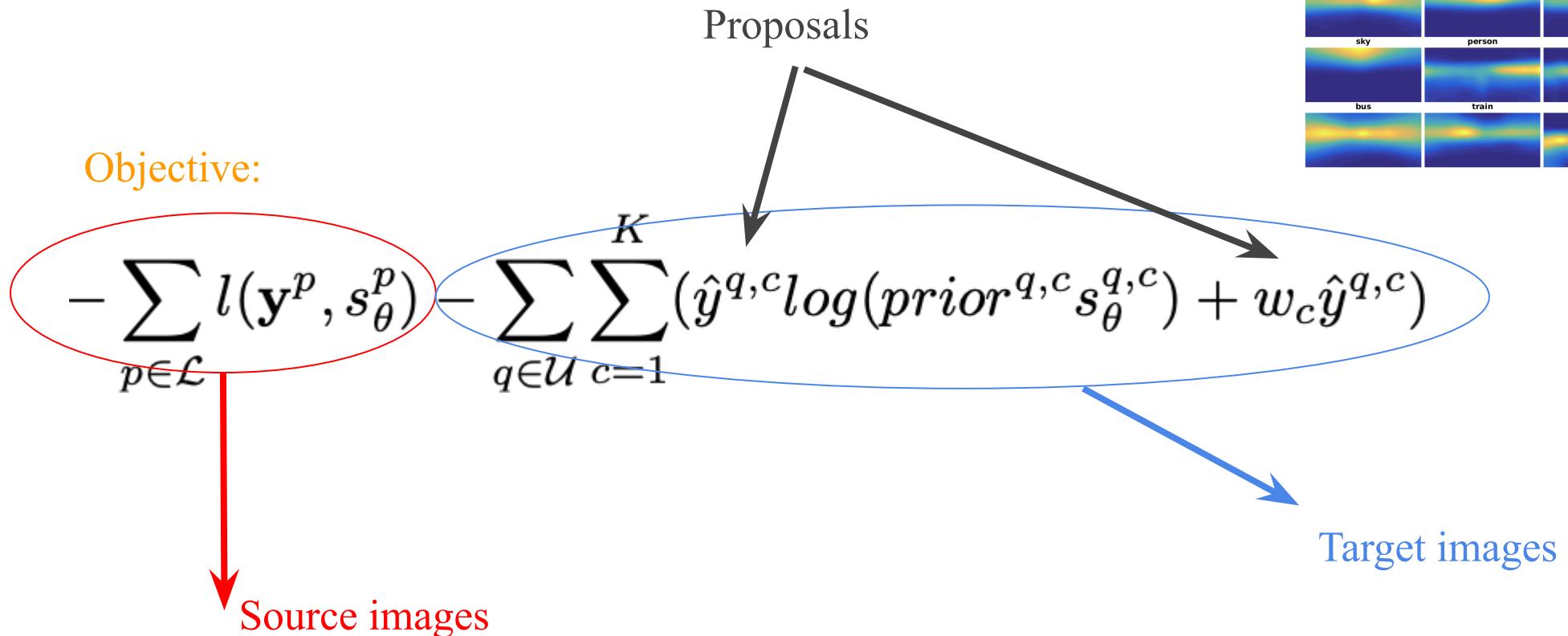


Objective:

$$-\sum_{p \in \mathcal{L}} l(\mathbf{y}^p, s_\theta^p) - \sum_{q \in \mathcal{U}} \sum_{c=1}^K (\hat{y}^{q,c} \log(prior^{q,c} s_\theta^{q,c}) + w_c \hat{y}^{q,c})$$

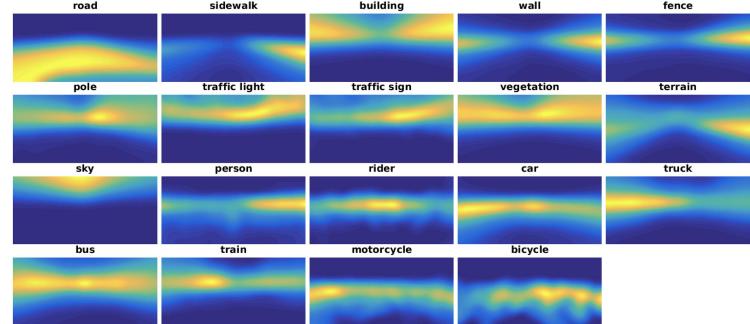
Constrained optimization (in CNNs)

Equality constraints (at pixel-level)



Constrained optimization (in CNNs)

Equality constraints (at pixel-level)



Objective:

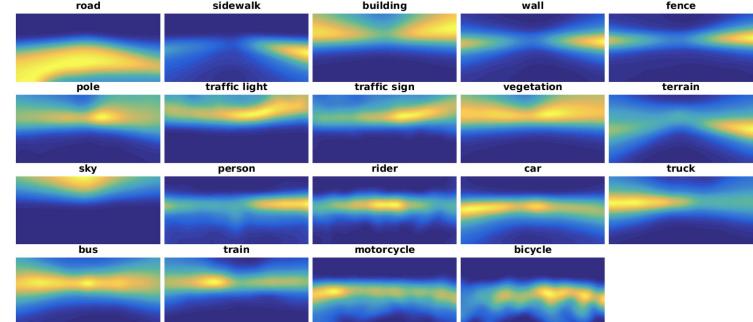
$$-\sum_{p \in \mathcal{L}} l(\mathbf{y}^p, s_\theta^p) - \sum_{q \in \mathcal{U}} \sum_{c=1}^K (\hat{y}^{q,c} \log(prior^{q,c} s_\theta^{q,c}) + w_c \hat{y}^{q,c})$$

This becomes two KL

$$KL(\hat{y}^{q,c} | prior^{q,c}) \quad KL(\hat{y}^{q,c} | s_\theta^{q,c})$$

Constrained optimization (in CNNs)

Equality constraints (at pixel-level)



Objective:

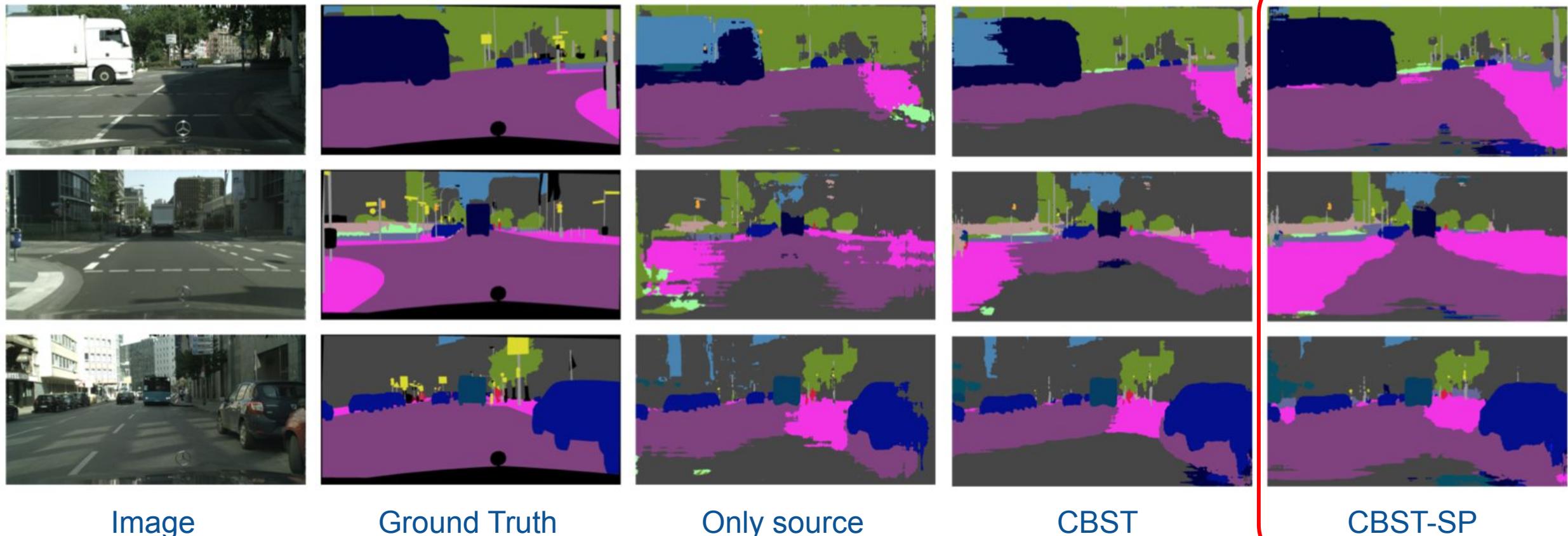
$$-\sum_{p \in \mathcal{L}} l(\mathbf{y}^p, s_\theta^p) - \sum_{q \in \mathcal{U}} \sum_{c=1}^K (\hat{y}^{q,c} \log(prior^{q,c} s_\theta^{q,c}) + w_c \hat{y}^{q,c})$$

Weights the proposals

Constrained optimization (in CNNs)

Equality constraints (at pixel-level)

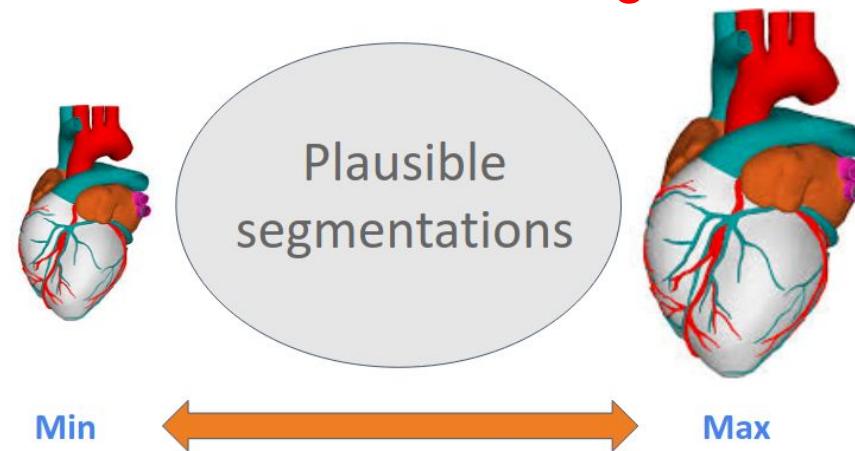
Spatial prior



Constrained optimization (in CNNs)

Inequality constraints

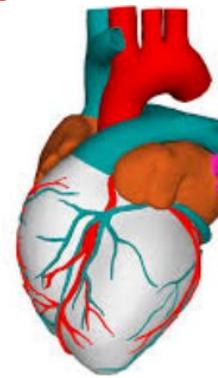
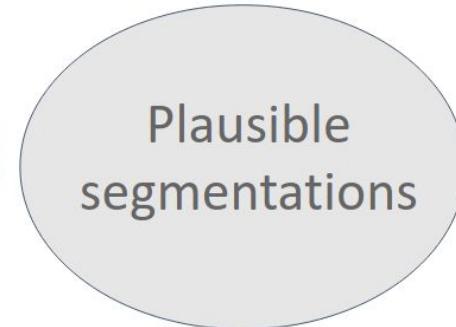
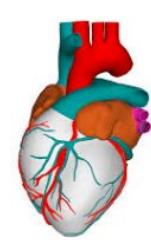
Prior size knowledge



Constrained optimization (in CNNs)

Inequality constraints

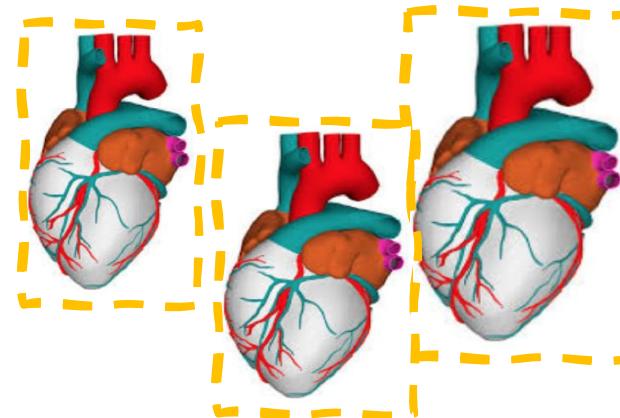
Prior size knowledge



Min



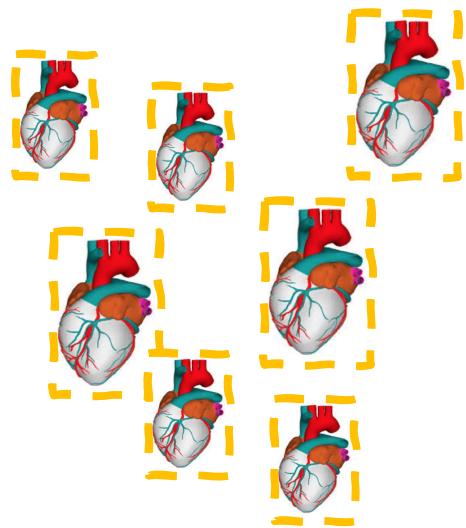
Max



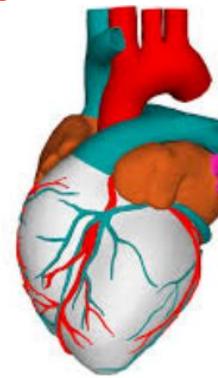
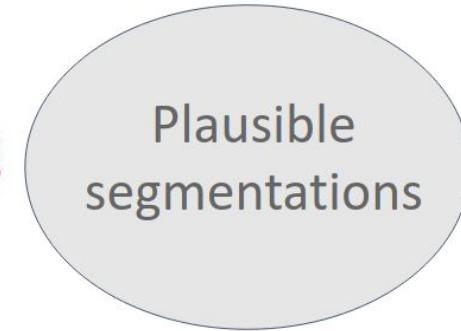
CNN predictions

Constrained optimization (in CNNs)

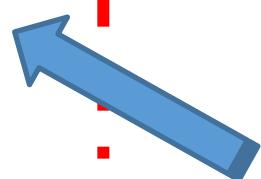
Inequality constraints



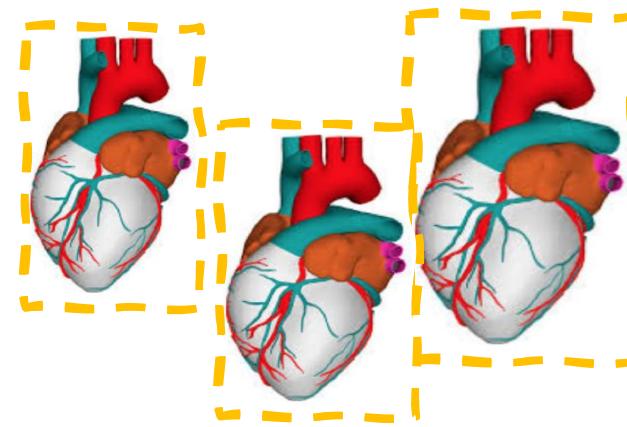
Prior size knowledge



Smaller

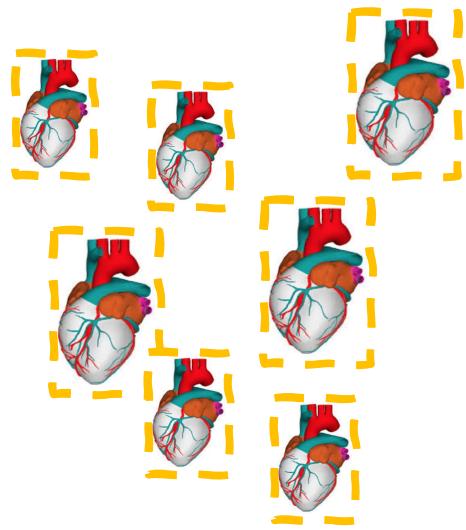


CNN predictions

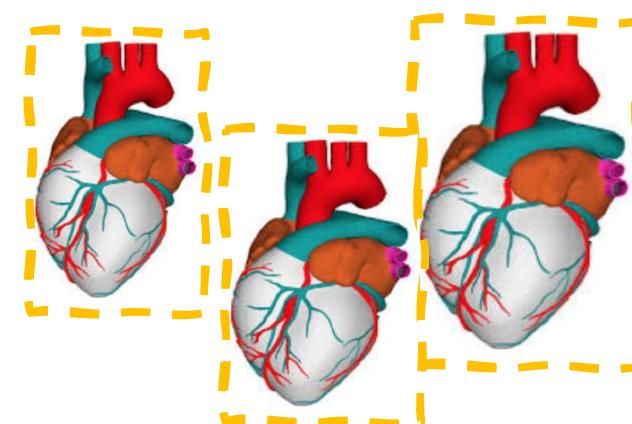
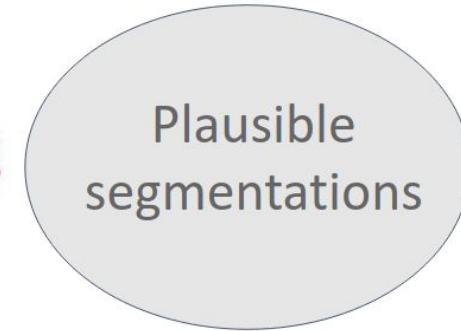


Constrained optimization (in CNNs)

Inequality constraints

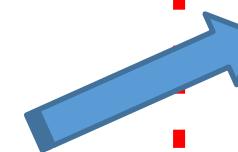


Prior size knowledge

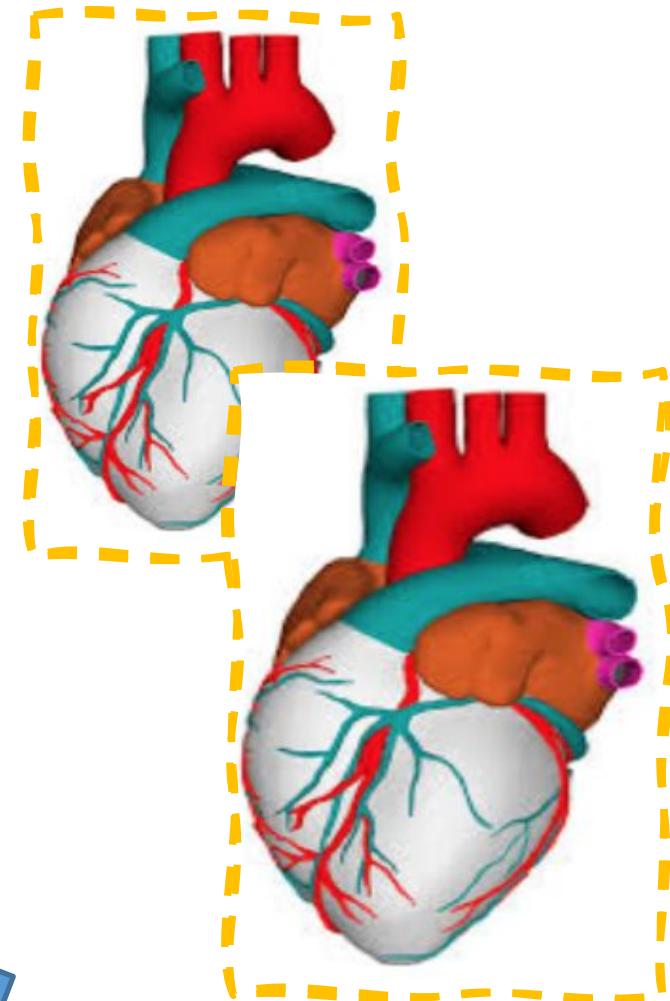


Smaller

CNN predictions

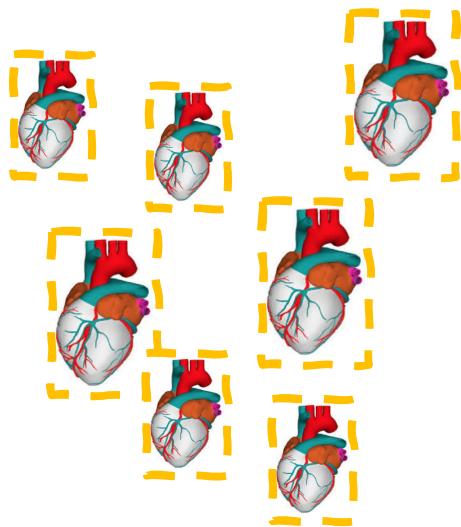


Larger

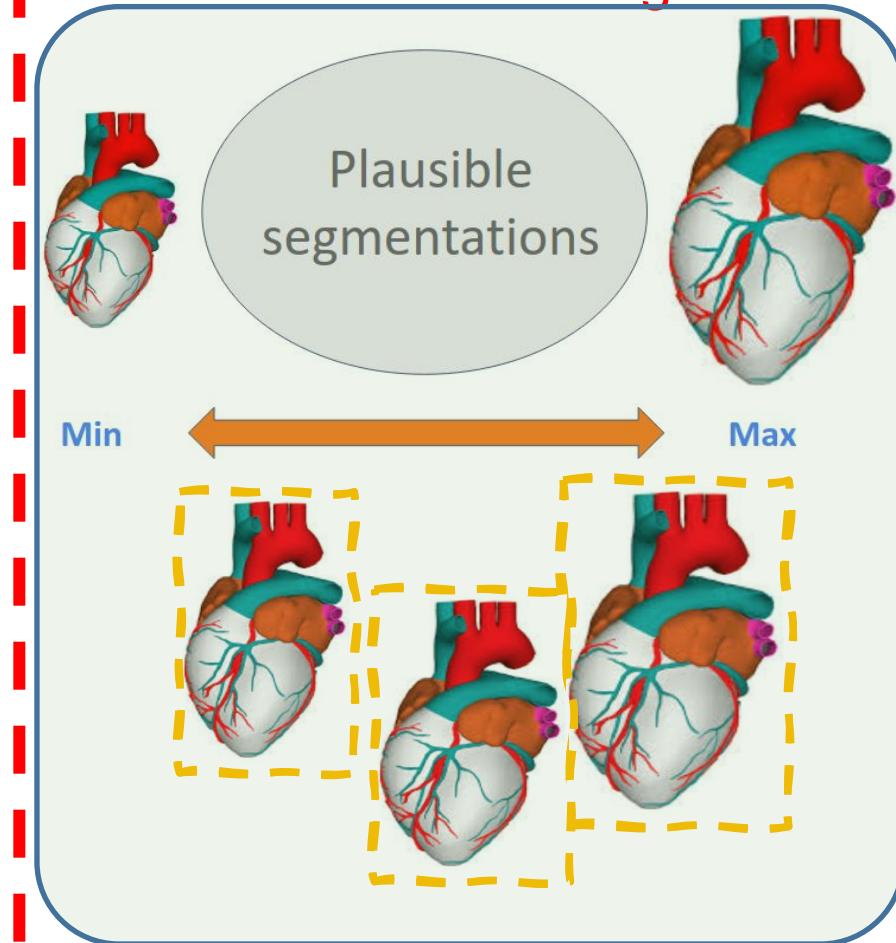


Constrained optimization (in CNNs)

Inequality constraints



Prior size knowledge

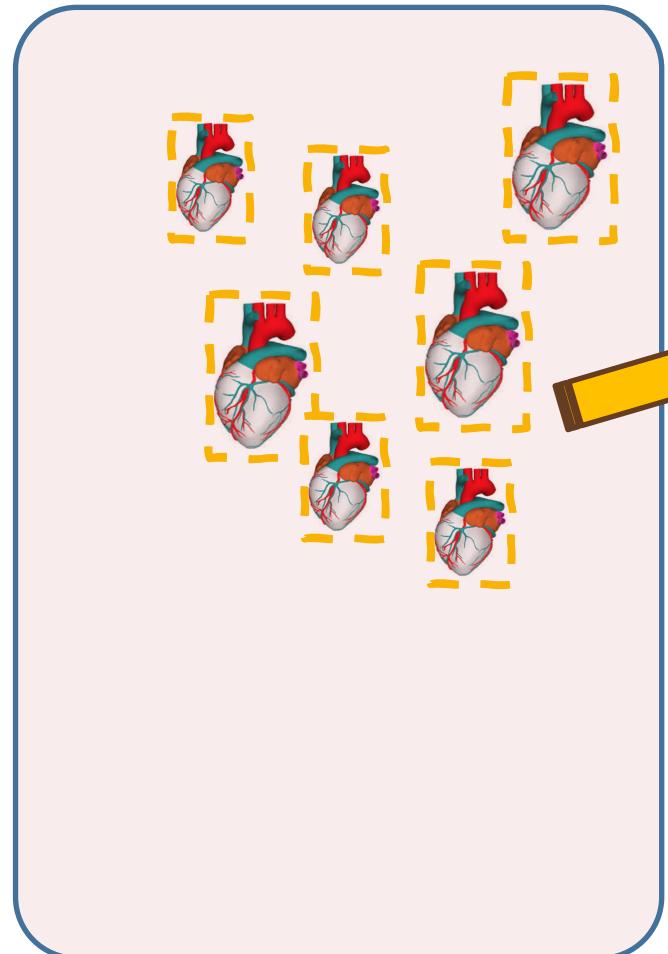


Smaller

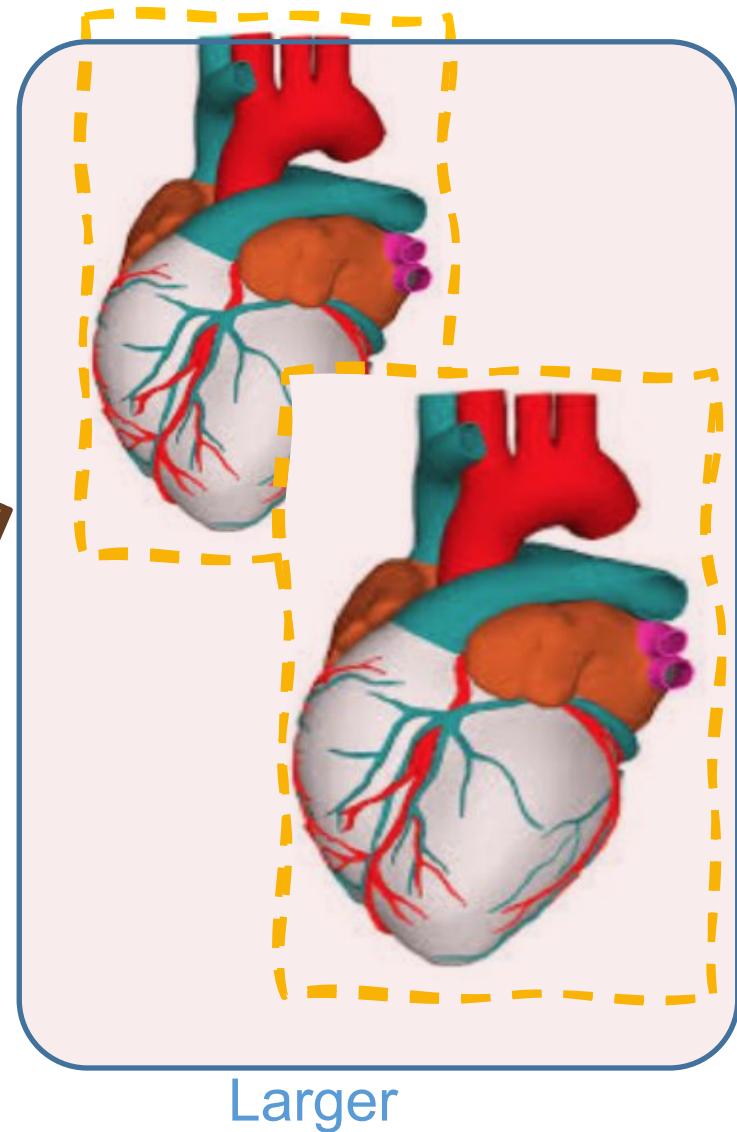
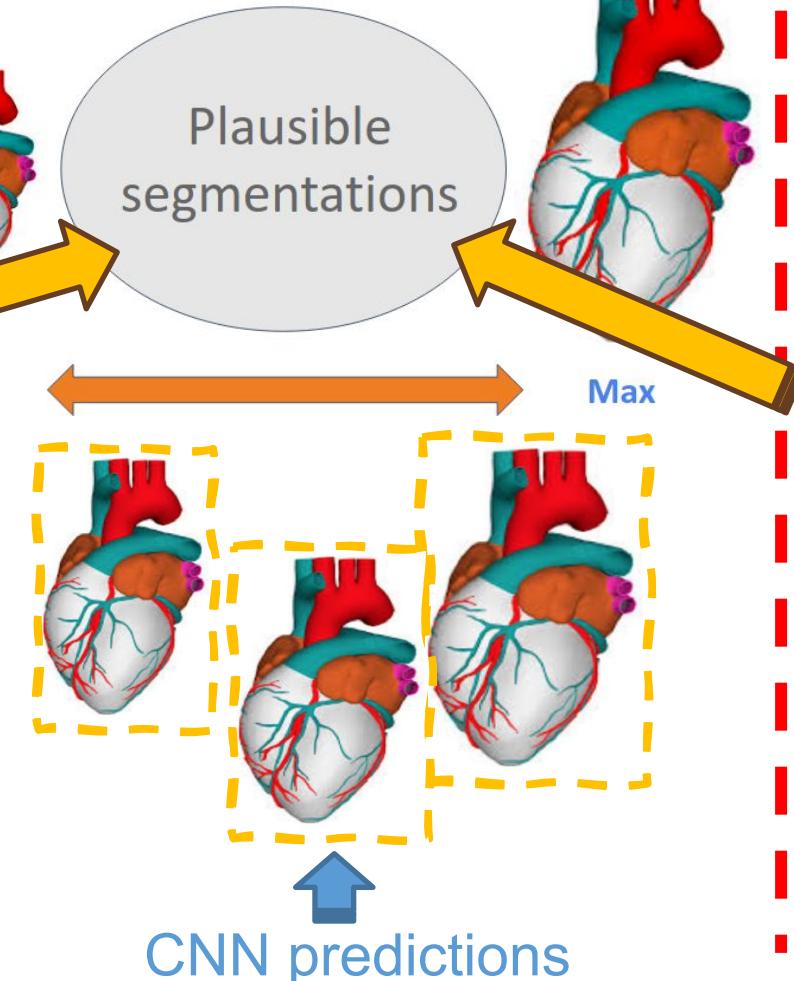
Larger

Constrained optimization (in CNNs)

Inequality constraints

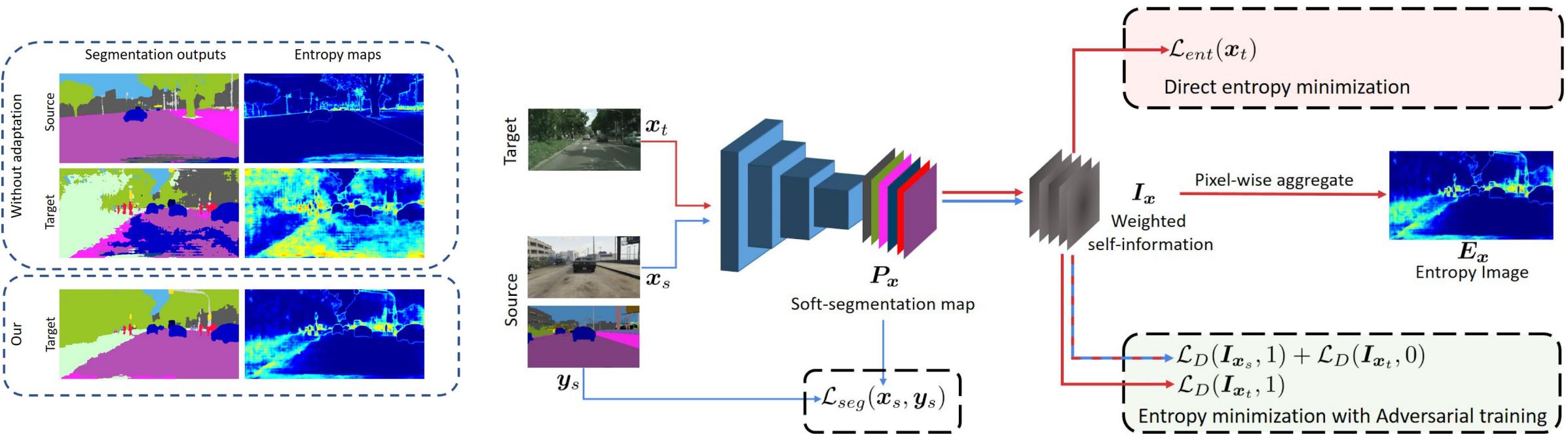


Prior size knowledge



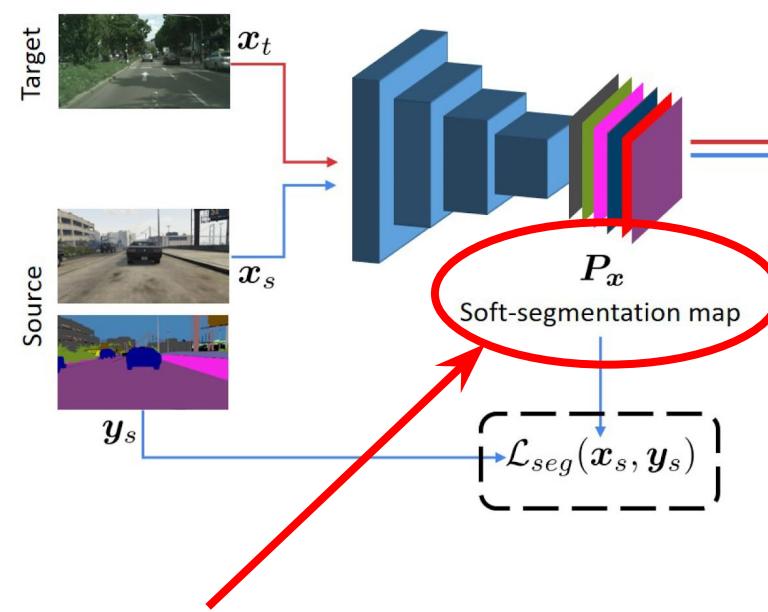
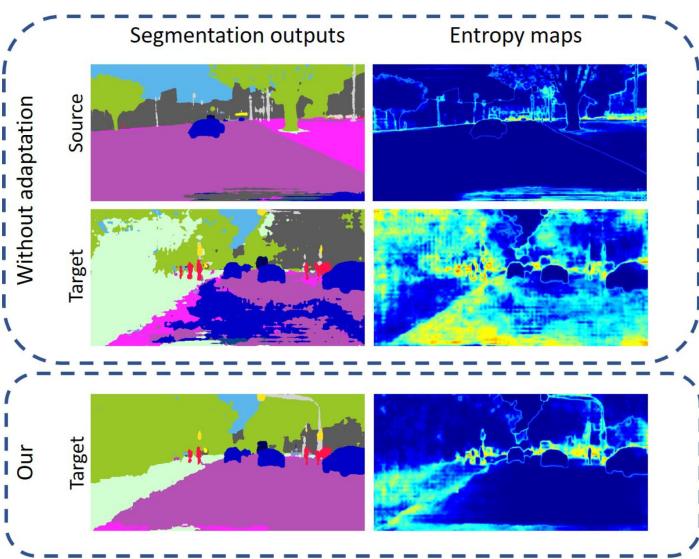
Constrained optimization (in CNNs)

Inequality constraints

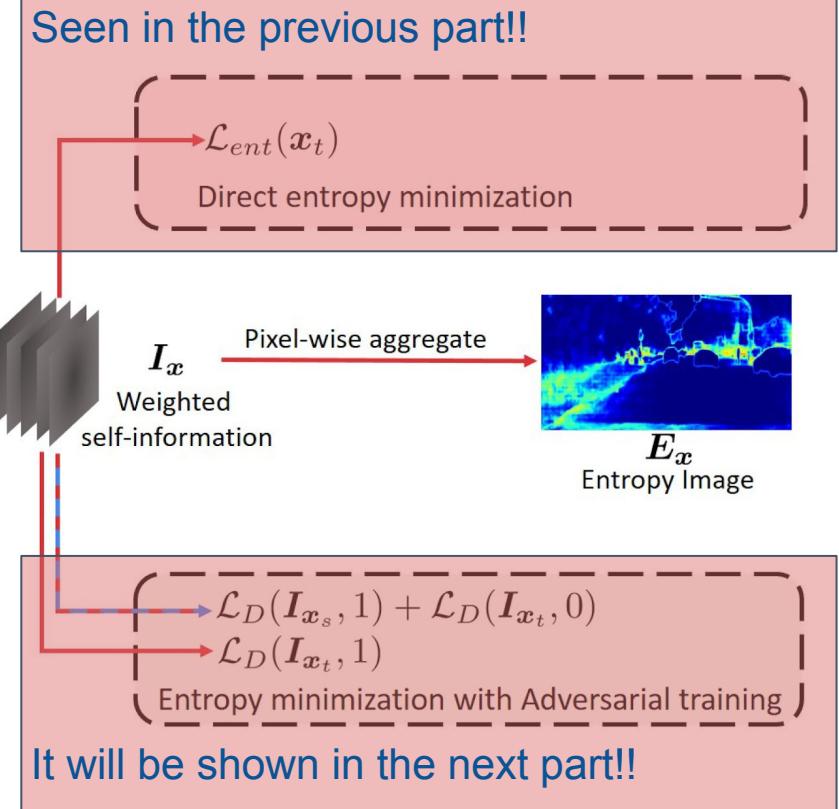


Constrained optimization (in CNNs)

Inequality constraints

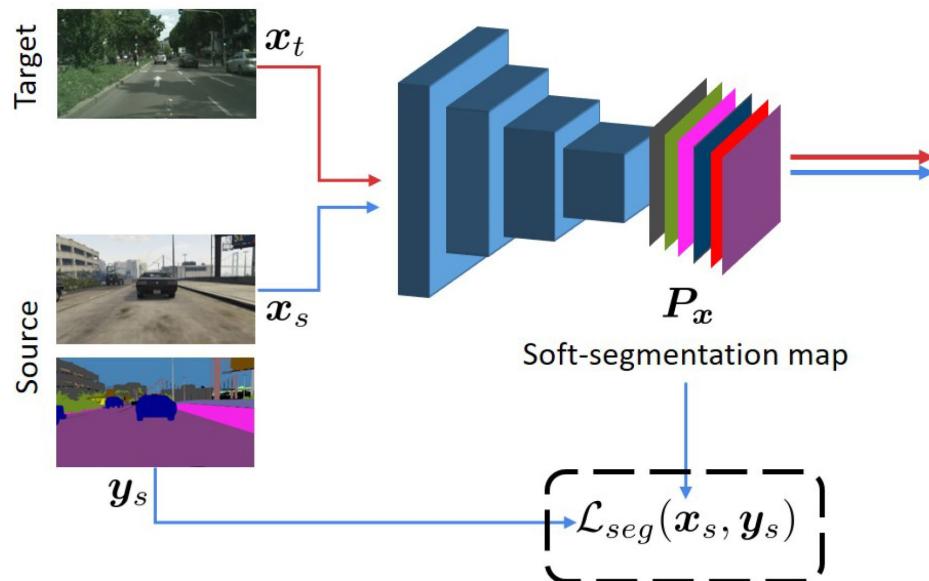


We focus on this now



Constrained optimization (in CNNs)

Inequality constraints



Class-ratio priors

$$\mathcal{L}_{cp}(\mathbf{x}_t) = \sum_{c=1}^C \max(0, \mu p_s^{(c)} - \mathbb{E}_c(P_{\mathbf{x}_t}^{(c)}))$$

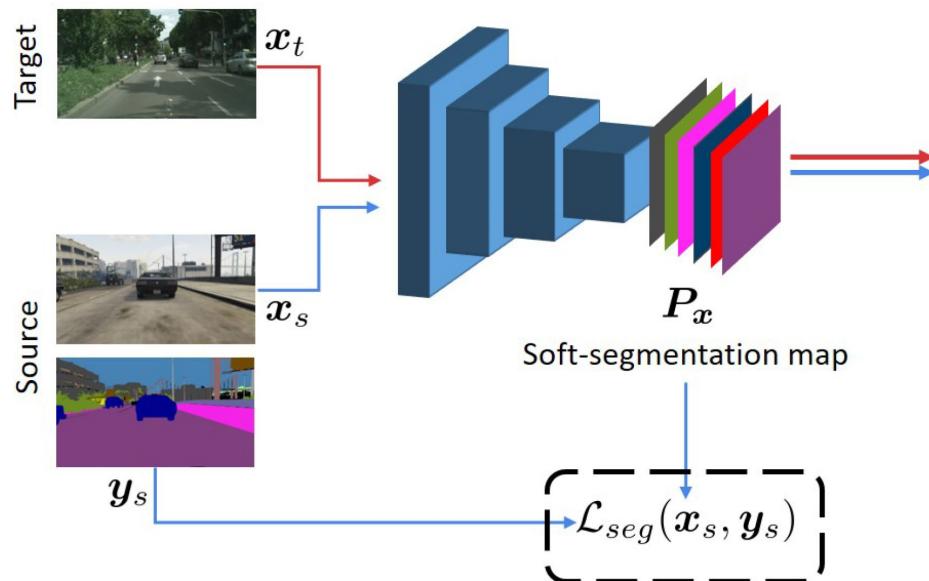
It relaxes the class prior
constraint

ℓ_1 -normalized histogram (source)

Estimated size on the prediction

Constrained optimization (in CNNs)

Inequality constraints



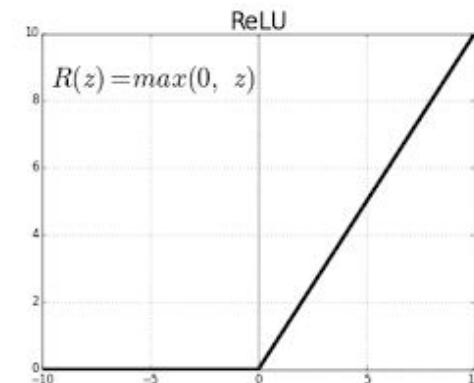
Class-ratio priors

It relaxes the class prior constraint

$$\mathcal{L}_{cp}(\mathbf{x}_t) = \sum_{c=1}^C \max(0, \mu p_s^{(c)} - \mathbb{E}_c(P_{\mathbf{x}_t}^{(c)}))$$

Estimated size on the prediction

ℓ_1 -normalized histogram (source)



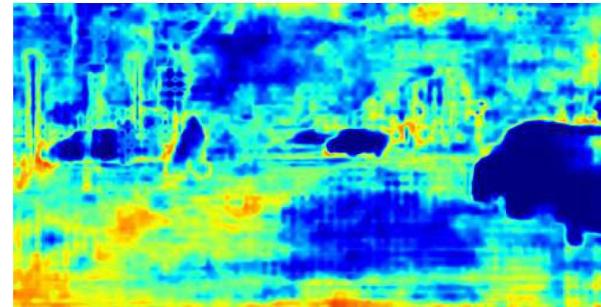
Constrained optimization (in CNNs)

Inequality constraints

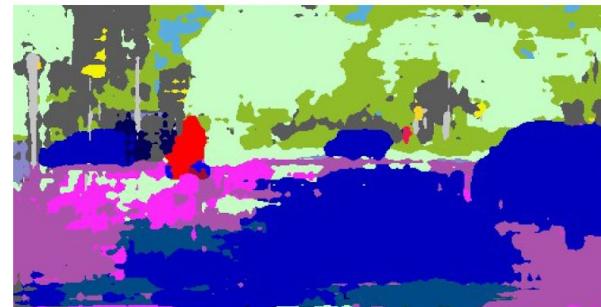
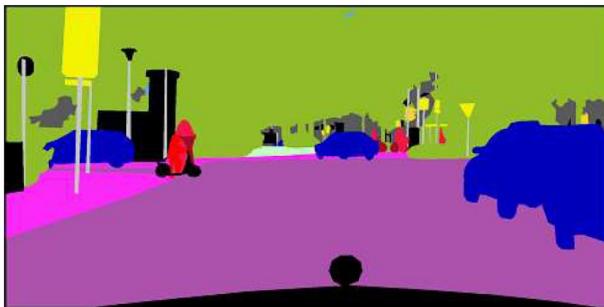
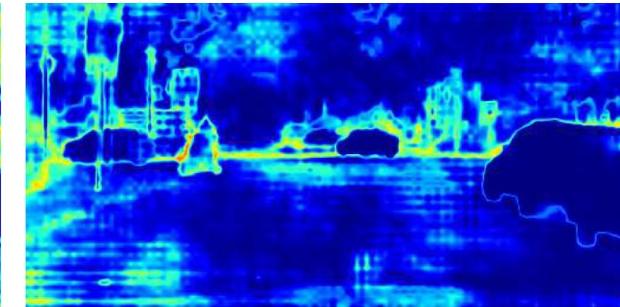
(a) Input image + GT



(b) Without adaptation



(c) MinEnt



Constrained optimization (in CNNs)

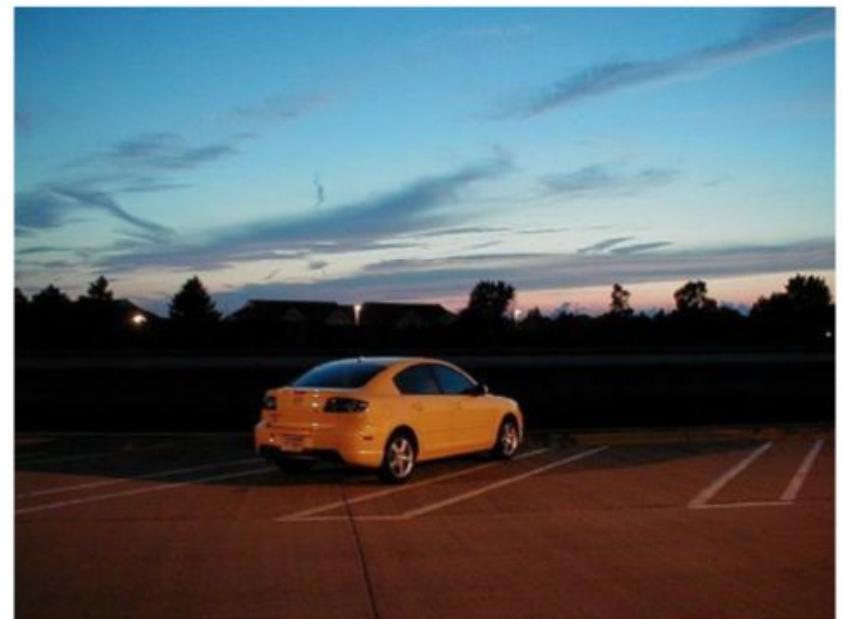
Inequality constraints

Information is given in
the form of image-tags

Suppression

$$\sum_{p \in \Omega} s_{\theta}^{p,c} \leq 0 \quad \forall c \notin C$$

“Person”



Constrained optimization (in CNNs)

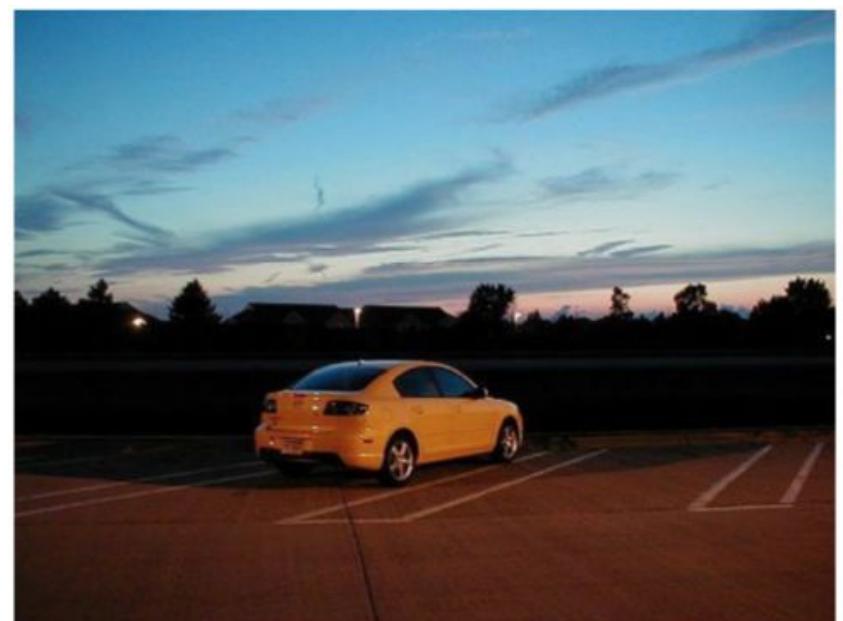
Inequality constraints

Information is given in
the form of image-tags

Inclusion
(or existence)

$$\sum_{p \in \Omega} s_{\theta}^{p,c} \geq 1 \quad \forall c \in C$$

“Car”



Constrained optimization (in CNNs)

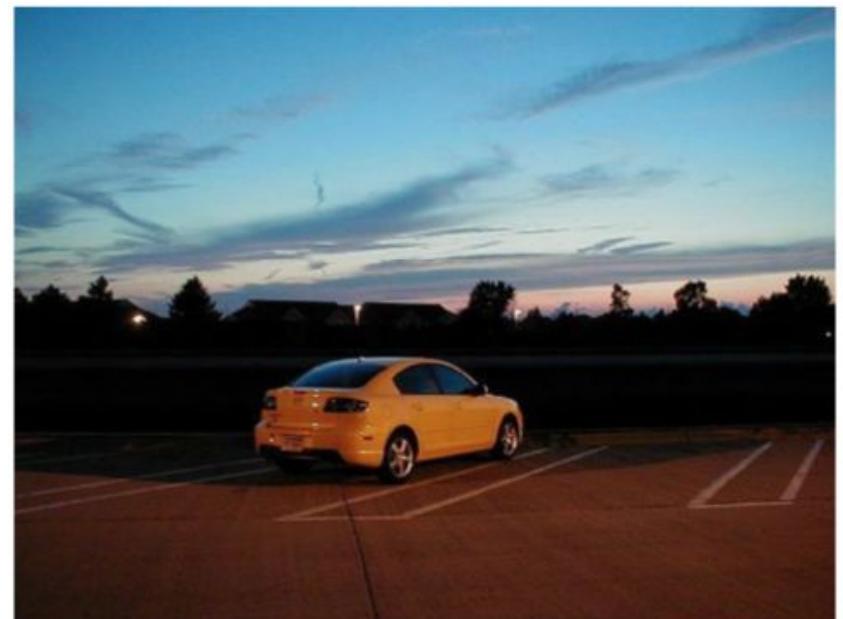
Inequality constraints

Information is given in
the form of image-tags

Target Size
 $a > 1$

$$\sum_{p \in \Omega} s_{\theta}^{p,c} \geq a \quad \forall c \in C$$

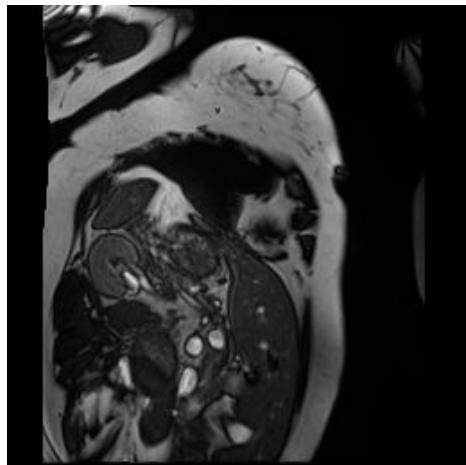
“Car”



Constrained optimization (in CNNs)

How we can benefit from this in the medical domain?

No cavity



Cavity

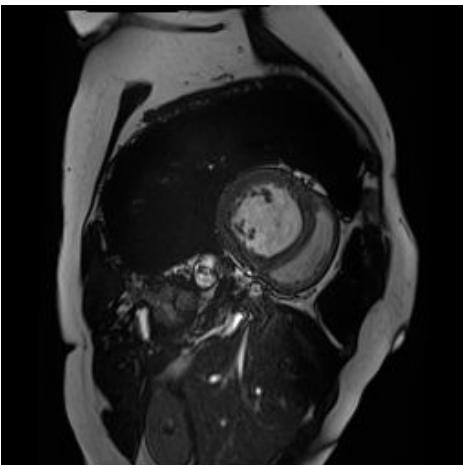


Image-tag information

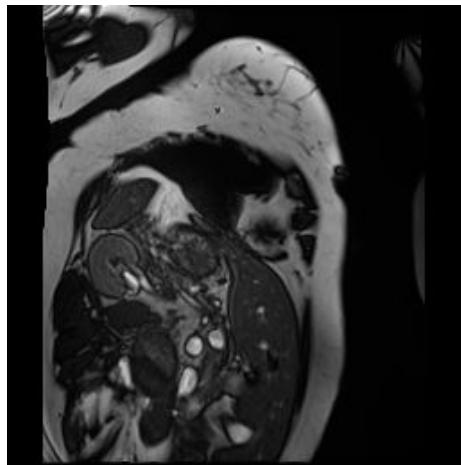
$$\sum_{p \in \Omega} s_{\theta}^{p,c} \leq 0$$

For negative image tags

Constrained optimization (in CNNs)

How we can benefit from this in the medical domain?

No cavity



Cavity

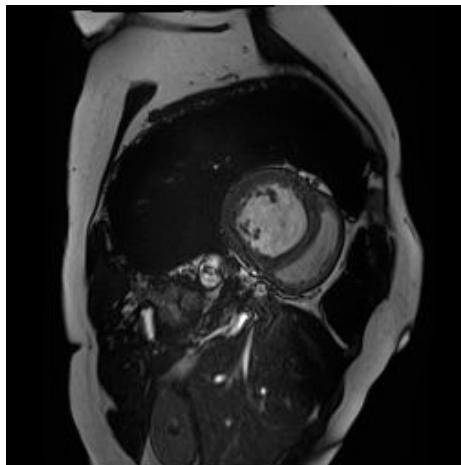
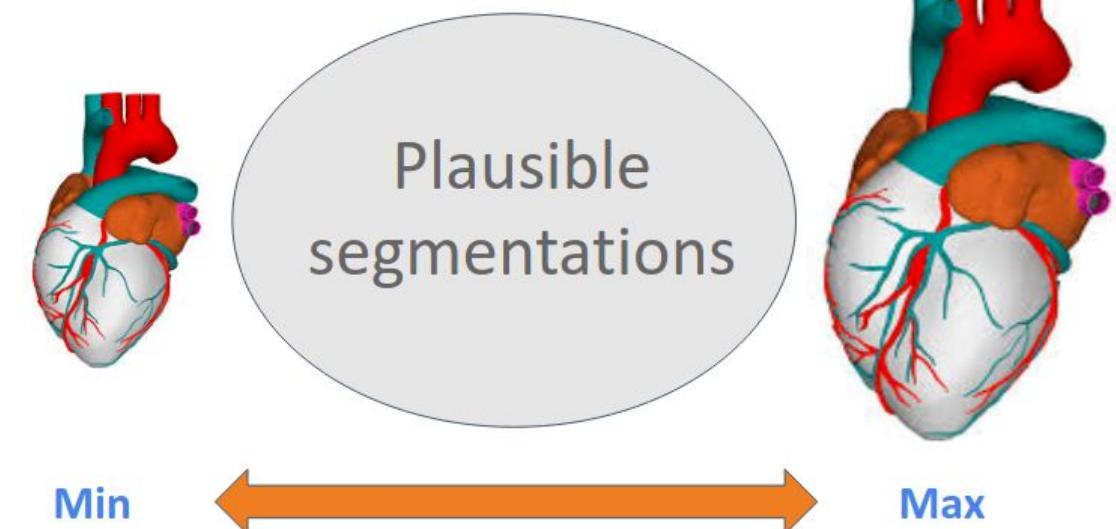


Image-tag information

$$\sum_{p \in \Omega} s_\theta^{p,c} \leq 0$$

For negative image tags

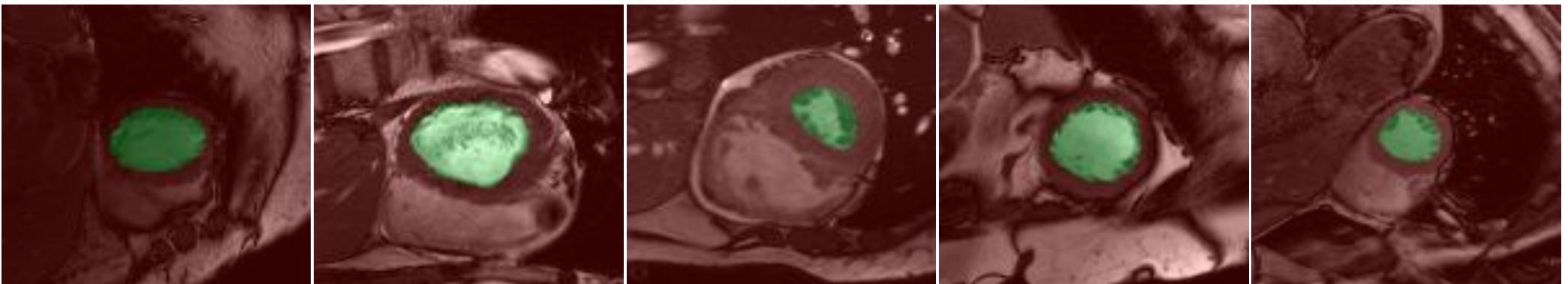


$$\min \leq \sum_{p \in \Omega} s_\theta^{p,c} \leq \max$$

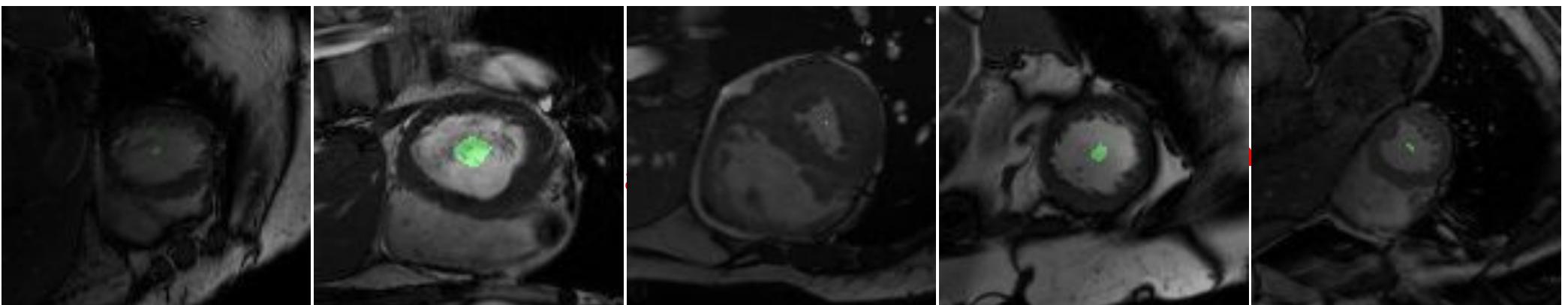
For positive image tags

Constrained optimization (in CNNs)

Inequality constraints (e.g, L2 penalty)



Full annotations



Partial annotations for cross-entropy

Constrained optimization (in CNNs)

Inequality constraints (e.g, L2 penalty)

Objective

$$\min_{\theta} \mathcal{H}(S) \quad \text{s.t.} \quad a \leq \sum_{p \in \Omega} s_{\theta}^{p,c} \leq b \quad \rightarrow \quad \mathcal{H}(S) + \lambda \mathcal{C}(V_S)$$

Constrained optimization (in CNNs)

Inequality constraints (e.g, L2 penalty)

Objective

$$\min_{\theta} \mathcal{H}(S) \quad \text{s.t.} \quad a \leq \sum_{p \in \Omega} s_{\theta}^{p,c} \leq b \quad \rightarrow \quad \mathcal{H}(S) + \lambda \mathcal{C}(V_S)$$

$$\mathcal{H}(S) = - \sum_{p \in \mathcal{L}} \log(s_{\theta}^p)$$

On annotated pixels

Constrained optimization (in CNNs)

Inequality constraints (e.g, L2 penalty)

Objective

$$\min_{\theta} \mathcal{H}(S) \quad \text{s.t.} \quad a \leq \sum_{p \in \Omega} s_{\theta}^{p,c} \leq b \quad \rightarrow \quad \mathcal{H}(S) + \lambda \mathcal{C}(V_S)$$

$$\mathcal{H}(S) = - \sum_{p \in \mathcal{L}} \log(s_{\theta}^p)$$

On annotated pixels

$$\mathcal{C}(V_S) = \begin{cases} (V_S - a)^2, & \text{if } V_S < a \\ (V_S - b)^2, & \text{if } V_S > b \\ 0, & \text{otherwise} \end{cases}$$

Constrained optimization (in CNNs)

Inequality constraints (e.g, L2 penalty)

Objective

$$\min_{\theta} \mathcal{H}(S) \quad \text{s.t.} \quad a \leq \sum_{p \in \Omega} s_{\theta}^{p,c} \leq b \quad \rightarrow \quad \mathcal{H}(S) + \lambda \mathcal{C}(V_S)$$

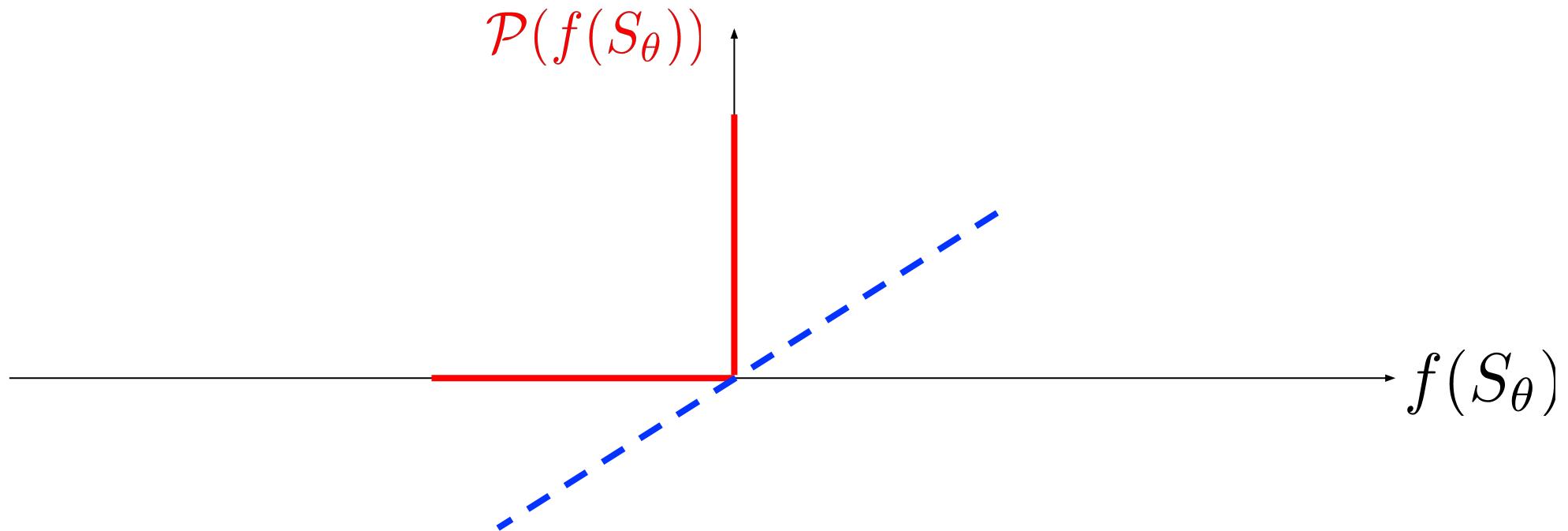
Back-propagation

$$-\frac{\partial \mathcal{C}(V_S)}{\partial \theta} \propto \begin{cases} (a - V_S) \frac{\partial S_p}{\partial \theta}, & \text{if } V_S < a \\ (b - V_S) \frac{\partial S_p}{\partial \theta}, & \text{if } V_S > b \\ 0, & \text{otherwise} \end{cases}$$

Constrained optimization (in CNNs)

Inequality constraints (Why not Lagrangian primal/dual?)

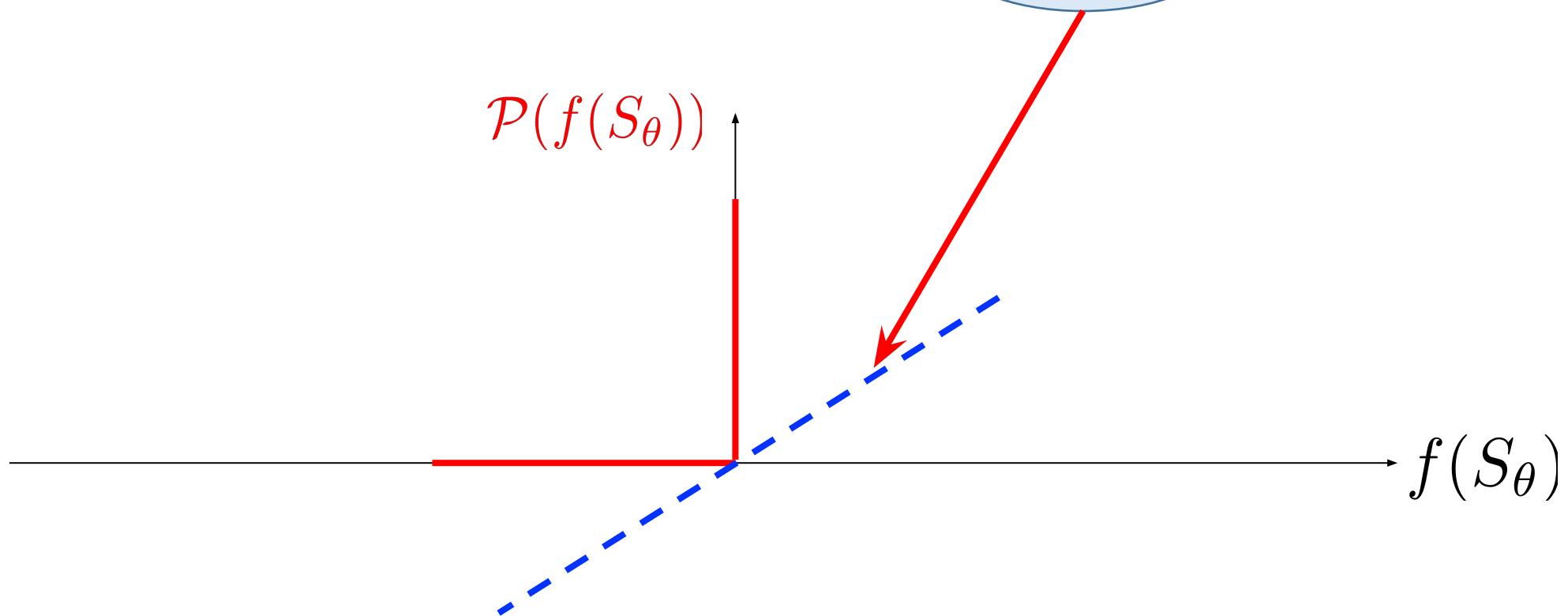
$$\mathcal{L}(S_\theta, \lambda) = \mathcal{E}(\theta) + \lambda f(S_\theta)$$



Constrained optimization (in CNNs)

Inequality constraints (Why not Lagrangian primal/dual?)

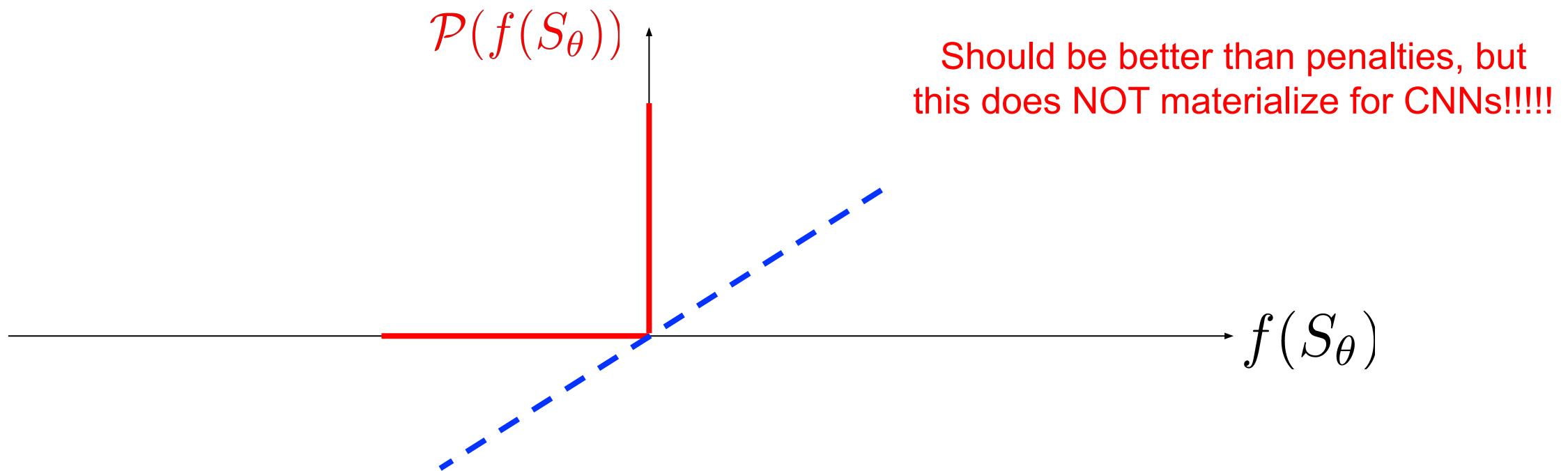
$$\mathcal{L}(S_\theta, \lambda) = \mathcal{E}(\theta) + \lambda f(S_\theta)$$



Constrained optimization (in CNNs)

Inequality constraints (Why not Lagrangian primal/dual?)

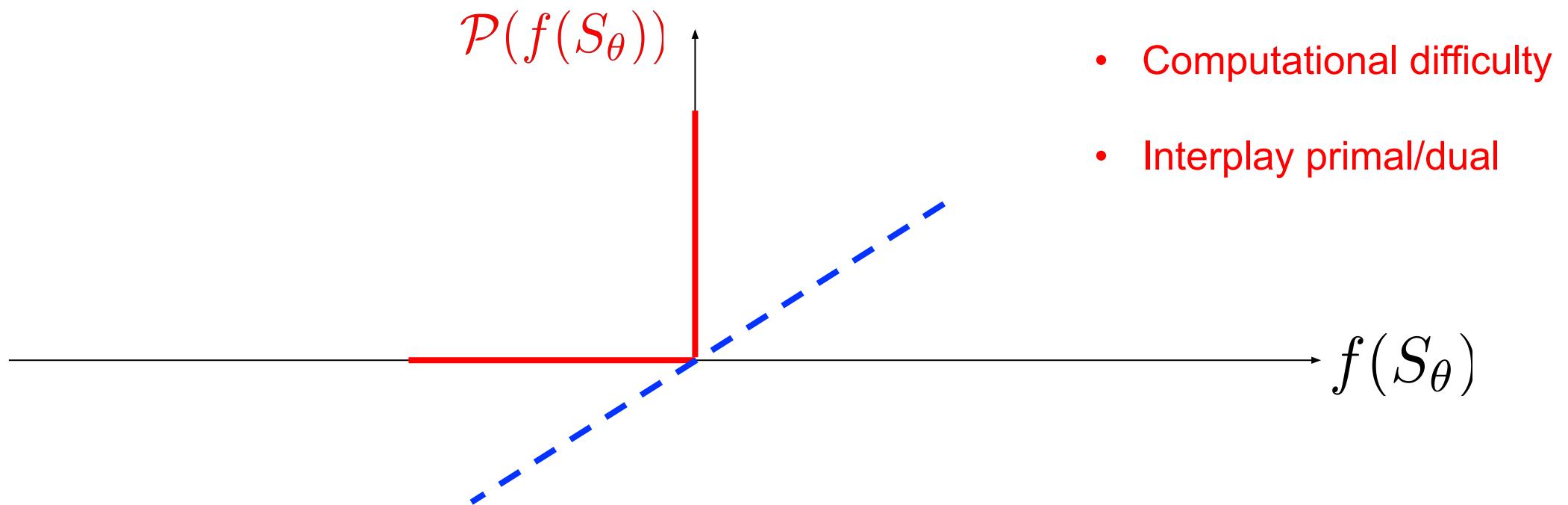
$$\mathcal{L}(S_\theta, \lambda) = \mathcal{E}(\theta) + \lambda f(S_\theta)$$



Constrained optimization (in CNNs)

Inequality constraints (Why not Lagrangian primal/dual?)

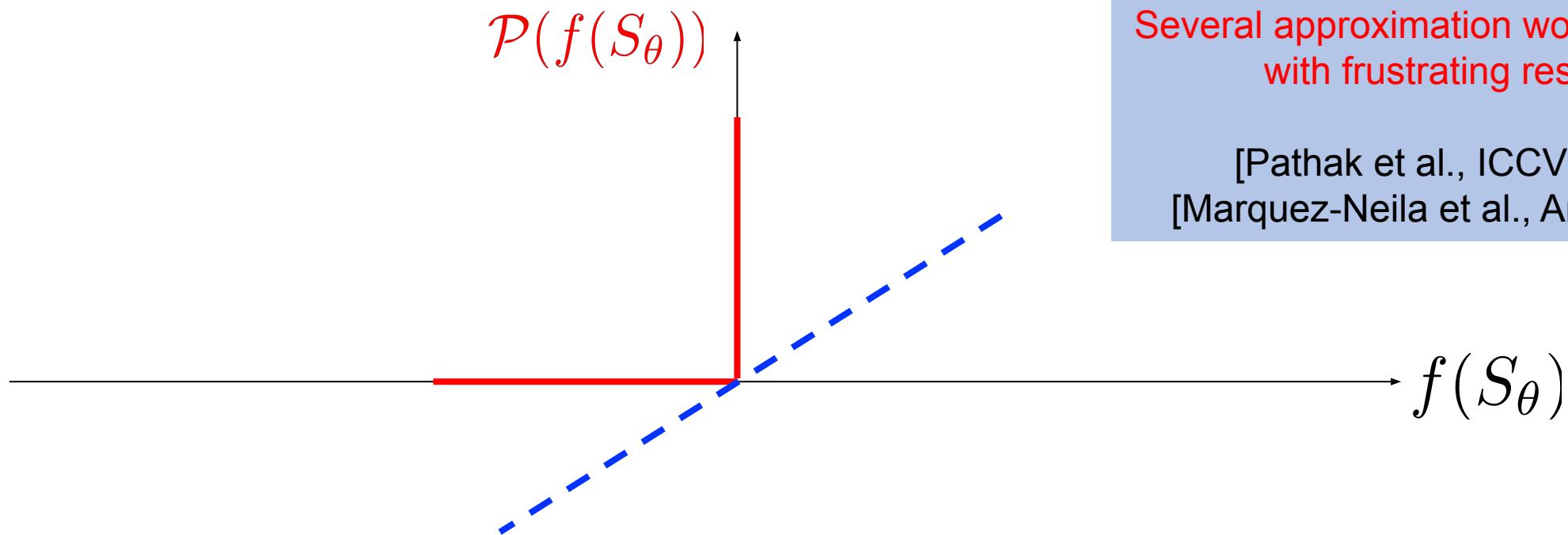
$$\mathcal{L}(S_\theta, \lambda) = \mathcal{E}(\theta) + \lambda f(S_\theta)$$



Constrained optimization (in CNNs)

Inequality constraints (Why not Lagrangian primal/dual?)

$$\mathcal{L}(S_\theta, \lambda) = \mathcal{E}(\theta) + \lambda f(S_\theta)$$



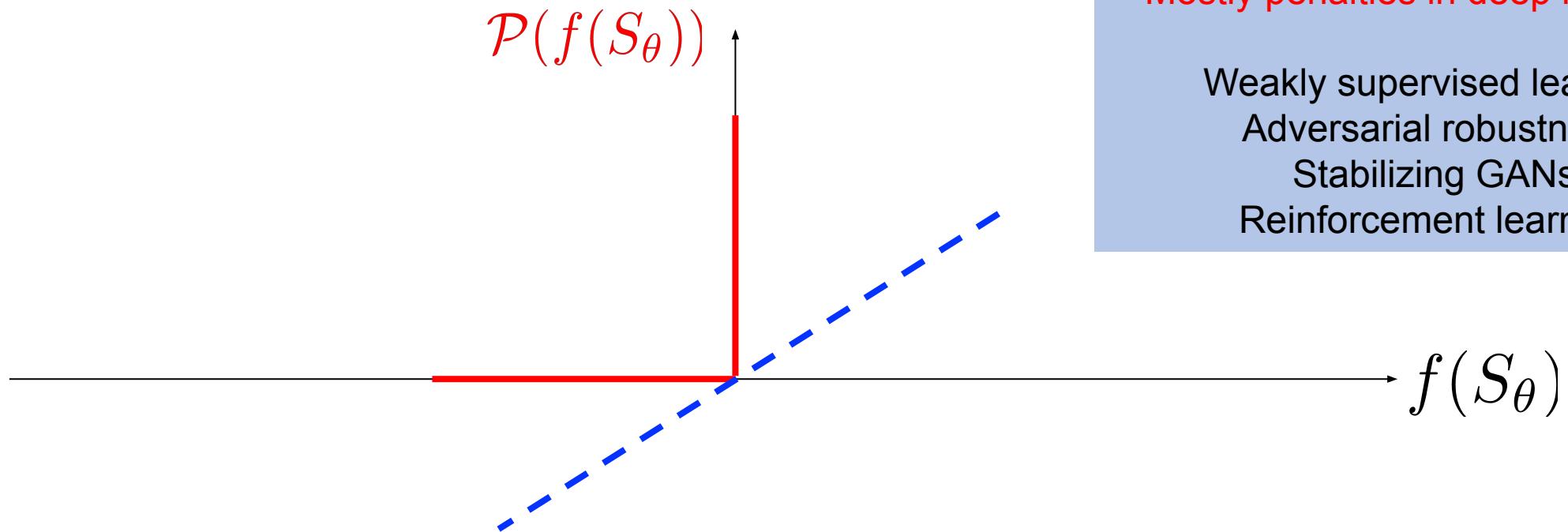
Several approximation works recently,
with frustrating results:

[Pathak et al., ICCV 2015]
[Marquez-Neila et al., ArXiv 2017]

Constrained optimization (in CNNs)

Inequality constraints (Why not Lagrangian primal/dual?)

$$\mathcal{L}(S_\theta, \lambda) = \mathcal{E}(\theta) + \lambda f(S_\theta)$$

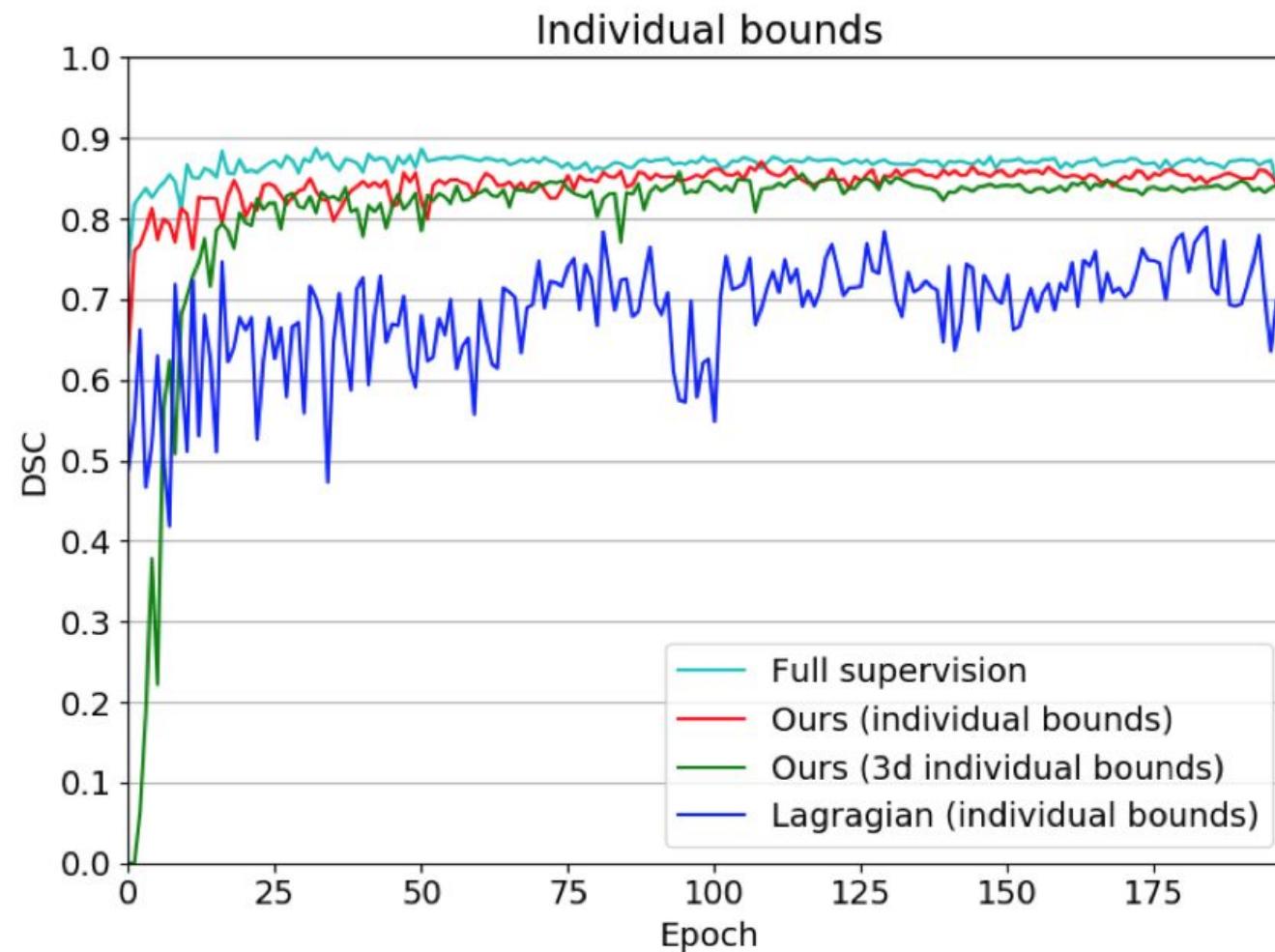


Mostly penalties in deep networks:

Weakly supervised learning
Adversarial robustness
Stabilizing GANs
Reinforcement learning

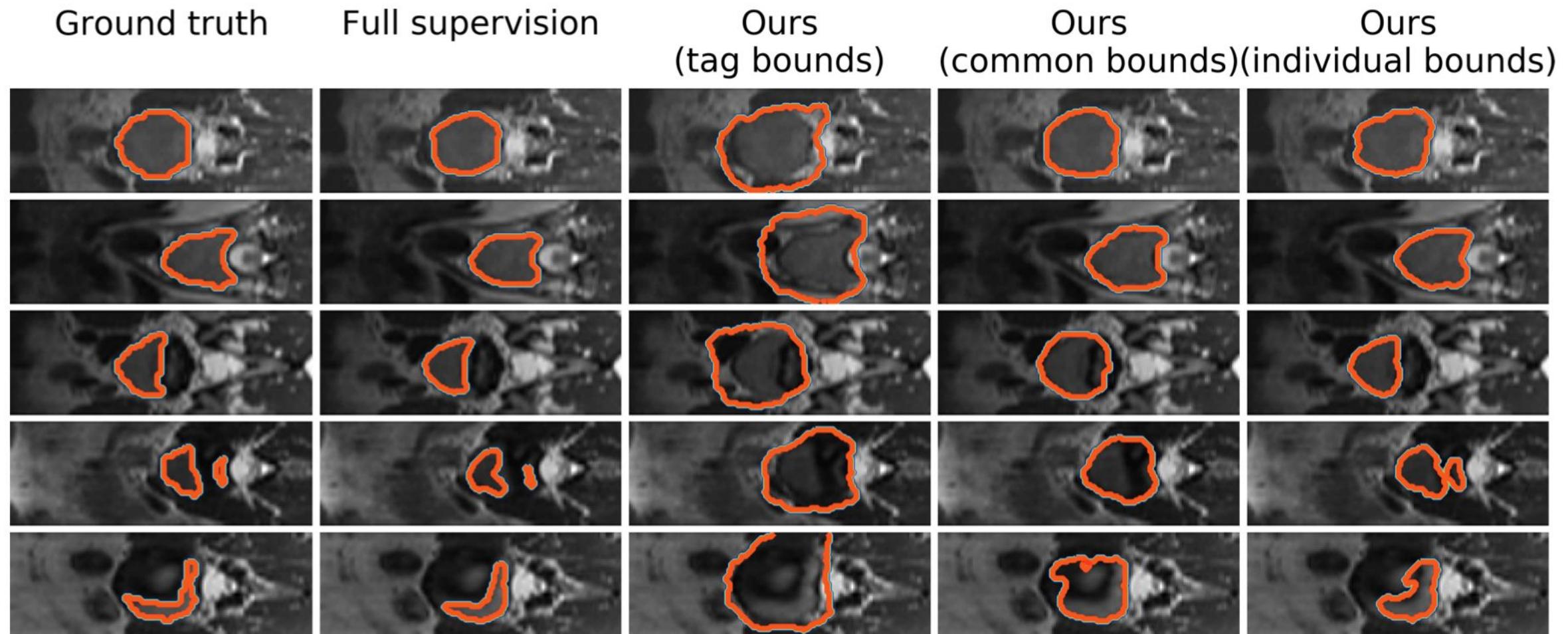
Constrained optimization (in CNNs)

Inequality constraints (e.g, L2 penalty)



Constrained optimization (in CNNs)

Inequality constraints (e.g, L2 penalty)



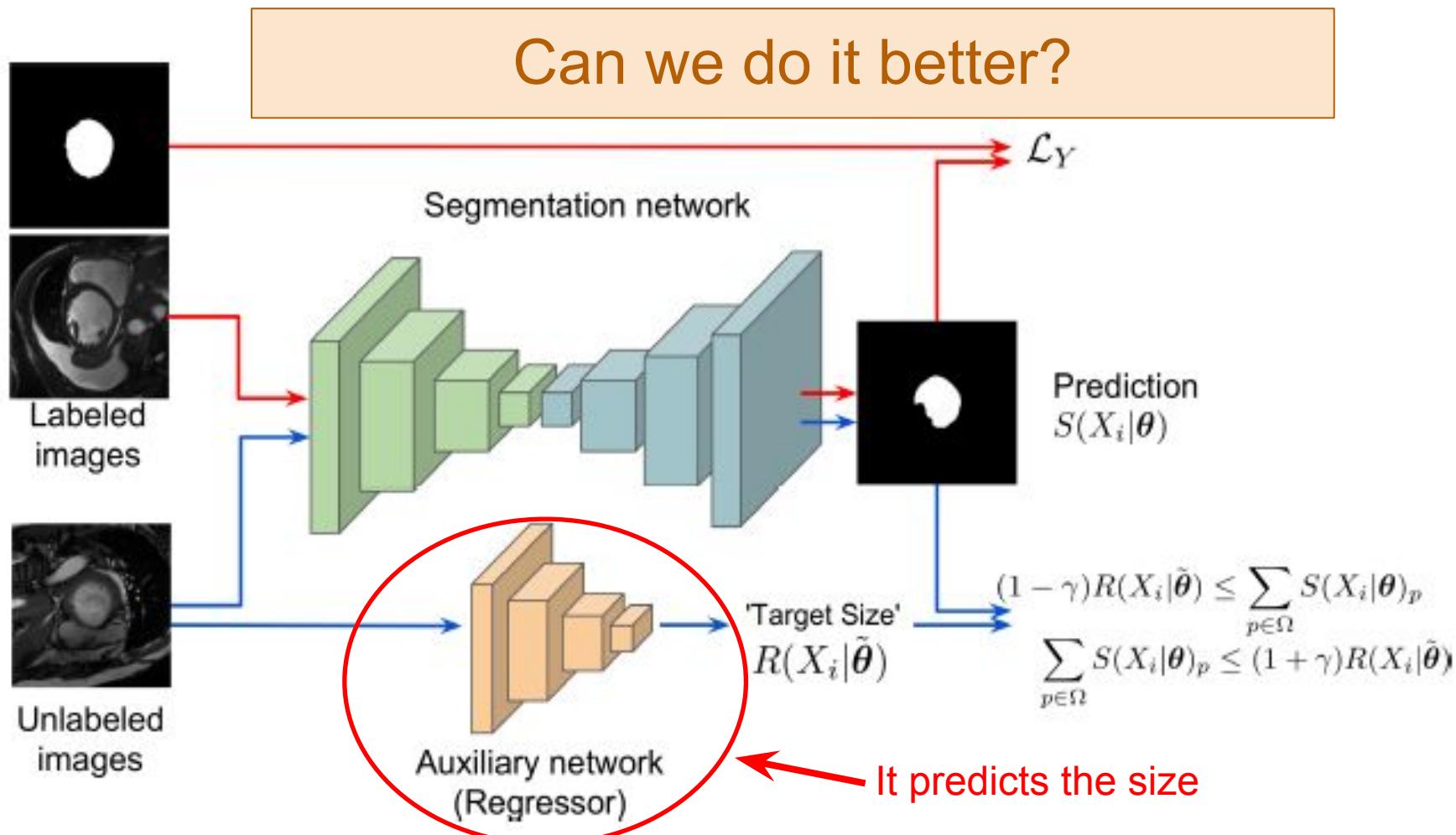
Constrained optimization (in CNNs)

Inequality constraints (e.g, L2 penalty)

Can we do it better?

Constrained optimization (in CNNs)

Inequality constraints (e.g, L2 penalty)



Constrained optimization (in CNNs)

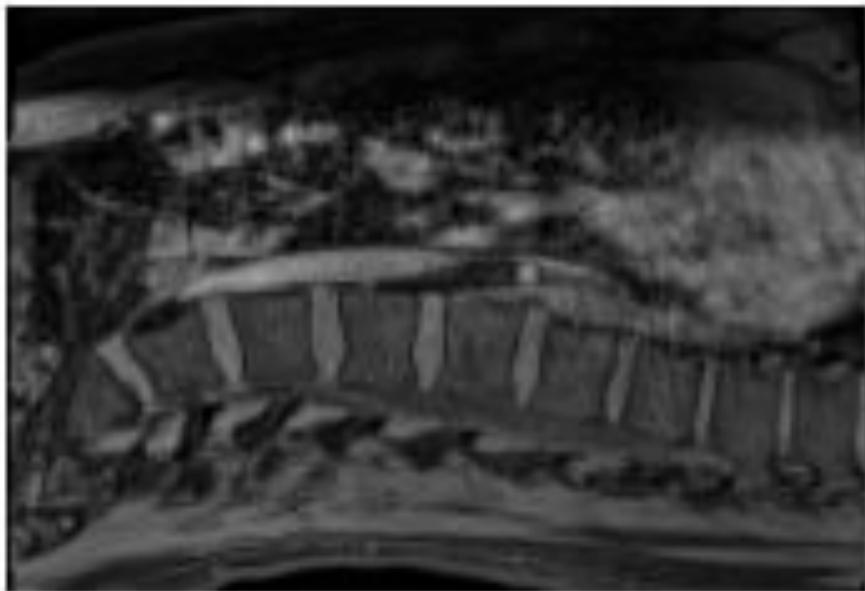
Inequality constraints (e.g, L2 penalty)

Also useful in Domain adaptation!

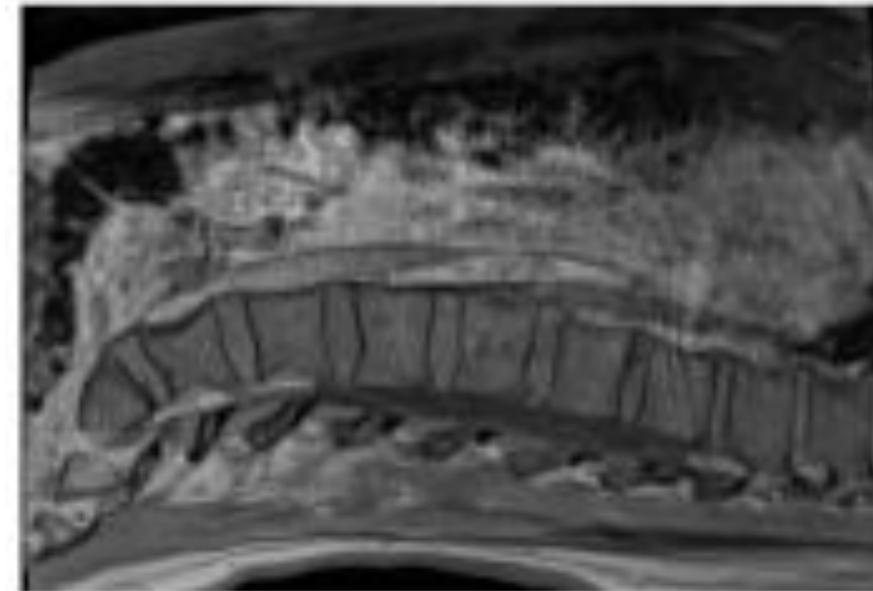
Constrained optimization (in CNNs)

Inequality constraints (e.g, L2 penalty)

Source (labeled) modality (WAT)



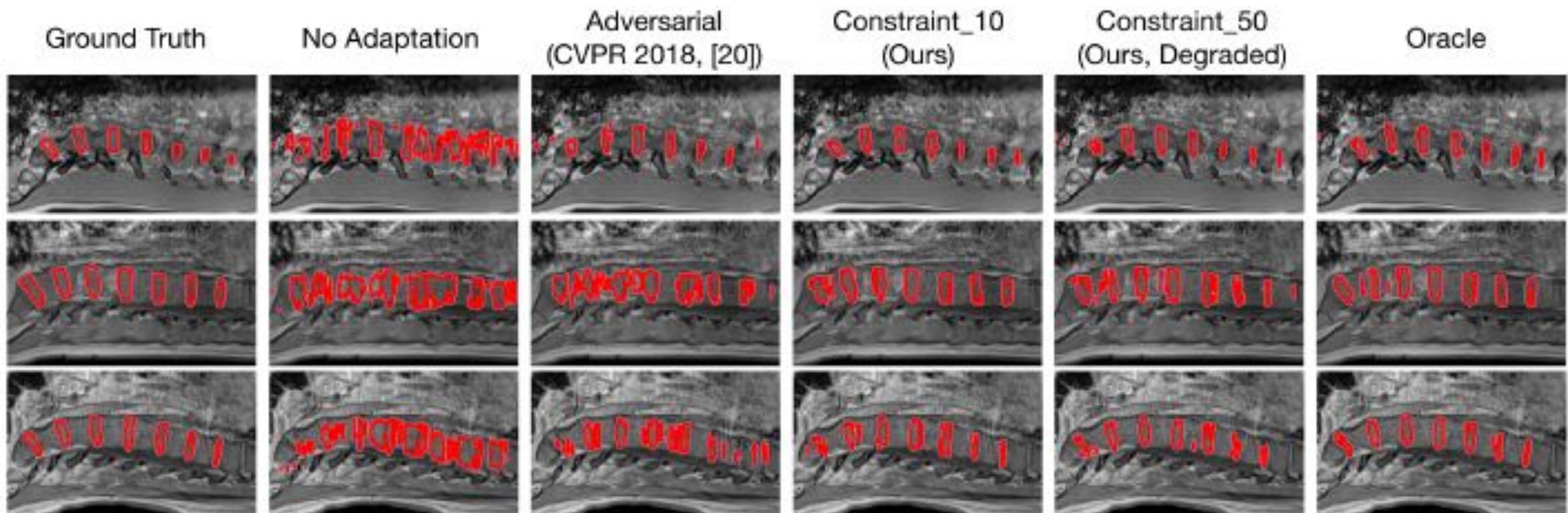
Target (unlabeled) modality (IP)



Dataset from IVD 2018 MICCAI Challenge

Constrained optimization (in CNNs)

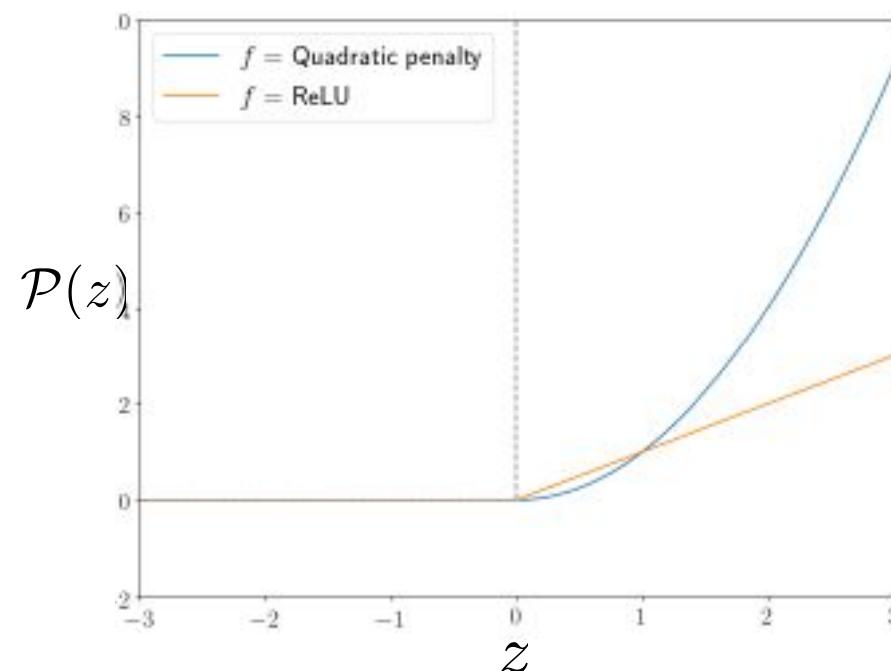
Inequality constraints (e.g, L2 penalty)



Limitations of penalties

$$\min_{\theta} \mathcal{J}(\theta)$$

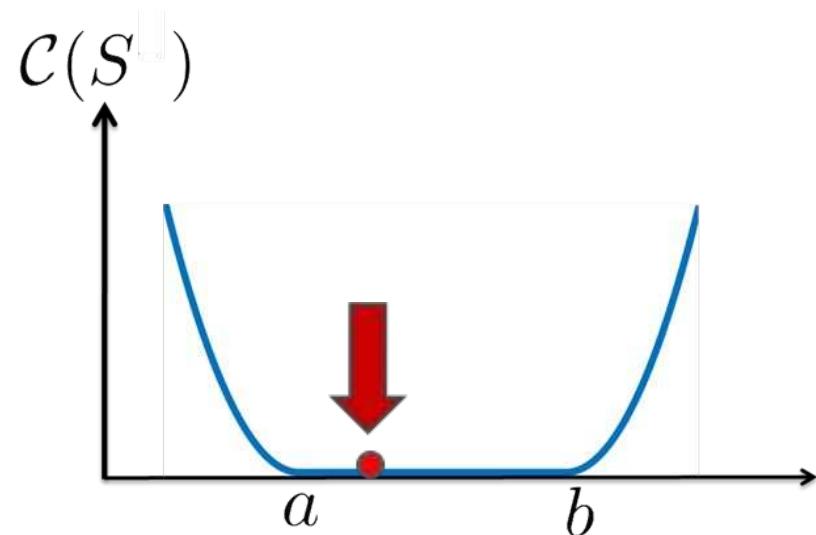
$$\mathcal{J}(\theta) = \mathcal{E}(\theta) + \lambda \mathcal{P}(f(S_\theta))$$



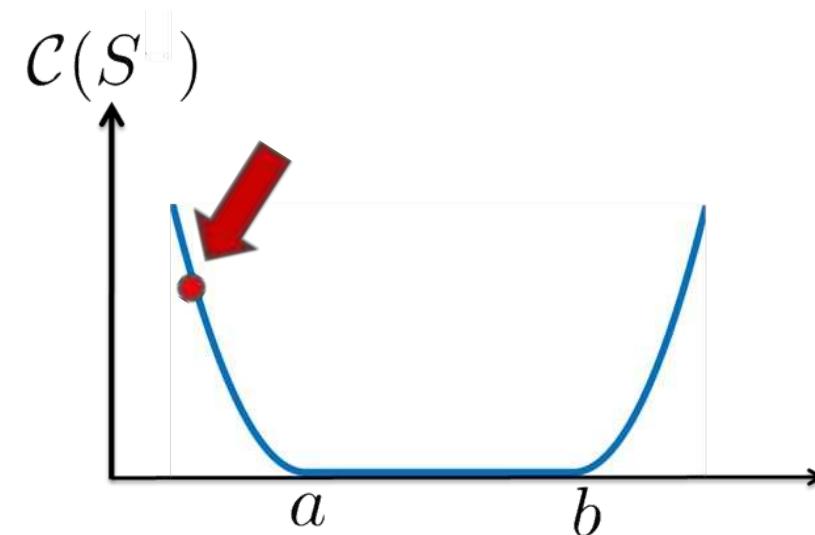
Problem: How to set the weight?
Multiples constraints make it worse?

Limitations of penalties

Multiple constraints



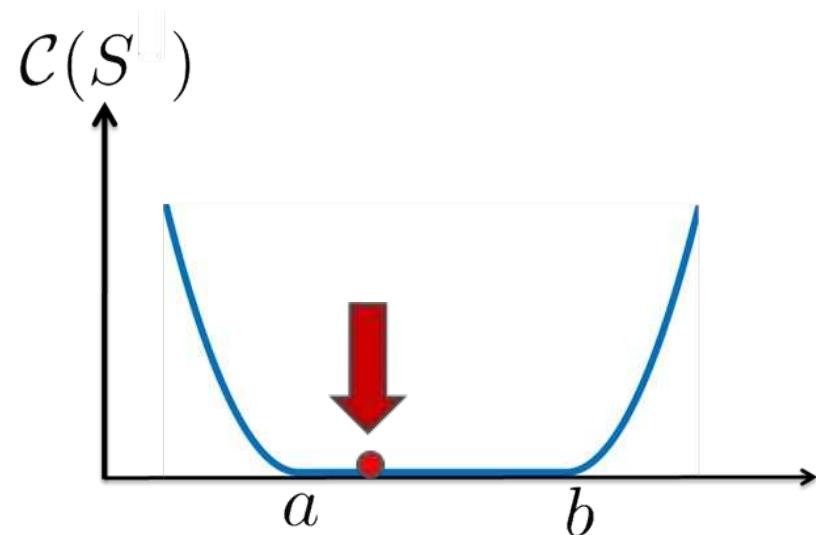
Constraint A satisfied



Constraint B violated

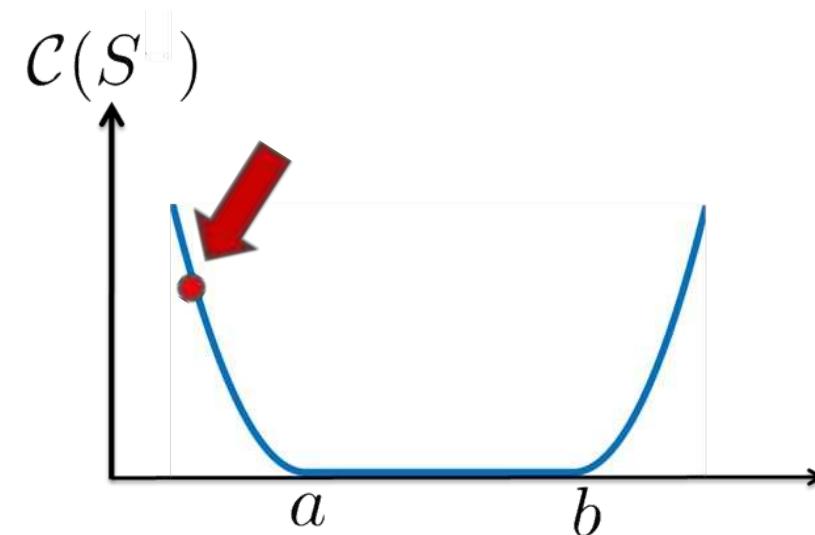
Limitations of penalties

Multiple constraints



Constraint A satisfied

Gradient is 0



Constraint B violated

Gradient is NOT 0

Log-barrier extensions: Approximates Lagrangian optimization but **NO** explicit dual steps

Lagrangian optimization can deal with these limitations:

- it finds automatically the **optimal weights** of the constraints.
- it acts as a **barrier** for satisfied constraints.
- it **guarantees constraint satisfaction** when feasible solutions exist.

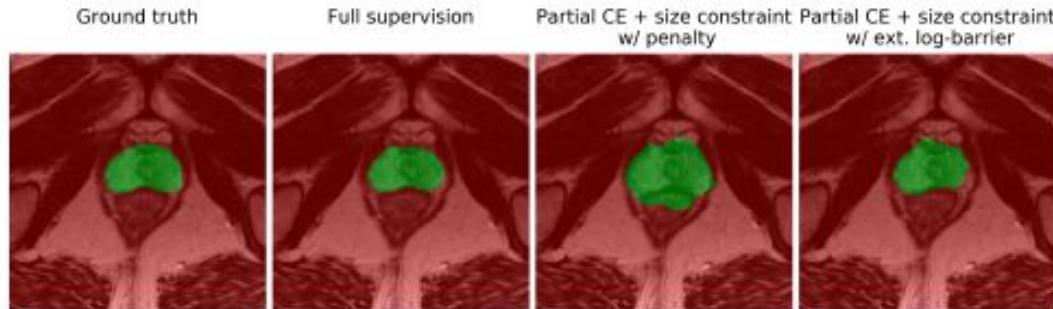
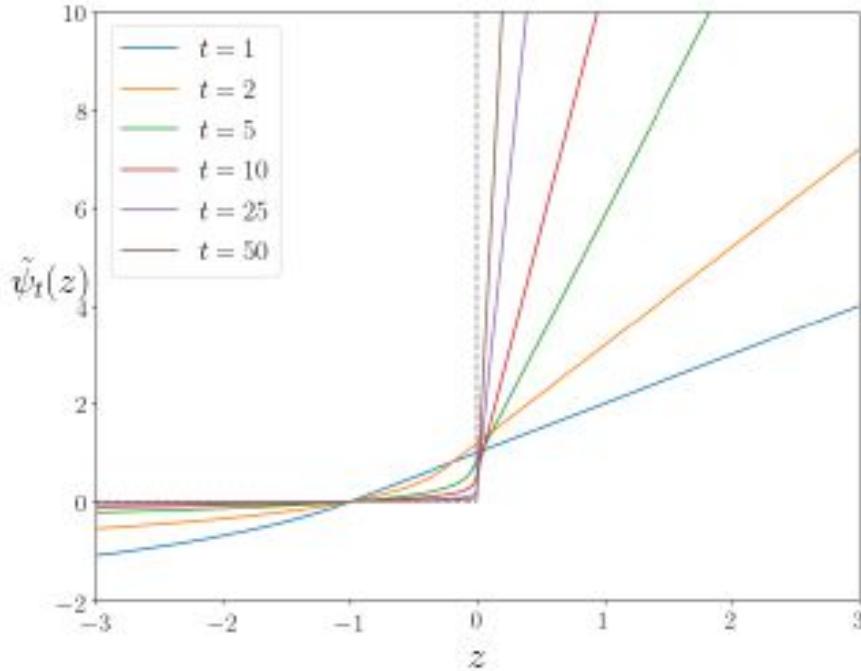
Log-barrier extensions: Approximates Lagrangian optimization but **NO** explicit dual steps

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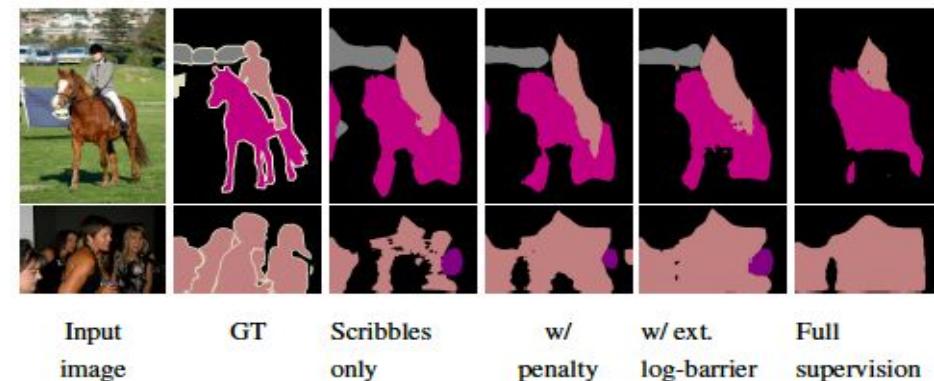
$$\min_{\boldsymbol{\theta}} \mathcal{E}(\boldsymbol{\theta}) + \sum_{i=1}^N \tilde{\psi}_t(f_i(S_{\boldsymbol{\theta}})) \quad \rightarrow \quad \tilde{\psi}_t(z) = \begin{cases} -\frac{1}{t} \log(-z) & \text{if } z \leq -\frac{1}{t^2} \\ tz - \frac{1}{t} \log(\frac{1}{t^2}) + \frac{1}{t} & \text{otherwise} \end{cases}$$

Log-barrier extensions: Approximates Lagrangian optimization but **NO** explicit dual steps

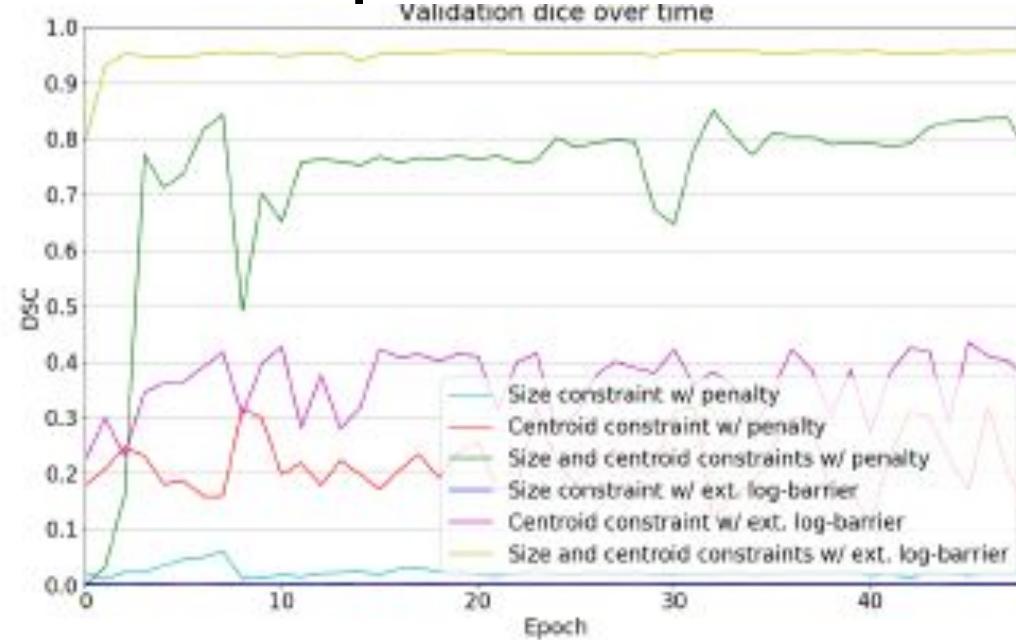


Promising results

Method	Dataset	
	PROMISE12 (DSC)	VOC2012 (mIoU)
Partial cross-entropy	0.032 (0.015)	48.48 (14.88)
w/ penalty [12]	0.830 (0.057)	52.22 (14.94)
w/ extended log-barrier	0.852 (0.038)	53.40 (14.62)
Full supervision	0.891 (0.032)	59.87 (16.94)

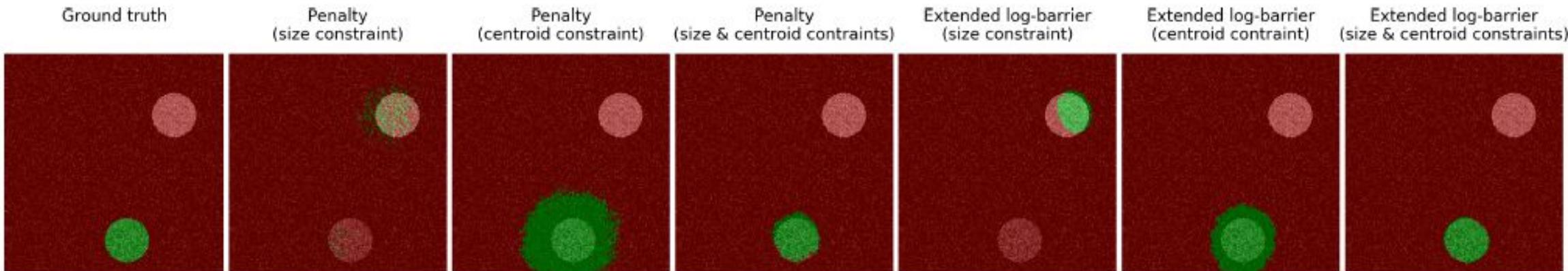


Log-barrier extensions: Approximates Lagrangian optimization but **NO** explicit dual steps



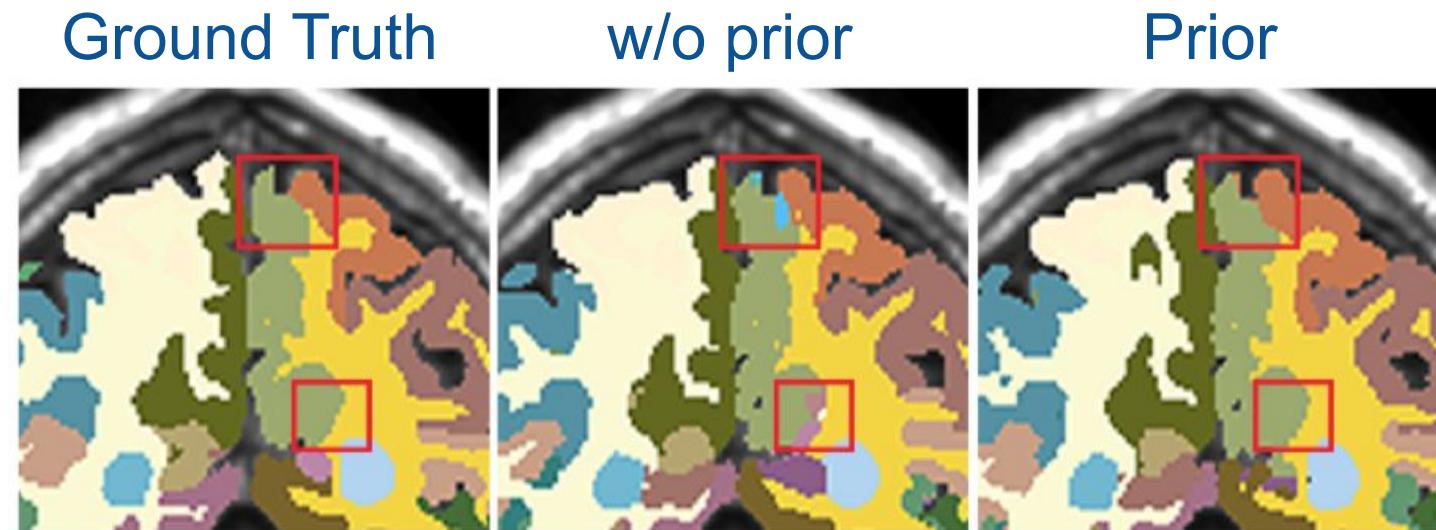
Promising results

Method	Constraints		
	Size	Centroid	Size & Centroid
Penalty [12]	0.0601	0.3197	0.8514
Extended log-barrier	0.0018	0.4347	0.9574



Other constraints (Semi-supervision)

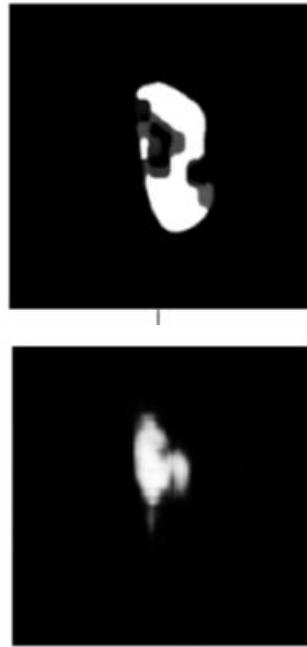
Connectivity of anatomical structures



Other constraints (Full-supervision)

Shape

Bad
segmentations



Good
segmentations



Other constraints (Full-supervision)

Shape

Bad
segmentations



Good
segmentations



During training

Oktay et al., IEEE TMI'17

Post-processing

Larrazabal et al., MICCAI'19
Painchaud et al., MICCAI'19

Take-home message

- Imposing constraints helps weakly-supervised segmentation learning by restricting plausible segmentations on unlabeled images
- Few constraints have been explored under low-labeled data regime
- Room for improvement (many opportunities)

Data-driven priors

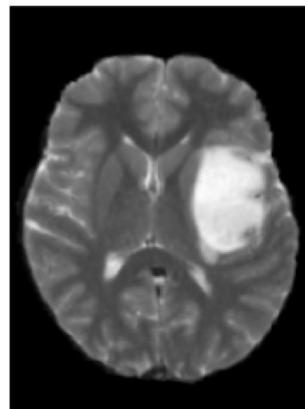
Introduction

Data-driven priors (cues)

Image tags



Person
Bike



Tumor

Original
Image

Image tags

- Pathak et al., Constrained convolutional neural networks for weakly supervised segmentation, ICCV 2015
- Kervadec et al., Constrained-CNN losses for weakly supervised segmentation, Media 2019.

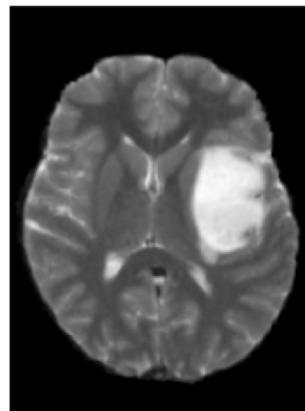
Data-driven priors (cues)

Image tags

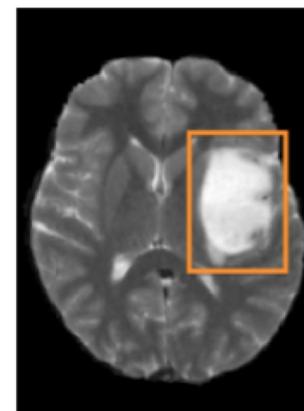
Bounding boxes



Person
Bike



Tumor



Original
Image

Image tags

Bounding
boxes

- Pathak et al., Constrained convolutional neural networks for weakly supervised segmentation, ICCV 2015
- Kervadec et al., Constrained-CNN losses for weakly supervised segmentation, Media 2019.

Data-driven priors (cues)

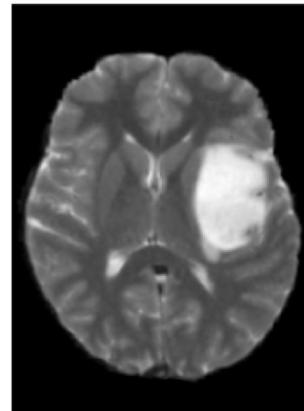
Image tags

Bounding boxes

Scribbles



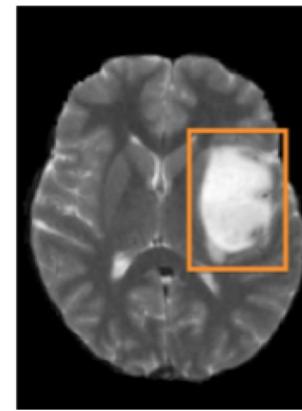
Person
Bike



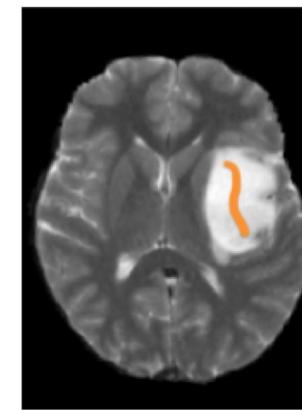
Tumor

Original
Image

Image tags



Bounding
boxes



Scribbles

- Pathak et al., Constrained convolutional neural networks for weakly supervised segmentation, ICCV 2015
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Data-driven priors (cues)

Image tags

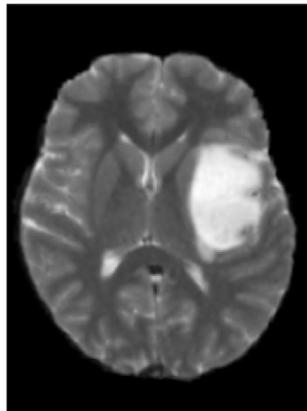
Bounding boxes

Scribbles

Points



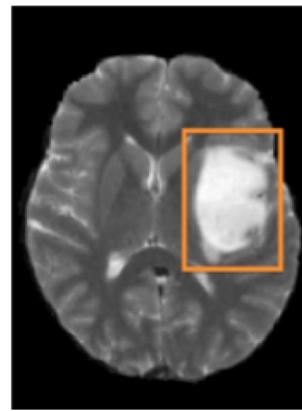
Person
Bike



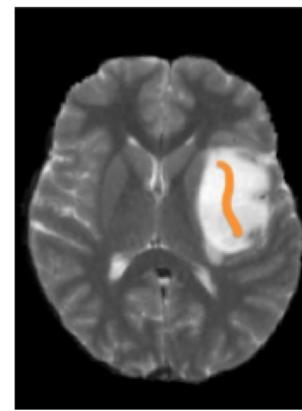
Tumor

Original
Image

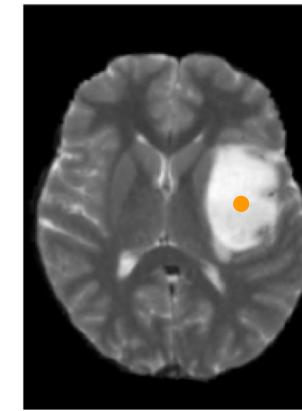
Image tags



Bounding
boxes



Scribbles



Points

- Pathak et al., Constrained convolutional neural networks for weakly supervised segmentation, ICCV 2015
- Kervadec et al., Constrained-CNN losses for weakly supervised segmentation, Media 2019.

Data-driven priors (cues)

Another data-driven priors

Image captions



A boy jumping on a skateboard

Extreme points

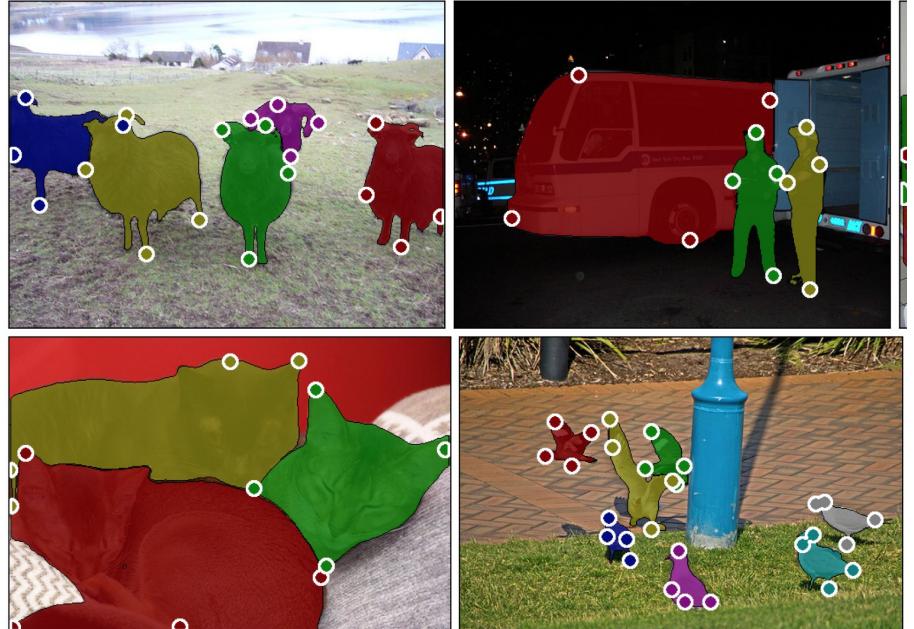


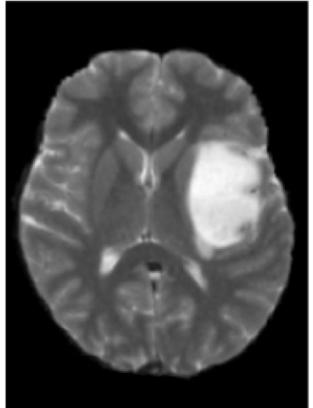
Image from Maninis et al, CVPR'18

- Maninis et al. Deep extreme cut: From extreme points to object segmentation. CVPR 2018

From global cues to pixel labels



Person
Bike



Tumor

Original Image

Image tags



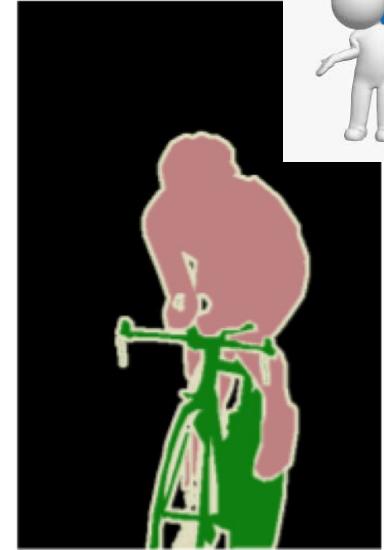
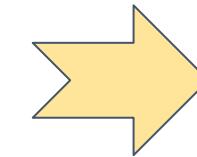
Bounding boxes



Scribbles

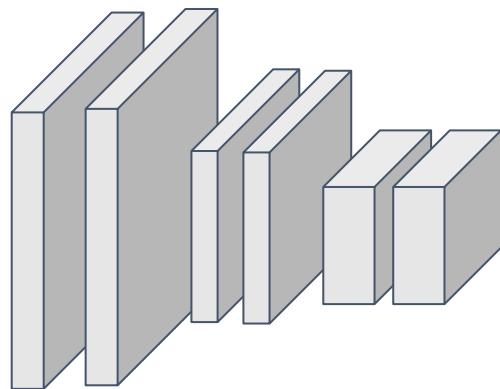
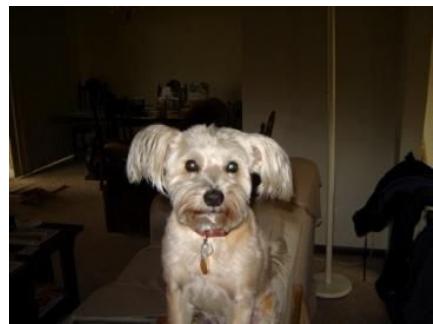


Points



From global cues to pixel labels

Step 1: Get a classification CNN



Convolutional layers



FC Layers

Class scores

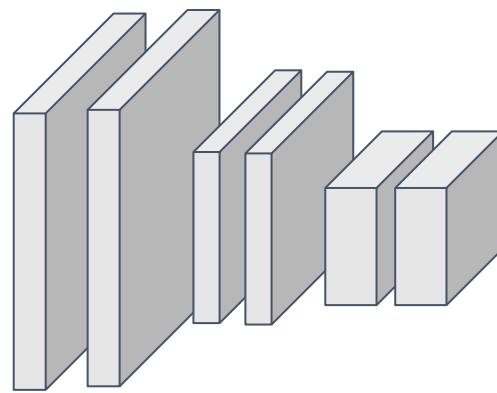
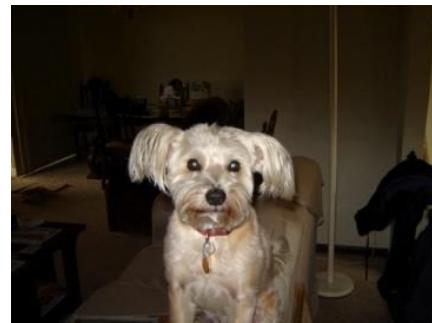
Cat

Dog

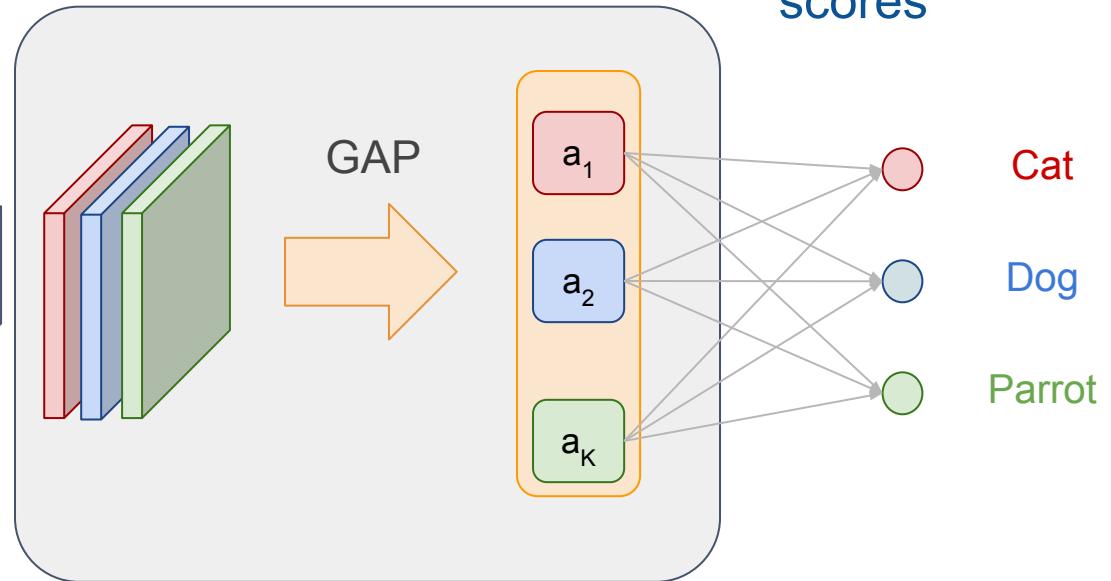
Parrot

From global cues to pixel labels

Step 2: Modify the last layers

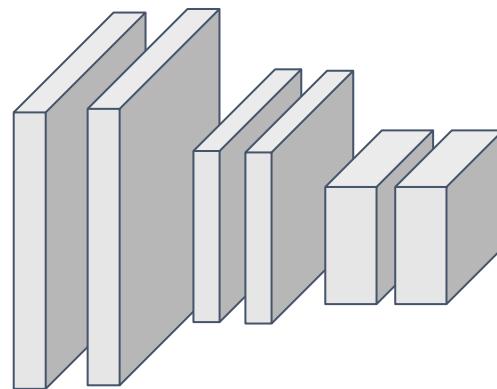
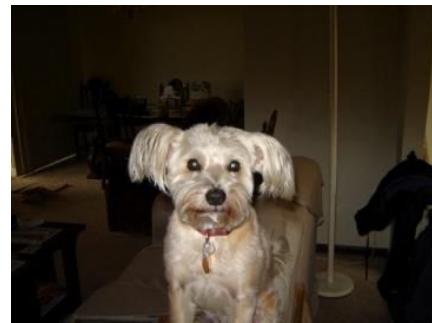


Convolutional layers

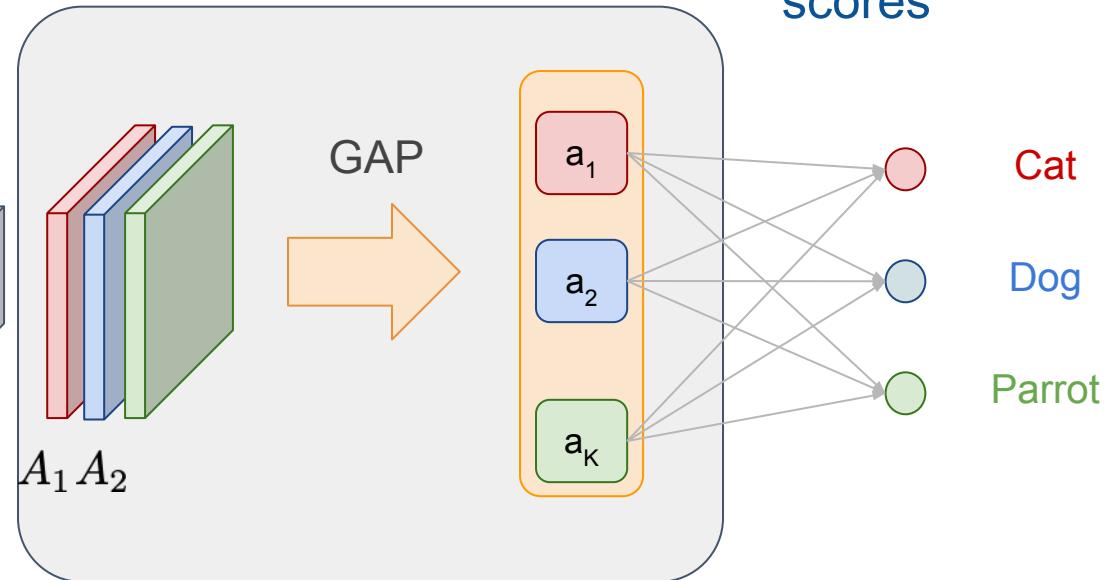


From global cues to pixel labels

Step 2: Modify the last layers



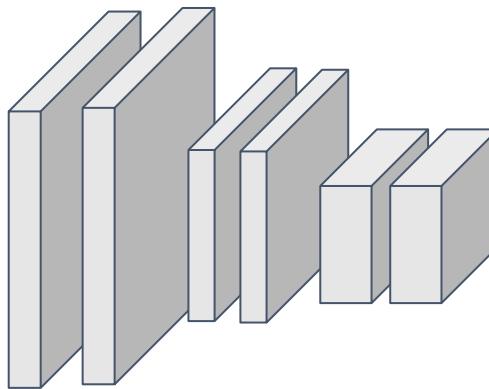
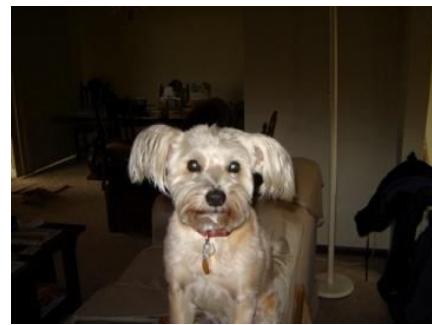
Convolutional layers



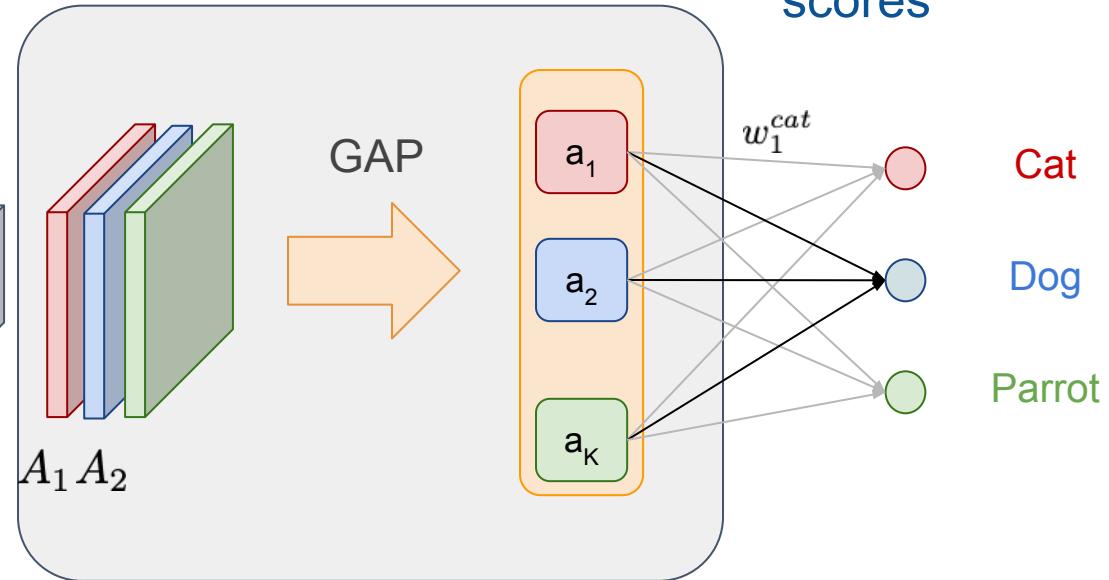
$$GAP(A_k) = a_k = \frac{1}{|N|} \sum_{x,y} A_k(x,y)$$

From global cues to pixel labels

Step 2: Modify the last layers



Convolutional layers



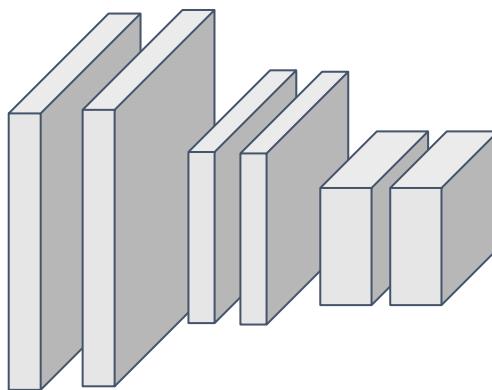
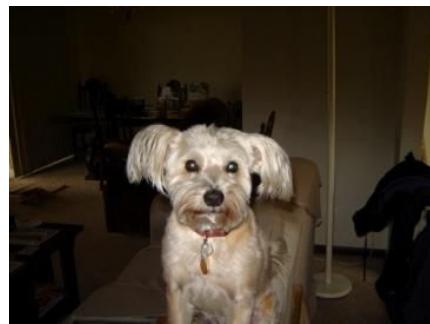
$$GAP(A_k) = a_k = \frac{1}{|N|} \sum_{x,y} A_k(x,y)$$

Class score
(logits)

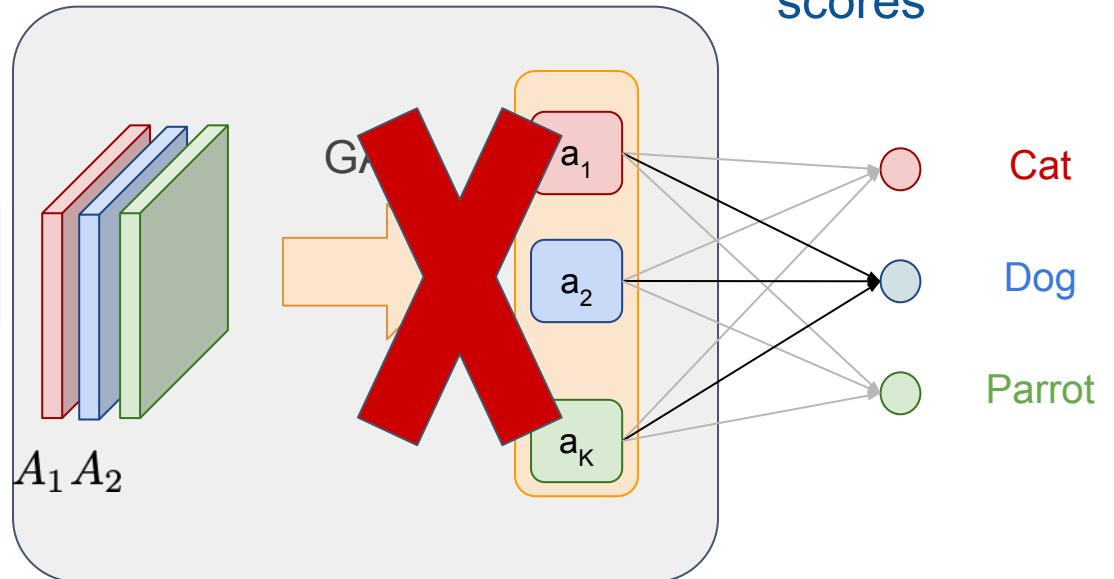
$$S_c = \sum_k w_k^c a_k = \frac{1}{N} \sum_k w_k^c \sum_{x,y} a_k(x,y)$$

From global cues to pixel labels

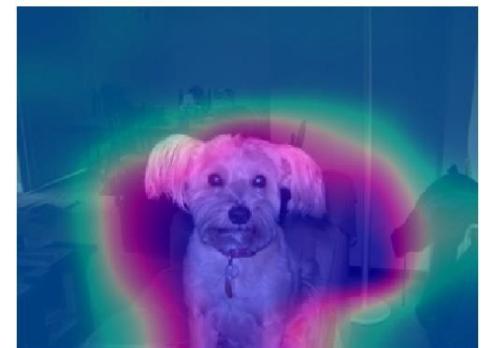
Step 3: Get the CAMs



Convolutional layers



$$CAM_{Dog}(x, y) = \sum_k w_k^{Dog} A_k(x, y) =$$



From global cues to pixel labels

Mushroom



Penguin



Teapot



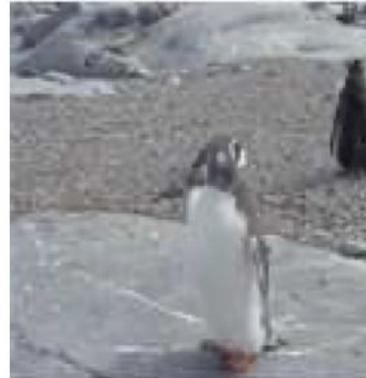
- Zhou et al., Learning deep features for discriminative localization. CVPR 2016

From global cues to pixel labels

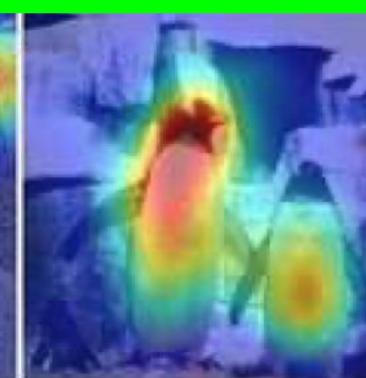
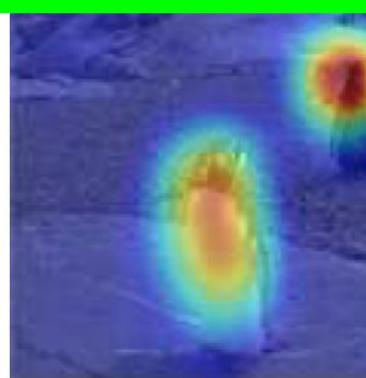
Mushroom



Penguin



Teapot



These activations maps can be used as **pseudo-masks**

- Zhou et al., Learning deep features for discriminative localization. CVPR 2016

From global cues to pixel labels

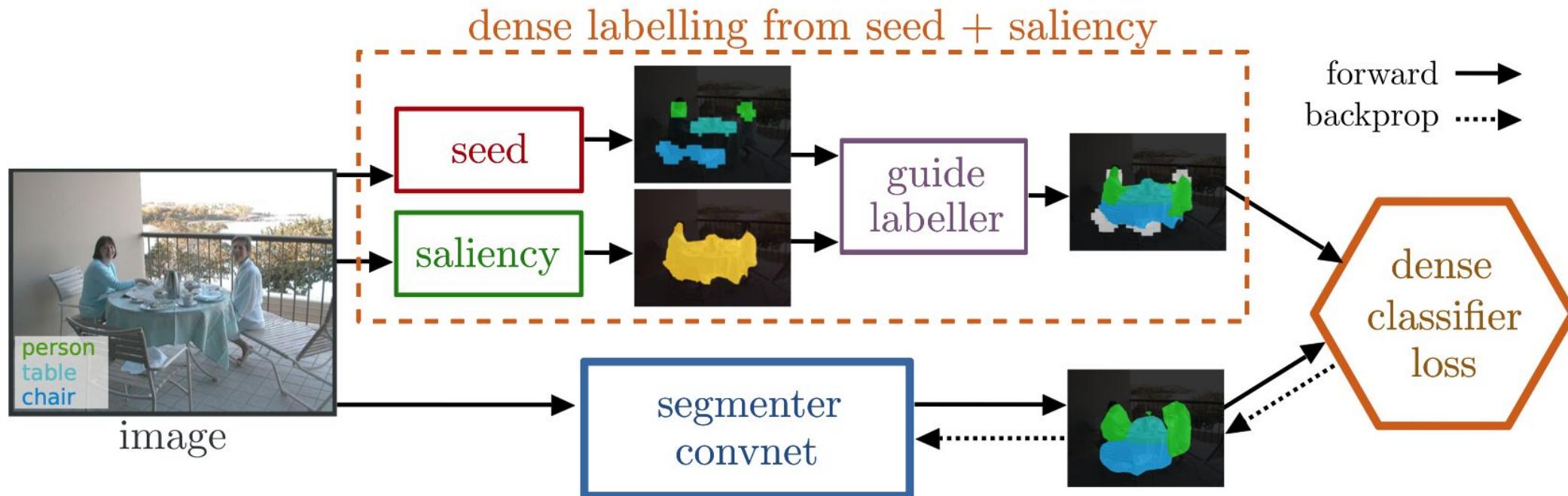
Problem: they focus only on highly discriminative regions



From global cues to pixel labels

Problem: they focus only on highly discriminative regions

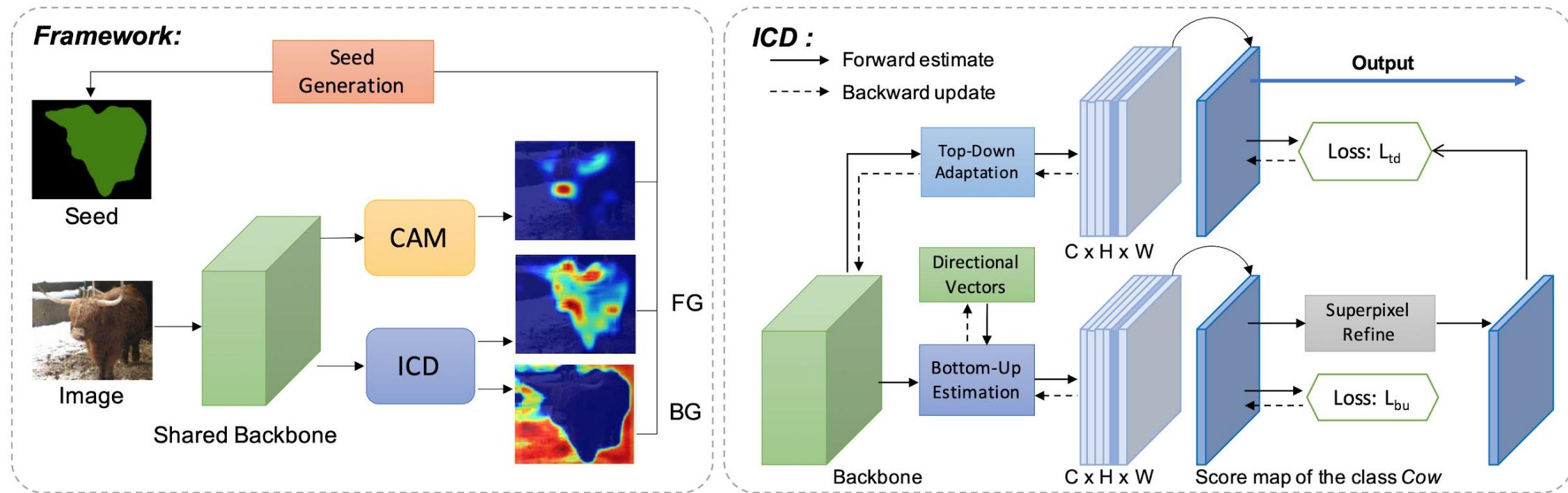
Incorporate saliency maps



From global cues to pixel labels

Problem: they focus only on highly discriminative regions

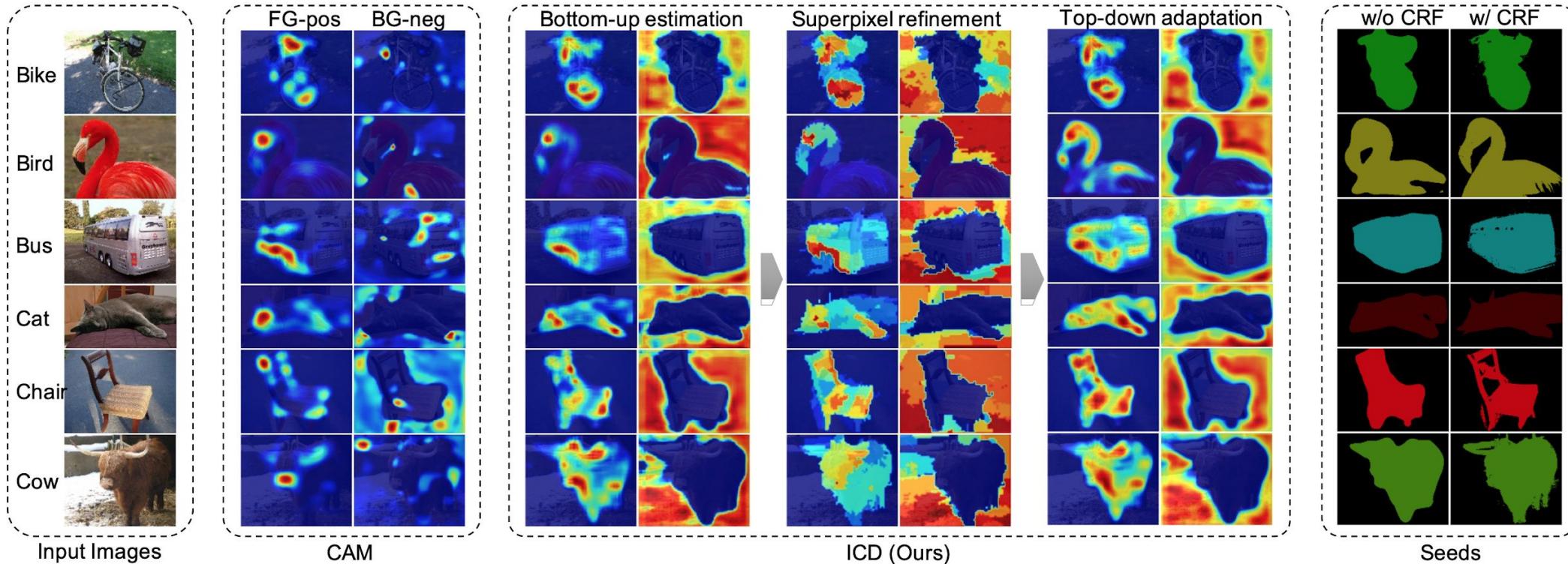
Incorporate saliency maps



From global cues to pixel labels

Problem: they focus only on highly discriminative regions

Incorporate saliency maps



From global cues to pixel labels

Problem: they focus only on highly discriminative regions

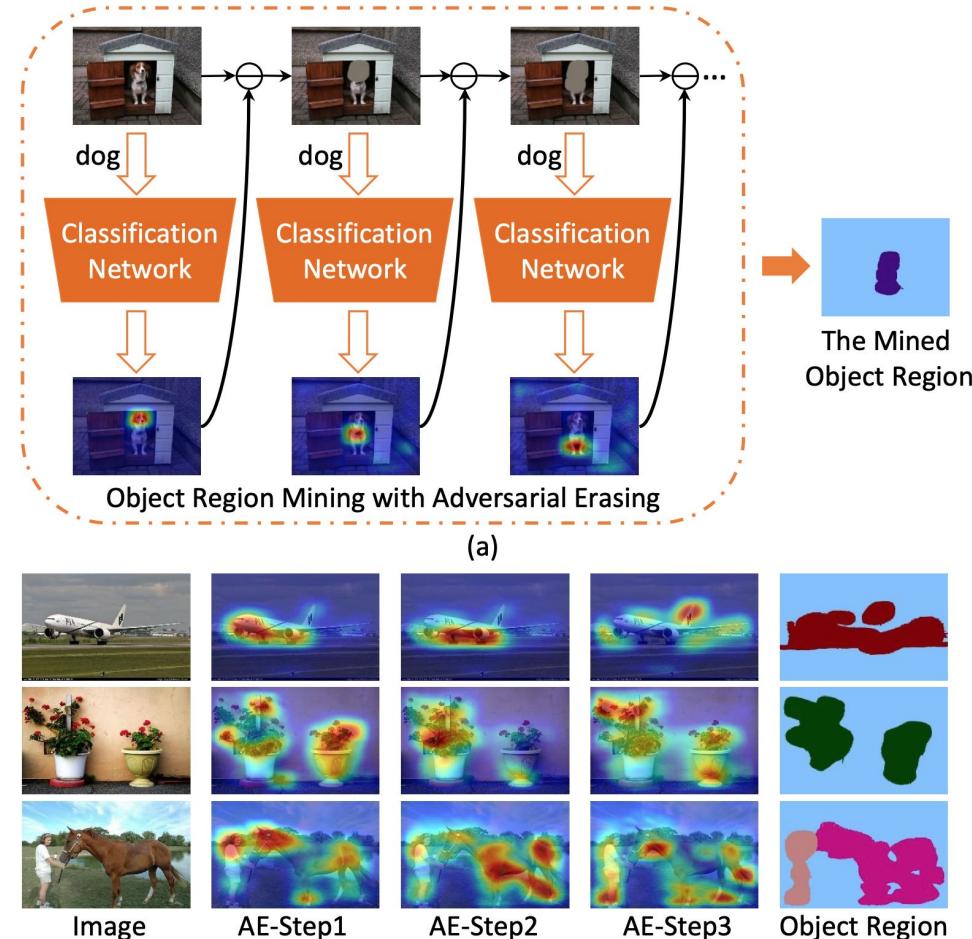
Incorporate saliency maps



From global cues to pixel labels

Problem: they focus only on highly discriminative regions

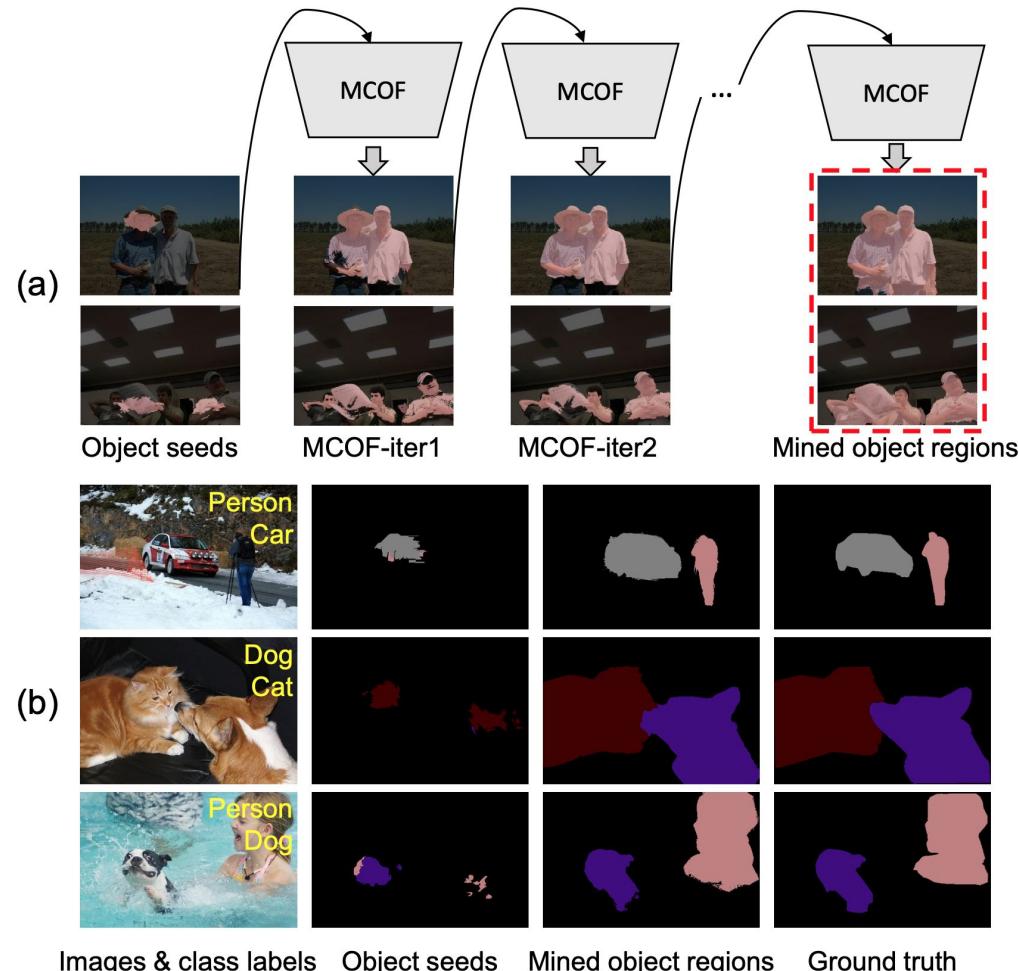
Region mining



From global cues to pixel labels

Problem: they focus only on highly discriminative regions

Region mining

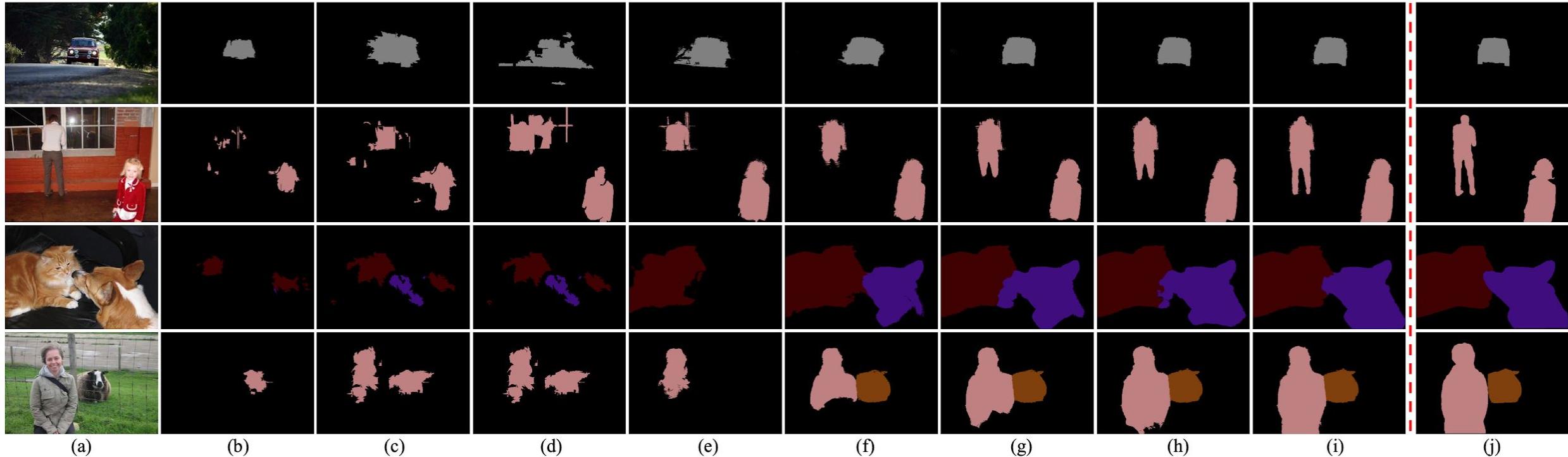


From global cues to pixel labels

Problem: they focus only on highly discriminative regions

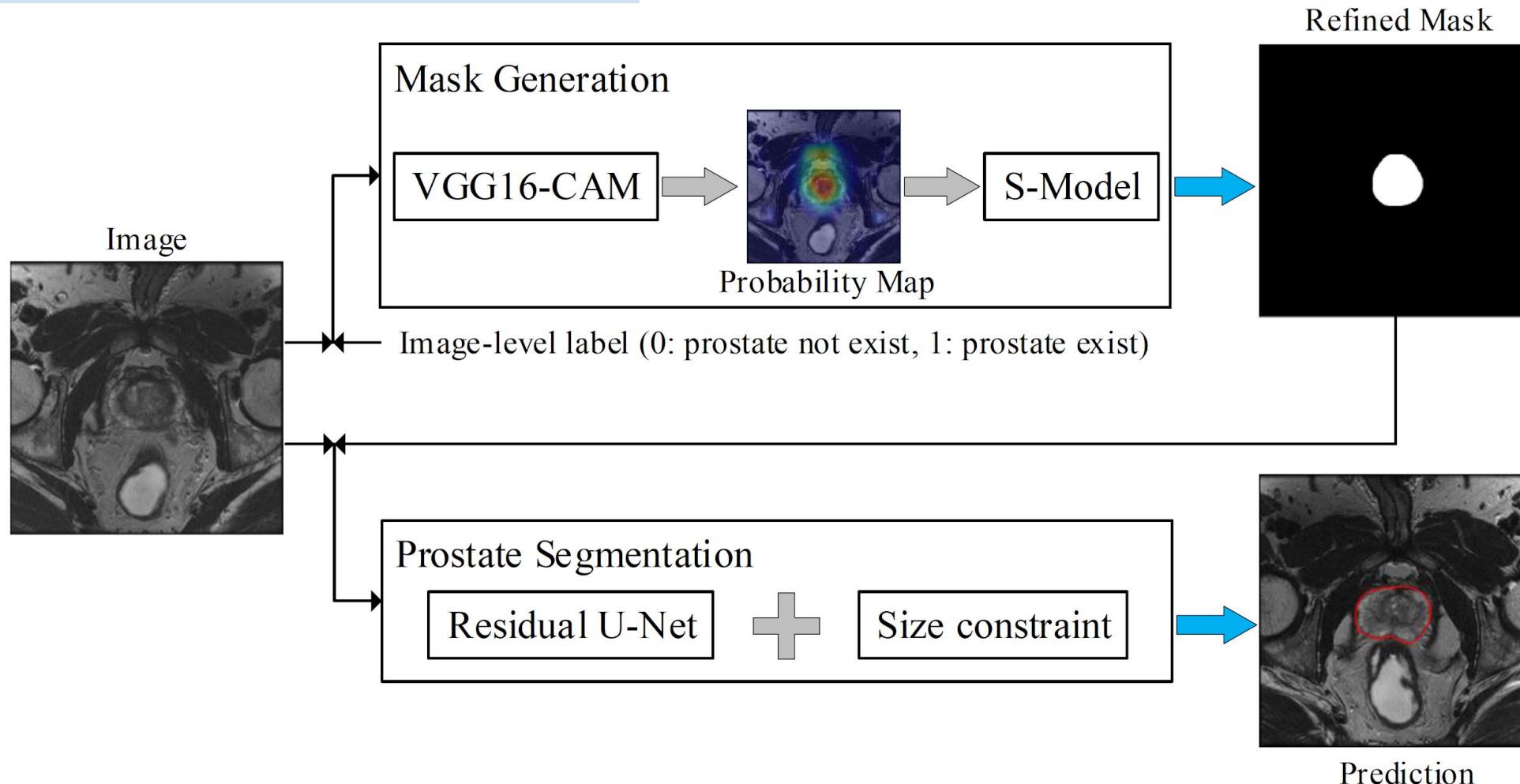
Region mining

Ground truth



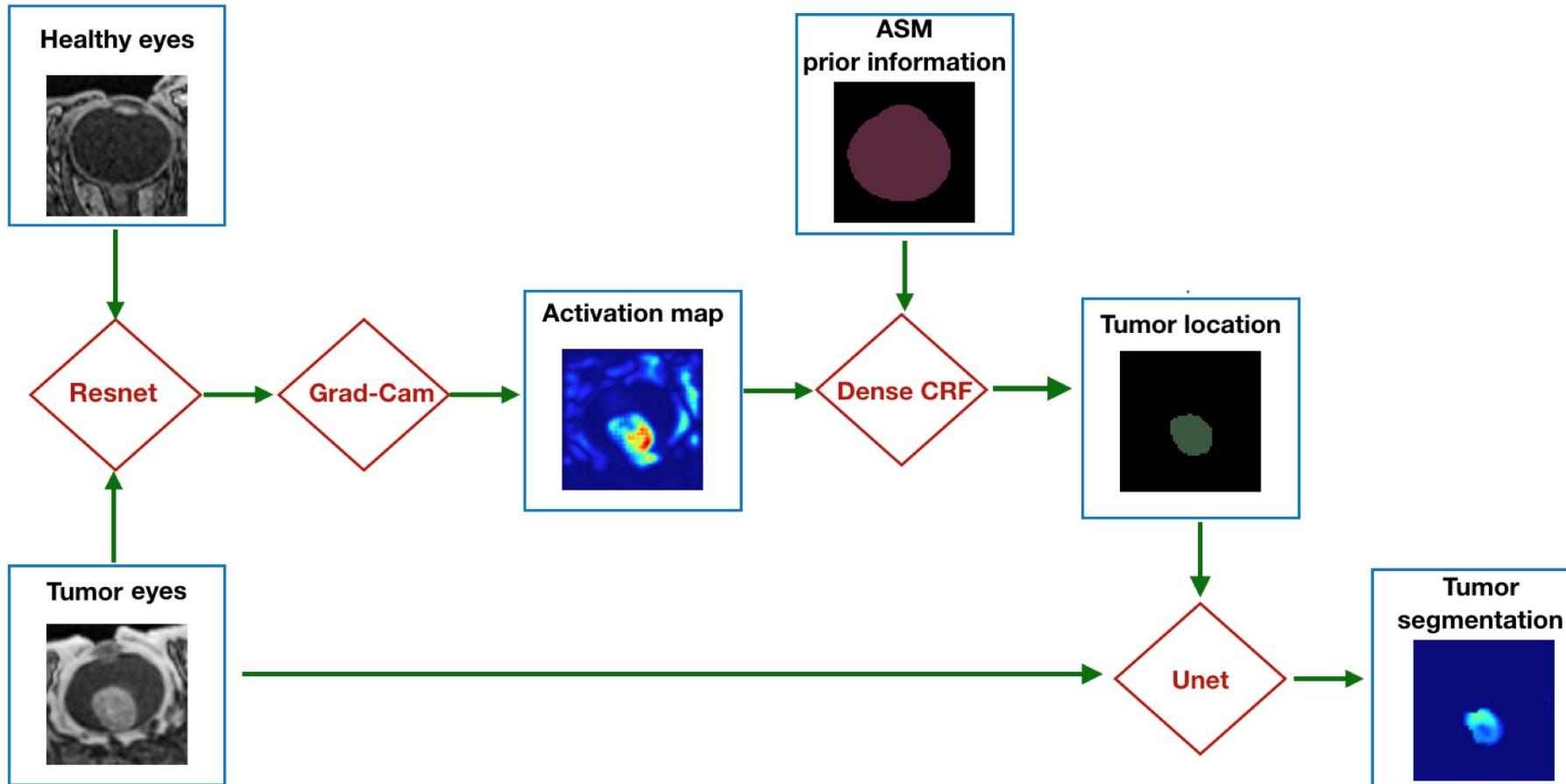
From global cues to pixel labels

CAMs in the medical domain



From global cues to pixel labels

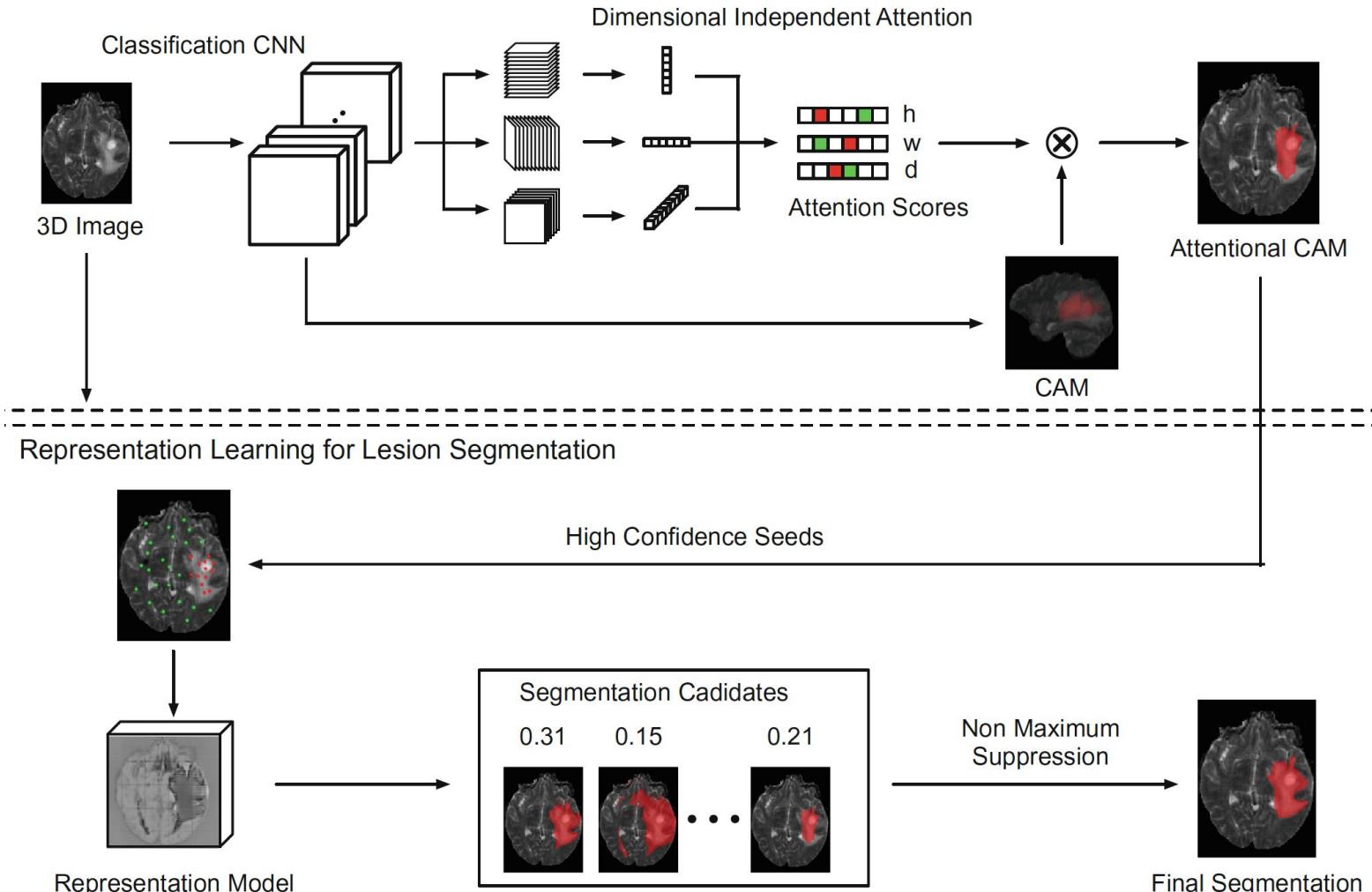
CAMs in the medical domain



From global cues to pixel labels

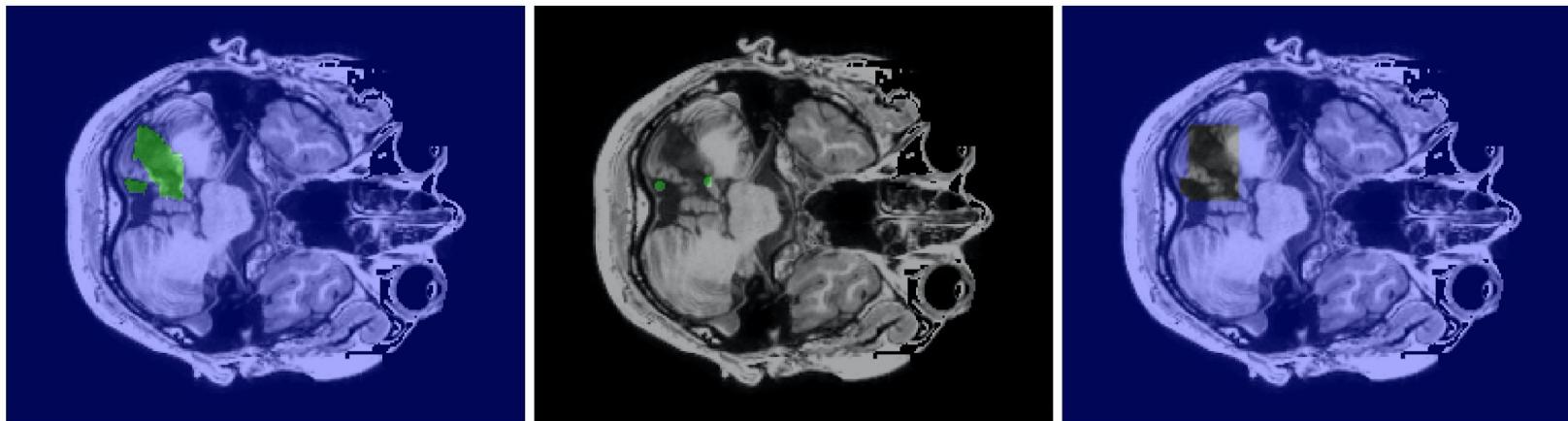
CAMs in the medical domain

Attentional CAM for Lesion Localization



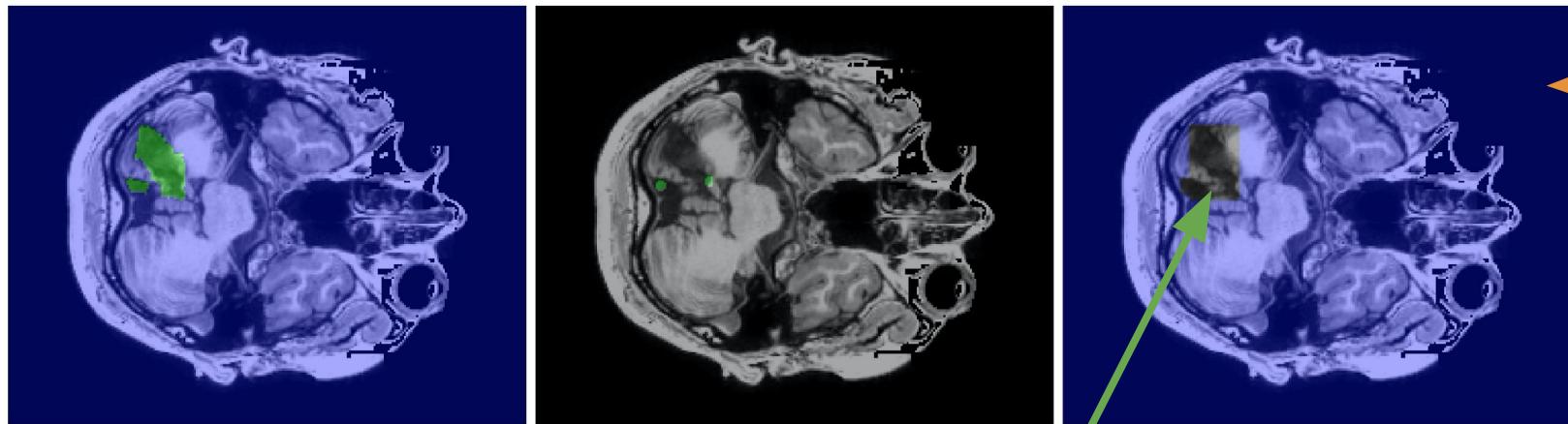
From global cues to pixel labels

Bounding boxes



From global cues to pixel labels

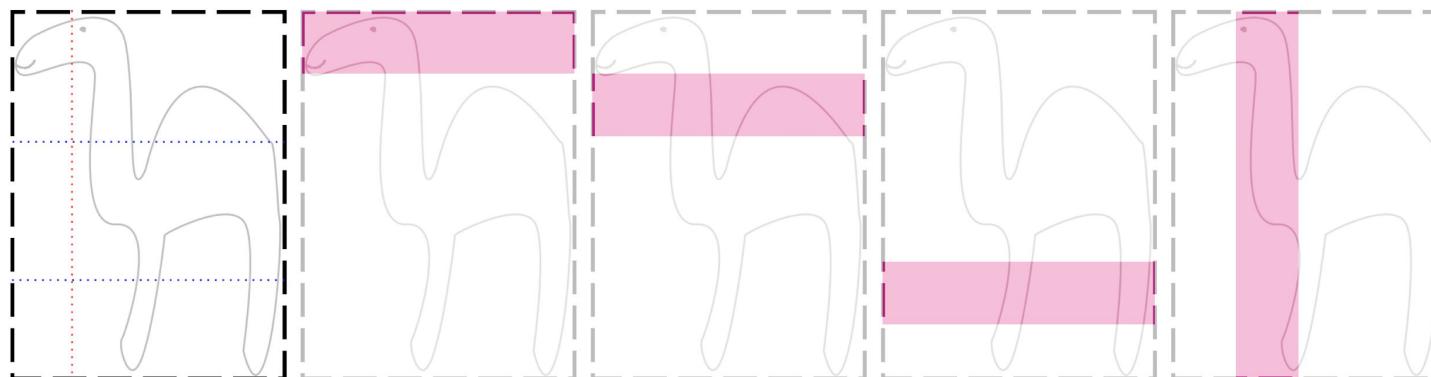
Bounding boxes



$$\sum_{p \in \Omega_O} s_{\theta}(p) \leq 0$$

Outside the bounding box
(Certainty)

Inside the bounding box
(Uncertainty)



Include a tightness prior term

$$\sum_{p \in s_l} y_p \geq w \quad \forall s_l \in \mathcal{S}_L$$