



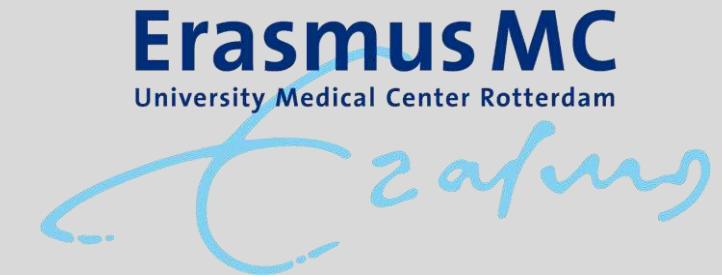
# MICCAI2022

Singapore

25<sup>th</sup> International Conference on  
Medical Image Computing and  
Computer Assisted Intervention

September 18-22, 2022

Resorts World Convention Centre Singapore

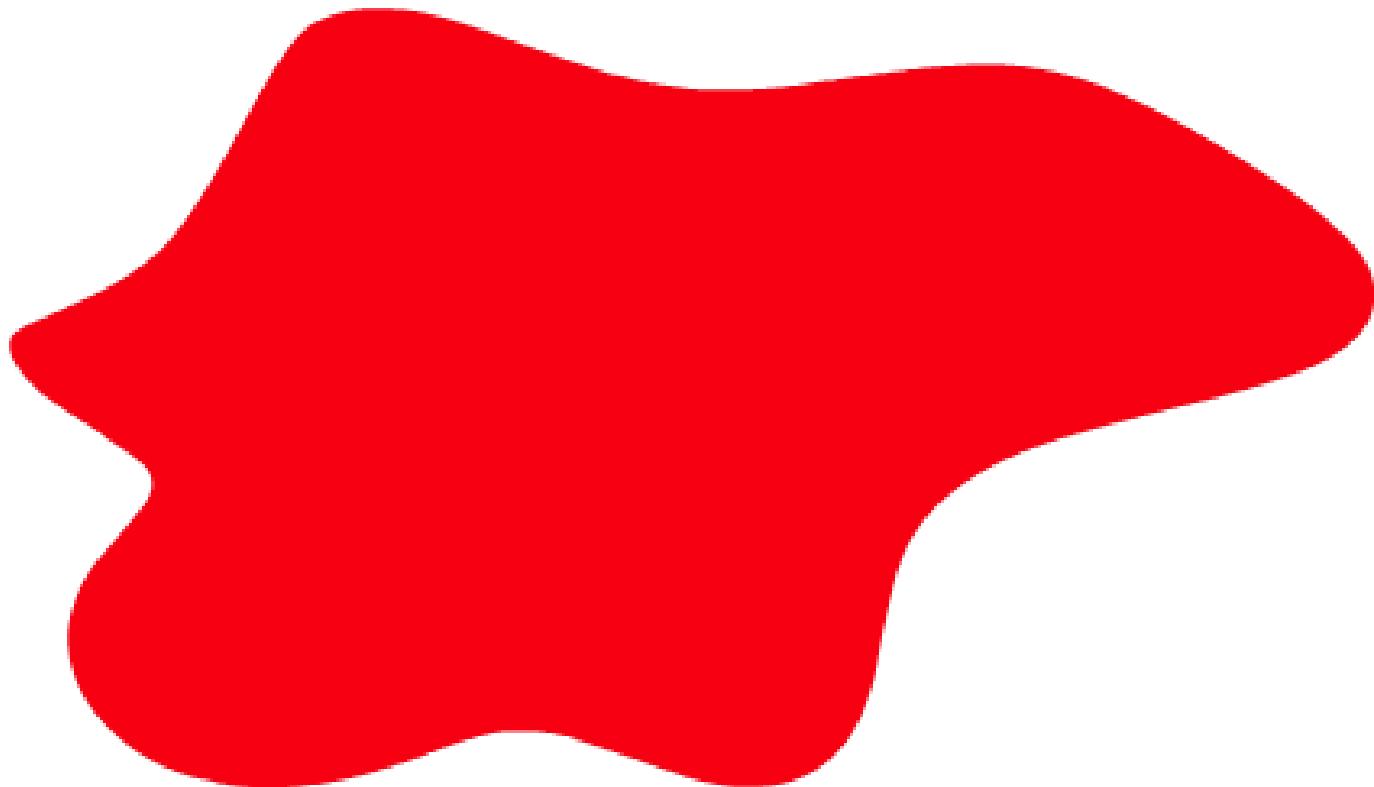


UC SANTA CRUZ

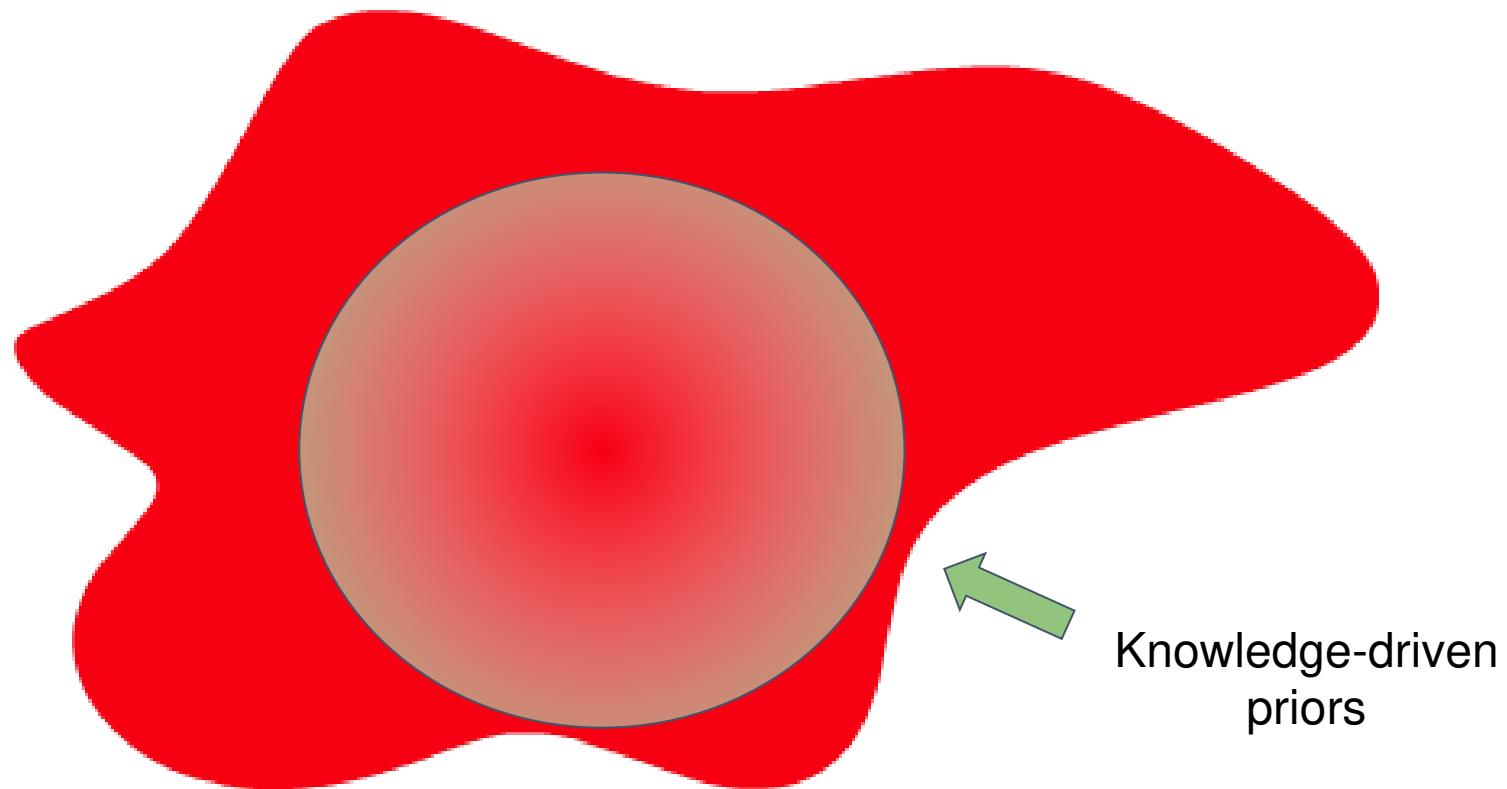
Learning with Limited Supervision  
- *Constrained CNNs* -

Yuyin Zhou (Yan Wang)  
Ismail Ben Ayed  
**Jose Dolz**  
Christian Desrosiers  
Marleen de Bruijne  
Hoel Kervadec

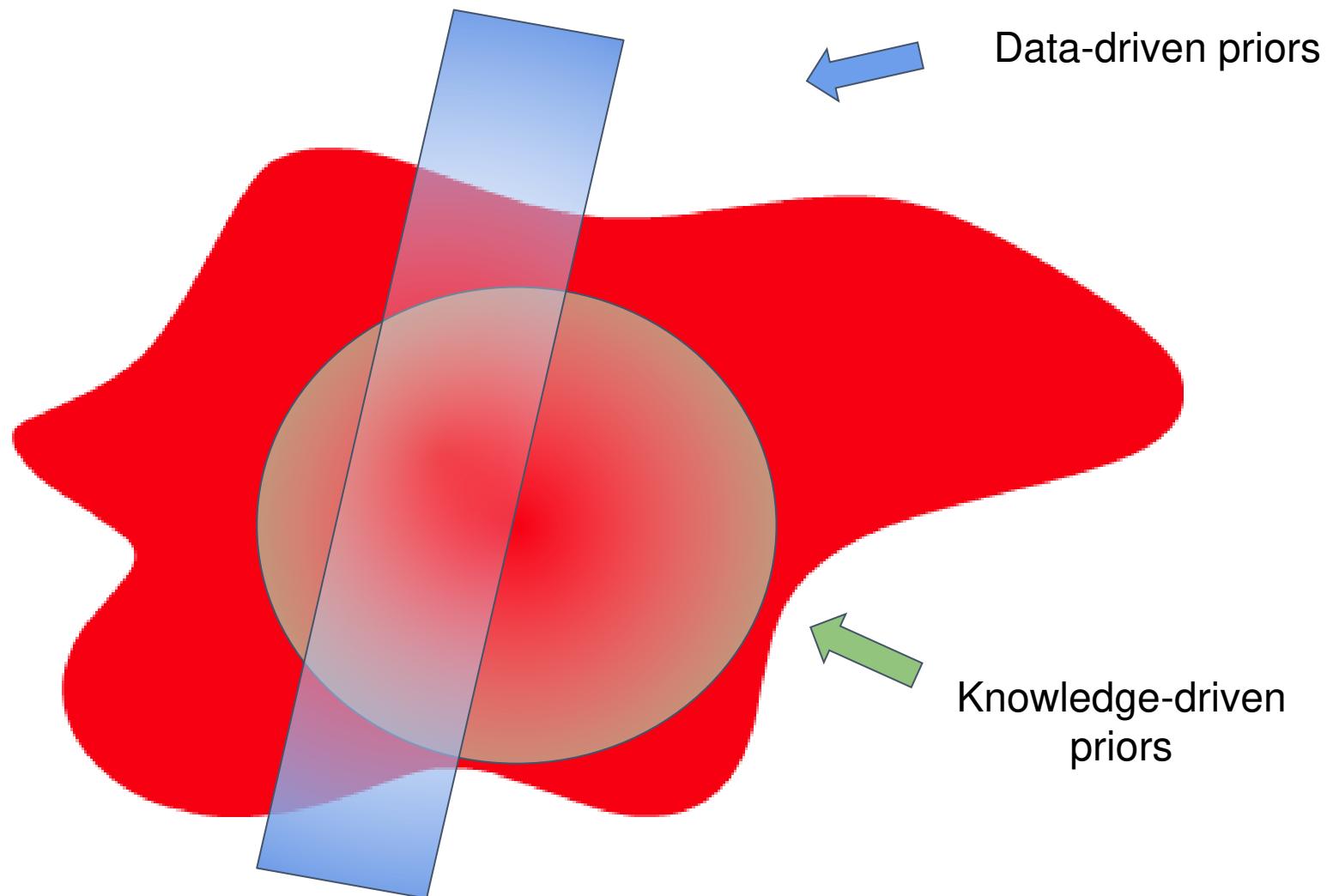
# Knowledge vs data driven priors



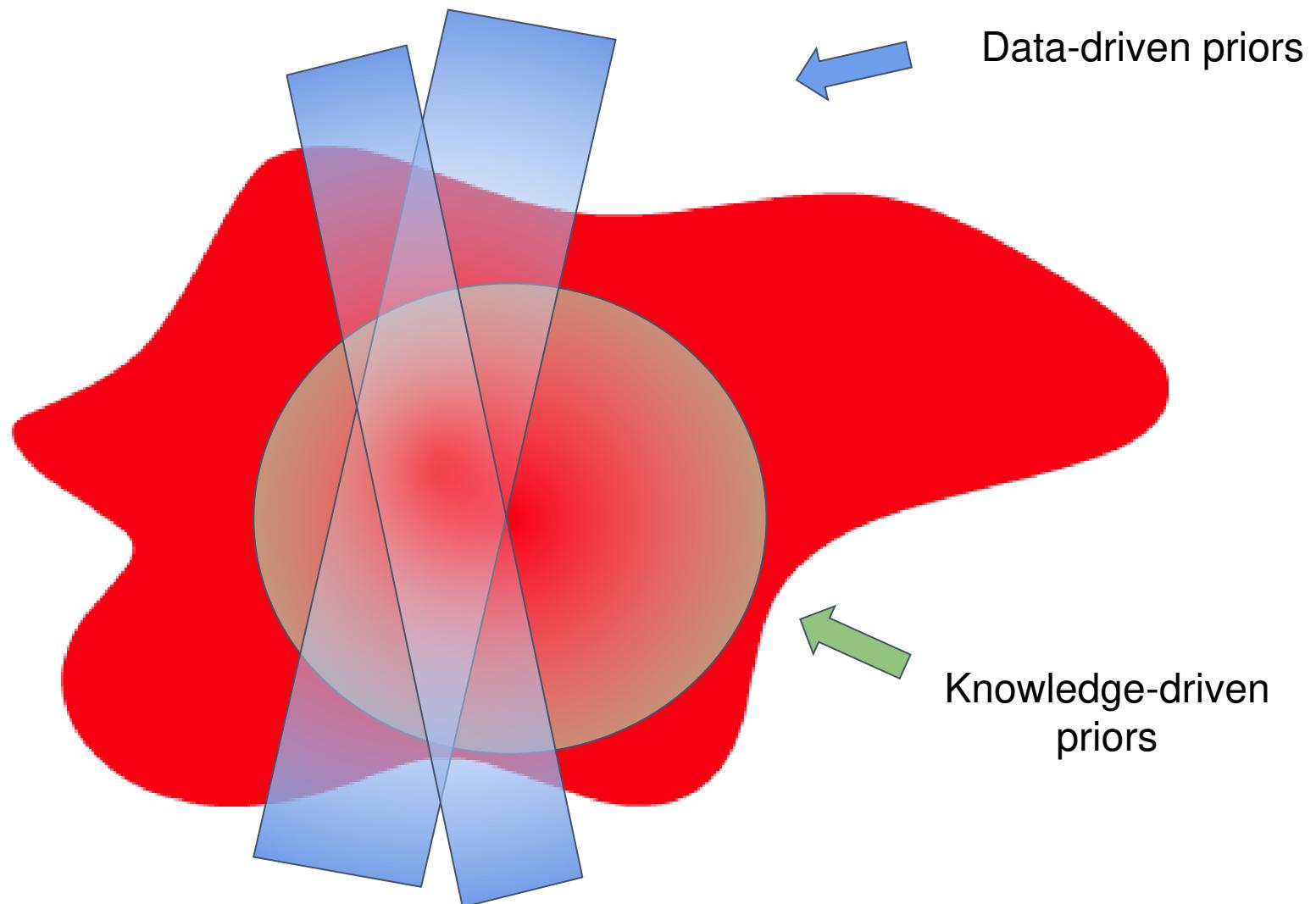
# Knowledge vs data driven priors



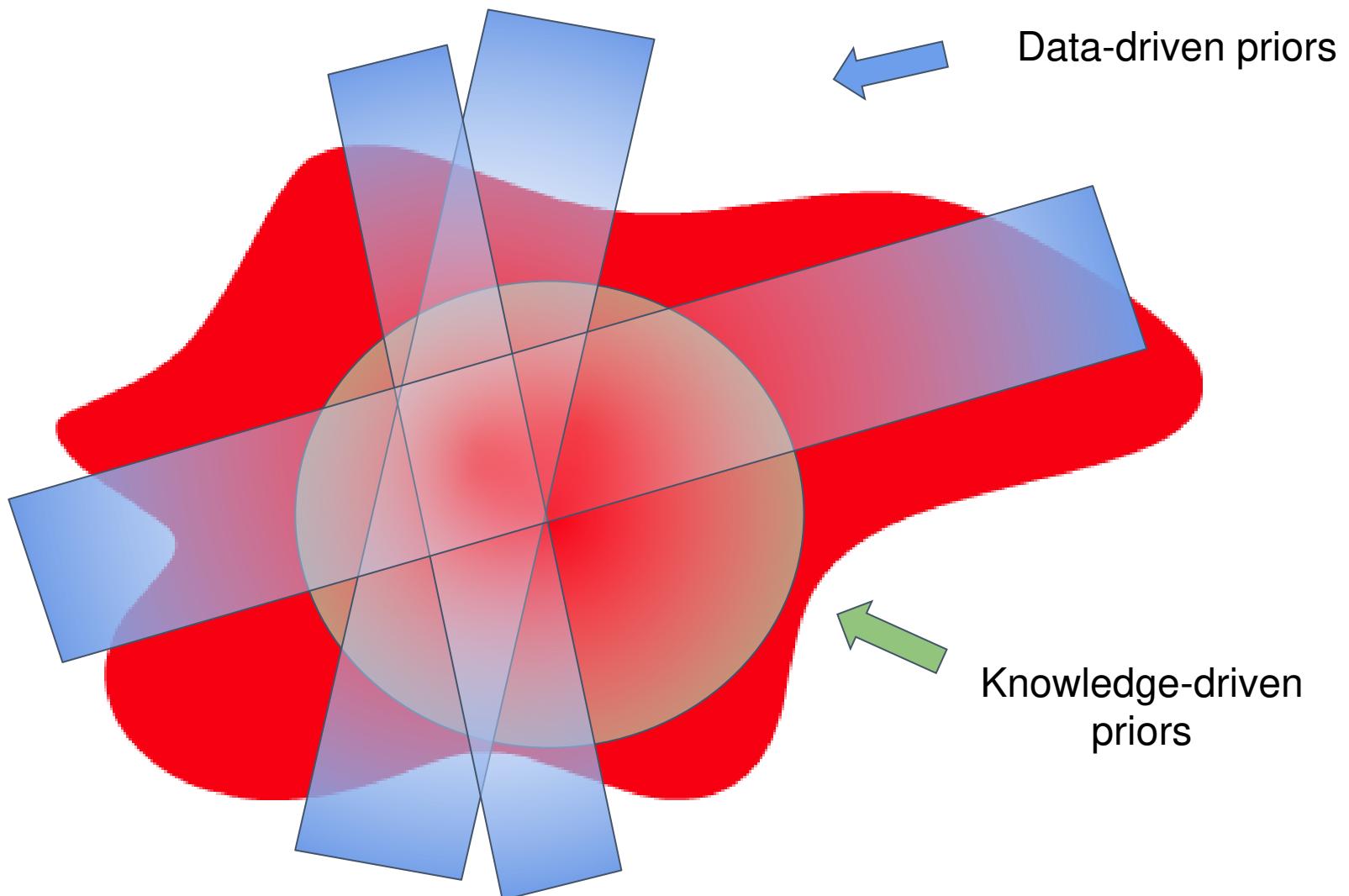
# Knowledge vs data driven priors



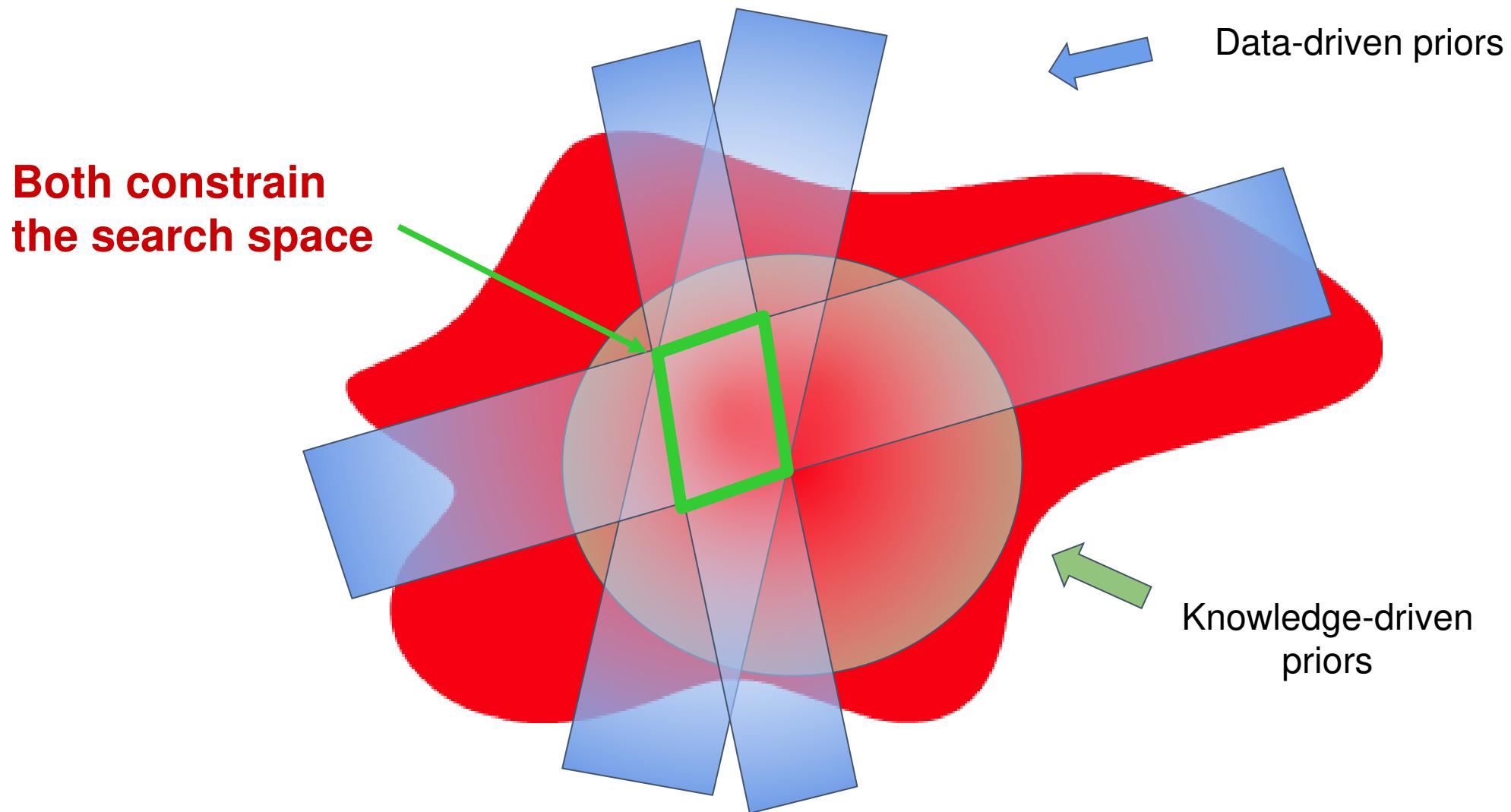
# Knowledge vs data driven priors



# Knowledge vs data driven priors



# Knowledge vs data driven priors

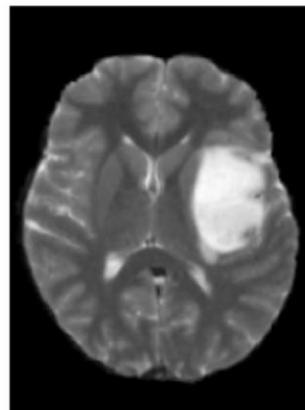


# Data-driven priors (cues)

## Image tags



Person  
Bike



Tumor

Original  
Image

Image tags

- Pathak et al., Constrained convolutional neural networks for weakly supervised segmentation, ICCV 2015
- Kervadec et al., Constrained-CNN losses for weakly supervised segmentation, Media 2019.

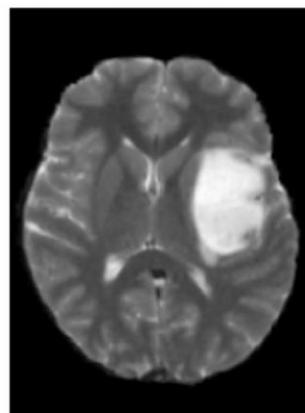
# Data-driven priors (cues)

Image tags

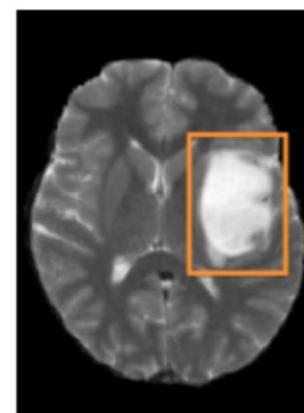
Bounding boxes



Person  
Bike



Tumor



Original  
Image

Image tags

Bounding  
boxes

- Pathak et al., Constrained convolutional neural networks for weakly supervised segmentation, ICCV 2015
- Kervadec et al., Constrained-CNN losses for weakly supervised segmentation, Media 2019.

# Data-driven priors (cues)

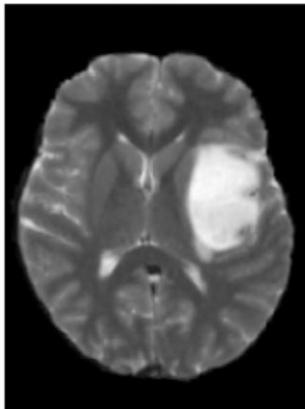
Image tags

Bounding boxes

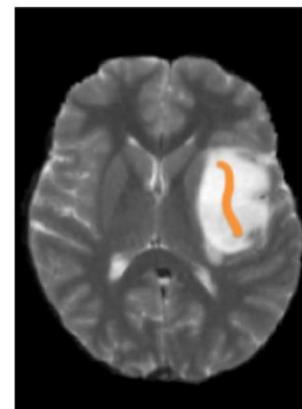
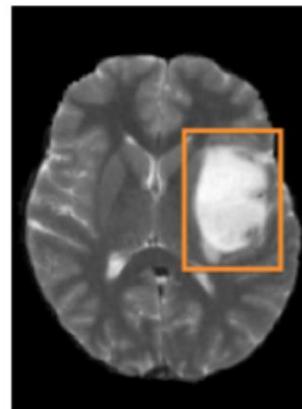
Scribbles



Person  
Bike



Tumor



Original  
Image

Image tags

Bounding  
boxes

Scribbles

- Pathak et al., Constrained convolutional neural networks for weakly supervised segmentation, ICCV 2015
- Kervadec et al., Constrained-CNN losses for weakly supervised segmentation, Media 2019.

# Data-driven priors (cues)

Image tags

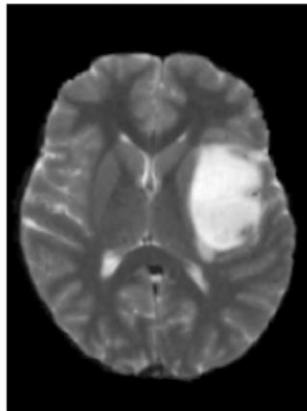
Bounding boxes

Scribbles

Points



Person  
Bike

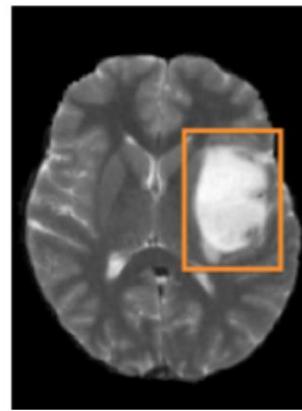


Tumor

Original  
Image



Image tags



Bounding  
boxes



Scribbles



Points

- Pathak et al., Constrained convolutional neural networks for weakly supervised segmentation, ICCV 2015
- Kervadec et al., Constrained-CNN losses for weakly supervised segmentation, Media 2019.

# Data-driven priors (cues)

Another data-driven priors

Image captions



A boy jumping on a skateboard

Extreme points

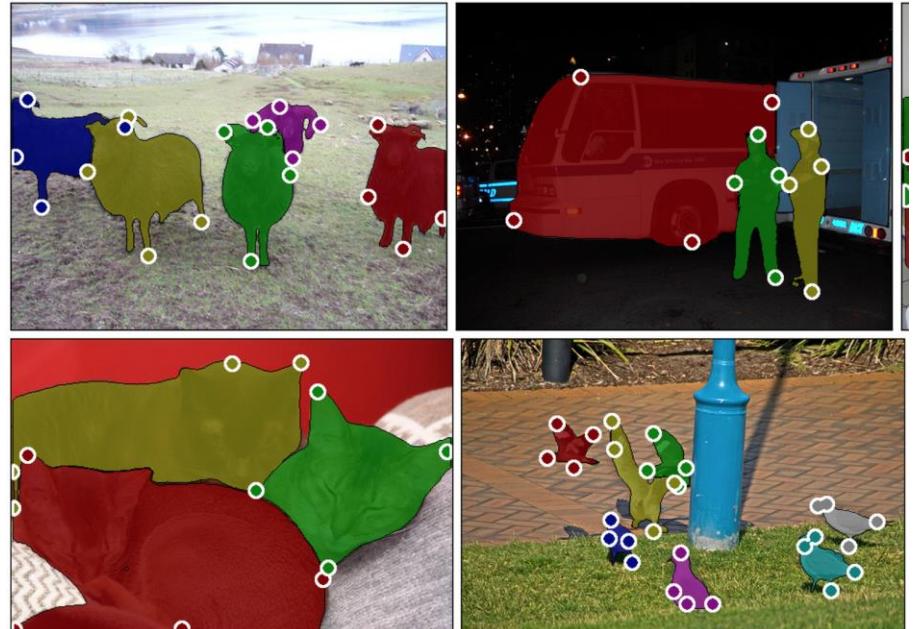


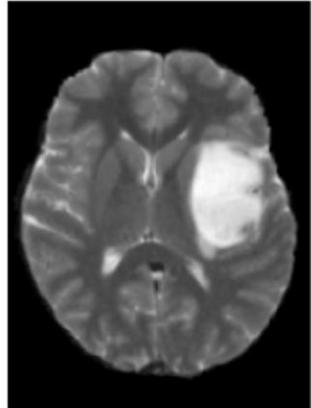
Image from Maninis et al, CVPR'18

- Maninis et al. Deep extreme cut: From extreme points to object segmentation. CVPR 2018

# From global cues to pixel labels



Person  
Bike



Tumor

Original Image

Image tags



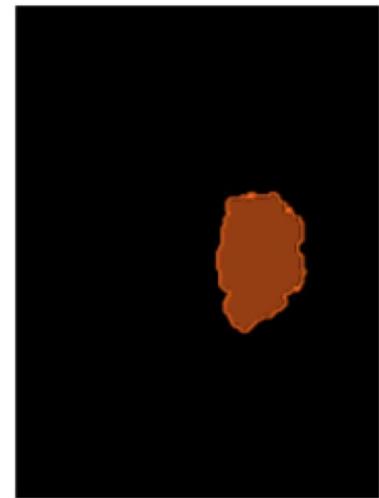
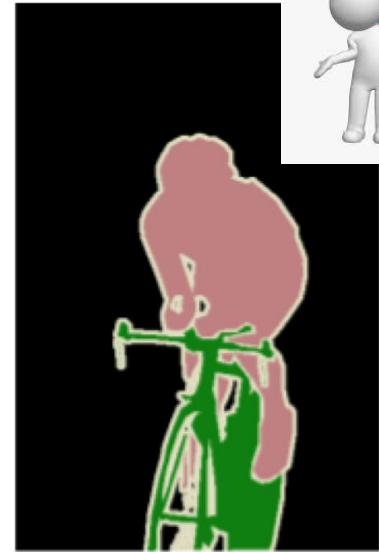
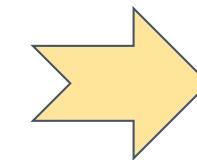
Bounding boxes



Scribbles

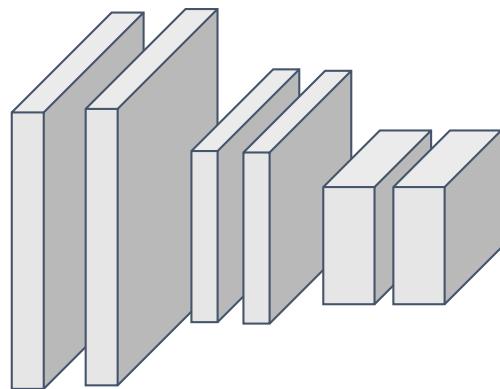
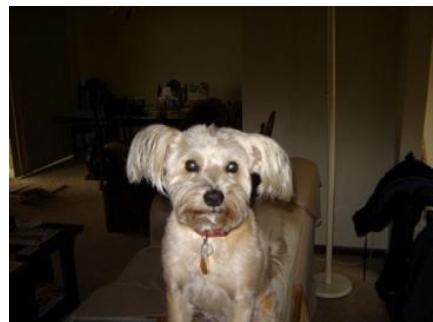


Points



# From global cues to pixel labels

## Step 1: Get a classification CNN



Convolutional layers



FC Layers

Class scores

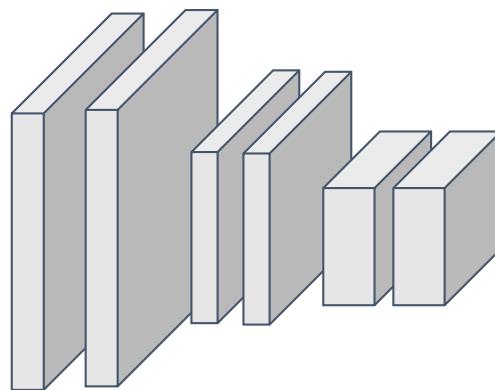
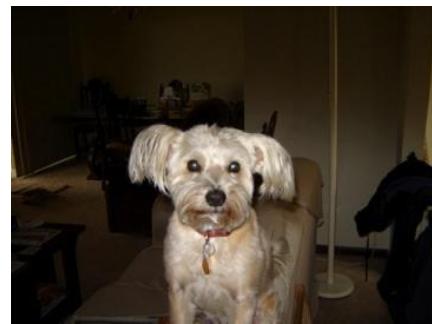
Cat

Dog

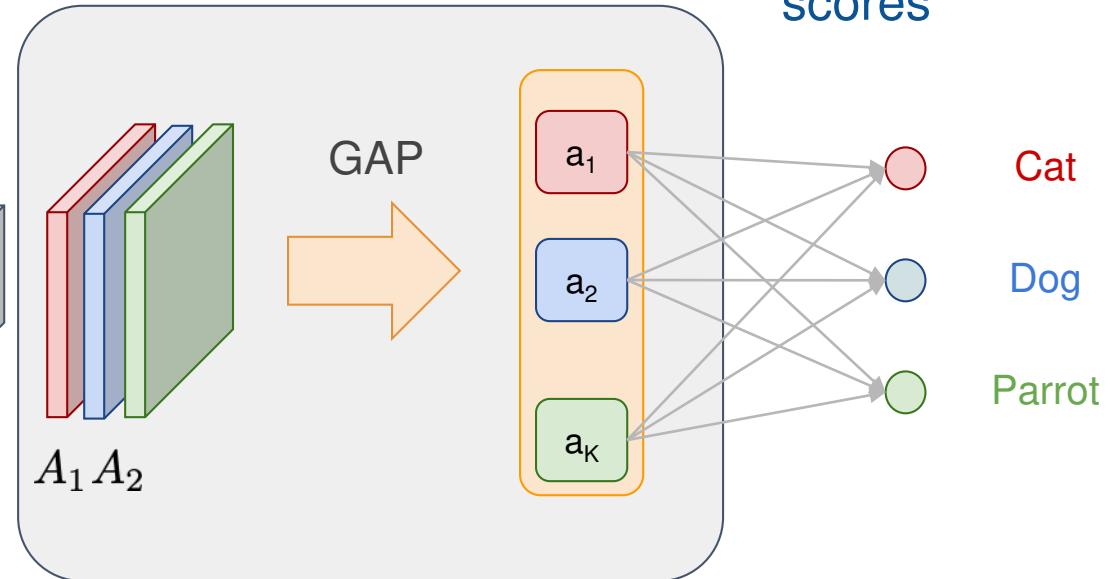
Parrot

# From global cues to pixel labels

## Step 2: Modify the last layers



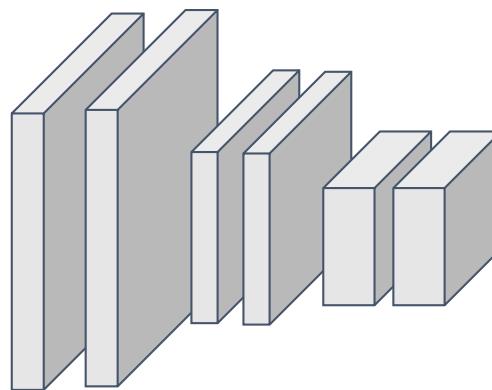
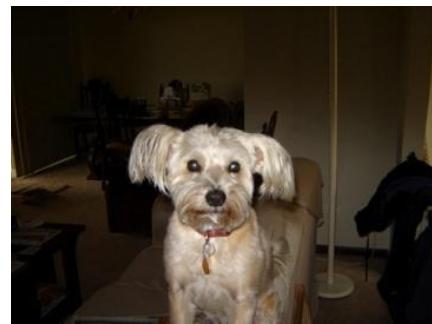
Convolutional layers



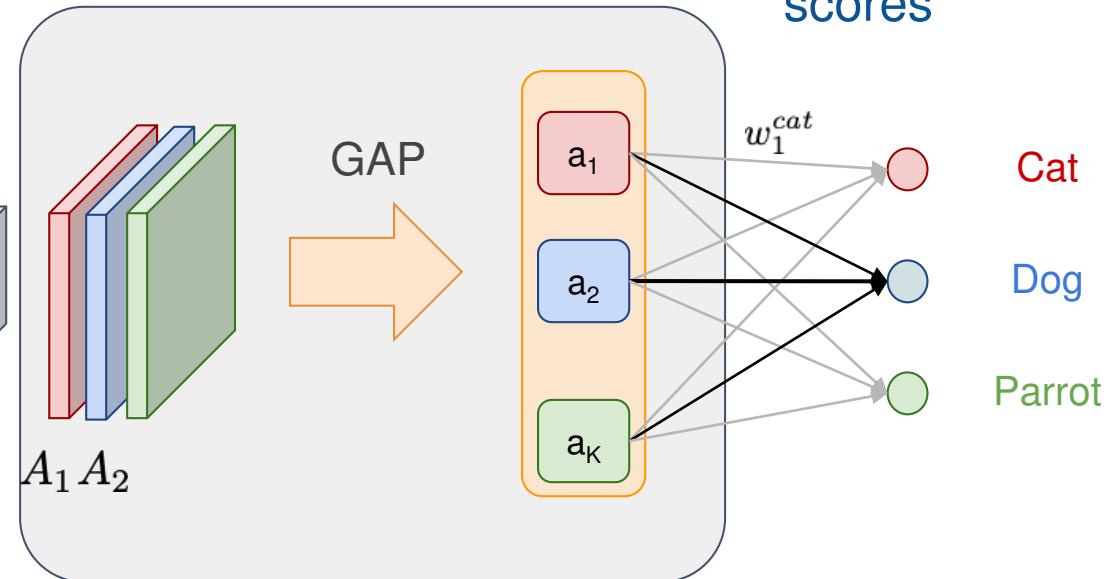
$$GAP(A_k) = a_k = \frac{1}{|N|} \sum_{x,y} A_k(x,y)$$

# From global cues to pixel labels

## Step 2: Modify the last layers



Convolutional layers



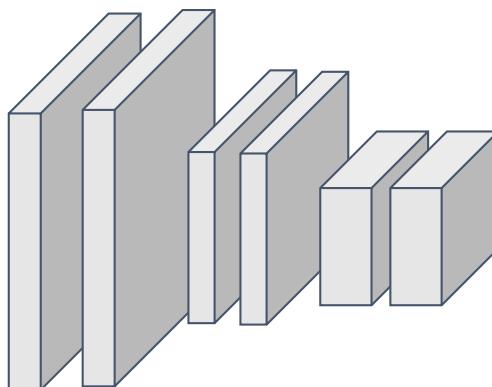
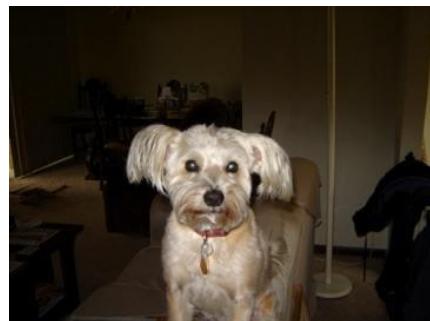
$$GAP(A_k) = a_k = \frac{1}{|N|} \sum_{x,y} A_k(x,y)$$

Class score  
(logits)

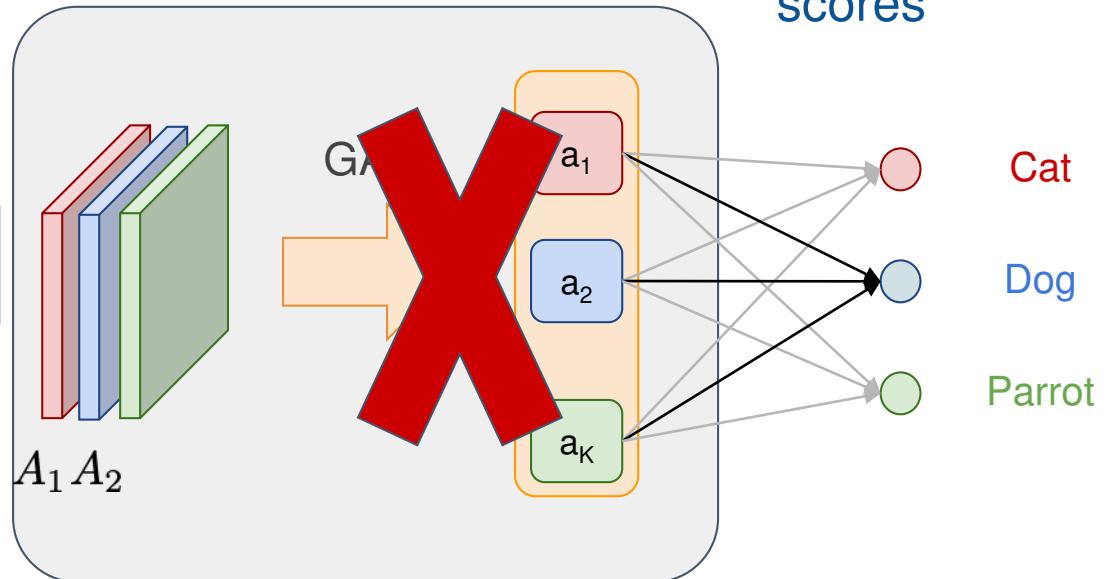
$$S_c = \sum_k w_k^c a_k = \frac{1}{N} \sum_k w_k^c \sum_{x,y} a_k(x,y)$$

# From global cues to pixel labels

## Step 3: Get the CAMs



Convolutional layers



$$CAM_{Dog}(x, y) = \sum_k w_k^{Dog} A_k(x, y) =$$

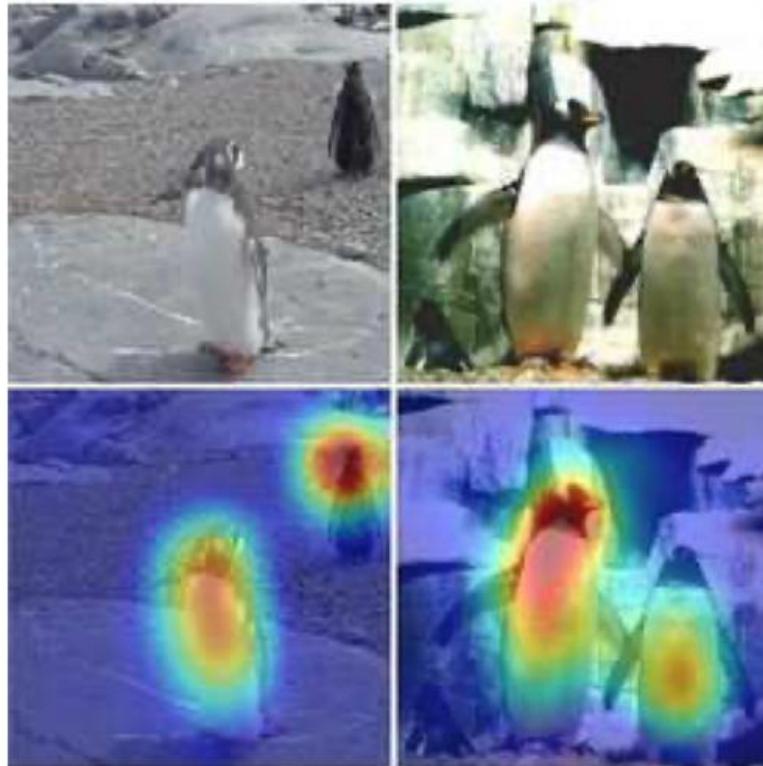


# From global cues to pixel labels

Mushroom



Penguin



Teapot

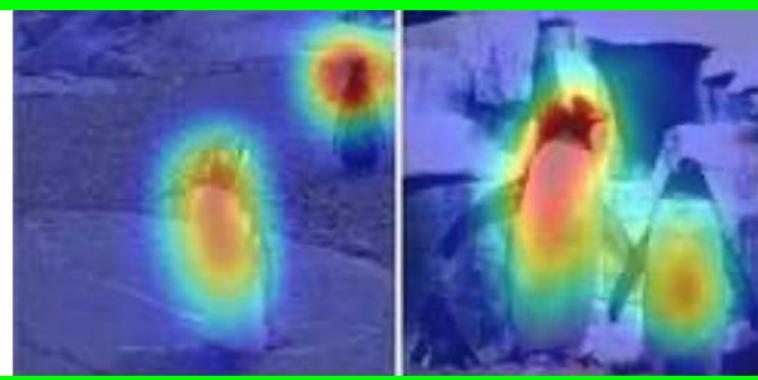


# From global cues to pixel labels

Mushroom



Penguin



Teapot



These activations maps can be used as **pseudo-masks**

- Zhou et al., Learning deep features for discriminative localization. CVPR 2016

# From global cues to pixel labels

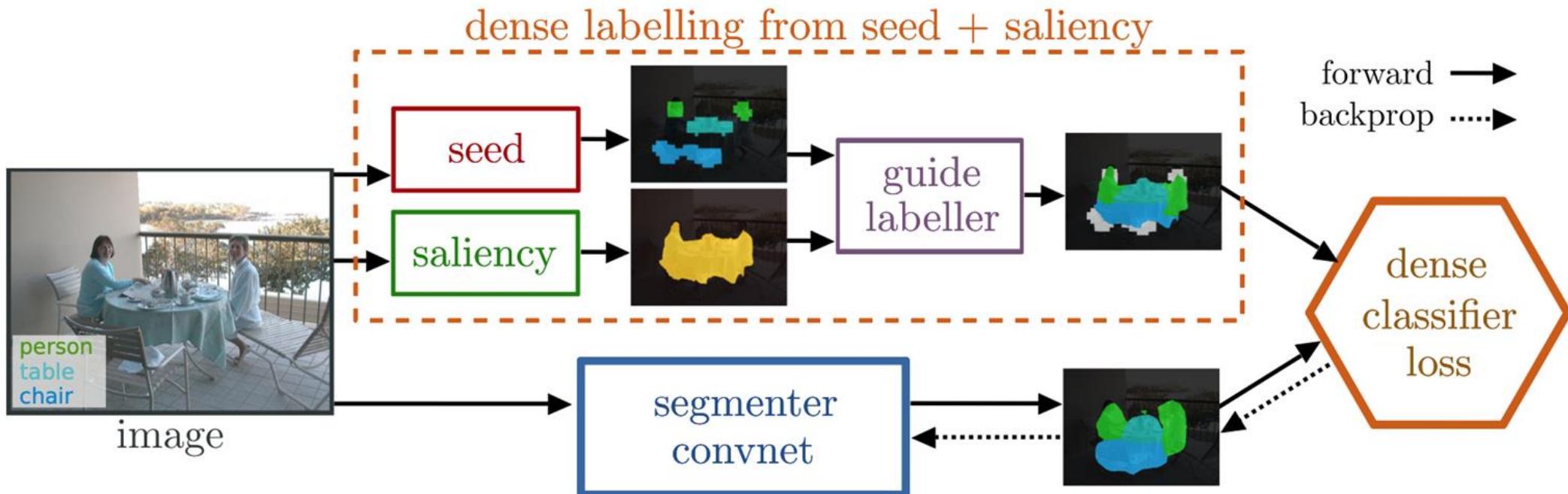
Problem: they focus only on highly discriminative regions



# From global cues to pixel labels

Problem: they focus only on highly discriminative regions

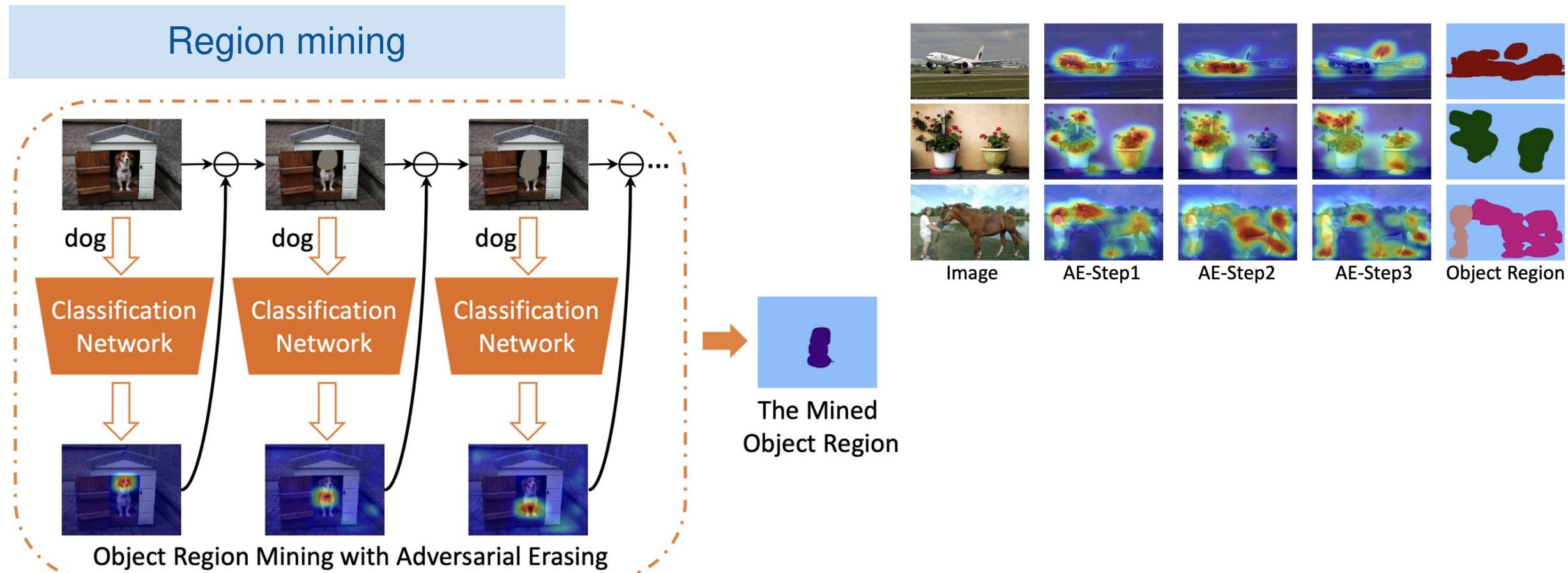
## Incorporate saliency maps



- Oh et al. Exploiting Saliency for Object Segmentation from Image Level Labels. CVPR 2017
- Fan et al. Learning Integral Objects With Intra-Class Discriminator for Weakly-Supervised Semantic Segmentation. CVPR 2020

# From global cues to pixel labels

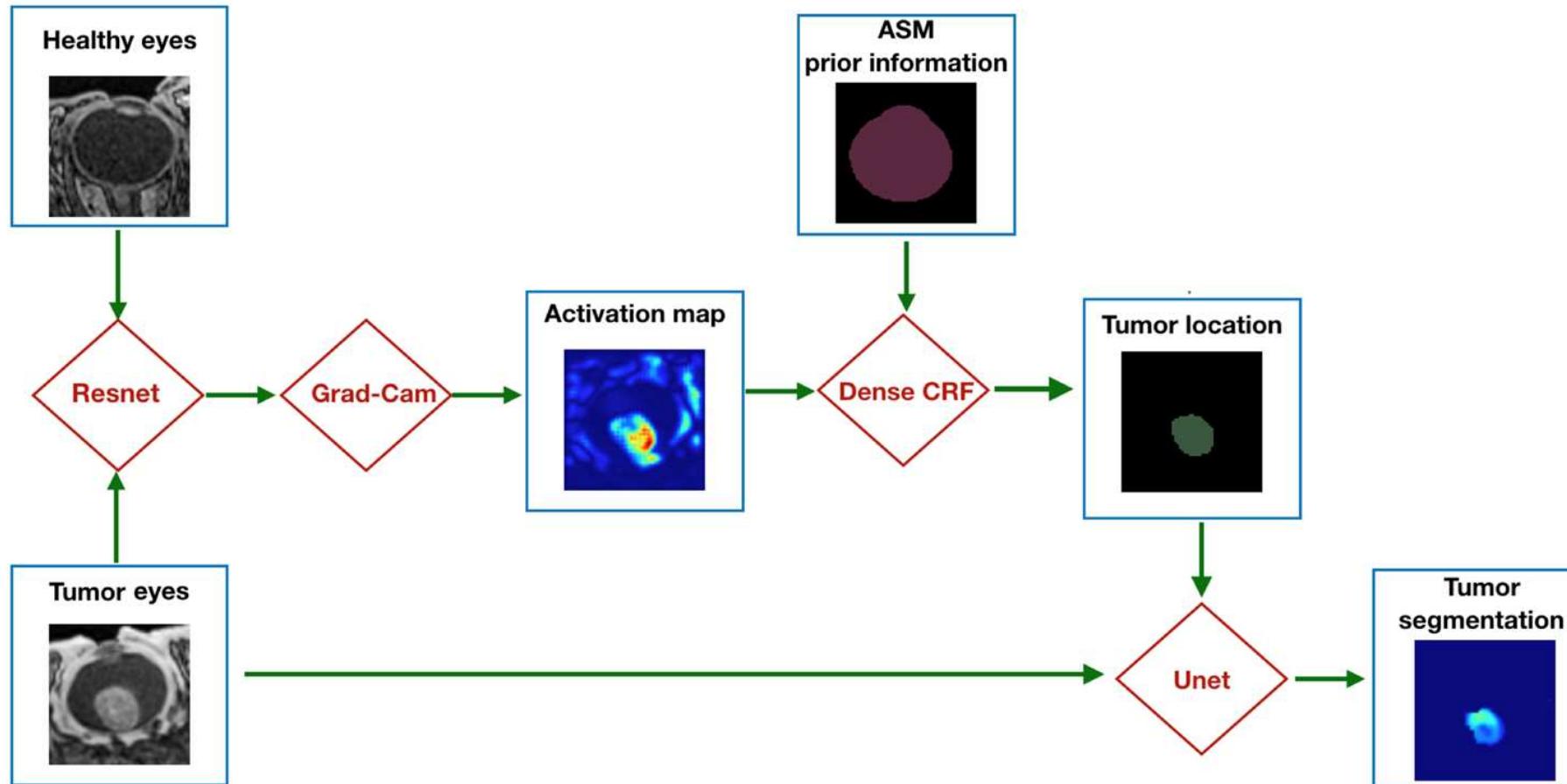
Problem: they focus only on highly discriminative regions



- Wei et al. Object Region Mining with Adversarial Erasing: A Simple Classification to Semantic Segmentation Approach. CVPR 2017
- Wang et al. Weakly-Supervised Semantic Segmentation by Iteratively Mining Common Object Features. CVPR 2018

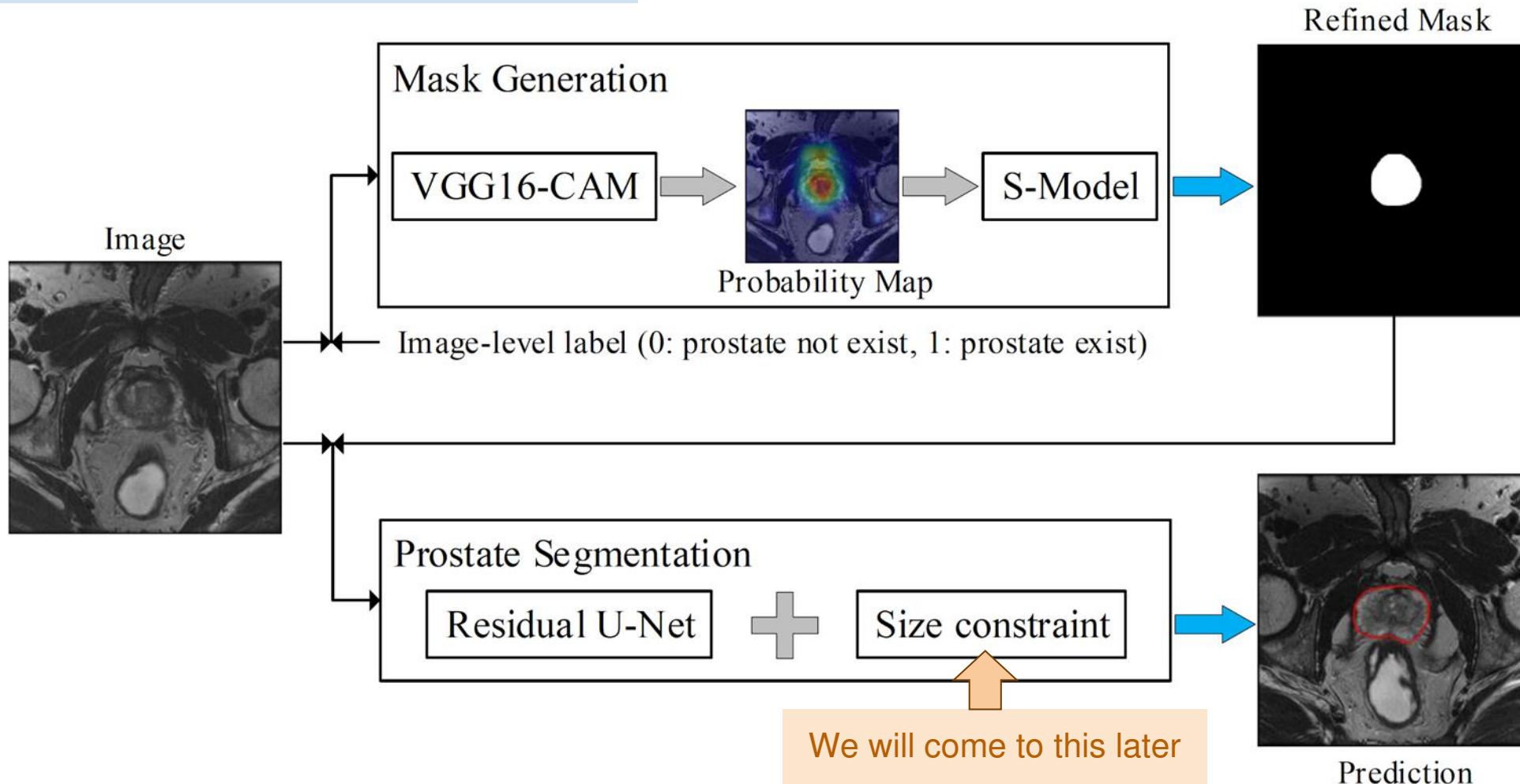
# From global cues to pixel labels

## CAMs in the medical domain



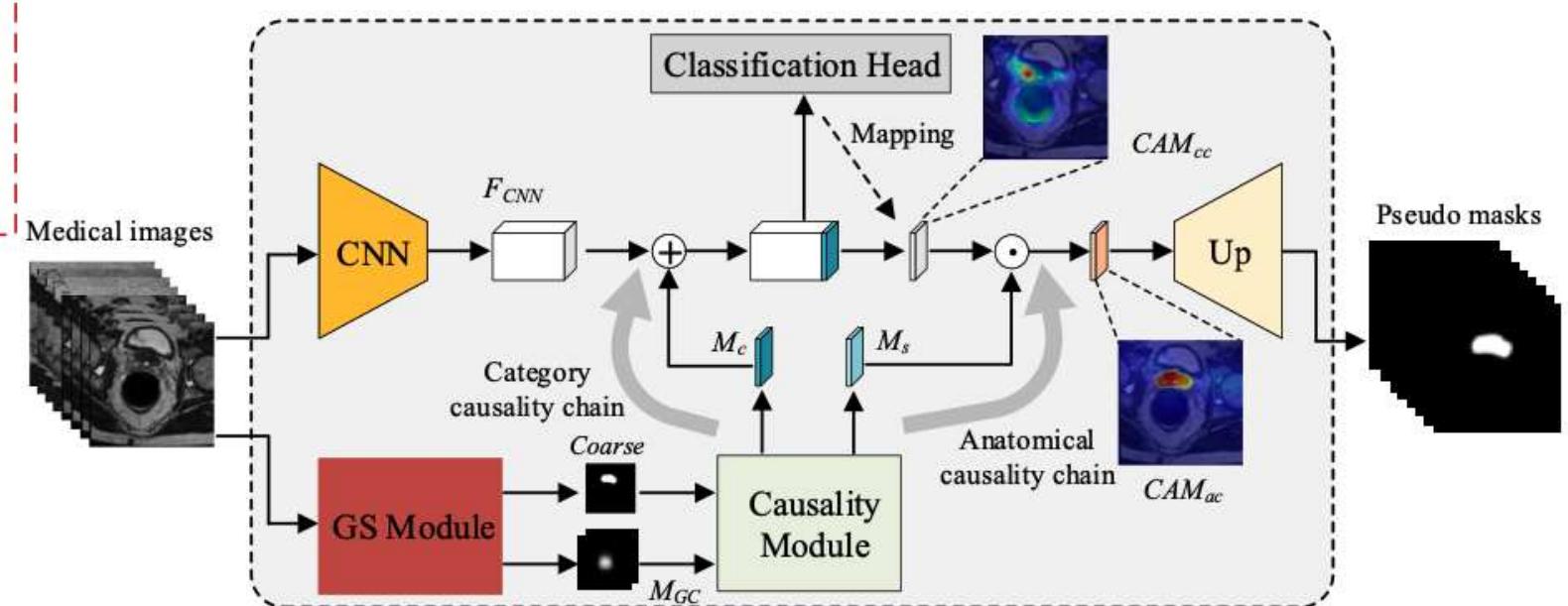
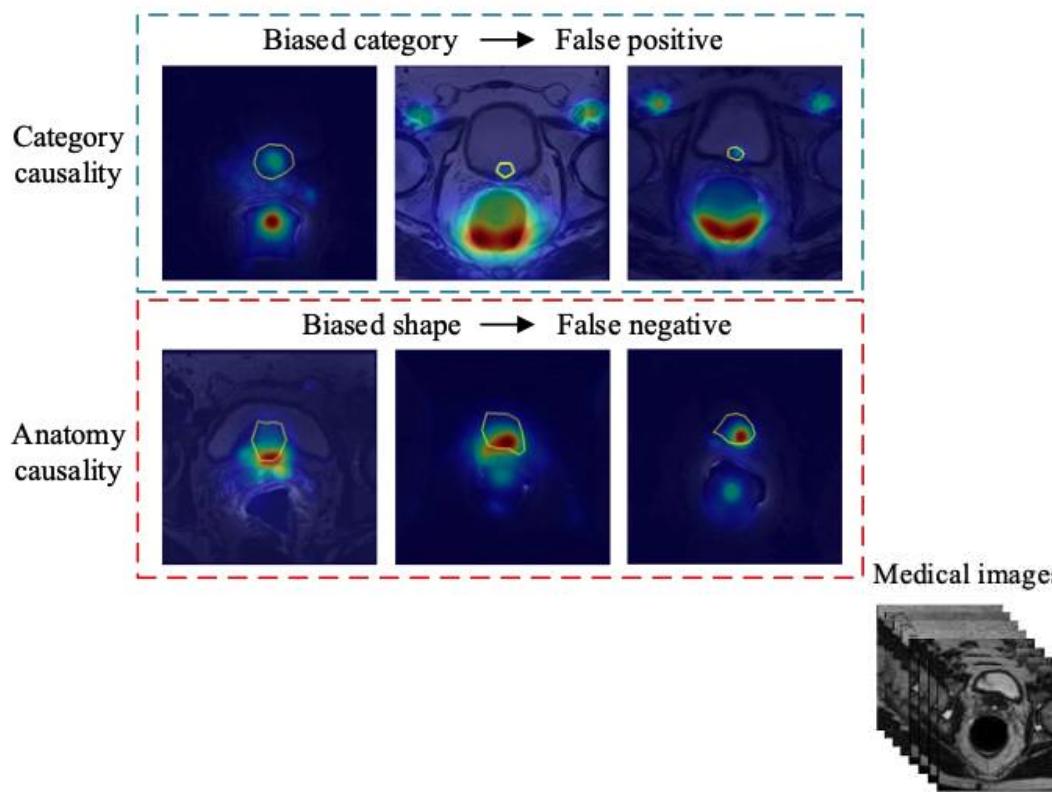
# From global cues to pixel labels

## CAMs in the medical domain



# From global cues to pixel labels

## CAMs in the medical domain



# Knowledge-driven priors

Common priors in natural images

Target Size



Incorrect sizes



Correct sizes

- Pathak et al., Constrained convolutional neural networks for weakly supervised segmentation, ICCV 2015
- Xu et al., Learning to Segment Under Various Forms of Weak Supervision, CVPR 2015
- Zhang et al., Curriculum Domain Adaptation for Semantic Segmentation of Urban Scenes. ICCV'17

# Knowledge-driven priors

Common priors in natural images

Incorrect  
location

Target Location



Correct  
location



- Remez et al. Learning to segment via cut-and-paste. ECCV 2018
- Georgakis et al Synthesizing training data for object detection in indoor scenes. RSS 2017

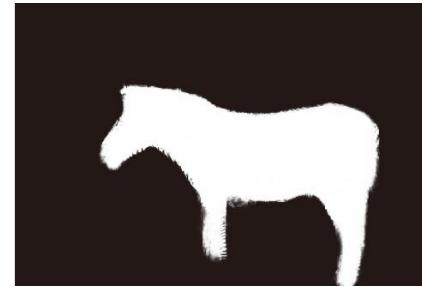
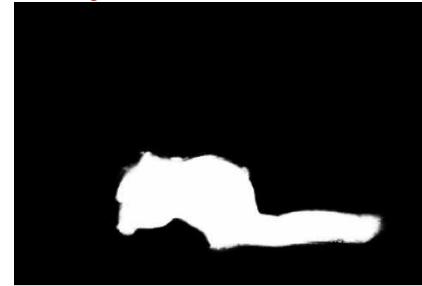
# Knowledge-driven priors

Common priors in natural images

Contrast  
Foreground/Background



Saliency



Images from Hou et al, CVPR'17

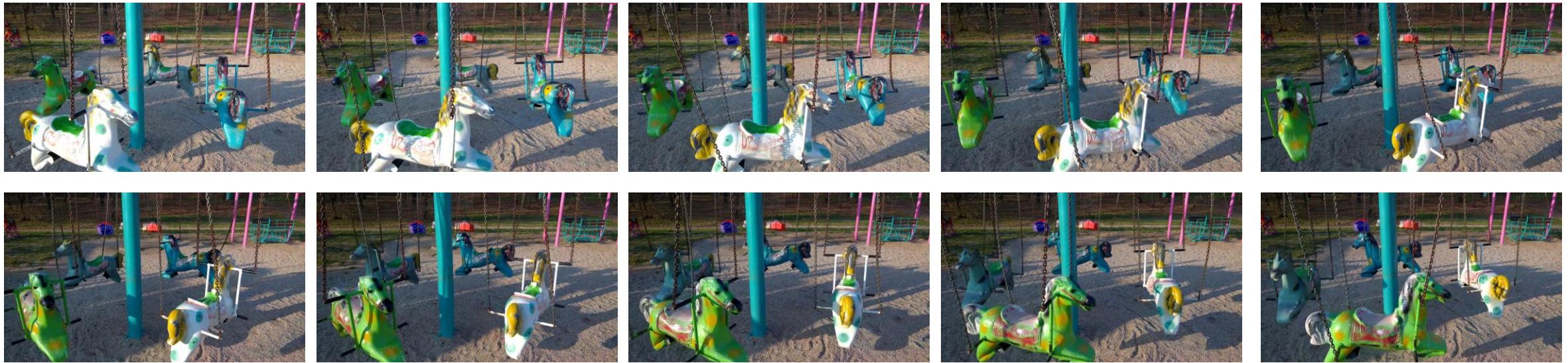
- Hou et al. Deeply supervised salient object detection with short connections. CVPR 2017
- Li et al. Instance-level salient object segmentation. CVPR 2017

# Knowledge-driven priors

Common priors in natural images

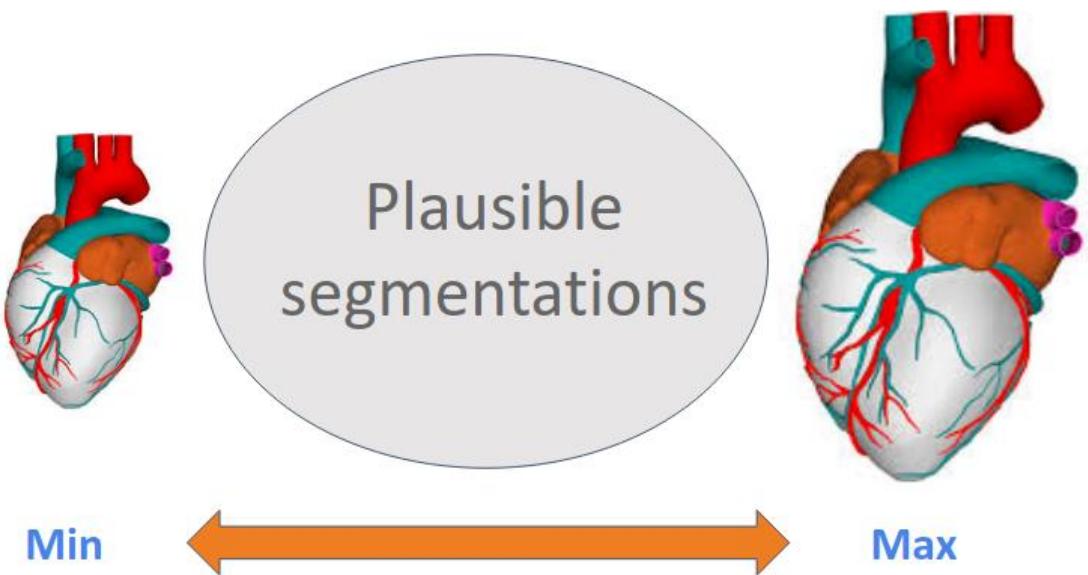
Motion

Images from the DAVIS Challenge Dataset



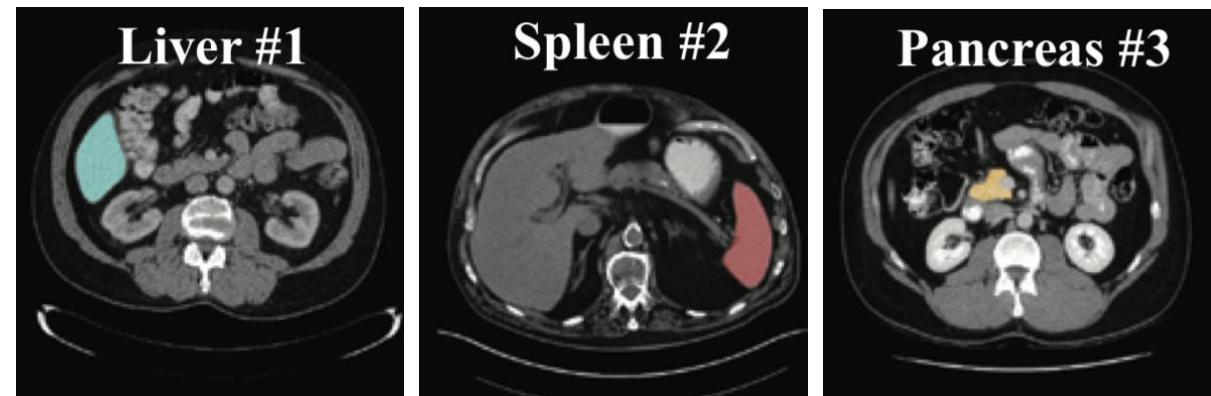
- Tokmakov et al. Weakly-supervised semantic segmentation using motion cues. ECCV 2016
- Pathak et al. Learning features by watching objects move. CVPR 2017

# Knowledge-driven priors



Anatomical priors

What about priors in the medical domain?



Partial labeled data  
(exploit target relationships)

# Constrained optimization (CNN)

Optimize (A)  
↑  
Task

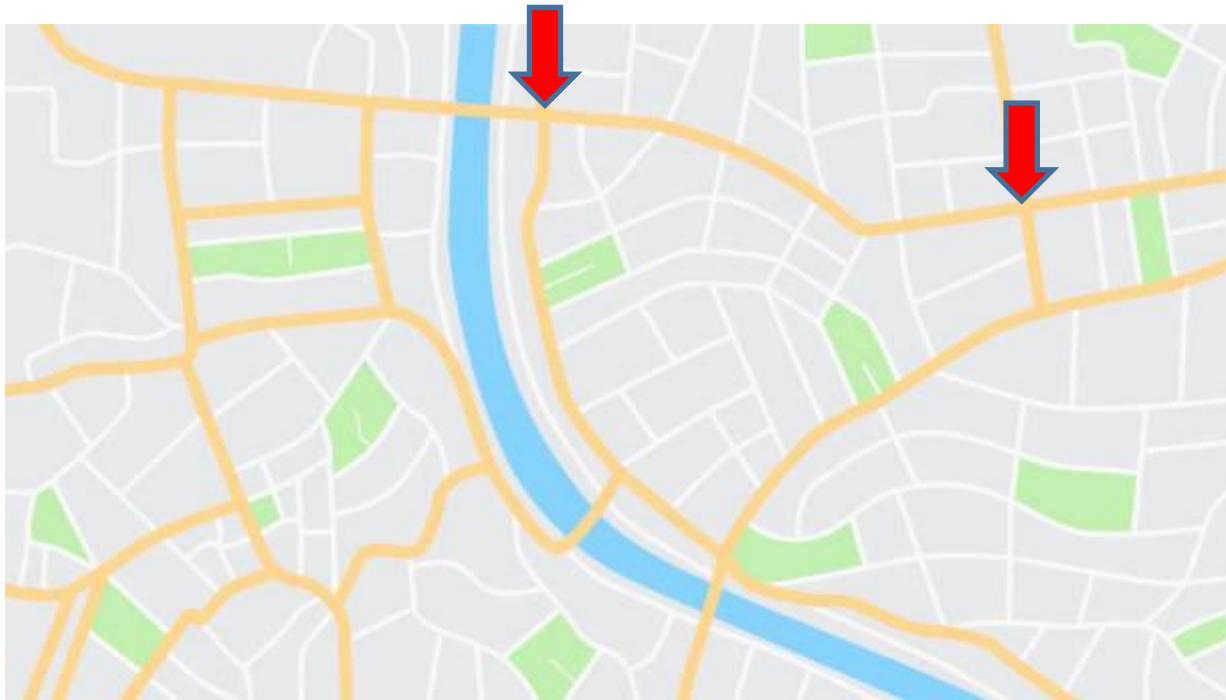
such that (B)  
↑  
Set of constraints

# Constrained optimization (CNN)

Optimize (A)  
↑  
Task

such that (B)  
↑  
Set of constraints

How we can go from  
point A to B?

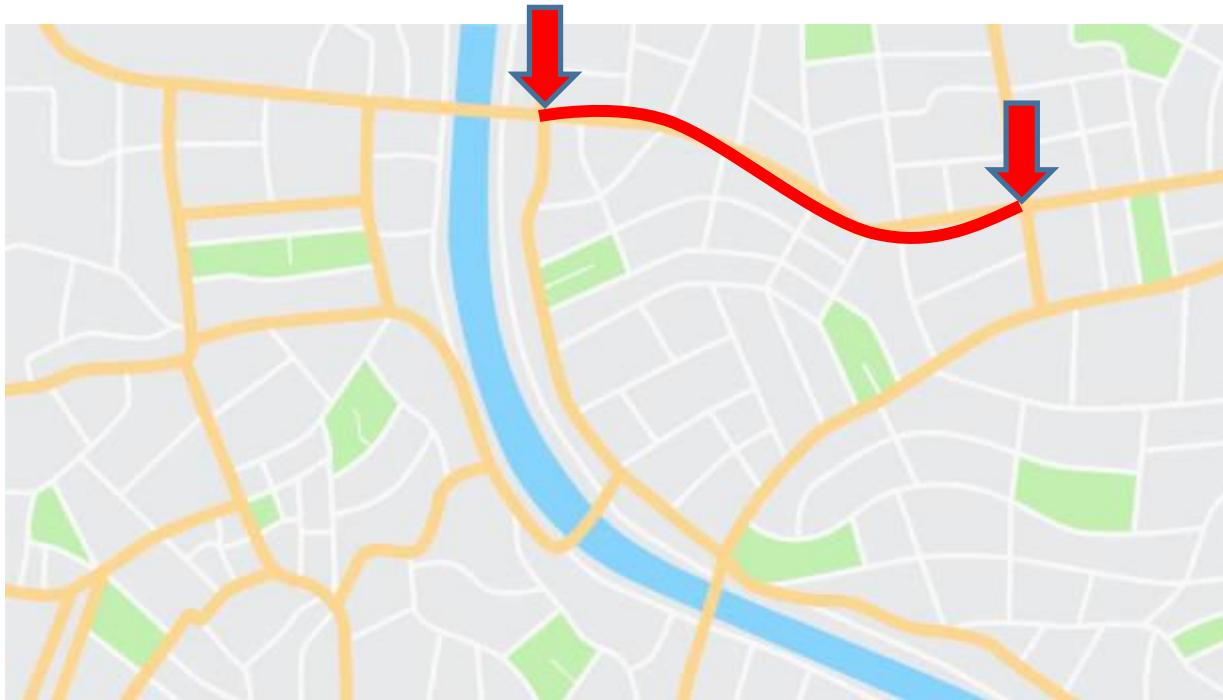


# Constrained optimization (CNN)

Optimize (A)  
↑  
Task

such that (B)  
↑  
Set of constraints

How we can go from  
point A to B?

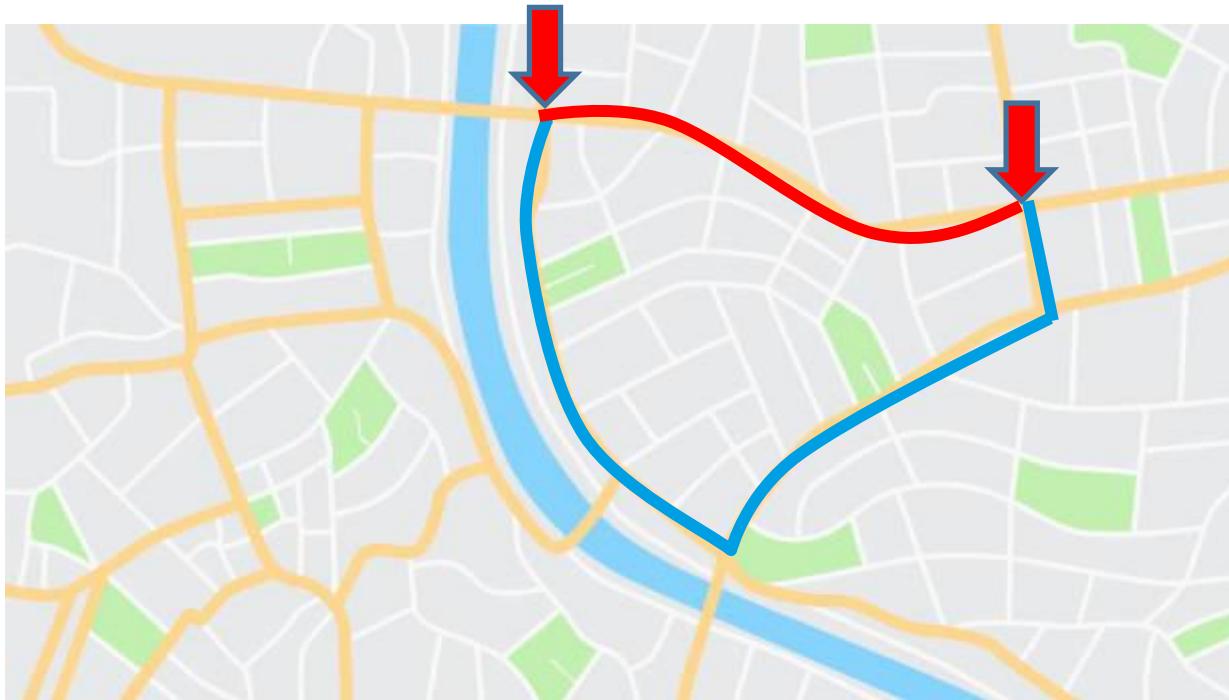


# Constrained optimization (CNN)

Optimize (A)  
↑  
Task

such that (B)  
↑  
Set of constraints

How we can go from  
point A to B?

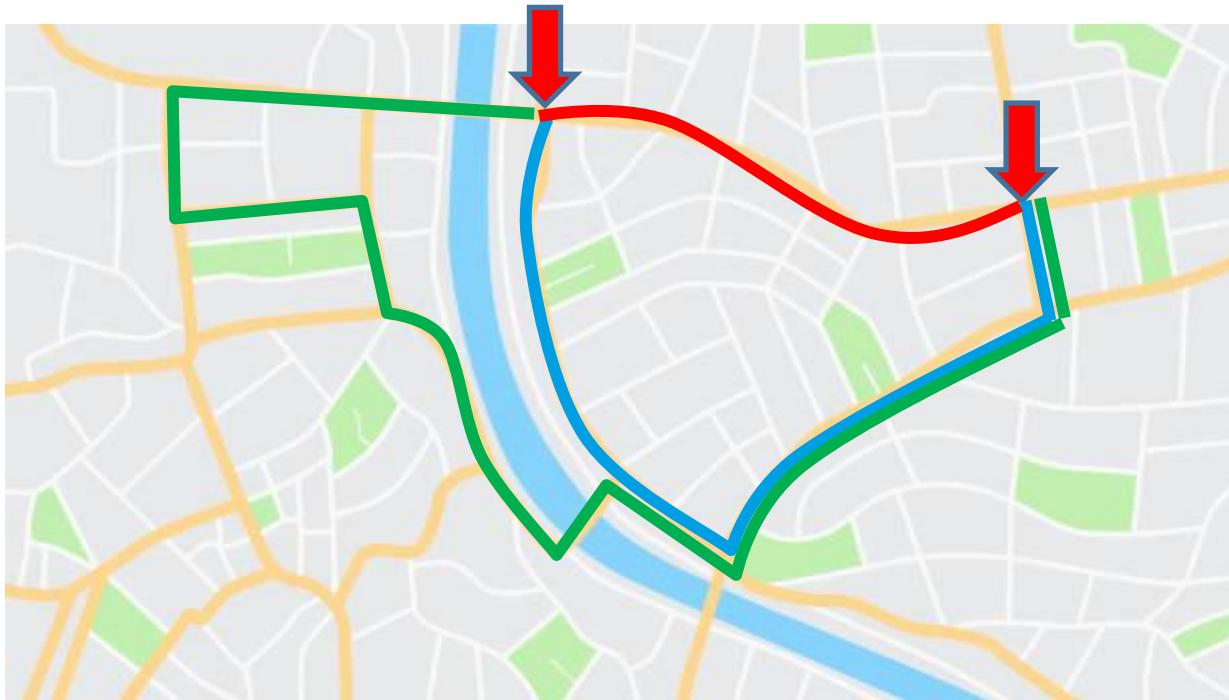


# Constrained optimization (CNN)

Optimize (A)  
↑  
Task

such that (B)  
↑  
Set of constraints

How we can go from  
point A to B?



Which is the best  
route?

# Constrained optimization (CNN)

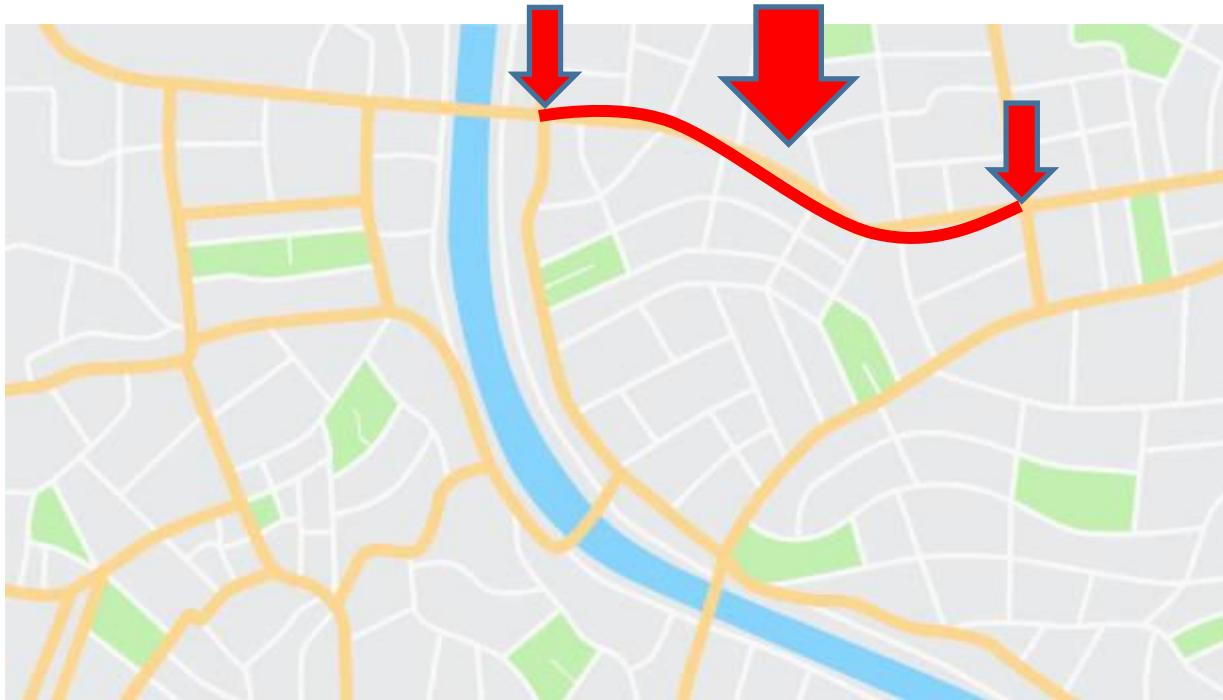
Optimize (A)

Task

such that (B)

Set of constraints

How we can go from point A to B?



Which is the best route?

***Constraint: shortest***

# Constrained optimization (CNN)

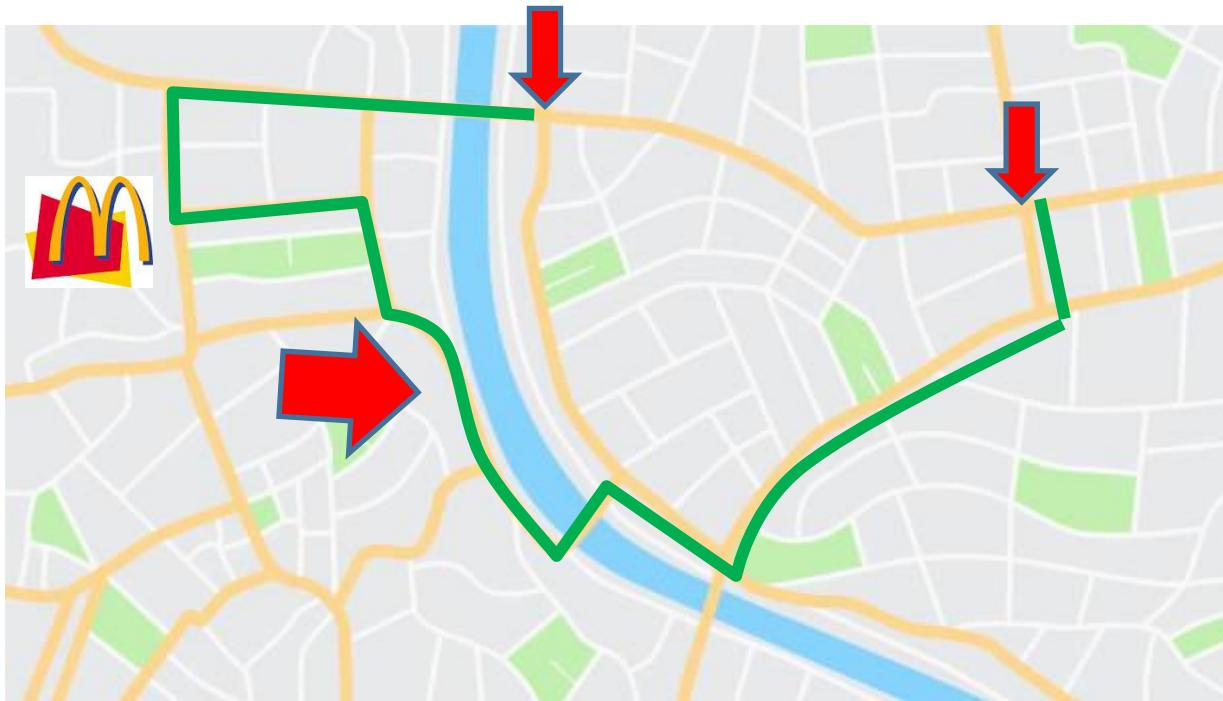
Optimize (A)

Task

such that (B)

Set of constraints

How we can go from point A to B?



Which is the best route?

*Constraint: shortest but going through a McDonalds*

# Constrained optimization (CNN)

Optimize (A) such that (B)

$$\min_{\theta} \mathcal{H}(S, Y) \quad s.t. \quad \sum_{n=0}^N s_n = A$$

Constrained problem

# Constrained optimization (CNN)

Optimize (A)

such that (B)

$$\min_{\theta} \mathcal{H}(S, Y) \quad s.t. \quad \sum_{n=0}^N s_n = A$$

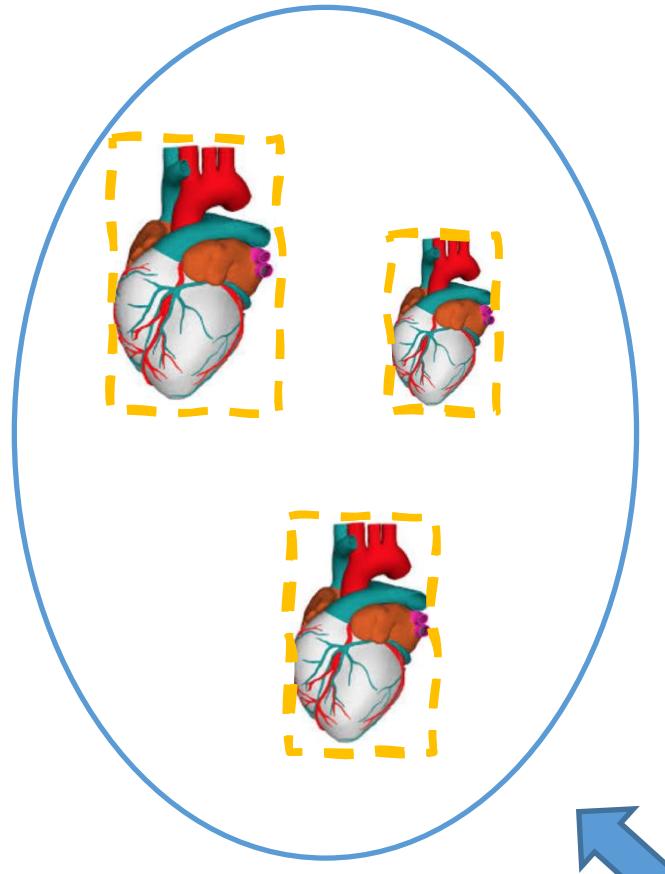
Constrained problem

$$\min_{\theta} \mathcal{H}(S, Y) - \lambda \left( \sum_{n=0}^N s_n - A \right)$$

Unconstrained problem

# Equality constraints

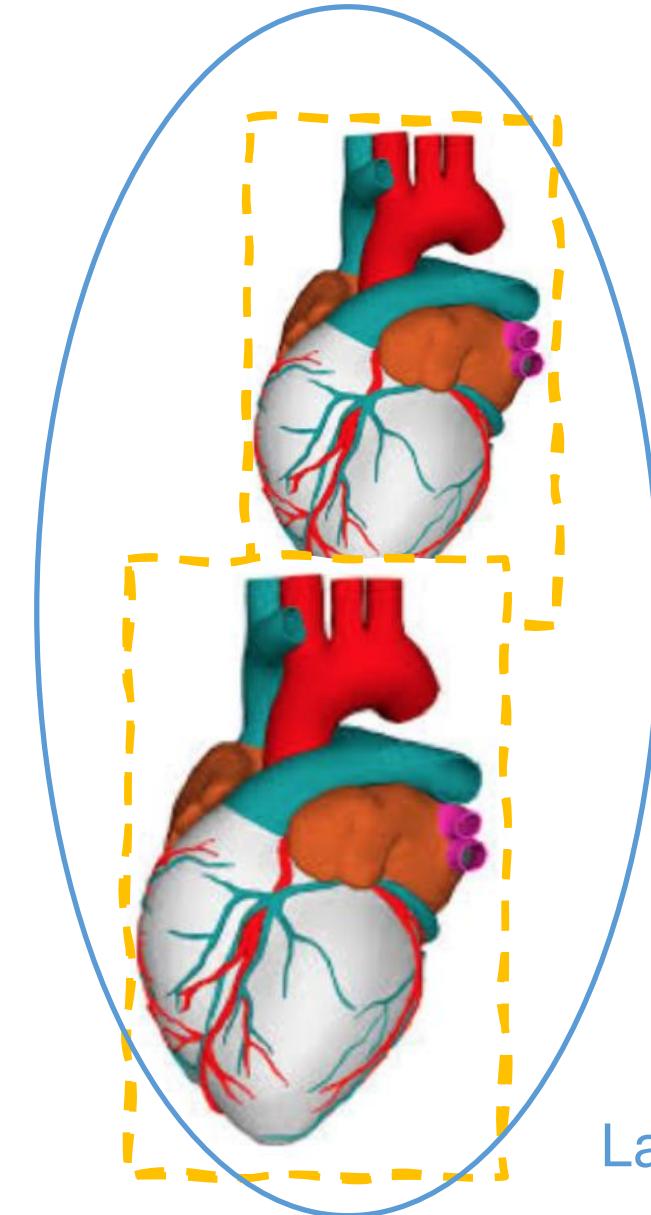
$$A=B$$



Smaller

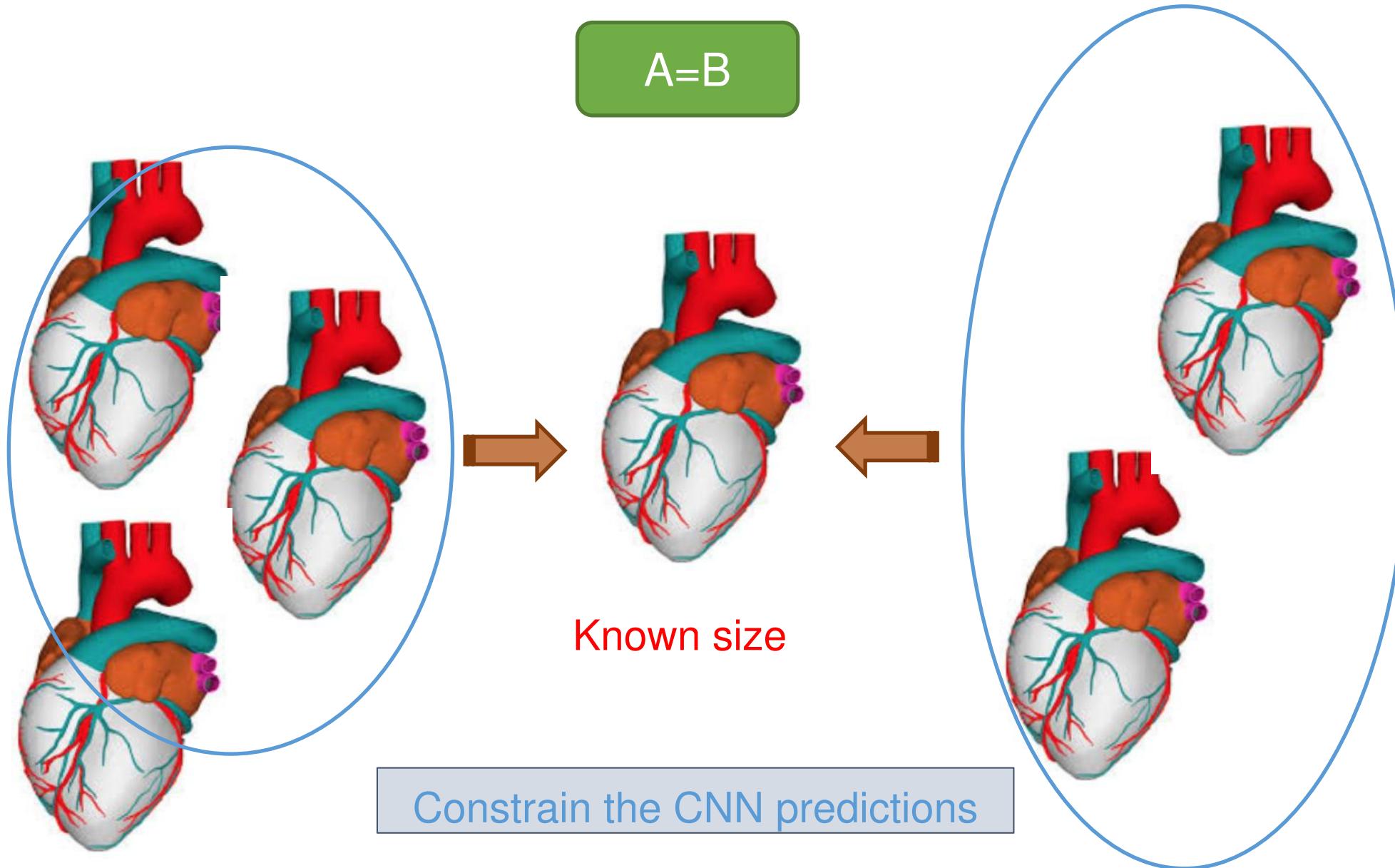
Known size

CNN predictions



Larger

# Equality constraints



# Equality constraints

## L2 Penalty

Input  
(Histology image)



Any CNN architecture



Output  
(Pixel-wise prediction)

# Equality constraints

## L2 Penalty

Input  
(Histology image)

Additional term

Any CNN architecture

$$l_{ac} = \mathbf{I}(Y_i = 1) \sum_i (v_i - a_i)^2$$



Output  
(Pixel-wise prediction)

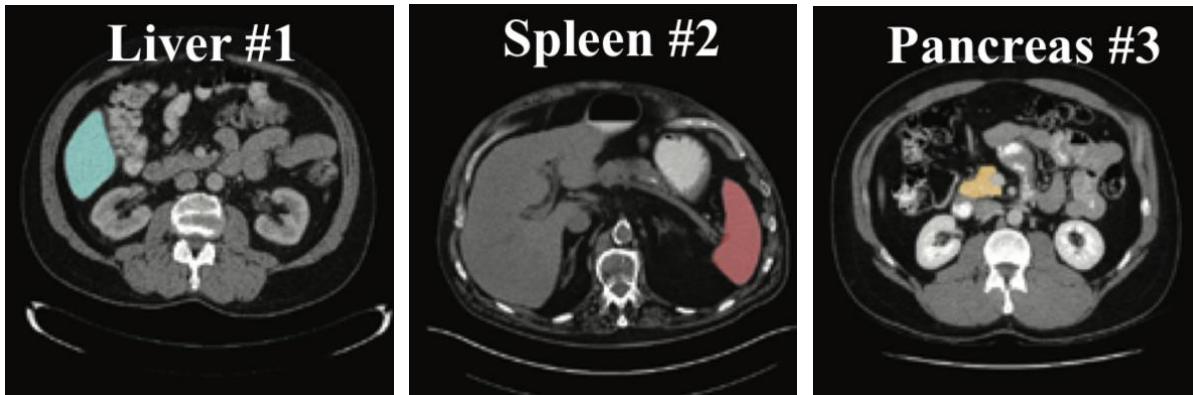
Predicted relative  
size (%)

$$v_i = \frac{1}{N} \sum_{p \in \Omega} s_\theta^{p,1}$$

Predicted size  
given by experts

# Equality constraints

Kullback-Leibler (KL)  
Divergence

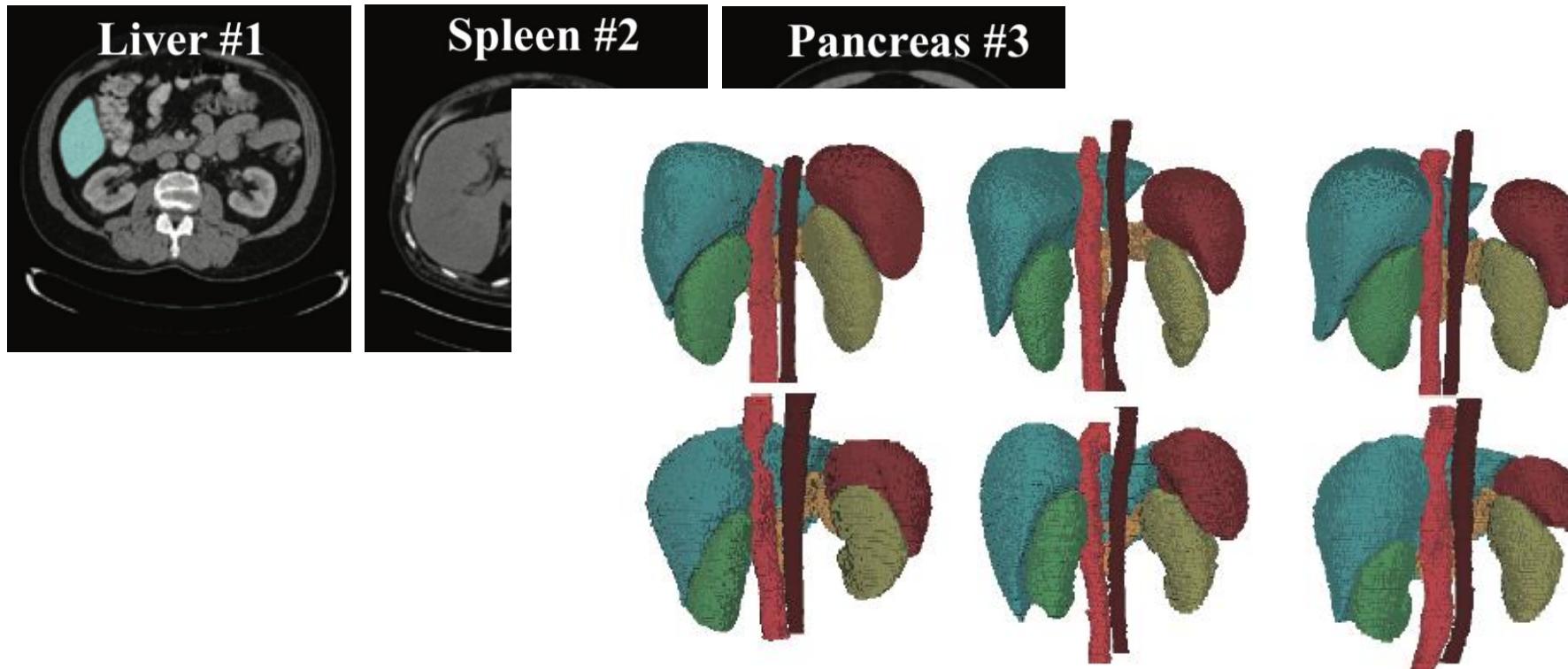


Partial annotations

# Equality constraints

Kullback-Leibler (KL)  
Divergence

Partial annotations



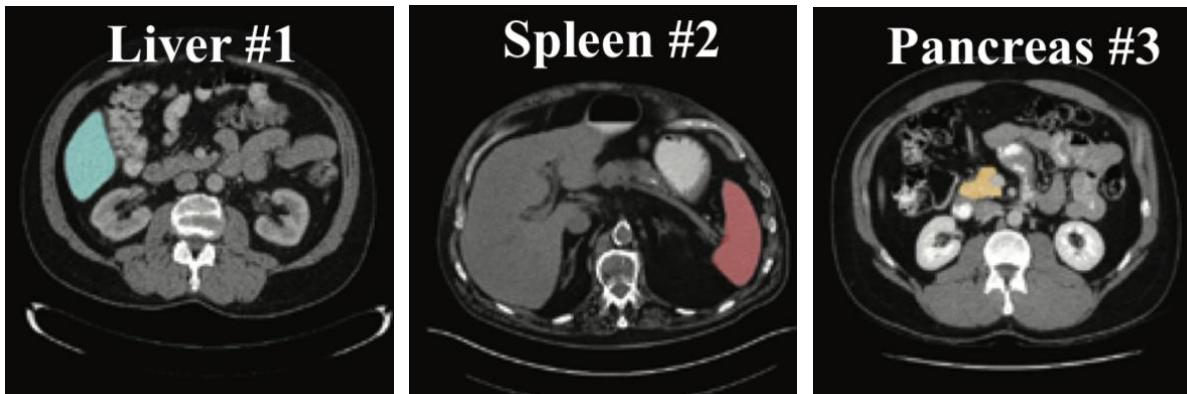
Prior on the proportion

Figure 1. 3D Visualization of several abdominal organs (liver, spleen, left kidney, right kidney, aorta, inferior vena cava) to show the similarity of patient-wise abdominal organ size distributions.

# Equality constraints

Kullback-Leibler (KL)  
Divergence

Partial annotations



Main objective:

$$\min \frac{1}{|\mathcal{L}|} \sum_{p \in \mathcal{L}} l(\mathbf{y}^p, \mathbf{s}_\theta^p) + \lambda_1 \frac{1}{|\mathcal{P}|} \sum_{q \in \mathcal{P}} l(\mathbf{y}^q, \mathbf{s}_\theta^q) + \lambda_2 \mathcal{J}(\theta)$$

Fully labeled images

Partially labeled images

Prior-aware loss

# Equality constraints

Kullback-Leibler (KL)  
Divergence

Partial annotations



Prior-aware loss

Averaged predicted  
distribution

$$\hat{\mathbf{p}} = \frac{1}{N} \sum_{p \in \mathcal{P}} \mathbf{s}_{\theta}^p$$

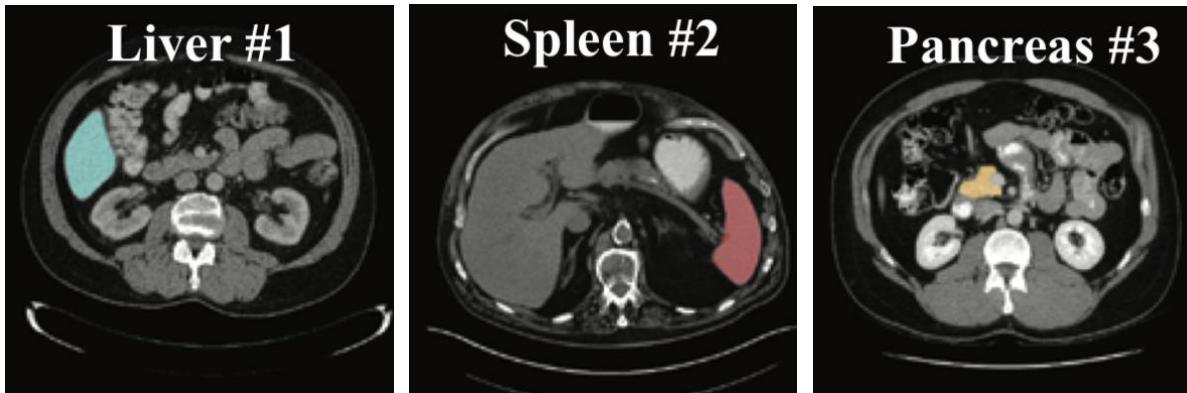
$[s_{\theta}^{p,0}, s_{\theta}^{p,1}, \dots, s_{\theta}^{p,|K|}]$

On partially labeled images

# Equality constraints

Kullback-Leibler (KL)  
Divergence

Partial annotations



Prior-aware loss

Embed prior knowledge

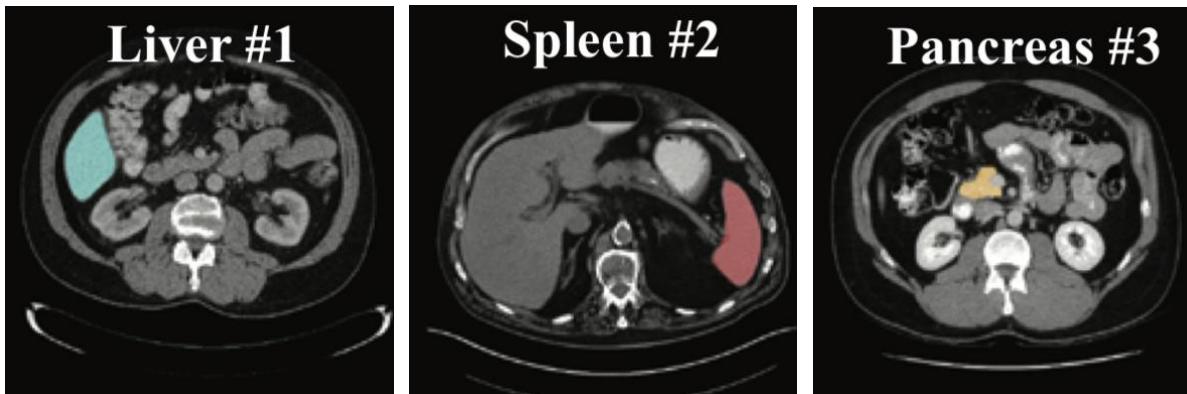
$$KL(\mathbf{q}|\hat{\mathbf{p}})$$



Real label distribution      Average predicted distribution

# Equality constraints

Kullback-Leibler (KL)  
Divergence



Partial annotations

KL can be expanded

$$\sum_c KL(q^c|\hat{p}^c) = - \sum_c (q^c \log \hat{p}^c + ((1 - q^c) \log(1 - \hat{p}^c)) + const$$

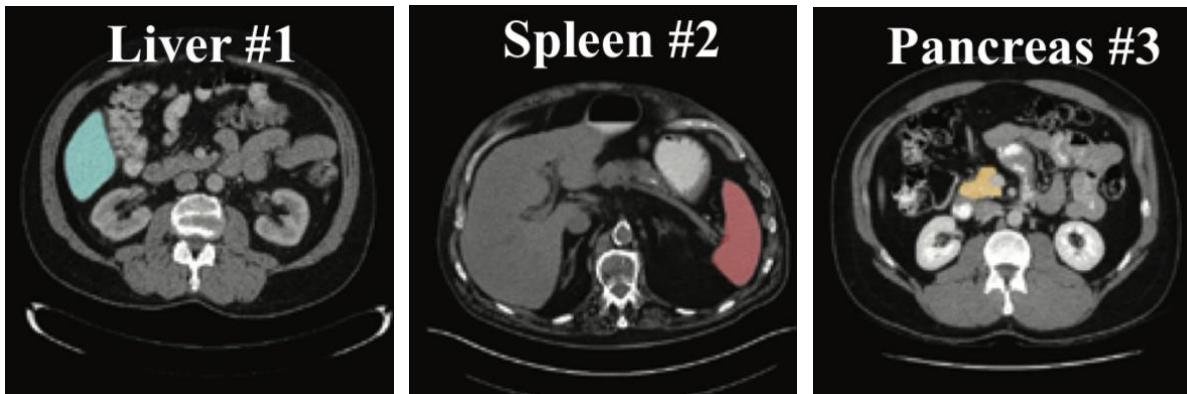
$\hat{p}_c = \frac{1}{N} \sum_{p \in \mathcal{P}} s_\theta^{p,c}$

Prior-aware loss

$$-\sum_{c=0}^{|K|} \left\{ q^c \log \left( \frac{1}{N} \sum_{p \in \mathcal{P}} s_\theta^{p,c} \right) + (1 - q^c) \log \left( 1 - \frac{1}{N} \sum_{p \in \mathcal{P}} s_\theta^{p,c} \right) \right\} + const$$

# Equality constraints

Kullback-Leibler (KL)  
Divergence



Partial annotations

$$\sum_c KL(q^c|\hat{p}^c) = - \sum_c (q^c \log \hat{p}^c + ((1 - q^c) \log(1 - \hat{p}^c))) + const$$

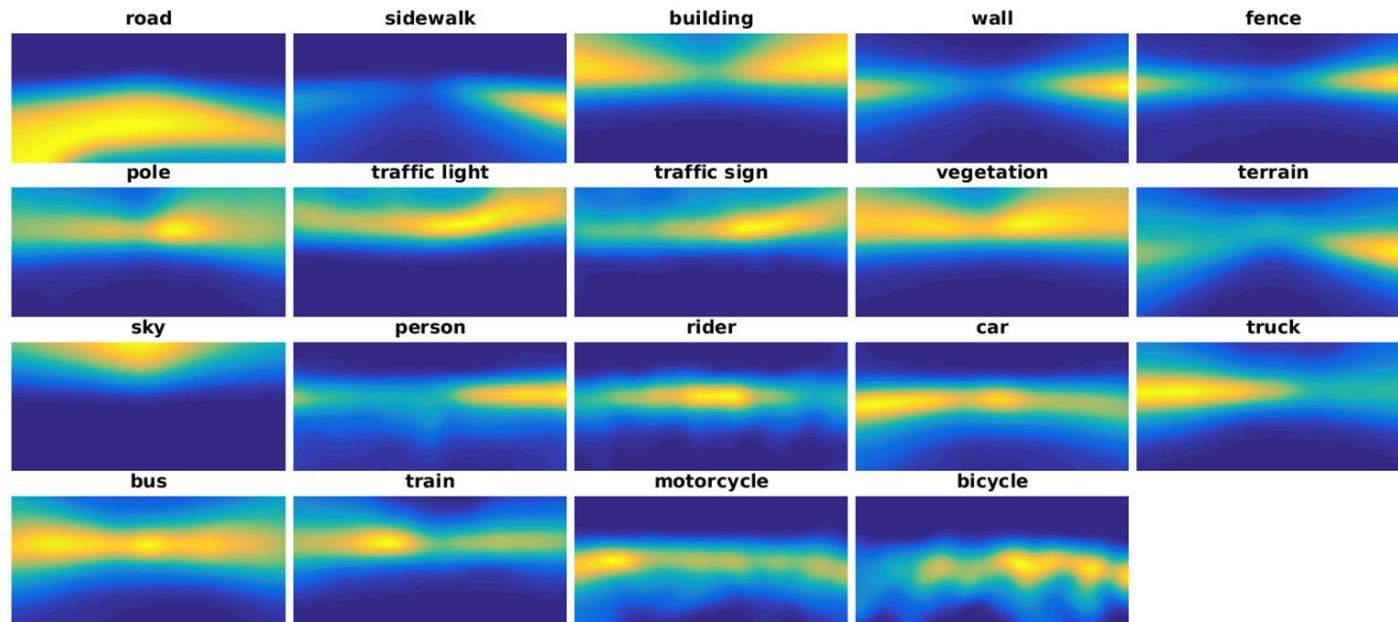
Prior-aware loss

$$-\sum_{c=0}^{|K|} \left\{ q^c \log \frac{1}{N} \sum_{p \in \mathcal{P}} \mathbf{s}_{\theta}^{p,c} + (1 - q^c) \log \left( 1 - \frac{1}{N} \sum_{p \in \mathcal{P}} \mathbf{s}_{\theta}^{p,c} \right) \right\} + const$$

This is problematic (average distribution of  $\hat{p}$  organ sizes inside log!!)

# Equality constraints

At pixel level



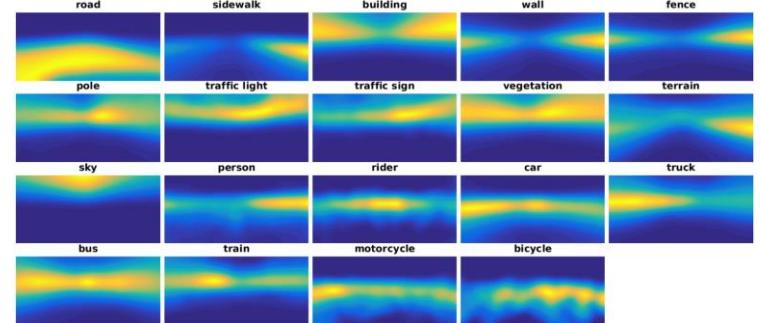
Spatial priors on GTA5

# Equality constraints

At pixel level

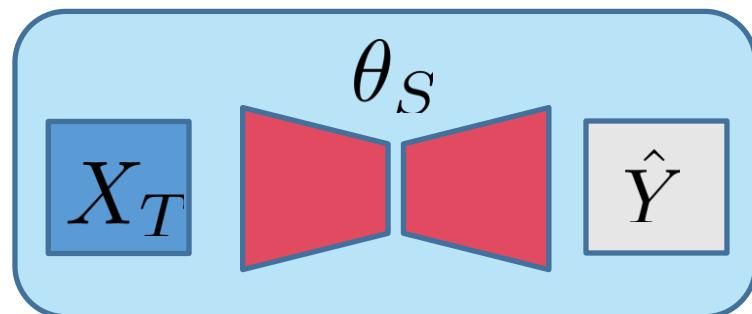
Objective:

$$-\sum_{p \in \mathcal{L}} l(\mathbf{y}^p, s_\theta^p) - \sum_{q \in \mathcal{U}} \sum_{c=1}^K (\hat{y}^{q,c} \log(prior^{q,c} s_\theta^{q,c}) + w_c \hat{y}^{q,c})$$



# Equality constraints

At pixel level

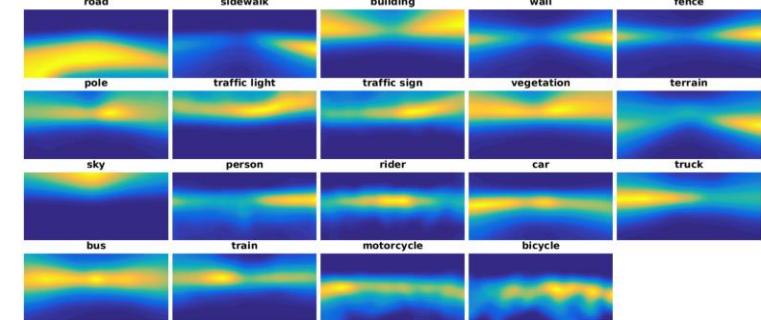


Proposals

Objective:

$$-\sum_{p \in \mathcal{L}} l(\mathbf{y}^p, s_\theta^p) - \sum_{q \in \mathcal{U}} \sum_{c=1}^K (\hat{y}^{q,c} \log(prior^{q,c} s_\theta^{q,c}) + w_c \hat{y}^{q,c})$$

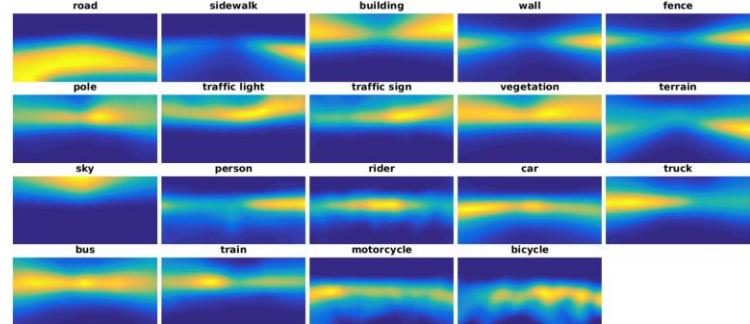
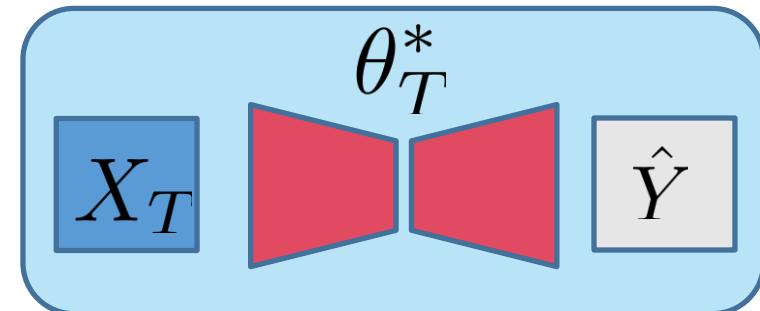
Source images



Target images

# Equality constraints

At pixel level



Objective:

$$-\sum_{p \in \mathcal{L}} l(\mathbf{y}^p, s_\theta^p) - \sum_{q \in \mathcal{U}} \sum_{c=1}^K (\hat{y}^{q,c} \log(prior^{q,c} s_\theta^{q,c}) + w_c \hat{y}^{q,c})$$

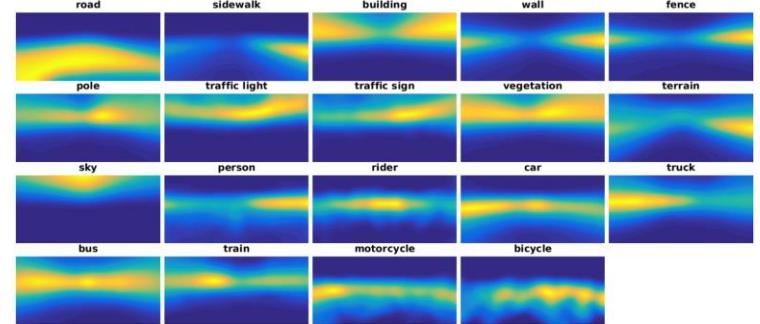
This becomes two KL

$$KL(\hat{y}^{q,c} | prior^{q,c}) \quad \quad \quad KL(\hat{y}^{q,c} | s_\theta^{q,c})$$

2-steps minimization process

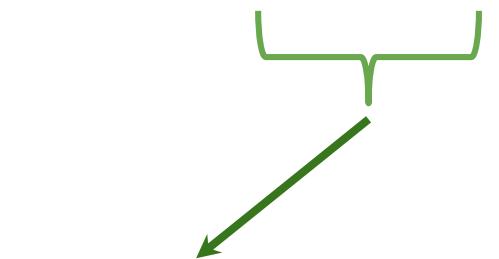
# Equality constraints

At pixel level



Objective:

$$-\sum_{p \in \mathcal{L}} l(\mathbf{y}^p, s_\theta^p) - \sum_{q \in \mathcal{U}} \sum_{c=1}^K (\hat{y}^{q,c} \log(prior^{q,c} s_\theta^{q,c}) + w_c \hat{y}^{q,c})$$

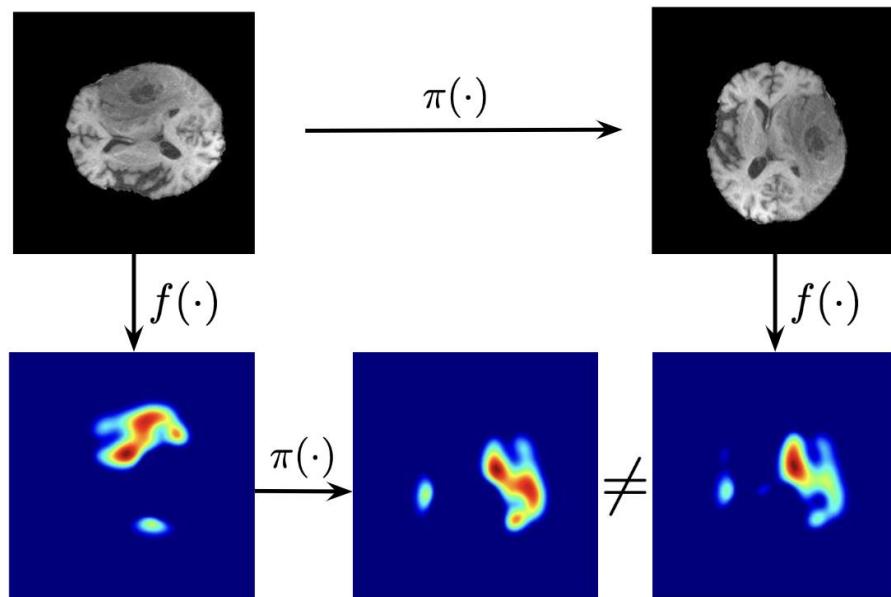


Weights the proposals

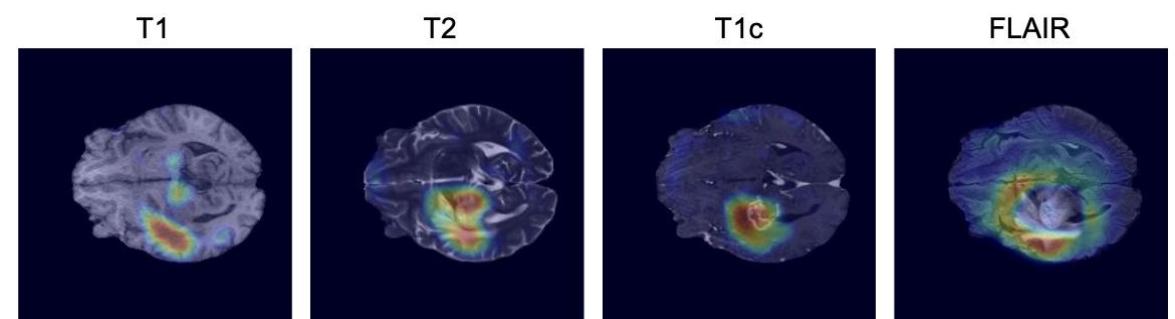
# Equality constraints

At pixel level

Imposing Consistency across image modalities



CAMs not equivariant to spatial  
transformations



CAMs not consistent across modalities

# Equality constraints

At pixel level

Consistency regularization term on the CAMs and between modalities

Same-modality equivariant  
constraints

$$l_{reg}(T(f(M_1)), f(T(M_1)))$$

Cross-modality equivariant  
constraints

$$l_{reg}(T(f(M_1)), f(T(M_2)))$$

# Equality constraints

At pixel level

Consistency regularization term on the CAMs and between modalities

Same-modality equivariant  
constraints

Cross-modality equivariant  
constraints

$$l_{reg}(T(f(M_1)), f(T(M_1)))$$

$$l_{reg}(T(f(M_1)), f(T(M_2)))$$

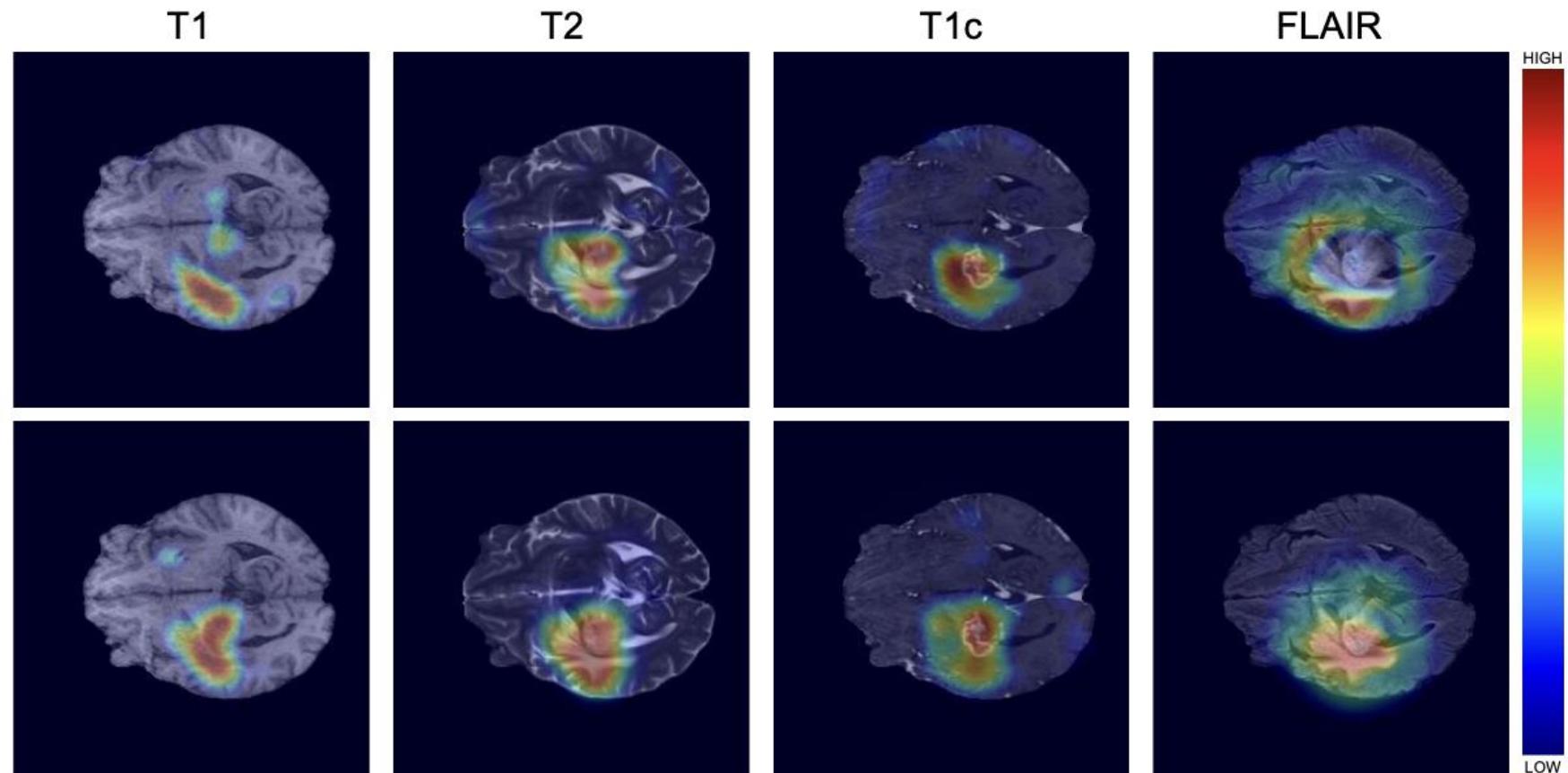
$$\mathcal{L}_{class} + l_{reg}(T(f(M_m)), f(T(M_m))) + l_{reg}(T(f(M_m)), f(T(M_n)))$$

# Equality constraints

At pixel level

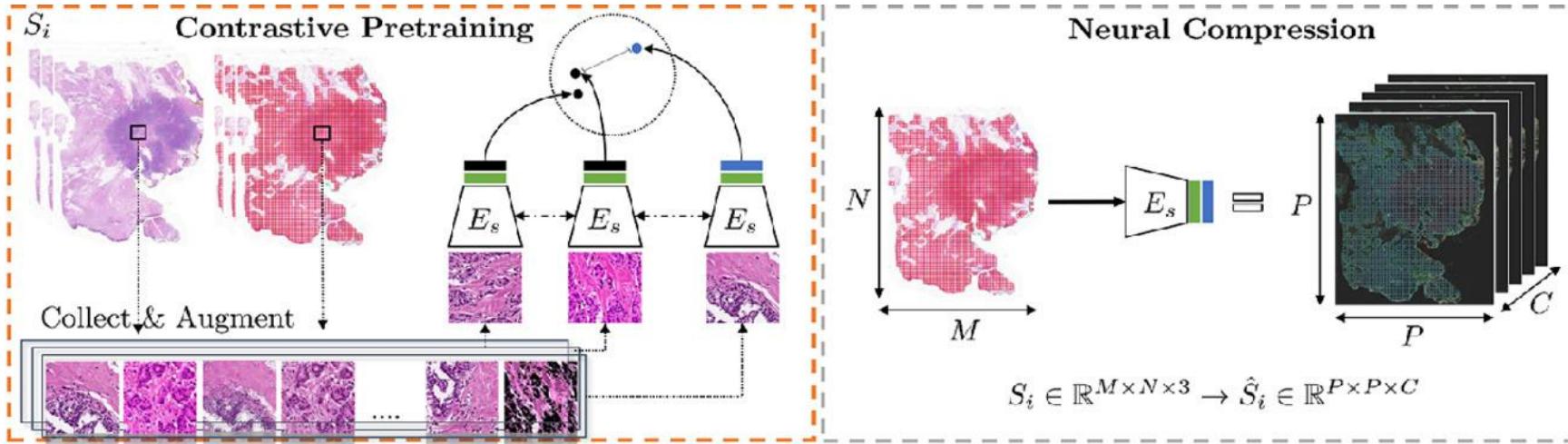
Baseline

Baseline + equivariant  
constraints

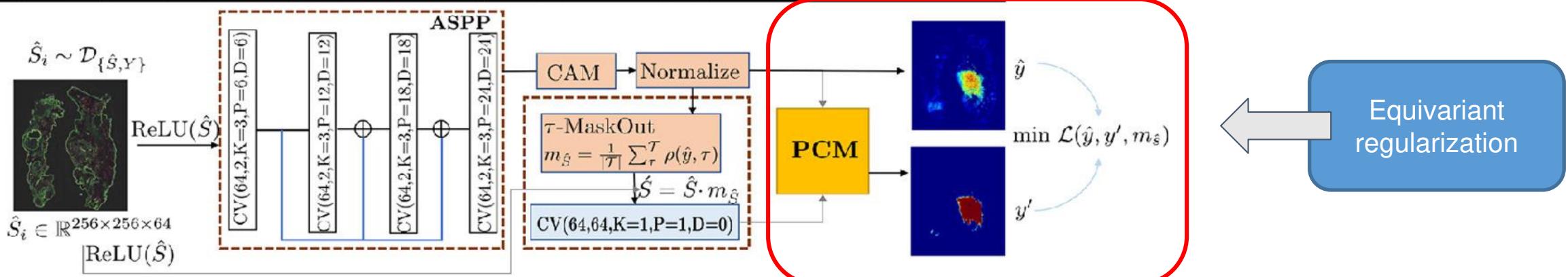


# Equality constraints

At pixel level



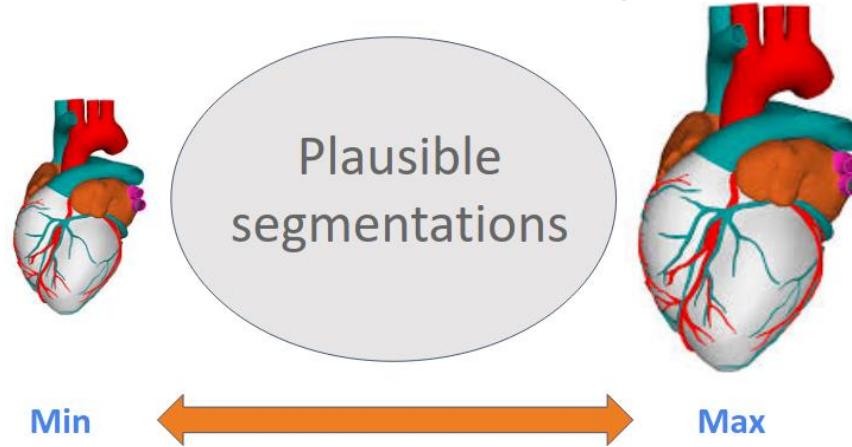
## Single-Stage Masked Weakly Supervised Segmentation - WSS-SS



# Inequality constraints

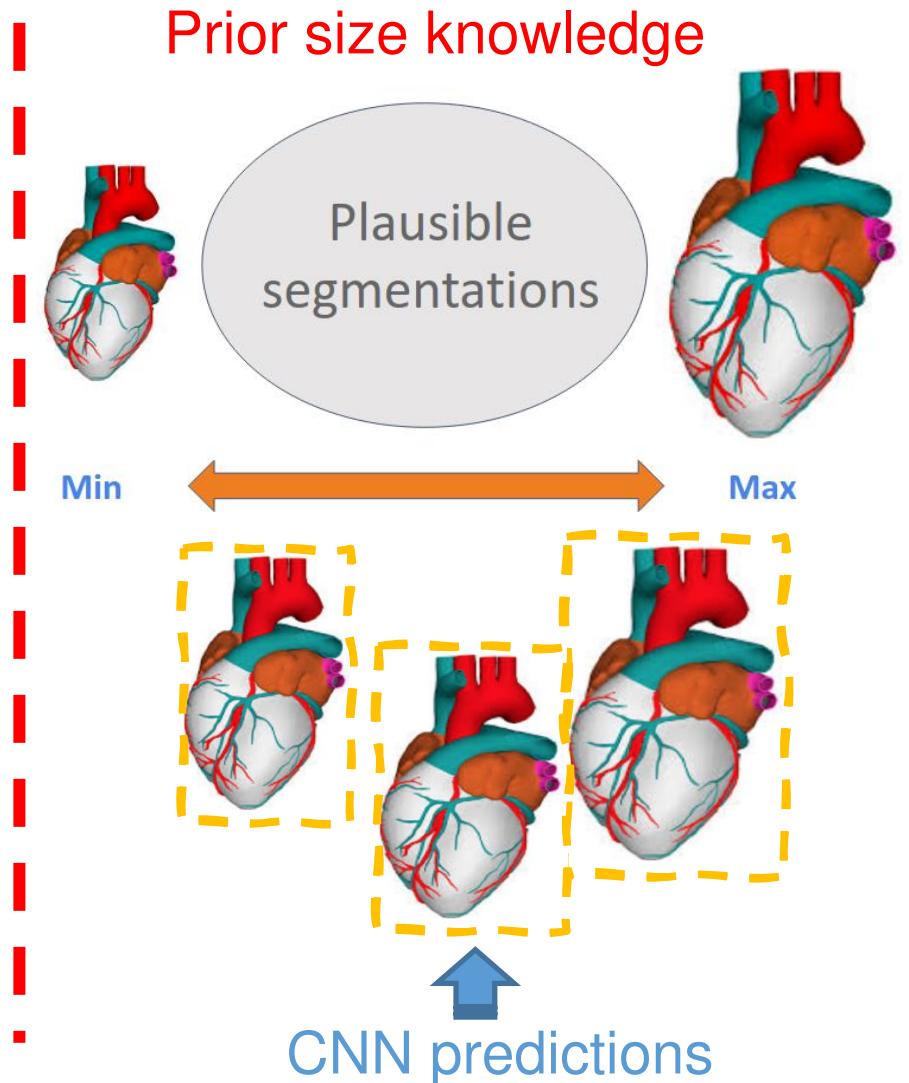
A<B,  
A>B,  
B1 < A < B2

Prior size knowledge



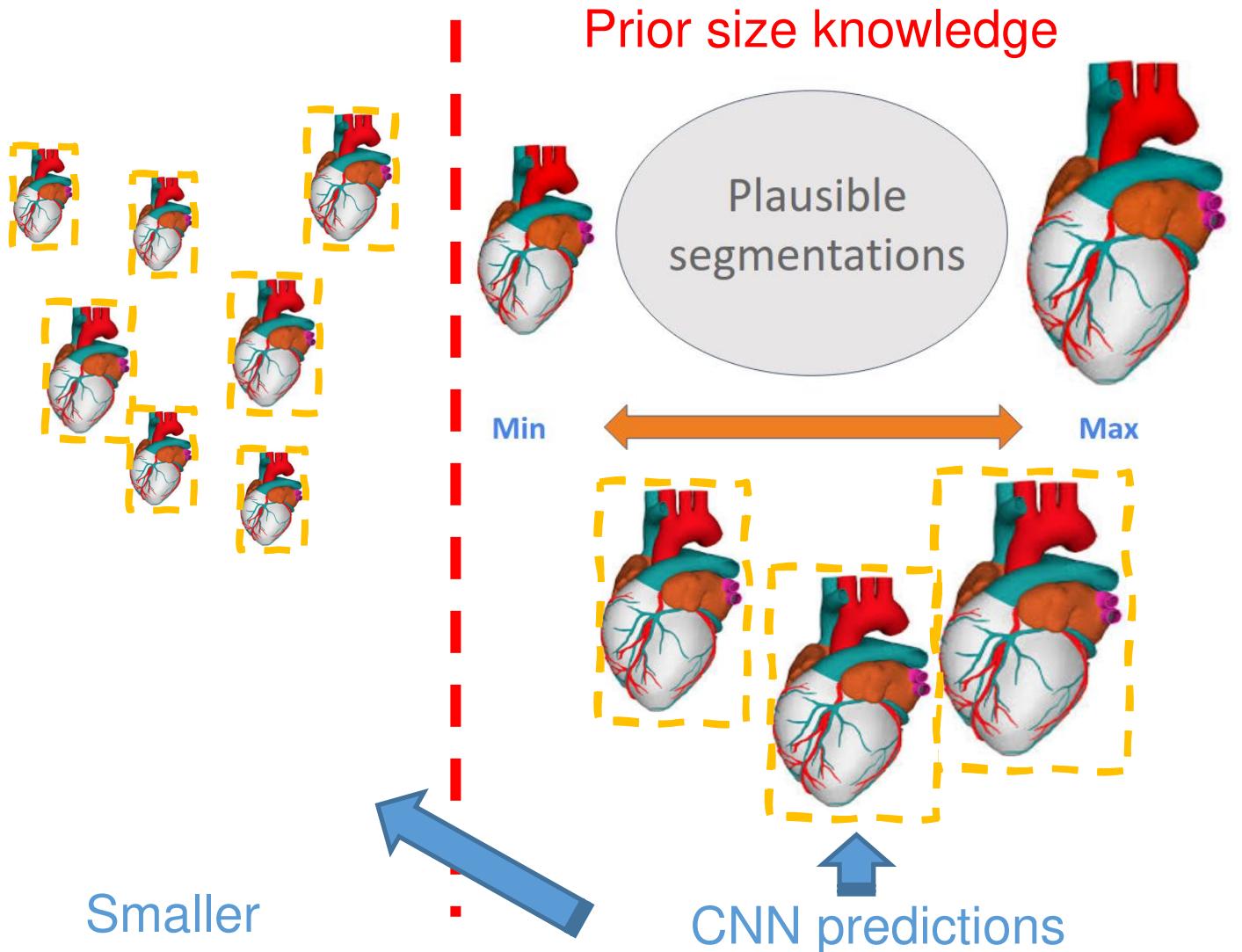
# Inequality constraints

A<B,  
A>B,  
B1 < A < B2

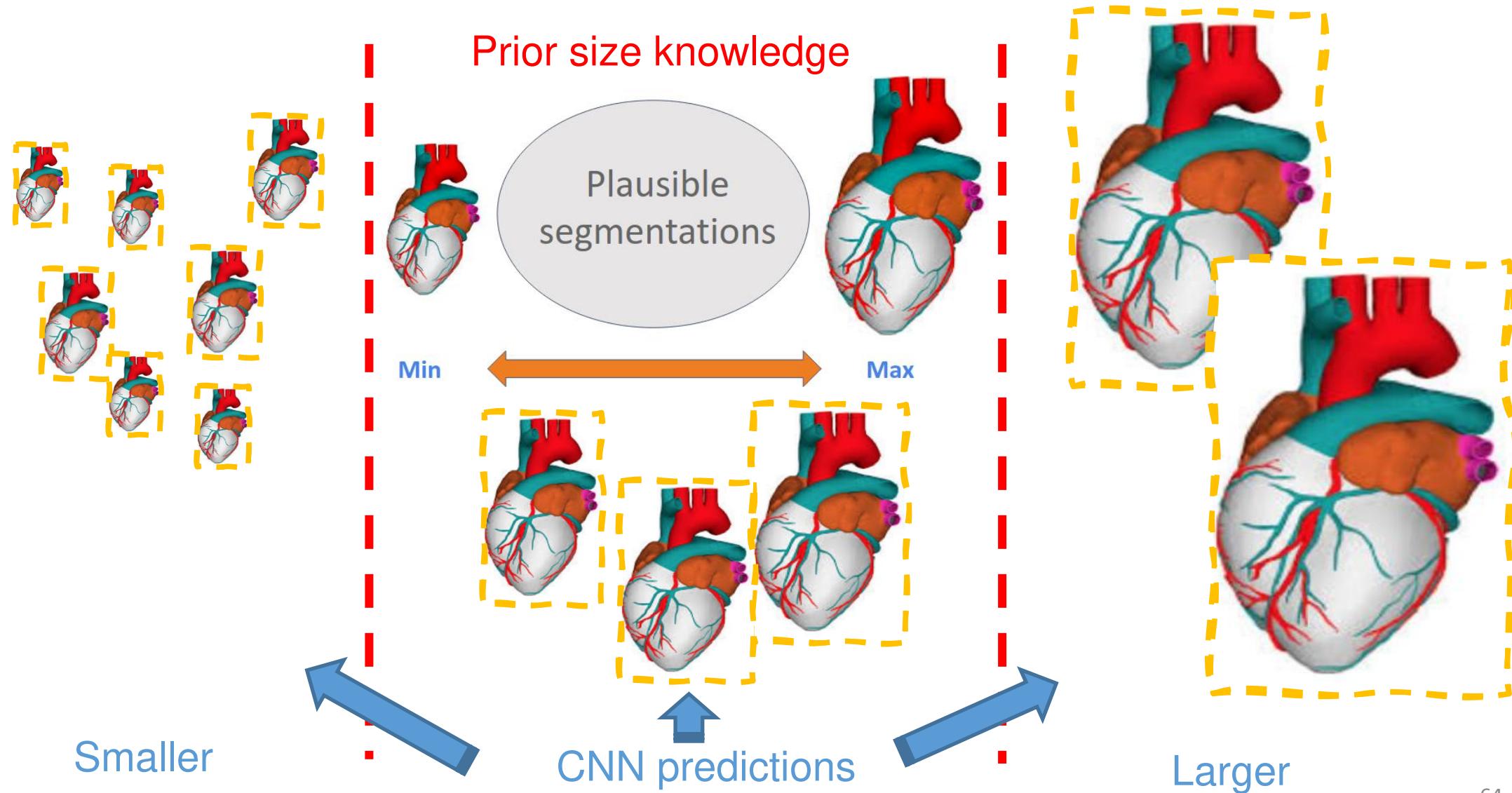


# Inequality constraints

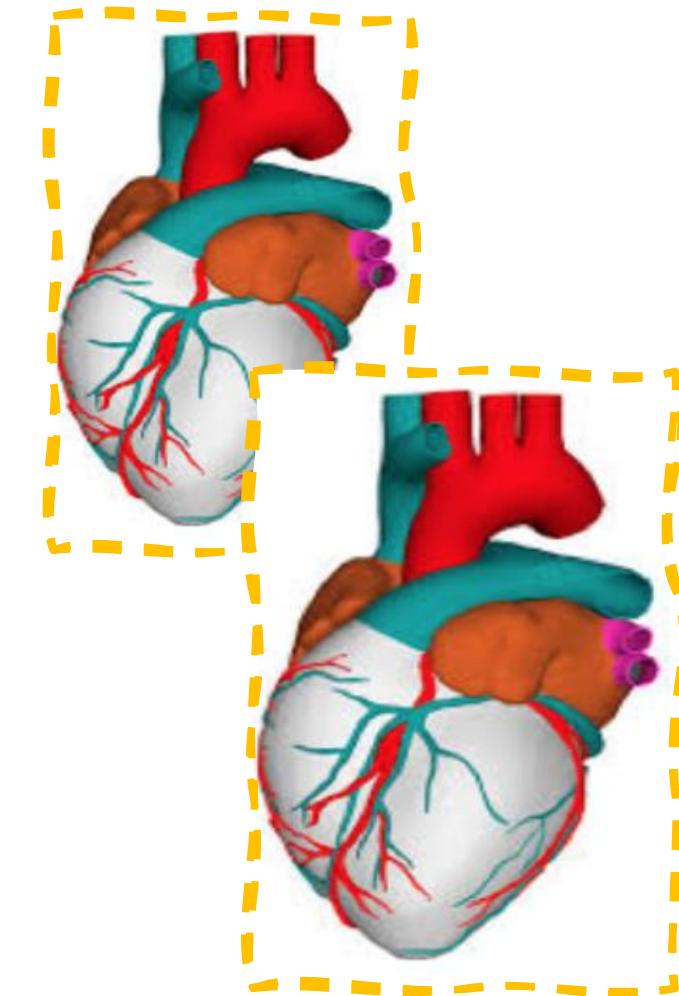
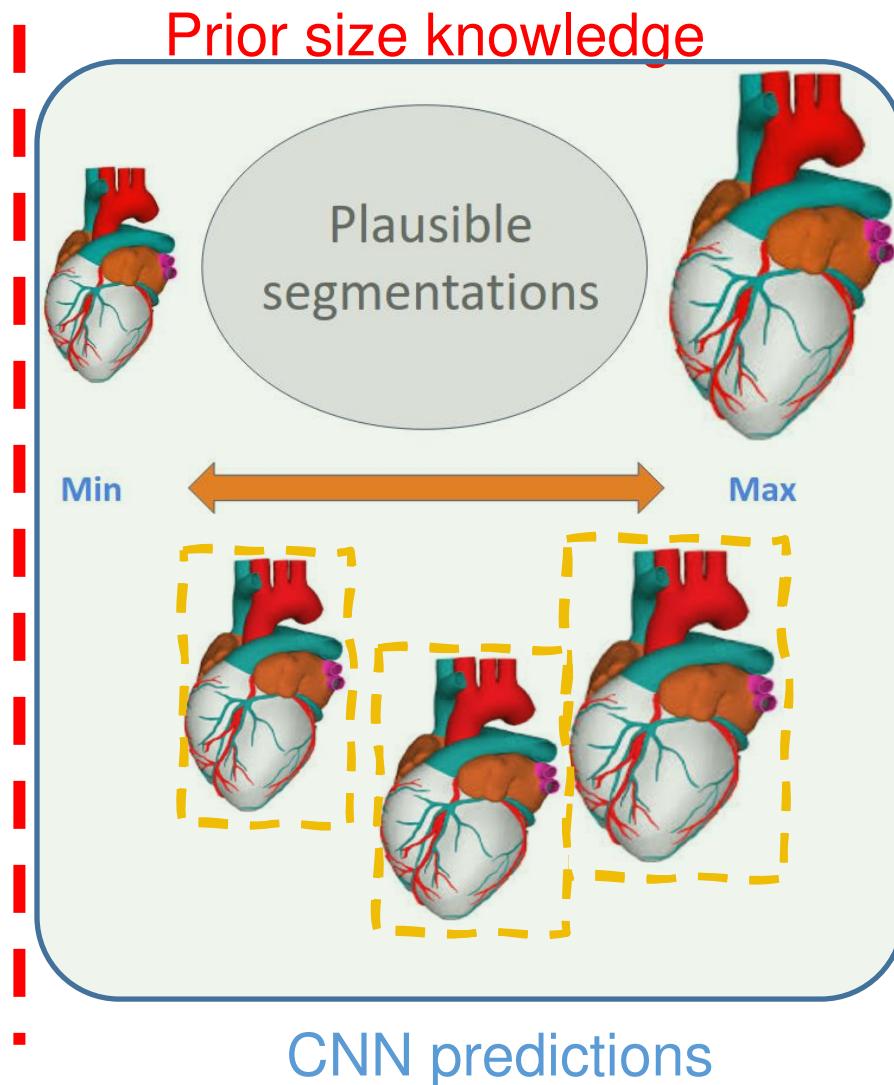
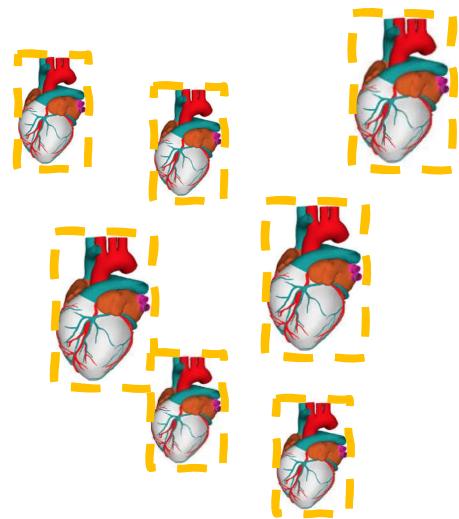
A<B,  
A>B,  
B1 < A < B2



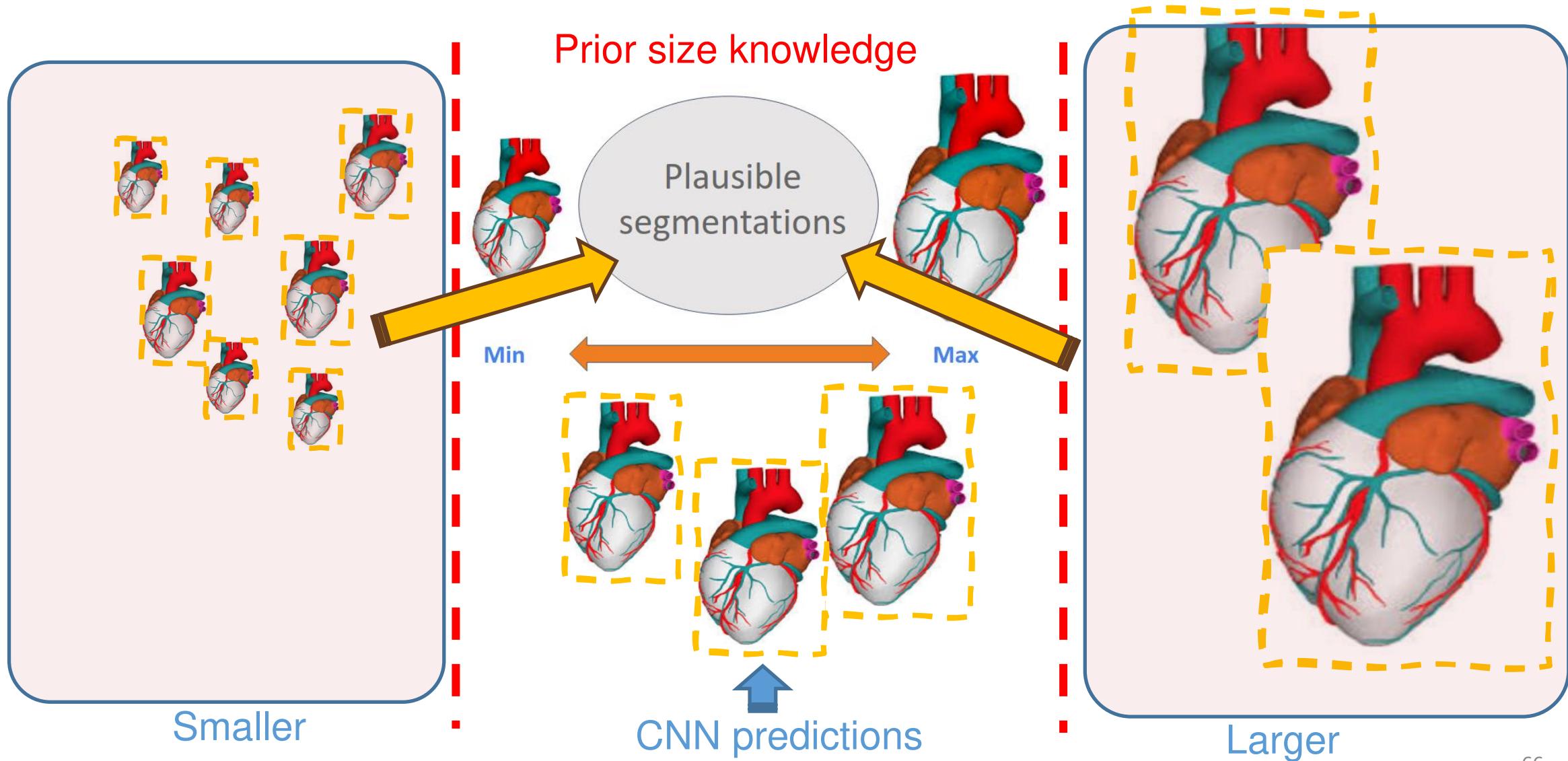
# Inequality constraints



# Inequality constraints



# Inequality constraints



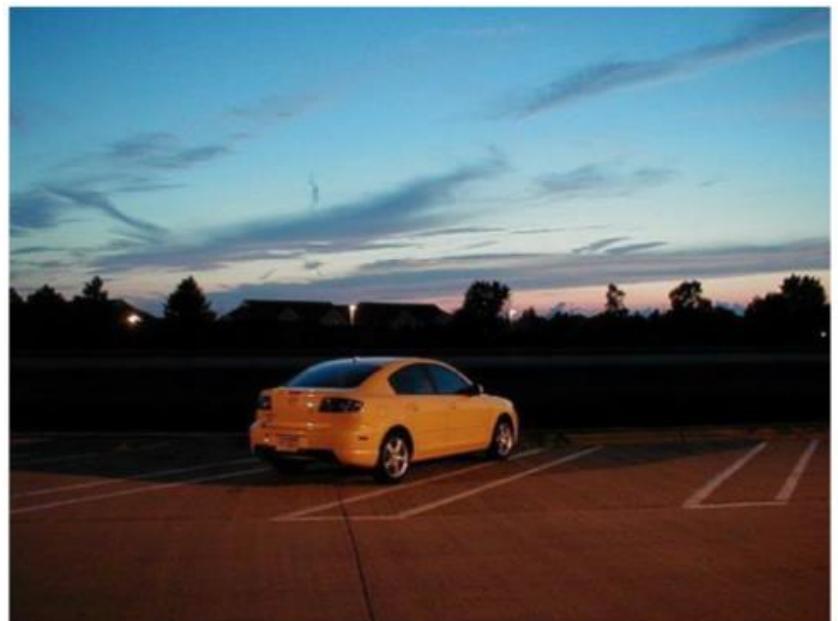
# Inequality constraints

Information is given in  
the form of image-tags

Suppression

$$\sum_{p \in \Omega} s_{\theta}^{p,c} \leq 0 \quad \forall c \notin C$$

“Person”



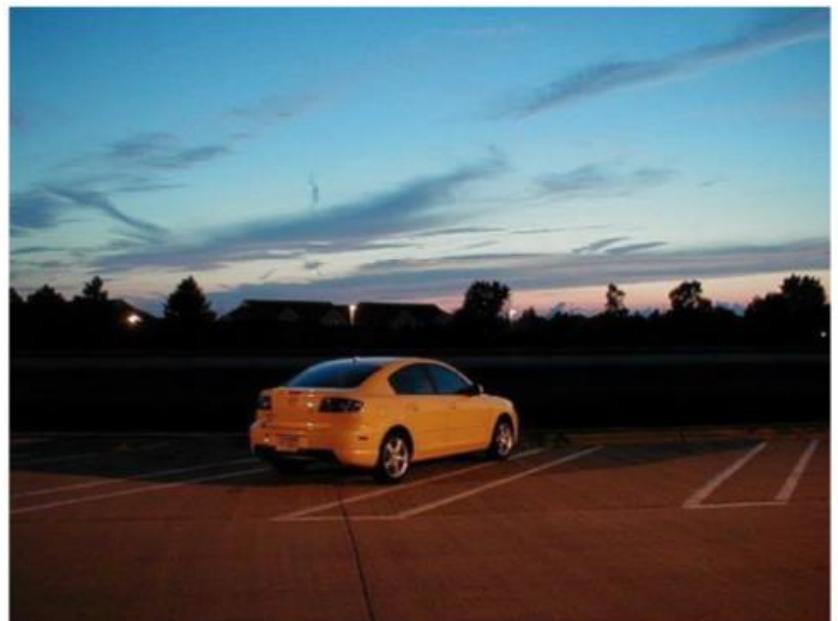
# Inequality constraints

Information is given in  
the form of image-tags

**Inclusion  
(or existence)**

$$\sum_{p \in \Omega} s_{\theta}^{p,c} \geq 1 \quad \forall c \in C$$

“Car”



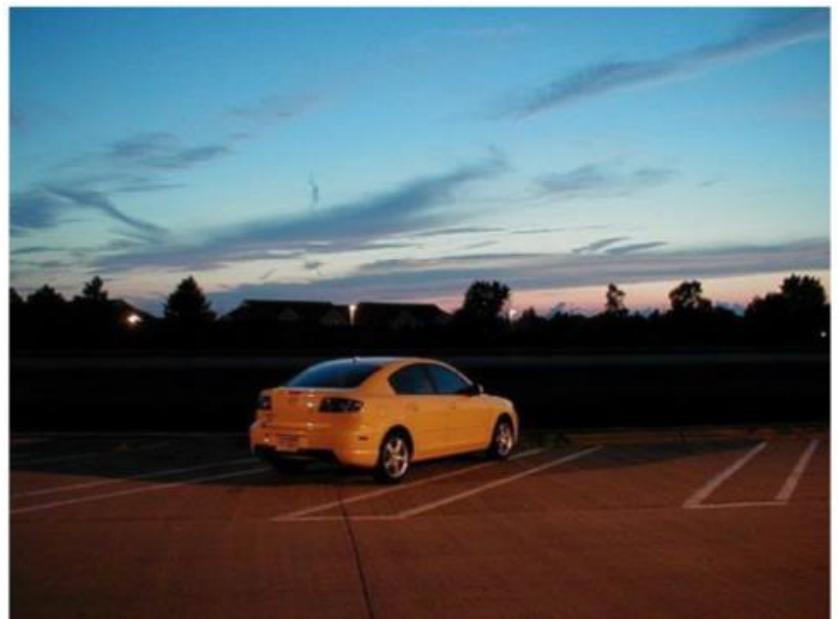
# Inequality constraints

Information is given in  
the form of image-tags

**Target Size**  
 $a > 1$

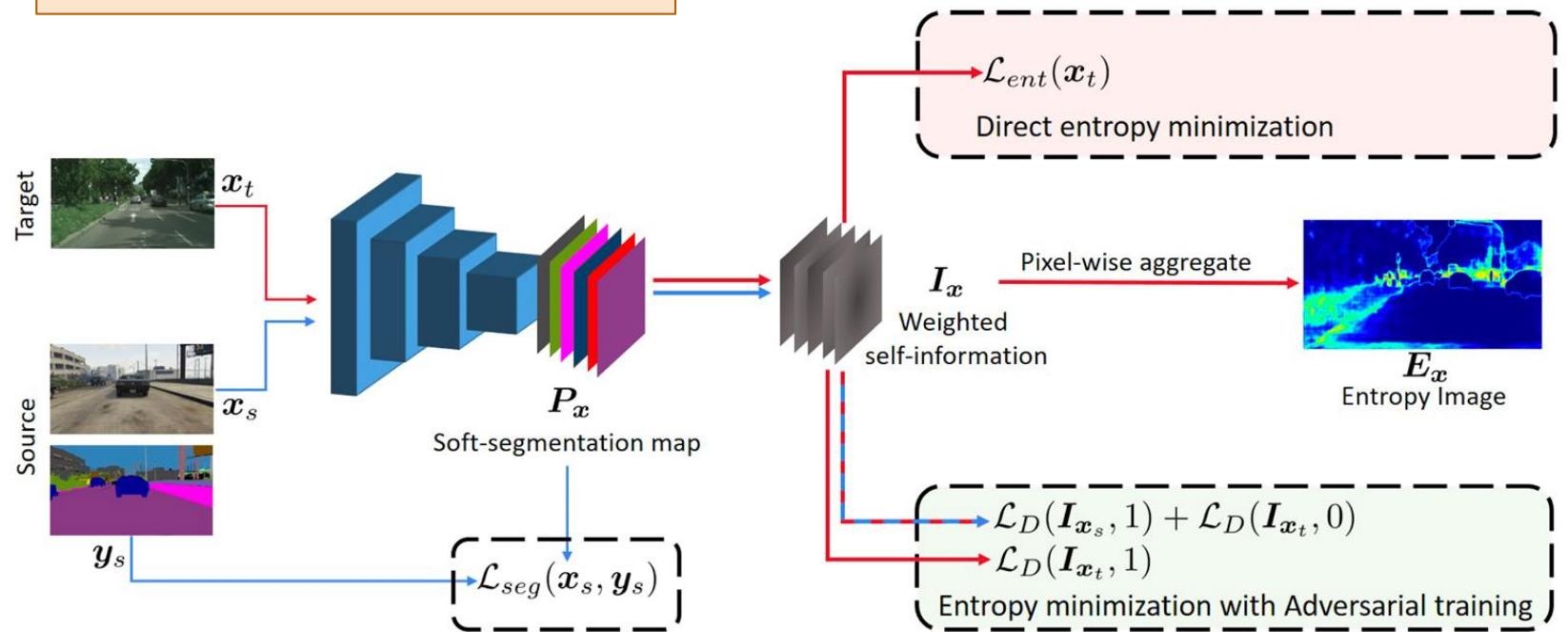
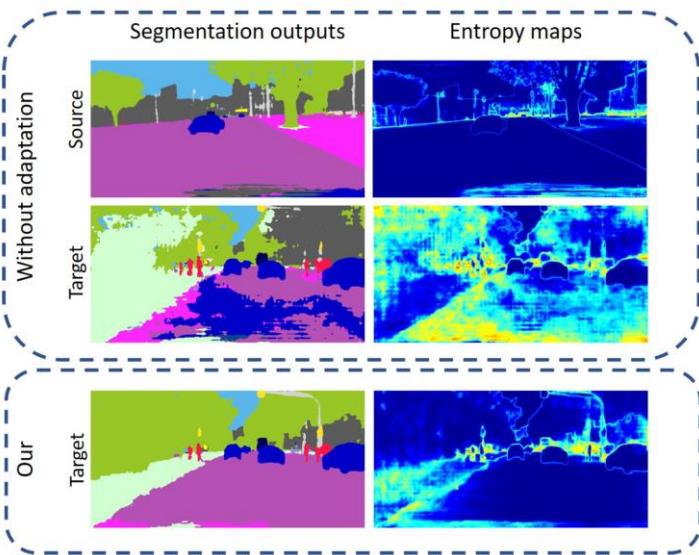
$$\sum_{p \in \Omega} s_{\theta}^{p,c} \geq a \quad \forall c \in C$$

“Car”



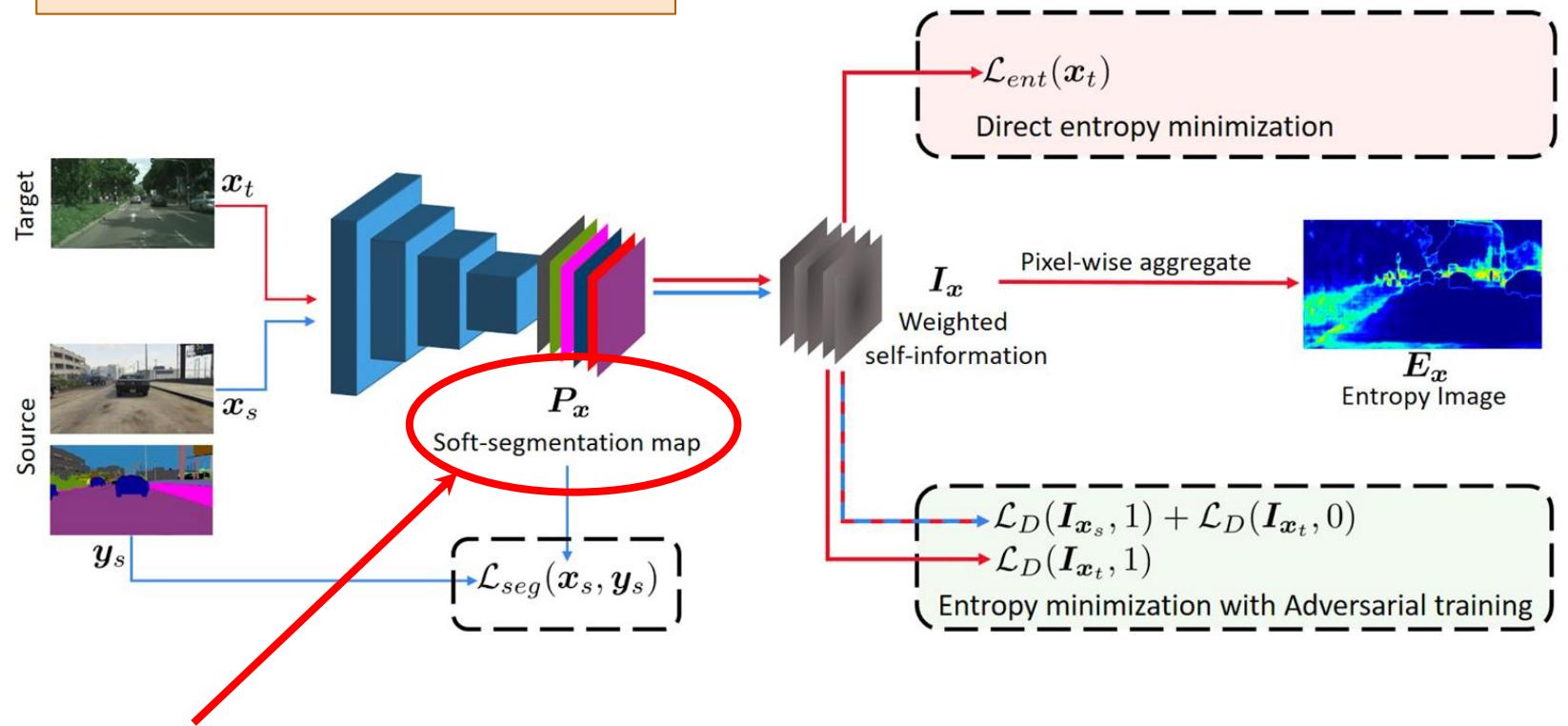
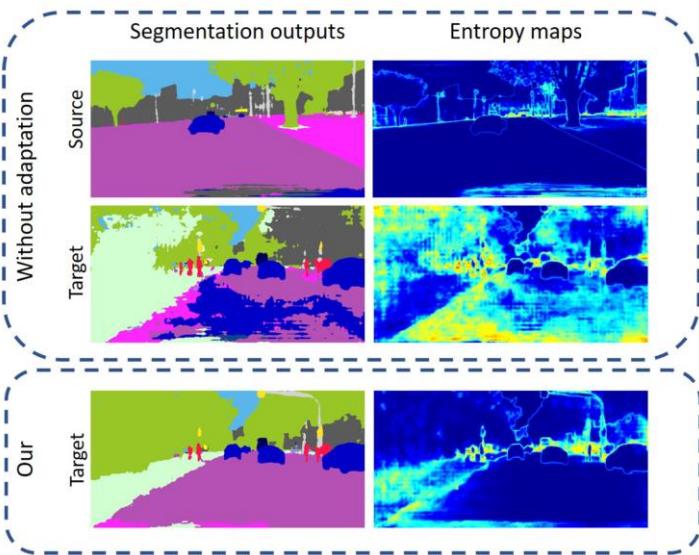
# Inequality constraints

Information (proportion)  
is given as a prior



# Inequality constraints

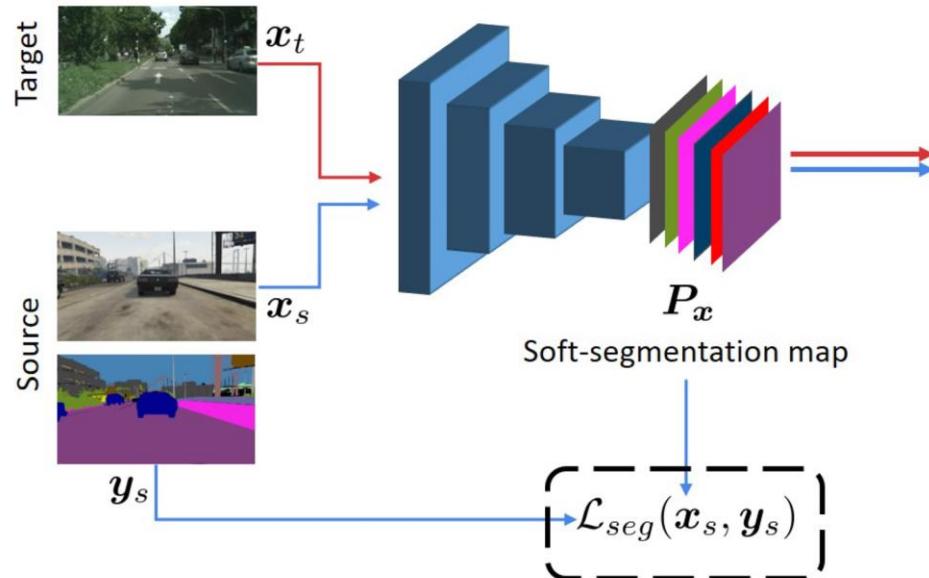
Information (proportion)  
is given as a prior



We focus on this now

# Inequality constraints

Information (proportion)  
is given as a prior



Class-ratio priors

It relaxes the class prior  
constraint

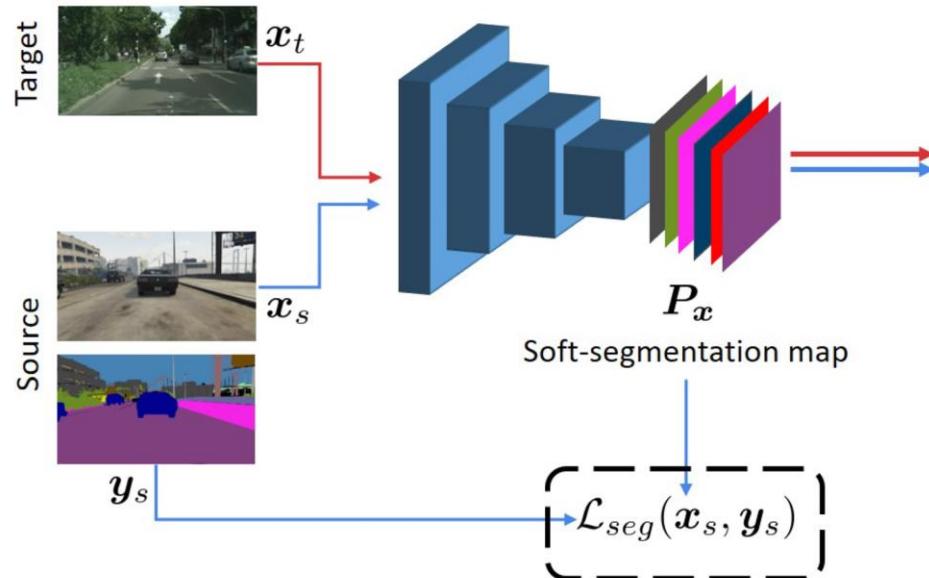
$\ell 1$ -normalized histogram (source)

$$\mathcal{L}_{cp}(\mathbf{x}_t) = \sum_{c=1}^C \max(0, \mu p_s^{(c)} - \mathbb{E}_c(P_{\mathbf{x}_t}^{(c)}))$$

Estimated size on the prediction

# Inequality constraints

Information (proportion)  
is given as a prior



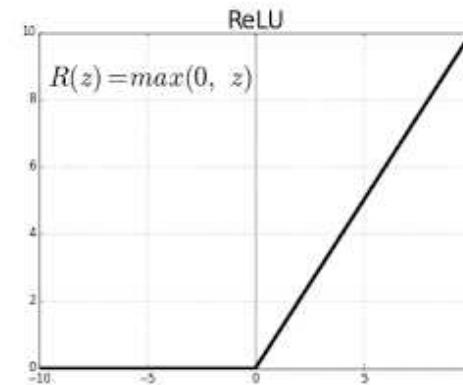
Class-ratio priors

It relaxes the class prior  
constraint

$$\mathcal{L}_{cp}(x_t) = \sum_{c=1}^C \max(0, \mu p_s^{(c)} - \mathbb{E}_c(P_{x_t}^{(c)}))$$

Estimated size on the prediction

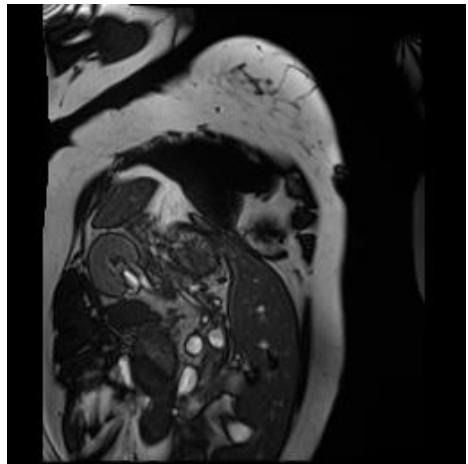
$\ell 1$ -normalized histogram (source)



# Inequality constraints

How we can benefit from this in the medical domain?

No cavity



Cavity

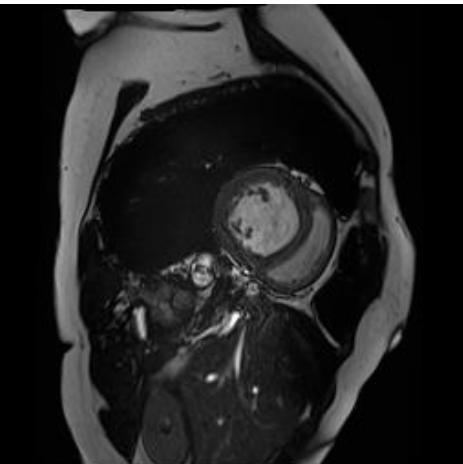


Image-tag information

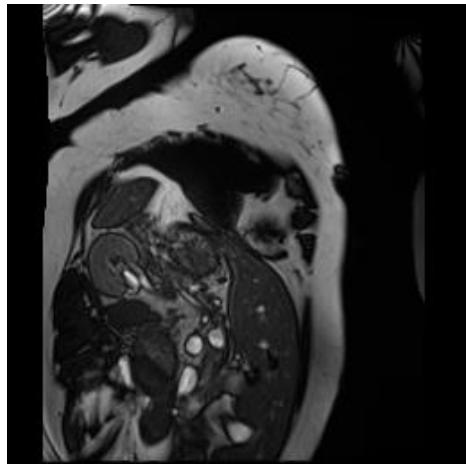
$$\sum_{p \in \Omega} s_{\theta}^{p,c} \leq 0$$

For negative image tags

# Inequality constraints

How we can benefit from this in the medical domain?

No cavity



Cavity

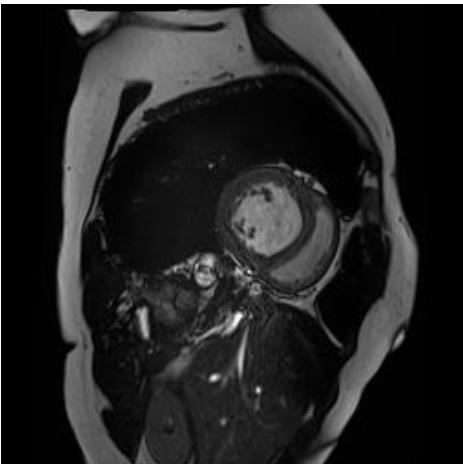
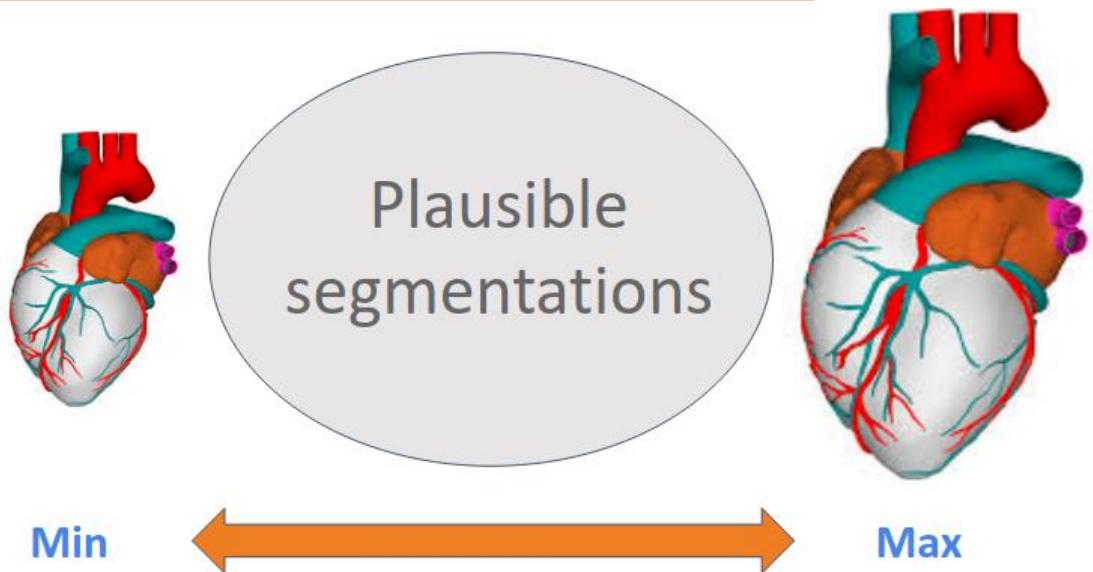


Image-tag information

$$\sum_{p \in \Omega} s_{\theta}^{p,c} \leq 0$$

For negative image tags

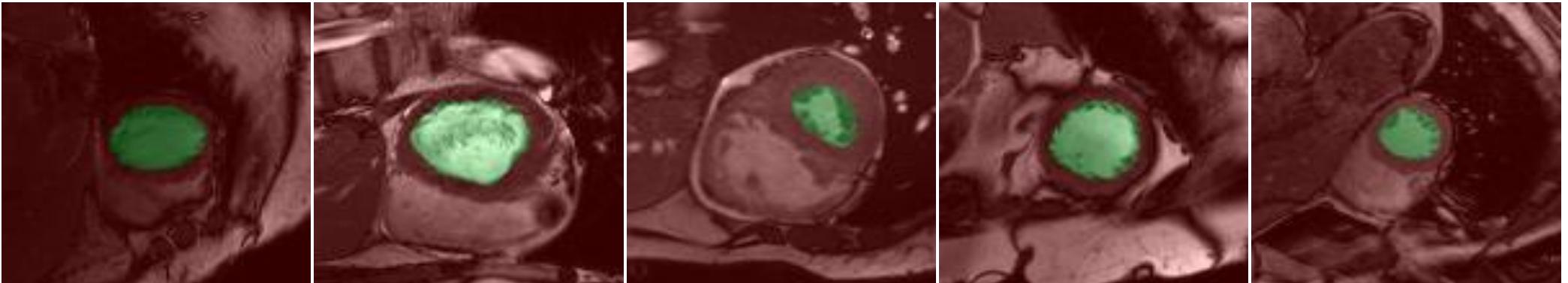


$$\min \leq \sum_{p \in \Omega} s_{\theta}^{p,c} \leq \max$$

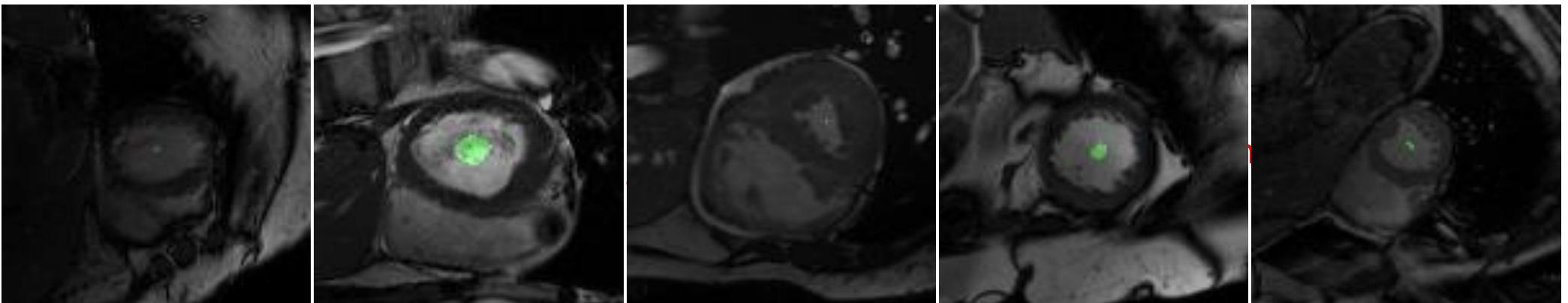
For positive image tags

# Inequality constraints

L2 Penalty



Full annotations



Partial annotations for cross-entropy

# Inequality constraints

## L2 Penalty

Objective

$$\min_{\theta} \mathcal{H}(S) \quad \text{s.t.} \quad a \leq \sum_{p \in \Omega} s_{\theta}^{p,c} \leq b \quad \rightarrow \quad \mathcal{H}(S) + \lambda \mathcal{C}(V_S)$$

# Inequality constraints

## L2 Penalty

### Objective

$$\min_{\theta} \mathcal{H}(S) \quad \text{s.t.} \quad a \leq \sum_{p \in \Omega} s_{\theta}^{p,c} \leq b \quad \rightarrow \quad \mathcal{H}(S) + \lambda \mathcal{C}(V_S)$$

$$\mathcal{H}(S) = - \sum_{p \in \mathcal{L}} \log(s_{\theta}^p)$$

On annotated pixels

# Inequality constraints

## L2 Penalty

Objective

$$\min_{\theta} \mathcal{H}(S) \quad \text{s.t.} \quad a \leq \sum_{p \in \Omega} s_{\theta}^{p,c} \leq b \quad \rightarrow \quad \mathcal{H}(S) + \lambda \mathcal{C}(V_S)$$

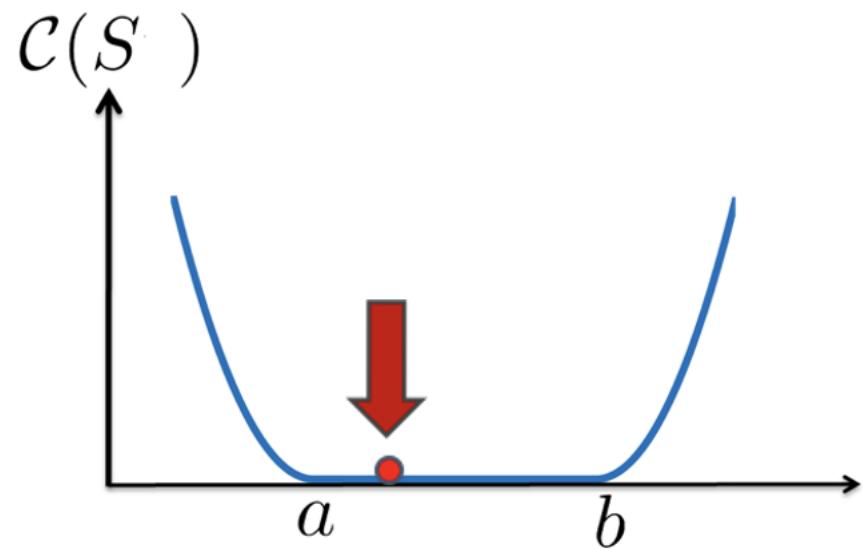
$$\mathcal{H}(S) = - \sum_{p \in \mathcal{L}} \log(s_{\theta}^p)$$

On annotated pixels

$$\mathcal{C}(V_S) = \begin{cases} (V_S - a)^2, & \text{if } V_S < a \\ (V_S - b)^2, & \text{if } V_S > b \\ 0, & \text{otherwise} \end{cases}$$

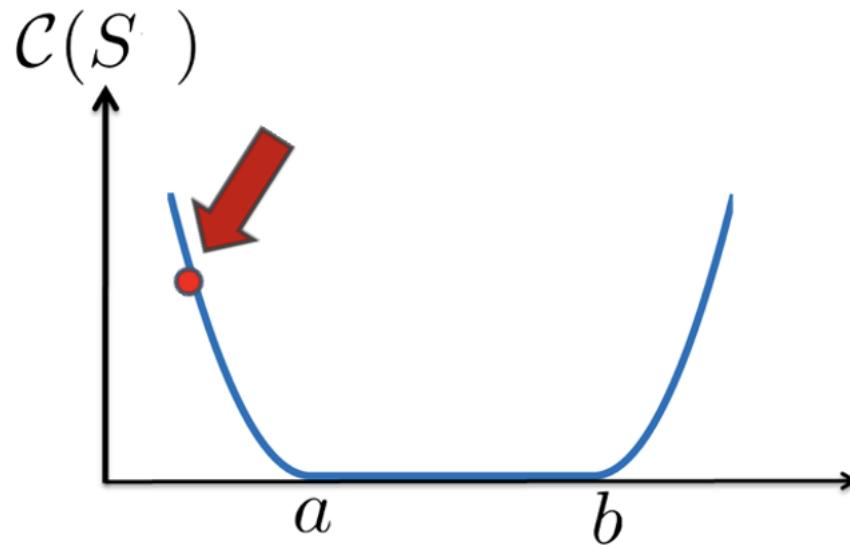
# Inequality constraints

L2 Penalty



Constraint A satisfied

Visual intuition



Constraint B violated

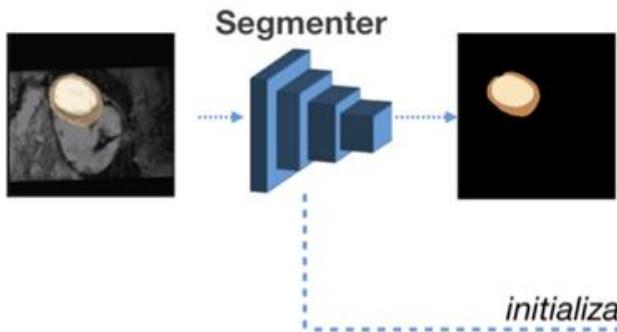
# Inequality constraints

L2 Penalty

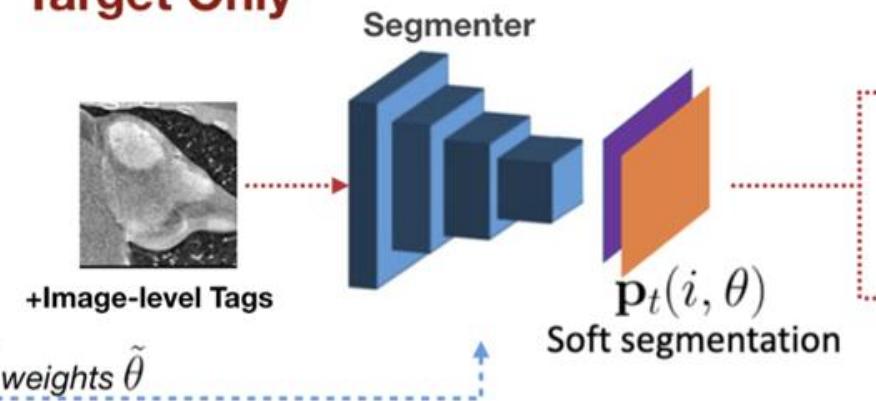
Source-free Domain Adaptation

Source Training phase

Source Only



Target Only



Target Adaptation phase

Class-ratio from approximate anatomical knowledge  
 $\tau_e(t, k)$

Class-ratio loss  
 $\lambda KL(\hat{\tau}(t, k, \theta), \tau_e(t, k))$

Direct entropy minimisation  
 $\sum_{i \in \Omega_t} \ell_{ent}(\mathbf{p}_t(i, \theta))$

# Inequality constraints

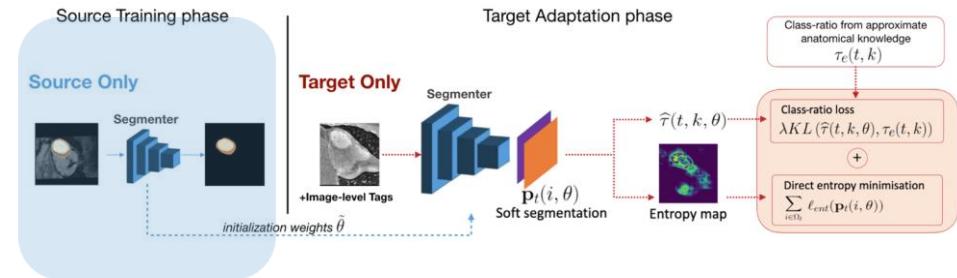
## L2 Penalty

Source-free: no access to source data when adapting

1-Train the network on  
the source domain

$$\min_{\theta} \sum_{p \in \mathcal{L}} l(\mathbf{y}^p, \mathbf{s}_{\theta}^p)$$

↑  
Set of labeled  
SOURCE pixels



# Inequality constraints

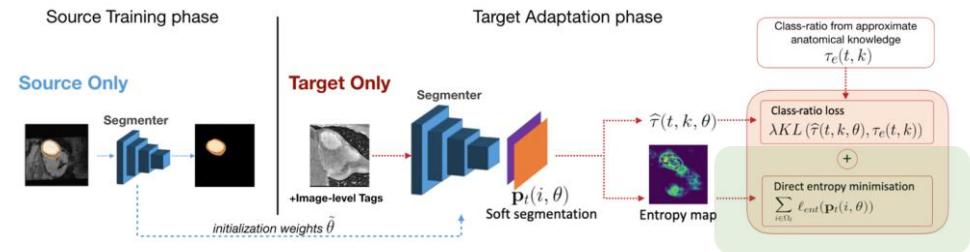
## L2 Penalty

Source-free: no access to source data when adapting

2-Adapt the model  
without accessing  
the source data

$$\mathcal{L}_{\mathcal{H}} = - \sum_{p \in \mathcal{T}} \sum_k \mathbf{s}_{\theta}^{p,k} \log \mathbf{s}_{\theta}^{p,k} + \mathcal{D}_{KL}(\hat{\tau}, \tau_e)$$

Minimize entropy on predicted  
TARGET pixels



# Inequality constraints

## L2 Penalty

Source-free: no access to source data when adapting

2-Adapt the model without accessing the source data

$$\mathcal{L}_H = - \sum_{p \in \mathcal{T}} \sum_k s_\theta^{p,k} \log s_\theta^{p,k} + \mathcal{D}_{KL}(\hat{\tau}, \tau_e)$$

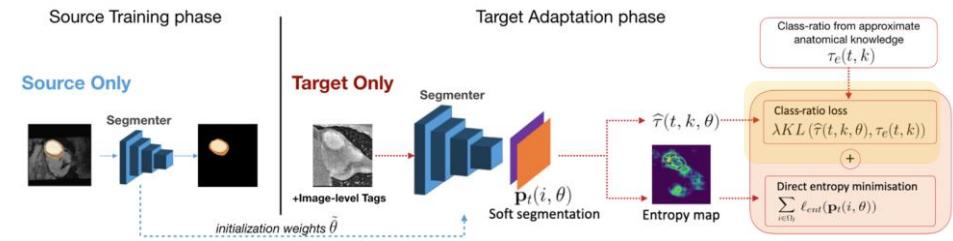
Minimize entropy on predicted TARGET pixels

$$\tau_e(t, k) \quad \hat{\tau}(t, k, \theta) = \frac{1}{|\Omega_t|} \sum_{i \in \Omega_t} s_\theta^{i,k}$$

Size regularizer

Estimated size by an auxiliary network trained on the source

Computed size from the segmentation of the target image



# Inequality constraints

L2 Penalty

But we can do more than simply the size

Shape moment  $\mu_{p,q}^{(k)}(s_{\theta}) := \sum_{i \in \Omega} s_{\theta}^{(i,k)} x_{(i)}^p y_{(i)}^q,$

Central moment  $\bar{\mu}_{p,q}^{(k)} := \sum_{i \in \Omega} s_{\theta}^{(i,k)} \left( x_{(i)} - \frac{\mu_{1,0}^{(k)}}{\mu_{0,0}^{(k)}} \right)^p \left( y_{(i)} - \frac{\mu_{0,1}^{(k)}}{\mu_{0,0}^{(k)}} \right)^q.$

# Inequality constraints

L2 Penalty

But we can do more than simply the size

From shape and central moment

Volume

$$\mathfrak{V}^{(k)}(s_{\theta}) := \mu_{0,0}^{(k)}(s_{\theta}).$$

Centroid

$$\mathfrak{C}^{(k)}(s_{\theta}) := \left( \frac{\mu_{1,0}^{(k)}(s_{\theta})}{\mu_{0,0}^{(k)}(s_{\theta})}, \frac{\mu_{0,1}^{(k)}(s_{\theta})}{\mu_{0,0}^{(k)}(s_{\theta})} \right).$$

Length

$$\mathfrak{L}^{(k)}(s_{\theta}) := \sum_{i,j \in \mathcal{G}_{\Omega}} |s_{\theta}^{(i,k)} - s_{\theta}^{(j,k)}| L_{\Omega,i,j}.$$

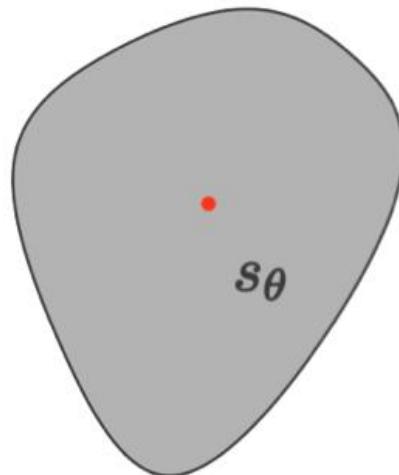
Laplacian

# Inequality constraints

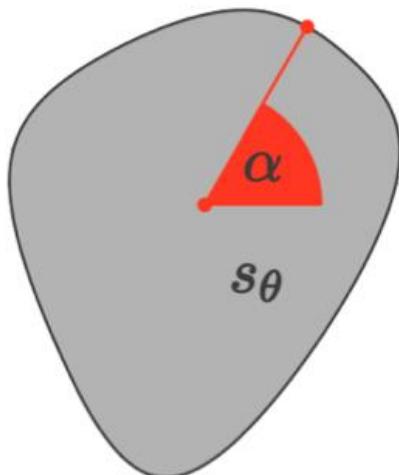
L2 Penalty

But we can do more than simply the size

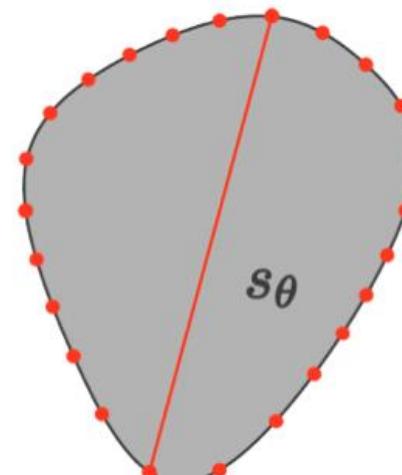
From shape and central moment



(a) Centroid  $\mathfrak{C}(s_\theta)$



(b) Radius  $\widehat{\mathfrak{R}}_\beta(s_\theta, \alpha)$



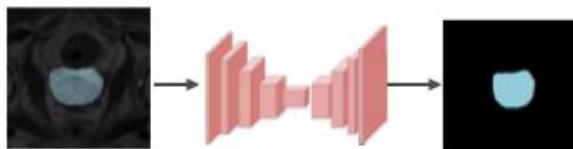
(c) Diameter  $\mathfrak{D}(s_\theta)$

# Inequality constraints

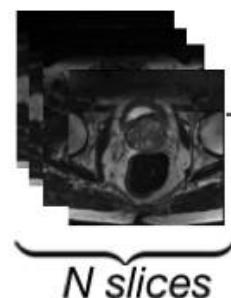
L2 Penalty

Test-Time Adaptation (TTA)

Source Training

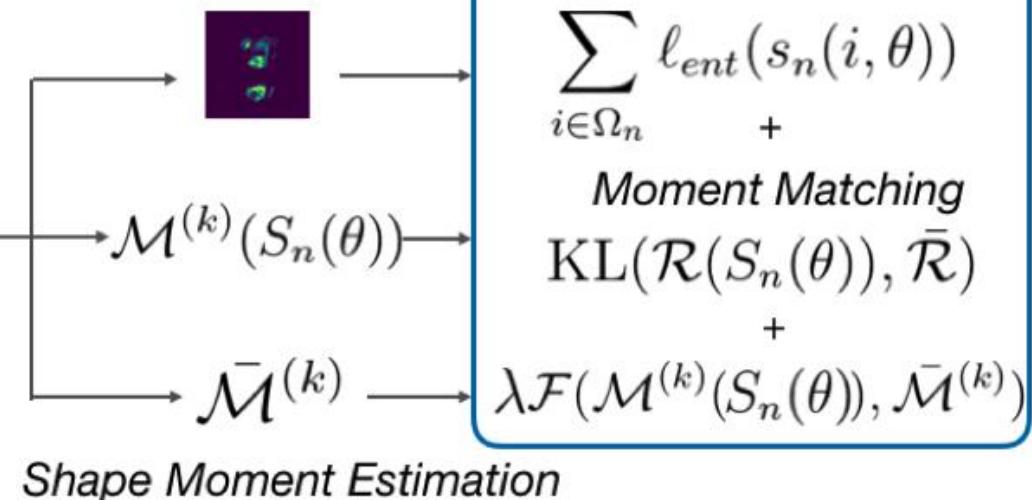


One Target Subject



initialization weights  $\tilde{\theta}$

Test-Time Adaptation with Single Target Image



# Take-home message

- Imposing constraints helps weakly-supervised segmentation learning by restricting plausible segmentations on weakly labeled and unlabeled images
- Few constraints have been explored under low-labeled data regime
- Room for improvement (many opportunities beyond weakly supervised segmentation)

Thank you!