

Yunzhe Jonas Li

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EDUCATION

University of California, Berkeley, GPA - 3.85/4

2024-2025

M.ENG., Electrical Engineering and Computer Sciences in Robotics.

Berkeley, CA

Coursework - 3D Computer Vision, Deep Learning for Computer Vision, Introduction of Robotics, Data Science, Agentic LLMs

Capstone Project - Optimization of Modularized Robot Design in Complex Scenes. Advisor: Prof. Masayoshi Tomizuka, Dr. Wei Zhan

Shanghai University, Rank - Top 1, GPA - 92.59/100

2020-2024

B.ENG., Computer Science.

Shanghai, China

WORK EXPERIENCE

Momenta | Software Engineer Intern

Jan 2024 - Jul 2024

- Delivered the first version of an autopilot **reversing feature** for **GM Cadillac LYRIQ** in parking lots, covering the **full product lifecycle**
- Developed a stuck-state detection benchmarking stack for reversing maneuver, integrating classification and precision-recall analysis
- Evaluated 800+ real parking test cases in 30+ garages over 4 months, enhancing collision-free reversing performance by **3%**
- Optimized threshold-based stuck-state detection by integrating SVM, refining borderline cases and reducing false positives by 15%
- Slashed workload for 4 product managers across 4 vehicle projects from **120min/day to 10 min/day** by automating data processing and report generation for 36,000+/day simulation test records evaluation, streamlining success rate analysis

DJI RoboMaster | [Git repo](#) | [Video](#)

Team Lead

2022-2024

- Led a 40-student team to deliver **8** fully functional robots **from scratch**, winning the **3rd place** in RoboMaster 2023
- Gained **US\$20,000** in sponsorship by improving shooting, motion control, and detection through **7000+ test iterations**

Co-Head of Robot Computer Vision

2020-2022

- Developed an adaptive vision pipeline for **real-time** auto aiming, integrating camera calibration, image preprocessing, YOLOv7 detection, object tracking, and fire control, earning **promotion** for code contributions and troubleshooting
- Boosted detection accuracy by 25%, upgrading from pure OpenCV detection to an OpenCV + **YOLOv7** hybrid system
- Initiated a non-linear least squares based tracking algorithm for planar rotating object in parametric sinusoidal speed, integrating pitch-yaw angle computation based on geometry for precise targeting, outperforming **90%** competitors in hit rate
- Refactored the system from **Python to C++** with 5 peers, achieving **60 fps** on NVIDIA NX and **80 fps** on NVIDIA AGX

FIRST Tech Challenge | [Team Documentary](#) | Team Lead

2017-2020

- Bent the performance of a 15-member team, leading to **2 FIRST World Championships admissions**(top 2 % out of 7500 teams globally), **1 Inspire Award**(1st out of 40 teams), and **3 Connect Awards**(top 8% out of 60 teams)
- Developed an autonomous system using multiple sensors and **OpenCV/TensorFlow SDK**, achieving **95%+** detection accuracy and securing the **highest** Regional score with rule-based human driver imitating strategies

RESEARCH - National Natural Science Foundation of China

Visual Explainer For Deep Learning Image Classification (No.61936001) | [Git repo](#) | [Video](#)

2023-2024

- Designed a 2-stage **semantic segmentation** pipeline and an **AutoEncoder** with tree constraints, using Shapley Values to extract and rank concepts by importance, boosting explanation consistency score by 35% on 1000+ images from 20 **ImageNet** classes
- Developed a **Django backend APIs** for page navigation, handling **GET** and **POST** requests, and efficient data retrieval
- Built a **Vue.js frontend** with user authentication, image segmentation, and contribution heatmap visualization

Mining Property Relations of NASICON Solid Electrolyte (No.52073169)

2021-2022

- Developed a **BERT-based** pipeline to extract 106,896 entities and 260,475 entity-relation triples from 1,808 research papers, storing results in Neo4j and MySQL for knowledge discovery
- Optimized the NER model by labeling 7,000+ high-quality sentences, improving precision by 5%, recall by 3%, and F1-score by 4%

Selected Projects

3D Vision and IMU-aided TurtleBot Recovery | [Website](#) | ROS2, OpenCV, Feature-matching, 3D transformation, RealSense

- Developed a ROS2-based pipeline to correct positional drift, integrating IMU data, RealSense D435i images, and feature-matching
- Engineered an image-based transformation module, computing relative pose difference based on depth feature correspondences

MealMate: From Cravings to Carts | [Git repo](#) | [Video](#) | LLM, Flask, React.js, Python, HTML&CSS

- Designed an **LLM-powered assistant** to generate tailored shopping lists using user preferences and real-time inventory
- Benchmarked GPT-4o-mini against GPT-4 and GPT-3.5-turbo for LLM agent performance, demonstrating 20% higher recipe match precision and 40% suggestion accuracy, and 42% faster processing time
- Built a showcase using **React.js** for the frontend and **Flask** for the backend with effective prompts and transaction logic

Sawyer Arm Control Performed pick-place tasks using **MovelIt** and **ROS2**, applying kinematics, trajectory planning, and AR tag detection

Abstract: Your LeetCode Learning Assistant Developed a **LLM-based tool** to summarize and retain key solution patterns for review