

# LAB3 MATLAB Programming

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## 目录

Introduction.....	1
Results and Analysis.....	1
3.8.....	1
(a).....	2
(b).....	3
(C).....	4
(d).....	5
(e).....	6
(f).....	7
3.10.....	9
(a).....	9
(b).....	9
(c).....	10
(d).....	12
(e).....	12
(f).....	13
(g).....	14
(h).....	15
(i).....	17
Function.....	18
Experience.....	18

## Introduction

In this lab assignment, we learned about :

- 1.Usage and scenarios of fft() and ifft() functions in MATLAB
- 2.The concept of algorithmic time complexity
- 3.Try to call the above functions to analyse the signal in the frequency domain.
- 4.Understand the effect of filters on signals
- 5.Compare the time impact of using different algorithmic strategies to deal with real-world problems.

## Results and Analysis

### 3.8

This exercise demonstrates the effect of first-order recursive discrete-time filters on periodic signals. You will examine the frequency responses of two different systems and construct a periodic signal to use as input for these systems. This exercise assumes you are familiar with using `fft` and `ifft` to compute the DTFS of a periodic signal as described in Tutorial 3.1. In addition, it is also assumed you are proficient with the `filter` and `freqz` commands described in Tutorials 2.2 and 3.2. Several parts of this exercise will generate vectors which should be purely real, but have very small imaginary parts due to roundoff errors. Use `real` to remove these residual imaginary parts from the vectors.

This exercise focuses on two causal LTI systems described by first-order difference equations:

$$\begin{aligned}\text{System 1: } y[n] - 0.8y[n-1] &= x[n], \\ \text{System 2: } y[n] + 0.8y[n-1] &= x[n].\end{aligned}$$

The input signal  $x[n]$  will be the periodic signal with period  $N = 20$  described by the following coefficients

$$a_k = \begin{cases} 3/4, & k = \pm 1, \\ -1/2, & k = \pm 9, \\ 0, & \text{otherwise.} \end{cases}$$

(a)

(a). Define vectors `a1` and `b1` for the difference equation describing System 1 and `a2` and `b2` for System 2. Use `filter` and `freqz` to compute the frequency responses of the systems. Similarly, define `a2` and `b2` to describe System 2.

In Matlab, the coefficients at the output and input of the system are recorded using `ai`, `bi`, respectively. For the system in this question, we have `a1=[1 -0.8]`, `a2=[1 0.8]`, `b1=b2=1`

```
%System 1
a1=[1 -0.8];
b1=1;
y1=filter(b1,a1,x);
```

```
%System 2
a2=[1 0.8];
b2=1;
y2=filter(b2,a2,x);
```

(b)

- (b). Use `freqz` to evaluate the frequency responses of Systems 1 and 2 between 0 and  $2\pi$ . Note that you will have to use the 'whole' option to do this. Use `plot` and `abs` to generate appropriately labeled graphs of the frequency response for both systems. Based on the frequency response, specify whether each system is a highpass, lowpass, or bandpass filter.

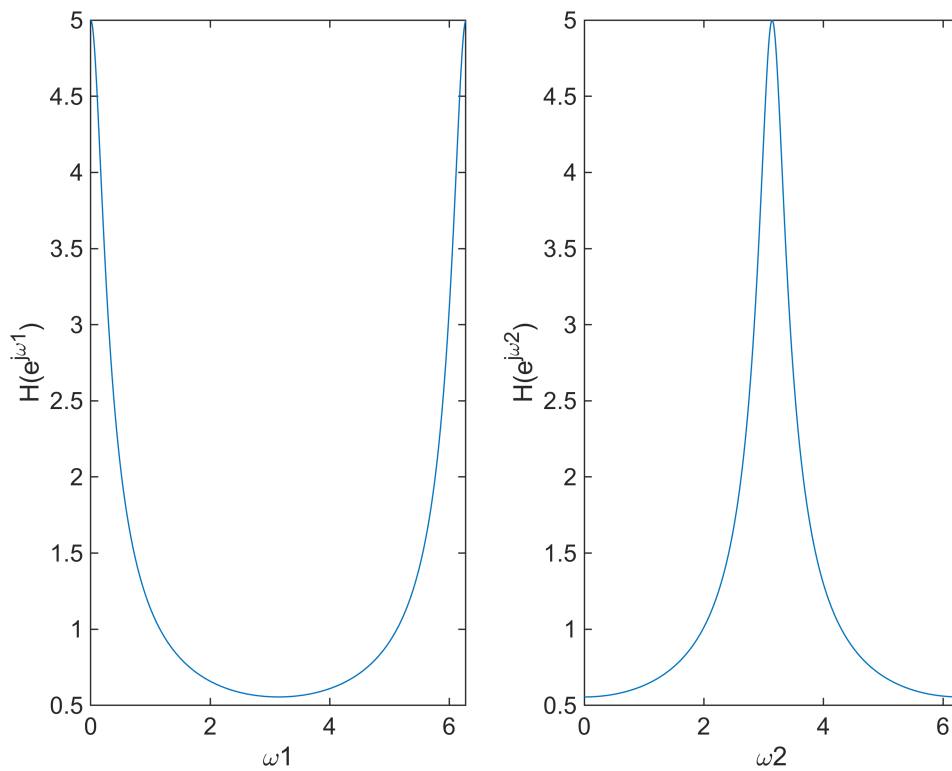
n=1024

```
n=1024
```

```
n = 1024
```

```
%System 1
a1=[1 -0.8];
b1=1;
[H1, Omega1]=freqz(b1,a1,n,'whole');
subplot(1,2,1);
plot(Omega1,abs(H1));
xlabel('\omega_1');ylabel('H(e^{j\omega_1})');

%System 2
a2=[1 0.8];
b2=1;
[H2, Omega2]=freqz(b2,a2,n,'whole');
subplot(1,2,2);
plot(Omega2,abs(H2));
xlabel('\omega_2');ylabel('H(e^{j\omega_2})');
```



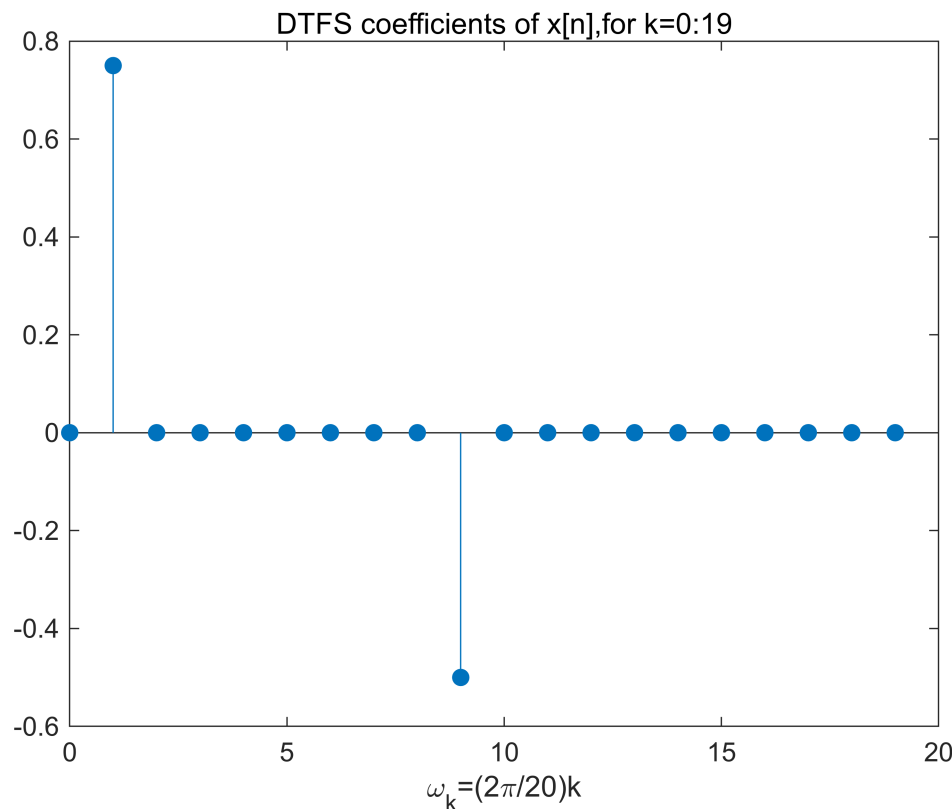
From the image, system 1 is a low pass filter and system 2 is a high pass filter.

(C)

- (c). Use Eq. (3.10) to define the vector  $\mathbf{a}_x$  to be the DTFS coefficients of  $x[n]$ . Generate a plot of the DTFS coefficients using `stem` where the x-axis is frequency  $\omega_k = (2\pi/20)k$ . Compare this plot with the frequency response generated in Part (b), and for each system state which frequency component is amplified and which will be attenuated when  $x[n]$  is the input to the system.

Create the vector  $\mathbf{a}_x$  and graph it

```
clear; clc; close all;
a_x = zeros(1, 20);
a_x(2) = 3/4;
a_x(10) = -0.5;
stem(0:19, a_x, 'filled');
title('DTFS coefficients of x[n], for k=0:19');
xlabel('\omega_k=(2\pi/20)k');
```



System 1 will amplify component  $k=1$  and attenuate component  $k=9$ . System 2 will do the opposite..

(d)

- (d). Define  $\mathbf{x\_20}$  to be one period of  $x[n]$  for  $0 \leq n \leq 19$  using `ifft` with in Tutorial 3.1. Use  $\mathbf{x\_20}$  to create  $\mathbf{x}$ , consisting of 6 periods of  $x[n]$  for Also define  $\mathbf{n}$  to be this range of sample indices, and generate a plot interval using `stem`.

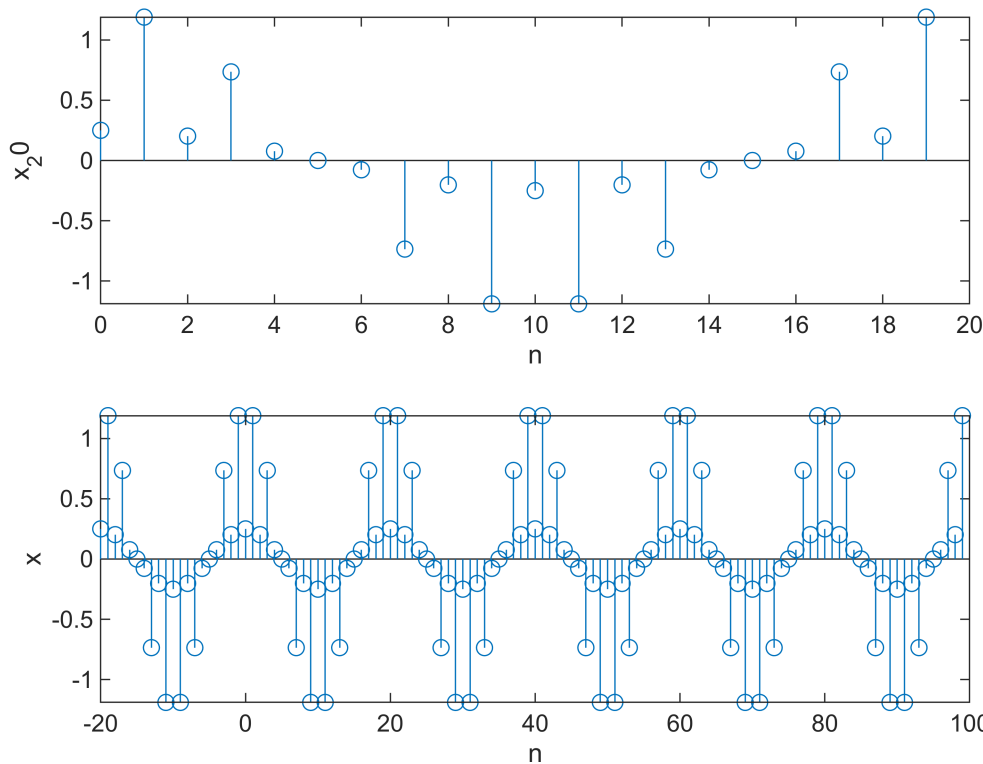
Use the `ifft` function to represent  $\mathbf{x\_20}$ , then use the `repmat` function to record the value of  $\mathbf{x}$  over multiple cycles for the graph.

```
x_20 = ifft(a_x) * length(a_x);
n = -20: 99;

%plot;
subplot(2,1,1);
stem(0:19,real(x_20));
xlabel('n');ylabel('x_20');

x=real(repmat(x_20,1,6));
subplot(2,1,2);
stem(n,x);
```

```
xlabel('n');
ylabel('x');
```



(e)

- (e). Use `filter` to compute  $y_1$  and  $y_2$ , the outputs of Systems 1 and 2 with input  $x$ . Plot both outputs for  $0 \leq n \leq 99$  using `stem`. Based on the plots, determine which output contains more high frequency energy and which has more low frequency energy. Do the plots confirm your answers in Part (c)?

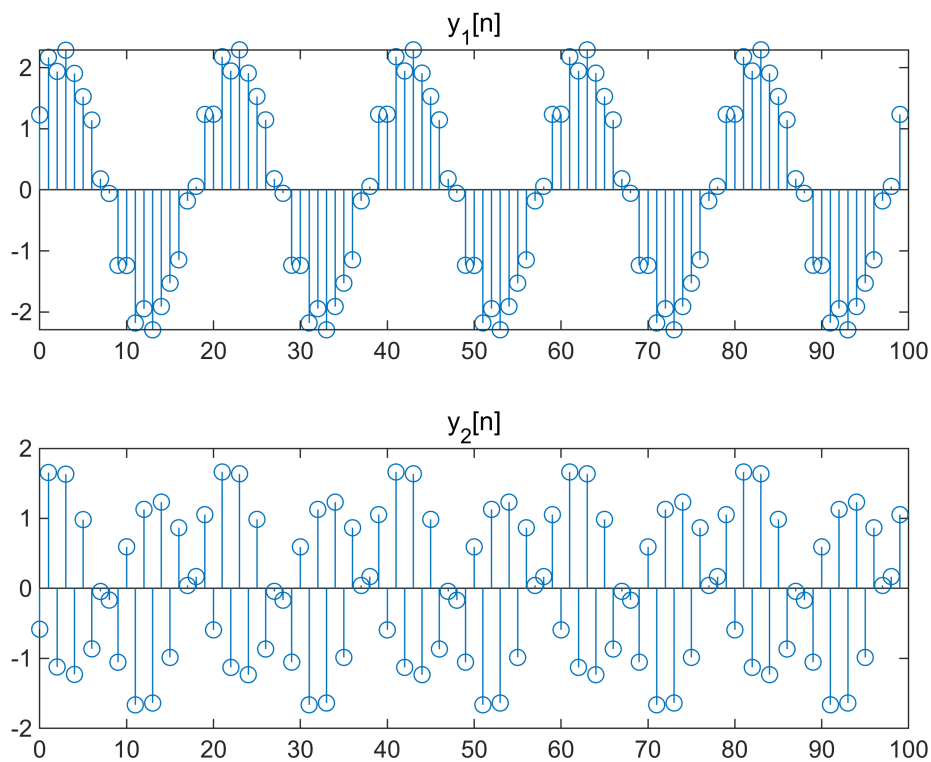
Use the filter function to obtain the output signals  $y_1$ ,  $y_2$  and graph them.

```
clear; clc; close all;
a_x = zeros(1, 20);
a_x(2) = 3/4;
a_x(10) = -0.5;
x_20 = ifft(a_x) * length(a_x);
x = real(repmat(x_20, 1, 6));
%System 1
a1 = [1 -0.8];
b1 = 1;
y1 = filter(b1, a1, x);
```

```

%System 2
a2=[1 0.8];
b2=1;
y2=filter(b2,a2,x);
n=-20:99;
subplot(2, 1, 1);
stem(n, y1);
xlim([0, 100]);
title('y_1[n]');
subplot(2, 1, 2);
stem(n, y2);
xlim([0, 100]);
title('y_2[n]');

```



$y_1$  has more low frequency energy.  $y_2$  has more high frequency energy. It confirmed the answers in part c.

(f)

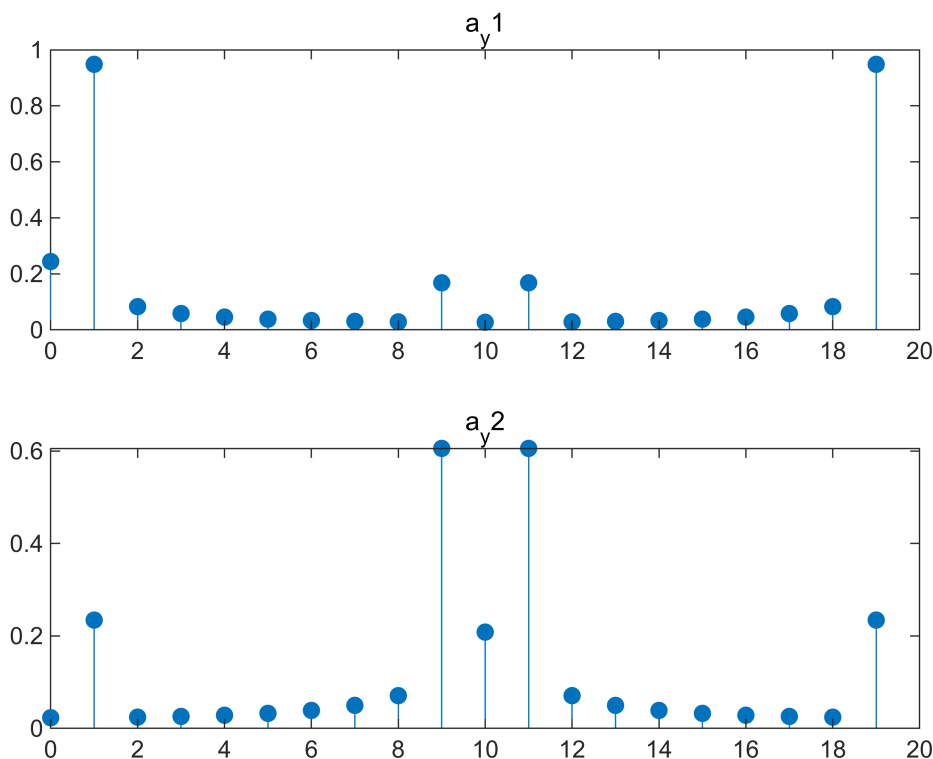


(f). Define  $y1\_20$  and  $y2\_20$  to be the segments of  $y1$  and  $y2$  corresponding to  $y_2[n]$  for  $0 \leq n \leq 19$ . Use these vectors and `fft` to compute  $a\_y1$  and  $a\_y2$ , the DTFS coefficients of  $y1$  and  $y2$ . Use `stem` and `abs` to generate plots of the DTFS coefficients for both sequences. Do these plots agree with Part (e)?

According to the question, take a one period  $y$  signal and obtain its Fourier series coefficients by `fft` function and make a graph.

```
y1_20 = y1(1:20);
y2_20 = y2(1:20);
a_y1 = fft(y1_20) / length(y1_20);
a_y2 = fft(y2_20) / length(y2_20);

subplot(2, 1, 1);
stem(0:19, abs(a_y1), 'filled');
title('a_y1');
subplot(2, 1, 2);
stem(0:19, abs(a_y2), 'filled');
title('a_y2');
```





Comparison with the Fourier level coefficient plots of the input signals reveals that the high frequency component is suppressed after system 1 and the low frequency component is suppressed after system 2. The plots agreed with the answers in part e.

### 3.10

## The FFT Algorithm for Computing the DTFS

The DTFS for a periodic discrete-time signal with fundamental period  $N$  is given by Eq. (3.2).

(a)

- (a). Argue that computing each coefficient  $a_k$  requires  $N + 1$  complex multiplications and  $N - 1$  complex additions. Assume that the functions  $e^{-jk(2\pi/N)n}$  do not require any computation. Using this result, how many operations are required to compute the DTFS for a signal with fundamental period  $N$ ? Note that the number of operations required is independent of the particular signal  $x[n]$ .

$N+1$  complex multiplications for computing  $a_0$  and  $a_{N/2}$ ;

$2(N-1)$  complex multiplications for computing the remaining coefficients;

$N-1$  complex additions for computing all coefficients;

So, the total number of operations required to compute the DTFS is  $N+1+2(N-1)+N-1 = 4N-2$ .

(b)

- (b). If you have not already done the Advanced Problem in Exercise 3.5, do it now. You will compare the amount of computation this algorithm

amount required by `fft`. You can measure the number of operations used to implement Eq. (3.2) by using the internal flops (floating point operations: additions and multiplications) counter of MATLAB as follows:

```
>> x = (0.9).^[0:N-1]; % create one period of x[n]
>> flops(0); % set MATLAB's internal computation counter to 0
>> X = dtfs(x,0); % Store the DTFS of x[n] in X
>> c = flops; % Store the number of operations in c
```

Find `c` for computing `X` using `dtfs` for  $N = 8, 32, 64, 128$ , and  $256$ . Save the results in the vector `dtfscomps`.

Since the new version of matlab removes the `flop` function, we use `tic,toc` to computing `X` using `dtfs` and `fft` for  $N=8,32,64,128$ ,and  $256$ . save them in the `dtfscomps` and `fftcomps`

```
clear; clc; close all;
N = [8, 32, 64, 128, 256];
dtfscomps = zeros(1, length(N));
fftcomps = zeros(1, length(N));
for i = 1:length(N)
    x = (0.9).^(0:N(i)-1);
    tic;
    dtfs(x,0);
    c1 = toc;
    dtfscomps(i) = c1;
    tic;
    fft(x) / 5;
    c2=toc;
    fftcomps(i) = c2;
end
dtfscomps
```

```
dtfscomps = 1x5
10-3 x
    0.2425    0.0507    0.0832    0.0412    0.1117
```

(c)

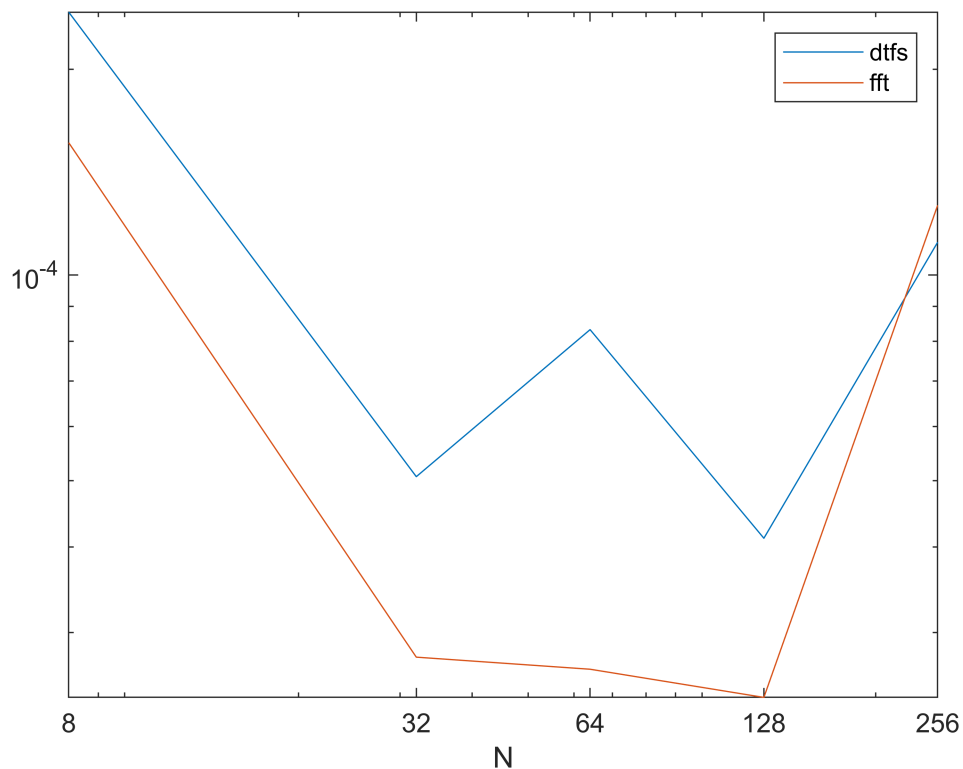
(c). Now, compute the DTFS coefficients of  $x[n]$  for  $N = 8, 32, 64, 128$  using `fft` as shown in Tutorial 3.1. Use `flops` to find the number of operations for each value of  $N$  and store these values in the vector `fftcomps`. Plot `fftcomps` versus  $N$  using `loglog`. How does the number of operations required by `fft` compare to that required by `dtfs`, particularly for large values of  $N$ ?

plot

```
fftcomps
```

```
fftcomps = 1x5
10^-3 x
    0.1562    0.0276    0.0265    0.0241    0.1265
```

```
figure;
loglog(N,dtfscomps);
xticks(N);
hold on;
loglog(N,fftcomps);
legend('dtfs','fft');
xlabel('N');
```



(d)

- (d). What is the fundamental period,  $N_y$ , of  $y[n]$ ? Argue that directly implementing periodic convolution according to Eq. (3.11) requires  $\mathcal{O}(N^2)$  operations and multiplications). Remember that computing one period of  $y[n]$  characterize the entire signal.

The fundamental period,  $N_y$ , of  $y[n]$  is  $N$ ;

$$y[n + N] = \sum_{r=0}^{N-1} x[r]h[n + N - r] = \sum_{r=0}^{N-1} x[r]h[n - r] = y[n]$$

$N$  is the period of  $y[n]$ , and the fundamental period of  $h[n]$ .

(e)

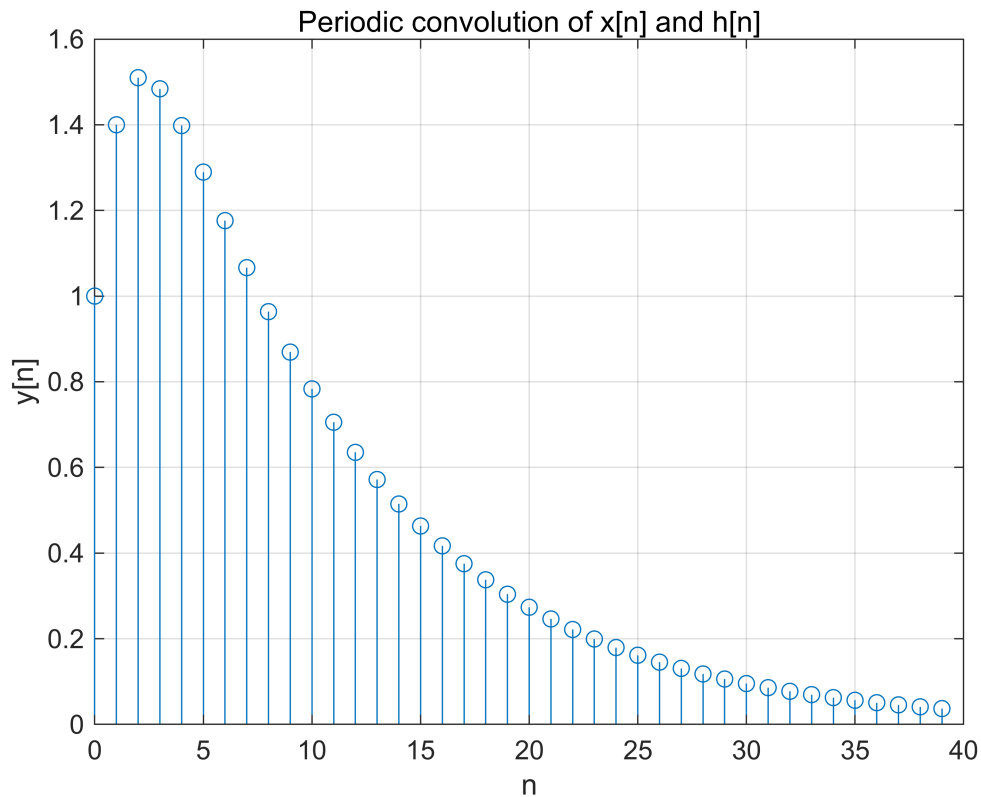
- (e). Assume both  $x[n]$  and  $h[n]$  have fundamental period  $N = 40$ , and are  $(0.9)^n$  and  $h[n] = (0.5)^n$  over the interval  $0 \leq n \leq N - 1$ . Compute the periodic convolution of  $x[n]$  with  $h[n]$  and plot  $y[n]$  for  $0 \leq n \leq N_y - 1$ . Store the number of operations, given by `flops`, required to implement the convolution in `f40c`. To set `flops(0)` after creating `x` and `h`, the vectors representing  $x[n]$  and  $h[n]$ . To implement the periodic convolution, first store  $x[n]$  and  $h[n]$  over  $0 \leq n \leq N - 1$  in the row vectors `x` and `h`, respectively. Set `flops(0)` before `conv([x x],h)`. The periodic convolution can be extracted from a signal.

```
clear; clc; close all;
N = 40;
x = (0.9).^(0:N-1);
h = (0.5).^(0:N-1);
n = 0+0:(2*N-1)+(N-1);
tic;
y = conv([x x], h);
f40c = toc;
f40c
```

```
f40c = 0.0015
```

```
stem(n(1:N), y(1:N));
xlabel('n'); ylabel('y[n]');
title('Periodic convolution of x[n] and h[n]');
```

```
grid on;
```



(f)

(f). Repeat Part (e) for  $N = 80$ , again plotting a period of  $y[n]$  and storing the results of operations in **f80c**.

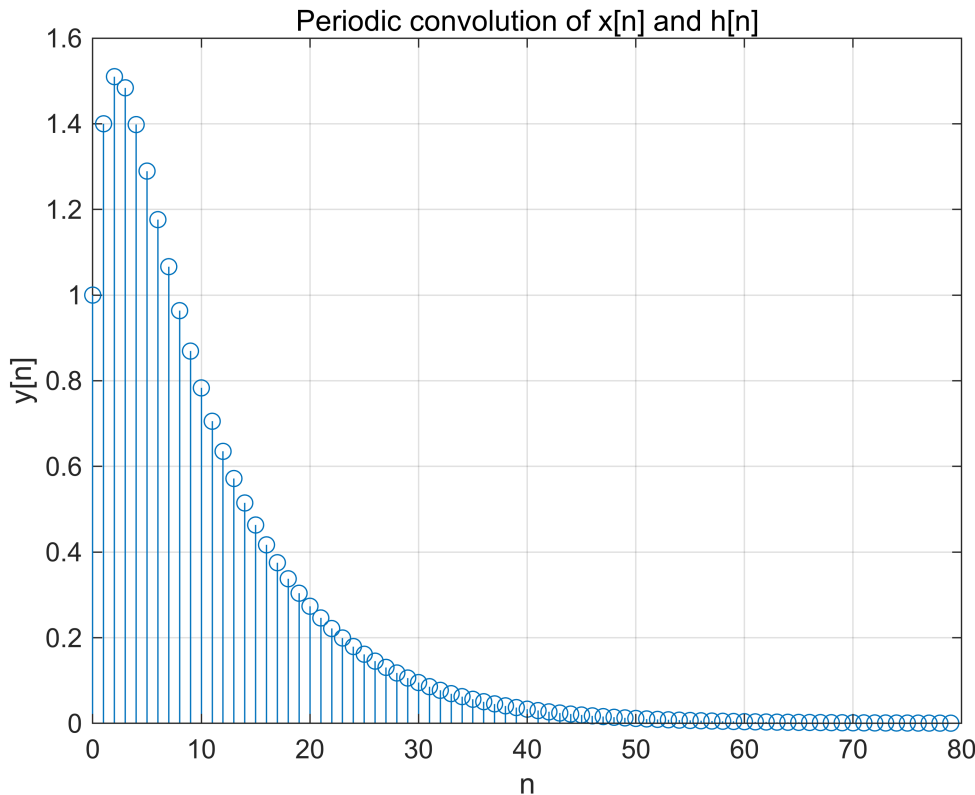
same as (e)

```
clear; clc; close all;  
N = 80;  
x = (0.9).^(0:N-1);  
h = (0.5).^(0:N-1);  
n = 0+0:(2*N-1)+(N-1);  
tic;  
y = conv([x x], h);  
f80c = toc;  
f80c
```

```
f80c = 0.0018
```

```
stem(n(1:N), y(1:N));  
xlabel('n'); ylabel('y[n]');
```

```
title('Periodic convolution of x[n] and h[n]');
grid on;
```



(g)

- (g). Assume  $x[n]$  and  $h[n]$  are defined as in Part (e). Use the periodic convolution of the DTFS to implement the periodic convolution<sup>2</sup>. Namely, compute the DTFS coefficients of both  $x[n]$  and  $h[n]$  using `fft` as described in Tutorial 3. Use the periodic convolution property to form the DTFS coefficients of  $y[n]$ . Find  $y[n]$  from the DTFS coefficients using `ifft`. The `ifft` algorithm is similar to the FFT, and also requires  $\mathcal{O}(N \log N)$  operations for a signal with period  $N$ . To check the validity of your implementation, plot  $y[n]$  for  $n = 0, \dots, 79$  and compare this signal to that computed in Part (e). Remember, from Tutorial 3.1, the signal  $y[n]$  might have a small imaginary component due to round-off errors. Store the total number of operations required to compute `f40f`, and remember to set `flops(0)` after creating the representation of  $h[n]$  in MATLAB.

```

clear; clc; close all;
N = 40;
x = (0.9).^(0:N-1);
h = (0.5).^(0:N-1);
n = 0+0:(2*N-1)+(N-1);
tic;
X = fft(x) / N;
H = fft(h) / N;
Y = N.*X .* H;
y = ifft(Y) * N;
f40f = toc;
f40f

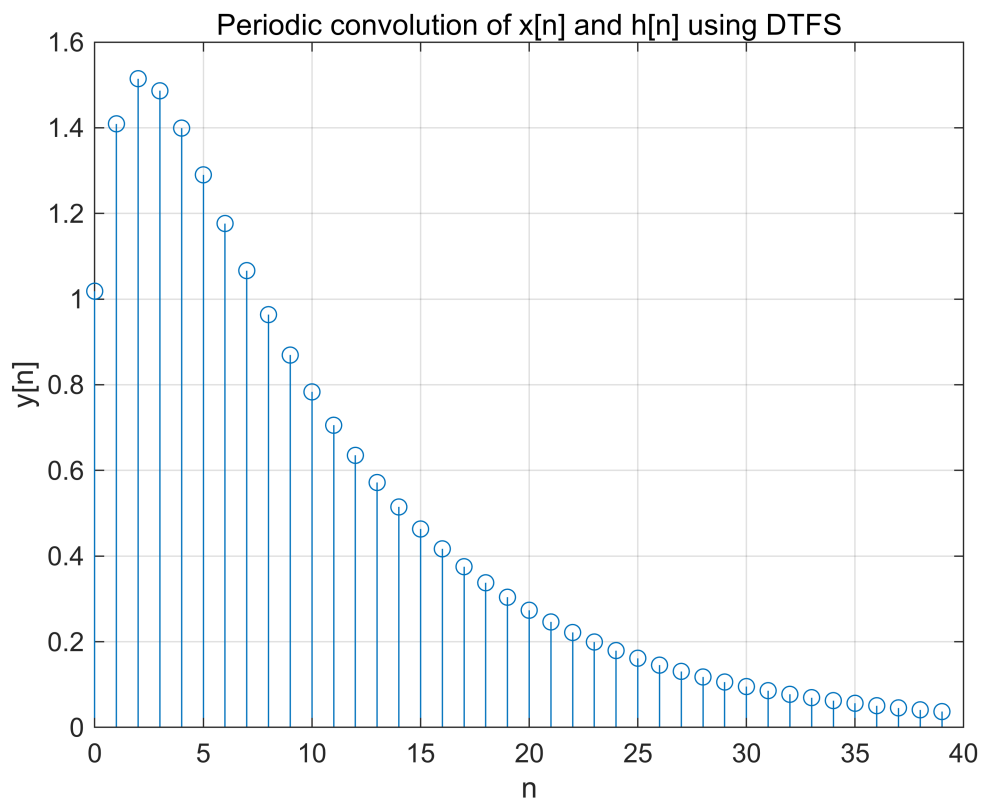
```

f40f = 0.0043

```

stem(n(1:N),y(1:N));
xlabel('n'); ylabel('y[n]');
title('Periodic convolution of x[n] and h[n] using DTFS');
grid on;

```



(h)



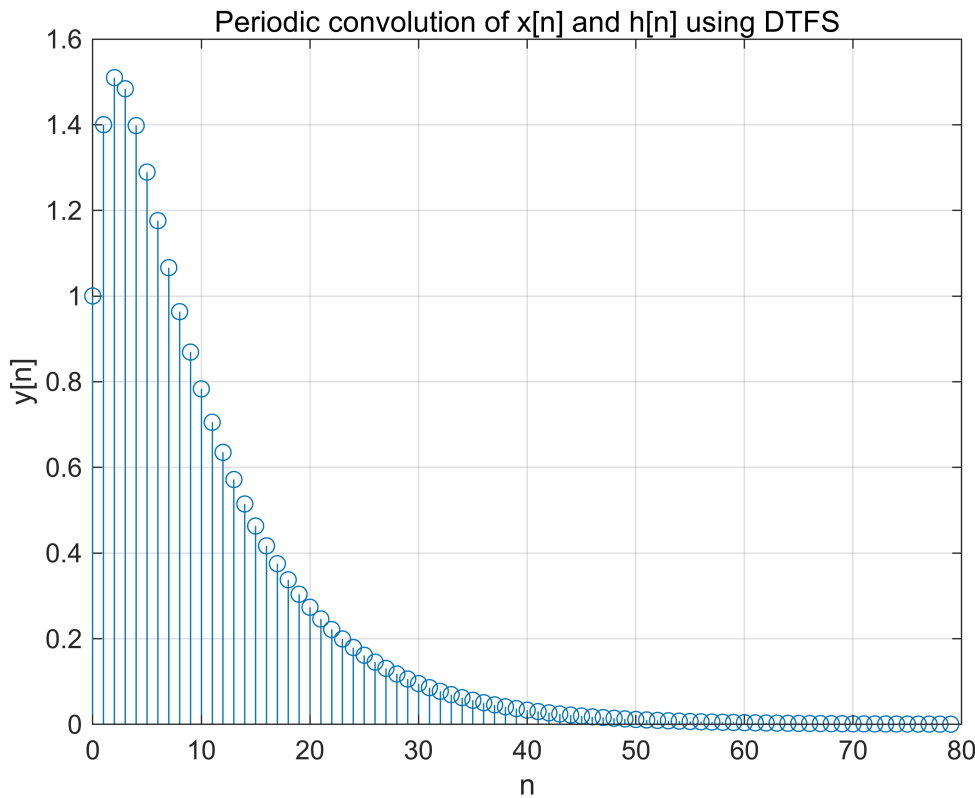
(h). Repeat Part (g) for  $N = 80$ , again plotting a period of  $y[n]$  and storing the time of operations in `f80f`. Again check the validity of your implementation of  $y[n]$  with that computed in Part (f).

same as (g)

```
clear; clc; close all;
N = 80;
x = (0.9).^(0:N-1);
h = (0.5).^(0:N-1);
n = 0+0:(2*N-1)+(N-1);
tic;
X = fft(x) / N;
H = fft(h) / N;
Y = N.*X .* H;
y = ifft(Y) * N;
f80f = toc;
f80f
```

```
f80f = 0.0047
```

```
stem(n(1:N),y(1:N));
xlabel('n'); ylabel('y[n]');
title('Periodic convolution of x[n] and h[n] using DTFS');
grid on;
```



(i)

- (i). Compute the ratios of  $f_{40c}$  to  $f_{40f}$  and  $f_{80c}$  to  $f_{80f}$ . How do these ratios change for  $N = 40$  and  $N = 80$ ? Which method of convolution is more efficient for  $N = 40$ ? Which method would you choose for  $N > 80$ ? Justify your answer.

```
clear; clc; close all;
f40c=0.0015; f80c=0.0018; f40f=0.0043; f80f=0.0047;
ratio_40=f40c / f40f;
ratio_80=f80c / f80f;
ratio_40
```

```
ratio_40 = 0.3488
```

```
ratio_80
```

```
ratio_80 = 0.3830
```

these ratios increase as  $N$  increases, which means that the difference in efficiency between the two methods becomes more significant for larger values of  $N$ .

Therefore, the method of convolution that is more efficient for each value of  $N$  is the one that uses the periodic convolution property of the DTFS

This method would also be the preferred choice for  $N > 80$

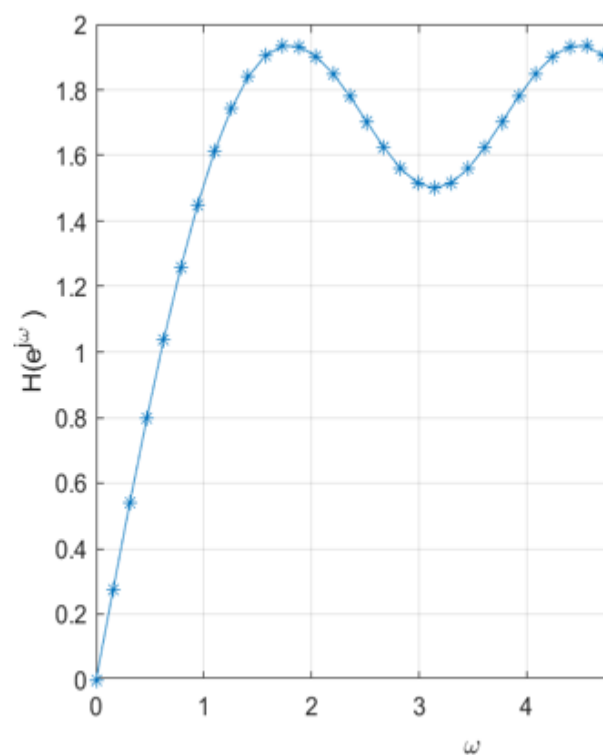
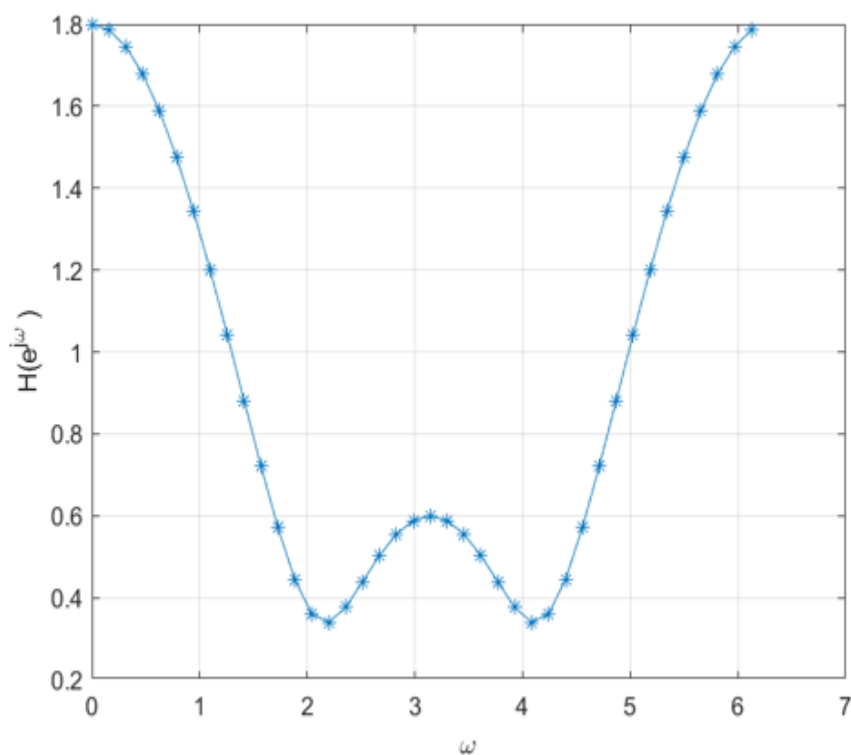
## Function

```
function X = dtfs(x, k)
N = length(x);
if nargin < 2
    k = 0:N-1;
end
X = zeros(1, length(k));
for i = 1:length(k)
    n = 0:N-1;
    X(i) = sum(x .* exp(-1j * 2 * pi * k(i) * n / N)) / N;
end
end
```

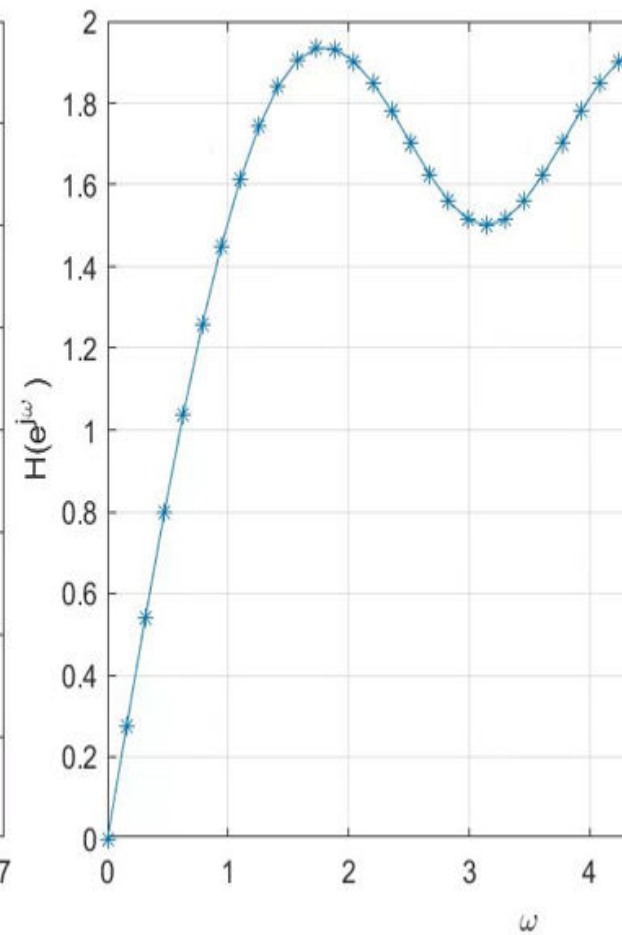
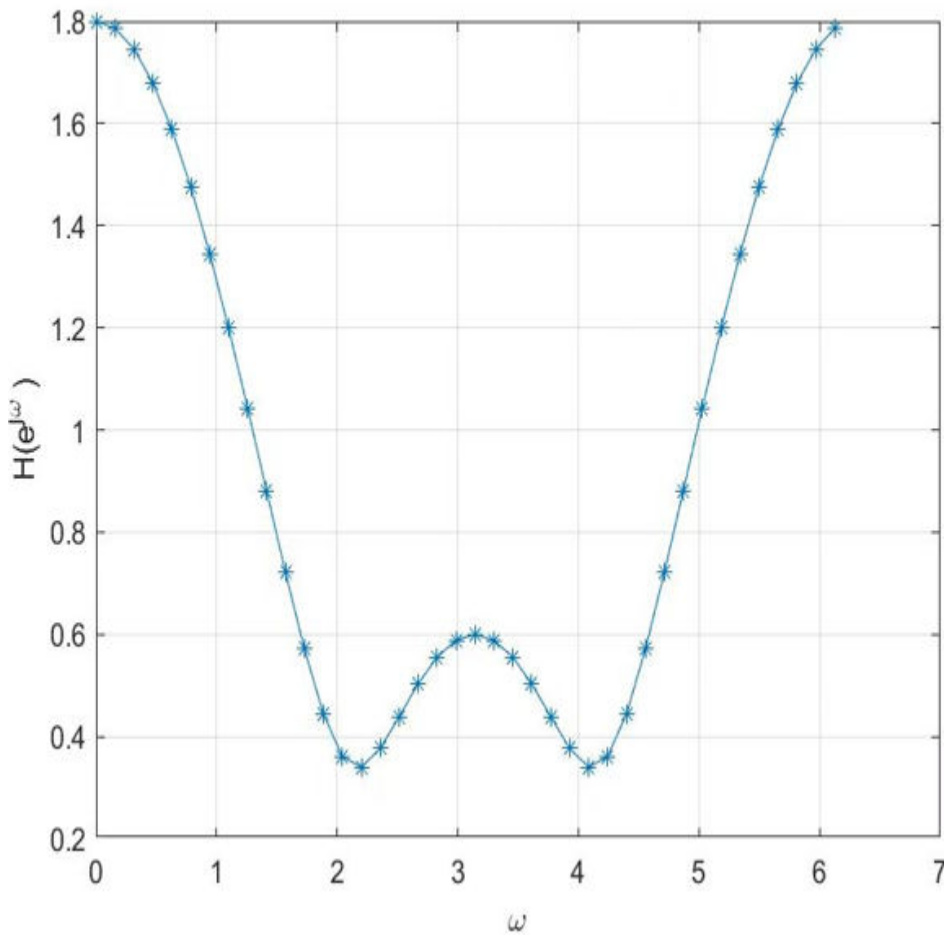
## Experience

exercise figure

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1. We have learnt about the use of the `fft()`, which can be used to decompose a signal: converting a signal into its Fourier series representation.
2. We have learnt about the use of the `ifft()`, which performs the synthesis of the signal: it represents a series of signals corresponding to the Fourier series coefficients.
3. We learnt how filters work: signals of different frequencies are amplified or reduced in a specific way to achieve the effects of "high pass", "low pass" and "band pass".
4. When choosing an algorithm to solve a problem, it is important to consider the time complexity and other relevant parameters while satisfying the functionality to achieve the most efficient use of the code to complete the task.
5. We realize that different systems do have different filtering effects