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# Online Deep Learning Learning Deep Neural Networks on the Fly

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Joint work with

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### **Overview**

### **Introduction & Motivation**

Online Learning and Deep Learning Challenges in using Deep Networks for Online Learning

### **Online Deep Learning (ODL)**

Shallow to Deep Principle Architecture for ODL Hedge Backpropagation

### **Experiments**

Online Performance
Other Insights



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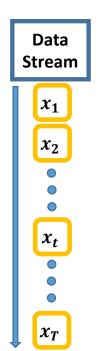
**Online Learning and Deep Learning** 

Online Learning

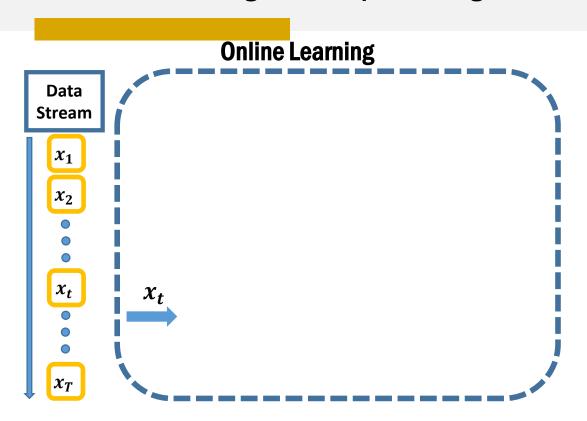


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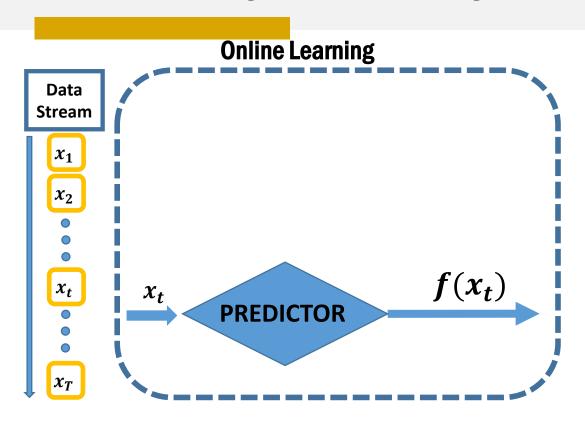
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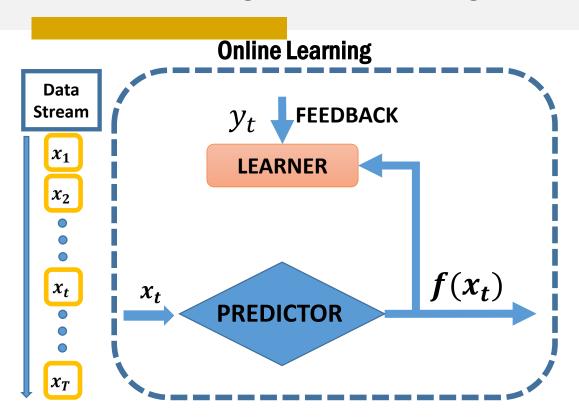




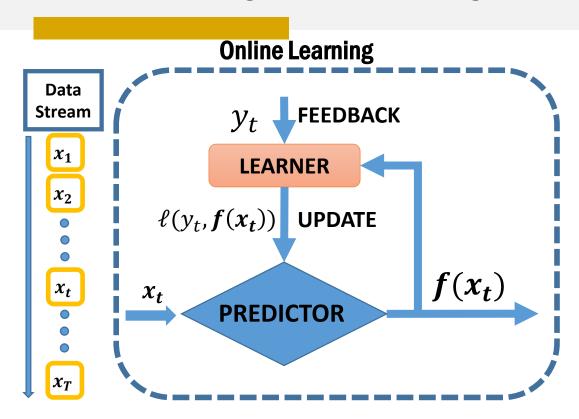






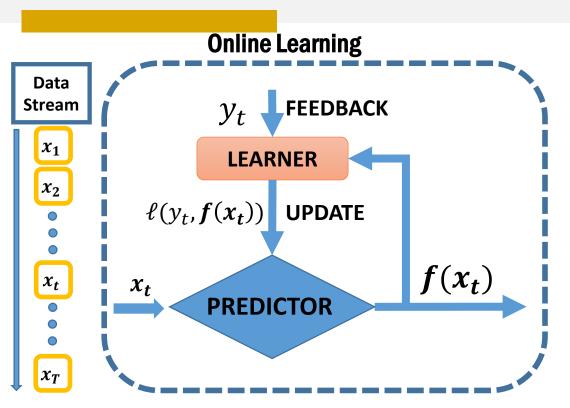








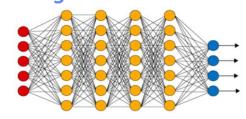
### Online Learning and Deep Learning



### **Deep Learning**

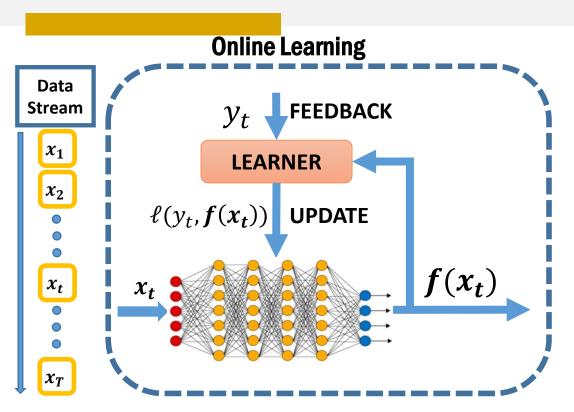
### State of the art in many applications

- Easily beats kernel methods
- Krizhevsky et al. 2012
- Simonyan & Zisserman 2014
- He et al. 2016
- Huang et. al 2017





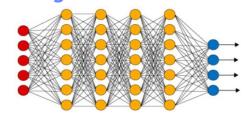
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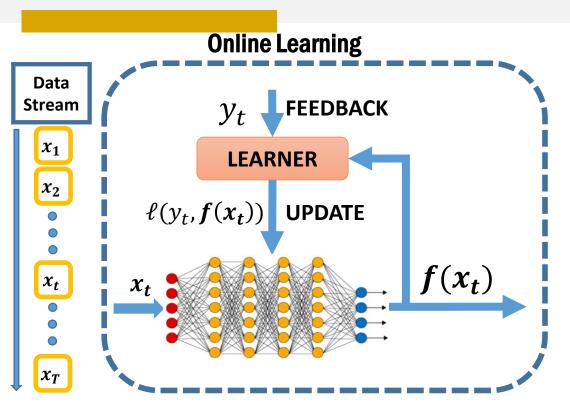
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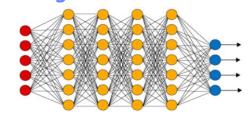
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### **Deep Learning**

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### **Existing Online Deep Learning**

Very limited work that addresses Deep Learning in Online Setting

Few Attempts (Zhou et al. 2012, Lee et. al. 2016): Consider Mini-batch Optimization



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Challenges in using Deep Networks for Online Learning (1/2)

### Choose a (very) deep network -

Choosing a sufficiently complex network ensures that the pattern in data **CAN** be learnt

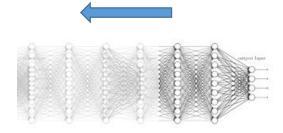
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### **Vanishing Gradient**



Bengio et al. 1994 Hochreiter 1998, etc.



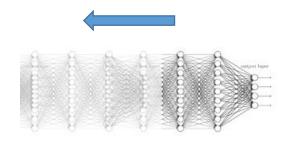
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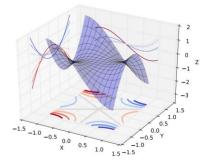
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### **Vanishing Gradient**

# Saddle Points (& Local Minima)



Bengio et al. 1994 Hochreiter 1998, etc.



Dauphin et al. 2014



Challenges in using Deep Networks for Online Learning (1/2)

### Choose a (very) deep network -

Choosing a sufficiently complex network ensures that the pattern in data **CAN** be learnt ... however ... particularly for online settings ...

# Vanishing Gradient Saddle Points (& Local Minima) Reuse Bengio et al. 1994 Hochreiter 1998, etc. Diminishing Feature Reuse Srivastava et al. 2015



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Challenges in using Deep Networks for Online Learning (1/2)

**Unique Problem** – prefer different depths at different stages of training



Challenges in using Deep Networks for Online Learning (1/2)

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 $x_1$ 



 $x_t$ 



 $x_T$ 



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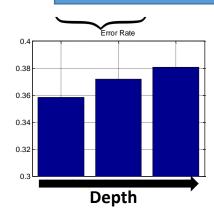
 $x_1$ 

• • •

 $x_t$ 

• • •

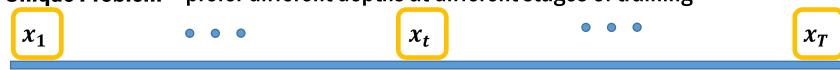
 $x_T$ 

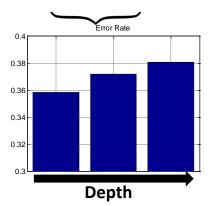


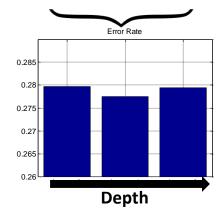


Challenges in using Deep Networks for Online Learning (1/2)

**Unique Problem** – prefer different depths at different stages of training









Challenges in using Deep Networks for Online Learning (1/2)

**Unique Problem** – prefer different depths at different stages of training  $x_1$  $x_t$  $\chi_T$ Error Rate Error Rate Error Rate 0.38 0.285 0.265 0.28 0.36 0.275 0.26 0.34 0.27 0.32 0.255 0.265 Depth **Depth** Depth



Challenges in using Deep Networks for Online Learning (1/2)

**Unique Problem** – prefer different depths at different stages of training  $\boldsymbol{x_1}$  $\boldsymbol{x_t}$  $\chi_T$ Error Rate Error Rate Error Rate 0.38 0.285 0.265 0.36 0.275 0.26 0.34 0.27 0.32 0.255 0.265 **Depth Depth** Depth

Final Error – anyone could be best depending on how much of the data has been processed.

Problem is magnified for concept-drift scenarios

**Best of both worlds?** 



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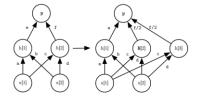
Depth

### **Shallow to Deep Principle**

# **Explicitly Shallow to Deep (Function Preservation Principle)**

Net2Net Chen et al. 2016

NetMorph Wei et al. 2016



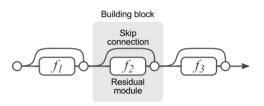
# **Implicitly Shallow to Deep**

ResNet He et al. 2016

Highway Net Srivastava et al. 2015

DenseNet Huang et al. 2017

also Fractal Net Larsson et al. 2017





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**Architecture for ODL** 

**Shallow to Deep** principle is suited for Online Deep Learning

Start Shallow → Faster Convergence

Become Deeper → Deep Representation

### **Proposed Architecture**

Attach intermediate classifier to every hidden layer



Architecture for ODL

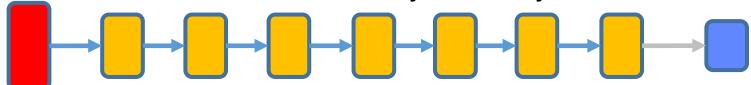
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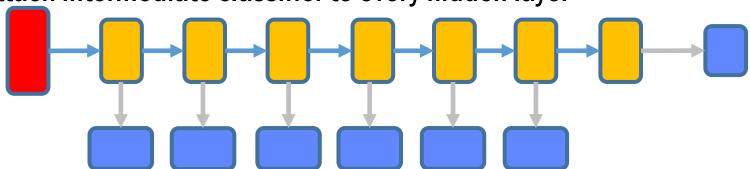
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Architecture for ODL

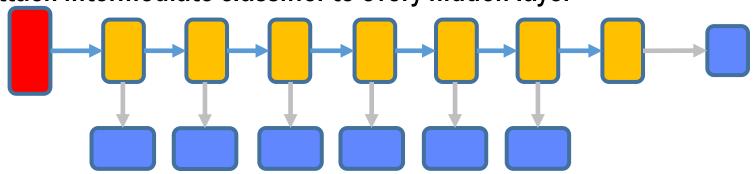
### **Shallow to Deep** principle is suited for Online Deep Learning

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Dynamically vary the Effective Depth based on the data



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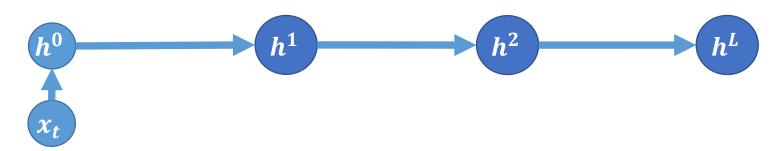
Hedge Backpropagation (1/3)



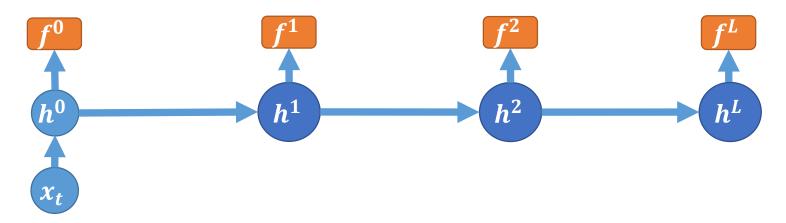




Hedge Backpropagation (1/3)

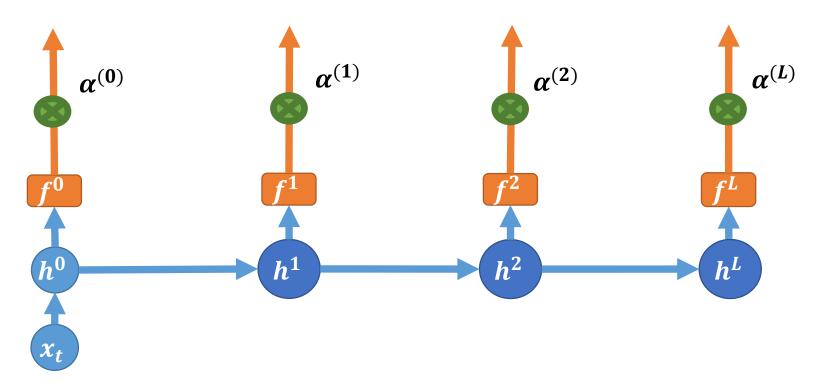






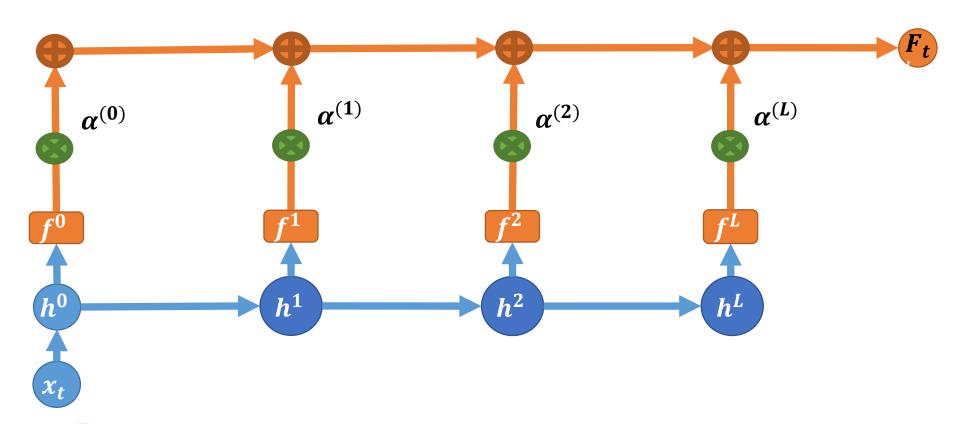


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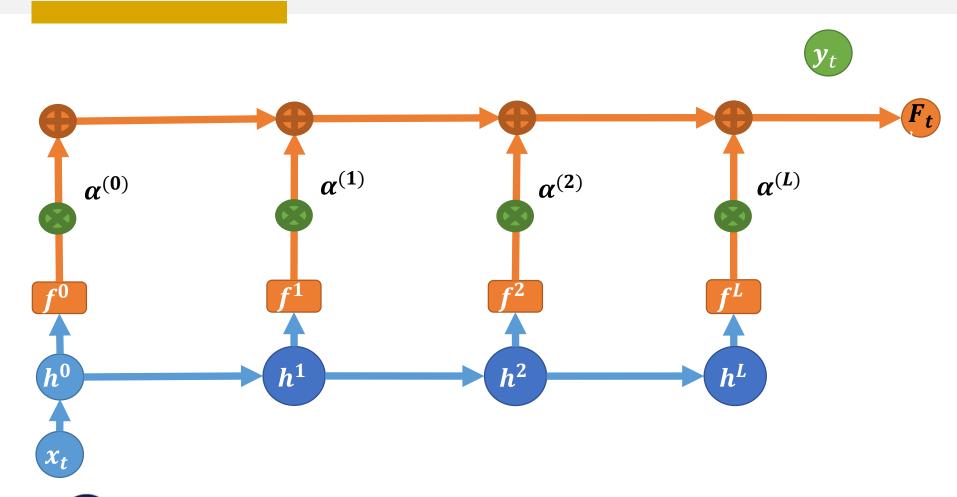




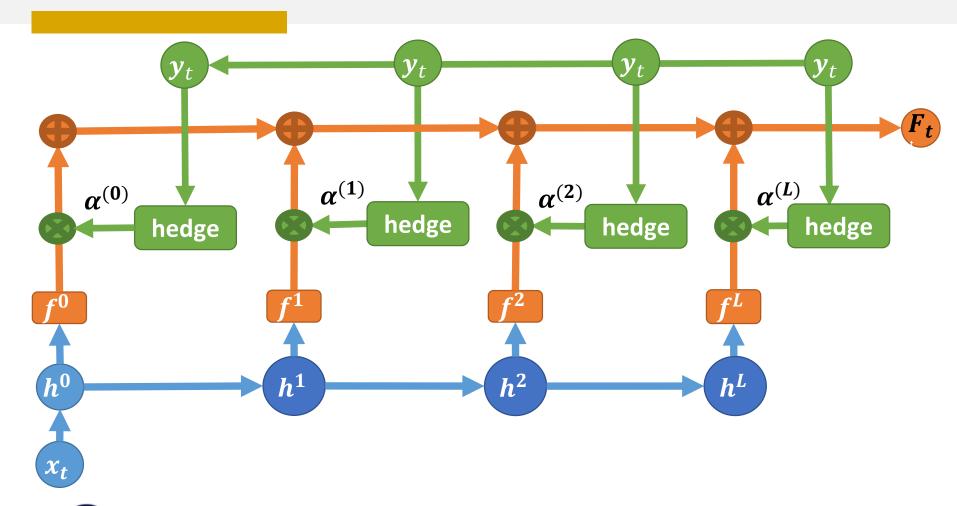
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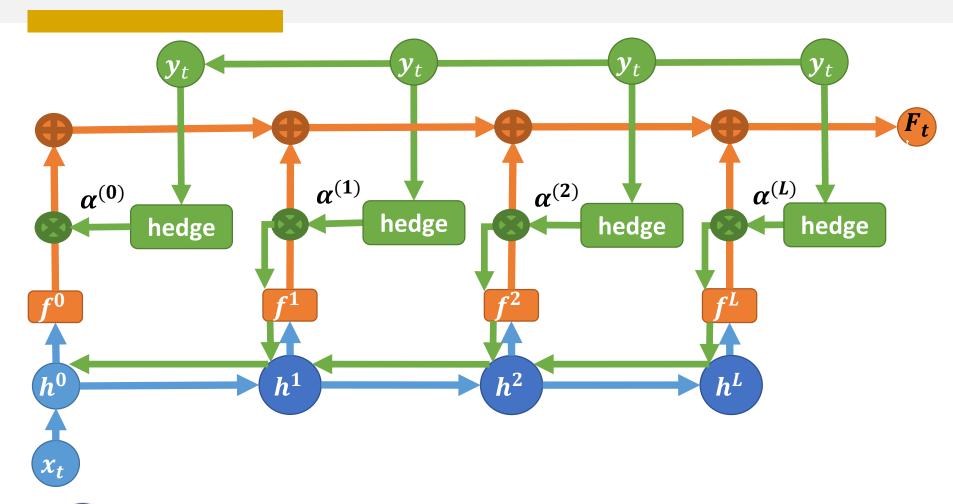






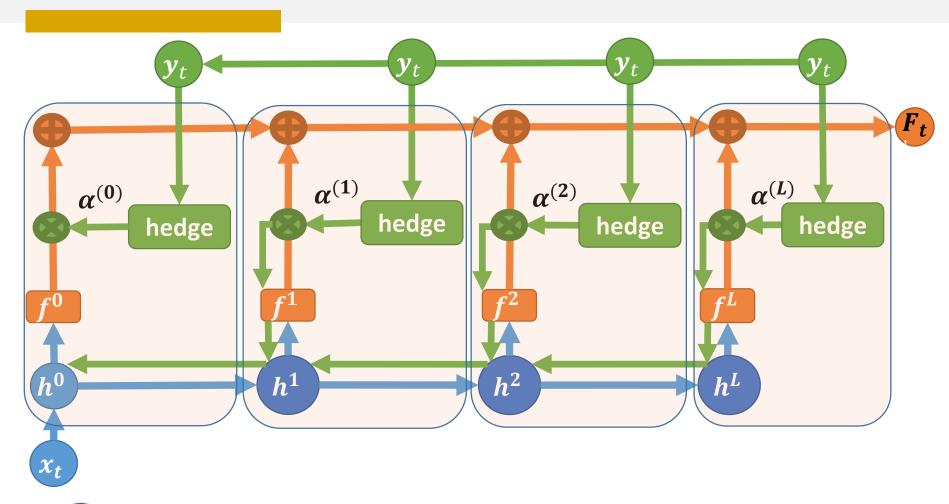








Hedge Backpropagation (1/3)





**Hedge Backpropagation (2/3)** 



Hedge Backpropagation (2/3)

### A **Dynamic** Objective Function

$$\mathcal{L}(\mathbf{F}(\mathbf{x}), y) = \sum_{l=0}^{L} \alpha^{(l)} \mathcal{L}(\mathbf{f}^{(l)}(\mathbf{x}), y)$$



Hedge Backpropagation (2/3)

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### 3 Main Updates

Loss / Classifier Weight update (Hedge)

**Classifier Update** 

**DNN Update** 



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$$\alpha_{t+1}^{(l)} \leftarrow \alpha_t^{(l)} \beta^{\mathcal{L}(\mathbf{f}^{(l)}(\mathbf{x}), y)}$$

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$$\Theta_{t+1}^{(l)} \leftarrow \Theta_{t}^{(l)} - \eta \nabla_{\Theta_{t}^{(l)}} \mathcal{L}(\mathbf{F}(\mathbf{x}_{t}, y_{t}))$$

$$= \Theta_{t}^{(l)} - \eta \alpha^{(l)} \nabla_{\Theta_{t}^{(l)}} \mathcal{L}(\mathbf{f}^{(l)}, y_{t})$$

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Hedge Backpropagation (2/3)

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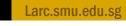
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**Smoothing Parameter** 

$$\alpha^{(l)} \leftarrow \max\left(\alpha^{(l)}, \frac{s}{L}\right)$$



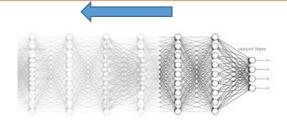


Hedge Backpropagation (3/3)



Hedge Backpropagation (3/3)

### **Vanishing Gradient**



Intermediate classifiers reduce initial susceptibility to Vanishing Gradient



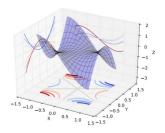
Hedge Backpropagation (3/3)

### **Vanishing Gradient**

# amput layer

Intermediate classifiers reduce initial susceptibility to Vanishing Gradient

## Saddle Points (& Local Minima)

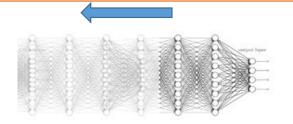


Multiple Loss functions allow easier exits from saddle points



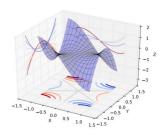
Hedge Backpropagation (3/3)

#### **Vanishing Gradient**



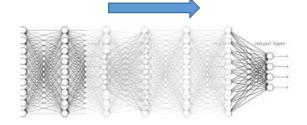
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## Saddle Points (& Local Minima)



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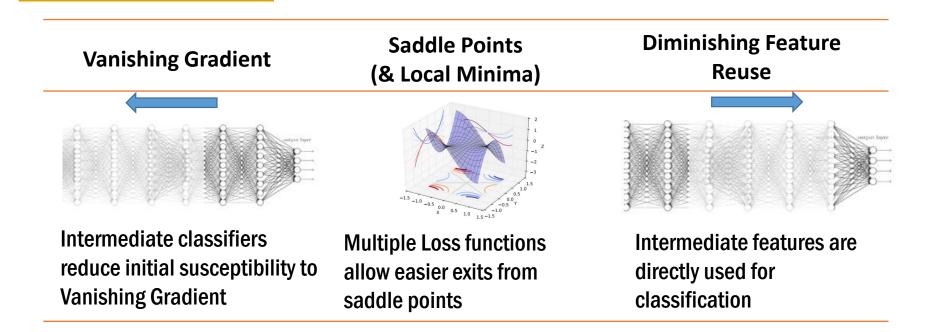
## Diminishing Feature Reuse



Intermediate features are directly used for classification



Hedge Backpropagation (3/3)



### **Parallel Interpretations**

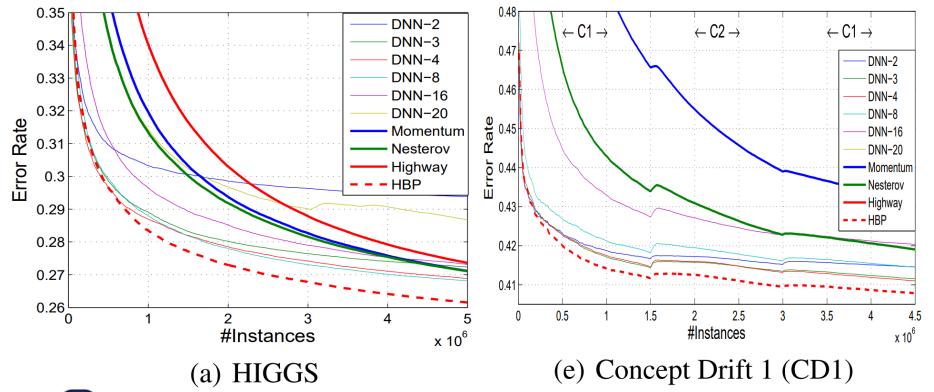
Student-Teacher Learning | Lifelong Learning | Concept-Drift Adaptation, etc.



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Convergence behavior on stationary and concept drift datasets

**Baselines**: Linear and Kernel OL | DNNs with varying depth | DNN-20 – with momentum, Highway **Proposed:** Online Deep Learning by Hedge Backpropagation (DNN-20)

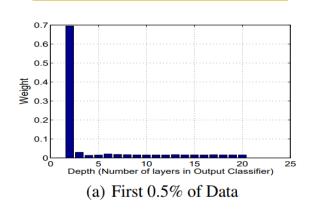


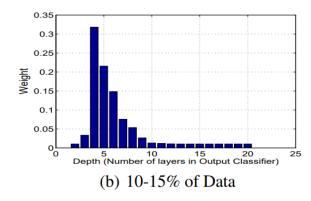


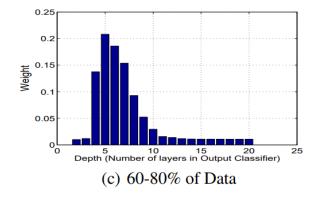
Other Insights



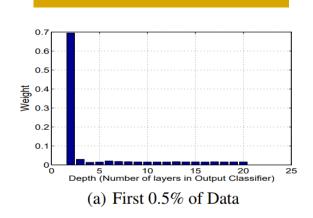
### **Other Insights**

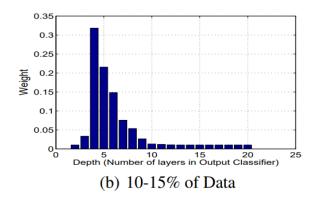


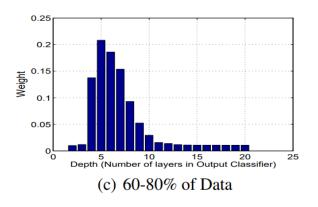


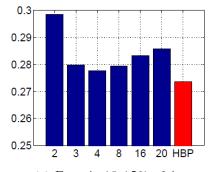


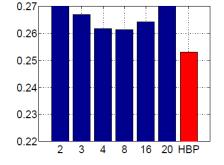
### **Other Insights**











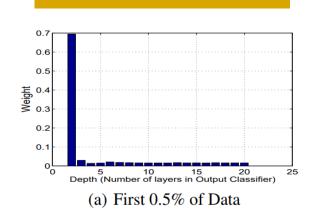
(a) Error in 10-15% of data

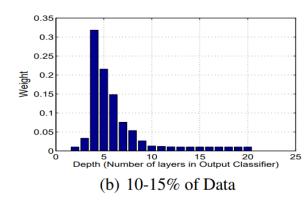
(b) Error in 60-80% of data

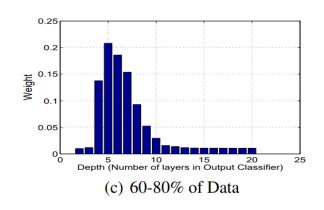


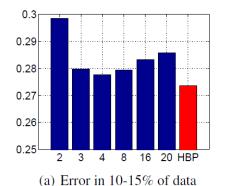
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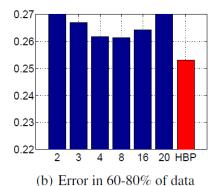
### **Other Insights**











### **Error Variation with Depth**

Depth	12	16	20	30
Online BP	0.2692	0.2731	0.2868	0.4770
HBP	0.2609	0.2613	0.2615	0.2620



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### **Acknowledgements**

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## Thank you



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