

## 1. 計算內積:

$$\langle f, g \rangle := \int_{-\pi}^{\pi} f(x)g(x)dx$$

where  $f(x) = \sin(x)$ ,  $g(x) = \cos(x)$

In [1]:

```
import numpy as np
```

In [2]:

```
import scipy.integrate as integrate
import scipy.special as special
```

In [3]:

```
result = integrate.quad(lambda x: np.sin(x)*np.cos(x), -np.pi, np.pi)
```

In [4]:

```
result # the first term is the result, the second term is the error
```

Out[4]:

```
(0.0, 2.2102770810800183e-14)
```

## 2. Gram-Schmidt procedure:

[GS 參考資料 \(http://moocs.nccu.edu.tw/media/19162#tab-step\)](http://moocs.nccu.edu.tw/media/19162#tab-step)

[QR decomposition 參考資料 \(http://moocs.nccu.edu.tw/media/19163\)](http://moocs.nccu.edu.tw/media/19163)

In [9]:

```
import numpy.random as rn
import numpy.linalg as la
```

In [26]:

```
def GS(A, tol=10**-15):
    m, n = A.shape
    Idx = list() # store the
    Q = np.mat(np.zeros((m, n))) # store the result matrix
    Q[:,0] = A[:,0] / la.norm(A[:,0]) # the first vector of the original basis
    for i in range(1, n): # start from the 2nd column till nth column
        Q[:,i] = A[:,i].copy()
        for j in range(i): # inner product
            Q[:,i] = Q[:,i] - Q[:,j] * float(Q[:,j].T * Q[:,i])
        if la.norm(Q[:,i]) > tol: # normalize
            Q[:,i] = Q[:,i] / la.norm(Q[:,i])
        else:
            Idx.append(i)
    return Q, Idx
```

In [35]:

```
x = rn.randn(3)
A = np.mat([x, x**2, x**3, x**4, x**5])
print(A)
print(A.shape)
```

```
[[-1.20608003  0.89880674  2.09276926]
 [ 1.45462904  0.80785356  4.37968318]
 [-1.75439904  0.72610422  9.16566633]
 [ 2.11594564  0.65262737 19.18162475]
 [-2.55199979  0.58658588 40.14271465]]
(5, 3)
```

In [36]:

```
q, idx = GS(A)
q
```

Out[36]:

```
matrix([[ -0.28717478,  0.49644677, -0.48315358],
 [ 0.34635576,  0.56078365, -0.12655933],
 [-0.41773277,  0.36585077, -0.23534973],
 [ 0.50381915,  0.49549174,  0.45730232],
 [-0.60764622,  0.24434288,  0.69715884]])
```

### 3. $P_U(\sin(x))$

$$U = \text{span}(1, x, x^2, x^3, x^4, x^5)$$

In [85]:

```
x = rn.randn(5)
B = np.mat([x, x**2, x**3, x**4, x**5])
```

In [86]:

```
q2, idx2 = GS(B)
```

In [87]:

```
q2.shape
```

Out[87]:

```
(5, 5)
```

In [89]:

```
res = np.mat(np.zeros((5, 1)))  
for i in range(q2.shape[1]): # column of q2  
    sin = np.sin(x).reshape(1, 5)  
    res = q2[:,i]*(sin * q2[:,i])  
  
p_u_sinx = res  
p_u_sinx
```

Out[89]:

```
matrix([[ -0.02099247],  
        [ -0.16076548],  
        [  0.05517341],  
        [  0.21959042],  
        [ -0.11417569]])
```