

《物理与人工智能》

AI与量子多体物理

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2025/11/24 （第12周）



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What is emergence?

- Emergence occurs when a complex entity has properties or behaviors that its parts do not have on their own, and emerge only when they interact in a wider whole.

4 August 1972, Volume 177, Number 4047

SCIENCE

More Is Different

P. W. Anderson

Universal macroscopic
behaviors

Numerous microscopic
degrees of freedom

✓ Image
recognition:

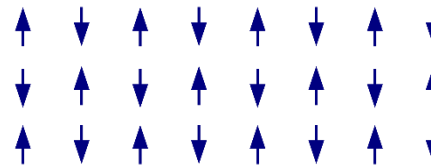
flower



a single
pixel

✓ Many-body
physics:

antiferromagnet



a single
spin

✓ And more:

wet

water molecule

macroeconomy

individual



What are phases?



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- Renormalization group – a pathway towards understanding collective behaviors

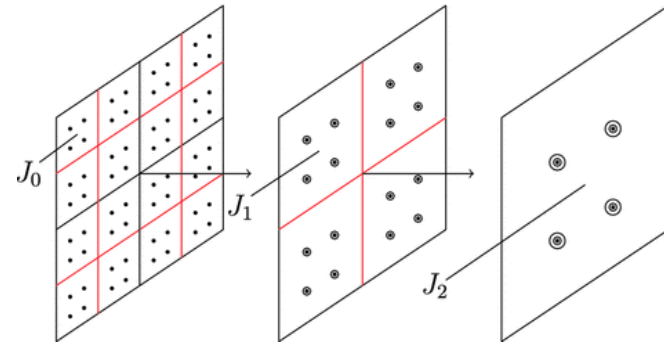


Kenneth G. Wilson
1982 Nobel Prize
in Physics

$$H = -J \sum_{\langle ij \rangle} \sigma_i \cdot \sigma_j$$

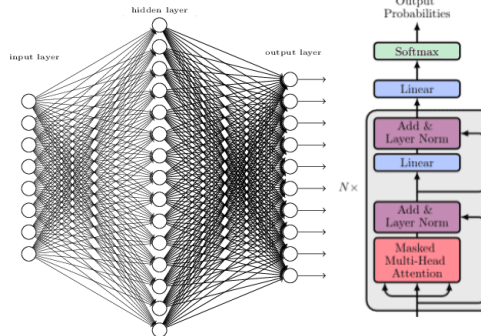
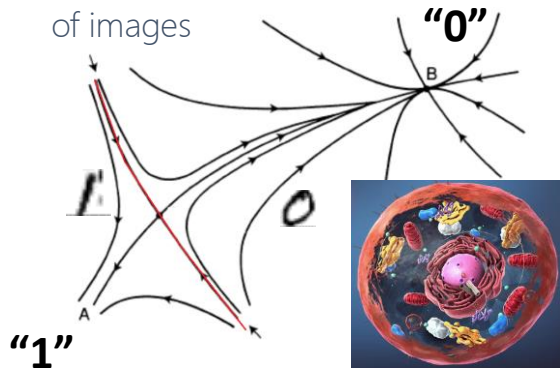
$J_\infty \rightarrow 0$ J_c $J_\infty \rightarrow \infty$
paramagnetic phase ferromagnetic phase

universal properties irrespective of microscopic details

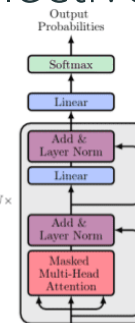


- Image recognition, AI, even life, are collective behaviors

schematic "RG flow"
of images



No two cells are
exactly the same!



John Hopfield & Geoffrey Hinton
2024 Nobel Prize in Physics



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AI for Quantum Phase Recognition

Review: discriminative AI



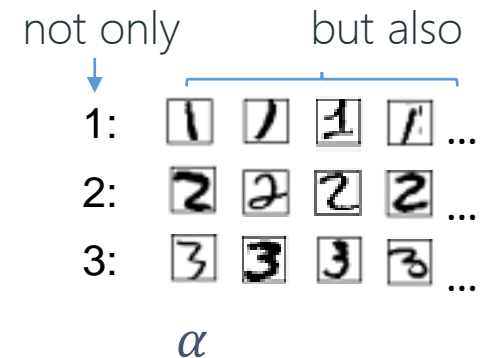
- Viability – review: discriminative AI and supervised machine learning

- With interpretability



- Necessity – sometimes:

- Diverse phases and candidates
- Hidden, abstract, and complex rules
- Noises and fluctuations
- Big data, experimentally or numerically



A quantum many-body state:

$$|\Psi\rangle = \sum_{\alpha} \phi_{\alpha} \left(\begin{array}{cccccc} \uparrow & \downarrow & \uparrow & \downarrow & \uparrow & \downarrow \\ \downarrow & \uparrow & \downarrow & \uparrow & \downarrow & \uparrow \\ \uparrow & \downarrow & \uparrow & \downarrow & \uparrow & \downarrow \end{array} \right)$$

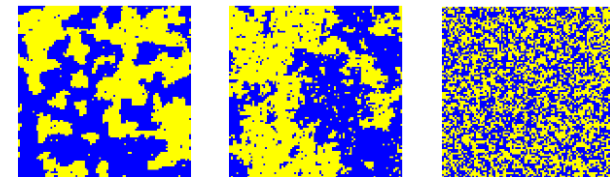
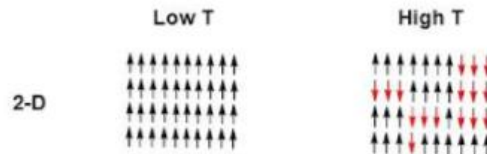
The Fock space is exponentially large $2^{30} \sim 1000000000$, $2^{1000} \sim 100 \dots 00$ with >300 zeros!



- The Ising model:

$$H(\sigma) = -J \sum_{\langle i j \rangle} \sigma_i \sigma_j$$

two phases: ferromagnetic (ordered) vs paramagnetic (disordered)



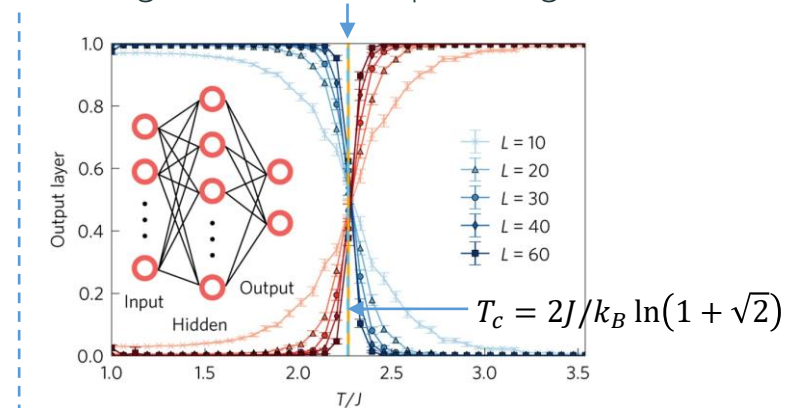
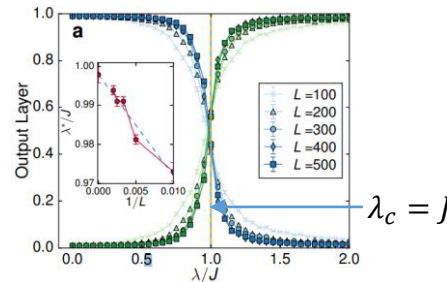
ferromagnetic critical paramagnetic

Numerical data: Monte Carlo samples

- The Aubry-Andre model (quasicrystal):

$$H = -J \sum_i (c_i^\dagger c_{i+1} + \text{h.c.}) + 2\lambda \sum_i \cos(2\pi\phi i) c_i^\dagger c_i$$

Numerical data: LDOS
delocalized vs localized



simple HW assignment: phase diagram (5pt)

Juan Carrasquilla, Roger G. Melko, 2017.



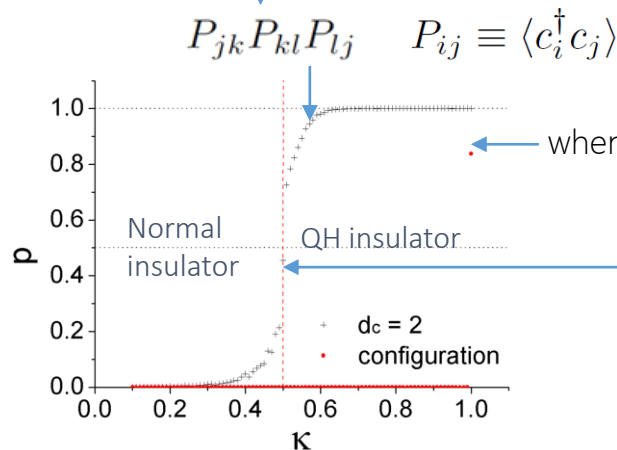
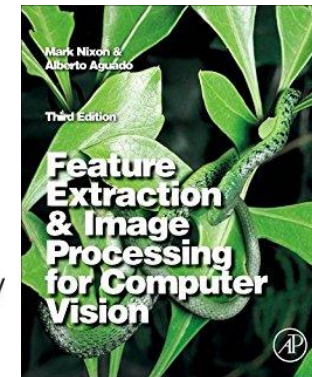
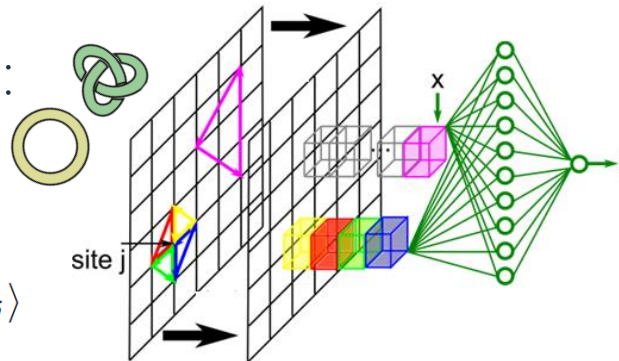
- Quantum and topological phases: the compatibility issue

a feature selection layer to bridge between

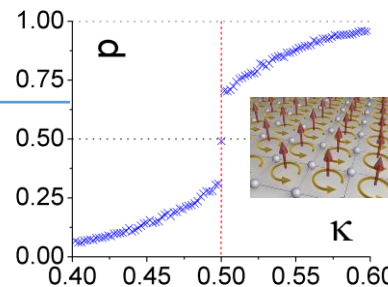


- E.g., topological phases:

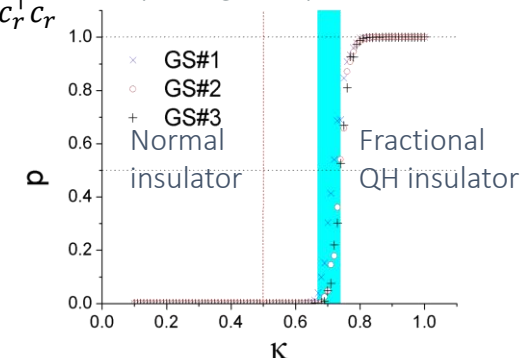
relevant operators in the Kubo formula for σ_{xy}



when operators are irrelevant, e.g., $n_r = c_r^\dagger c_r$



strongly-correlated topological phases:



Yi Zhang, E.-A. Kim, 2017.

- From quantum many-body models, for quantum many-body models:

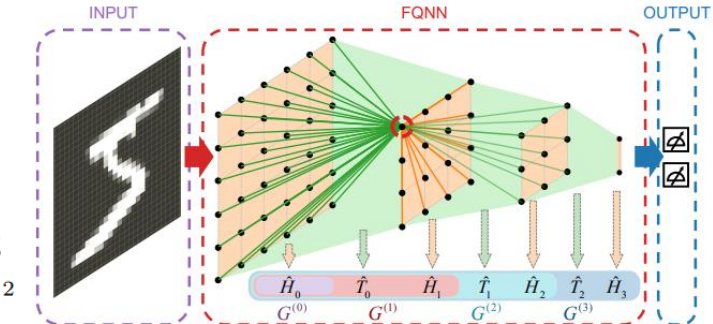
- Observation 1: various model parameters

$$H = \sum_{rr'} t_{rr'} c_r^\dagger c_{r'} + \sum_r \mu_r c_r^\dagger c_r + \sum_r U_r c_r^\dagger c_r n_r^f + \dots$$

- Observation 2: nonlinear physical properties

$$\text{LDOS: } y_k = -\frac{1}{\pi} \Im \left[\hat{\mathbf{G}}_{L,L}^{(L)} \right]_{k,k} \quad \text{Conductance } y = \sum_m \left| \left[\hat{\mathbf{G}}_{0,L}^{(L)} \right]_{m,1} \right|^2$$

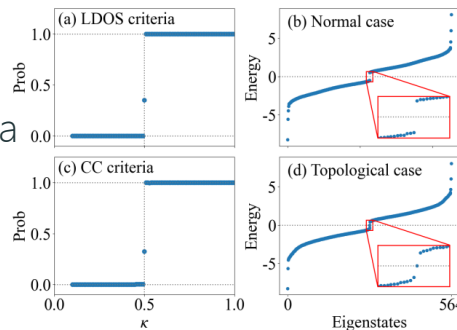
- Observation 3: efficient recursive methods



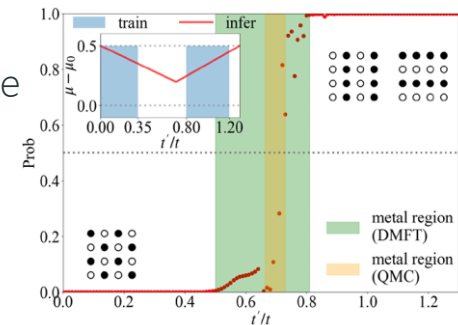
$$\begin{cases} \hat{\mathbf{G}}_{N,N}^{(N)} = \left[z\hat{I} - \hat{H}_N - \hat{T}_{N-1}^\dagger \hat{\mathbf{G}}_{N-1,N-1}^{(N-1)} \hat{T}_{N-1} \right]^{-1} \\ \hat{\mathbf{G}}_{i,N}^{(N)} = \hat{\mathbf{G}}_{i,N-1}^{(N-1)} \hat{T}_{N-1} \hat{\mathbf{G}}_{N,N}^{(N)} \end{cases}$$

- Direct quantum and topological phase recognitions without presumptions:

map and recognize topological phases via collective properties of FQNN models:



recognize emergent charge density wave phases – (un)controlled estimates in FQNNs (original) models:

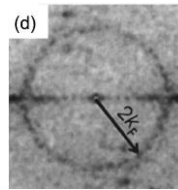
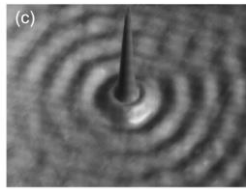


Pei-Lin Zheng, et al. 2023, 2024.



- Interpretation of big, complex experimental data

Quasi-particle interference pattern as a Fermi-surface probe of electron liquids

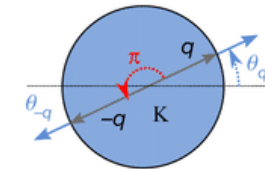
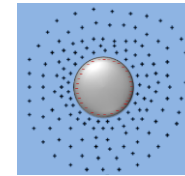


Fourier transform



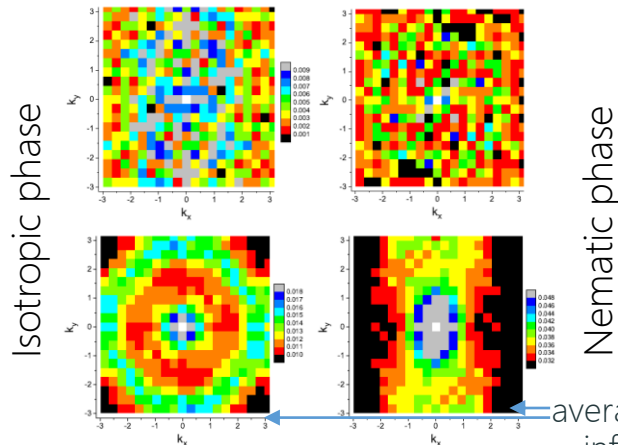
synergy between
experiment and theory

Friedel oscillations as a screening and back-scattering process around a local impurity

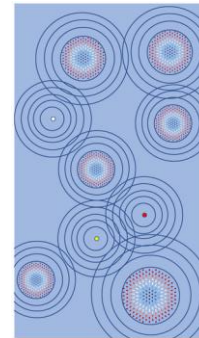


Momentum space

- However, our theoretical capacity largely lags behind our real-world complexity:

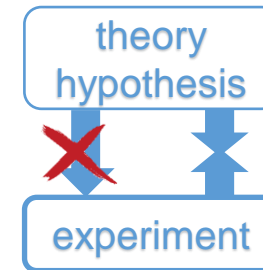


Nematic phase



averaged over 1000 FOVs
= information is still present

Predict
big data,
noisy data,
many-body,
hidden rules,
etc.
Verify



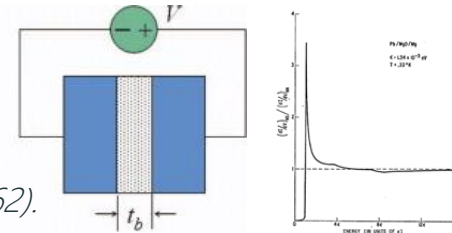
AI interface

Yi Zhang, et al. 2020.

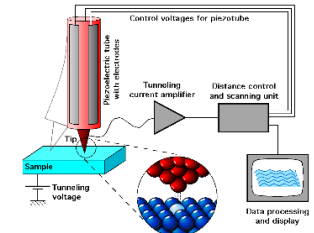


- How experiments have evolved: from

*Giaever et al.,
Phys. Rev. 126, 941 (1962).*

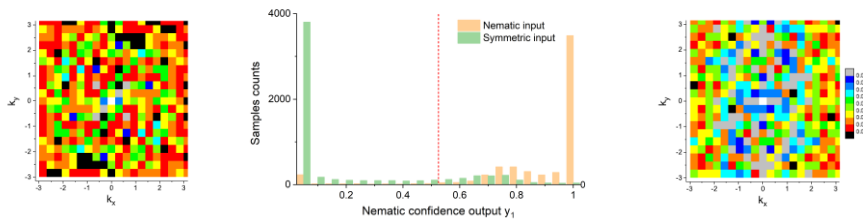


to

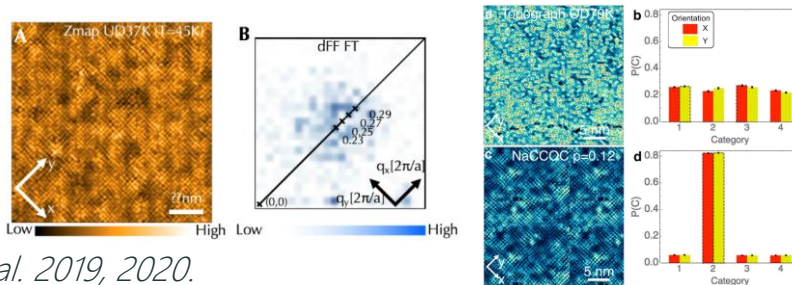


- Idea: Train with the big noisy data, trained for the big noisy data

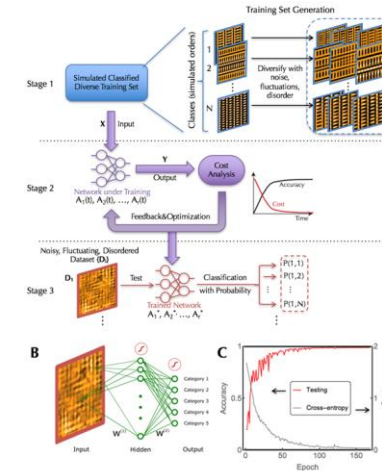
Recognition of nematic phases from STM data



Recognition of CDW phases from STM data

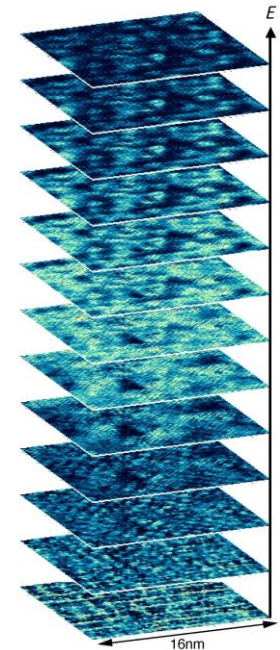


Yi Zhang, et al. 2019, 2020.



generalizable to other big noisy experimental data, e.g. neutron scattering

Anjana Samarakoon, et al. 2020.

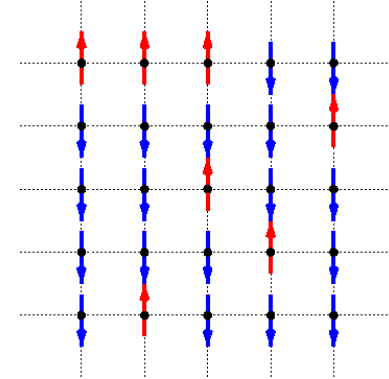


AI for Quantum Monte Carlo Methods

Review: generative AI



- Statistical mechanics: $W(\vec{x}) = \frac{1}{Z} \exp \left[-\frac{E(\vec{x})}{k_B T} \right]$, $Z = \sum_{\vec{x}} \exp \left[-\frac{E(\vec{x})}{k_B T} \right]$
 - Example: Ising model $E(\vec{x}) = -\sum_{\langle ij \rangle} J x_i x_j$, $x_i = \pm 1$
- The Metropolis Algorithm: (also used in simulated annealing)
 1. Generate a random initial state $\vec{x}_{t=0}$ with energy $E(\vec{x}_{t=0})$;
 2. Flip a random spin $x_i \rightarrow -x_i$ and calculate the energy $E(\vec{x}_?)$ of this trial state $\vec{x}_?$;
 3. Calculate the difference in energy generated by the spin flip, $\Delta E = E(\vec{x}_?) - E(\vec{x}_t)$;
 - If $\Delta E \leq 0$ (the trial spin state is energetically favorable), accept the spin flip;
 - If $\Delta E > 0$, accept the spin flip with probability $p = \exp(-\Delta E/k_B T)$;
 4. Measure the target physical quantities, e.g., energy, magnetization, etc.
 5. Repeat steps (2) to (4) until sufficient number N of uncorrelated samples are obtained.



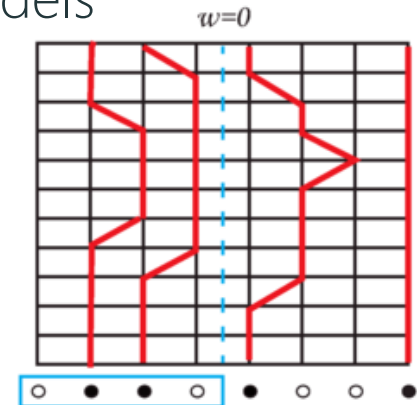
The target probabilities are guaranteed by detailed balance:

$$\frac{W(A)}{W(B)} = \frac{P(B \rightarrow A)}{P(A \rightarrow B)} = \exp \left(-\frac{E_A - E_B}{k_B T} \right)$$



- Also applicable to certain quantum many-body models

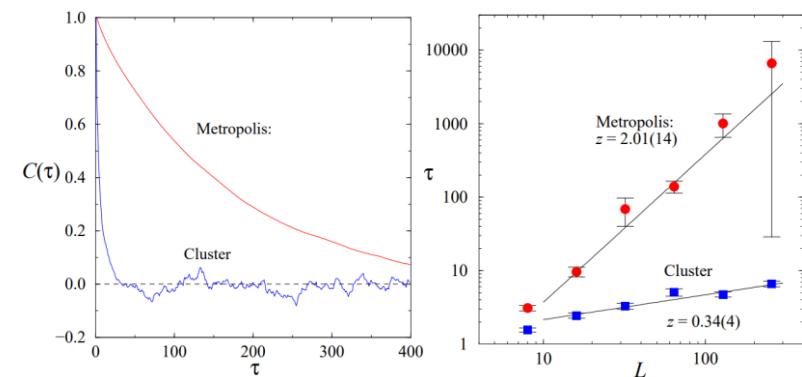
- Auxiliary-Field Quantum Monte Carlo
- Path Integral Monte Carlo
- Determinantal Monte Carlo
- Stochastic Series Expansion Quantum Monte Carlo, etc.



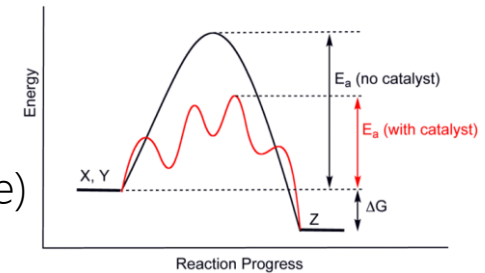
commonly sampling configurations in $(d+1)$ -dims space-(imaginary)-time

- However, local minima cause critical slowing down – cluster update:

1. Choose a random site x_i .
2. Add neighbor site $x_j = x_i$ into the cluster with probability $p = 1 - e^{-2\beta J}$.
3. Grow the cluster until all neighbors are considered. Flip cluster.



- Pros and cons of cluster update:
 - probability $W(\vec{x})$ ensured via detailed balance
 - global updates with high efficiency (100% acceptance rate)
 - yet, heavily reliant on the model



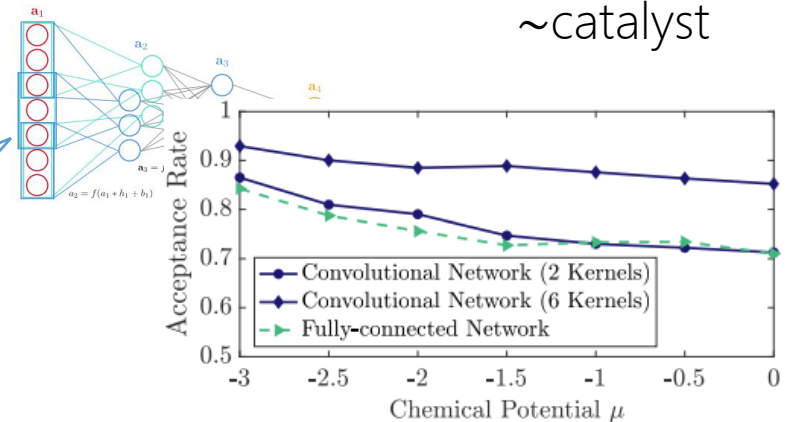
We cannot flip a random cluster with detailed-balance probability, which equals exponentially small acceptance rate! → globally distinctive states with similar weights
~catalyst

- Idea: fitting $W(\vec{x})$ with an AI model:

then accept cluster with acceptance rate:

$$\alpha(A \rightarrow B) = \min\{1, e^{-\beta[(E_B - E_B^{\text{eff}}) - (E_A - E_A^{\text{eff}})]}\}$$

after which the MC is **exact**.



Huitao Shen, Junwei Liu, and Liang Fu, 2018.



- Graph models: probability distribution with statistical mechanics

$$\mu(v) = \frac{1}{Z} \exp \left\{ \sum_i \theta_i v_i + \sum_{(i,j) \in E} \theta_{ij} v_i v_j \right\}$$

- Restricted Boltzmann Machine

“Restricted”

Similar to and trainable as ANN:

- ◆ A *binary* graphic model with no intra-layer connections
- ◆ The configuration probability follows Boltzmann distribution

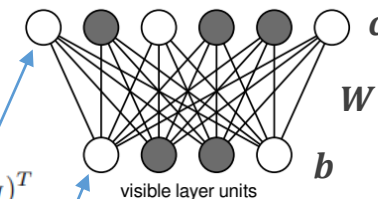
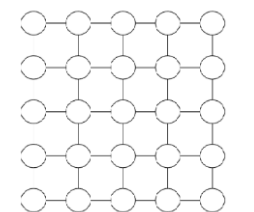
$$P(\mathbf{X}, \mathbf{H}) = \frac{1}{Z} \exp(-E(\mathbf{X}, \mathbf{H}))$$

$$E(\mathbf{X}, \mathbf{H}) = -\mathbf{X}^T \mathbf{b} - \mathbf{c}^T \mathbf{H} - \mathbf{X}^T \mathbf{W} \mathbf{H}$$

- ◆ \mathbf{W} , \mathbf{b} , and \mathbf{c} as model parameters, after training:

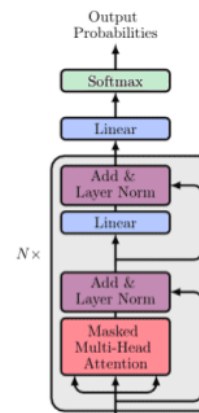
maximize the likelihood of given data
or fit to a given distribution

Generating handwritten digits:



$$\mathbf{H} = (H_1, \dots, H_J)^T$$

$$\mathbf{X} = (X_1, \dots, X_I)^T$$



- Generative Pre-trained Transformer (GPT)



- Example: the Falicov-Kimball model on 2D square lattice

$$\hat{H}_{\text{FK}} = \sum_{i,j} \hat{c}_i^\dagger \mathcal{K}_{ij} \hat{c}_j + U \sum_{i=1}^N \left(\hat{n}_i - \frac{1}{2} \right) \left(x_i - \frac{1}{2} \right)$$

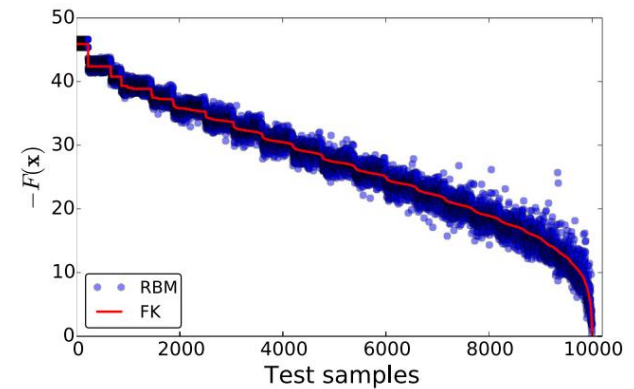
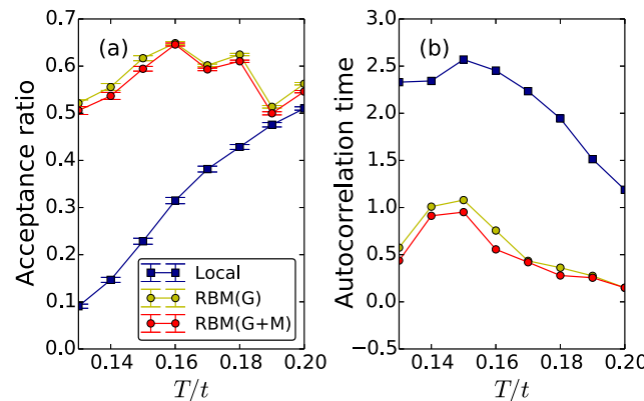
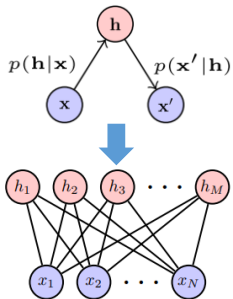
$$p_{\text{FK}}(\mathbf{x}) = e^{-F_{\text{FK}}(\mathbf{x})} / Z_{\text{FK}}$$

$$\left\{ \begin{array}{l} x_i \in \{0,1\} \\ \mathcal{K}_{ij} = -t \quad U/t = 4 \\ \beta = 1/T \end{array} \right.$$

- The trained RBM successfully captures the probability distribution:

compensate with: $A(\mathbf{x} \rightarrow \mathbf{x}') = \min \left[1, \frac{p(\mathbf{x})}{p(\mathbf{x}')} \cdot \frac{p_{\text{FK}}(\mathbf{x}')}{p_{\text{FK}}(\mathbf{x})} \right]$

- Nonlocal updates from hidden variables:



drastically improved acceptance rate and autocorrelation time

Li Huang and Lei Wang, 2017.



AI for Quantum Control and Optimization

Review: reinforcement learning



Quantum Processes – Quantum Compiling




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- ◆ Classical computer:




Logical gates:

AND




IN 1	IN 2	OUT
0	0	0
0	1	0
1	0	0
1	1	1

OR



IN 1	IN 2	OUT
0	0	0
0	1	1
1	0	1
1	1	1

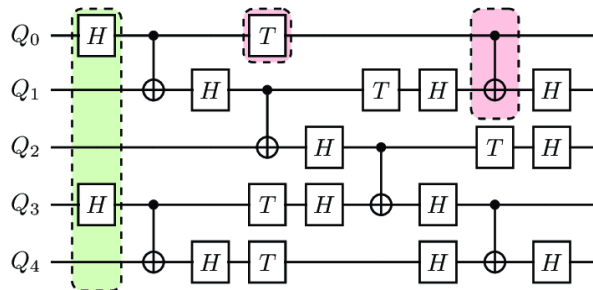
NOT



IN	OUT
0	1
1	0



- ◆ Quantum computer:



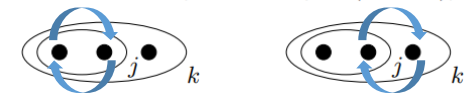
Fundamental quantum gates:

$$\text{Hadamard (H)} \quad \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$$

$$\pi/8 \text{ (T)} \quad \begin{bmatrix} 1 & 0 \\ 0 & e^{i\pi/4} \end{bmatrix}$$

$$\sigma_1 = \begin{pmatrix} \eta^{-4} & 0 \\ 0 & \eta^3 \end{pmatrix} \quad \sigma_2 = \begin{pmatrix} -\phi^{-1}\eta^{-1} & \phi^{-\frac{1}{2}}\eta^{-3} \\ \phi^{-\frac{1}{2}}\eta^{-3} & -\phi^{-1} \end{pmatrix}$$

$$\eta = e^{i\pi/5} \quad \phi = (\sqrt{5} + 1)/2$$



braiding of Fibonacci anyons

Chetan Nayak, et al., 2008.

- Goal: find *fast* a *short* sequence $U \approx U_1^{n_1} U_2^{n_2} U_1^{n_3} U_2^{n_4} \dots$ *close* to U_{tar}

- ◆ brute-force: good length complexity but bad time complexity
- ◆ Solovay-Kitaev (recursive): good time complexity but bad length complexity



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- Reinforcement learning: An agent that interacts with an environment and maximizes reward (minimizes penalty)



AlphaGo

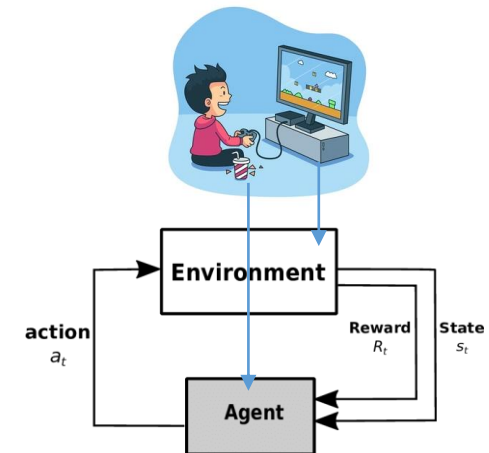


S : current state; A : action upon state; R : reward

$S \xrightarrow{A} S' \xrightarrow{A'} S'' \xrightarrow{A''} \dots \rightarrow \text{target}$

AI ← accumulated reward R

- Video games: S : screen; A : joystick input; R : score, life, cleared levels ...
- Chess, Go: S : current board configuration; A : next move; R : win ...
- Rubik's cube: S : current colorings; A : next twist; R : (minus) steps taken ...



Training the AI model self-consistently with the Bellman equation:

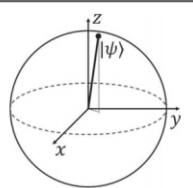

$$Q^{new}(s_t, a_t) \leftarrow \underbrace{Q(s_t, a_t)}_{\text{old value}} + \underbrace{\alpha}_{\text{learning rate}} \cdot \underbrace{\left(\underbrace{r_t}_{\text{reward}} + \underbrace{\gamma}_{\text{discount factor}} \cdot \underbrace{\max_a Q(s_{t+1}, a)}_{\text{estimate of optimal future value}} - \underbrace{Q(s_t, a_t)}_{\text{old value}} \right)}_{\text{new value (temporal difference target)}}$$

temporal difference



- Comparison between Rubik's cube and quantum compiling:

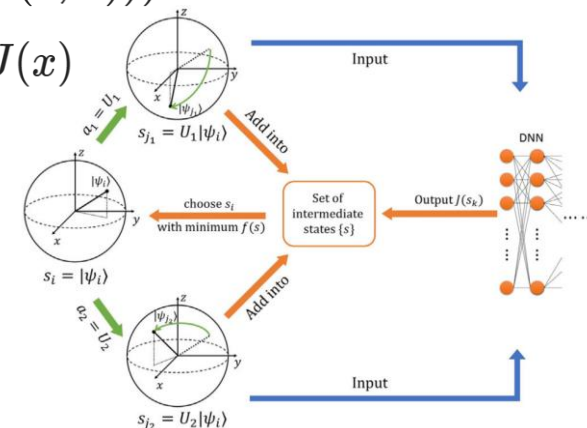
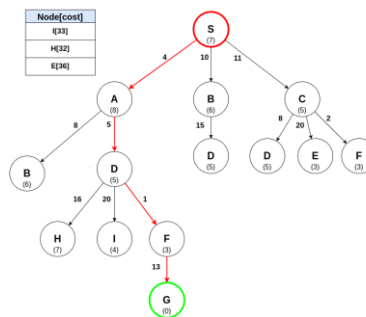
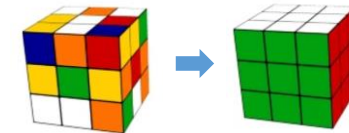
- ◆ S : current configuration / unitary U
- ◆ A : applied rotation / elementary gate U_i
- ◆ R : expected distance towards solution

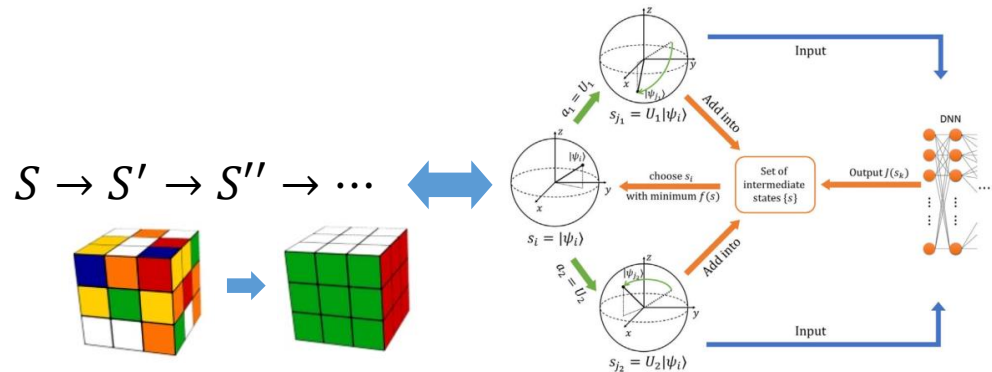
System		
Initial state	The unitary to be approximated	The scrambled cube
Target state	The identity matrix	The solved cube
Basic move	A gate from the universal set	Rotation of one face

- Combine the cost(-to-go) function:

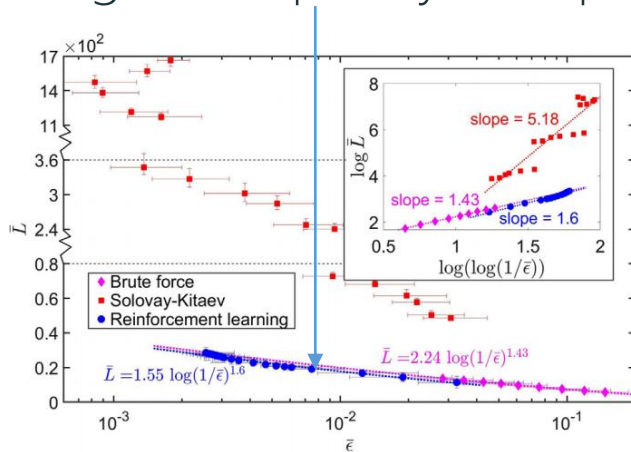
Q-learning: $J(s) = \min_a (1 + J(A(s, a)))$

with the weighted A* search: $f(x) = \lambda g(x) + J(x)$

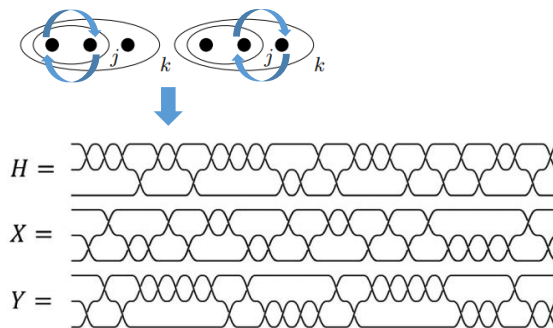




- Time complexity: comparable to the SK recursion, very efficient
- Length complexity: comparable to brute force



Typical target-unitary examples :



better than
 $O(10^{-3})$ precision

A novel *good-enough* solver

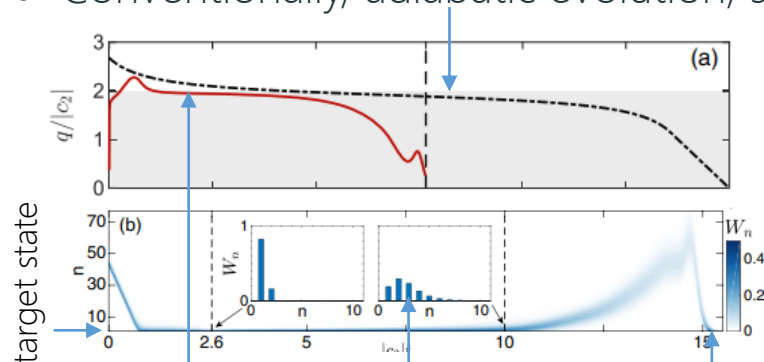
Yuan-Hang Zhang, Pei-Lin Zheng, Yi Zhang, and Dong-Ling Deng, 2020.



- Quantum process – quantum state preparation, e.g., the Dicke state

$$H = \frac{c_2}{2N} \mathbf{L}^2 - q(t)N_0 \quad c_2 < 0 \quad |\psi_{\text{Dicke}}^{(0)}\rangle \equiv |N, L_z = 0\rangle$$

- Conventionally, adiabatic evolution, slowly turn off $q(t)$ to keep at ground state

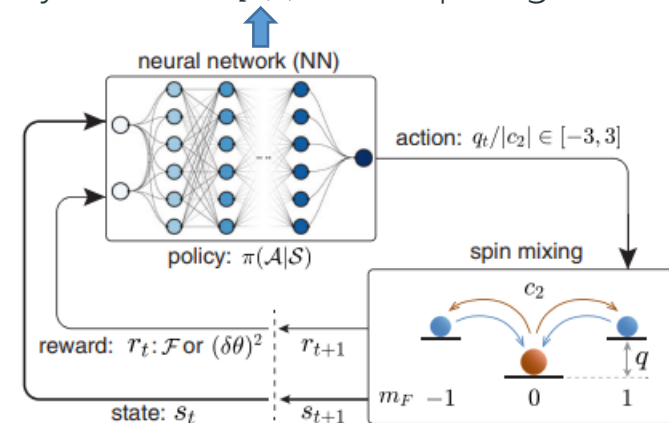


- AI allows to think outside the box:

A faster process is obtained via reinforcement learning

Excited states are generated in the meantime – no adiabaticity

Nevertheless, final state large overlap with target $\mathcal{F} = |\langle \psi(t) | \psi_{\text{Dicke}}^{(0)} \rangle|^2$



$$s_t: \rho_0 = \langle N_0 \rangle / N, \quad \langle \delta N_0^2 \rangle / N^2, \quad |\langle a_{+1}^\dagger a_{-1}^\dagger a_0^2 \rangle| / N^2$$

$$\theta_s = \arg \langle a_{+1}^\dagger a_{-1}^\dagger a_0^2 \rangle$$



- AI for quantum phases: numerical and experimental data and models
- AI for quantum methods: synergy and catalyst for algorithmic efficiency
- AI for quantum control: quantum compiling and state preparation
- Discussions:
 - 'A good chef cannot make a decent meal with no ingredients.'*
 - ◆ No black magic: performance bounded from above by the quality of the samples.
 - ◆ Even for the best case scenario, AI methods are approximate.
 - ◆ Use the knowledge and intuition to improve, every bit helps!
 - ◆ Reverse thinking and consider AI for reverse thinking
 - ◆ Sometimes, trying an idea out is the best way to verify its practicality.
- We are still at an early stage of AI for Physics and Science.

*Know your target
and limitations!*



谢谢



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