Multitask Recommender Systems for Cancer Drug Response

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Contents:

1	Introduction 1.1 Background	2 2 2 3	
2	Installation 2.1 Using Conda	4	
3	Data3.1 Synthetic Data	5 5	
4	Base Classes	7	
5	Single Task Learning	9	
6	Neural Collaborative Filtering	11	
7	Gaussian Processes 7.1 Single Task GPs	15 15 17	
8	Optuna Example Hyperparameter Optimization KNN, SVD, NNMF		
9	Visualizing High-dimensional Parameter Relationships 1.1 Preparing the Dataset	21 22 22 23 23 23 23 23 24	
1(STL and MTL GP Regression Walkthrough O.1 Setting Up Datasets	25 25	

10.2 Single Task Gaussian Process Example	26	
10.3 Multitask Background	27	
10.4 Hadamard Product MTL	27	
10.5 Example Visualizing Covariance Using Getter	28	
10.6 Full Multitask GP with Multitask Kernel	28	
10.7 Example Find Initial Conditions	29	
11 Featurized NCF Example	31	
12 MTL NCF with Pooled MLP Example	33	
13 MTL NCF with Pooled MF	34	
14 Featurized NCF Train Test Curve Example	36	
15 Python Script Example 15.1 Python Script Example	39 39	
16 Indices and tables	40	
Bibliography	41	
Python Module Index		
Index	43	

Hello, this is intended to be technical documentation that will make it easier to use data pipeline and the methods for recommender systems in this project. So far, this proejct consists of wrappers around open source software purposed for multitask learning between datasets containing drug/cancer interactions. For now, these docs aren't intended for developers trying to use this as an API but just collaborators who might want to use the code directly.

If you are reading this and have any suggestions for features to be added / changes to be made email me at ladd12@llnl.gov

Introduction

1.1 Background

The goal of this code is to accurately model the interactions between cancer drugs and cancer cell lines across multiple datasets. Datasets can be from:

- National Cancer Institute (NCI)¹ [Sch11]
- Broad Institute Cancer and Cell Line Encyclopedia² [eal19]
- Genomics and Drug Sensitivity in Cancer³
- National Institute of Health Clincial Trials Reporting Program⁴[Sch11]

1.2 Problem Statement

We need to have each of the following things from each dataset: a sparse ratings/interaction matrix indicating the (IC50) effective concentrations of each drug for each type of cancer and features for each respective drug and cell line. Here are some examples of services that generate theses features:

- Dragon7 (discontinued)⁵
- MOE⁶
- Lincs Cell Features⁷

Then we try to fit machine learning models to this data **to create valid predictors what the outcome of future drug and cancer line interactions will be** in order to inform future experiments and clinical doctors. Finally, in this introduction it will be useful to outline what ML methods we are using and some basic properties.

¹ https://www.cancer.gov/

² https://portals.broadinstitute.org/ccle

³ https://www.cancerrxgene.org/

⁴ https://www.cancer.gov/about-nci/organization/ccct/ctrp

⁵ https://chm.kode-solutions.net/products dragon.php

⁶ https://www.chemcomp.com/Products.htm

⁷ http://www.lincsproject.org/

1.3 Methods

Table 1: ML Methods Used

Method	MTL or STL	Feature Based?	Source
Collaborative Filtering Matrix Fac-	STL and MTL	Feature Based	Surprise
torization			[Hug20]
K Nearest Neighbors	STL	Not Feature	Surprise
		Based	[Hug20]
Nonnegative Matrix Factorization	STL	Feature Based	Surprise
			[Hug20]
Feedforward Neural Net	STL	Feature Based	Custom w/
			Pytorch
			[PGM+19]
Gaussian Process	STL and MTL	Feature Based	Gpytorch
			[GPB+18]
Neural Collaborative Filtering	STL and MTL	Both	Author Github
			[HLZ+17]

1.3. Methods 3

Installation

2.1 Using Conda

- 1. Navigate to root directory, where environment.yml is located
- 2. conda env create -f environment.yml
- 3. conda activate mtl4c_env
- 4. Verify that environment installed correctly with conda env list

Open to any other suggestions for env sharing, like docker.

Data

3.1 Synthetic Data

We can't publish real data, so instead there is a file that will load synthetic data. This file and it's attributes are important for adapting this software. If you want to use this code, the best way would be to create a loader class with similar methods to the methods outlined below.

```
 \begin{array}{c} \textbf{class SyntheticDataCreator}(num\_tasks{=}1, \ cellsPerTask{=}300, \ drugsPerTask{=}10, \\ function{='}gaussian{'}, \ normalize{=}True, \ noise{=}0.1, \\ graph{=}False, test\_split{=}0.3, **kwargs) \end{array}
```

create synthetic data

Args:

num_tasks (int): number of tasks to create

cellsPerTask (int): number of cells to make for each task, this is dimension n of our ratings matrix

drugsPerTask (int): number of drugs to make for each task, this is dimension m
 of our ratings matrix

sparsityPct (int (0,100)): this is the amount of sparsity to put on the ratings matrix, the a higher percentage corresponds to a more sparse prediction matrix. Must be between 0 and 100.

function (string): gaussian or cosine indicating recipe for synthetic data

normalize (boolean): Boolean, whether data should be normalized

test_split (float [0,1]): determines size of training and testing data

noise (boolean): amount of noise to use in creating synthetic data, the higher this value is the less correlation between generated tasks

Returns object with:

self.datasets (list): list of strings indicating dataset names

self.data (dict): multilevel dictionary with keys for train/test, then keys for x,y, then finally keys for dataset name. ie: self.data['train']['x'][name1] gives training data for task 1. The models are built correspondingly.

- self.trainRatings (np.array): array of ratings with shape (n,m) where
 n is the number of training cells / task and m is the number training of
 drugs / task
- **self.testRating (np.array):** array of ratings with shape (n,m) where n is the number of test cells / task and m is the number training of drugs / task

create x and y()

Wrapper for prepare data

 ${\tt generateCosSynthData} (num_tasks = 1, ptsPerTask = 1000, noise = 0.1, graph = False)$

Method used to generate synthetic data with the cosine function. This function selects set of uniform points on interval 0 to 1 and scales them each on intervals of 2c*pi Where c is in range [1,nfeatures] user can set nfeatures in optional_params.txt. Each feature maps to the same y value because they are shfited by one period. Then finally, some noise is added to each y, in order to control the correlation between tasks. The more noise -> the less correlation.

generateSynthData(num tasks=1, ptsPerTask=1000, noise=0.1, graph=False)

Generates gaussian synthetic data. Coefficients apply common linear transformation to multivariate gaussian vectors. Number of gaussian vectors = nfeatures and cna be changed in optional_params.txt to add/remove features. Some noise added to coefficients to control correlation, similar to cosine function more noise -> less correlation.

prepare_data()

Run this public method to prepare data

```
set_test_split(new test split)
```

Update the dict of test split.

shuffle and split()

As stated in the name, shuffles and splits data again. Will fail if data has not been initialized

3.2 Example

Now that we have instantiated dataset object, we can use dataset.data as a dictionary to access all the data

```
task0_train_x = dataset.data['train']['x']['0']
task0_train_y = dataset.data['train']['y']['0']
task0_test_x = dataset.data['test']['x']['0']
task0_test_y = dataset.data['test']['y']['0']
```

3.2. Example 6

Base Classes

```
class BaseEstimator(name, type met, paradigm, output shape)
    Abstract class representing a generic STL Method.
    abstract evaluate()
        Perform prediction.
        Args x (np.array): np.array w/shape (nsamples,nfeatures) y (np.array): np.array
            w/shape (nsamples,1)
        Return results (np.array): np.array of errors
    abstract fit()
        fit model parameters
        Args x (np.array): np.array w/shape (nsamples,nfeatures) y (np.array): np.array
            w/shape (nsamples,1)
    abstract predict()
        Perform prediction.
        Args x (np.array): np.array w/shape (nsamples,nfeatures)
    set output directory(output dir)
        Set output folder path.
        Args: output_dir (str): path to output directory.
    abstract set params()
        Set method's parameters for optuna
class BaseMTLEstimator(name, type met)
    Base class for multitask learning estimators
    fit(x, **kwargs)
        fit model parameters
        Args x (dict): dictionary with keys corresponding to feature vectors for each task
            eg: {"CCLE": np.array w/shape (nsamples,nfeatures)} y (dict): dictionary with
            keys corresponding to output vectors for each task eq: {"CCLE": np.array
            w/shape (nsamples,1)}
    predict(x, **kwargs)
        predict model parameters
```

 $\label{eq:args} \textbf{Args} \ x \ (dict): \ dictionary \ with \ keys \ corresponding \ to \ feature \ vectors \ for \ each \ task \\ eg: \ \{\text{``CCLE'': np.array w/shape (nsamples,nfeatures)}\}$

Single Task Learning

These methods, mainly from Surprise (citation), offer clear recommender system benchmarks.

```
Bases: methods.base.BaseSurpriseSTLEstimator

Matrix Factorization

Args:

n_factors (int): number of latent vectors/factors for matrix factorization

n_epochs (int): Integer, The number of iteration of the SGD procedure. Default is 20

see https://surprise.readthedocs.io/en/stable/matrix_factorization.html for more info

class NonNegative_MF(n_factors, n_epochs=50, name='NonNegative_MF')

Bases: methods.base.BaseSurpriseSTLEstimator

Nonnegative Matrix Factorization

Args:
```

n_factors (int): number of latent vectors/factors for matrix factorizationn_epochs (int): Integer, The number of iteration of the SGD procedure. Default is 20

see https://surprise.readthedocs.io/en/stable/matrix factorization.html for more info

```
class KNN_Basic(k, name='KNN_Basic', sim_options=None)
    Bases: methods.base.BaseSurpriseSTLEstimator
    Args:
```

class SVD MF(*n factors, n epochs=50, name='SVD MF'*)

sim_options (optional): option from surprise for a similarity metric

class NN(input_dim, arch, activation)

Bases: torch.nn.modules.module.Module Vanilla Neural Network implementation

k (int): number of neighbors

Args:

```
input (int): dimension of input data
```

arch (list): list specifying architecture for each layer

activation (string): string specifying what activation to use ie: "ReLU" or "Sigmoid" or "TanH"

forward(x)

Defines the computation performed at every call.

Should be overridden by all subclasses.

Note: Although the recipe for forward pass needs to be defined within this function, one should call the Module instance afterwards instead of this since the former takes care of running the registered hooks while the latter silently ignores them.

Neural Collaborative Filtering

class Neural_Collaborative_Filtering_Features(hyperparams,

name='Neural_Collaborative_Filtering_Features',
type_met='feature_based',
paradigm='stl', output_shape=None,
warm_start=False,
learner=None, learning_rate=None, reg_mf=None,
num_factors=None)

Bases: methods.base.BaseEstimator

Neural Collaborative Filtering adapted from https://github.com/hexiangnan/neural_collaborative filtering

Combines matrix factorization and Multilayer Perceptron. **Uses cell and drug features Args:**

hyperparams (dict):

dictionary containing keys for each hyperparameter.

num_epochs (int): number of epochs to train for

batch size (int): size of each batch in training epochs

mf_dim (int): number of factors to be used by matrix factorization

layers (list): list describing architecure for multilayer perceptron. ie: [32,16,8]

reg_mf (float): regularization penalty for matrix factorization

reg_layer (list): list describing architecure for regularizing multilayer perceptron. ie: [32,16,8]. Must match length of layers

num negatives: ignore this, deprecated

learning_rate (int): learning rate for gradient descent weight optimization

learner (string): name of learner to use. Options are sgd, adam, rmsprop, decayed sgd, scheduled sgd, adagrad

warmstart (boolean): whether to instantiate a model for each task or keep training the same one.

Ignore the other arguments, they are there to pass in hyperparameters with optuna.

Bases: methods.base.BaseEstimator

Neural Collaborative Filtering adapted for regression from https://github.com/hexiangnan/neural_collaborative_filtering

Combines matrix factorization and Multilayer Perceptron. **Does not use cell and drug features**

Args:

hyperparams (dict):

dictionary containing keys for each hyperparameter.

num_epochs (int): number of epochs to train for

batch_size (int): size of each batch in training epochs

mf dim (int): number of factors to be used by matrix factorization

layers (list): list describing architecure for multilayer perceptron. ie: [32,16,8]

reg mf (float): regularization penalty for matrix factorization

reg_layer (list): list describing architecture for regularizing multilayer perceptron. ie: [32,16,8]. Must match length of layers

porception. io. [62/10/0]. Fract materiorigin or

num negatives: ignore this, deprecated

learning_rate (int): learning rate for gradient descent weight optimization

learner (string): name of learner to use. Options are sgd, adam, rmsprop, decayed sgd, scheduled sgd, adagrad

warmstart (boolean): whether to instantiate a model for each task or keep training the same one.

Ignore the other arguments, they are there to pass in hyperparameters with optuna.

class Neural Collaborative Filtering FeaturesMTLMLP(hyperparams,

```
name='Neural_Collaborative_Filtering_Featu

type_met='feature_based',

paradigm='mtl', out-

put_shape=None,

warm_start=False,

learner=None, learn-

ing_rate=None,
```

reg_mf=None,
num factors=None)

Bases: methods.base.BaseMTLEstimator

NCF adapted for multitask model that first trains shared MLP on pooled data, then trains a seperate GMF model for each task.

Combines matrix factorization and Multilayer Perceptron. **Uses cell and drug features Args:**

hyperparams (dict):

dictionary containing keys for each hyperparameter. num_epochs (int): number of epochs to train for

batch_size (int): size of each batch in training epochs

mf_dim (int): number of factors to be used by matrix factorization

layers (list): list describing architecure for multilayer perceptron. ie: [32,16,8]

reg_mf (float): regularization penalty for matrix factorization

reg_layer (list): list describing architecure for regularizing multilayer perceptron. ie: [32,16,8]. Must match length of layers

learning_rate (int): learning rate for gradient descent weight optimization

learner (string): name of learner to use. Options are sgd, adam, rmsprop, decayed sgd, scheduled sgd, adagrad

mlp_lr (float): (0,1) float for learning rate for pooled MLP model.

warmstart (boolean): whether to instantiate a model for each task or keep training the same one.

Ignore the other arguments, they are there to pass in hyperparameters with optuna.

class Neural_Collaborative_Filtering_FeaturesMTLMF(hyperparams,

name='Neural_Collaborative_Filtering_Featur type_met='feature_based', paradigm='mtl', output_shape=None, warm_start=False, learner=None, learning_rate=None, reg_mf=None, num_factors=None)

Bases: methods.base.BaseMTLEstimator

NCF adapted for multitask model that first trains shared MF on pooled data, then trains a seperate MLP model for each task.

Combines matrix factorization and Multilayer Perceptron. **Uses cell and drug features**

Args:

hyperparams (dict):

dictionary containing keys for each hyperparameter.

num epochs (int): number of epochs to train for

batch_size (int): size of each batch in training epochs

mf_dim (int): number of factors to be used by matrix factorization

layers (list): list describing architecure for multilayer perceptron. ie: [32,16,8]

reg_mf (float): regularization penalty for matrix factorization

reg_layer (list): list describing architecure for regularizing multilayer perceptron. ie: [32,16,8]. Must match length of layers

learning_rate (int): learning rate for gradient descent weight optimization

learner (string): name of learner to use. Options are sgd, adam, rmsprop, decayed sgd, scheduled sgd, adagrad

mf_lr (float): (0,1) float for learning rate for pooled MF model.

warmstart (boolean): whether to instantiate a model for each task or keep training the same one.

Ignore the other arguments, they are there to pass in hyperparameters with optuna.

Gaussian Processes

learning rate=0.1,

7.1 Single Task GPs

class ExactGPRegression(name='ExactGP',

```
noise covar=1.0, length scale=100.0, output scale=1.0)
    Bases: methods.base.BaseOwnSTLEstimator
    Exact GP, Gaussian Process evaluated at all training points
    Args:
            name (optional, string): model name
            num iters (int): number of iterations for Gaussian Process
            learning_rate (int): learning rate for conjugate gradient. recommended
               around .1 or .01
            noise covar (float): hyperparamter, noise assumed in the data
        lengthscale (float): hyperparameter, magnitude relative to assumed correlation
            in data
        output scale (optional, float): scaling parameter
class ExactGPCompositeKernelRegression(name='ExactGPCompositeKernel',
                                            num iters=50,
                                                                             learn-
                                                                  noise covar=1.0,
                                           ing rate=0.1,
                                           length scale cell=100.0,
                                           output scale cell=1.0,
                                           length scale drug=100.0,
                                                                               out-
                                           put scale druq=1.0)
    Bases: methods.base.BaseOwnSTLEstimator
    Exact GP where seperate Kernels are evaluated for drugs and cells and then muliplied
    or added to make a shared kernel, Gaussian Process evaluated at all training points
    Args:
            name (optional, string): model name
            num iters (int): number of iterations for Gaussian Process
```

num iters=50,

learning rate (int): learning rate for conjugate gradient. recommended

```
around .1 or .01
            noise covar (float): hyperparamter, noise assumed in the data
        length_scale_cell (float): hyperparameter, magnitude relative to assumed cor-
            relation in cell data
        length scale drug (float): hyperparameter, magnitude relative to assumed cor-
            relation in drug data
        output scale drug (optional, float): scaling parameter for drug data
        output scale cell (optional, float): scaling parameter for cell data
class SparseGPRegression(name='SparseGP', num iters=50,
                                                                learning rate=0.1,
                            noise covar=1.0, length scale=100.0, output scale=1.0,
                            n inducing points=500, use initial=True)
    Bases: methods.base.BaseOwnSTLEstimator
    Sparse GP, Gaussian Process evaluated only at N inducing points sampled from training
    points
    Args:
            name (optional, string): model name
            num iters (int): number of iterations for Gaussian Process
            learning rate (int): learning rate for conjugate gradient. recommended
               around .1 or .01
            noise covar (float): hyperparamter, noise assumed in the data
        lengthscale (float): hyperparameter, magnitude relative to assumed correlation
            in data
        output scale (optional, float): scaling parameter
        n inducing points (optional, int): number of training points to sample from for
            Gaussian Process
class SparseGPCompositeKernelRegression(name='SparseGPCompositeKernel',
                                             num iters=50,
                                                                             learn-
                                             ing rate=0.1,
                                                                  noise covar=1.0,
                                            length scale cell=100.0,
                                            output scale cell=1.0,
                                            length scale drug=100.0,
                                            output scale drug=1.0.
                                             n inducing points=500)
    Bases: methods.base.BaseOwnSTLEstimator
    Sparse GP where seperate Kernels are evaluated for drugs and cells and then muliplied
    or added to make a shared kernel, Gaussian Process evaluated at only n inducing train-
    ing points
    Args:
            name (optional, string): model name
            num iters (int): number of iterations for Gaussian Process
```

```
learning rate (int): learning rate for conjugate gradient. recommended
               around .1 or .01
            noise covar (float): hyperparamter, noise assumed in the data
        length_scale_cell (float): hyperparameter, magnitude relative to assumed cor-
            relation in cell data
        length scale drug (float): hyperparameter, magnitude relative to assumed cor-
            relation in drug data
        output scale drug (optional, float): scaling parameter for drug data
        output scale cell (optional, float): scaling parameter for cell data
        n inducing points (optional, int): number of training points to sample from for
            Gaussian Process
7.2 MultiTask GPs
class HadamardMTL(name='HadamardMTL',
                                                                learning rate=0.1,
                                              num iters=50,
                    noise covar=1.0,
                                        length scale=100.0,
                                                                 output scale=1.0,
                    n inducina points=500.
                                              composite=False.
                                                                    validate=False.
                    bias=False, stabilize=False, use initial=True)
    Bases: methods.base.BaseMTLEstimator
    pipeline suited implementation of https://docs.gpytorch.ai/en/v1.1.1/examples/03
    Multitask Exact GPs/Hadamard Multitask GP Regression.html
            name (optional, string): model name
            num iters (int): number of iterations for Gaussian Process
            learning rate (int): learning rate for conjugate gradient. recommended
               around .1 or .01
            noise covar (float): hyperparamter, noise assumed in the data
        lengthscale (float): hyperparameter, magnitude relative to assumed correlation
            in data
        output scale (optional, float): scaling parameter
        n inducing points (optional, int): number of training points to sample from for
            Gaussian Process
        composite (bool): whether to use composite kernel or not
        validate (bool): whether to produce validation curve data as well during training
        bias (bool): whether to add bias term for each dataset
```

Args:

7.2. MultiTask GPs 17

stabilize (bool): whether to stabilize loss at the end

use initial (bool): whether to even use initial parameters

 $\begin{array}{ll} \textbf{class GPyFullMTL} (name='fullGP', num_iters=50, learning_rate=0.1, noise_covar=1.0, \\ length_scale=100.0, \quad output_scale=1.0, \quad n_inducing_points=500, \\ use_initial=True, num_tasks=1, validate=False) \end{array}$

Bases: methods.base.BaseMTLEstimator

Adapted of Full MultiTask GP model from GpyTorch

Args:

name (optional, string): model name

num_iters (int): number of iterations for Gaussian Process

learning_rate (int): learning rate for conjugate gradient. recommended
 around .1 or .01

noise_covar (float): hyperparamter, noise assumed in the data

lengthscale (float): hyperparameter, magnitude relative to assumed correlation in data

output scale (optional, float): scaling parameter

bias only (bool): deprecated. Do not use.

num_tasks (int): number of tasks you are giving model, should be equal to number
 of datasets

7.2. MultiTask GPs 18



Optuna Example Hyperparameter Optimization KNN, SVD, NNMF

In order for the code below to work for a different method/model, the model should have member functions like this:

```
[2]: import os, sys
    sys.path.append('../')
    import hp optimization as hopt
    from optuna.visualization import plot optimization history, \
                                      plot_intermediate_values, \
                                      plot_contour
    from design import ModelTraining
    from methods.matrix factorization.MF STL import MF STL
    from methods.matrix factorization.MF import SVD MF, NonNegative MF
    from methods.knn.KNN import KNN Normalized
    from shutil import copyfile
    from UTILS.utils import datasetParams2str
    from datasets import SyntheticData as SD
    outdir = '../outputs/experiment 004x' # make sure that it lines up with the experiment
     →'s filename
    if not os.path.exists(outdir):
        os.makedirs(outdir)
```

(continued from previous page)

```
dataset.prepare_data()
[]: methods = [KNN_Normalized(k=10), SVD_MF(n_factors=100), NonNegative_MF(n_
     →factors=100)]
     i = 0
     for method in methods:
         if i == 0:
              study = hopt.optimize hyper params(method, dataset,n trials=5)
              i += 1
         else:
              study = hopt.optimize_hyper_params(method, dataset,n_trials=50)
         plot_optimization_history(study)
         plot intermediate values(study)
         plot contour(study)
         print("best params for "+ method.name + " : ",study.best params)
         # copy the study, i.e. hyperparam trials
         dataset_str = datasetParams2str(dataset.__dict__)
         study_name = '{}_{{}}'.format(method.name,dataset_str)
storage='hyperparam_experiments/{}.db'.format(study_name)
         copyfile(storage, os.path.join(outdir,study name + '.db'))
```

[]:

Visualizing High-dimensional Parameter Relationships

This notebook demonstrates various visualizations of studies in Optuna. The hyperparameters of a neural network trained to classify images are optimized and the resulting study is then visualized using these features.

Note: If a parameter contains missing values, a trial with missing values is not plotted.

```
[]: # If you run this notebook on Google Colaboratory, uncomment the below to install 

→Optuna.
#! pip install --quiet optuna
```

SOURCE: https://github.com/optuna/optuna/blob/master/examples/visualization/plot_study.ipynb

9.1 Preparing the Dataset

```
[]: from sklearn.datasets import fetch_openml
from sklearn.model_selection import train_test_split

mnist = fetch_openml(name='Fashion-MNIST', version=1)
classes = list(set(mnist.target))

# For demonstrational purpose, only use a subset of the dataset.
n_samples = 4000
data = mnist.data[:n_samples]
target = mnist.target[:n_samples]

x_train, x_valid, y_train, y_valid = train_test_split(data, target)
```

9.2 Defining the Objective Function

```
[ ]: from sklearn.neural_network import MLPClassifier

def objective(trial):

    clf = MLPClassifier(
        hidden_layer_sizes=tuple([trial.suggest_int('n_units_l{}'.format(i), 32, 64)_u
        for i in range(3)]),
        learning_rate_init=trial.suggest_float('lr_init', 1e-5, 1e-1, log=True),
)

    for step in range(100):
        clf.partial_fit(x_train, y_train, classes=classes)
        value = clf.score(x_valid, y_valid)

# Report intermediate objective value.
        trial.report(value, step)

# Handle pruning based on the intermediate value.
        if trial.should_prune():
            raise optuna.TrialPruned()

return value
```

9.3 Running the Optimization

```
[]: import optuna

optuna.logging.set_verbosity(optuna.logging.WARNING) # This verbosity change is just

→to simplify the notebook output.

study = optuna.create_study(direction='maximize', pruner=optuna.pruners.

→MedianPruner())
study.optimize(objective, n_trials=100)
```

9.4 Visualizing the Optimization History

```
[ ]: from optuna.visualization import plot_optimization_history
plot_optimization_history(study)
```

9.5 Visualizing the Learning Curves of the Trials

```
[ ]: from optuna.visualization import plot_intermediate_values
plot_intermediate_values(study)
```

9.6 Visualizing High-dimensional Parameter Relationships

```
[]: from optuna.visualization import plot_parallel_coordinate
    plot_parallel_coordinate(study)

[]: plot_parallel_coordinate(study, params=['lr_init', 'n_units_10'])
```

9.7 Visualizing Parameter Relationships

```
[ ]: from optuna.visualization import plot_contour
    plot_contour(study)

[ ]: plot_contour(study, params=['n_units_l0', 'n_units_l1'])
```

9.8 Visualizing Individual Parameters

```
[ ]: from optuna.visualization import plot_slice
    plot_slice(study)
[ ]: plot_slice(study, params=['n_units_l0', 'n_units_l1'])
```

9.9 Visualizing Parameter Importances

[]: from optuna.visualization import plot_param_importances
plot_param_importances(study)

STL and MTL GP Regression Walkthrough

```
[3]: import sys
    sys.path.append('../')
    #from design import ModelTraining
    from datasets import SyntheticData as SD
    import numpy as np
    from sklearn.model_selection import train_test_split
    import pandas as pd
    from time import time
    import matplotlib.pyplot as plt
    import methods.mtl.MTL_GP as MtlGP
    import os
    import numpy as np
    import matplotlib
    import seaborn as sns
```

10.1 Setting Up Datasets

The very first step to running through these Gaussian Process Tutorials is retrieving some data to train our models on. Here we are using the CTRP, GDSC and CCLE datasets mentioned in the introduction.

10.2 Single Task Gaussian Process Example

below is an exaple of training and testing a basic Sparse Gaussian Process from gpytorch with our data.

Next, we have a more complex method, composite kernel Gaussian Process Regression

10.3 Multitask Background

Given a set of observations y_0 we wish to learn parameters θ_x and k^x of the matrix K_f . k^x is a covariance function over the inputs and θ_x are the parameters for that specific covariance function

10.4 Hadamard Product MTL

A clear limitation of the last method is that although it is technically multitask, it will fail to capture most task relationships. In order to do this I'll introduce another spin on vanilla GP Regression.

Now we just have one model parameterized as:

$$y_i = f(x_i) + \varepsilon_i$$
$$f \sim \mathcal{GP}(C_t, K_\theta)$$
$$\theta \sim p(\theta)$$
$$\varepsilon_i \stackrel{iid}{\sim} \mathcal{N}(0, \sigma^2)$$

With one key difference. Our kernel is now defined as: $K([x,i],[x',j]) = k_{inputs}(x,x') * k_{tasks}(i,j)$ where $k_{tasks} \$ is an "index kernel", essentially a lookup table for inter-task covariance. This lookup table is defined $\forall i,j \in the set of tasks T$. Here's a basic example with 4 datapoints and 2 tasks.

rmse = np.sqrt(np.sum(((y_pred[name].numpy() - dataset.data['test']['y'][name])_u

→** 2) / len(y_pred[name])))
print(rmse, name)

10.5 Example Visualizing Covariance Using Getter

```
[]: full_covar = hadamardMTL.model.getCovar().numpy()
   plt.imshow(full_covar)
   plt.imshow(hadamardMTL.model.getCovar().numpy())

[]: from mpl_toolkits.axes_grid1 import make_axes_locatable
   fig, ax = plt.subplots()
   task_covar = hadamardMTL.model.getTaskCovar().numpy() # cast from torch to numpy
   im = ax.imshow(task_covar, cmap="Reds")
   ax.set_xticks([200,800,1300])
   ax.set_xticklabels(dataset.datasets)
   ax.set_yticks([200,800,1300])
   ax.set_yticklabels(dataset.datasets)
   divider = make_axes_locatable(ax)
   cax = divider.append_axes("right", size="10%", pad=0.5)
   cbar = plt.colorbar(im, cax = cax)
```

10.6 Full Multitask GP with Multitask Kernel

10.7 Example Find Initial Conditions

In order to understand what parameters to start at, we can test different configurations of initial conditions

 $(tensor(1.2674, grad_fn=), {'likelihood.noise_covar.noise': 0.7006388902664185, 'covar module.lengthscale': 10.444199562072754})$

```
[ ]:
```

```
sys.path.append('../')
from design import ModelTraining
import matplotlib.pyplot as plt
import methods.matrix_factorization.FeaturizedNCF as NCF_feat
import methods.matrix_factorization.CustomInputNCF as NCF
from datasets import SyntheticData as SD
import numpy as np
from sklearn.model_selection import train_test_split
import pandas as pd
from time import time
from UTILS import utils
import methods.mtl.NCF_MTL as NCF_MTL
```

NonFeaturized NCF

```
[3]: #%capture
    import importlib
    importlib.reload(NCF)
    dataset = SD.SyntheticDataCreator(num tasks=3,cellsPerTask=400, drugsPerTask=10,...
     →function="cosine",
                 normalize=False, noise=1, graph=False, test split=0.3)
    dataset.prepare data()
    hyperparams = {'batch size': 32, 'epochs': 200, 'layers': '[64,32,16,8]', \
                        'learner': 'rmsprop', 'lr': 0.001, 'num factors': 8, 'num neg': 4,,,
     \
                        'reg layers': '[0,0,0,0]', 'reg mf': 0.0, 'verbose': 1, 'warm start
     →':False}
    NCF1 = NCF.Neural Collaborative Filtering(hyperparams, 'name', 'non feature based')
     →# can be feature based
            # it needs to be non bc models does feature transform
                                                                          (continues on next page)
```

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```
# iterate through datasets in single task learning paradigm
y_pred = \{\}
for name in dataset.datasets:
    NCF1.fit(x=dataset.trainRatings[name])
    y pred[name] = NCF1.predict(dataset.testRatings[name])
#rmse
for name in y_pred.keys():
    rmse = np.sqrt(np.sum(((y_pred[name][:,0] - dataset.data['test']['y'][name]) **_
→2) / len(y_pred[name])))
    print(rmse, name)
MODEL HAS BEEN DEFINED
TRAINING...
NCF reinitialized
PREDICTING...
TRAINING...
NCF reinitialized
75
150
PREDICTING...
TRAINING...
NCF reinitialized
75
150
PREDICTING...
0.8048341314316828 0
0.9302123806595449 1
0.9556996063227641 2
```

Featurized NCF Example

```
[4]: #%capture
    import importlib
    #reload python import so we don't have to start and restart kernel
    importlib.reload(NCF feat)
    hyperparams = {'batch_size': 64, 'epochs': 100, 'layers': '[64,32,16,8]', 'learner':
     →'adam', 'lr': 0.001, \
                    'num_factors': 16, 'num_neg': 4, 'reg_layers': '[0.01,0,0,0.01]', 'reg_
     →mf': 0.01,\
                    'verbose': 1, 'warm_start':False}
    NCF2 = NCF_feat.Neural_Collaborative_Filtering_Features(hyperparams, 'name', 'feature_
     ⇒based') # can be feature based
            # it needs to be non bc models does feature transform
    # iterate through datasets in single task learning paradigm
    y pred = \{\}
    for k in dataset.datasets:
        NCF2.fit(x=dataset.data['train']['x'][k], y=dataset.data['train']['y'][k])
        y_pred[k] = NCF2.predict(dataset.data['test']['x'][k])
    #rmse
    for name in y_pred.keys():
        rmse = np.sqrt(np.sum(((y_pred[name][:,0] - dataset.data['test']['y'][name]) **_
     →2) / len(y_pred[name])))
        print(rmse, name)
    model has been defined
    TRAINING...
    NCF reinitialized
    break... model converged
    PREDICTING...
    (1200, 20)
    TRAINING...
    NCF reinitialized
    break... model converged
    PREDICTING...
```

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(1200, 20)
TRAINING...
NCF reinitialized
break... model converged
PREDICTING...
(1200, 20)
0.25058302922958736 0
0.24961774086704824 1
0.25494508025729135 2

MTL NCF with Pooled MLP Example

```
[5]: #%capture
    import importlib
    importlib.reload(NCF_MTL)
    hyperparams_mtlmlp = {'batch_size': 64, 'epochs': 150, 'layers': '[64,32,16,8]', \
                        'learner': 'adam', 'lr': .001, 'mlp_lr': .001, 'num_factors': 10, \
                        'reg_layers': '[0,0,0,.01]', 'reg_mf': 0.01, 'verbose': 1}
    NCF3 = NCF_MTL.Neural_Collaborative_Filtering_FeaturesMTLMLP(hyperparams_mtlmlp, 'name
     →', 'feature_based')
    NCF3.fit(x=dataset.data['train']['x'],
                                        y=dataset.data['train']['y'],
                                        cat_point=dataset.cat_point)
    y_pred = NCF3.predict(dataset.data['test']['x'], dataset.data['test']['y'])
    #rmse
    for name in y_pred.keys():
        rmse = np.sqrt(np.sum(((y_pred[name][:,0] - dataset.data['test']['y'][name]) **_
     →2) / len(y_pred[name])))
        print(rmse, name)
    model has been defined
    PREDICTING...
    0.8660533164359661 0
    0.6996997536437438 1
    0.624245763614103 2
```

MTL NCF with Pooled MF

```
[6]: #%capture
    import importlib
    importlib.reload(NCF MTL)
    'reg_layers': '[0,0,0,.01]', 'reg_mf': 0.01, 'verbose': 1}
    NCF3 = NCF MTL.Neural Collaborative Filtering FeaturesMTLMLP(hyperparams mtlmlp, 'name
    →', 'feature based')
    NCF3.fit(x=dataset.data['train']['x'],
                                   y=dataset.data['train']['y'],
                                   cat point=dataset.cat point)
    y pred = NCF3.predict(dataset.data['test']['x'], dataset.data['test']['y'])
    for name in y_pred.keys():
       rmse = np.sqrt(np.sum(((y_pred[name][:,0] - dataset.data['test']['y'][name]) **_
    →2) / len(y pred[name])))
       print(rmse, name)
    model has been defined
    PREDICTING...
    0.7123474321731185 0
    1.7743642422838766 1
    0.4966135018616864 2
```

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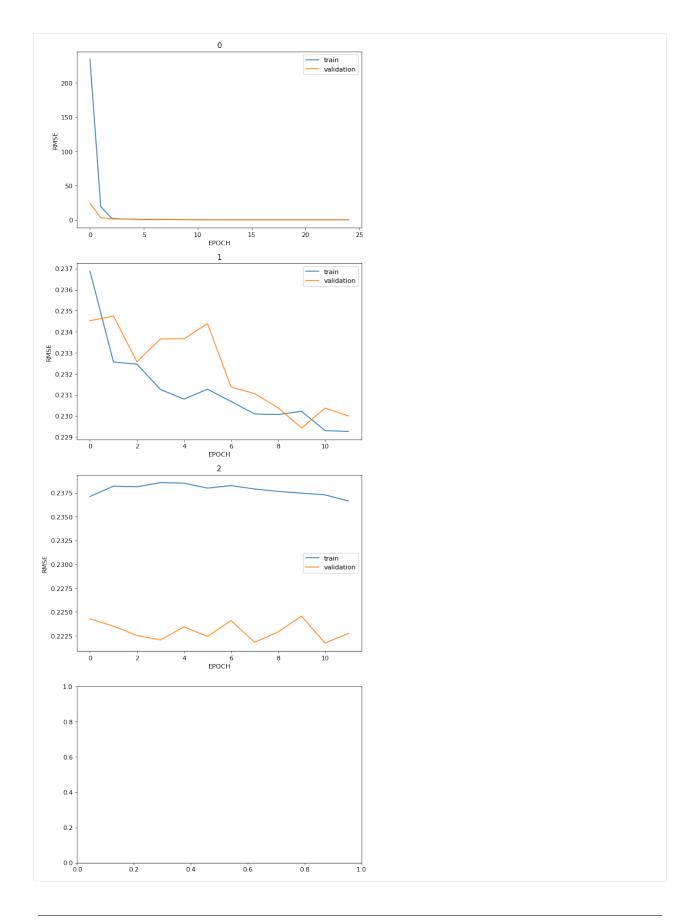
Featurized NCF Train Test Curve Example

```
[7]: #%capture
    import importlib
    #reload python import so we don't have to start and restart kernel
    importlib.reload(NCF feat)
    hyperparams = {'batch size': 64, 'epochs': 1, 'layers': '[64,32,16,8]', \
                        'learner': 'adam', 'lr': 0.001, 'mf_pretrain': '', 'mlp_pretrain':
     \hookrightarrow 1 1, \
                        'num_factors': 16, 'num_neg': 4, 'out': 1, 'path': 'Data/', \
                        'reg_layers': '[0.01,0,0,0.01]', 'reg_mf': 0.01, 'verbose': 1,
     → 'warm start':False}
    model = NCF_feat.Neural_Collaborative_Filtering_Features(hyperparams, 'name',
     →'feature based') # can be feature based
            # it needs to be non bc models does feature transform
    epochs = 600
    batch_size = 64
    plot_counter = 0
    fig, axs = plt.subplots(4, figsize=(8,20))
    for k in dataset.datasets:
        print(k)
        train rmses = []
        test_rmses = []
        for epoch in range(epochs):
             if epoch % 10 == 0:
                 print("epoch : " , epoch)
            t1 = time()
            # Generate training instances
            train_x = dataset.data['train']['x'][k][:30000]
            train_y = dataset.data['train']['y'][k][:30000]
            test_x = dataset.data['test']['x'][k][:10000]
            test y = dataset.data['test']['y'][k][:10000]
             overlap = 0
    #
               for y in test y:
                   if y in train y:
    #
                       overlap += 1
              print(overlap, "Overlap")
             train hist = model.model.fit({'user inputs':np.array(train x[:,:10]), 'item
     →inputs':np.array(train x[:,10:])} \
                                                                           (continues on next page)
```

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```
, np.array(train_y), batch_size=batch_size,_
⇒epochs=1, verbose=0, shuffle=False)
        test_hist = model.model.evaluate({'user_inputs':np.array(test_x[:,:10]),
→'item_inputs':np.array(test_x[:,10:])}, np.array(test_y),
                            batch size=batch size, verbose=0, return dict=True)
        t2 = time()
       #print("train: ",train_hist.history['root_mean_squared error'], "test: ",...
→test hist['root mean squared error'])
       train rmses.append(train hist.history['root mean squared error'])
       test rmses.append(test_hist['root_mean_squared_error'])
       if epoch > 10 and np.max(train rmses[epoch-10:epoch] - np.min(train

¬rmses[epoch-10:epoch])) < .008:</pre>
            print("BREAK")
            break
    axs[plot counter].plot(train rmses)
    axs[plot counter].plot(test rmses)
    axs[plot_counter].set_title(k)
    axs[plot counter].legend(['train', 'validation'])
    axs[plot counter].set ylabel('RMSE')
    axs[plot_counter].set_xlabel('EPOCH')
    plot counter += 1
    print('min train err: ',min(train rmses), "min test err: ", min(test rmses) )
model has been defined
epoch: 0
epoch: 10
epoch: 20
BREAK
min train err: [0.2359551042318344] min test err: 0.23274201154708862
epoch: 0
epoch: 10
BREAK
min train err: [0.22925961017608643] min test err: 0.22942525148391724
epoch: 0
epoch: 10
BREAK
min train err: [0.23665441572666168] min test err: 0.2217150777578354
/usr/tce/packages/python/python-3.7.2/lib/python3.7/site-packages/matplotlib/figure.
→py:2366: UserWarning: This figure includes Axes that are not compatible with tight
→layout, so results might be incorrect.
 warnings.warn("This figure includes Axes that are not compatible "
```



Python Script Example

15.1 Python Script Example

```
import sys
sys.path.append('../')
from design import ModelTraining
from methods.mtl.MF_MTL import MF_MTL
from methods.matrix factorization.MF STL import MF STL
# from methods.regressor.FFNN import FeedForwardNN
from methods.matrix factorization.MF import SVD MF, NonNegative MF
from methods.knn.KNN import KNN Normalized
from datasets.DrugCellLines import DrugCellLinesMTL
if name == ' main ':
    drug_transform = {'type': 'pca', 'num_comp': 10}
cell_transform = {'type': 'pca', 'num_comp': 10}
    dataset = DrugCellLinesMTL(['CCLE', 'GDSC', 'CTRP', 'NCI60'], common=True,
                                unseen cells=False, normalize=True,
                                test_split=0.2, drug_transform=drug_transform,
                                cell transform=cell transform)
    dataset.prepare data()
    methods = [SVD MF(n factors=100),
               KNN Normalized(k=10)]
    metrics = ['rmse', 'explained variance score', 'mae']
    exp_folder = __file__.strip('.py')
    exp = ModelTraining(exp folder)
    exp.execute(dataset, methods, metrics, nruns=1)
    exp.generate report()
```

16

Indices and tables

- genindex
- modindex
- search

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Python Module Index

d
datasets.SyntheticData, 5

Index

В	N
BaseEstimator (class in methods.base), 7 BaseMTLEstimator (class in methods.base), 7	Neural_Collaborative_Filtering (class in meth- ods.matrix_factorization.CustomInputNCF), 12
C create_x_and_y() (SyntheticDataCreator method), 6	Neural_Collaborative_Filtering_Features (class in methods.matrix_factorization.FeaturizedNCF),
D datasets.SyntheticData module, 5 E evaluate() (BaseEstimator method), 7 ExactGPCompositeKernelRegression (class in methods.regressor.ExactGPCompositeKernel), 15 ExactGPRegression (class in methods.regressor.ExactGP), 15	Neural_Collaborative_Filtering_FeaturesMTLMF
F fit() (BaseEstimator method), 7 fit() (BaseMTLEstimator method), 7 forward() (NN method), 10 G generateCosSynthData() (SyntheticDataCreator method), 6 generateSynthData() (SyntheticDataCreator method), 6 GPyFullMTL (class in methods.mtl.MTL_GP), 17 H HadamardMTL (class in methods.mtl.MTL_GP), 17 K KNN_Basic (class in methods.knn.KNN), 9 M	Set_output_directory() (BaseEstimator method), 7 set_params() (BaseEstimator method), 7 set_test_split() (SyntheticDataCreator method), 6 shuffle_and_split() (SyntheticDataCreator method), 6 SparseGPCompositeKernelRegression (class in methods.regressor.SparseGPCompositeKernel), 16 SparseGPRegression (class in methods.regressor.SparseGP), 16 SVD_MF (class in methods.matrix_factorization.MF), 9 SyntheticDataCreator (class in datasets.SyntheticData), 5
module datasets.SyntheticData, 5	