KiboCUBE Academy

Lecture 08

Introduction to CubeSat Power Control System

Teikyo University

Department of Aerospace Engineering

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This lecture is NOT specifically about KiboCUBE and covers GENERAL engineering topics of space development and utilization for CubeSats.

The specific information and requirements for applying to KiboCUBE can be found at:

https://www.unoosa.org/oosa/en/ourwork/psa/hsti/kibocube.htm







Lecturer Introduction





© The University of Tokyo / NESTA, 2014 (from Left) **UNIFORM-1, HODOYOSHI-3, HODOYOSHI-4**

Fight model picture before shipping, April 2014

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Position:

2010 - Ph.D. Degree in Kyushu University

2010 - Project Researcher, Kyushu University – QSAT-EOS Project

2011 - Project Researcher, Tokyo University – UNIFORM-1 & Hodoyoshi-3/4 Project, TRICOM Project

2017 - Project Lecturer, Tokyo University – AQT-D/RWASAT-1 Project, MicroDragon Project

2020 - Lecturer, Teikyo University – TeikyoSat-4 Project

Research Topics:

Micro/Nano/Pico-Satellite System Design and Electrical Components Design, Ground Station Development

Contents

- 1. Introduction
- 2. Power Generation
- 3. Power Storage
- 4. Power Control and Distribution
- 5. EPS Subsystem Integration
- 6. Conclusion



1.1. Introduction of EPS for Micro/Nano/Pico-satellite (CubeSat)

EPS (**Electrical Power Supply**) is the most important subsystem from the viewpoint of energy handling

Typically, the EPS Consists of

- Power **generation**
- Power storage
- Power control & distribution

Keywords;

- **Efficiency** (per unit mass or per unit area)
- **Robustness** (for mission success)
- **Redundancy** (for mission success)
- **Safety** (for Launcher requirements)

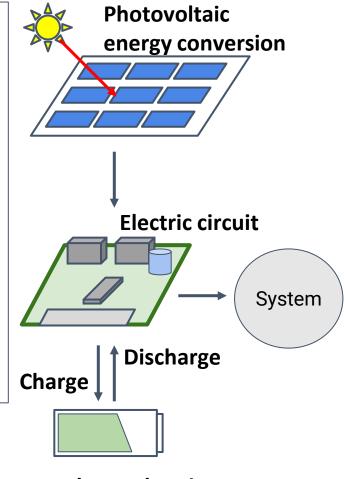
EPS

Electrical

Power

Supply

(Subsystem)

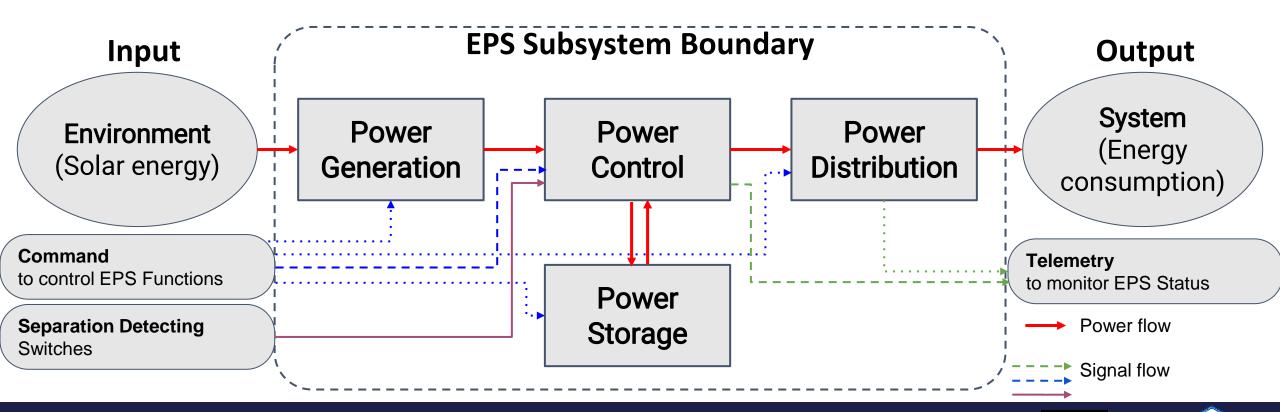


Electrochemistry energy conversion

1.2. EPS Architecture Examples for Micro/Nano/Pico-satellite (CubeSat)

Architecture: the style and design of a building or buildings → the **style** and **design** of **a system**

- The number of components
- The kind of components
- The connections between components (voltage, current, signal, ground)



1.2. EPS Architecture Examples for Micro/Nano/Pico-satellite (CubeSat)

Typical EPS Architectures

[1] Solar cell only: Rare case (System is not able to work during an eclipse)

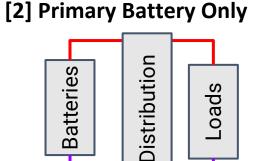
[2] Primary battery only: Rare case (System is able to work up to the battery life)

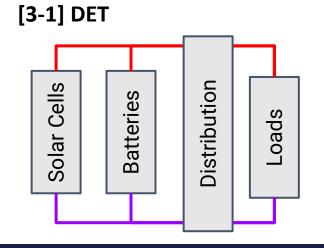
[3] Solar cell + secondary battery: Major use (for long-time operation)

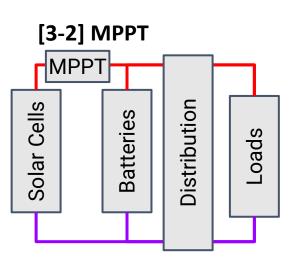
[3-1] **DET(Direct Energy Transfer)**Direct solar cell connection

[3-2] MPPT (Max Peak Power Tracking) control

Solar Cells Cells Distribution Loads







1.2. EPS Architecture Examples for Micro/Nano/Pico-satellite (CubeSat)

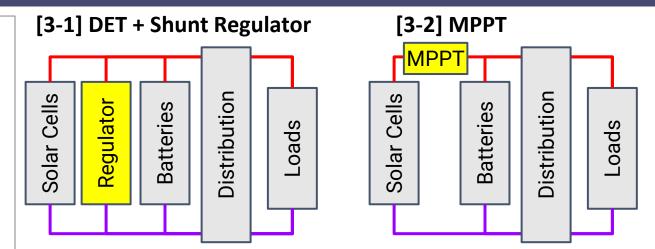
Comparison of DET vs MPTT

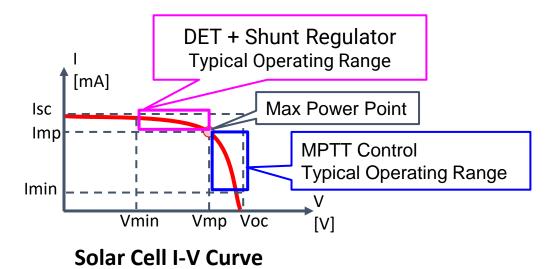
[3-1] DET(Direct Energy Transfer) + shunt regulator

- Shunt regulator circuit is connected between solar cells and batteries in parallel to control solar cell operating points
- ☐ Typical operating range: **near CC** (Constant Current) from Vmin to near Vmp

[3-2] MPPT (Max Peak Power Tracking) control

- MPPT circuit is connected between solar cells and batteries in series to control solar cell operating point
- ☐ Typical operating range: **near CV** (Constant Voltage) from Imin to near Imp





1.3. Key Concepts of EPS for Micro/Nano/Pico-satellite (CubeSat)

Key Concepts for better EPS Design and Implementation Efficiency (per unit mass or per unit area) Solar cell: $[W/m^2] \rightarrow [\%]$ (Solar energy conversion efficiency) Battery: [Wh/kg] (Capacity per unit mass) DC/DC converter: [%] (Energy transfer efficiency: output power / input power) **Robustness** (for mission success) Failure risk minimization **Redundancy** (for mission success) Fault tolerant, stand-by alternative functions, backup **Safety** (for launcher requirements) Never cause a catastrophic/critical hazard during launch

1.3. Key Concepts of EPS for Micro/Nano/Pico-satellite (CubeSat)

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Primary Design Process for EPS			
 Step 1: Identify requirements → Orbit type, mission life, payload definition, duty ratio of bus functions 			
☐ Step 2: Select and size power source→ Power generation (solar cell)			
☐ Step 3: Select and size power storage→ Power storage (battery)			
☐ Step 4: Identify power control & distribution architecture			
Iteration is needed until all interface conditions and requirements are satisfied			

Step	Information Required
1. Identify requirements	Top-level requirements, mission type and orbit (LEO or GEO) satellite configuration, mission life, payload definition
2. Select and size power source	Mission type, satellite configuration, average load for electrical power
3. Select and size energy storage	Mission orbital parameters, average and peak power load requirements
4. Identify EPS architecture	Power source selection, mission life, regulating for mission load thermal control requirement

1.3. Key Concepts of EPS for Micro/Nano/Pico-satellite (CubeSat)

Consideration priority for a reasonably reliable EPS design and implementation

- 1. Keep a simple configuration and a simple operation plan (single task)
- 2. Select devices with **low power** consumption and that have been **demonstrated on-orbit as much as possible**
- 3. The CPU (or equivalent control unit / digital controller) of the EPS component should be able to recover from hang-ups by a power-on reset (especially, for tolerance against TID/SEU/SEL)
- 4. Failure recovery options and redundant configurations
- 5. Pursuit of **power conversion efficiency**
- **6. Advanced** functions (Autonomous control, parallel tasks)

After upper level design and verification has been considered, move on to the next step

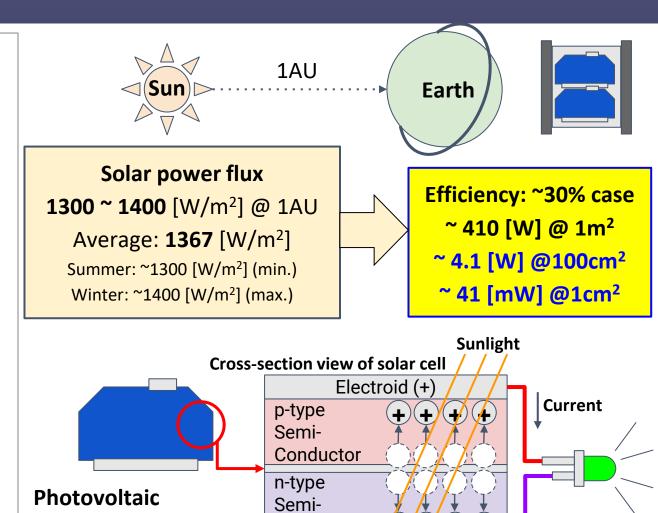
1.3. Key Concepts of EPS for Micro/Nano/Pico-satellite (CubeSat)

Pra	ctical Know-How for Better Power Balance Design
	Relationship between Power generation and satellite attitude mode (solar cell coverage ratio to sun) Sun pointing: Power generation is rich Earth pointing: Depends on the angle b/t sunshine and solar cell panel Tumbling: Smaller power generation Accuracy of power generation is dependent on the development level and maturity of the Attitude Control Subsystem
	Enough power modes (the combination of components being ON/OFF) should be defined The minimum power mode for survival independent on the satellite attitude
	Identify constant power-ON components and ON/OFF controllable components Constant power-ON components: PCU, PDU, Sensors, MTQs, etc. ON/OFF controllable components: Mission camera, mission data transmitter, etc. (operation plan example) Mission data downlink, 8 mins above Japan; image shooting 5 min×10 times Management of surplus or lack of power by controlling the operating time or duty ratio of the mission device, high-power transmitter, or actuators (MTQs or RWs)



2.1. Introduction of Solar Cell

- □ Power generation on CubeSats is realized by solar power architecture (solar cells / solar panels / solar arrays)
- ☐ Solar cell: a semiconductor device applying a photovoltaic effect (same structure as a diode)
- ☐ Solar power flux is **1367 [W/m²]** in orbit average at 1 AU (Astronomical Unit)
 - □ $100 \text{cm}^2 (10 \text{cm x } 10 \text{cm}) \rightarrow \sim 4.1 \text{ [W]}$ at solar cell **efficiency** $\sim 30\%$ case
 - ☐ Filling efficiency considering mechanical interface of a CubeSat frame is ~65-70%
 - → ~ 2.6 [W] per 1 surface 1U CubeSat (at nominal temperature condition: ~25 degC)



Conductor

Electroid (-

energy conversion

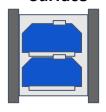
concept diagram

2.2. Major Characteristics of Solar Cell

Solar Cell Selection Checkpoints Triple-Junction(TJ) (or Multi-Junction) type solar cell is popular (high-efficiency) Solar cell hardware configuration **CIC: Cover-glass Interconnected Cell** is better from the viewpoint of easy assembly Thickness of cover-glass affects the lifetime against total dose on-orbit **Dimension** and **position of the electrodes** affects the solar panel design (cell layout) Within 80 x 40 mm size cell is popular \rightarrow In the case of 1U CubeSat, 2 solar cells are allocated on a surface option: 2 series? or 2 parallel? (depends on the power control circuit design)



Typical 1U CubeSat Surface



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Typical Spec. of Solar cell	Typical Si-Cell	Typical TJ
Open Circuit Voltage [V]	0.6	2.7
Short Circuit Current [mA]	1150	410
Max. Power [W]	0.5	1.0
Max. Power Voltage [V]	0.5	2.5
Max. Power Current [mA]	1000	500
Efficiency	15 ~ 17 %	28 ~ 30%
Dimensions [mm]	60 x 40	80 x 40
Mass [g]	~~	~~

Solar Cell Panel Array Considerations

How many in series? : MPPT input voltage

How many in parallel? : Operational time & margin

2.3. Design and Testing of Solar Cell Panel

Solar Cell Properties Investigation

- Performance test: V_{OC} , I_{SC} , I_{mp} , V_{mp} , P_{mp}
 - ☐ Using solar simulated light: 100% on orbit (with isothermal stage to change the cell surface temperature)
 - ☐ Performance evaluation : I-V curve and P-V curve corresponding to datasheets
 - Nominal Pmp: ~1.25 [W] @Vmp = 2.0 [V]
 Hot case: ~1.0 [W] @Vmp = 2.5 [V]
 Cold case: ~1.5 [W] @Vmp = 3.0 [V]

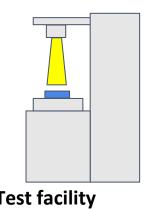
(Refer to the datasheet when this kind of performance test is not able to be performed by your own project)

[Important]

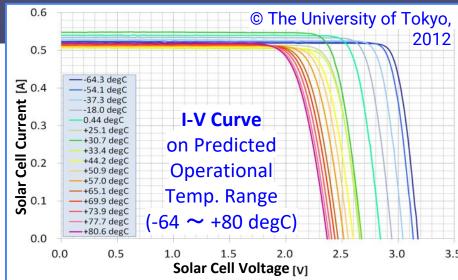
Identification of performance change on the operational temperature range

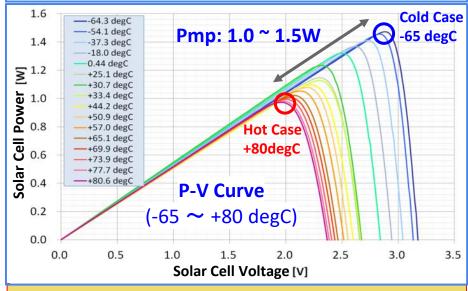


Test cell coupon
Triple-Junction
(GalnP2/GaAs/Ge)
CIC-type product
efficiency: ~29%



Test facility conceptual image



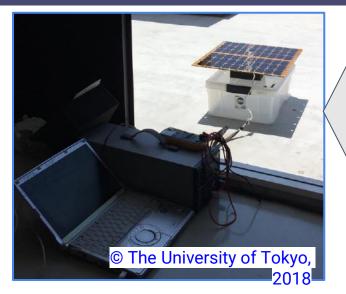


Data example based on a past MicroSat mission

2.3. Design and Testing of Solar Cell Panel

Solar Cell Panel Tests

- ☐ Functional tests to confirm workmanship
 - ☐ Under natural sunlight
 - Using solar simulated light
 - Using large testing facility
- ☐ Performance evaluation test: I-V curve
 - ☐ Under natural sunlight
 - Using large testing facility



Outdoor by using natural sunlight

~ 65 - 70% of 1 Solar on Orbit

Inside room
by using
small solar lamp

~ 10 -15%

of 1 solar on orbit



Experiment image example based on past MicroSat mission

2.4. Examples of Solar Cell Panel Products

Solar Cell Panel Design Example (for CubeSat)

- ☐ Solar Cell: **3 series** x **1 parallel** configuration
- ☐ 1 String(series connection): 1 same surface (Never connect on the other surface in series)
- Solar cell panel assembly checkpoints
 - ☐ Interconnectors (electrodes) attaching process (soldering or spot welding)
 - ☐ Gluing workmanship for cell attaching
 - → air bubbles remaining must be avoided
 - ☐ Clearance b/t cells and bolt holes
 - Electrical insulation



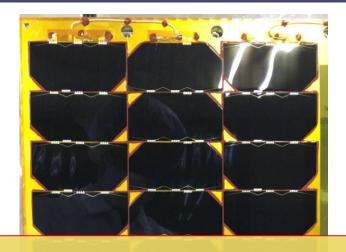
A design example based on a past ISS CubeSat mission (sample product image)



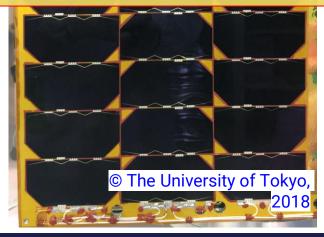
2.4. Examples of Solar Cell Panel Products

Solar Cell Panel Design Example (for MicroSat)

- ☐ 1 solar cell string = 10 or 20 series
- Same checkpoints as the CubeSat case are also important
- ☐ Solar cell layout & clearance each cells
 - ☐ As increasing of series number, difference of voltage b/t closest cells must be careful
 - → To reduce the risk of discharging to cause dielectric breakdown of cells
 - [Recommended min. clearance: 1mm]
 - ☐ Current loop of each solar cell string
 - → To reduce the effect of magnetic force generation by current loop (one of attitude anomaly causes)



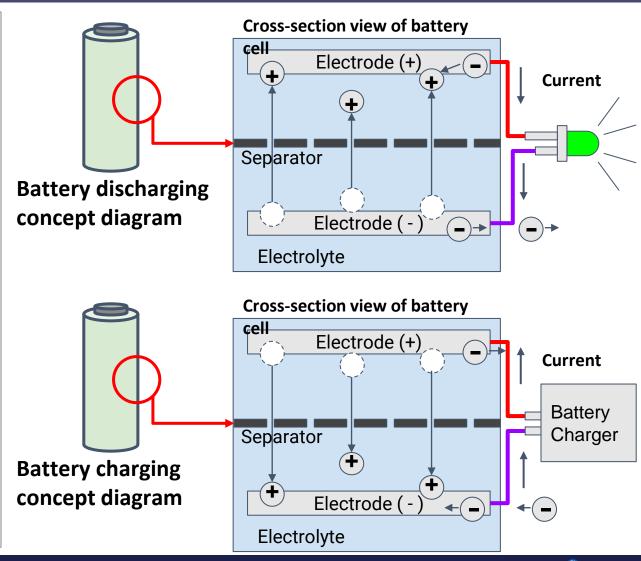
A design example based on a MicroSat mission (sample product image)





3.1. Introduction of Battery

- ☐ Solar energy is not always available during operations; the orbit condition (eclipse), or peak loads over the solar cell power generation
- Primary and secondary batteries are used for power storage
- □ Battery cell is an electrochemistry device applying oxidation-reduction reactions (ion generation)
- Batteries are classified according to their different electrochemistry.
- □ As primary-type batteries are not rechargeable, they are typically used for short mission durations



3.2. Major Characteristics of Battery

Secondary Battery (Rechargeable) Options

- Datasheets must be checked before purchasing the battery cells
- ☐ Initial inspection and screening tests should be performed by the project to select better cells for the fight model
- ☐ **Ni-MH** type is **safer**, but mass efficiency is smaller than typical Li-Ion cell
- ☐ **Li-Ion** type is **more efficient**, but the hazard risk is relatively high

Project decision: Ni-MH or Li-Ion (depends on the maturity level of project members) especially for the case of Li-Ion, a well-educated person must handle the cell

Typical Spec. of Battery	Typical Ni-MH	Typical Li-lon
Typical Voltage [V]	~1.2	~3.6
Voltage Range [V]	1.0 ~ 1.5	2.5 ~ 4.2
Capacity [Ah]	1.0 ~ 2.5	3.0 ~ 3.5
Max. Discharging Current [A]	~ 5.0	3.0 ~ 6.0
Temperature Range [degC]	-20 ~ +50	0 ~ +40
Dimensions [mm]	Ф15 x L50	Ф18 x L65
Mass [g]	30	50

Battery Module Assembly

How many in series? : Bus voltage

How many in parallel? : Operational time

3.3. Design and Testing of Battery

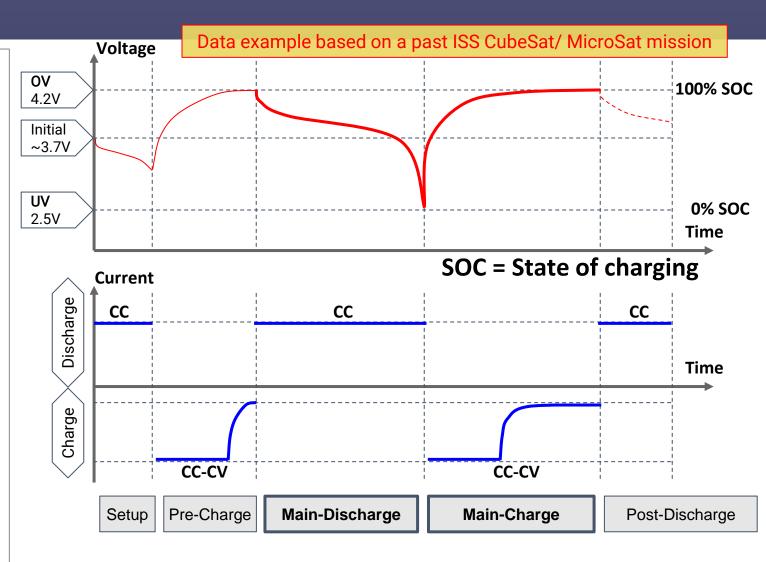
Battery Cell Performance Verification

- Use common charging and discharging profiles for battery cell performance measurements
- ☐ Current condition, charging stop voltage (Over Voltage Condition), discharging stop voltage (Under Voltage Condition) depends on the individual battery cell-type (Check the battery cell datasheet)
- ☐ (Recommended option)

 Keep a constant temperature during measurement by using an isothermal chamber

[Important]

Temperature characteristics must be checked!



Charging and discharging measurement profile setting example

3.3. Design and Testing of Battery

Battery cell performance on the operational temperature range

- General properties of a battery cell against temperature changing
 - Hot condition is **better**

[+25 ~ +40 degC]

(enhance internal electrochemical

reaction)

Cold condition is **bad**

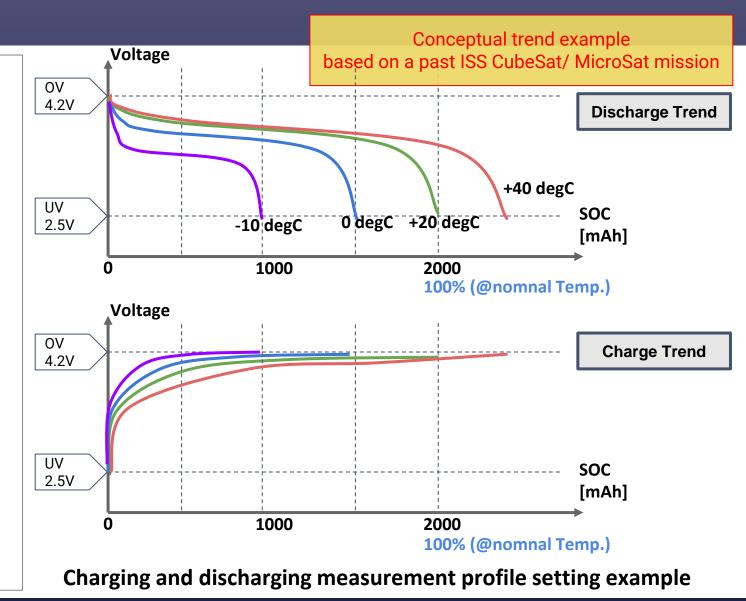
[< 0 degC]

(become severe to perform

charging/discharging

by **internal resistance** increasing)

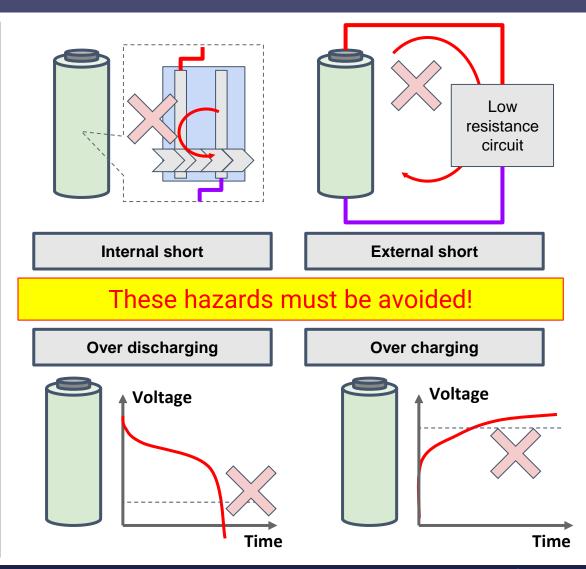
consider this point for power budget analysis



3.4. Safety Design and Testing of Battery

Typical Battery Cell Hazards

- ☐ Internal short: Initial failure, structural damage [Action] screening test (described on next page)
- ☐ External short: Circuit failure, workmanship error
 [Action] current shut-down function test of fuse device
 or PTC (Positive Temperature Coefficient) device
- Over charging: Circuit failure, workmanship error [Action] power control circuit function test or battery protection circuit function test
- → Over discharging: Circuit failure, workmanship error [Action] power control circuit function test or battery protection circuit function test



3.4. Safety Design and Testing of Battery

Battery Cell Safety Properties Verification (to mitigate the risk of internal short)

- Standard check process including charging and discharging profile measurements
- 2-kinds of environmental tolerance tests
 - □ Vacuum leak test

If there are any cells with a leakage problem, its mass could change significantly before and after the test

☐ Random vibration test

If there is a cell with a problem in its internal structure, there could be a large difference in charge/discharge characteristics before and after the test

Must refer to the latest test requirement documents from the launch opportunity

Example test & check flow (based on past CubeSat mission)

Check #1

Vacuum leak test Check #2

Random vibration test

Check #3

Contents of Check (Common for #1, #2, #3)

- Visual inspection / Odor confirmation
- Mass measurement
- OCV (Open Circuit Voltage) measurement
- Charge and discharge characteristics
- Discharge temperature characteristics test
- Discharge capacity measurement

Check points

Mass change

OCV change

Capacity change



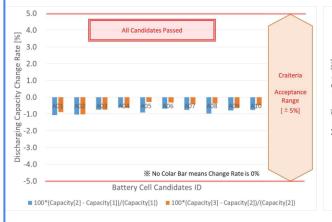
3.4. Safety Design and Testing of Battery

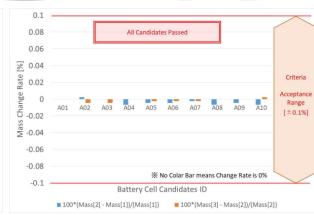
Battery Cell Safety Properties Verification (to mitigate the risk of internal short)

- ☐ Differences of each check (#1→#2, #2→#3) should be summarized in a table (Example: Table as shown in the upper left)
- Check which of these differences meet the requirement or not (Example: Graphs as shown in the lower left)
- ☐ Select the passed cells and consider pairing of the same parallel combinations (similar profile cells must be paired)

Example of battery cell check result table & figures

ID	Visual	Odor	Mass [g]	OCV [V]	Internal	Discharge	Discharge	Charging
	Check	Check			Resistance	Capacity	Temp.	Discharging
					[mΩ]	[mAh]	Increase	Profile
							[degC]	
A01	Fine	Fine	45.838	3.673	36.5	3160.91	+5.2	Fine
A02	Fine	Fine	45.902	3.674	37.4	3162.15	+4.8	Fine
A03	Fine	Fine	45.831	3.673	40.0	3149.74	+4.3	Fine
A04	Fine	Fine	45.663	3.674	39.6	3162.91	+4.2	Fine
A05	Fine	Fine	45.654	3.672	37.2	3149.92	+4.3	Fine



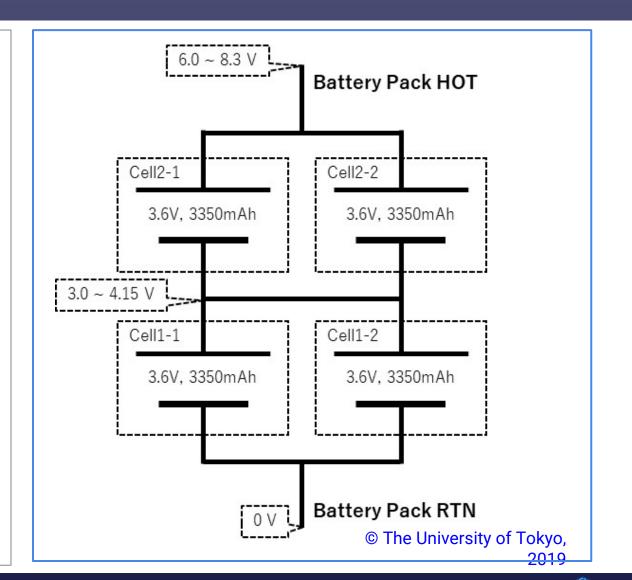


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3.5. Examples of Battery Module Products

Battery Module Design Example

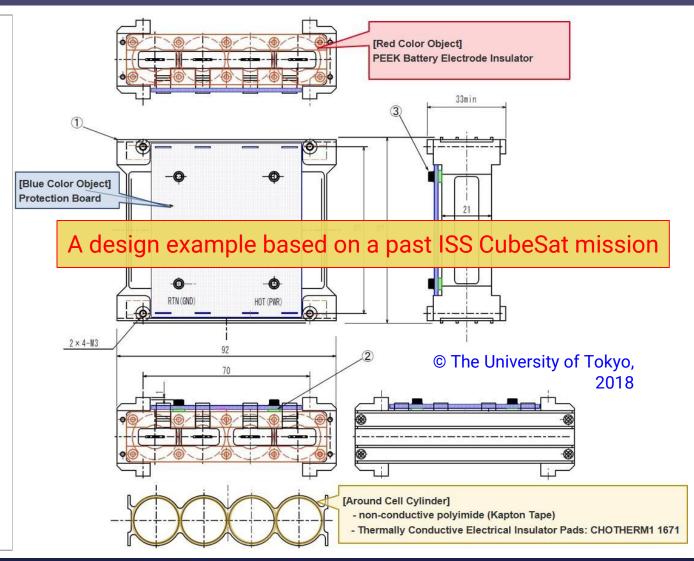
- Li-Ion battery: 2 series x 2 parallel (2S2P) configuration (Total: 4 cells)
- **Ladder-type connection**
 - → Mid-point b/t 1st stage and 2nd stage is connected (depends on the cell characteristics)



3.5. Examples of Battery Module Products

Battery Module Design Example

- ☐ Li-Ion battery: 2 series x 2 parallel configuration (4 cylindrical cells case)
- Mechanical integration checkpoints
 - ☐ Fasten holdings around the cell to reduce the risk of displacement by vibration / shock conditions during launch
 - ☐ Thermal conductivity or thermal insulation conditions (depends on the thermal environment of the CubeSat)
 - ☐ Electrical insulation around electrodes (+ / -)



3.5. Examples of Battery Module Products

Battery Module Design Example

- ☐ Li-Ion battery: 2 series x 2 parallel configuration (4 cylindrical cells case)
- Mechanical spec. checkpoints
 - ☐ Black color

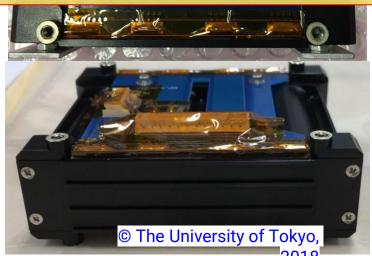
 thermal conductivity

 or thermal insulation condition

 (depends on thermal analysis of entire satellite)
 - ☐ Electrical insulation around electrode (+ /)



A design example based on a past ISS CubeSat mission (sample product image)



Dimensions: 92 x 78 x 34 mm

Mass: 330 g



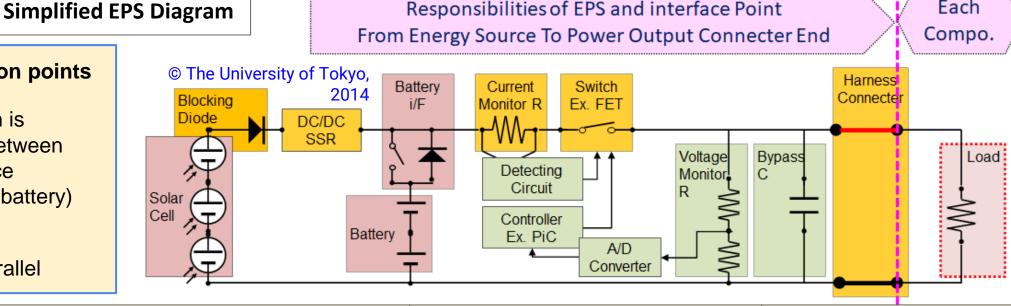
4.1. Introduction of EPS Circuit Design



Consideration points

How the item is connected between energy source (solar cell or battery) and load?

Series or Parallel



Responsibilities of EPS and interface Point

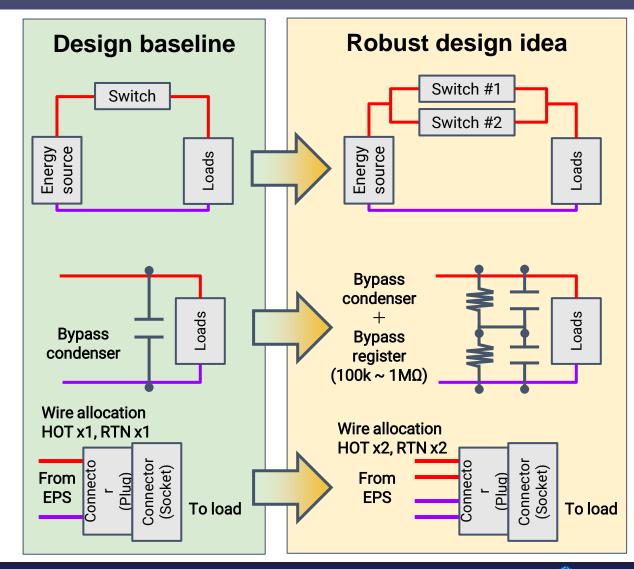
	Items (typical electrical parts)	Open mode failure	Short mode failure
Series connection	Blocking diode, DC/DC converter, switch(FET) current monitor, harness, connecter, etc.	Current path is cut off → Critical !! Must be avoided	Current is provided but, switch is not able to be turned off
Parallel connection	Over current detecting circuit, voltage monitor, bypass c, etc.	Power line is kept fine but, the function might be lost	Waste of large amount of current → Critical!! Must be avoided

Each

4.2. EPS Circuit Design Examples

Design Trade-off: Element Redundancy vs System Resource (Mass or Volume or Area)

- → High-priority loads (ex. main telecommunication, OBC, attitude control, fundamental bus-function)
 → as shown in robust design idea, dual or triple allocation of the circuit elements or parts is most useful approach
- ☐ Current limit resistance insertion is also an effective approach to protect against unexpected energy loss
- → However, the area of PCB (Print Circuit Board)
 might be limited to mount all required circuits
 - ☐ [Action 1] **High density layout** of the circuit by using smaller package
 - ☐ [Action 2] Accept single points for **low priority loads** (mission camera, temperature sensor)



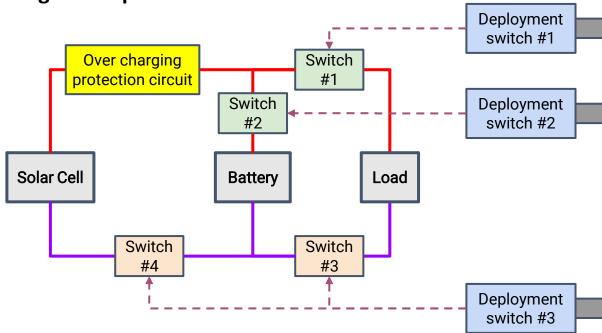
4.3. Safety Design and Testing of EPS Circuit (Inhibit Concepts)

Inhibit Requirement and Design Approach

- Typical ISS condition: 3-inhibit between energy source (solar cell or battery) and load
- 3-inhibit = 3 switches or fuses to **cut off energy** transfer
- "3" means "2 fail-safe": the possibility of all 3 switches breaking at the same time is very small for a random failure
- The risk of design-induced failure of inhibit circuit must be mitigated by performing enough functional tests on the ground
- To avoid unexpected trouble after launch, heterogeneous combination is also useful ex) Switch #1 & #2 = Product-A,

Switch #3 & #4 = Product-B,

Design Example of EPS Inhibit Architecture



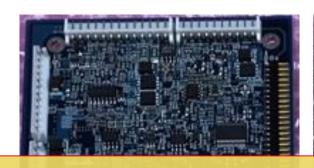
All Combinations are protected by 3-inhibit

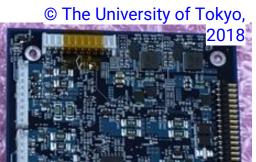
- Solar cell to load: for unexpected load activation
- Battery to load: for unexpected load activation or battery external short or battery over discharging
- Solar cell to load: for battery over charging

4.4. Examples of EPS Circuit Boards Products

Checkpoints of EPS Circuit Board Design

- Parts layout : Clearance between mechanical interface (bolt holes) and closest parts
- Large-current paths should be made larger (> 1 mm width for copper pattern at 1A current)
- Ground plane layout and consideration of categorization of GND to reduce unexpected noise transfer between analog and digital
- **Maintainability**: During replacing the discreet parts (like **R** or **C** or **L**) to change the circuit's constant or properties (like over current detecting constant, under voltage detecting constant, battery charging CC/CV setting, timer waiting setting, IC's mode setting), suitable layout or package size should be considered (like easy to perform soldering)





Design examples based on past ISS CubeSat missions (sample product image)

Power Control Board

Dimensions: 90 x 90 x 8 mm

Mass: 45 g **Functions**

- 3 Inhibit Circuit
- **MPPT Circuit**
- **Battery charging Circuit**
- 2 Output port (Unregulated bus) **[1 for Power Distribution** Boardl

Power Distribution Board

Dimensions: 90 x 90 x 8 mm

Mass: 42 g **Functions**

- > 8 Output ports (+3.3V or +5V Regulated) [selectable by changing discreet parts]
- **Current and Voltage** monitoring A/D Conversion circuit



5. EPS Subsystem Integration

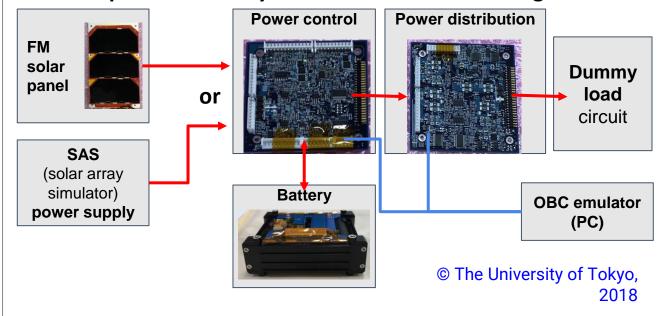
5.1. End-to-End Test of EPS

End-to-End Test

- ☐ To verify the **EPS integrated functionality** after individual design and production of EPS components (solar cell panel, battery, power control/distribution)
- ☐ Use a **test harness** or **actual FM harness** or **motherboard** to connect all EPS components (depends on purpose of test)
- ☐ SAS (Solar Array Simulator) power supply tends to be used on the table test in the case of focusing on the circuit boards and battery validation
- ☐ In the case of focusing on the actual FM solar panel performance or interface check, FM solar panels are attached to the power control boards

Suitable test configurations must be considered

An example of EPS subsystem end-to-end test configuration



Additional test devices

- ☐ FM deployment switches: for interface check
- ☐ Multi-meter (current / voltage): to verify the monitoring functions of A/D conversion
- ☐ Oscilloscope: for checking the noise condition of power output or signal interface

5. EPS Subsystem Integration

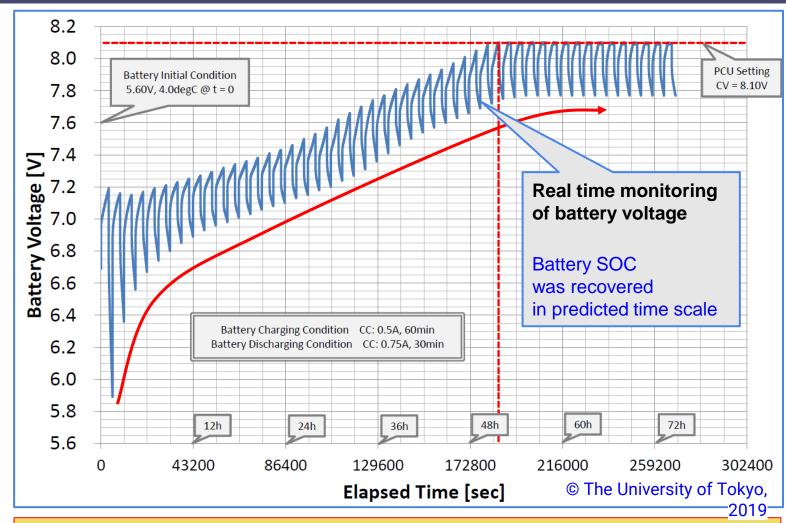
5.1. End-to-End Test of EPS

Example of EPS End-to-End Test
Battery Charging Test from 0% SOC
(Recovery from a dead battery state)
[Off-nominal case test]

Configuration: **EPS subsystem level**

Environment: **+4.0 degC constant** (by isothermal chamber, based on the predicted temperature on-orbit)

Test condition: 60min charging, 30 min discharging (emulated orbit condition) constant current



Example test data based on a past ISS CubeSat mission

5. EPS Subsystem Integration

5.2. Key Concepts and Checkpoints of EPS Integration for Mission Success

Table. Checkpoints of EPS design and implementation summary

#	Category	Topic		
EPS-01	Solar cell	□ Temperature trends of I-V Curve / P-V Curve performance □ Series / parallel architecture design □ Panel hardware design		
EPS-02	Battery	 □ Temperature trends of charging / discharging performance □ Screening test of the FM battery cells (for initial performance check) □ Screening test of the FM battery cells (for initial safety condition check) □ Series / parallel architecture design □ Module hardware design 		
EPS-03	Power control	□ Power control method □ Selection of parts or modules or products □ Bus voltage □ The number of output ports □ Redundancy design		
EPS-04	Power distribution	□ The number of output ports □ Selection of parts or modules or products □ Properties of each output port (voltage, current limit) □ Redundancy design		
EPS-05	Inhibit	□ Corresponding to the safety requirements □ Connection to each deployment switch		
EPS-06	End-to-end	□ Test configurations □ Nominal case tests □ Off-nominal case tests		



6. Conclusion

EPS is the most important subsystem from the viewpoint of energy handling Power Generation: State-of-the-art trend → Multi-Junction Solar Cell: ~30 % efficiency I-V curve profile corresponding to the operational temperature range should be confirmed at the single cell level Power storage: State-of-the-art trend \rightarrow Li-Ion battery is popular: 3.0 \sim 3.5 Ah capacity charging/discharging profile corresponding to operational temperature range should be confirmed at the single cell level Li-Ion secondary battery is a very **hazardous** item → Learn how to handle the cell well before starting the actual product design Power control and distribution: effective redundancy design or robust ideas must be considered within system resources (like area or volume or mass) EPS subsystem end-to-end test: Not only **nominal case**, but also **off-nominal case**

