# CS170–Spring 2019 — Homework 11 Solutions

Ran Liao, SID 3034504227 April 14, 2019

Collaborators:Jingyi Xu, Renee Pu

# 1 Study Group

Name	SID
Ran Liao	3034504227
Jingyi Xu	3032003885
Renee Pu	3032083302

# 2 Bipartite Vertex Cover

## (a) Main Idea

Since G is a bipartite graph, we can split V into two disjoint set L and R such that there's no edge linking two vertices in the same set.

Then, run max-flow algorithm on following graph G'. Add nodes s and t into the graph. Add a directed edge from s to every node in L and from every node in R to t. Convert the undirected edges between L and R to directed edges. Set the capacity of every edge to 1. As textbook mentioned, this max-flow can be converted into a max-matching.

A minimum vertex cover can be constructed as follows. Let U be the set of unmatched vertices in L, and Z be the set of vertices that are either in U or are connected to U by alternating paths(a path of odd length that starts and ends with a non-covered vertex, and whose edges alternate between matched edges and unmatched edges). Let  $K = (L \setminus Z) \cup (R \cap Z)$ . Z is the minimum vertex cover we're looking for.

## (b) **Proof of Correctness**

Suppose that M is a maximum matching. No vertex in a vertex cover can cover more than one edge of M. So |M| is a lower bound for vertex cover and if we can construct a vertex cover with |M| vertices, it must be a minimum cover.

Every edge e in E either belongs to an alternating path, or it has a left endpoint in K. If e is matched but not in an alternating path, then its left endpoint cannot be in an alternating path (because two matched edges can not share a vertex) and thus belongs to  $(L \setminus Z)$ . Alternatively, if e is unmatched but not in an alternating path, then its left endpoint cannot be in an alternating path, for such a path could be extended by adding e to it. Thus, K forms a vertex cover with size |M|.

## 3 Direct Bipartite Matching

## (a) Main Idea

To prove M is a maximum matching if and only if there does not exist an alternating path, it's equivalent to prove M is **not** a maximum matching if and only if there does **exist** an alternating path.

Suppose M is not a maximum matching, run the max-flow algorithm on this graph. At least one augment path can be found. Denote it as  $s \to v_1 \to v_2 \to \cdots \to v_{2n} \to t$ . When i is odd,  $v_i \in L$  and  $v_i \to v_{i+1} \in E \setminus M$ , otherwise  $v_i \in R$  and  $v_i \to v_{i+1} \in M$ . The number of edges in this path is odd. Therefore, it is an alternating path.

Suppose there does exist an alternating path. Denote it as  $v_1 \to v_2 \to \cdots \to v_{2n}$ . By definition,  $(v_1, v_2), (v_3, v_4) \cdots (v_{2n-1}, v_{2n}) \in E \setminus M$  and denote it as  $E_1$ . Denote the remaining edges as  $E_2$ . We can construct a larger flow M' as follows.

$$M' = (M \cup E_1) \setminus E_2$$

Therefore, M cannot be a maximum matching.

### (b) (i) Main Idea

Create a dumb node s and add edge (s, v) if v is an unmatched vertex. Use a global variable depth to record the depth of the search tree. If depth is odd, only unmatched edges can be explored. Otherwise only matched edges can be explored. Run BFS starting from s.

## (ii) Proof of Correctness

The alternating path will start from an unmatched point and alternating between matched and unmatched edges. The variable depth will be helpful to determine whether to explore matched edges or unmatched edges.

#### (iii) Runtime Analysis

The modified BFS will not change overall runtime. Therefore it is O(|V| + |E|).

#### (c) (i) Main Idea

Find an alternating path use the algorithm in part b and construct a larger matching use method mentioned in part a. Keep doing this until there's no alternating path exists.

#### (ii) Proof of Correctness

As proved in part a, M is a maximum matching if and only if there does not exist an alternating path. And if there's an alternating path, part b algorithm will find it.

#### (iii) Runtime Analysis

The algorithm in part b will be run at most O(|V|) times, and each run will cost O(|V| + |E|). Therefore, the overall runtime is O((|V| + |E|)|V|) = O(|V||E|).

# 4 Zero-Sum Battle

(a)

 $\max p$ 

 $p \le -10x_1 + 4x_2 + 6x_3$  (payoff when trainer B chooses the ice Pokemon)  $p \le 3x_1 - 1x_2 - 9x_3$  (payoff when trainer B chooses the water Pokemon)  $p \le 3x_1 - 3x_2 + 2x_3$  (payoff when trainer B chooses the fire Pokemon)

$$x_1 + x_2 + x_3 = 1$$
$$x_1 \ge 0$$
$$x_2 \ge 0$$
$$x_3 \ge 0$$

The optimal strategy is (0.335, 0.563, 0.102) and the payoff is -0.48.

(b)

 $\min p$ 

 $p \ge -10y_1 + 3y_2 + 3y_3$  (payoff when trainer A chooses the dragon Pokemon)  $p \ge 4y_1 - 1y_2 - 3y_3$  (payoff when trainer A chooses the steel Pokemon)  $p \ge 6y_1 - 9y_2 + 2y_3$  (payoff when trainer A chooses the rock Pokemon)

$$y_1 + y_2 + y_3 = 1$$
$$y_1 \ge 0$$
$$y_2 \ge 0$$
$$y_3 \ge 0$$

The optimal strategy is (0.268, 0.323, 0.409) and the payoff is -0.48.

# 5 Domination

- (a) It should be 0 since choosing E instead will always give a better payoff.
- (b) It should also be 0 since choosing B instead will always give a better payoff(column player wants to minimize the payoff).
- (c) Both of them should be (0.5, 0.5), since they are completely symmetric