

**Discussion 07:**

# **Path Tracing and Material Modeling**

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**Computer Graphics and Imaging  
UC Berkeley CS184/284A, Spring 2019**

**Let's re-orient ourselves!**

# Where are we?

## Course Roadmap

### Rasterization Pipeline

#### Core Concepts

- Sampling
- Antialiasing
- Transforms

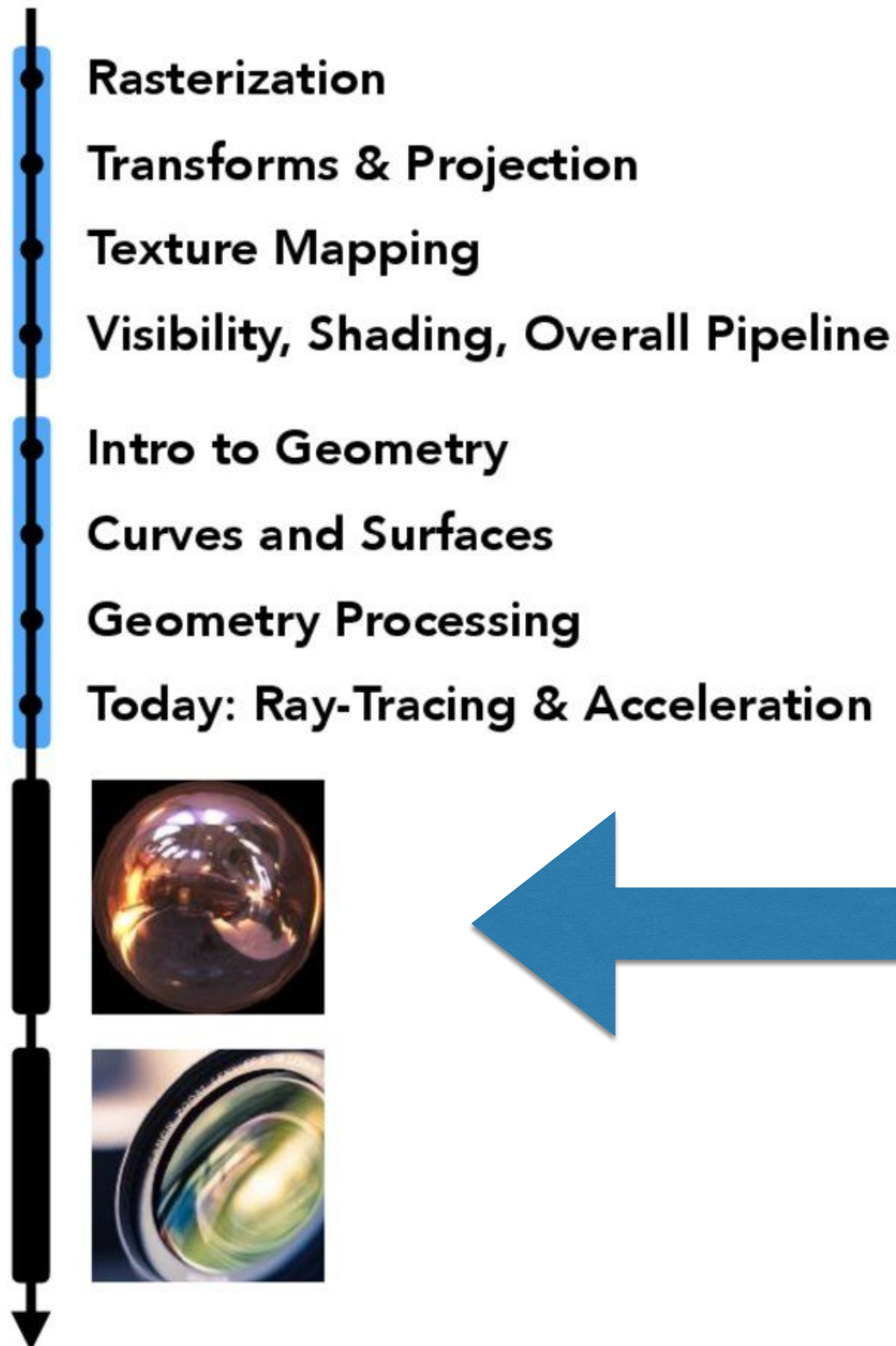
### Geometric Modeling

#### Core Concepts

- Splines, Bezier Curves
- Topological Mesh Representations
- Subdivision, Geometry Processing

### Lighting & Materials

### Cameras & Imaging

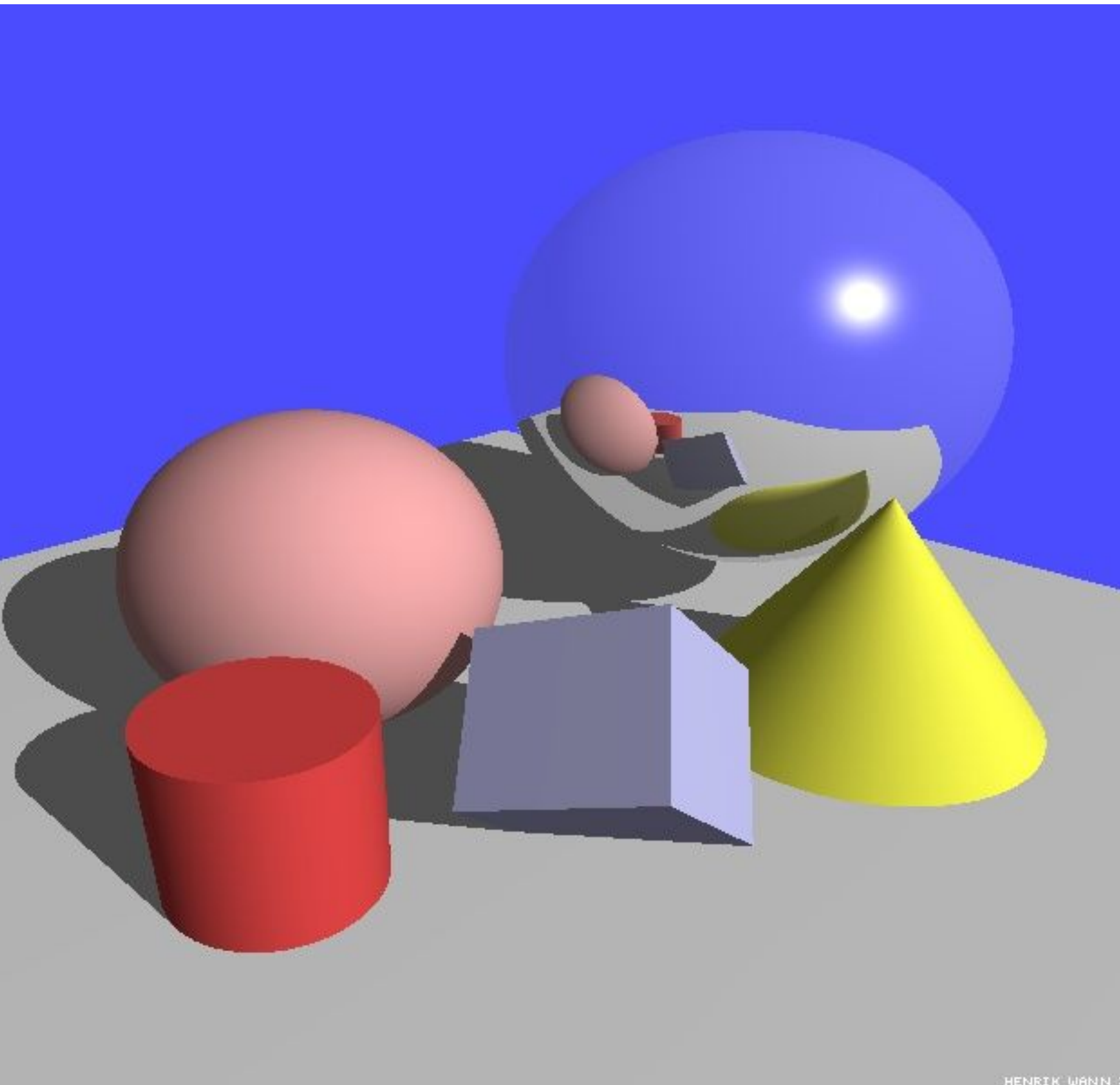


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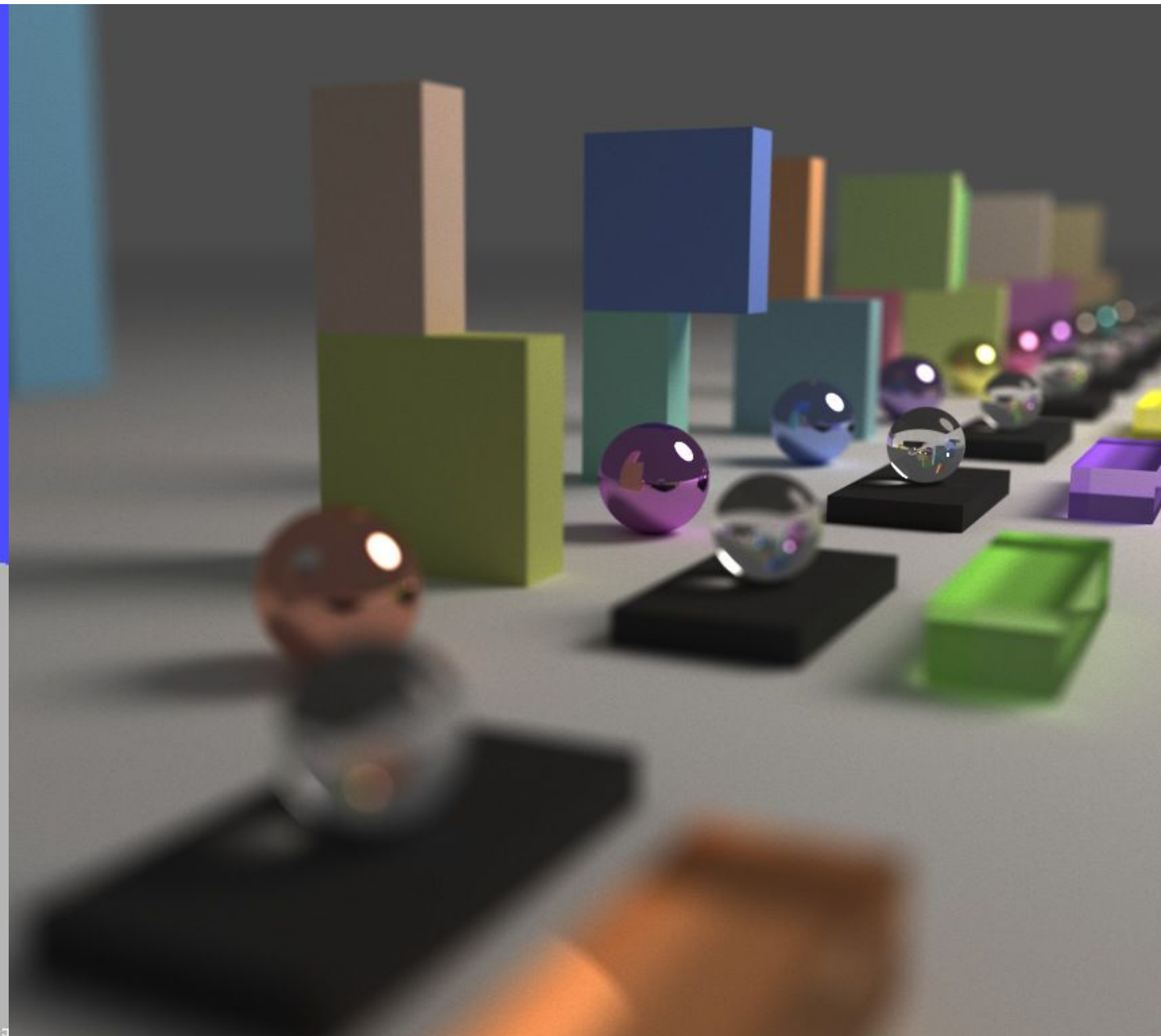
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# **Path Traced Global Illumination (AKA Proj3-1 and 3-2!)**

# Ray Tracing vs. Path Tracing



Ray tracing



Path tracing



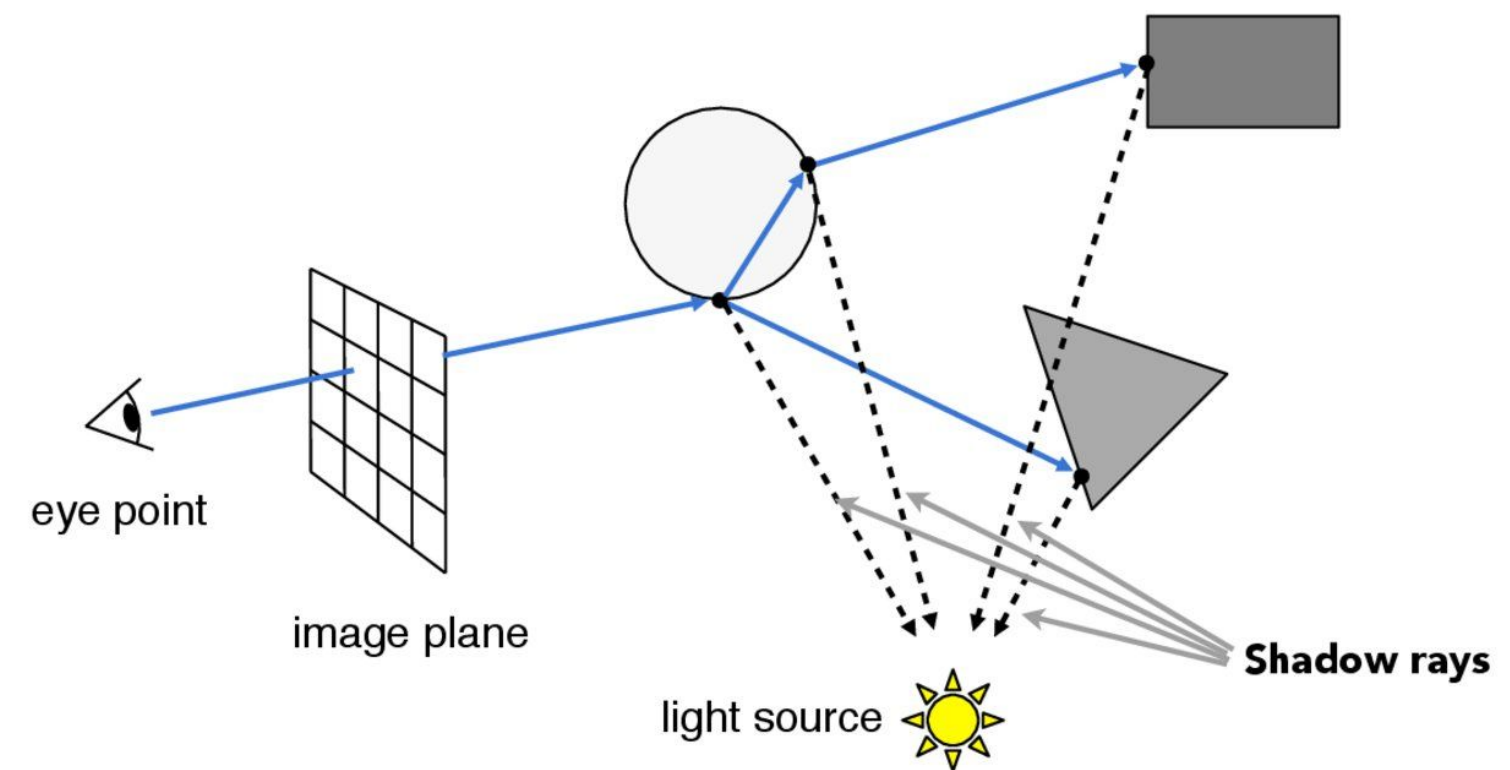
# What method will you use to render this?



# Path Tracing at a High Level

- Shoot a ray from eye into scene
- Intersect with object
- Figure out how that point is lit
  - (how? — this is the meat of path tracing)

## Recursive Ray Tracing



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**Now let's walk through what we did  
in Proj 3-1!**



# Rays and Intersections

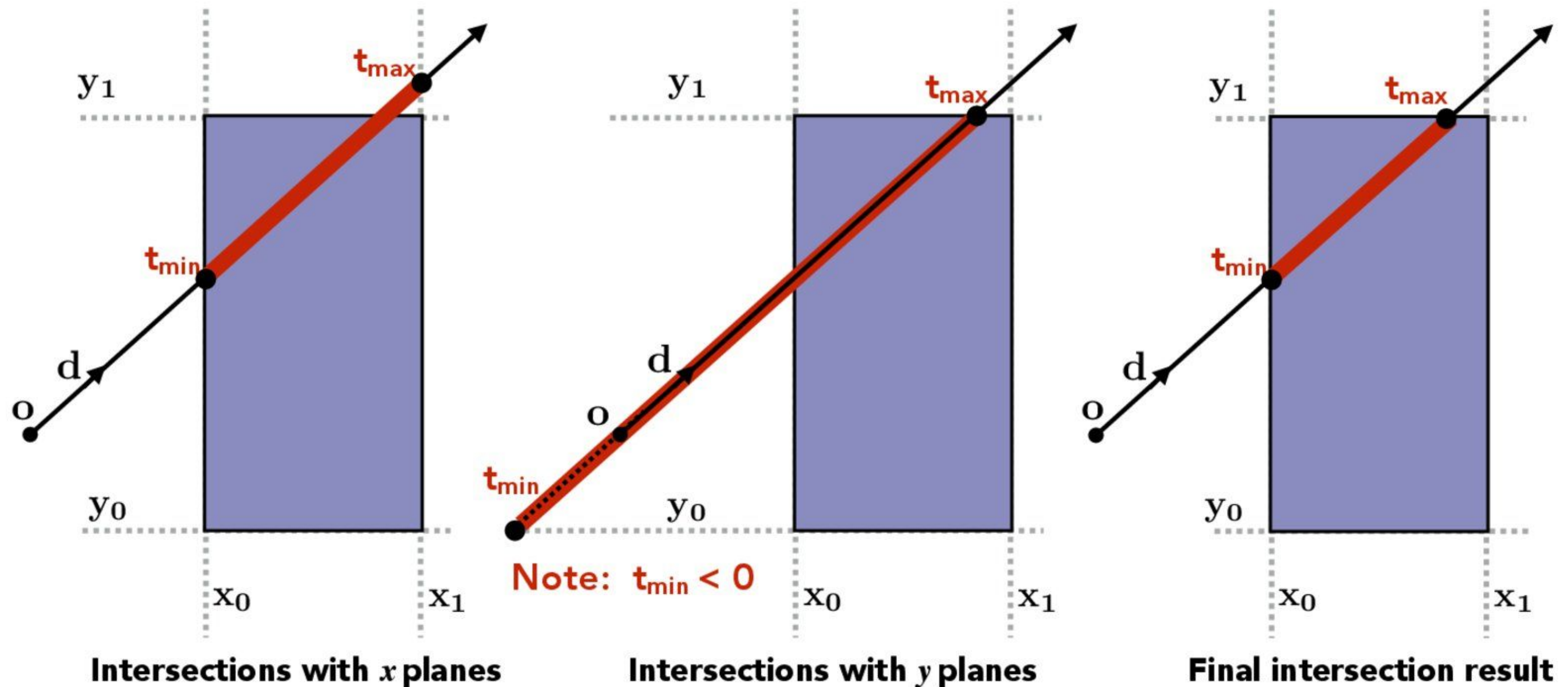
- Iterate over each pixel, and generate some number of samples (1 through the center, or more than one randomly)
- Generate a ray in camera space, and transform that into a ray in world space
- Intersections against two primitives: triangles and spheres
  - How many possible intersections against triangles?
  - How many against spheres?

# BVHs and BBox Ray Intersections

- Only an optimization — does this affect correctness?
- Constructing a BVH tree, then testing intersections against that hierarchy
  - Why do we test against both left and right nodes, regardless of success?

# Ray Intersection with Axis-Aligned Box

2D example; 3D is the same! Compute intersections with slabs and take intersection of  $t_{\min}/t_{\max}$  intervals



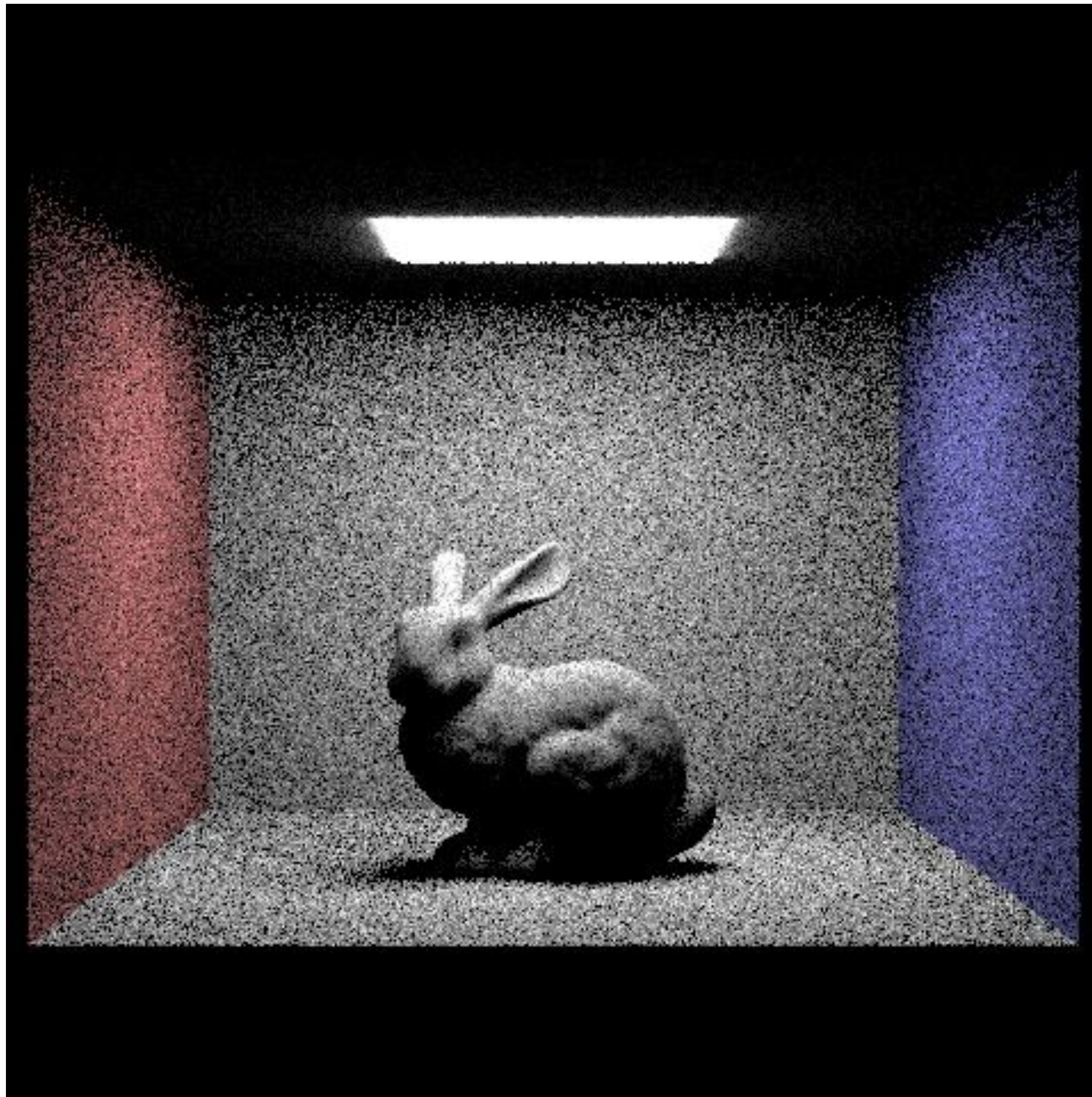
How do we know when the ray misses the box?

# Direct Illumination

- Hemisphere lighting
  - From your hit point, randomly sample a direction (uniformly from hemisphere) and cast a ray that way
  - If this ray hits something, then get the emitted light from that “something”
  - Then scale by the hit point’s BSDF (why?), cosine factor (why?), and pdf (why?)



# Direct Illumination



Why is this *correct*,  
but *noisy*?

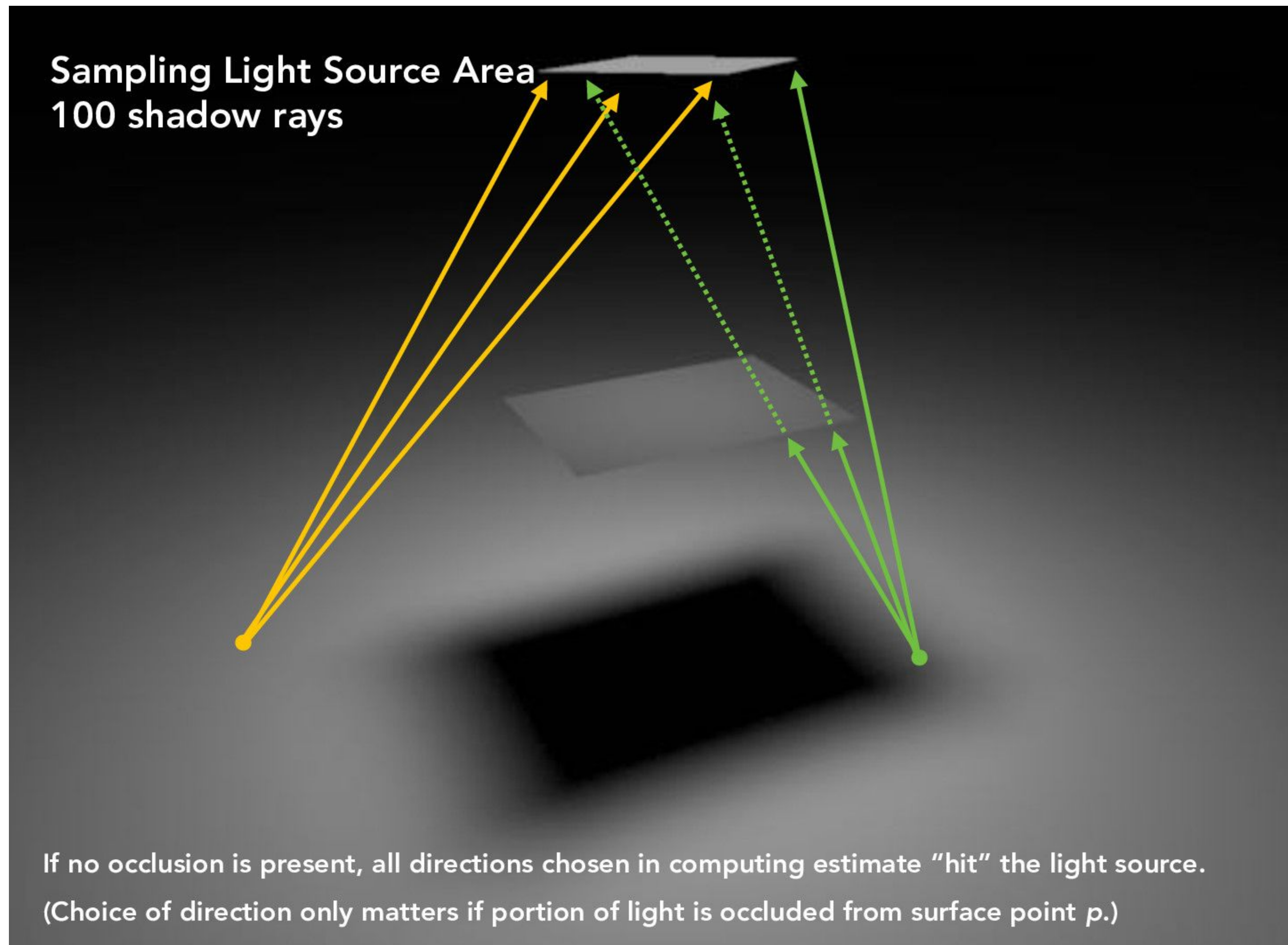
How do we improve  
this?

# Direct Illumination

- Importance Sampling
  - We still have a hit point, but rather than sampling a random direction, sample a ray that we know connects the hit point and a point on the light
  - This time, we need a shadow ray — why?



# Direct Illumination



# Global Illumination

- We broke this into three functions:
  - Zero bounce radiance
  - At least one bounce radiance
    - One bounce radiance



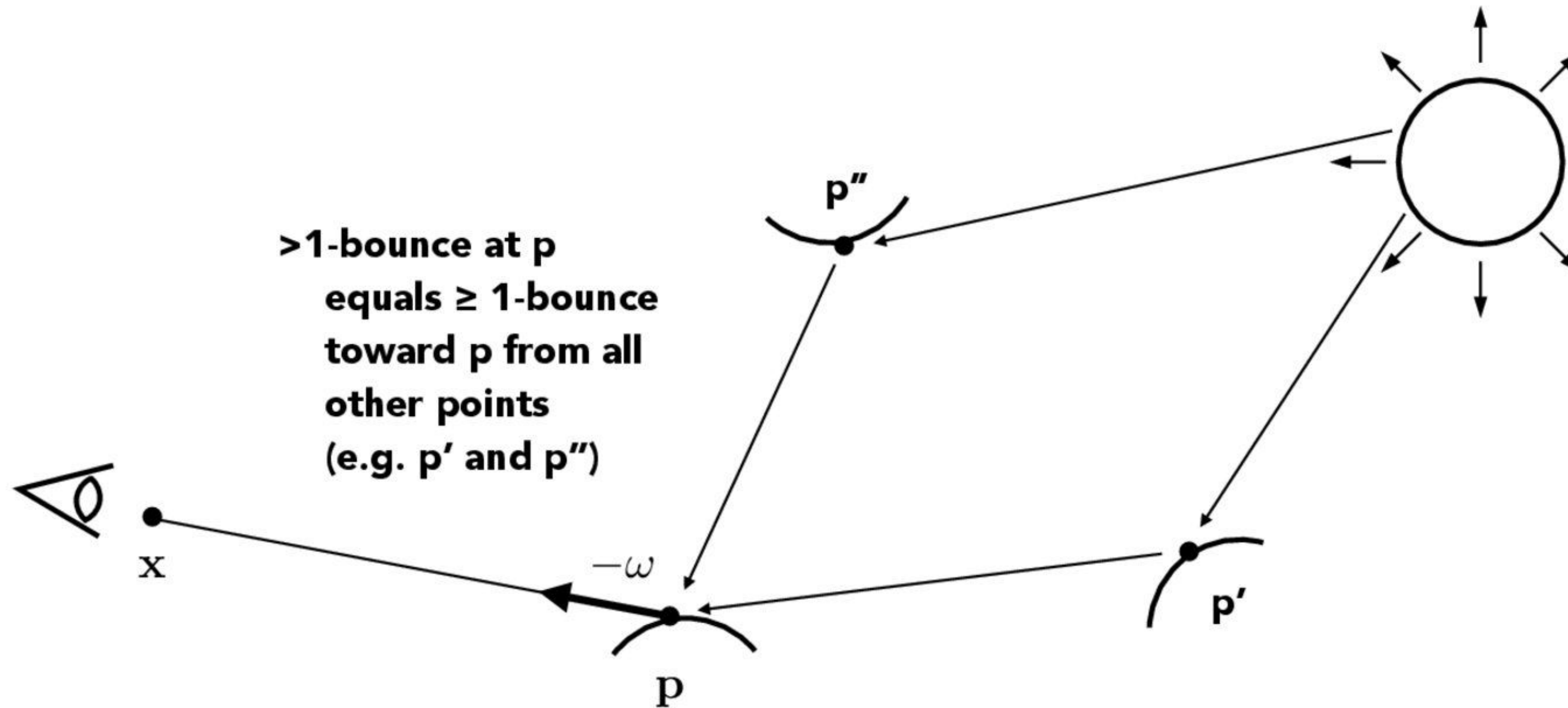
# Path Tracing Pseudocode

```
AtLeastOneBounceRadiance(p, wo)           // out at p, dir wo
    L = OneBounceRadiance(p, wo);          // direct illum

    wi, pdf = p.brdf.sampleDirection();    // Imp. sampling
    p' = intersectScene(p, wi);
    cpdf = continuationProbability(p.brdf, wi, wo);
    if (random01() < cpdf)                  // Russ. Roulette
        L += AtLeastOneBounceRadiance(p', -wi) // Recursive est. of
            * p.brdf(wi, wo) * costheta / pdf / cpdf; // indirect illum
    return L;

OneBounceRadiance(p, wo)                   // out at p, dir wo
    return DirectLightingSampleLights(p, wo); // direct illum
```

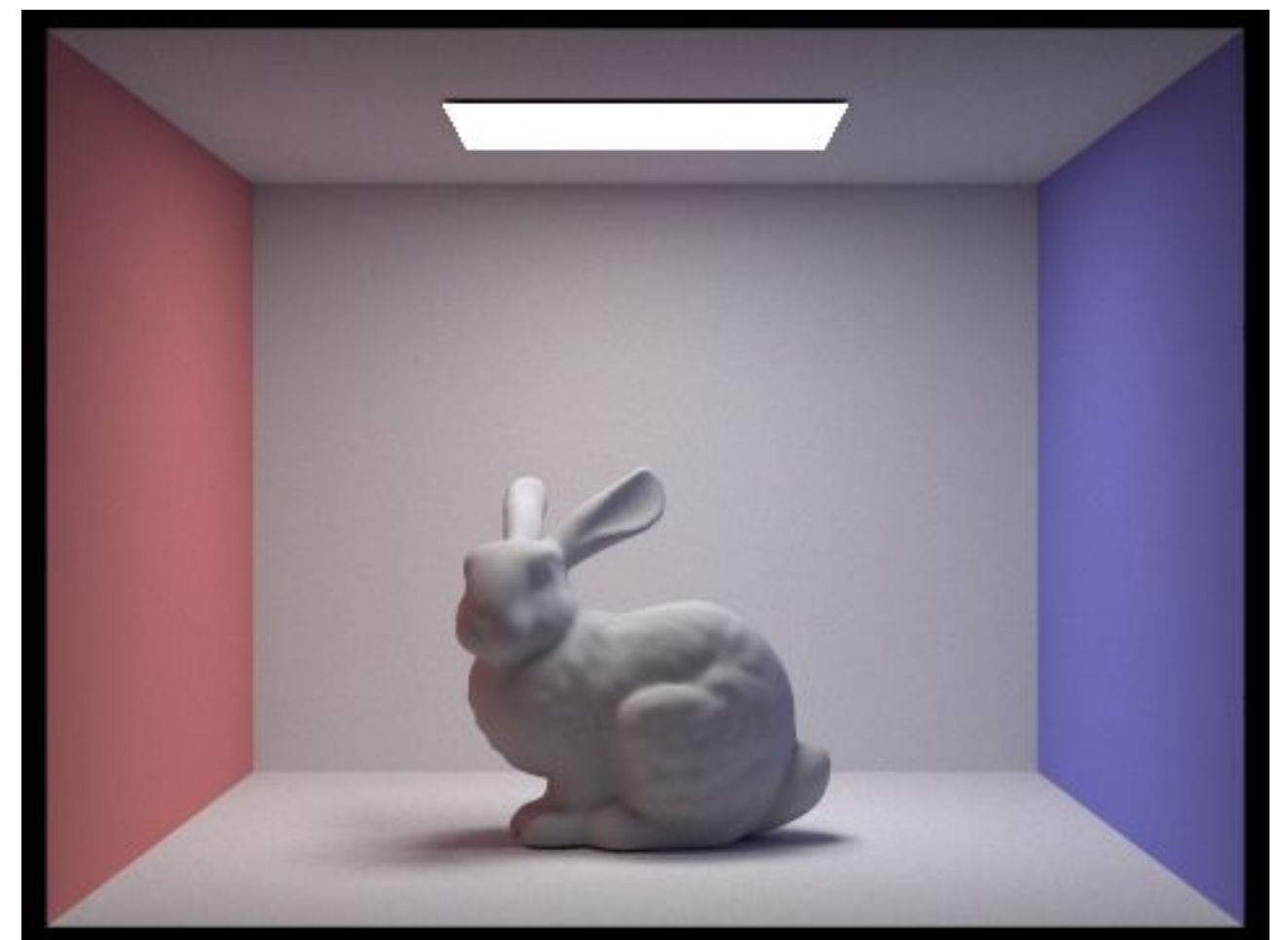
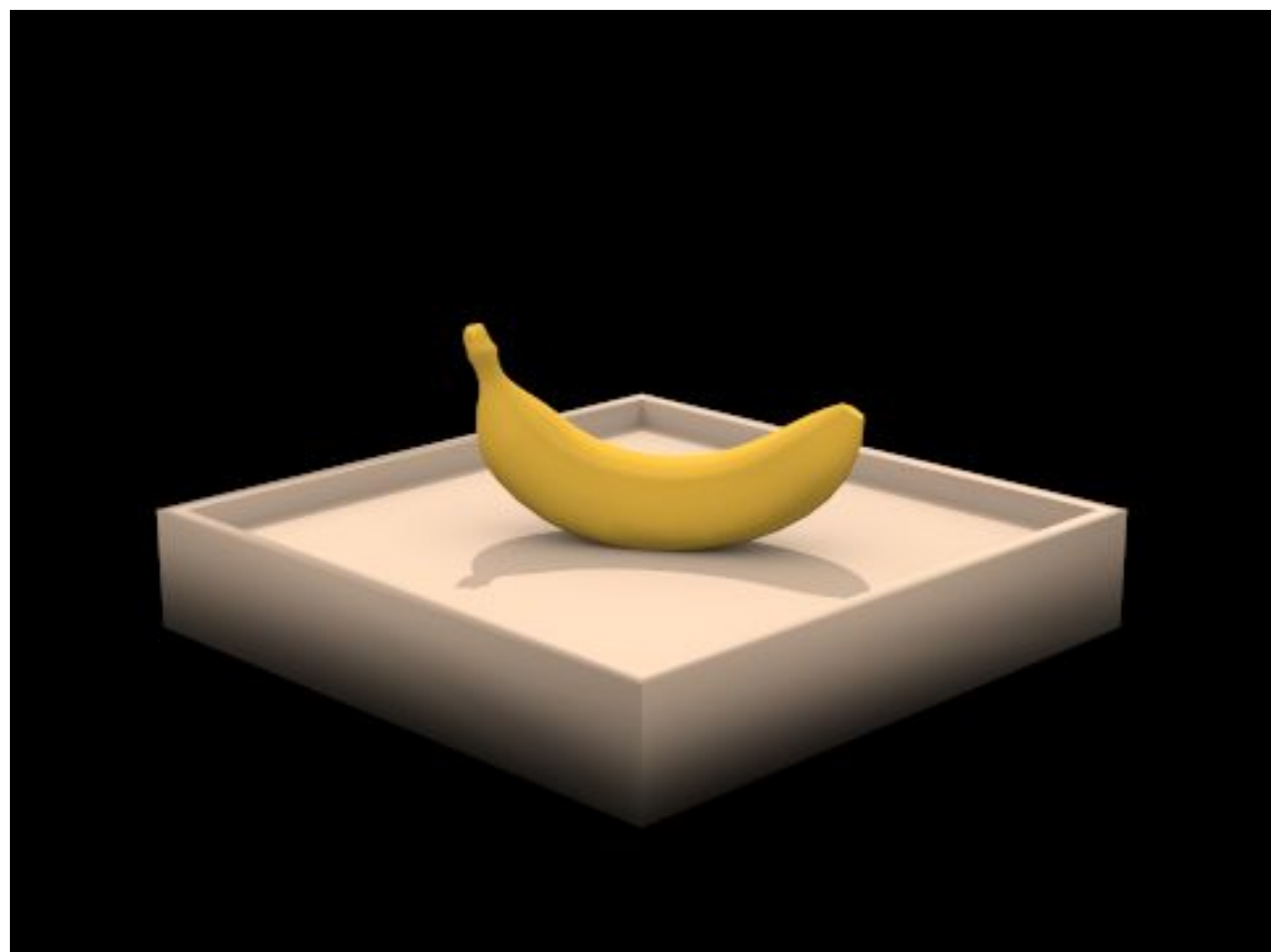
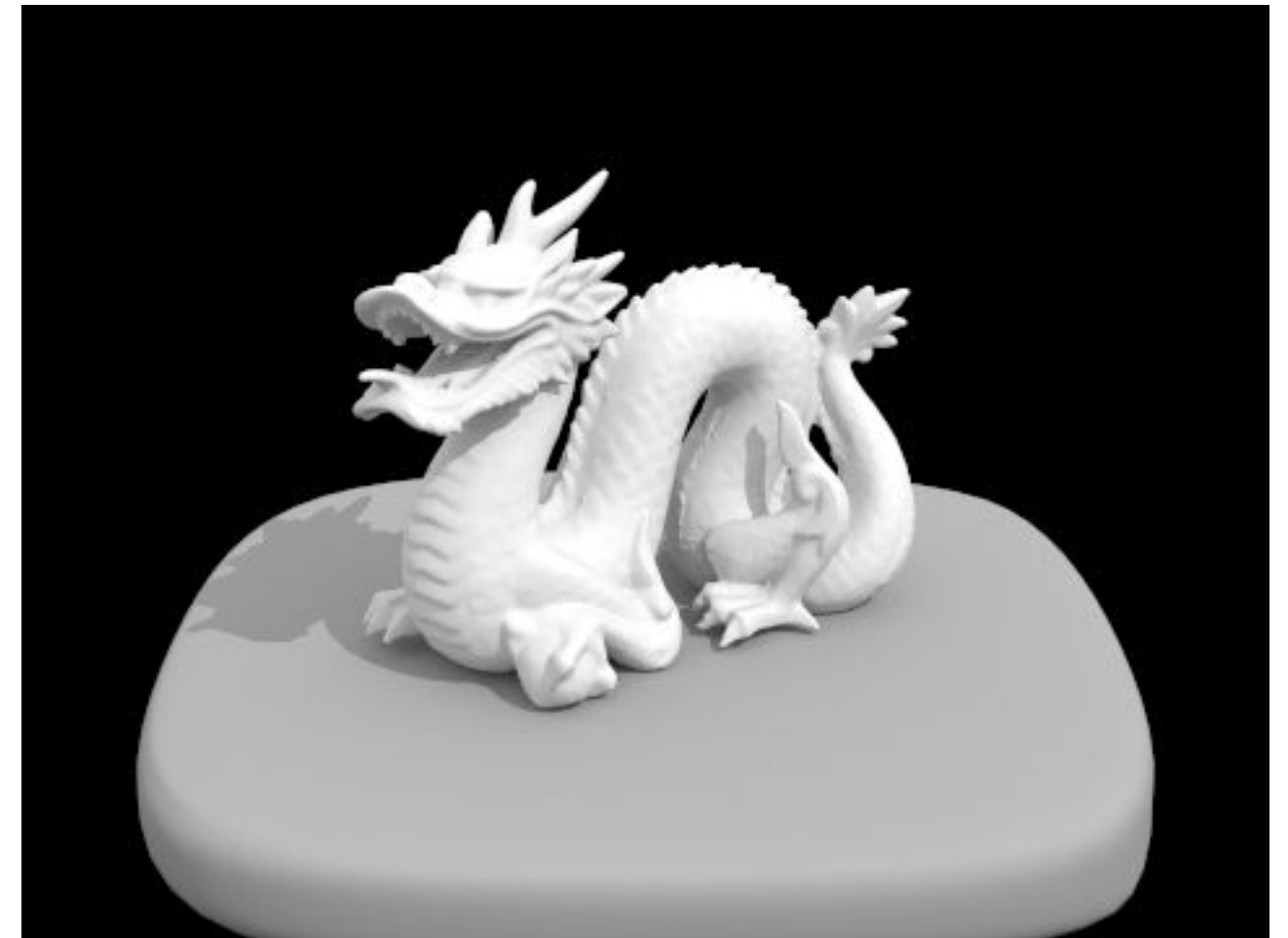
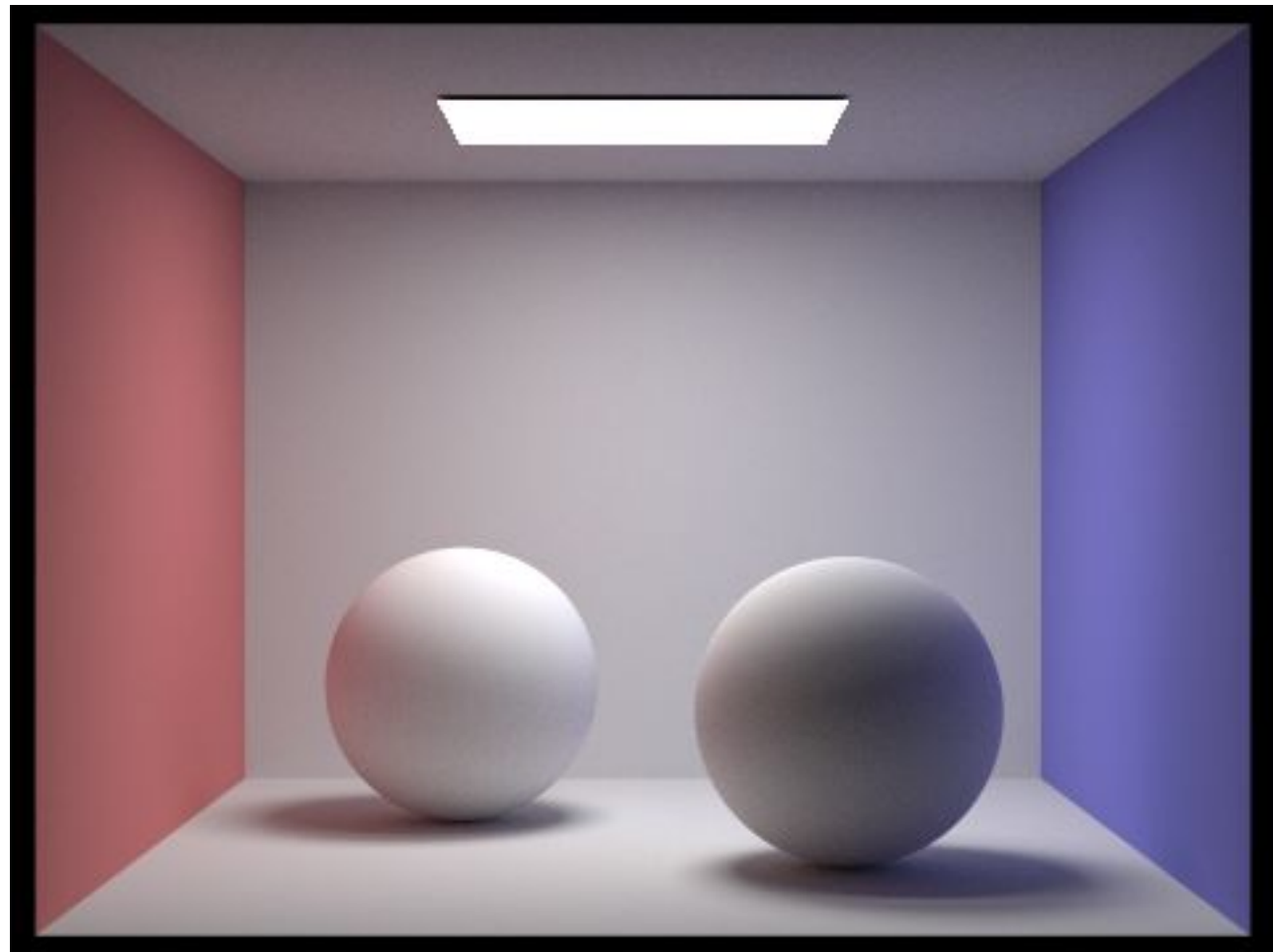
# Consider Evaluation of $>1$ Bounce of Light



At  $p$ , consider light contributions from paths of varying bounce-length

- 0-bounce: light emitted from  $p$  ( $p$  is on a light source)
- 1-bounce: from light to  $p$  to  $x$  ("direct illumination")
- $>1$ -bounce: from light to at least one other point to  $p$  to  $x$  ("indirect illumination")

# Now we can render scenes like:



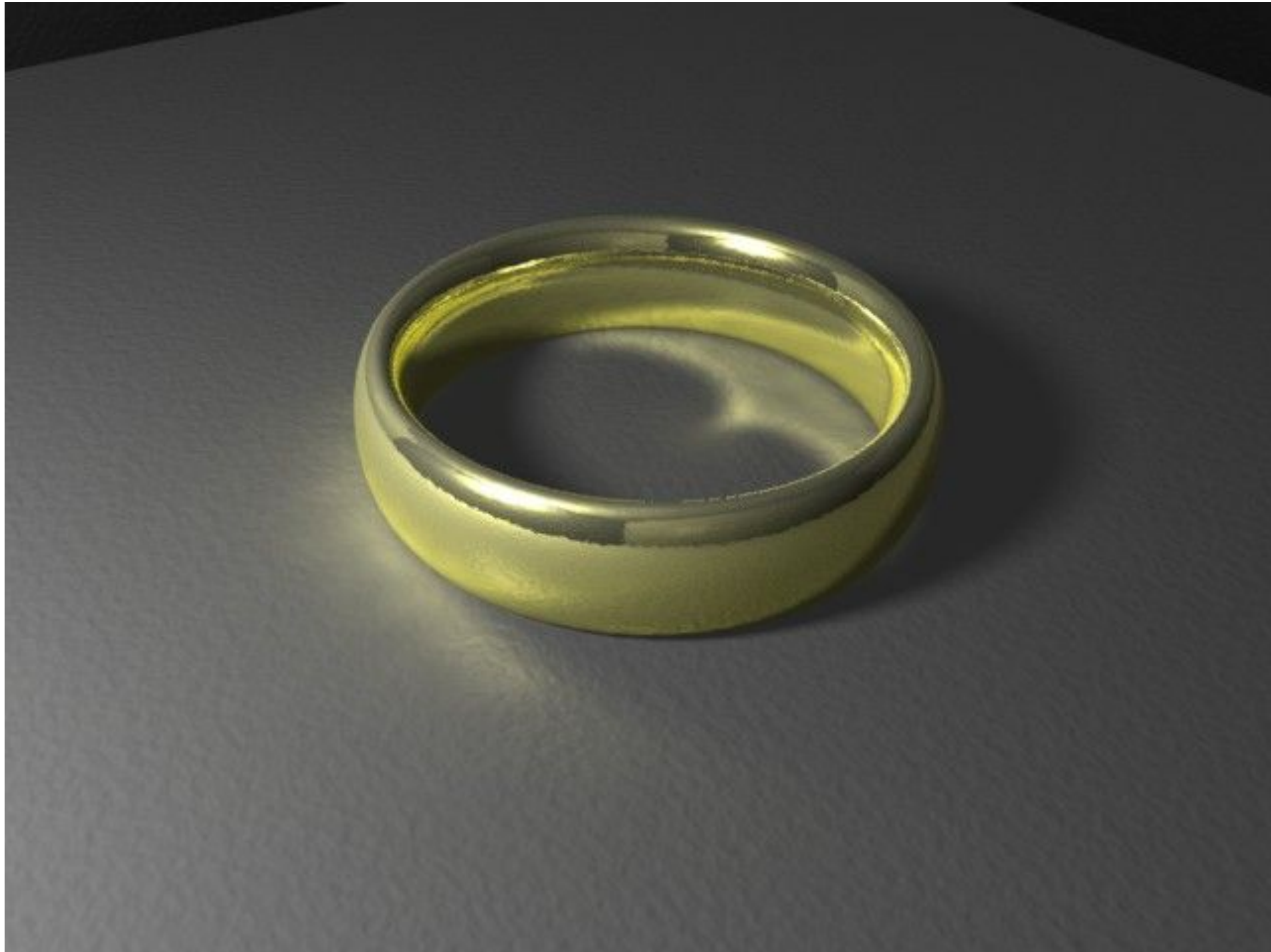


# What's the difference w/ or w/o GI?





# Is Path Tracing Suitable to Render This Scene?



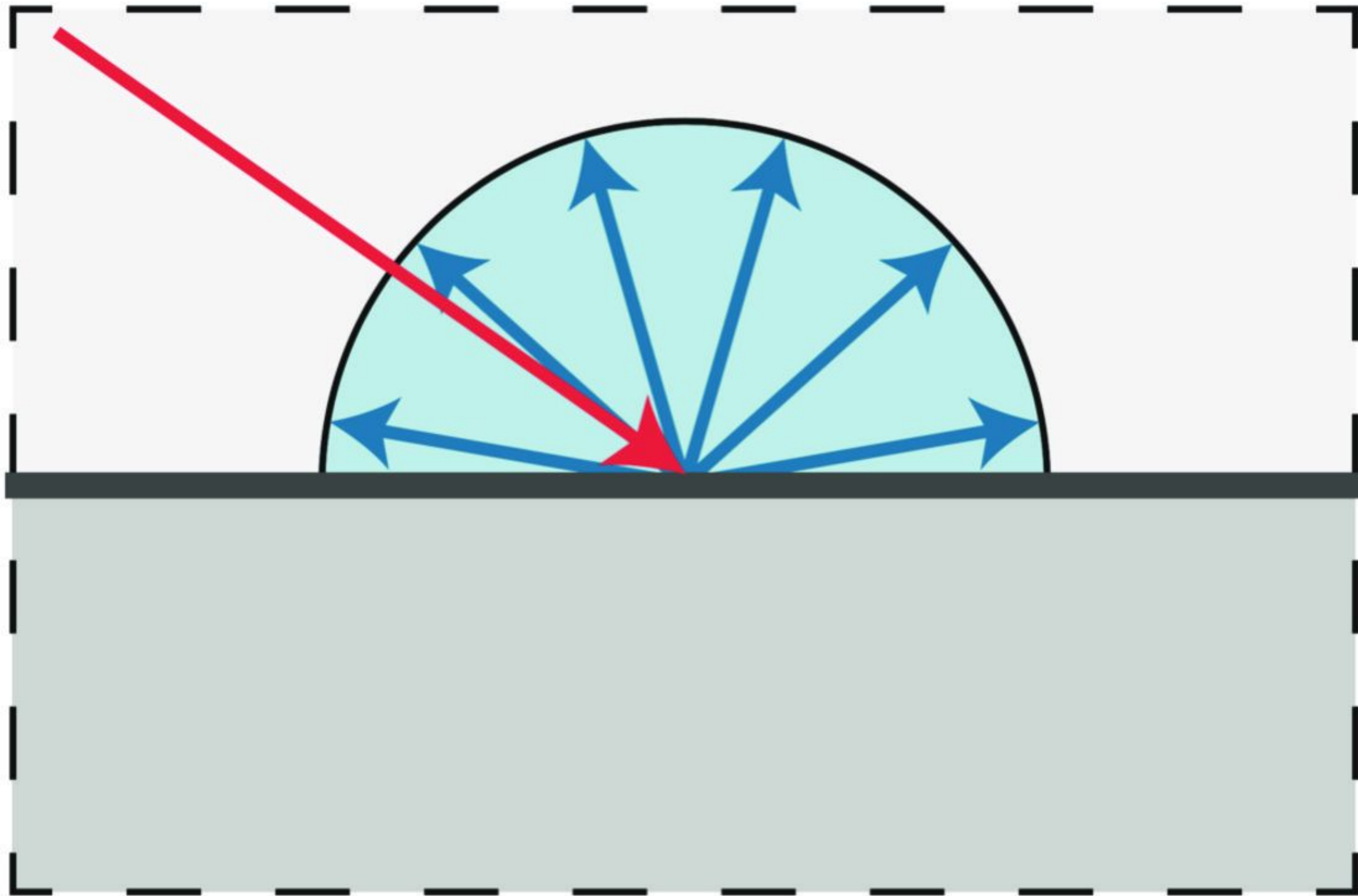
**Material**

# What materials will you use to render this?



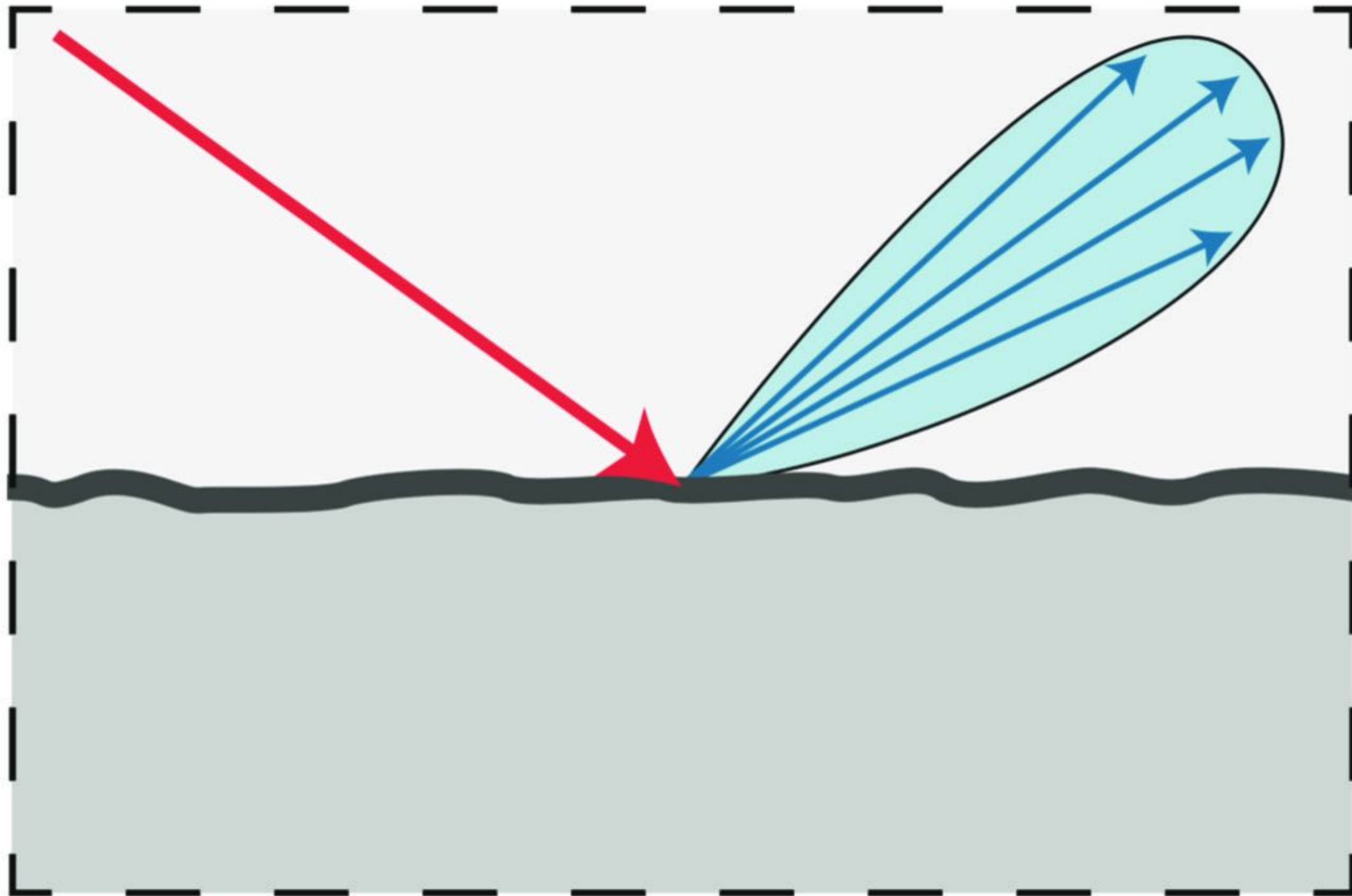


# What is this material?

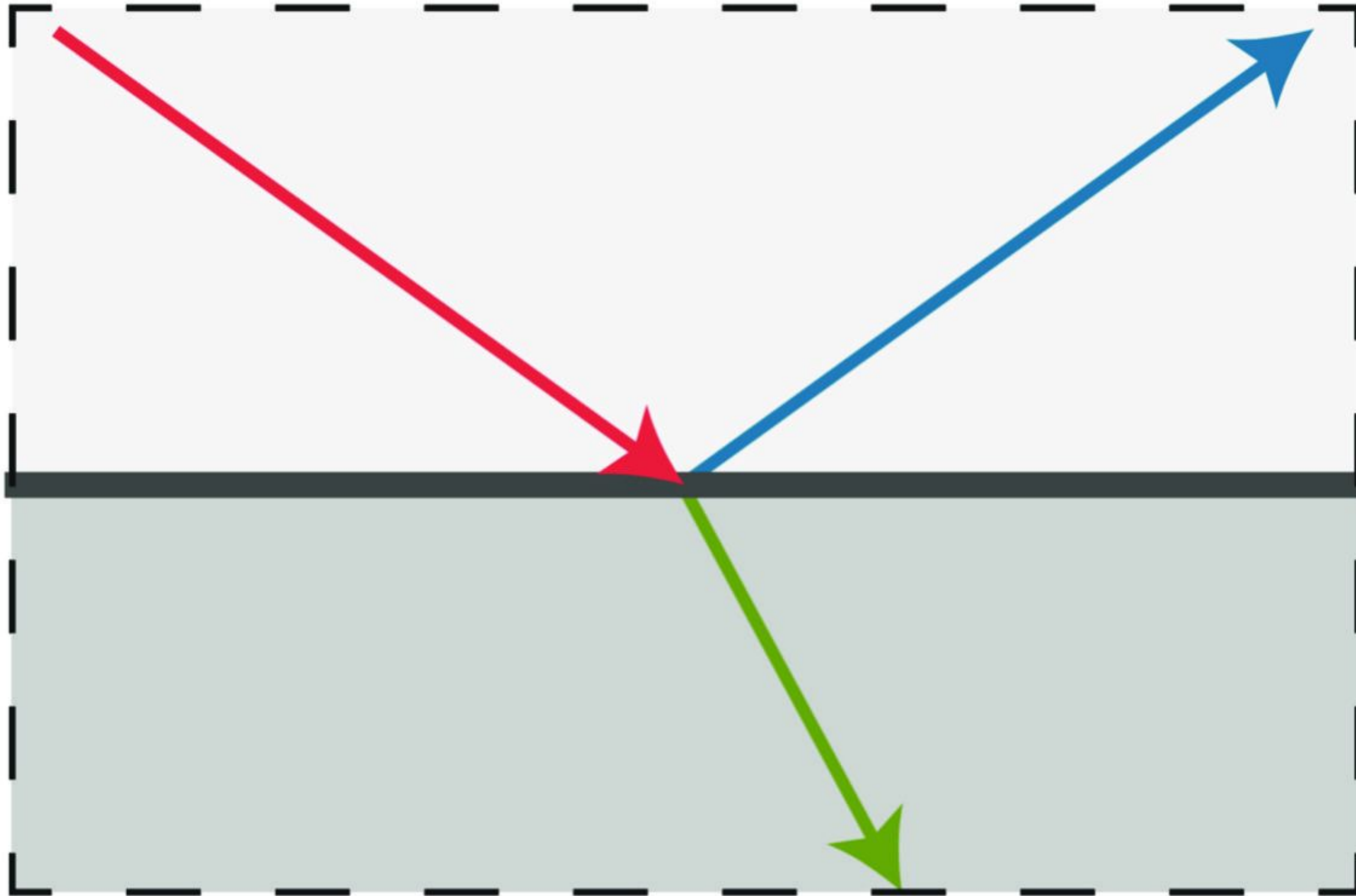


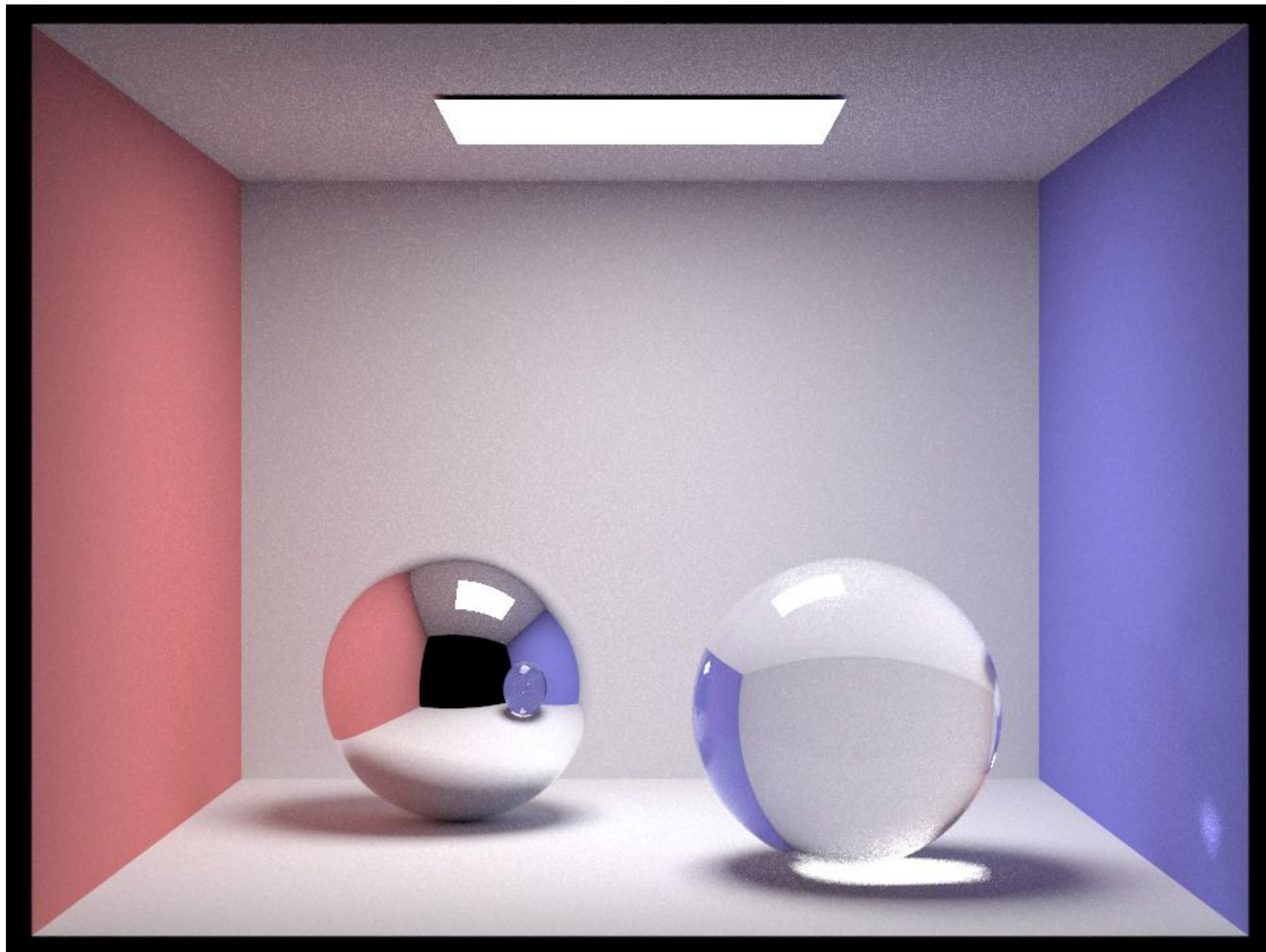


# What is this material?



# What is this material?

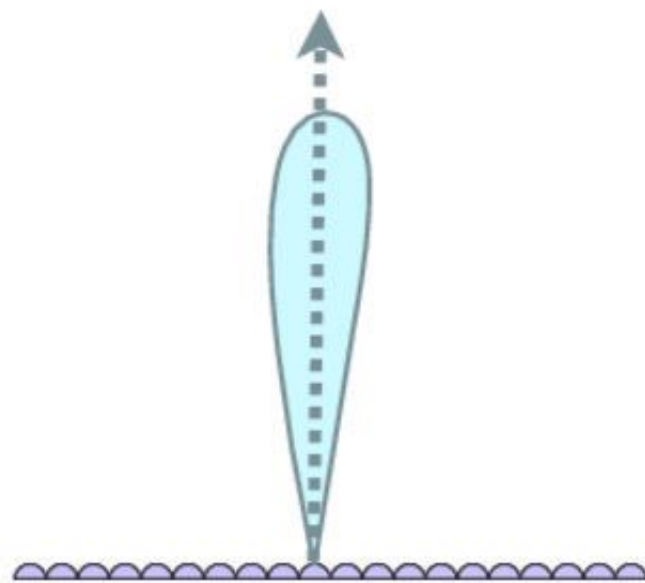




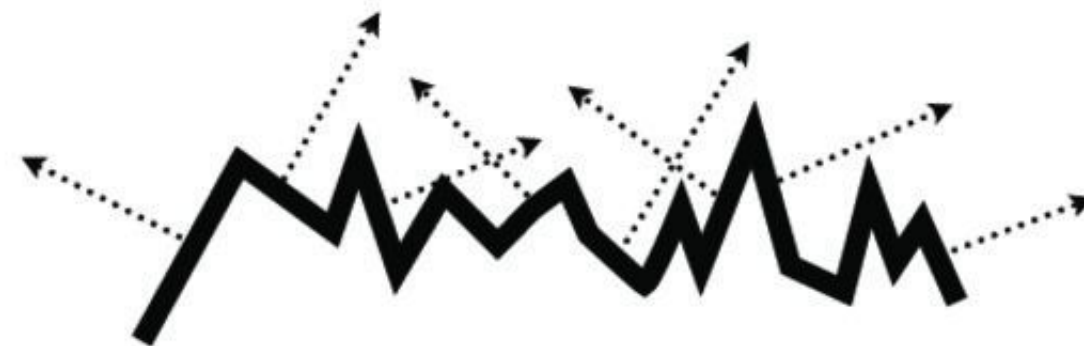
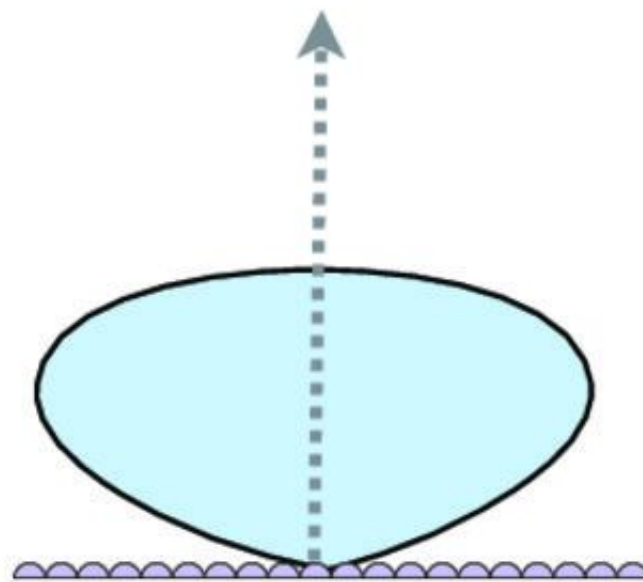


# Microfacet BRDF

- Key: the **distribution** of microfacets' normals
  - Concentrated  $\Leftrightarrow$  glossy

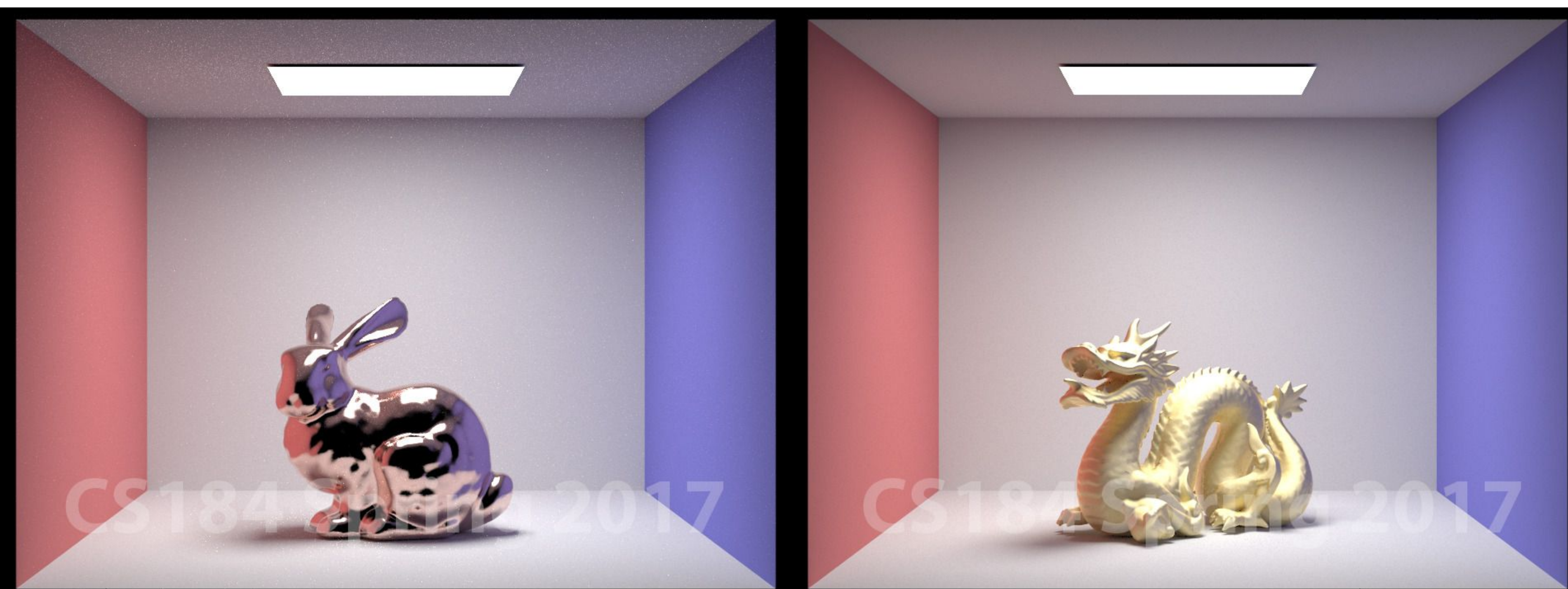


- Spread  $\Leftrightarrow$  diffuse



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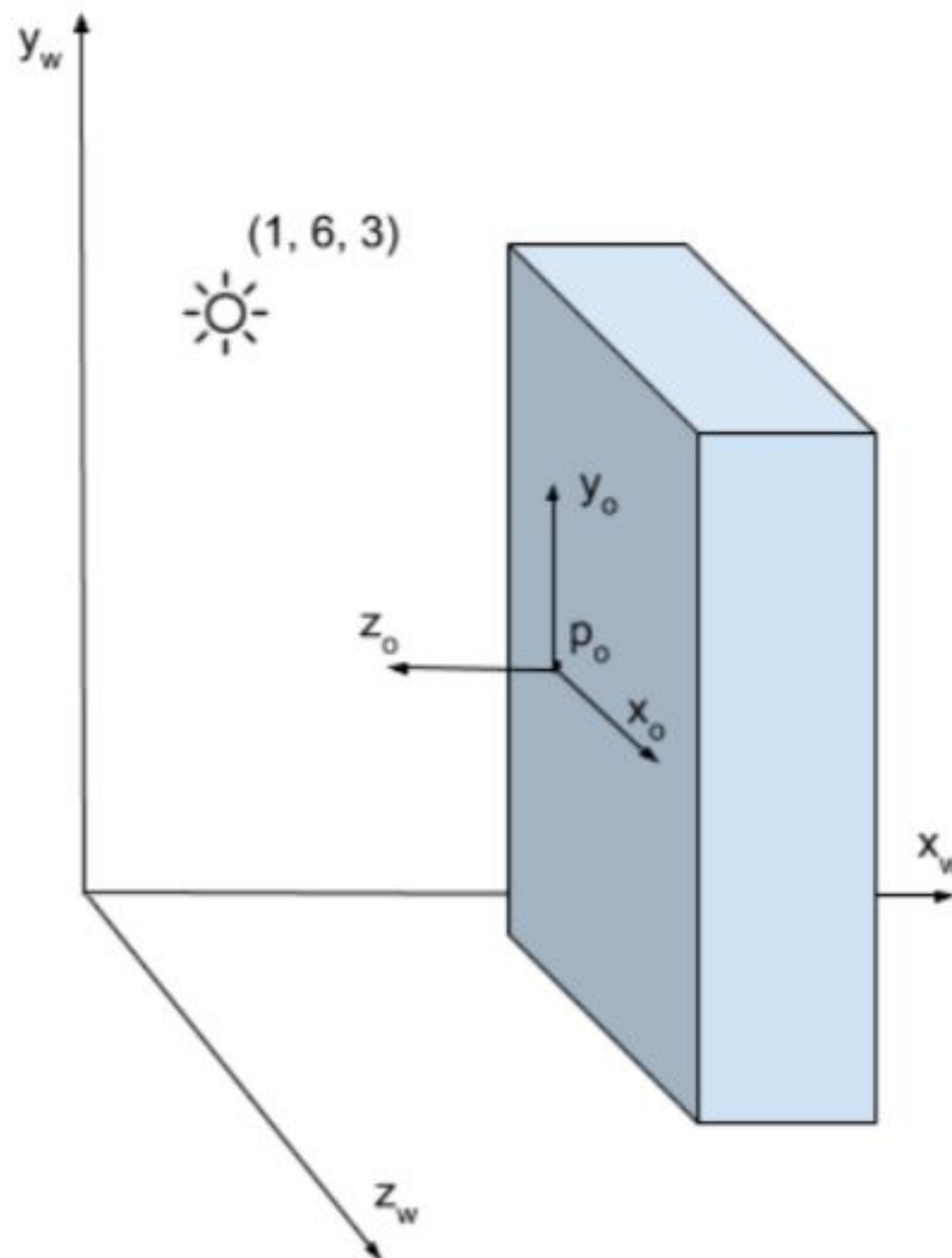




# Past Midterms

# Sp18 Exam 1

- (c) Suppose we are trying to calculate the diffuse Lambertian term of the shaded color for a surface point  $p_o$ , as shown below.



# Sp18 Exam 1

In world coordinates, let  $p_o = (3, 4, 3)$  be the origin of the object's coordinate system, and let the object's local axes be  $x_o = (0, 0, 1)$ ,  $y_o = (0, 1, 0)$ ,  $z_o = (-1, 0, 0)$ . The scene has a single point light, located at  $p_l = (1, 6, 3)$ , also in world coordinates.

- i. (3 points) What is the homogeneous change of coordinates matrix from object to world space? That is, what is the matrix  $M_{o2w}$  such that  $M_{o2w} x_{obj} = x_{world}$ ? Hint: it should be in the form

$$M_{o2w} = \begin{bmatrix} \mathbf{u} & \mathbf{v} & \mathbf{w} & \mathbf{o} \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

- ii. (3 points) The diffuse Lambertian term of a surface shading calculation has the form

$$L_d = k_d \left( \frac{I}{r^2} \right) \max(0, n \cdot l)$$

For this light,  $k_d = 1$ ,  $I = 16$ . What is  $r^2$  for the given point on the surface with respect to the light?

# Sp18 Exam 1

iii. (3 points) What is  $l$  in object coordinates, normalized?

iv. (3 points) Putting it all together, what is the diffuse Lambertian term  $L_d$ ?



# Sp18 Exam 1

## (a) Ray-Cylinder Intersection

- i. (4 points) In lecture, we have seen how to determine the points of intersection of a ray with a box or a sphere. In this question we will perform a similar derivation of the intersection points of a ray and a cylinder. Recall the equation for an infinitely-long cylinder aligned along the z-axis with radius  $r$ :

$$x^2 + y^2 - r^2 = 0$$

Consider a ray with origin  $\mathbf{o} = (-2, -2, -2)$  and direction  $\mathbf{d} = (1, 1, 1)$ , with a ray equation  $\mathbf{r}(t) = \mathbf{o} + t\mathbf{d}$ . Calculate any and all  $t$ -value(s) for intersection with this ray and the infinitely-long cylinder aligned along the z-axis with radius 2. Write the smaller intersection time into  $t_0$  and the larger into  $t_1$ .

$t_0 =$  \_\_\_\_\_

$t_1 =$  \_\_\_\_\_