

**Due:** Tuesday 4/29/2019 at 11:59pm (submit via Gradescope).

Leave self assessment boxes blank for this due date.

**Self assessment due:** Monday 5/6/2019 at 11:59pm (submit via Gradescope)

For the self assessment, **fill in the self assessment boxes in your original submission** (you can download a PDF copy of your submission from Gradescope – be sure to delete any extra title pages that Gradescope attaches). For each subpart where your original answer was correct, write “correct.” Otherwise, write and explain the correct answer. **Do not leave any boxes empty.**

If you did not submit the homework (or skipped some questions) but wish to receive credit for the self-assessment, we ask that you first complete the homework without looking at the solutions, and then perform the self assessment afterwards.

**Policy:** Can be solved in groups (acknowledge collaborators) but must be written up individually

**Submission:** Your submission should be a PDF that matches this template. Each page of the PDF should align with the corresponding page of the template (page 1 has name/collaborators, question 1 begins on page 2, etc.). **Do not reorder, split, combine, or add extra pages.** The intention is that you print out the template, write on the page in pen/pencil, and then scan or take pictures of the pages to make your submission. You may also fill out this template digitally (e.g. using a tablet.)

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SID	30340504227
Collaborators	None

# Q1. The OMNIBUS

## (a) Search

- (i) [~~true~~ or false] Uniform-cost search will never expand more nodes than A\*-search.
- (ii) [~~true~~ or false] Depth-first search will always expand more nodes than breadth-first search.
- (iii) [~~true~~ or false] The heuristic  $h(n) = 0$  is admissible for every search problem.
- (iv) [~~true~~ or false] The heuristic  $h(n) = 1$  is admissible for every search problem.
- (v) [~~true~~ or false] The heuristic  $h(n) = c(n)$ , where  $c(n)$  is the true cheapest cost to get from the node  $n$  to a goal state, is admissible for every search problem.

**Self assessment** If correct, write “correct” in the box. Otherwise, write and explain the correct answer.

Correct

## (b) CSPs

- (i) [~~true~~ or false] The most-constrained variable heuristic provides a way to select the next variable to assign in a backtracking search for solving a CSP.
- (ii) [~~true~~ or false] By using the most-constrained variable heuristic and the least-constraining value heuristic we can solve every CSP in time linear in the number of variables.

**Self assessment** If correct, write “correct” in the box. Otherwise, write and explain the correct answer.

Correct

## (c) Games

- (i) [~~true~~ or false] When using alpha-beta pruning, it is possible to get an incorrect value at the root node by choosing a bad ordering when expanding children.
- (ii) [~~true~~ or false] When using alpha-beta pruning, the computational savings are independent of the order in which children are expanded.
- (iii) [~~true~~ or false] When using expectimax to compute a policy, re-scaling the values of all the leaf nodes by multiplying them all with 10 can result in a different policy being optimal.

**Self assessment** If correct, write “correct” in the box. Otherwise, write and explain the correct answer.

Correct

## (d) MDPs For this question, assume that the MDP has a finite number of states.

- (i) [~~true~~ or false] For an MDP  $(S, A, T, \gamma, R)$  if we only change the reward function  $R$  the optimal policy is guaranteed to remain the same.
- (ii) [~~true~~ or false] Value iteration is guaranteed to converge if the discount factor ( $\gamma$ ) satisfies  $0 < \gamma < 1$ .
- (iii) [~~true~~ or false] Policies found by value iteration are superior to policies found by policy iteration.

**Self assessment** If correct, write “correct” in the box. Otherwise, write and explain the correct answer.

Correct

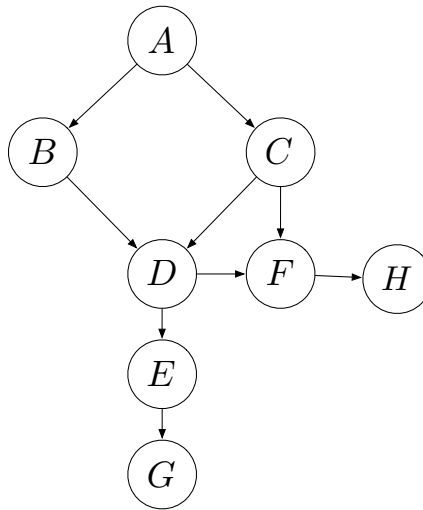
(e) **Reinforcement Learning**

- (i) ☒ *true* or *false* Q-learning can learn the optimal Q-function  $Q^*$  without ever executing the optimal policy.
- (ii) ☒ *true* or *false* If an MDP has a transition model  $T$  that assigns non-zero probability for all triples  $T(s, a, s')$  then Q-learning will fail.

**Self assessment** If correct, write “correct” in the box. Otherwise, write and explain the correct answer.

Correct

- (f) **Bayes’ Nets** For each of the conditional independence assertions given below, circle whether they are guaranteed to be true, guaranteed to be false, or cannot be determined for the given Bayes’ net.



$B \perp\!\!\!\perp C$	Guaranteed true	Guaranteed false	<input checked="" type="radio"/> Cannot be determined
$B \perp\!\!\!\perp C \mid G$	Guaranteed true	<input checked="" type="radio"/> Guaranteed false	Cannot be determined
$B \perp\!\!\!\perp C \mid H$	Guaranteed true	<input checked="" type="radio"/> Guaranteed false	Cannot be determined
$A \perp\!\!\!\perp D \mid G$	Guaranteed true	<input checked="" type="radio"/> Guaranteed false	Cannot be determined
$A \perp\!\!\!\perp D \mid H$	Guaranteed true	<input checked="" type="radio"/> Guaranteed false	Cannot be determined
$B \perp\!\!\!\perp C \mid A, F$	<input checked="" type="radio"/> Guaranteed true	Guaranteed false	Cannot be determined
$F \perp\!\!\!\perp B \mid D, A$	<input checked="" type="radio"/> Guaranteed true	Guaranteed false	Cannot be determined
$F \perp\!\!\!\perp B \mid D, C$	<input checked="" type="radio"/> Guaranteed true	Guaranteed false	Cannot be determined

**Self assessment** If correct, write “correct” in the box. Otherwise, write and explain the correct answer.

## Q2. Perceptron

- (a) Suppose you have a binary perceptron in 2D with weight vector  $\mathbf{w} = r [w_1, w_2]^T$ . You are given  $w_1$  and  $w_2$ , and are given that  $r > 0$ , but otherwise not told what  $r$  is. *Assume that ties are broken as positive.*

Can you determine the perceptron's classification of a new example  $x$  with known feature vector  $f(x)$ ?

☒ Always    ☐ Sometimes    ☐ Never

- (b) Now you are learning a multi-class perceptron between 4 classes. The weight vectors are currently  $[1, 0]^T$ ,  $[0, 1]^T$ ,  $[-1, 0]^T$ ,  $[0, -1]^T$  for the classes A, B, C, and D. The next training example  $x$  has a **label of A** and feature vector  $f(x)$ .

For the following questions, *do not make any assumptions about tie-breaking.* (Do not write down a solution that creates a tie.)

- (i) Write down a feature vector in which no weight vectors will be updated.

$$f(x) = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad \text{Not possible}$$

- (ii) Write down a feature vector in which **only**  $\mathbf{w}_A$  will be updated by the perceptron.

$$f(x) = \begin{bmatrix} \phantom{0} \\ \phantom{0} \end{bmatrix} \quad \text{Not possible}$$

- (iii) Write down a feature vector in which **only**  $\mathbf{w}_A$  and  $\mathbf{w}_B$  will be updated by the perceptron.

$$f(x) = \begin{bmatrix} -1 \\ 2 \end{bmatrix} \quad \text{Not possible}$$

- (iv) Write down a feature vector in which **only**  $\mathbf{w}_A$  and  $\mathbf{w}_C$  will be updated by the perceptron.

$$f(x) = \begin{bmatrix} -2 \\ 1 \end{bmatrix} \quad \text{Not possible}$$

The weight vectors are the same as before, but now there is a bias feature with value of 1 for all  $x$  and the weight of this bias feature is 0,  $-2$ ,  $1$ ,  $-1$  for classes A, B, C, and D respectively. As before, the next training example  $x$  has a **label of A** and a feature vector  $f(x)$ . The always “1” bias feature is the first entry in  $f(x)$ .

- (v) Write down a feature vector in which **only**  $\mathbf{w}_B$  and  $\mathbf{w}_C$  will be updated by the perceptron.

$$f(x) = \begin{bmatrix} 1 \\ \phantom{0} \end{bmatrix} \quad \text{Not possible}$$

- (vi) Write down a feature vector in which **only**  $\mathbf{w}_A$  and  $\mathbf{w}_C$  will be updated by the perceptron.

$$f(x) = \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix} \quad \text{Not possible}$$

**Self assessment** If correct, write “correct” in the box. Otherwise, **write and explain** the correct answer.

Correct