

Statistics 568 Bayesian Analysis

Multiparameter Models

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Noninformative and weakly informative priors

Sometimes, You may want Your prior distribution to play a minimal role in the posterior distribution. *Let the data speak for themselves.*

- ▶ “Vague”, “flat”, or “diffuse” prior;
- ▶ **Reference prior;**

Perhaps **weakly informative priors** should be preferred. Or, use hierarchical modeling and sensitivity analysis.

Proper vs improper prior distributions

In the Normal location model

$$p(y | \theta) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{1}{2\sigma^2} (y - \theta)^2\right),$$

a flat prior for θ , i.e. $p(\theta) \propto 1$, is *improper*.

Definition

A prior density is proper if it does not depend on data and integrates to 1.

- ▶ Non-informative priors can often be improper.
- ▶ Improper prior distributions can (but not always) lead to proper posterior distributions. **Avoid improper posterior distributions at all cost!***

*Unless it is Your intention to specify a merely finitely additive probability model.

Jeffreys' invariance principle. Suppose $\phi = \phi(\theta)$ is a one-to-one transformation of the parameter. A noninformative prior $p(\theta)$ should express equivalent probability assignment for the transformed ϕ . That is, we want a prior that's invariant to parametrization:

$$p(\phi) = p(\theta) \left| \frac{d\theta}{d\phi} \right|.$$

Reference priors

This means that one should set

$$p(\theta) \propto |J(\theta)|^{1/2}$$

where

$$J(\theta) = E \left(\left[\frac{d \log p(y | \theta)}{d\theta} \right]^2 \mid \theta \right) = -E \left(\frac{d^2 \log p(y | \theta)}{d\theta^2} \mid \theta \right)$$

is the Fisher information for θ . *Why?*

Example. For Binomial model $y \mid \theta \sim \text{Bin}(n, \theta)$, Jeffreys' prior is

$$\theta \sim \text{Beta}(1/2, 1/2).$$

Note.

- ▶ Jeffreys' prior may be improper;
- ▶ Extension to multiparameter models may be controversial;
- ▶ Jeffreys' prior is entirely determined by the sampling model. Is it still a prior in the truest sense?

Multiparameter models: marginalization

Model parameter is multi-dimensional: $\theta = (\theta_1, \theta_2)$, in which θ_1 is of interest, and θ_2 is a **nuisance parameter**.

The **marginal posterior** distribution for θ_1 :

$$p(\theta_1 | y) = \int p(\theta_1, \theta_2 | y) d\theta_2.$$

Multiparameter models: marginalization

The posterior predictive distribution is in a sense a marginal posterior distribution:

$$\begin{aligned} p(\tilde{y} | y) &= \int p(\tilde{y} | \theta) p(\theta | y) d\theta \\ &= \int p(\tilde{y}, \theta | y) d\theta. \end{aligned}$$

Location-scale Normal model, noninformative prior

Sampling model:

$$y \mid \mu, \sigma^2 \sim N(\mu, \sigma^2).$$

A noninformative prior that is uniform on $(\mu, \log \sigma)$:

$$p(\mu, \sigma^2) \propto \sigma^{-2}.$$

Is this prior proper?

Location-scale Normal model, noninformative prior

Joint posterior:

$$\begin{aligned} p(\mu, \sigma^2 \mid y) &\propto \sigma^{-2} \prod_{i=1}^n \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{1}{2\sigma^2}(y_i - \mu)^2\right) \\ &\propto \sigma^{-n-2} \exp\left(-\frac{1}{2\sigma^2} [(n-1)s^2 + n(\bar{y} - \mu)^2]\right) \end{aligned}$$

where

$$\bar{y} = \frac{1}{n} \sum_{i=1}^n y_i, \quad s^2 = \frac{1}{n-1} \sum_{i=1}^n (y_i - \bar{y})^2$$

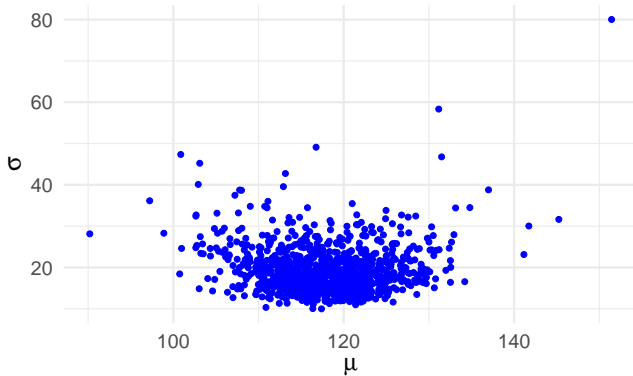
are the sample mean and sample variance.

Location-scale Normal model, noninformative prior

Joint posterior draws

$$\mu^{(s)}, \sigma^{(s)} \sim p(\mu, \sigma \mid y)$$

Draws from the joint posterior distribution

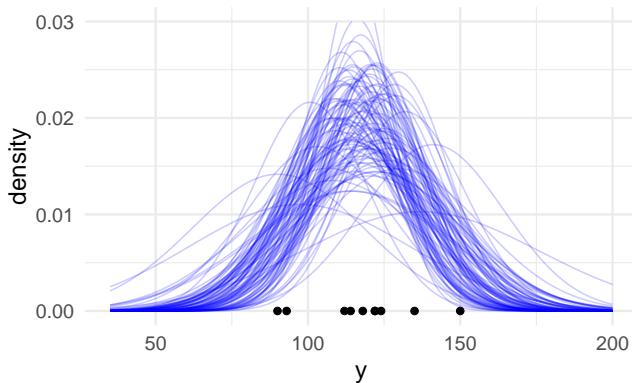


Location-scale Normal model, noninformative prior

Joint posterior draws

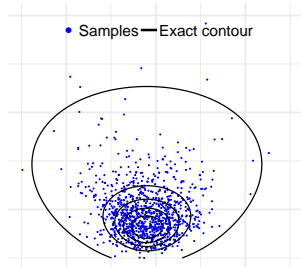
$$\mu^{(s)}, \sigma^{(s)} \sim p(\mu, \sigma \mid y)$$

Gaussians with posterior draw parameters

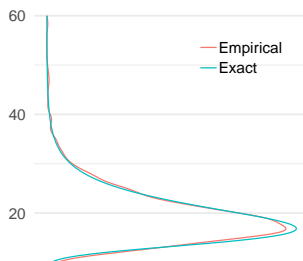


Location-scale Normal model, noninformative prior

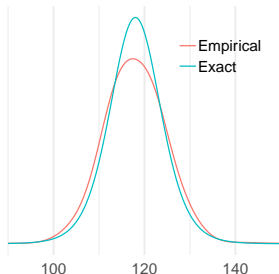
Joint posterior



Marginal of sigma



Marginal of mu



$$\mu^{(s)}, \sigma^{(s)} \sim p(\mu, \sigma | y)$$

marginals

$$p(\mu | y) = \int p(\mu, \sigma | y) d\sigma$$

$$p(\sigma | y) = \int p(\mu, \sigma | y) d\mu$$

Location-scale Normal model, noninformative prior

$$p(\mu, \sigma^2 \mid y) \propto \sigma^{-n-2} \exp \left(-\frac{1}{2\sigma^2} [(n-1)s^2 + n(\bar{y} - \mu)^2] \right)$$

Univariate **factorization** of the joint posterior:

- ▶ $\mu \mid \sigma^2, y \sim$
- ▶ $\sigma^2 \mid y \sim$

Location-scale Normal model, noninformative prior

$$p(\sigma^2 | y) \propto$$

Location-scale Normal model, noninformative prior

Marginal posterior for μ :

$$p(\mu \mid y) = \int_0^\infty p(\mu, \sigma^2 \mid y) d\sigma^2$$

$$\propto \left[1 + \frac{n(\mu - \bar{y})^2}{(n-1)s^2} \right]^{-n/2} \sim t_{n-1} \left(\bar{y}, \frac{s^2}{n} \right).$$

Location-scale Normal model, noninformative prior

Posterior predictive distribution for a future observation \tilde{y} :

$$p(\tilde{y} | y) = \int p(\tilde{y} | \mu, \sigma^2, y) p(\mu, \sigma^2 | y) d\mu d\sigma^2.$$

A more clever arrangement:

$$p(\tilde{y} | y) = \int p(\tilde{y} | \sigma^2, y) p(\sigma^2 | y) d\sigma^2$$

We have

$$\tilde{y} | y \sim t_{n-1} \left(\bar{y}, \left(1 + \frac{1}{n} \right) s^2 \right).$$

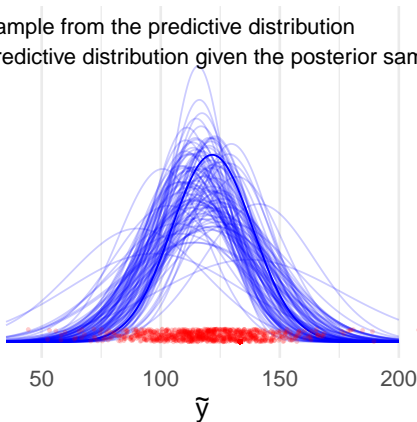
Location-scale Normal model, noninformative prior

Monte Carlo strategy for posterior predictive draws:

$$\begin{aligned}\mu^{(s)}, \sigma^{(s)} &\sim p(\mu, \sigma \mid y) \\ \tilde{y}^{(s)} \mid \mu^{(s)}, \sigma^{(s)} &\sim p(\tilde{y} \mid \mu^{(s)}, \sigma^{(s)})\end{aligned}$$

Posterior predictive distribution

- Sample from the predictive distribution
- Predictive distribution given the posterior sample



Location-scale Normal model, conjugate prior

Parameterize the conjugate prior for the Normal location-scale model as

$$\begin{aligned}\mu \mid \sigma^2 &\sim N(\mu_0, \sigma^2/\kappa_0), \\ \sigma^2 &\sim \text{Inv-}\chi^2(\nu_0, \sigma_0^2),\end{aligned}$$

jointly denoted as

$$(\mu, \sigma^2) \sim \text{N-Inv-}\chi^2(\mu_0, \sigma_0^2/\kappa_0; \nu_0, \sigma_0^2).$$

Notice that the two parameters are *apriori* dependent.

Location-scale Normal model, conjugate prior

Joint posterior

$$\mu, \sigma^2 \mid y \sim \text{N-Inv-}\chi^2(\mu_n, \sigma_n^2/\kappa_n; \nu_n, \sigma_n^2),$$

where

$$\mu_n = \frac{\kappa_0}{\kappa_0 + n} \mu_0 + \frac{n}{\kappa_0 + n} \bar{y},$$

$$\kappa_n = \kappa_0 + n,$$

$$\nu_n = \nu_0 + n,$$

$$\nu_n \sigma_n^2 = \nu_0 \sigma_0^2 + (n-1)s^2 + \frac{\kappa_0 n}{\kappa_0 + n} (\bar{y} - \mu_0)^2.$$

Location-scale Normal model, conjugate prior

Joint posterior

$$\mu, \sigma^2 \mid y \sim \text{N-Inv-}\chi^2(\mu_n, \sigma_n^2/\kappa_n; \nu_n, \sigma_n^2),$$

which upon factorization,

$$\begin{aligned}\mu \mid \sigma^2, y &\sim N(\mu_n, \sigma^2/\kappa_n), \\ \sigma^2 &\sim \text{Inv-}\chi^2(\nu_n, \sigma_n^2).\end{aligned}$$

The marginal posterior for μ

$$\mu \mid y \sim t_{\nu_n} \left(\mu_n, \frac{\sigma_n^2}{\kappa_n} \right).$$

Example: Bioassay

An experiment administers various dose levels of some substance to batches of animals, and record the outcomes. Data is of the form

$$(x_i, n_i, y_i), i = 1, \dots, k$$

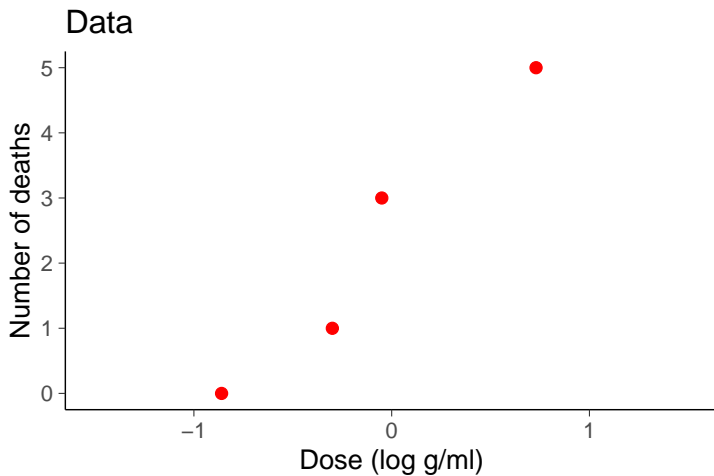
where

- ▶ x_i : the i th of k dose levels,
- ▶ n_i : # animals in batch i ;
- ▶ y_i : # animals in batch i with positive outcome, e.g. death: '(.

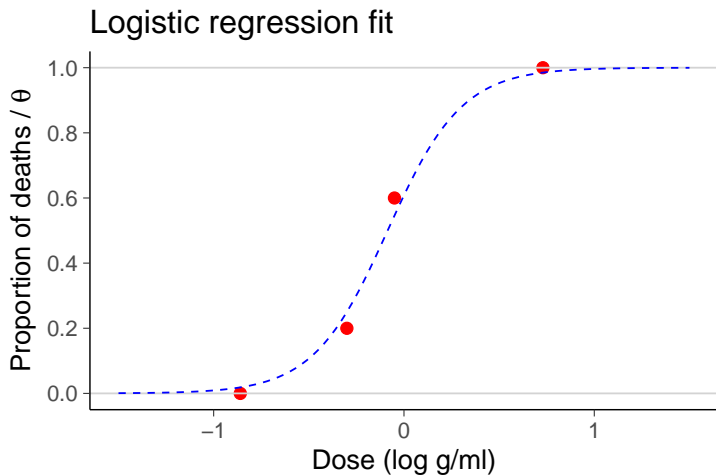
Dose, x_i (log g/ml)	Number of animals, n_i	Number of deaths, y_i
-0.86	5	0
-0.30	5	1
-0.05	5	3
0.73	5	5

Table: Table 3.1 of BDA3

Example: Bioassay



Example: Bioassay



Example: Bioassay

Consider the **logistic regression** model (with one predictor per observation). Sampling model:

$$y_i \mid \theta_i \sim \text{Bin}(n_i, \theta_i)$$
$$\text{logit}(\theta_i) = \log \frac{\theta_i}{1 - \theta_i} = \alpha + \beta x_i$$

Example: Bioassay

Likelihood:

$$p(y_i \mid \alpha, \beta, n_i, x_i) \propto [\text{logit}^{-1}(\alpha + \beta x_i)]^{y_i} [1 - \text{logit}^{-1}(\alpha + \beta x_i)]^{n_i - y_i}.$$

Posterior:

$$p(\alpha, \beta \mid y, n, x) \propto p(\alpha, \beta) \prod_{i=1}^n p(y_i \mid \alpha, \beta, n_i, x_i).$$

With uniform prior $p(\alpha, \beta) \propto 1$, this is not simply analytical. We will compute the joint posterior at a grid of points (α, β) , and use it to produce posterior draws $(\alpha^{(s)}, \beta^{(s)})$.

Example: Bioassay - LD50

LD50 is the dose level, denote as x_{LD50} , at which the probability of death is 50%. For the logistic model,

$$E\left(\frac{y_i}{n_i}\right) = \text{logit}^{-1}(\alpha + \beta x_{LD50}) = 0.5,$$

that is,

$$x_{LD50} = -\alpha/\beta.$$

Posterior draws $(\alpha^{(s)}, \beta^{(s)})$ can be used, e.g. to estimate

$$-\frac{1}{S} \sum_{s=1}^S \frac{\alpha^{(s)}}{\beta^{(s)}} \rightarrow E[x_{LD50}].$$

See R.