

STAT1006 Week 9 Cheat Sheet

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Matrix Approach to Linear Regression

- Still exactly the same as linear regression, just a different representation
- Notation:
 - Vectors are lowercase bold letters: $\mathbf{y}, \hat{\mathbf{e}}, \boldsymbol{\beta}, \hat{\boldsymbol{\beta}}$
 - Matrices are uppercase bold letters: \mathbf{X}, \mathbf{I}
 - Scalars represented by italicised letters: y_i, x_i

Matrix Revision

Matrix Position Labels

$$\mathbf{X} = \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix} \rightarrow a_{ij}$$

* This pattern is represented as a_{ij} , where * i represents the i-th row * j represents the j-th column * Vectors are just $n \times 1$ matrices, and we will treat them as matrices * They are represented as a single column of data with n rows

Matrix Transpose:

- The transpose of an $r \times c$ matrix, is a $c \times r$ matrix
 - Written as \mathbf{X}'
 - The elements of \mathbf{X} are x_{ij}
 - The elements of \mathbf{X}' are x_{ji}

$$\mathbf{X} = \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{pmatrix} \rightarrow \mathbf{X}' = \begin{pmatrix} 1 & 4 & 7 \\ 2 & 5 & 8 \\ 3 & 6 & 9 \end{pmatrix}$$

Special Matrices

- Symmetrical matrices:
 - $\mathbf{A} = \mathbf{A}'$
 - This will be $n \times n$ matrices
 - This means that when transposed, the top left, to bottom right diagonal is the same as the original

$$\mathbf{A}_{2 \times 2} = \begin{pmatrix} \boxed{1} & 2 \\ 3 & \boxed{4} \end{pmatrix} \rightarrow \mathbf{A}'_{2 \times 2} = \begin{pmatrix} \boxed{1} & 3 \\ 2 & \boxed{4} \end{pmatrix}$$

- Diagonal matrices:
 - Where the matrix is made up of zeros, except for the top left, to bottom right diagonal
 - Will be a $n \times n$ matrix

$$\mathbf{A}_{3 \times 3} = \begin{pmatrix} \boxed{1} & 0 & 0 \\ 0 & \boxed{2} & 0 \\ 0 & 0 & \boxed{3} \end{pmatrix}$$

- Identity matrices:
 - The same as a diagonal matrix, except the diagonal is filled with ones

$$\mathbf{I}_{3 \times 3} = \begin{pmatrix} \boxed{1} & 0 & 0 \\ 0 & \boxed{1} & 0 \\ 0 & 0 & \boxed{1} \end{pmatrix}$$

- Unity Matrices:
 - All ones
 - Shape/size is irrelevant

$$\mathbf{1}_{2 \times 3} = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix}$$

- Zero matrices:
 - Same as unity matrix, except all zeroes

$$\mathbf{1}_{2 \times 3} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

Matrix Inversion

- You can use the identity matrix to find the inverse
- The inverse is the matrix you multiply the original matrix by to end up with an identity matrix

$$\mathbf{A} = \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}$$

- We want to find unknowns a, b, c, d

$$\mathbf{A}^{-1} = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \rightarrow$$

- We know that

$$\mathbf{A}\mathbf{A}^{-1} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \rightarrow$$

- And we have the equations

$$\mathbf{A}\mathbf{A}^{-1} = \begin{pmatrix} 1a + 2c & 1b + 2d \\ 3a + 4c & 3b + 4d \end{pmatrix}$$

- We are then able to then show that

$$\mathbf{A}^{-1} = \begin{pmatrix} 1 & -\frac{1}{4} \\ 0 & \frac{1}{4} \end{pmatrix} \rightarrow \text{and so } a = 1; b = -\frac{1}{4}; c = 0; d = \frac{1}{4}$$

Matrix Addition/Subtraction

- Just add the corresponding elements
- Can only add/subtract matrices with matching dimensions

Matrix Multiplication

- For each element of matrix \mathbf{A} , multiply x_i with x_j from matrix \mathbf{B} , where $i = j$
- Therefore Matrix \mathbf{A} must have the same number of rows, as matrix \mathbf{B} has columns

$$\begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{pmatrix} \begin{pmatrix} a & b \\ c & d \\ e & f \end{pmatrix} = \begin{pmatrix} 1a & 2c & 3e \\ 4b & 5d & 6f \end{pmatrix}$$

SLR in Matrix Form

- For $Y_i = \beta_0 + \beta_1 X_i + \varepsilon_i$; $Var(\varepsilon_i) = \sigma^2$
- It can be written as follows:

$$\mathbf{Y} = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{pmatrix}; \mathbf{X} = \begin{pmatrix} 1 & X_1 \\ 1 & X_2 \\ \vdots & \vdots \\ 1 & X_n \end{pmatrix}; \boldsymbol{\varepsilon} = \begin{pmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \vdots \\ \varepsilon_n \end{pmatrix}; \boldsymbol{\beta} = \begin{pmatrix} \beta_0 \\ \beta_1 \end{pmatrix}$$

- Where \mathbf{Y} is $n \times 1$, \mathbf{X} is $n \times 2$, $\boldsymbol{\varepsilon}$ is $n \times 1$, and $\boldsymbol{\beta}$ is 2×1
- \mathbf{X} has a row of 1's because you need to have as many rows as there are unknown parameters (not including σ). The 1 allows us to find β_0
- So;

$$\mathbf{X}\boldsymbol{\beta} = \begin{pmatrix} 1 & X_1 \\ 1 & X_2 \\ \vdots & \vdots \\ 1 & X_n \end{pmatrix} \begin{pmatrix} \beta_0 \\ \beta_1 \end{pmatrix} = \begin{pmatrix} \beta_0 & \beta_1 X_1 \\ \beta_0 & \beta_1 X_2 \\ \vdots & \vdots \\ \beta_0 & \beta_1 X_n \end{pmatrix}$$

- So the simple linear model in matrix notation is:
 - $\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\varepsilon}$
- Due to transposing, the sum of squares terms are given by
 - $\sum \varepsilon_i^2$
 - For any vector a , $a'a$ represents the sum of the squares of the elements of a

SLR Matrix Means, Variance and Covariance

- Mean:
 - We know that $E(Y_n|X) = \beta_0 + \beta_1 X_n$
 - This is equivalent to $E(\mathbf{Y}|\mathbf{X}) = \mathbf{X}\boldsymbol{\beta}$
 - * Because $E(\boldsymbol{\varepsilon}) = 0$
- For any set of observations \mathbf{Y} , p is the number of parameters estimated (number of explanatory variables plus one for β_0)
- Variance:
 - we know that $Var(Y) \approx \frac{1}{n-c} \sum (Y_i - \hat{Y}_i)^2$
 - * And that the linear assumptions means $Var(\varepsilon_i) = \sigma^2$
- Covariance
 - We know that $Cov(Y, X) \approx \frac{1}{n} \sum (Y_i - \bar{Y}_i)(X_i - \bar{X}_i) = \frac{1}{n} (\sum X_i Y_i - n\bar{X}\bar{Y})$
 - * And the linear assumptions means that $Cov(\varepsilon_i, \varepsilon_j) = 0$
- In matrix form $Var(\boldsymbol{\varepsilon}) = \sigma^2 I_n$
 - Where I_n is an identity matrix of size n
 - For a vector the term Var refers to a matrix containing the variance of each element of the vector, plus all the possible covariances between elements in the vector

$$E(\boldsymbol{\varepsilon}) = \begin{pmatrix} E(\varepsilon_1) = 0 \\ E(\varepsilon_2) = 0 \\ \vdots \\ E(\varepsilon_n) = 0 \end{pmatrix}; Var(\boldsymbol{\varepsilon}) = \begin{pmatrix} Var(\varepsilon_1) = \sigma^2 & Cov(\varepsilon_1, \varepsilon_2) = 0 \\ Cov(\varepsilon_2, \varepsilon_2) = 0 & Var(\varepsilon_2) = \sigma^2 \end{pmatrix} = \sigma^2 \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

- so for any vector \mathbf{Y} :
 - $Var(\mathbf{Y}) = E[(\mathbf{Y} - E(\mathbf{Y}))(\mathbf{Y} - E(\mathbf{Y}))']$
 - $Var(a\mathbf{Y}) = a^2 Var(\mathbf{Y})$
 - $Var(\mathbf{A}\mathbf{Y}) = \mathbf{A} Var(\mathbf{Y}) \mathbf{A}'$
 - $E(\mathbf{A}\mathbf{Y}) = \mathbf{A} E(\mathbf{Y})$
 - $Cov(\mathbf{X}, \mathbf{Y}) = E[(\mathbf{X} - E(\mathbf{X}))'(\mathbf{Y} - E(\mathbf{Y}))]$

Least Squares Estimation

- To estimate β , we must minimise SSE
 - $SSE = \varepsilon'\varepsilon = (\mathbf{Y} - \mathbf{X}\beta)$
- To do this we solve the Normal equations
 - $\sum Y_i = n\beta_0 + \beta_1 \sum X_i$
 - And $\sum X_i Y_i = \beta_0 \sum X_i + \beta_1 \sum X_i^2$
- In matrix form
 - $\mathbf{X}'\mathbf{Y} = \mathbf{X}'\mathbf{X}\beta$
 - $(\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{Y} = \hat{\beta}$

Estimates, Predicted Values, Sample Variance and Covariance

- Unbiased estimate
 - $E(\hat{\beta}) = \beta$
 - The LSR estimates are unbiased
- Predicted values and residuals
 - $\hat{\mathbf{Y}} = \mathbf{X}\hat{\beta}$
 - $\hat{\varepsilon} = \mathbf{Y} - \hat{\mathbf{Y}} = \mathbf{Y} - \mathbf{X}\hat{\beta}$
 - And $\hat{\mathbf{Y}} = \mathbf{H}\mathbf{Y}$, or the hat matrix
 - * It transforms the observations \mathbf{Y} into the predicted values
 - * $\mathbf{H}\mathbf{H} = \mathbf{H}$
- So, $\hat{\varepsilon} = (\mathbf{I} - \mathbf{H})\mathbf{Y}$
- And so the variances of the parameter estimates
 - $Var(\hat{\beta}) = \sigma^2(\mathbf{X}'\mathbf{X})^{-1}$
 - This matrix will be the same as before, except it will contain $Cov(\hat{\beta}_0, \hat{\beta}_1)$

Confidence interval for the Regression Line

- We know that $Var(\hat{Y}|X_0) = \sigma^2 \left(\frac{1}{n} + \frac{(X_0 - \bar{X})^2}{\sum (X_i - \bar{X})^2} \right)$
 - So, $Var(\hat{Y}|X_0) = \sigma^2 \mathbf{X}'_0 (\mathbf{X}'\mathbf{X})^{-1} X_0$
- For a given point $\hat{Y} = \hat{\beta}_0 + \hat{\beta}_1 X_0 = (1 X_0) \hat{\beta} = \mathbf{X}'_0 \hat{\beta}$
 - So for a given point $Var(Y|X_0) = \sigma^2 [1 + \mathbf{X}'_0 (\mathbf{X}'\mathbf{X})^{-1} X_0]$

Thinking in Terms of Matrices

1. Write down the Normal Equations for regression
2. Write these as a matrix equation
3. Consider how each element of the matrix and vector that don't involve β can be written as an inner product
4. What vectors are involved in these inner products?
5. Define a matrix \mathbf{X} and a vector \mathbf{Y} , so that you can write the Normal Equations as $\mathbf{X}'\mathbf{X}\beta = \mathbf{X}'\mathbf{Y}$
6. Use the same \mathbf{X} and \mathbf{Y} to write out the original equations relating responses to covariates

Multiple Regression

- When you want to look at multiple explanatory variables for one response variable
- One Y, multiple X's
- Population multiple regression equation:
 - $\mu_y = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \dots + \beta_p x_p$
 - * Where p is the number of explanatory variables

Multiple linear regression model:

- $y_i = \beta_0 + \beta_1 x_{i1} + \dots + \beta_p x_{ip} + \varepsilon_i$
 - For $i = 1, 2, \dots, n$
 - This is a linear function of the explanatory variables
 - * It is no longer a straight line, but it is a multidimensional straight(linear) plane
 - * Can use ggplot to plot 3 dimensions in R (max dimensions)
- Matrix form:
 - $\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\varepsilon}$

$$\mathbf{Y} = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{pmatrix}; \mathbf{X} = \begin{pmatrix} 1 & X_{11} & X_{12} & \dots & X_{1(p+1)} \\ 1 & X_{21} & X_{22} & \dots & X_{2(p+1)} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & X_{n1} & X_{n2} & \dots & X_{n(p+1)} \end{pmatrix}; \boldsymbol{\varepsilon} = \begin{pmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \vdots \\ \varepsilon_n \end{pmatrix}; \boldsymbol{\beta} = \begin{pmatrix} \beta_0 \\ \beta_1 \\ \vdots \\ \beta_{p+1} \end{pmatrix}$$

- Where $X = X_{ij}$, where $i = 1, 2, \dots, n$, and $j = 1, 2, \dots, p, p + 1$
- And \mathbf{Y} is $n \times 1$, \mathbf{X} is $n \times (p + 1)$, $\boldsymbol{\varepsilon}$ is $n \times 1$, and $\boldsymbol{\beta}$ is $(p + 1) \times 1$
- You can write \mathbf{X} as $\mathbf{X} = [1, X_1, X_2, \dots, X_p]'$
- The coefficient β_i represents the average change in the response when the variable x_i increases by one unit and **all other variables are held constant**
- Assumptions:
 - The deviations ε_i are independent and Normally distributed $N(0, \sigma)$
 - * That σ^2 is unknown
 - Check these by ensuring there is no pattern in the residual plot
 - That $n > p$
 - * if $n < p$, possibly infinitely many solutions
 - * if $n = p$, a solution, if it exists, is unique
 - * if $n > p$, no solution
 - So we estimate using least squares

Parameter Estimation

- We know that $E(Y|x) = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \dots + \beta_p x_p$
 - Don't need to include variables that are not significant
- And that $\sigma^2 \approx s^2 = \frac{\sum e_i^2}{n-p-1} = \frac{\sum (y_i - \hat{y}_i)^2}{n-p-1}$
- For the least squares estimate:
 - $y = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\varepsilon}, \boldsymbol{\varepsilon} \sim N(0, \mathbf{I}\sigma^2)$
 - And so the least squares estimate is
 - * $\hat{\boldsymbol{\beta}} = (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{Y}$
 - * So We can find the fitted values and hat matrix the same as for SLR
- Covariance matrix:
 - $\text{Var}(\hat{\boldsymbol{\beta}}) = (\mathbf{X}'\mathbf{X})^{-1}\sigma^2$
 - $s^2 = \frac{SSE}{n-p-1} = \frac{1}{n-p-1}\boldsymbol{\varepsilon}'\boldsymbol{\varepsilon}$
 - * The only difference is the denominator

Confidence Intervals

- Confidence intervals are per β_j
 - A level C confidence interval for β_j is
 - * $\beta_j \pm t^* SE_{\beta_j}$

Significance Test

- Also per β_j
- Testing the hypothesis $H_0 : \beta_j = 0$
 - Calculate the t statistic
 - * $t = \frac{\beta_j}{SE_{\beta_j}} \sim t(n - p - 1)$
 - * When the null is true
 - Software usually gives a two-sided p-value, so halve for one sided
- If we test $H_0 : \beta_j = 0$ for each j, and find that NONE of the p tests are significant, this means we fail to reject the null, and we remove at least one variable and re-test
 - If all are significant, reject the null hypothesis
- So for testing $H_0 : \beta_i = 0$ using a t-test
 - $\frac{\hat{\beta}_i - 0}{se(\hat{\beta}_i)} \sim t_{n-p-1}$
 - And $se(\hat{\beta}_i)$ is the square root of the ith diagonal element of $Var(\hat{\beta})$
- Useful to look at a scatterplot matrix
 - Need to make sure you're looking at the plots where the explanatory variable is on the x-axis.
 - Can also look at the relationship between the explanatory variables themselves
 - They do not provide enough information to understand the joint relationship between response and the predictors
 - * Need to take into account the relationship between the predictors
- Focus on univariate summaries (one explanatory at a time), beware multivariate summaries

Multivariate Linear Regression in R

- `variable.lm = lm(response ~ x1 + x2 + ... + xp, data = df)`
 - If your using all other columns, can simplify to:
 - `variable.lm = lm(response ~ ., data = df)`
- Need to use Adjusted R-Squared for R^2
- For \mathbf{X} matrix (separated from \mathbf{Y} matrix)
 - $(\mathbf{X}'\mathbf{X})$ is `t(X) %*% X`
 - $(\mathbf{X}'\mathbf{X})^{-1}$ is `solve(t(X) %*% X)`
 - $(\mathbf{X}'\mathbf{Y})$ is `t(X) %*% Y`
 - $\hat{\beta}$ is `solve(t(X) %*% X) %*% t(X) %*% Y`
 - $Var(\hat{\beta})$ & $Cov(\hat{\beta})$ is `print(solve(t(X) %*% X) %*% X, digits = n)`

| | | x1 | x2 |
|----|--|--|--|
| | <div style="border: 1px solid black; padding: 2px;"><i>Var</i></div> | Cov | Cov |
| x1 | Cov | <div style="border: 1px solid black; padding: 2px;"><i>Var</i></div> | Cov |
| x2 | Cov | Cov | <div style="border: 1px solid black; padding: 2px;"><i>Var</i></div> |

- $\sigma \sim s$ is in the summary table, or you can call it directly with `summary(variable.lm)$sigma`
- Then use that for Var with `s * sqrt(diag(solve(t(X) %*% X) %*% X))`