tutorial_2_model_selection

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Gaussian model selection in the simplified Georgopoulos setting

In this setting, we measure n times the same cell but each time with a different angle of movement $\forall i \in \{0,\dots,n-1\},\ u_i=2\pi(\frac{i}{n}).$ We decompose the regression function on a Fourier basis until size p with $2p+1 \leq n$.

Question 1. Create a matrix X of size $n \times 2p + 1$. For $u_i = 2\pi(\frac{i}{n})$, the coefficient $X_{i,j}$ is given as follows:

```
egin{aligned} X_{i+1,j} &= 1 & 	ext{if } j = 1 \ X_{i+1,j} &= \cos(ku_i) & 	ext{if } j = 2k \ X_{i+1,j} &= \sin(ku_i) & 	ext{if } j = 2k+1 \end{aligned}
```

```
u \leftarrow function(i, n) \{2*pi*i/n\}
generate_fourier_matrix <- function(n, p) {</pre>
  ### Generates a matrix of size (n, 2p+1) of fourier
  ### coefficients
  # Checks if the parameters are ill-defined
  if (2*p+1>n) {
    print("FAILED to comply with 2p+1 lesser or equal to n")
    return(NULL)
  # Computes the fourier matrix
  fourier = matrix(NA, nrow=n, ncol=2*p+1)
  for (row in 1:n) {
    for (col in 1:(2*p+1)) {
      # Checks for the first column to populate with 1s
      if (col==1) {
        fourier[row, col] = 1
      } else {
        # Checks for pair-numbered columns, then populates
        if (col%%2==0){
          k = col/2
          fourier[row, col] = cos(k*u(row-1,n)) # row-1 as i starts at 0
        } else {
          k = (col-1)/2
          fourier[row, col] = sin(k*u(row-1,n))
  return(fourier)
```

We print an example matrix X with parameters n=10 and p=2:

```
X = generate_fourier_matrix(10, 2)
round(X, 5)
```

```
##
        [,1]
                [,2]
                        [,3]
                                 [,4]
                                         [,5]
##
        1 1.00000 0.00000 1.00000 0.00000
  [1,]
## [2,]
        1 0.80902 0.58779 0.30902 0.95106
## [3,]
        1 0.30902 0.95106 -0.80902 0.58779
## [4,]
        1 -0.30902 0.95106 -0.80902 -0.58779
## [5,]
        1 -0.80902 0.58779 0.30902 -0.95106
## [6,]
        1 -1.00000 0.00000 1.00000 0.00000
## [7,]
        1 -0.80902 -0.58779 0.30902 0.95106
## [8,]
        1 -0.30902 -0.95106 -0.80902 0.58779
## [9,]
        1 0.30902 -0.95106 -0.80902 -0.58779
## [10,]
          1 0.80902 -0.58779 0.30902 -0.95106
```

Question 2. By computing the different scalar products (with R), show that the columns of X are orthogonal but not of norm 1 and renormalize them: this gives you the matrix X'.

```
check <- function(vec1, vec2) {</pre>
 ### Two vectors v1 and v2 are orthogonal if their inner
 ### product is equal to zero
 # Rounding to account for floating point memory mgt
  round(sum(vec1 * vec2), 15) == 0
}
check_length <- function(x) {</pre>
 # Check the length of unique elems in a list of two elements
 # Used to remove elems of a permutation where the same index
 # is used twice
 length(unique(x))==2
check_orthogonality <- function(matrix_to_check) {</pre>
 ### Exhaustively checks for the orthogonality of each columns
 ### of a matrix with each other
 nc = dim(matrix_to_check)[2]
 # Computes all permutations of column indexes
 # not optimized, contains clones (swapped indexes)
 perms = expand.grid(c1=1:nc, c2=1:nc, stringsAsFactors=F)
 perms = perms[apply(perms, 1, check_length),]
 # Interatively checks for orthogonality
 all(apply(perms, 1,function(x) {check(
    matrix_to_check[,x[1]], matrix_to_check[,x[2]])
    }))
}
norm <- function(vec) {sqrt(sum(vec * vec))}</pre>
compute_norm_list <- function(matrix_to_check) {</pre>
 ### Computes the norm of each column of a matrix and returns
 ### the list of norms
 apply(matrix_to_check, 2, norm)
}
orthonormalize_matrix <- function(matrix_to_cast) {</pre>
 ### Divides every column vector of a matrix by its norm
  apply(matrix_to_cast, 2, function(x){x/norm(x)})
}
```

We check whether our previous example matrix X has its vectors orthogonal with each other.

```
check_orthogonality(X)
```

```
## [1] TRUE
```

We then check whether the column vectors of the example matrix X have a norm different from 1. The respective norms of the 5 columns are:

```
compute_norm_list(X)
```

```
## [1] 3.162278 2.236068 2.236068 2.236068 2.236068
```

We then normalize each column vector of the example matrix X by its norm, and check that the norm of each column vector of the resulting matrix X' is 1.

```
Xprime = orthonormalize_matrix(X)
compute_norm_list(Xprime)
```

```
## [1] 1 1 1 1 1
```

We can also check whether X^\prime is orthonormal once the normalization step has been performed:

```
# Rounding to take into account floating point memory mgt # QQ^t = I round(t(Xprime)%*%Xprime, 15)
```

```
[,1] [,2] [,3] [,4] [,5]
##
## [1,]
           1
                0
                      0
                           0
                      0
                                0
## [2,]
           0
                1
                           0
           0
                0
                           0
                                0
## [3,]
                     1
## [4,]
           0
                0
                      0
                           1
                                0
## [5,]
           0
                0
                                1
```

Question 3. Give, for a given d < p, the projection estimator of the regression function composed of the first 2d + 1 Fourier coefficients. Transform this into a function in R.

```
construct_projection_matrix <- function(X, d) {
    ### Retrieves the first 2*d+1 columns of the generated fourier
    ### projection matrix
    # Checks if the parameters are ill-defined
    if (2*d+1>=dim(X)[2]) {
        print("FAILED to comply with 2d+1 <= ncols(X) (i.e. d >= p)")
        return(NULL)
    }
    # Returns the truncated projection matrix
    X[,1:(2*d+1)]
}
```

Question 4. Simulate two different experiments:

$$egin{aligned} Y_i &= 16 + 14\cos(u_i) + 5\epsilon_i \ Y_i &= 10\exp(-rac{(u_i - \pi)^2}{0.2}) + 1*\epsilon_i \ \end{aligned}$$
 with $\epsilon_i \sim \mathcal{N}(0,1)$ (IID)

Plot the data, the true function to estimate and 4 or 5 different projection estimators in each cases. Explain the problem of overfitting and the problem of taking a model of too low dimension. NB: you can try other regression function if you want

We decide to proceed with an example simulation with n=1000 (i.e. the same cell is measured 1000 times with a different angle of movement). We arbitrarily set the factor p to 200, leaving us enough space to produce 5 values d such that $d \in \{1, \ldots, p-1\}$.

We choose for d the values: 2, 5, 25, 100, 150. Our choice is oriented by wanting to display the problem of overfitting in modelling as well as when too few parameters are selected.

Given 1000 observations for each simulation and a maximum of 200 Fourier coefficients, we select the f ollowing amounts of coefficients to perform projection/regressions: 2 5 25 50 199

We compute the general matrix X' of the Fourier-basis regression function to be used for the rest of the exercise to compute projection estimators:

```
# Generates the orthonormal matrix Xprime as our X matrix
X = orthonormalize_matrix(generate_fourier_matrix(n, p))
```

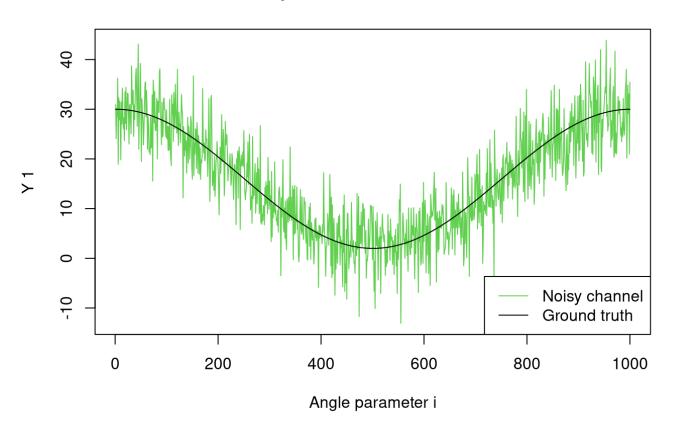
We can now generate the two simulations (both the base truth and acquired noisy signal):

```
# Declares the simulation functions
generate_experiment_1 <- function(n) {</pre>
  ### Generates the simulation 1: 16+14*cos(u i)+5*\epsilon i
  ### We recall i \in \{0, n-1\}, to inform the use of seq()
  f \leftarrow function(x)\{16+14*cos(u(x,n))\}
  truth = apply(as.matrix(seq(0,n-1,1)),1,f)
  noise = 5*rnorm(n,0,1)
  return(list("truth"=truth, "noisy_signal"=truth+noise))
}
generate_experiment_2 <- function(n) {</pre>
  ### Generates the simulation 2: 10*exp(-\frac{(u_i-\pi)^2}{0.2})
                                    + \epsilon_i
  ### We recall i \in \{0, n-1\}, to inform the use of seq()
  f \leftarrow function(x)\{10*exp(-(u(x,n)-pi)^2/0.2)\}
  truth = apply(as.matrix(seq(0,n-1,1)),1,f)
  noise = rnorm(n,0,1)
  return(list("truth"=truth, "noisy_signal"=truth+noise))
}
# Generates the simulations
Y1 = generate_experiment_1(n)
Y2 = generate_experiment_2(n)
```

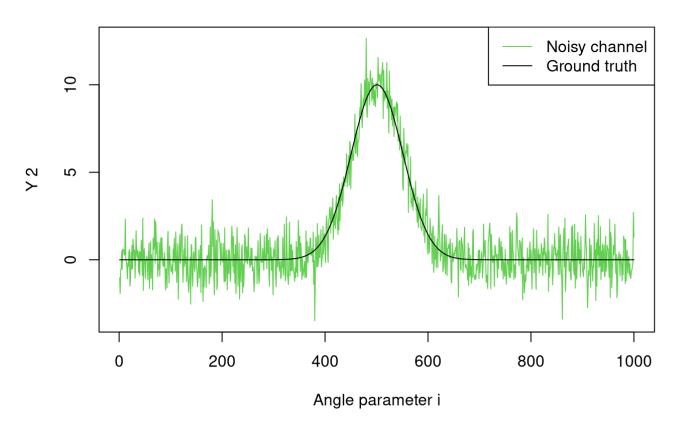
Once the data generated, we can plot the truth and its noisy channel (simulated):

```
plot_simulation <- function(Y, simulation_num, legend_position=NULL, title=NULL) {</pre>
 ### Plots the simulated data with some branch check to see if
 ### it stands alone or will be used later on for overplotting other signals
 if (is.null(legend_position)){
    colors = c("azure2", 1)
 } else {
    colors = c(3,1)
 if (is.null(title)){
    title = paste("Experiment", simulation_num, "simulations")
 # Plots the given data
 plot(Y$noisy_signal, type="l", col=colors[1],
       main=title,
       xlab="Angle parameter i",
       ylab=paste("Y",simulation_num))
 lines(Y$truth, type="l", col=colors[2])
 # If required, prints the legend
 if (is.null(legend_position)==F) {
    legend(x=legend_position,
           legend=c("Noisy channel", "Ground truth"),
           lty=c(1,1),
           col=colors)
 }
}
plot_simulation(Y1, 1, legend_position="bottomright")
```

Experiment 1 simulations



Experiment 2 simulations



Based on this data, we can first compute the resulting projection estimators for the 5 values of d we previously chose. We can also work back the predicted signal based on the resulting Fourier-basis regression.

```
generate projection estimators <- function(</pre>
 projection_matrix, signal, d, print_coeffs = T
 ) {
 ### Prints out the projection estimators given the convolution of a
 ### Fourier-basis regression matrix with the original noisy signal
 ### Returns the retro-projection (i.e. the regression) of the original
 ### signal with the estimators
 # Computes the estimators and prints them
 estimators = signal %*% projection_matrix
 if (print_coeffs) {
    if (length(estimators) <= 10) {</pre>
      cat("Given a Fourier-basis projection matrix with", d, "coefficients, ",
          "the computed estimators are:", estimators, "\n\n")
    } else {
      cat("Given a Fourier-basis projection matrix with", d, "coefficients, ",
          "the first", round(10+d/10), "computed estimators are:",
          estimators[1:round(10+d/10)],"\n\n")
    }
 }
 # Computes the retroprojection and returns it
  retroprojection = estimators %*% t(projection matrix)
  return(retroprojection)
}
compute_retroprojections <- function (</pre>
 projection_matrix, signal, d_sequence, simulation_number
  ) {
 ### Computes for each d value the corresponding estimators and the retro-
 ### projection of the original noisy signal for plotting purposes
  cat("Computation for simulation Y", simulation\_number,":\n")
 apply(d_sequence,1,function(d){generate_projection_estimators(
    projection_matrix[,1:(2*d+1)],
    signal,
 )})
}
predicted_Y1 = compute_retroprojections(X, Y1$noisy_signal, d_sequence, 1)
## Computation for simulation Y 1 :
```

```
## Computation for simulation Y 1 :
## Given a Fourier-basis projection matrix with 2 coefficients, the computed estimators are: 499.7605 30
2.7456 7.126159 7.623821 3.480203
##
## Given a Fourier-basis projection matrix with 5 coefficients, the first 10 computed estimators are: 49
9.7605 302.7456 7.126159 7.623821 3.480203 -4.768477 0.102288 5.631147 7.243351 2.109828
##
## Given a Fourier-basis projection matrix with 25 coefficients, the first 12 computed estimators are: 4
99.7605 302.7456 7.126159 7.623821 3.480203 -4.768477 0.102288 5.631147 7.243351 2.109828 1.510844 -6.219
446
##
## Given a Fourier-basis projection matrix with 50 coefficients, the first 15 computed estimators are: 4
99.7605 302.7456 7.126159 7.623821 3.480203 -4.768477 0.102288 5.631147 7.243351 2.109828 1.510844 -6.219
446 -6.488756 -9.381153 -0.7670025
##
## Given a Fourier-basis projection matrix with 199 coefficients, the first 30 computed estimators are: 4
99.7605 302.7456 7.126159 7.623821 3.480203 -4.768477 0.102288 5.631147 7.243351 2.109828 1.510844 -6.219
446 -6.488756 -9.381153 -0.7670025 1.61144 -2.889967 -6.178573 8.027966 -0.5300009 8.051157 -4.742265 3.
561217 1.825468 7.018801 0.0477998 9.00664 -1.002543 -10.75795 -4.374501
```

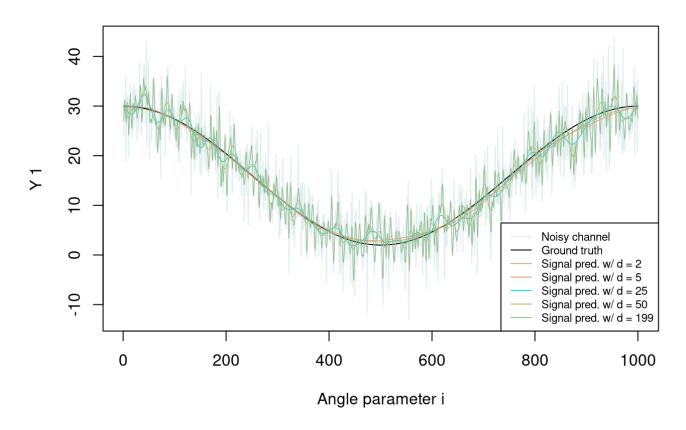
predicted_Y2 = compute_retroprojections(X, Y2\$noisy_signal, d_sequence, 2)

```
## Computation for simulation Y 2 :
## Given a Fourier-basis projection matrix with 2 coefficients, the computed estimators are: 39.97692 -5
3.31488 -1.658143 46.54344 1.139688
##
## Given a Fourier-basis projection matrix with 5 coefficients, the first 10 computed estimators are: 3
9.97692 -53.31488 -1.658143 46.54344 1.139688 -36.73931 -1.543742 26.32711 1.652099 -16.88448
##
## Given a Fourier-basis projection matrix with 25 coefficients, the first 12 computed estimators are: 3
9.97692 -53.31488 -1.658143 46.54344 1.139688 -36.73931 -1.543742 26.32711 1.652099 -16.88448 0.4403855
9.601576
##
## Given a Fourier-basis projection matrix with 50 coefficients, the first 15 computed estimators are: 3
9.97692 -53.31488 -1.658143 46.54344 1.139688 -36.73931 -1.543742 26.32711 1.652099 -16.88448 0.4403855
9.601576 0.5453965 -5.970074 0.6364952
##
## Given a Fourier-basis projection matrix with 199 coefficients, the first 30 computed estimators are: 39.97692 -53.31488 -1.658143 46.54344 1.139688 -36.73931 -1.543742 26.32711 1.652099 -16.88448 0.4403855
9.601576 0.5453965 -5.970074 0.6364952 2.065646 -0.206294 -1.979342 -1.748079 0.5549805 0.4383661 0.54850
98 1.052259 -0.3722075 0.686713 -1.407419 0.9029792 0.003281312 -0.4926788 1.043011
```

We now can plot the predicted signals over their original ground truth and recorded noisy channel.

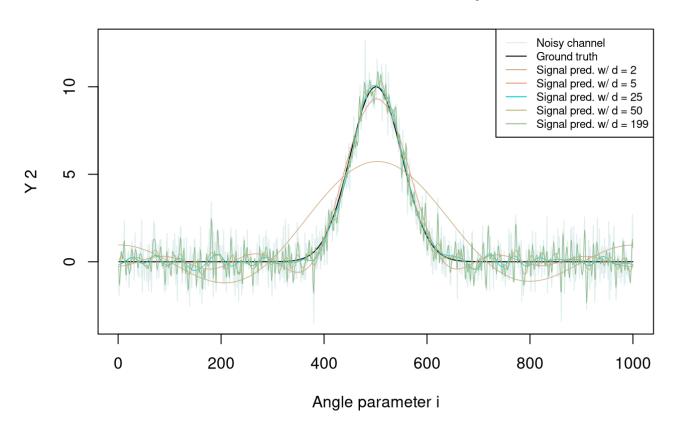
```
overplot_predicted_signals <- function(predictions, d_sequence, legend_position) {</pre>
 ### Based on the function plot simulation(), overplots the predicted signals
 ### given a number of projection estimators
 # Declares legend variables
 colors = c("azure2", 1, "burlywood3", "darksalmon",
             "darkturquoise", "darkkhaki", "darkseagreen")
 names = c(c("Noisy channel", "Ground truth"),
            c(apply(d_sequence, 1,
                    function(x){paste("Signal pred. w/ d =", x)})))
 # Computes the lines to add to a previously declared plot
 for (i in 1:dim(predictions)[2]) {
    lines(predictions[,i], type="l",col=colors[i+2], lwd=0.7)
 # Adds the legend
 legend(x=legend_position,
           legend=names,
           lty=1,
           col=colors,
         cex=0.7)
}
plot_simulation(Y1, 1, title="Y1 simulation with Fourier-basis predictions")
overplot_predicted_signals(predicted_Y1, d_sequence,legend_position="bottomright")
```

Y1 simulation with Fourier-basis predictions



plot_simulation(Y2, 2, title="Y2 simulation with Fourier-basis predictions")
overplot_predicted_signals(predicted_Y2, d_sequence,legend_position="topright")

Y2 simulation with Fourier-basis predictions



Observations (the problem of overfitting and underfitting):

Overfitting is the situation where training a model relies on enough parameters that it starts learning/fitting over the noise of the [training] dataset as well as the underlying ground truth.

Underfitting is the reverse situation where training a model does not have enough parameter to learn/fit the [training] dataset. There is not enough parameter in this case.

In the previous two simulations we can outline examples for those two behaviors:

- **Simulation 1** (an example of overfitting): We see that, using a Fourier basis, we do not require many Fourier coefficients (parametrized by the number d) to approximate the underlying ground truth (Note: this is due to the sinusoidal shape of the signal which is captured fairly well by simple fourier transforms). As such, increasing the number of Fourier coefficients by increasing the size of the projection matrix X leads to overfitting as, the larger the parameter d, the more fitted-to-the-noise the prediction of the original signal becomes (as seen in the graph above)
- Simulation 2 (an example of underfitting, and overfitting): We see that, using a Fourier basis, we require a high number of Fourier coefficients (parametrized by the number d) to approximate the underlying ground truth (further expansion on this in 'note on interpretation'). As such, increasing the number of Fourier coefficients by increasing the size of the projection matrix X yields to a better approximation of the original ground truth. In opposition, a low number of Fourier coefficients (when d is low) results in a failure of the fitting process, i.e. there is underfitting. However we also see that if we take in too many Fourier coefficients, we also start fitting to the noise (as seen in the graph above)

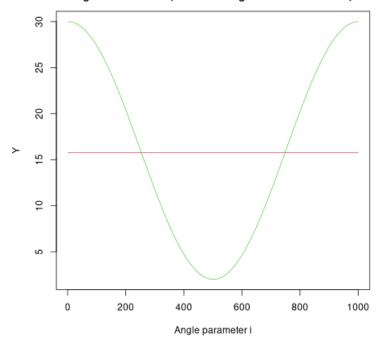
We can visualize this fitting process using the animation library from R.

This following chunk is not run by R studio as it is formatted as a markdown quote chunk. Change it to a .Rmd code chunk to run it

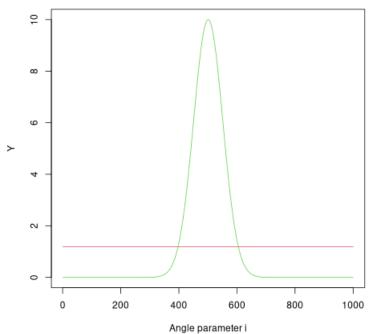
Note: The 3 following graphs are .gif animations, switch to the .HTML file (in your web browser) to visualize them.

```
#install.packages("animation")
library(animation)
plot_ground_truth_vs_pred <- function(X, signal, d, title){</pre>
  pred = compute_retroprojections(X, signal$noisy_signal, as.matrix(d), "")
  plot(signal$truth, type="l", col=3,
         main=title,
         xlab="Angle parameter i",
         ylab="Y")
  lines(pred, type="l", col=2)
}
ani.options(interval=.25); saveGIF({for (i in 0:50){
  plot_ground_truth_vs_pred(
    X, Y1, i, paste("Prediction of ground truth (simulation 1)\nsignal with d = ",
                    i, " (in increasing order from 0 to 50)"))
}})
ani.options(interval=.25); saveGIF({for (i in 0:50){
  plot ground truth vs pred(
    X, Y2, i, paste("Prediction of ground truth (simulation 2)\nsignal with d = ",
                    i, " (in increasing order from 0 to 50)"))
}})
```

Prediction of ground truth (simulation 1) signal with d = 0 (in increasing order from 0 to 50)



Prediction of ground truth (simulation 2) signal with d = 0 (in increasing order from 0 to 50)



Note on interpretation:

The Fourier Transform is a signal decomposition method that extracts frequency and amplitude information from stationary signals while obfuscating frequency-time information.

$$\hat{f}(\omega) = \int_{-\infty}^{+\infty} f(t)e^{-2\pi i\omega t}dt$$

t, time

 ω , a frequency

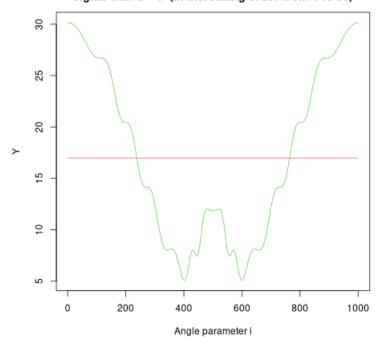
f(t), a signal intensity vs. time function

This obfuscation can be seen in the previous graph but by replacing the frequency-time concept with the angle parameter (which is technically parametrized by two vectors M and C). In this situation, the Fourier Transform part of the regression allows us to either have an accurate approximation of short spikes (simulation 2) or a better resolution at larger scales. We can see this effect below:

$$Y = Y1 + Y2 + \cos(-Y1 + Y2)$$

We that we have a hard time fitting the ground truth using Fourier coefficients due a trade-off between capturing short spikes and wider behavior.

Prediction of ground truth (sim = sim1 + sim2 + cos(-sim1+sim2)) signal with d = 0 (in increasing order from 0 to 50)



This graph could also be considered as displaying the Gibbs phenomenon (https://en.wikipedia.org/wiki/Gibbs phenomenon).

Question 5. Make a function in R which, for a given p, computes the Mallow's Cp criterion for all the models ($d \le p$) and gives the estimator which minimizes the criterion. NB: the behavior would be similar for other models with - log-likelihood and AIC criterion

We compute the best estimator given Mallow's Cp criterion for both simulation 1 and 2 given our previous parameter p=200.

```
compute_mallow_cp <- function(simulation, projection_matrix, d) {</pre>
 ### Computes Mallow's cp for a given d value
 preds = generate_projection_estimators(projection_matrix[,1:(2*d+1)],
                                          simulation$noisy_signal, d,
                                          print_coeffs=F)
 penalization = var(as.vector(preds))*d
  least square = base::norm(simulation$truth-preds, "2")
 base::norm(least_square, "2") + penalization
}
compute mallow cp drange <- function(</pre>
 ### Computes Mallow's Cp over a range of d values
 simulation, projection matrix, p, simulation number
 ) {
 if (p<0) {
    print("FAILED to comply with p >= 0 as, given d <= p, d must be positive.")
    return(NULL)
 f <- function(x){compute_mallow_cp(simulation, projection_matrix, x)}</pre>
 criteria = apply(as.matrix(seq(0, p, 1)),1,f)
 cat("The best Mallow's Cp criterion for simulation", simulation_number,
      "indicates the best estimator d is: d =", which.min(criteria)-1, "\n")
  return(criteria)
}
Y1_mallowcp_criterion = compute_mallow_cp_drange(Y1, X, p,1)
```

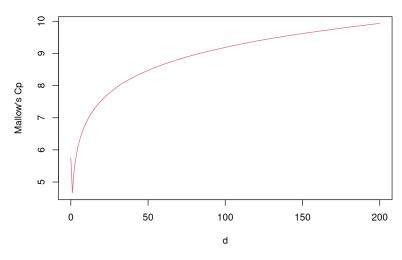
The best Mallow's Cp criterion for simulation 1 indicates the best estimator d is: d = 1

```
Y2_mallowcp_criterion = compute_mallow_cp_drange(Y2, X, p,2)
```

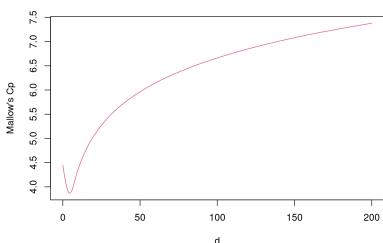
```
## The best Mallow's Cp criterion for simulation 2 indicates the best estimator d is: d = 4
```

We then plot the Mallow's Cp critera obtained over the whole range of p (starting from 0), using the log-scale if need be.

Mallow's Cp for simulation 1, given d<=p

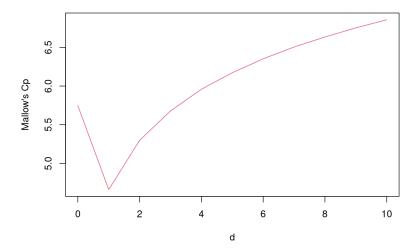


Mallow's Cp for simulation 2, given d<=p

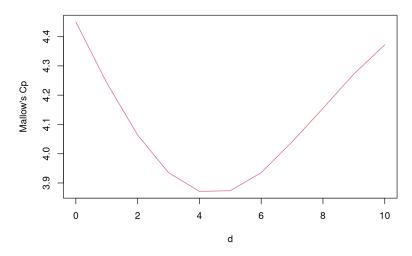


We can also zoom around where the best estimators were found:

Mallow's Cp for simulation 1, given $d = \{0,...,10\}$



Mallow's Cp for simulation 2, given $d = \{0,...,10\}$



Question 6. Let us now fix p and look at all the subspaces V that can be written on the basis up to 2p+1. For instance, we could have a subspace generated by $1,\cos(u),\sin(2u)$. Let us look at the BIC criterion and assume σ^2 is known. Simplify the formulas to show that this minimization problem is solved by taking as non-zeros coordinates the ones for which $|< Y|e_i>|$ is larger than $\sqrt{\ln(n)\sigma^2}$. Implement this method and show the resulting estimator on both previous cases.

Demonstration:

Not found, see notes about ideas.

Computing the estimators:

```
compute best vectors <- function(simulation, projection matrix, known var,
                                  simulation_number) {
   ### Computes whether a given inner product of a signal and a vector e_1 is
   ### larger than a given penalization dependent on the observation size
   ### and a known variance
   f <- function(x){</pre>
     inner_product = abs(simulation$noisy_signal %*% x)
     penalization = sqrt(log(length(simulation$noisy_signal))*known_var)
     inner_product >= penalization
   bests = which(apply(projection_matrix, 2, f))
   cat("The best vectors for the simulation", simulation_number,
       "are the following (1-indexed):", bests, "\n")
   bests
 }
 Y1_best_vectors = compute_best_vectors(Y1, X, var(Y1$truth), 1)
 ## The best vectors for the simulation 1 are the following (1-indexed): 1 2
 Y2_best_vectors = compute_best_vectors(Y2, X, var(Y2\truth), 2)
 ## The best vectors for the simulation 2 are the following (1-indexed): 1 2 4 6 8 10 12
We now have the best vectors, we can compute the estimators:
 compute_retroprojections_2 <- function (</pre>
   projection_matrix, signal, d_sequence, simulation_number
   ) {
   ### Computes for each d value the corresponding estimators and the retro-
   ### projection of the original noisy signal for plotting purposes
   cat("Computation for simulation Y", simulation_number,":\n")
   generate_projection_estimators(projection_matrix[,d_sequence],
```

```
signal$noisy_signal,
                                 paste(d_sequence, collapse=","))
}
predicted_Y1_afterBIC = compute_retroprojections_2(X, Y1, Y1_best_vectors, 1)
```

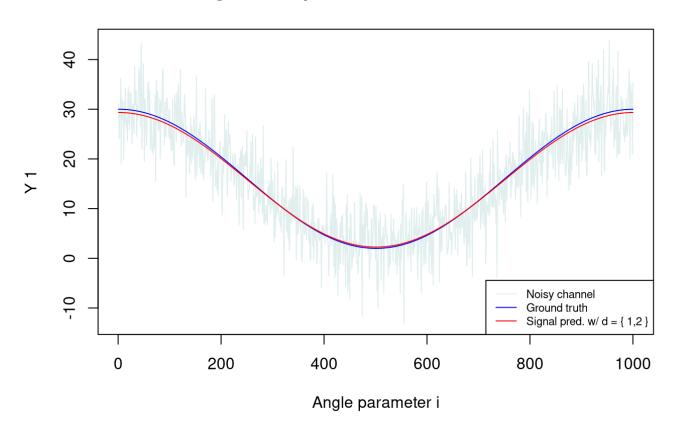
```
## Given a Fourier-basis projection matrix with 1,2 coefficients, the computed estimators are: 499.7605
302.7456
predicted_Y2_afterBIC = compute_retroprojections_2(X, Y2, Y2_best_vectors, 2)
```

Computation for simulation Y 1 :

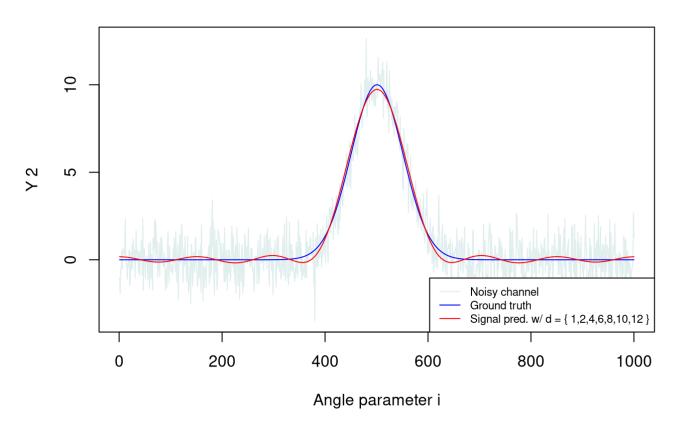
```
## Computation for simulation Y 2 :
## Given a Fourier-basis projection matrix with 1,2,4,6,8,10,12 coefficients, the computed estimators ar
e: 39.97692 -53.31488 46.54344 -36.73931 26.32711 -16.88448 9.601576
```

```
plot_predicted_signals_afterBIC <- function(signal, predictions, d_sequence,</pre>
                                            title, simulation_number,
                                            legend_position) {
 ### Plots the projection using the estimators retrieved with the BIC method
 # Declares legend variables
 colors = c("azure2", "blue", "red")
 names = c("Noisy channel", "Ground truth",
            paste("Signal pred. w/ d = {", paste(d_sequence, collapse=","),
                  "}"))
 # Computes the lines to add to a previously declared plot
 plot(signal$noisy_signal, type="l", col=colors[1],
       main=title,
       xlab="Angle parameter i",
       ylab=paste("Y", simulation_number))
 lines(signal$truth, type="l", col=colors[2])
 lines(as.vector(predictions), type="l", col=colors[3])
 # Adds the legend
 legend(x=legend_position,
           legend=names,
           lty=1,
           col=colors,
         cex=0.7)
}
plot_predicted_signals_afterBIC(Y1, predicted_Y1_afterBIC, Y1_best_vectors,
                                title="Y1 signal with prediction with BIC-estimators",
                                1, "bottomright")
```

Y1 signal with prediction with BIC-estimators



Y1 signal with prediction with BIC-estimators



Notes:

We recall from the class that the BIC is defined as such:

$$egin{aligned} \hat{M} &= \mathop{argmin}_{M \in \mathcal{M}} \left[rac{ln(n)dim(M)}{2} - lg(f_{\hat{ heta}_M}(X))
ight] \ &= \mathop{argmin}_{M \in \mathcal{M}} \left[rac{ln(n)d}{2} - lg(f_{\hat{ heta}_M}(X))
ight] \end{aligned}$$

Using information provided online: 1 (https://datacadamia.com/data_mining/bic), 2 (https://en.wikipedia.org /wiki/Bayesian_information_criterion#Gaussian_special_case), 3 (https://stats.stackexchange.com/questions/339126/in-bayesianinformation-criterion-bic-why-does-having-bigger-n-get-penalized), 4 (https://stats.stackexchange.com/questions/411820/why-is-thebayesian-information-criterion-called-that-way), 5 (https://www.statology.org/bic-in-r/), we can rework the BIC to fit the current example such that, given a fixed n, the number of observations, d the number of parameters, and σ^2 the known variance

$$BIC = rac{RSS + ln(n)d\sigma^2}{n}$$

RSS, the residual sum of squares

Ideas:

- Cauchy Schwartz Inequality: $|< Y|e_i>|\le ||Y||\times ||e_i||$ i.e. $|< Y|e_i>|\le ||Y||$ as $||e_i||=1$ (orthogonal basis) $|< Y|e_i>|=Y^te_i=\sum_{j=1}^n(Y_j*e_{i,j})$