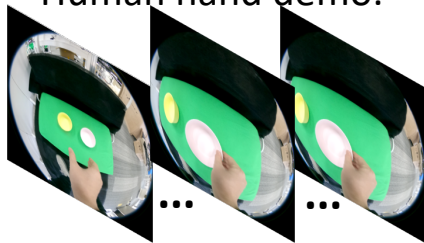




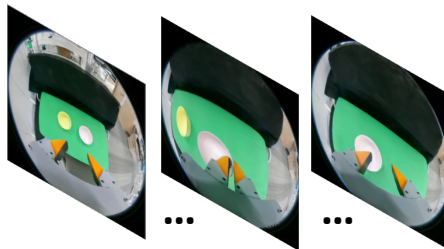
Human hand demo.



Diffusion
Model

Pose
Extraction

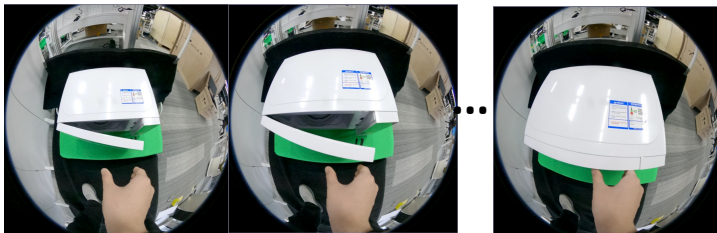
Generated robot demo.



Extracted actions
 Δx Δg $\Delta \theta$

Policy Train

Collected human hand demonstration



Policy model prediction

