

图的数据结构(邻接矩阵)

```
typedef struct GNode *PtrToGNode;
struct GNode{
    int Nv; /* 顶点数 */
    int Ne; /* 边数 */
    VertexType vex[Maxsize]; /* 顶点表*/
    EdgeType G[MaxVertexNum][MaxVertexNum]; /* 邻接矩阵, 边表*/
};
typedef PtrToGNode MGraph; /* 以邻接矩阵存储的图类型 */
```

深度优先遍历 (递归)

深度优先遍历 (迭代)



```
void DFS(MGraph graph, int v) {
   stack<int> st;
   visit(v);
   visited[v];
    st.push(v);
   while(!st.empty()){
       int data, i;
        data = st.top();
        for(i = 0; i < graph->Nv; ++i){
            if(graph->G[data][i] == 1 \&\& visited[vex[i]] == 1){
                visit(vex[i]);
                visited[vex[i]] = true;
                st.push(v);
                break;
            }
        if(i == graph->Nv) st.pop();
```

图的广度优先遍历(迭代)

图的数据结构描述(邻接表)



```
typedef struct ArcNode{ // 边表结点
                     // 该弧所指向的顶点的位置
   int adjvex;
   struct ArcNode *nextArc; // 指向下一条弧的指针
}ArcNode;
typedef struct VNode{ // 顶点表结点
                     // 顶点信息
   int data;
   ArcNode* firstArc;
                     // 指向第一条依附该顶点的弧的指针
}VNode, AdjList[MaxVertexNum];
typedef struct{
  AdjList vertices; // 邻接表
  int vexnum;
                     // 顶点数目
                  // 边数目
  int arcnum;
}ALGraph;
```

深度优先遍历(递归)

```
vector<bool> visited;
void DFS(ALGraph graph, int v) {
    visited[v] = true;
    ArcNode* p;
    visit(graph.vertices[v].data);
    p = G.verties[v].firstArc;
    while(p) {
        if(!visited[p->adjvex])
            DFS(graph, p->adjvex);
        p = p->nextArc;
    }
}
```

深度优先遍历(迭代)



```
void DFSTraverse(Graph graph, int v) { //图的非递归深度优先遍历
   int i, visited[MaxSize], top;
   ArcNode *stack[MaxSize],*p;
   for(i = 0; i < graph.vexnum; i++){ //将所有顶点都添加未访问标志0
       visited[i] = 0;
   printf("%4c", graph.vertices[v].data); //访问顶点v并将访问标志置为1
   visited[v] = 1;
   top = -1; //初始化栈
   p = graph.vertices[v].firstArc; //p指向顶点v的第一个邻接点
   while (top > -1 || p != NULL) {
       while (p!=NULL) {
           if(visited[p->adjvex] == 1){
              p = p->nextarc;
           }else{
               printf("%4c",graph.vertices[p->adjvex].data);
               visited[p->adjvex]=1;
               stack[++top] = p;
               p = graph.vertices[p->adjvex].firstArc;
       }
       if (top > -1) {
           p = stack[top--];
           p = p->nextArc;
       }
```

广度优先遍历



```
void BFS ( ALGraph Graph, Vertex S, void (*Visit) (Vertex) ) {
   int q[MaxVertexNum];
   int front = -1;
    int rear = -1;
   q[++rear] = S;
   while(front < rear)</pre>
       int temp = q[++front];
       Visit(temp);
       Visited[temp] = true;
       PtrToAdjVNode k = (Graph->vertices[temp]).firstArc;
        while(k)
            int e = k->adjvex;
            if(!Visited[e])
               Visited[e]=true;
                q[++rear]=e;
            k=k->nextArc;
       }
   }
}
```

拓扑排序



```
bool TopologicalSort(Graph G) {
   //若G存在拓扑排序,返回true, 否则返回false
   InitStack(S);
   for (int i=0; i < G.vexnum; ++i) {
       if(indegree[i] == 0)
          S.push(i);
       int count = 0;
       while(!IsEmpty(S)) {
          Pop(S,i);
          print[count++] = i;
          for(p = G.vertices[i].firstarc; p; p = p->next){
              //将所有i所指向的顶点的入度减1, 并且将入度减为0的顶点压入栈s
                  v = p->adjvex;
                  if(!(--indegree[v]))
                      S.push(v); // 入度为0 则入栈
          }//for
       }//while
       if(count < G.vexnum) // 拓扑排序失败 有回路
           return false;
       else
          return true;
}
```