## **Vector Space**

## Vector Space

vector space is a set V of column vectors (or row vectors) with properties:

- contains zero vector
- if contains v and w, then contains cv + dw (c and d are constant)

 $\mathbb{R}^n$  represents all column vectors with n component

## **Subspace**

subspace is a vector space in  $\mathbb{R}^n$ 

## 2. Column Space and Nullspace

## Column Space of A

let 
$$A = \begin{bmatrix} 1 & 1 & 2 \\ 2 & 1 & 3 \\ 3 & 1 & 4 \\ 4 & 1 & 5 \end{bmatrix}$$

A is a subspace of  $\mathbb{R}^4$ 

find b for Ax = b have solution x

$$\begin{bmatrix} 1 & 1 & 2 \\ 2 & 1 & 3 \\ 3 & 1 & 4 \\ 4 & 1 & 5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ b_4 \end{bmatrix}$$

a useful approach is choosing solution x first and find corresponding b

x are coefficient in a linear combination of columns of A all their linear combination form a subspace called column space C(A) therefore Ax = b is solvable when b is in C(A)

the solution may not form a subspace when it does not pass through origin

### Null Space of A

the null space N(A) of a matrix A is collection of all solution to Ax = 0

$$\begin{bmatrix} 1 & 1 & 2 \\ 2 & 1 & 3 \\ 3 & 1 & 4 \\ 4 & 1 & 5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

$$A(cx) = cAx = c(0) = 0$$

therefore N(A) = cx is collection of all solution, c is random constant

## 3. Solving Ax = 0

$$A = \begin{bmatrix} 1 & 2 & 2 & 2 \\ 2 & 4 & 6 & 8 \\ 3 & 6 & 8 & 10 \end{bmatrix}$$

apply elimination to A

$$A = \begin{bmatrix} 1 & 2 & 2 & 2 \\ 2 & 4 & 6 & 8 \\ 3 & 6 & 8 & 10 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 2 & 2 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix} = U$$

the rank r of U is the number of pivots it has, which is 2

the column with pivot:  $\begin{bmatrix} \boxed{1} \\ 0 \\ 0 \end{bmatrix}$  and  $\begin{bmatrix} 2 \\ \boxed{1} \\ 0 \end{bmatrix}$  are pivot column

the column with no pivot:  $\begin{bmatrix} 2 \\ 0 \\ 0 \end{bmatrix}$  and  $\begin{bmatrix} 2 \\ 2 \\ 0 \end{bmatrix}$  are free column

the x corresponding to free column:  $x_2$ ,  $x_4$  can be randomly assigned the number of free column is n-r

### **Reduced Row Echelon Form**

in rref, pivot column will have all  $\,0\,$  except the pivot with value  $\,1\,$ 

$$U = \begin{bmatrix} 1 & 2 & 2 & 2 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 2 & 2 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix} = R \ (rref)$$

change column order of  $\it R$  to put pivot columns together

$$R = \begin{bmatrix} 1 & 2 & 2 & 2 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} \boxed{1 & 0} \\ 0 & 1 \end{bmatrix} \begin{bmatrix} \boxed{2 & -2} \\ 0 & 2 \end{bmatrix} = \begin{bmatrix} I & F \\ 0 & 0 \end{bmatrix}$$

where I is identical matrix  $\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$  with r column,  $F = \begin{bmatrix} 2 & -2 \\ 0 & 2 \end{bmatrix}$  with n-r column

$$RN = \begin{bmatrix} I & F \\ 0 & 0 \end{bmatrix} N = 0$$

$$\Rightarrow \boxed{N = c \begin{bmatrix} -F \\ I \end{bmatrix}}$$

N has n-r columns and I is modified to n-r columns

example:

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 6 \\ 2 & 6 & 8 \\ 2 & 8 & 10 \end{bmatrix} \xrightarrow{rref} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$N(A) = c \begin{bmatrix} -F \\ I \end{bmatrix} = c \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix}$$

## 4. Solving Ax = b

use augmented matrix to present Ax = b

$$A = \begin{bmatrix} 1 & 2 & 2 & 2 & b_1 \\ 2 & 4 & 6 & 8 & b_2 \\ 3 & 6 & 8 & 10 & b_3 \end{bmatrix}$$

apply the elimination

$$[A|b] = \begin{bmatrix} 1 & 2 & 2 & 2 & b_1 \\ 2 & 4 & 6 & 8 & b_2 \\ 3 & 6 & 8 & 10 & b_3 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 2 & 2 & b_1 \\ 0 & 0 & 2 & 4 & b_2 - 2b_1 \\ 0 & 0 & 0 & 0 & b_3 - b_2 - b_1 \end{bmatrix}$$

find a particular  $x_p$  to fit the equation

(for convenience, we can assign free variables with 0 and 1 and find pivot) find N(A), written as  $x_n$ 

$$A(x_n + x_p) = Ax_n + Ax_p = \mathbf{0} + \mathbf{b} = \mathbf{b}$$

therefore  $x_n + x_p$  is the complete solution for Ax = b

#### **Number of Rank**

• full column rank  $r = n \Rightarrow$  no free variables

$$R = \begin{bmatrix} I \\ 0 \end{bmatrix}$$

 $x_p$  has either 0 or 1 solution

• full row rank (n > m) $r = m \Rightarrow \text{free variables} = n - r$ 

$$R = \begin{bmatrix} I & F \end{bmatrix}$$

Ax = b is solvable for every b and has infinite solution

• full rank  $r = m = n \Rightarrow A$  is invertible

$$R = I$$

Ax = b is solvable for every b and has 1 solution

## 5. Linearity

## **Linear Independence**

vectors 
$$v_1,v_2,v_3\cdots v_n$$
 are linear independent if and only if  $t_1=t_2=\cdots=t_n$  for  $t_1v_1+t_2v_2+\cdots+t_nv_n=0$ 

### **Dimension**

vectors  $v_1,v_2,v_3\cdots v_n$  can at most span a n dimensional space  $\mathbb{R}^n$  if  $v_1,v_2,v_3\cdots v_n$  are linear independent

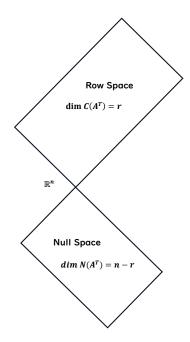
when C(A) is a space:  $\dim C(A) = r$   $\dim N(A) = n - r$ 

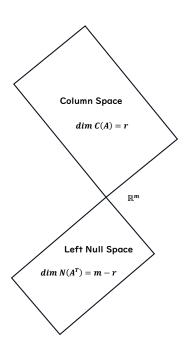
#### **Basis**

basis of a space  $\mathbb{R}^n$  is a sequence of vector  $v_1, v_2, v_3 \cdots v_n$  the basis are independent and span to form the space

## 6. Four Fundamental Subspaces

### $m \times n$ matrix A





# **Left Null Space**

left null space  $N(A^T)$  is collection of y satisfying  $A^Ty=0$   $A^Ty=0 \Rightarrow y^TA=0$ , therefore called left null space

$$EA = R \Rightarrow [A_{m \times n} | I_{m \times n}] \rightarrow [R_{m \times n} | E_{m \times n}] \Rightarrow E$$
 if  $A$  is invertible matrix, then  $y^T = E$