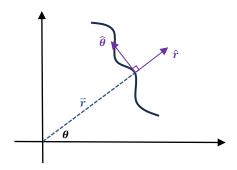
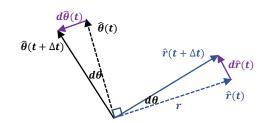
Kinematics Particles

2D Polar Coordinate System



- \hat{r} is unit vector parallel to \vec{r} (radial)
- $\widehat{ heta}$ is unit vector vertical to \overrightarrow{r} (tangential)

Velocity in 2D polar coordinates



$$\begin{split} \vec{r} &= r\hat{r} \\ \vec{v} &= \frac{d\vec{r}}{dt} = \frac{d(r \cdot \hat{r})}{dt} = \frac{dr}{dt}\hat{r} + r\frac{d\hat{r}}{dt} \\ d\hat{r} &\cong |\hat{r}|d\theta\hat{\theta} = d\theta\hat{\theta} \\ \frac{d\hat{r}}{dt} &= \frac{d\theta}{dt}\hat{\theta} \\ \vec{v} &= \dot{r}_{v_r}\hat{r} + \dot{r}_{\theta}\dot{\theta}\hat{\theta} = v_r\hat{r} + v_\theta\hat{\theta} \\ \\ |\vec{v} &= v_r\hat{r} + v_\theta\hat{\theta} \end{split}$$

Acceleration in 2D polar coordinates

$$\begin{split} \overrightarrow{a} &= \frac{d\overrightarrow{v}}{dt} = \frac{d \left(v_r \widehat{r} + v_\theta \widehat{\theta} \right)}{dt} = \frac{d^2 r}{dt^2} \widehat{r} + \frac{dr}{dt} \frac{d\widehat{r}}{dt} + \frac{dr}{dt} \frac{d\theta}{dt} \widehat{\theta} + r \frac{d\theta}{dt} \frac{d\widehat{\theta}}{dt} + r \frac{d^2 \theta}{dt^2} \\ d\widehat{\theta} &\cong \left| \overrightarrow{\theta} \right| d\theta (-\widehat{r}) = -d\theta \widehat{r} \\ \Rightarrow \left[\overrightarrow{a} = \left(\overrightarrow{r} - r \dot{\theta}^2 \right) \widehat{r} + \left(r \ddot{\theta} + 2 \dot{r} \dot{\theta} \right) \widehat{\theta} \right] \end{split}$$

3D Polar Coordinate System

$$\begin{split} \vec{r} &= r\hat{r} + z\hat{z} \\ \vec{v} &= v_r\hat{r} + v_\theta\hat{\theta} + \dot{z}\hat{z} \\ \vec{a} &= \left(\ddot{r} - r\dot{\theta}^2\right)\hat{r} + \left(r\ddot{\theta} + 2\dot{r}\dot{\theta}\right)\hat{\theta} + \ddot{z}\hat{z} \end{split}$$