

# Exploring gauge-fixing conditions with gradient-based optimization\*

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## 1. Motivation

- **Lattice gauge fixing** is necessary to calculate gauge-variant quantities, such as those needed for renormalization, where one connects to perturbative schemes by minimizing an **gauge-fixing functional** (e.g. Landau gauge).
- **Maximal-tree gauges** are useful to deform the path integral contour for improving the signal-to-noise ratio of observables like Wilson loops [1].
- Systematic parameterization and **exploration of gauge-fixing schemes** provides a useful tool in these contexts.

## 2. Approach

- We define a **general parameterization of a gauge-fixing functional**. Minimizing over the gauge orbit fixes to a gauge defined by the parameters.
- The parameterization includes Landau gauge, Coulomb gauge, and maximal tree gauges, as well as more general gauges.
- We introduce a **gradient-based algorithm** that allows us to optimize parameters defining the gauge-fixing scheme to minimize an arbitrary loss function.

## 3. Algorithm

$$\text{General gauge-fixing functional} \quad E \propto - \sum_{x,\mu} \text{Tr}(p_\mu(x) U_\mu^g(x)) \quad \begin{cases} p_i(x) = 1 \text{ (Coulomb gauge)} \\ p_\mu(x) = 1 \text{ (Landau gauge)} \\ p_\mu(x) = k_\mu(x) \in \{0,1\} \text{ (Max. trees)} \end{cases}$$

Gauge-fixed configurations,  $U_\mu^g(x)$ , are obtained by minimizing the functional. Given some objective function,  $l[U_\mu^g(x)]$ , the **adjoint-state method** [2] can be used to efficiently compute the gradient  $dl/dp_\mu(x)$  for optimizing the choice of  $p_\mu(x)$ .

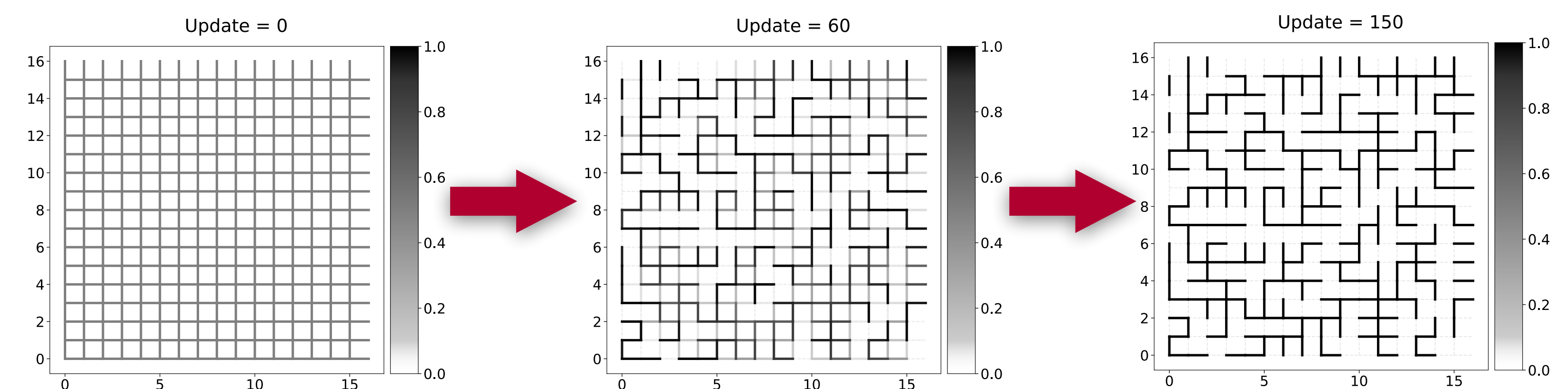
To restrict exploration to only **maximal tree gauges**, one must restrict  $p_\mu(x)$ .

Gradient-based optimization requires a smooth parameterization, thus define  $p_\mu(x)$  to be a **“soft” tree to smoothly interpolate between maximal trees**:

$$p_\mu(x) = \text{soft tree} = \text{weighted sum of all maximal trees}$$

This can be done by using **Kirchhoff's matrix-tree theorem** [3]. The final maximal tree can be obtained by using **Kruskal's algorithm**.

## 4. Results



- Generate a random maximal tree specified by  $k_\mu^P(x) \in \{0,1\}$  and obtain the corresponding  $U_\mu^P(x)$
- Create a soft tree  $p_\mu(x)$  using the matrix-tree theorem
- Gauge fix with  $p_\mu(x)$  and minimize to obtain  $U_\mu^g(x)$
- Minimize the loss function

$$l \propto \sum_{x,\mu} (U_\mu^P(x) - U_\mu^g(x))^2$$

