# **LS-Reader Tutorial**

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# Introduction

This document describes the application functions interface of LS-Reader using Python.

The LS-Reader is designed to read LS-DYNA results and it supports C, C++ and Python languages. It supports both Windows(vs2010, vs2015, vs2017, vs2019) and Linux(GCC>=4.1.2). Because of the simplicity of the LS-Reader, using the libraries is very convenie

# **Python**

# **D3plotReader**

```
API Functions (Recommended)
class D3plotReader():
    def __init__(self, path):
         pass
    Purpose: Constructor.
    ❖ Input: path: d3plot name.
    ❖ Return: D3plotReader object.
      Example: dr = D3plotReader("d3plot/file/path")
    def get_data(self, type, param):
        pass
    ❖ Purpose: Extract data.
    ❖ Input: type: type - enum the data variables' name in d3plot.
            param:
                      structure of description which is the advance setting for
               getting special data in d3plot.
    * Return: data.
      Example:
            dr = D3plotReader("d3plot/file/path")
            p = D3P_Parameter()
            p.ist = 11
            p.ipt = 0
            shell_stress = dr.get_data(DataType.D3P_SHELL_STRESS, p)
      Or
```

```
dr = D3plotReader("d3plot/file/path")
shell_stress = dr.get_data(
DataType.D3P_SHELL_STRESS, ist=11, ipt=0
)
```

# **API Functions (Deprecated)** class D3plotReader(): def init (self, path): pass ❖ Purpose: Constructor. ❖ Input: path: d3plot name. ❖ Return: D3plotReader object. Example:dr = D3plotReader("d3plot/file/path") def GetDataInt(self, type, param): pass Deprecated. Use the get\_data(...) instead. ❖ Purpose: Get an integer value. ❖ Input: type - enum the data variables' name in d3plot. Param - structure of description which is the advance setting for getting special data in d3plot. ❖ Return: int def GetDataFloat(self, type, param): pass Deprecated. Use the get\_data(...) instead. ❖ Purpose: Get a float value.

param - structure of description which is the advance setting for getting

❖ Input: type - enum the data variables' name in d3plot.

special data in d3plot.

❖ Return: float.

```
def GetDataString(self, type, param):
    pass
  Deprecated. Use the get_data(...) instead.
❖ Purpose: Get a string value.
❖ Input: type - enum the data variables' name in d3plot.
         param - structure of description which is the advance setting for getting
  special data in d3plot.
* Return: string.
def GetDataIntArray(self, type, param):
    pass
  Deprecated. Use the get_data(...) instead.
❖ Purpose: Get a int array.
❖ Input: type - enum the data variables' name in d3plot.
         param - structure of description which is the advance setting for getting
  special data in d3plot.
❖ Return: int array.
def GetDataFloatArray(self, type, param):
    pass
  Deprecated. Use the get_data(...) instead.
❖ Purpose: Get a float array.
```

❖ Input: type - enum the data variables' name in d3plot.

param - structure of description which is the advance setting for getting special data in d3plot.

❖ Return: float array.

# def GetDataVectorArray(self, type, param):

pass

Deprecated. Use the get\_data(...) instead.

- ❖ Purpose: Get a vector array.
- ❖ Input: type enum the data variables' name in d3plot.

param - structure of description which is the advance setting for getting special data in d3plot.

\* Return: vector array.

## def GetDataTensorArray(self, type, param):

pass

Deprecated. Use the get\_data(...) instead.

- ❖ Purpose: Get a tensor array.
- ❖ Input: type enum the data variables' name in d3plot.

param - structure of description which is the advance setting for getting special data in d3plot.

❖ Return: tensor array.

#### def GetDataSolidArray(self):

pass

Deprecated. Use the get\_data(...) instead.

- ❖ Purpose: Get solid elements array.
- ❖ Return: solid elements array.

# def GetDataTshellArray(self):

#### pass

Deprecated. Use the get\_data(...) instead.

- ❖ Purpose: Get tshell elements array.
- ❖ Return: tshell elements array.

# def GetDataBeamArray(self):

#### pass

Deprecated. Use the get\_data(...) instead.

- ❖ Purpose: Get beam elements array.
- ❖ Return: beam elements array.

# def GetDataShellArray(self):

#### pass

Deprecated. Use the get\_data(...) instead.

- ❖ Purpose: Get shell elements array.
- ❖ Return: shell elements array.

# def GetDataSphArray(self):

#### pass

Deprecated. Use the get\_data(...) instead.

- ❖ Purpose: Get sph elements array.
- ❖ Return: sph elements array.

#### **D3P** Parameter

parameter to call D3plotReader::get\_data\*, only specific those member variables you are interested, otherwise, ignore this.

```
class D3P_Parameter:
    def __init__(self):
        self.ist = -1
        self.ipt = -1
        self.ipart = -1
        self.ipart_user = -1
        self.i_rigid_wall = -1
        self.ides = -1
        self.ihv = -1
        self.index multisolver = -1
        self.id_var_multisolver = -1
        self.iuser = -1
        self.var name = ""
1.
      ist: Specify the state number, starting from 0, as follows:
      shell_thickness = dr.get_data(DataType.D3P_SHELL_THICKNESS, ist=11)
      0r
      p = D3P_Parameter()
      p.ist = 11
      shell_thickness = dr.get_data(DataType.D3P_SHELL_THICKNESS, p)
2.
      ipt: Specify the integration point, ranging in [0, MAXINT), as follows:
      shell_stress = dr.get_data(DataType.D3P_SHELL_STRESS, ist=11, ipt=0)
      0r
      p = D3P_Parameter()
```

```
p.ist = 11
      p.ipt = 0
      shell_stress = dr.get_data(DataType.D3P_SHELL_STRESS, p)
3.
      ipart: Specify the index of part, starting from 0, as follows:
      part name = dr.get data(DataType.D3P PART NAME, ipart=0)
      0r
      p = D3P_Parameter()
      p.ipart = 0
      part_name = dr.get_data(DataType.D3P_PART_NAME, p)
4.
      ipart_user: Specify the user id of part, as follows:
      num_shells = dr.get_data(DataType.D3P_NUM_SHELL, ipart_user=3)
5.
      i_rigid_wall: Specify the index of rigid wall, starting from 0, as follows:
      r_wall_f = dr.get_data(
             DataType.D3P_RIGID_WALL_FORCE, ist=11, i_rigid_wall=0
      )
      0r
      p = D3P_Parameter()
      p.ist = 11
      p.i_rigid_wall = 0
      r wall f = dr.get data(DataType.D3P RIGID WALL FORCE, p)
6.
      ides: Specify the index of the des data, starting from 0, as follows:
      num_des = dr.get_data(DataType.D3P_NUM_DES_PART_IN_GEOM, ides=0)
      0r
      p = D3P_Parameter()
      p.ides = 0
      num_des = dr.get_data(DataType.D3P_NUM_DES_PART_IN_GEOM, p)
7.
      ihv: Specify the index of history variables, starting from 0, as follows:
```

1

8. **index\_multisolver**: Specify the index of the multisolver domain, start from 0 and default is 0 also:

```
ms_id = dr.get_data(DataType.D3P_MS_DOMAIN_ID, index_multisolver=0)
Or

p = D3P_Parameter()
p.index_multisolver = 0

ms_id = dr.get_data(DataType.D3P_MS_DOMAIN_ID, p)
```

9. **id\_var\_multisolver**: Specify the index of the multisolver var, start from 0 and default is 0 also:

```
ms_varn = dr.get_data(DataType.D3P_MS_VAR_NAME, id_var_multisolver=0)
Or

p = D3P_Parameter()
p.id_var_multisolver = 0

ms_varn = dr.get_data(DataType.D3P_MS_VAR_NAME, p)
```

10. **iuser:** Specify the index of the user id:

```
internal_id = dr.get_data(DataType.D3P_SHELL_INTERNAL_ID, iuser=354)
```

11. **var\_name**: Specify name of output variables, currently used by DES and CPM data, default is empty

```
cpm_geodt = dr.get_data(DataType.D3P_CPM_GEOM_DATA, var_name='cpm1')
```

```
0r
p = D3P_Parameter()
p.var_name = 'cpm1'
cpm_geodt = dr.get_data(DataType.D3P_CPM_GEOM_DATA, p)
```

# **DataType**

```
class D3P_Vector():
    def x(self):
        pass
    def y(self):
        pass
    def z(self):
        pass
class D3P_VectorDouble():
    def x(self):
        pass
    def y(self):
        pass
    def z(self):
        pass
class D3P_Tensor():
    def x(self):
        pass
    def y(self):
        pass
    def z(self):
        pass
    def xy(self):
        pass
```

```
def yz(self):
        pass
    def zx(self):
        pass
class D3P_Solid():
    # return the value of nodal index(start from 0) plus one
    def node(self, index):
        pass
    def mat(self):
        pass
class D3P_Tshell():
    # return the value of nodal index(start from 0) plus one
    def node(self, index):
        pass
    def mat(self):
        pass
class D3P_Beam():
    # return the value of nodal index(start from 0) plus one
    def node(self, index):
        pass
    def mat(self):
        pass
class D3P_Shell():
```

```
\# return the value of nodal index(start from 0) plus one
    def node(self, index):
        pass
    def mat(self):
        pass
class D3P_Sph():
    def id(self):
        pass
    def mat(self):
        pass
class D3P_Var():
    def type(self):
        pass
    def name(self):
        pass
class D3P_Des():
    def id(self):
        pass
    def mat(self):
        pass
    def radius(self):
        pass
    def mass(self):
        pass
```

# def inertia(self):

# pass

name	conversion	length	paramete rs
D3P_NUM_STATES	int	1	ignore
D3P_TIMES	float	D3P_NUM_STATES	ignore
D3P_TITLE	Char		ignore
Global			
D3P_GLOBAL_KINETIC_ENERGY	float	1	ist
D3P_GLOBAL_INTERNAL_ENERGY	float	1	ist
D3P_GLOBAL_TOTAL_ENERGY	float	1	ist
D3P_GLOBAL_VELOCITY	D3P_Vector	1	ist
Part			
D3P_NUM_PARTS	int	1	ignore
D3P_PART_IDS	int	D3P_NUM_PARTS	ignore
D3P_PART_NAME	char	80	ipart
D3P_PART_INTERNAL_ENERGY	float	1	ist, ipart
D3P_PART_KINETIC_ENERGY	float	1	ist, ipart
D3P_PART_VELOCITY	D3P_Vector	1	ist, ipart
D3P_PART_MASS	float	1	ist, ipart
D3P_PART_HOURGLASS	float	1	ist, ipart
D3P_PART_INTERNAL_ID	int	1	iuser
RIGID WALL			
D3P_NUM_RIGID_WALL	int	1	ignore
D3P_RIGID_WALL_FORCE	float	1	ist, i_rigid_wal l
D3P_RIGID_WALL_POSITION	D3P_Vector	1	ist, i_rigid_wal l
NODE			
D3P_NUM_NODES	int	1	ignore
D3P_NODE_INITIAL_COORDINATES	D3P_Vector	D3P_NUM_NODES	ignore

D3P_NODE_IDS	int	D3P_NUM_NODES	ignore
D3P_NODE_TEMPERATURE	float	D3P_NUM_NODES	ist
D3P_NODE_COORDINATES	D3P_Vector	D3P_NUM_NODES	ist
D3P_NODE_VELOCITIES	D3P_Vector	D3P_NUM_NODES	ist
D3P_NODE_ACCELERATIONS	D3P_Vector	D3P_NUM_NODES	ist
D3P_NODE_COORDINATES_DOUBLE	D3P_VectorDoub	D3P_NUM_NODES	ist
D3P_NODE_VELOCITIES_DOUBLE	D3P_VectorDoub le	D3P_NUM_NODES	ist
D3P_NODE_ACCELERATIONS_DOUBLE	D3P_VectorDoub le	D3P_NUM_NODES	ist
D3P_NODE_INTERNAL_ID	int	1	iuser
SOLID			
D3P_NUM_SOLID	int	1	ignore
D3P_SOLID_MAXINT	int	1	ignore
D3P_SOLID_CONNECTIVITY_MAT	D3P_Solid	D3P_NUM_SOLID	ignore
D3P_SOLID_IDS	int	D3P_NUM_SOLID	ignore
D3P_SOLID_STRESS	D3P_Tensor	D3P_NUM_SOLID	ist, ipt if necessary
D3P_SOLID_EFFECTIVE_PLASTIC_STRA IN	float	D3P_NUM_SOLID	ist, ipt if necessary
D3P_SOLID_STRAIN	D3P_Tensor	D3P_NUM_SOLID	ist, ipt if necessary
D3P_SOLID_HISTORY_VAR	float	D3P_NUM_SOLID	ist, ipt, ihv
D3P_SOLID_INTERNAL_ID	int	1	iuser
TSHELL			
D3P_NUM_TSHELL	int	1	ignore
D3P_TSHELL_MAXINT	int	1	ignore
D3P_TSHELL_CONNECTIVITY_MAT	D3P_Tshe11	D3P_NUM_TSHELL	ignore

D3P_TSHELL_IDS	int	D3P_NUM_TSHELL	ignore
D3P_TSHELL_STRESS	D3P_Tensor	D3P_NUM_TSHELL	ist, ipt
D3P_TSHELL_EFFECTIVE_PLASTIC_STR AIN	float	D3P_NUM_TSHELL	ist, ipt
D3P_TSHELL_STRAIN	D3P_Tensor	D3P_NUM_TSHELL	ist, ipt
D3P_TSHELL_HISTORY_VAR	float	D3P_NUM_TSHELL	ist, ipt, ihv
D3P_TSHELL_INTERNAL_ID	int	1	iuser
BEAM			
D3P_NUM_BEAM	int	1	ignore
D3P_BEAM_MAXINT	int	1	ignore
D3P_BEAM_CONNECTIVITY_THIRD_MAT	D3P_Beam	D3P_NUM_BEAM	ignore
D3P_BEAM_IDS	int	D3P_NUM_BEAM	ignore
D3P_BEAM_AXIAL_FORCE	float	D3P_NUM_BEAM	ist
D3P_BEAM_S_SHEAR_RESULTANT	float	D3P_NUM_BEAM	ist
D3P_BEAM_T_SHEAR_RESULTANT	float	D3P_NUM_BEAM	ist
D3P_BEAM_S_BENDING_MOMENT	float	D3P_NUM_BEAM	ist
D3P_BEAM_T_BENDING_MOMENT	float	D3P_NUM_BEAM	ist
D3P_BEAM_TORSIONAL_RESULTANT	float	D3P_NUM_BEAM	ist
D3P_BEAM_RS_SHEAR_STRESS	float	D3P_NUM_BEAM	ist, ipt
D3P_BEAM_TR_SHEAR_STRESS	float	D3P_NUM_BEAM	ist, ipt
D3P_BEAM_AXIAL_STRESS	float	D3P_NUM_BEAM	ist, ipt
D3P_BEAM_AXIAL_PLASTIC_STRAIN	float	D3P_NUM_BEAM	ist, ipt
D3P_BEAM_AXIAL_STRAIN	float	D3P_NUM_BEAM	ist, ipt
D3P_BEAM_HISTORY_VAR	float	D3P_NUM_BEAM	ist, ipt, ihv
D3P_BEAM_INTERNAL_ID	int	1	iuser
SHELL			

D3P_NUM_SHELL	int	1	ignore
D3P_SHELL_MAXINT	int	1	ignore
D3P_SHELL_CONNECTIVITY_MAT	D3P_Shell	D3P_NUM_SHELL	ignore
D3P_SHELL_IDS	int	D3P_NUM_SHELL	ignore
D3P_SHELL_STRESS	D3P_Tensor	D3P_NUM_SHELL	ist, ipt
D3P_SHELL_EFFECTIVE_PLASTIC_STRAIN	float	D3P_NUM_SHELL	ist, ipt
D3P_SHELL_STRAIN	D3P_Tensor	D3P_NUM_SHELL	ist, ipt
D3P_SHELL_HISTORY_VAR	float	D3P_NUM_SHELL	ist, ipt, ihv
D3P_SHELL_MX	float	D3P_NUM_SHELL	ist
D3P_SHELL_MY	float	D3P_NUM_SHELL	ist
D3P_SHELL_MXY	float	D3P_NUM_SHELL	ist
D3P_SHELL_QX	float	D3P_NUM_SHELL	ist
D3P_SHELL_QY	float	D3P_NUM_SHELL	ist
D3P_SHELL_NX	float	D3P_NUM_SHELL	ist
D3P_SHELL_NY	float	D3P_NUM_SHELL	ist
D3P_SHELL_NXY	float	D3P_NUM_SHELL	ist
D3P_SHELL_INTERNAL_ID	int	1	iuser
DELETION			
D3P_HAS_DELETION	bool	1	ist
D3P_SOLID_DELETION	float	D3P_NUM_SOLID	ist
D3P_TSHELL_DELETION	float	D3P_NUM_TSHELL	ist
D3P_SHELL_DELETION	float	D3P_NUM_SHELL	ist
D3P_BEAM_DELETION	float	D3P_NUM_BEAM	ist
SPH			
D3P_NUM_SPH	int	1	ignore
D3P_SPH_NODE_MAT	D3P_Sph	D3P_NUM_SPH	ignore

D3P_SPH_RADIUS	float	D3P_NUM_SPH	ist
D3P_SPH_PRESSURE	float	D3P_NUM_SPH	ist
D3P_SPH_STRESS	D3P_Tensor	D3P_NUM_SPH	ist
D3P_SPH_PLASTIC_STRAIN	float	D3P_NUM_SPH	ist
D3P_SPH_DENSITY	float	D3P_NUM_SPH	ist
D3P_SPH_INTERNAL_ENERGY	float	D3P_NUM_SPH	ist
D3P_SPH_NUMBER_OF_PARTICLE_NEIGH BORS	int	D3P_NUM_SPH	ist
D3P_SPH_STRAIN	D3P_Tensor	D3P_NUM_SPH	ist
D3P_SPH_MASS	float	D3P_NUM_SPH	ist
D3P_SPH_INTERNAL_ID	int	1	iuser
DES			
D3P_HAS_DES_DATA	bool	1	ignore
D3P_NUM_DES_DATA	int	1	ignore
D3P_NUM_DES_PART_IN_GEOM	int	1	ides if necessary
D3P_NUM_DES_ELEM_IN_GEOM	int	1	ides if necessary
D3P_NUM_DES_PART_IN_STATE	int	1	ides if necessary
D3P_NUM_DES_ELEM_IN_STATE	int	1	ides if necessary
D3P_NUM_DES_PART_VAR_IN_GEOM	int	1	ides if necessary
D3P_DES_PART_VAR_LIST_IN_GEOM	D3P_Var	D3P_NUM_DES_PART_VA R_IN_GEOM	ides if necessary
D3P_NUM_DES_ELEM_VAR_IN_GEOM	int	1	ides if necessary
D3P_DES_ELEM_VAR_LIST_IN_GEOM	D3P_Var	D3P_NUM_DES_ELEM_VA R_IN_GEOM	ides if necessary
D3P_NUM_DES_PART_VAR_IN_STATE	int	1	ides if necessary

D3P_DES_PART_VAR_LIST_IN_STATE	D3P_Var	D3P_NUM_DES_PART_VA	ides if
		R_IN_STATE	necessary
D3P_NUM_DES_ELEM_VAR_IN_STATE	int	1	ides if
			necessary
D3P_DES_ELEM_VAR_LIST_IN_STATE	D3P_Var	D3P_NUM_DES_ELEM_VA R IN STATE	ides if necessary
D3P_DES_NODAL_MAT_RADIUS_MASS_IN ERTIA	D3P_Des	D3P_NUM_DES_ELEM_IN GEOM	ides if necessary
	/01 /		
D3P_DES_DATA_IN_STATE	int/float/vect or/tensordep	D3P_NUM_DES_ELEM_IN STATE	var_name, ist, ides
	ends		if
			necessary
CPM			
D3P_HAS_CPM_DATA	bool	1	ignore
D3P_CPM_NUM_AIRBAGS	int	1	ignore
D3P_CPM_NUM_PARTICLES	int	1	ignore
D3P_CPM_NUM_GEOM_VAR	int	1	ignore
D3P_CPM_GEOM_VAR_LIST	D3P_Var	D3P_CPM_NUM_GEOM_VA	ignore
		R	
D3P_CPM_GEOM_DATA	D3P_Var	D3P_CPM_NUM_GEOM_VA	ignore
		R	
D3P_CPM_NUM_STATE_VAR	int	1	ignore
D3P_CPM_STATE_VAR_LIST	D3P_Var	D3P_CPM_NUM_STATE_V	ignore
		AR	
D3P_CPM_STATE_DATA	int/floatde	D3P_CPM_NUM_PARTICL	var_name,
	pends	ES	ist
D3P_CPM_NUM_STATE_GEOM_VAR	int	1	ignore
D3P_CPM_STATE_GEOM_VAR_LIST	D3P_Var	D3P_CPM_NUM_STATE_G EOM_VAR	ignore
D3P_CPM_STATE_GEOM_DATA	int/floatde	D3P_CPM_NUM_AIRBAGS	var_name,
	pends		ist
Multisolver			

D3P_HAS_MS_DATA	bool	1	ignore
D3P_MS_NUM_DOMAINS	int	1	ignore
D3P_MS_DOMAIN_ID	int	1	index_multi solver
D3P_MS_DOMAIN_NAME	char	80	index_multi solver
D3P_MS_DOMAIN_VAR_NUM	int	1	index_multi solver
D3P_MS_DOMAIN_VARS_LIST	int	D3P_MS_DOMAIN_VAR_N UM	index_multi solver
D3P_MS_VAR_NAME	char	80	id_var_mult isolver
D3P_MS_VAR_IS_VECTOR	bool	1	id_var_mult isolver
D3P_MS_VAR_IS_SCALAR	bool	1	id_var_mult isolver
D3P_MS_VAR_IS_TENSOR	bool	1	id_var_mult isolver
D3P_MS_DOMAIN_VAR_LENGTH	int	1	ist, index_multi solver
D3P_MS_DOMAIN_IS_SOLID	bool	1	ist, index_multi solver
D3P_MS_DOMAIN_IS_SHELL	bool	1	ist, index_multi solver
D3P_MS_DOMAIN_IS_BEAM	bool	1	ist, index_multi solver
D3P_MS_DOMAIN_ELEM_NUM_IN_STATE	int	1	ist, index_multi solver
D3P_MS_SOLID_CONNECTIVITY_MAT_IN _STATE	D3P_Solid	D3P_MS_DOMAIN_ELEM_ NUM_IN_STATE	ist, index_multi solver

D3P_MS_SHELL_CONNECTIVITY_MAT_IN _STATE	D3P_She11	D3P_MS_DOMAIN_ELEM_ NUM_IN_STATE	ist, index_multi solver
D3P_MS_BEAM_CONNECTIVITY_MAT_IN_ STATE	D3P_Beam	D3P_MS_DOMAIN_ELEM_ NUM_IN_STATE	ist, index_multi solver
D3P_MS_DOMAIN_NODE_NUM_IN_STATE	int	1	ist, index_multi solver
D3P_MS_DOMAIN_COORD_IN_STATE	D3P_Vector	D3P_MS_DOMAIN_NODE_ NUM_IN_STATE	ist, index_multi solver
D3P_MS_DOMAIN_DATA_IN_STATE	float or D3P_Vector or D3P_Tensor	D3P_MS_DOMAIN_VAR_L ENGTH	ist, index_multi solver,id_v ar_multisol ver
D3P_MS_DOMAIN_DATA_IS_ON_STRUCTU RE_ELEMENT	bool	1	index_multi solver
D3P_MS_DOMAIN_DATA_IS_ON_MS_NODE	bool	1	index_multi solver
D3P_MS_DOMAIN_DATA_IS_ON_MS_ELEM ENT,	bool	1	index_multi solver
D3P_MS_DOMAIN_IS_FOLLOW_SURFACE_ METHOD	bool	1	index_multi solver
D3P_MS_DOMAIN_NODE_NUM_ONSURFACE _IN_STATE	int	1	ist, index_multi solver
D3P_MS_DOMAIN_SURFACE_IDS_IN_STA TE	int	D3P_MS_DOMAIN_NODE_ NUM_ONSURFACE_IN_ST ATE	ist, index_multi solver

#### How to use

#### Sample1.py

Purpose: obtain resultant displacement for all the nodes and find maximum value.

3D scatterplot(x=shell\_nodes\_x, y=shell\_nodes\_y, z=shell\_nodes\_z, c=resultant displacement of shell nodes)

ist: last.

```
from lsreader import D3plotReader, DataType as dt
import os
import matplotlib.pyplot as plt
from mpl_toolkits import mplot3d
from math import pow
d3plot = os.path.join(os.getcwd(), 'd3plot')
dr = D3plotReader(d3plot)
num_states = dr.get_data(dt.D3P_NUM_STATES)
nodes_init_coor = dr.get_data(
   dt.D3P NODE INITIAL COORDINATES, ist=num states-1
)
nodes_coor = dr.get_data(dt.D3P_NODE_COORDINATES, ist=num_states-1)
# obtain resultant displacement for all nodes and find maximum
nodes_res_disp = []
for i in range(nodes_coor.__len__()):
   disp_x = nodes_coor[i].x() - nodes_init_coor[i].x()
   disp_y = nodes_coor[i].y() - nodes_init_coor[i].y()
   disp_z = nodes_coor[i].z() - nodes_init_coor[i].z()
```

```
tmp = pow(disp_x, 2) + pow(disp_y, 2) + pow(disp_z, 2)
   nodes_res_disp.append(pow(tmp, 0.5))
print(
.....
Maximum resultant displacement of nodes is: {0}, index is: {1}
""".format(
   max(nodes_res_disp), nodes_res_disp.index(max(nodes_res_disp))
    )
)
# nodes coordinates of shell elements when ist=last
shells = dr.get_data(dt.D3P_SHELL_CONNECTIVITY_MAT)
nodes_shell = []
for shell in shells:
   nodes_shell.append(shell.node(0))
   nodes_shell.append(shell.node(1))
   nodes_shell.append(shell.node(2))
   nodes_shell.append(shell.node(3))
nodes_shell = list(set(nodes_shell))
nodes_shell.sort()
nodes_x, nodes_y, nodes_z, res = [], [], [], []
for node_shell in nodes_shell:
   nodes_x.append(nodes_coor[node_shell-1].x())
   nodes_y.append(nodes_coor[node_shell-1].y())
   nodes z.append(nodes coor[node shell-1].z())
    res.append(nodes_res_disp[node_shell-1])
```

```
# plotting
fig = plt.figure()
ax = fig.add_subplot(1, 1, 1, projection='3d')
scat = ax.scatter3D(
    nodes_x, nodes_y, nodes_z, c=res, s=15,
)
fig.colorbar(scat, label='Resultant Displacement')
ax.set_zlim3d(-50, 50)
plt.show()
```

#### Sample2.py

Purpose: extract Variable data for Multisolver.

State: 2

```
import lsreader
from lsreader import D3plotReader
from lsreader import DataType as dt
from lsreader import D3P_Parameter as dp
import os
d3plot = os.path.join(os.getcwd(), 'd3plot')
dr = D3plotReader(d3plot)
has_ms_data = dr.get_data(dt.D3P_HAS_MS_DATA)
if not has_ms_data:
   print("No Multisolver Data")
num ms datasets = dr.get data(dt.D3P MS NUM DOMAINS)
for dataset in range(num_ms_datasets):
    domain_var_ids = dr.get_data(dt.D3P_MS_DOMAIN_VARS_LIST, index_multisolver=da
taset)
   for var in range(domain_var_ids.__len__()):
        sizevar = dr.get data(dt.D3P MS DOMAIN VAR LENGTH, index multisolver=data
set, ist=2)
        is scalar = dr.get data(dt.D3P MS VAR IS SCALAR, id var multisolver=domai
n_var_ids[var])
        is_vector = dr.get_data(dt.D3P_MS_VAR_IS_VECTOR, id_var_multisolver=domai
n_var_ids[var])
```

```
is_tensor = dr.get_data(dt.D3P_MS_VAR_IS_TENSOR, id_var_multisolver=domai
n_var_ids[var])
        p = dp()
        p.ist=2
        p.index_multisolver = dataset
        p.id_var_multisolver = domain_var_ids[var]
        if is scalar:
            svalue = dr.get_data(dt.D3P_MS_DOMAIN_DATA_IN_STATE, p)
            print("Value type: scalar, value[0]={}".format(svalue[0]))
        if is_vector:
            vvalue = dr.get_data(dt.D3P_MS_DOMAIN_DATA_IN_STATE, p)
            print(
                   "Value type: vector, value[0].X()={}"
                   .format(vvalue[0].x())
            )
        if is_tensor:
            tvalue = dr.get_data(dt.D3P_MS_DOMAIN_DATA_IN_STATE, p)
            print(
                   "Value type: tensor, value[0].X()={}"
                   .format(tvalue[0].x())
            )
```

### Sample3.py

Purpose: extract stress of shells by part.

State: 2

Ipt: 0

Part User Id: 3

```
from lsreader import D3plotReader, DataType as dt

d3plot = os.path.join(os.getcwd(), 'd3plot')

dr = D3plotReader(d3plot)

num_shells = dr.get_data(dt.D3P_NUM_SHELL)

shell_stress = dr.get_data(
    dt.D3P_SHELL_STRESS, ist=1, ipt=0, ipart_user=3
)

# do something with shell_stress
```

#### BinoutReader

#### **API Functions**

```
class BinoutReader():
    def __init__(self, path):
         pass
    ❖ Purpose: Constructor.
    ❖ Input: path: binout name.
    ❖ Return: BinoutReader object.
      Example: br = BinoutReader("binout/file/path")
    @staticmethod
    def is_valid(path):
         pass
    Purpose: Check if the path is correct
    ❖ Input: path: binout name(full path).
    * Return: True or False.
    @staticmethod
    def write(path, x_array, y_array):
         pass
    ❖ Purpose: Output the x_array and y_array to path.
    ❖ Input: path: binout name(full path).
            x_array: The array of X direction.
            y_array: The array of Y direction.
    * Return: True.
```

```
def get_branch(self):
    pass
❖ Purpose: Get branches.
❖ Input: void.
* Return: The array of branches.
def set_branch(self, branch):
    pass
❖ Purpose: Set current branch.
❖ Input: branch: The name of the branch to set.
❖ Return: True.
def set_id(self, id, master):
    pass
❖ Purpose: Set current id.
❖ Input: id: The id to set. It can be string or integer.
        master: choose master or slave. It can be ignored.
* Return: True.
def get_id(self):
    pass
❖ Purpose: Get ids.
❖ Input: void.
❖ Return: The array of ids.
```

```
def set_component(component):
    pass
❖ Purpose: Set current component.
❖ Input: branch: The name of the component to set.
* Return: True.
def get_component():
    pass
Purpose: Get components.
❖ Input: void.
❖ Return: The array of components.
def get_x_array():
    pass
❖ Purpose: Get the array of X direction.
❖ Input: void.
❖ Return: The array of X direction.
def get_y_array():
    pass
❖ Purpose: Get the array of Y direction.
❖ Input: void.
❖ Return: The array of Y direction.
```

#### How to use

#### Sample1.py

Purpose: obtain branches and component, and get x\_array, y\_array.

Branch: nodout.

 ${\color{red} \textbf{Component: } x\_acceleration.}$ 

Id: 1787

Ouput: nodoutPy.dat

```
br = BinoutReader(data_path)

res = BinoutReader.is_valid(data_path)
print(res)

branches = br.get_branch()
for branch in branches:
    print(branch, end=',')

br.set_branch('nodout')
br.set_id(1787)
br.set_component('x_acceleration')
x_array = br.get_x_array()
y_array = br.get_y_array()
out_path = os.path.join(cwd, 'nodoutPy.dat')
BinoutReader.write(out_path, x_array, y_array)
```