

Unity Tutorial: Car Controller with script

Step 1: Open **Unity** and go to your **Scene**

To make your life easier: Let's assume you have a car model and if you do not, feel free to use the standard assets or just make a square box and assume that as a car model.

Step 2: First make sure you have created a base box and change its **Position** to **X:0, Y:1, Z:0**

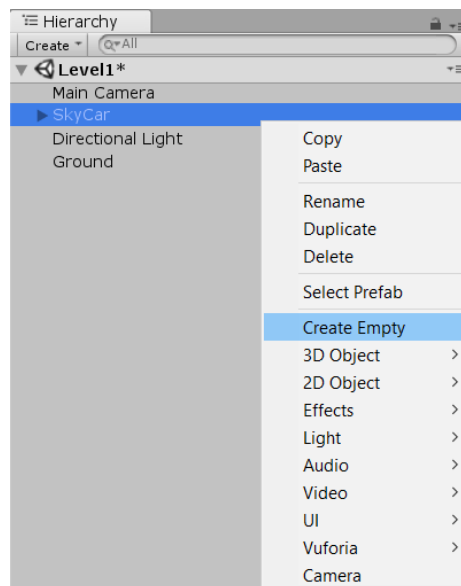
And change its **Scale** to **X: 55, Y: 0.05, Z: 55**

Then place the Car Model on top of that

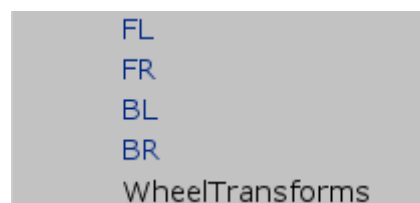
Let's call it **SkyCar** for now

Then Right Click **SkyCar** and **Create Empty**

Then rename it to **WheelTransforms**



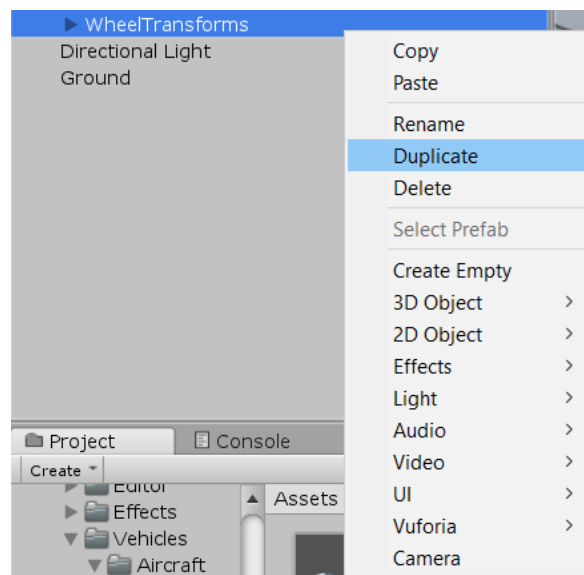
To make your life easier: rename your Wheels to, **FL, FR, BL** and **BR** for front left, front right and so on.



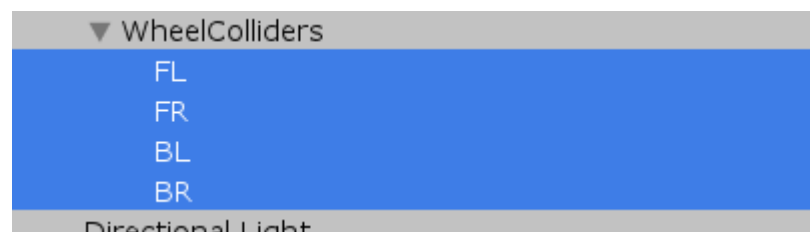
Then select them all and put them in the **Sub Section** of **Wheel Transforms**

To make your life easier: Now would be a good time to adjust the camera on your car (click on Main Camera and use the QWERT to adjust to your liking).

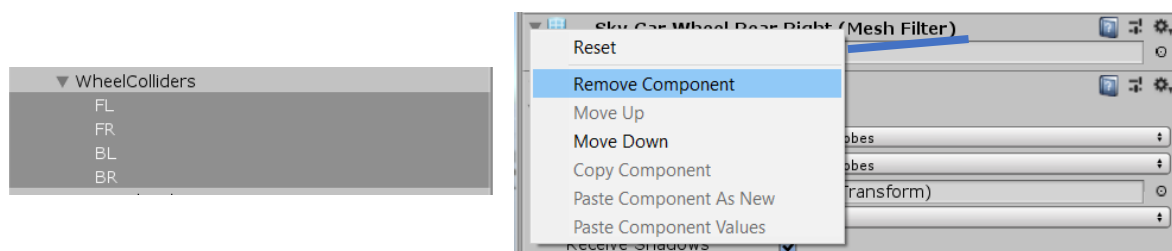
Now **Right Click** on **WheelTransforms** and **Duplicate** it



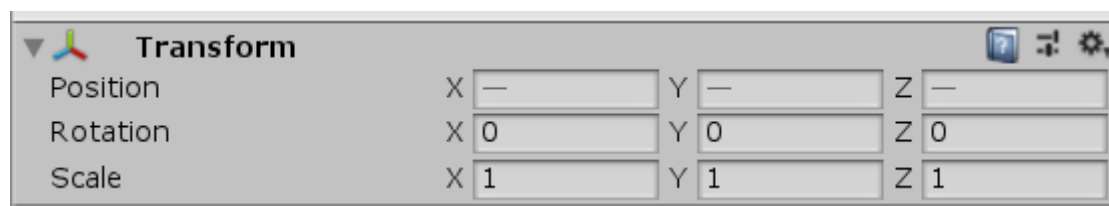
Rename it to **WheelColliders**, then open the sub rout and select all 4 wheels [ASB]



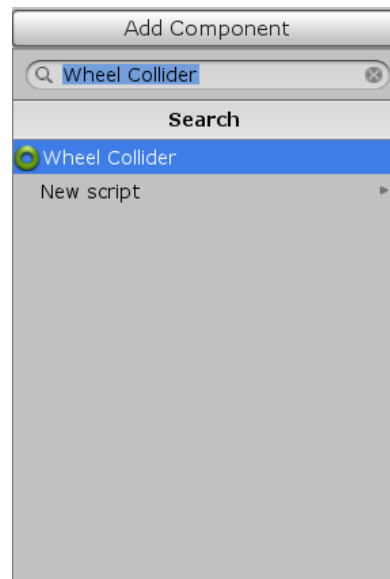
Make sure you **Remove Component** the **Mesh Filter** and **Mesh Renderer** for all 4 wheels [ASB]



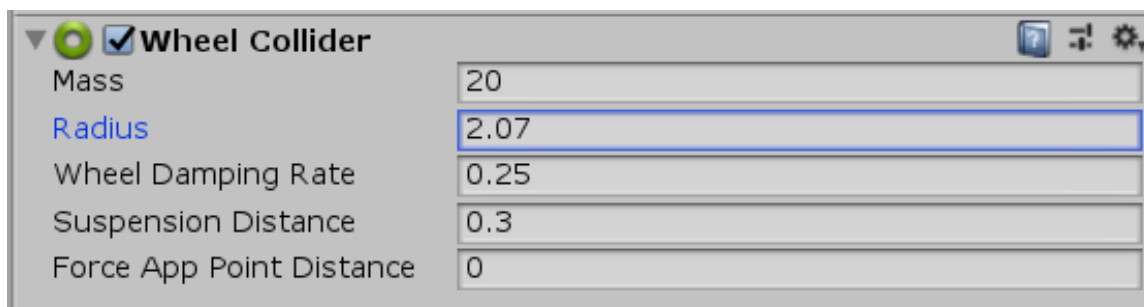
Then make sure their **Scale** is **X: 1, Y: 1, Z: 1** [ASB]



Having them still **selected**, **Add New Component > Wheel Collider** [ASB]



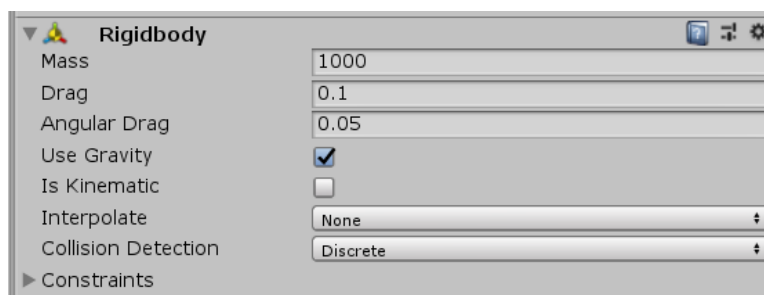
Make the **Radius = 2.7** [ASB]



Then Select the **SkyCar** at the **Hierarchy > Add Component > Rigidbody**

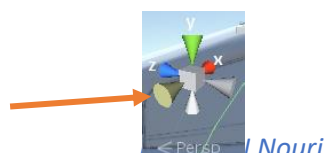
Change the **Mass** to **1000** (For now, you might want to change this value if you feel your car is not fast enough)

Also change **Drag** to **0.1** [ASB]

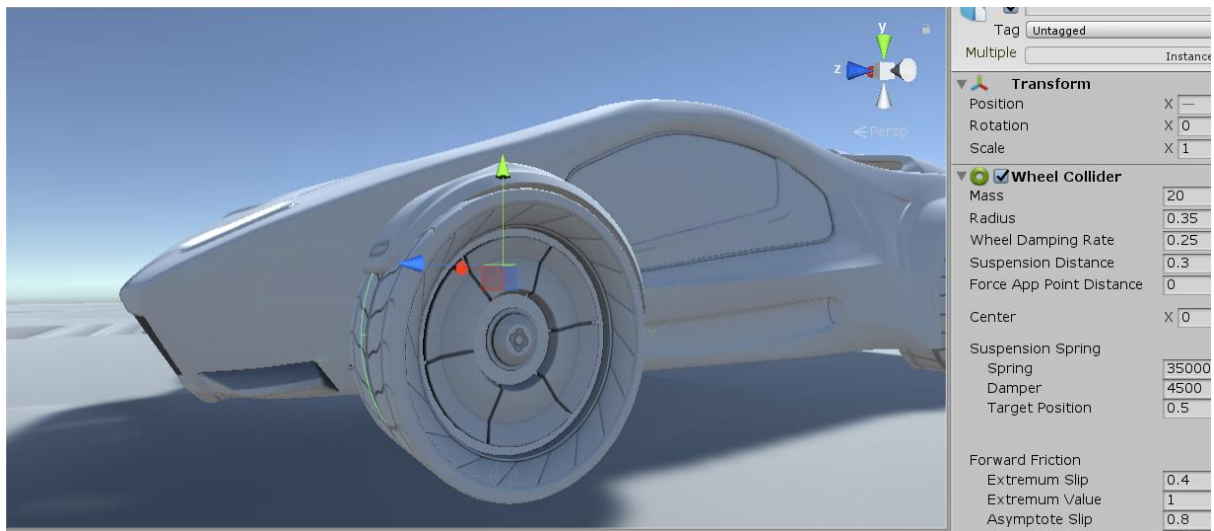


Then go back to the **WheelColliders > Select all 4 Wheels**

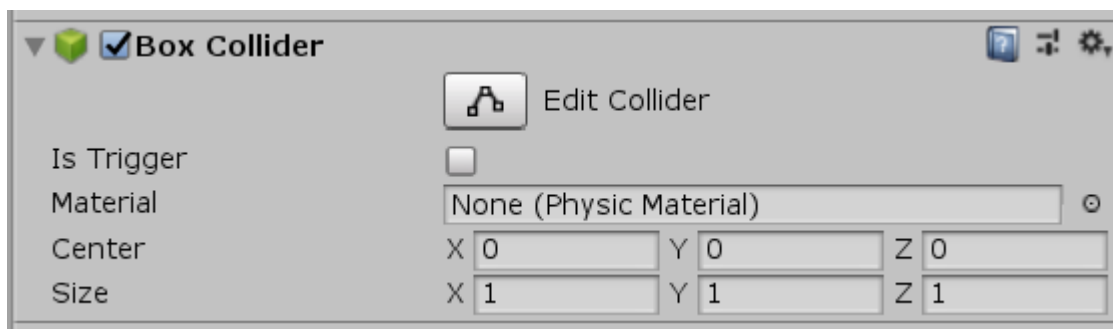
Then using the **side view** (To do that, you can use the **View Navigator** on top right) [ASB]



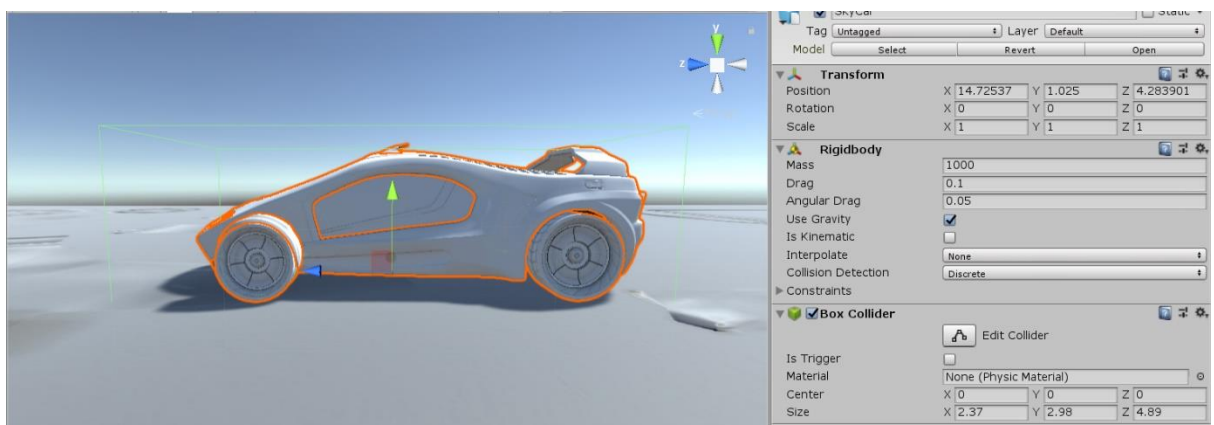
Step 3: Change the **Radius** till the **Green lines** match the shape of the wheels [ASB]



Then Select **SkyCar > Add Component > Box Collider** [ASB]



Then change its **size** so your car would **fit** inside of the **green 'Box'** [ASB]



Step 4: SkyCar > Add Component > New Script > CarController

To make your life easier: Go to your Asset and make sure you move your **Script** into your Script Folder

Then > **Open the Script**

Just so you know: You need to implement the **Wheel Colliders**, **Wheel Game object**, **Top Speed**, **Maximum Torque** and so on, to do that use the code below and pay attention to the **comments** to understand the **behaviour of the code** and its **grammar**, Comments are followed **'//'** and are in green.

Step 5: Follow these codes:

The definition part:

```

1  using System.Collections;
2  using System.Collections.Generic;
3  using UnityEngine;
4
5  public class CarController : MonoBehaviour {
6      // Wheel Colliders
7      public WheelCollider WheelFL;
8      public WheelCollider WheelFR;
9      public WheelCollider WheelBL;
10     public WheelCollider WheelBR;
11
12     //Wheel GameObjects
13     public GameObject FL;
14     public GameObject FR;
15     public GameObject BL;
16     public GameObject BR;
17
18     public float topSpeed = 500f; // The Top Speed
19     public float maxTorque = 200f; // The Maximum Torque to apply to the wheels
20     public float maxSteerAngle = 75f;
21     public float currentSpeed;
22     public float maxBrakeTorque = 2200;
23
24     private float Forward; // Forward Axis
25     private float Turn; // Turn Axis
26     private float Brake; // Break Axis
27
28     private Rigidbody rb; // Rigidbody of the car
29

```

The Void Start and the Void FixUpdate:

```

30 // Use this for initialization:
31 void Start () {
32     rb = GetComponent<Rigidbody>();
33 }
34
35 void FixedUpdate () { //Fixed Update is more physics realistic
36     Forward = Input.GetAxis("Vertical");//The Vertical and the Horizontal make the WASD and the arrow keys moving keys
37     Turn = Input.GetAxis("Horizontal");
38     Brake = Input.GetAxis("Jump");// the jump is same as space key
39
40     WheelFL.steerAngle = maxSteerAngle * Turn;
41     WheelFR.steerAngle = maxSteerAngle * Turn;
42
43     currentSpeed = 2 * 22 / 7 * WheelBL.radius * WheelBL.rpm * 60 / 100; // Formula for calculating speed in kmph
44
45     if(currentSpeed < topSpeed)
46     {
47         WheelBL.motorTorque = maxTorque * Forward;// Runs the Wheel on the Back Left Wheel
48         WheelBR.motorTorque = maxTorque * Forward;// Runs the Wheel on the Back Right Wheel
49         // you can just use the back wheels, but I am picky, and I want all my wheels to run.
50         WheelFL.motorTorque = maxTorque * Forward;// Runs the Wheel on the Front Left Wheel
51         WheelFR.motorTorque = maxTorque * Forward;// Runs the Wheel on the Front Back Wheel
52     } // will try to slow the car before top speed but it wont be accurate
53
54     WheelBL.brakeTorque = maxBrakeTorque * Brake;//This is the brakes for each wheel
55     WheelBR.brakeTorque = maxBrakeTorque * Brake;
56     WheelFL.brakeTorque = maxBrakeTorque * Brake;
57     WheelFR.brakeTorque = maxBrakeTorque * Brake;
58 }

```

The **Void Update**:

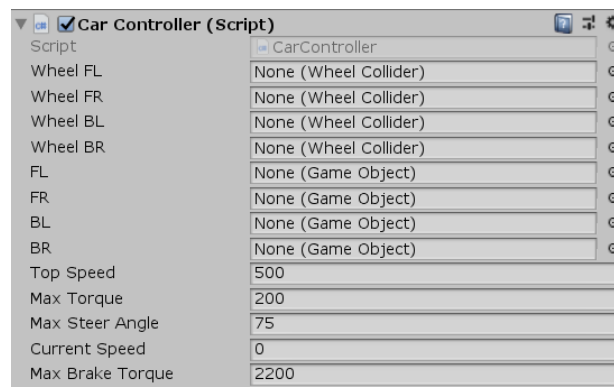
```

59 void Update() // Update is called once per frame
60 {
61     Quaternion flq;//Rotation of The Wheel Collider
62     Vector3 flv;//Position of The Wheel Collider
63     WheelFL.GetWorldPose(out flv, out flq); // Get the wheel collider position and rotation
64     BL.transform.position = flv;
65     BL.transform.rotation = flq;
66
67     Quaternion Blq;//Rotation of The Wheel Collider
68     Vector3 Blv;//Position of The Wheel Collider
69     WheelBL.GetWorldPose(out Blv, out Blq); // Get the wheel collider position and rotation
70     FL.transform.position = Blv;
71     FL.transform.rotation = Blq;
72
73     Quaternion fRq;//Rotation of The Wheel Collider
74     Vector3 fRv;//Position of The Wheel Collider
75     WheelFR.GetWorldPose(out fRv, out fRq); // Get the wheel collider position and rotation
76     FR.transform.position = fRv;
77     FR.transform.rotation = fRq;
78
79     Quaternion BRq;//Rotation of The Wheel Collider
80     Vector3 BRv;//Position of The Wheel Collider
81     WheelBR.GetWorldPose(out BRv, out BRq); // Get the wheel collider position and rotation
82     BR.transform.position = BRv;
83     BR.transform.rotation = BRq;
84 }
85
86

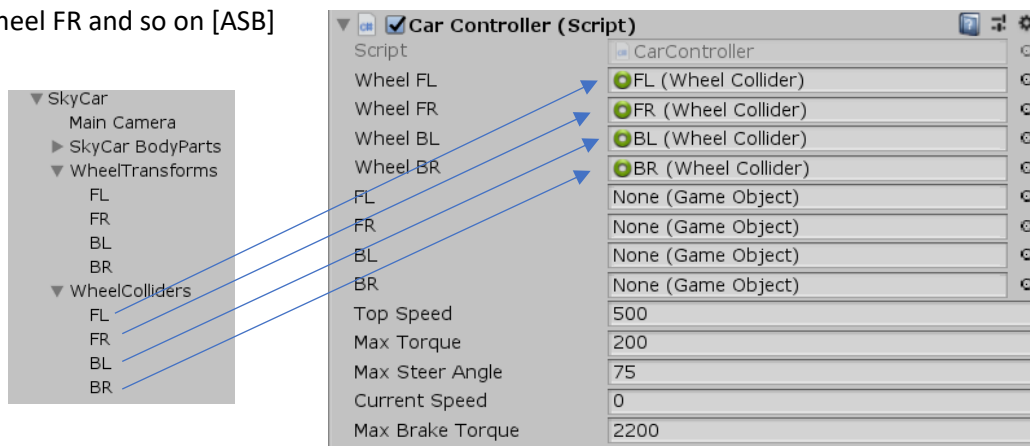
```

Then **Save all** and return to **Unity**

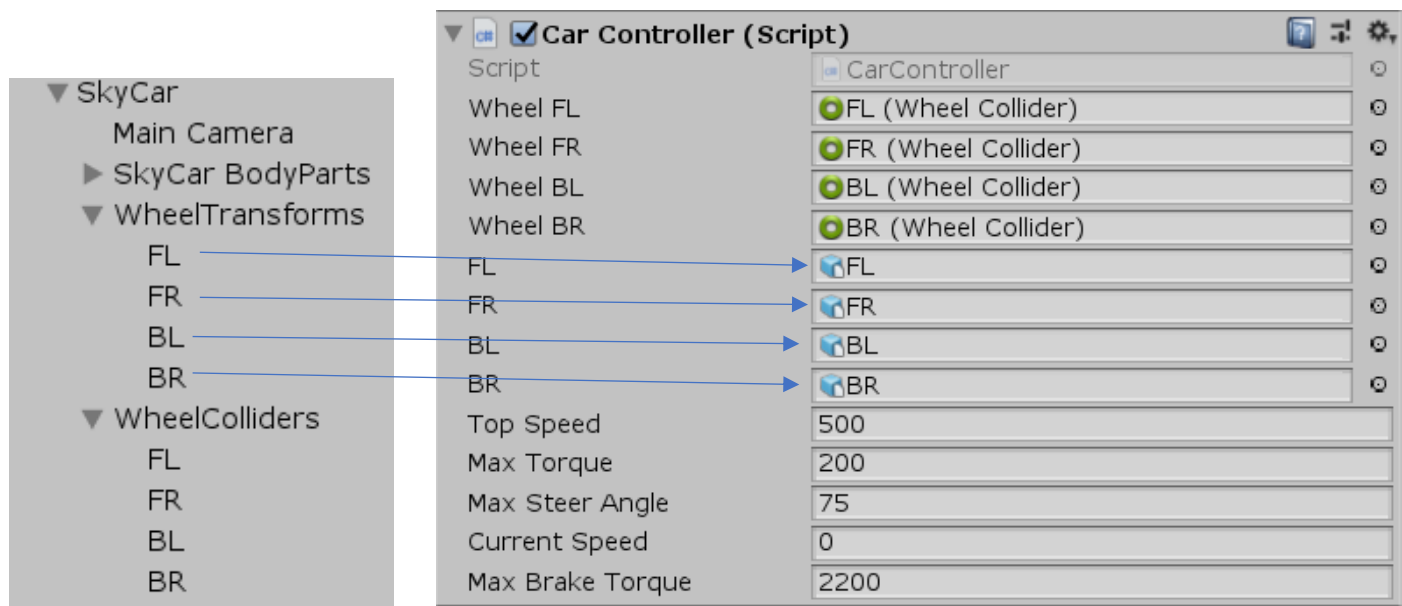
Step 6: When you returned to unity, Under **SkyCar Inspections**, you should have a bigger section for script than you did before [ASB]



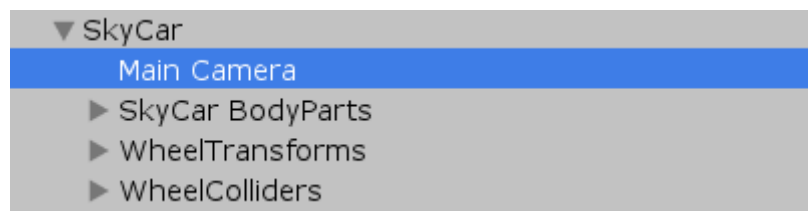
Then open the **WheelCollider** sub route in Hierarchy and drag and drop FL for Wheel FL, FR for Wheel FR and so on [ASB]



Then [do the same](#) for **WheelTransforms** for the next four spaces below it [ASB]



Step 7: Drag the **Main Camera** and drop it under sub rout of **SkyCar** so the [camera follows the car](#) [ASB]



Step 8: Save your work and Enjoy the ride 😊