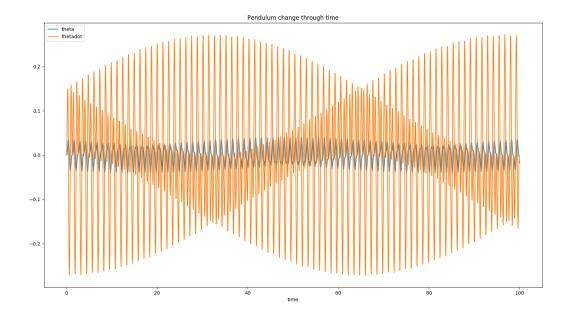
Daniel Louback S. Lubanco

```
Exercises 7
"
Pendulun
d_dtheta = -g/l*sin(theta)+C*cos(theta)*sin(Omega*t)
import numpy as np
from scipy.integrate import odeint
from math import *
import matplotlib.pyplot as plt
#from IPython.display import display, clear_output
#import time
def sys(theta, t, l, C, omega, g):
  theta1 = theta[0]
  theta2 = theta[1]
  dtheta1_dt = theta2
  dtheta2 dt = -g/l*sin(theta1) + C*cos(theta2)*sin(omega*t)
  dtheta dt = [dtheta1 dt, dtheta2 dt]
  return dtheta dt
def main():
  C = 2
  l = 10/100 \text{ #m}
  t = np.linspace(0,100,2500)
  g = 9.81
  theta_0=np.array([0,0]).T
  omega = np.sqrt(g/l)#5
  theta = odeint(sys,theta_0,t,args = (l,C,omega,g))
  plt.plot(t,theta)
  print(theta)
  plt.legend(['theta','thetadot'])
  plt.title("Pendulum change through time with force in natural pendulum's frequency")
  plt.xlabel("time")
  plt.show()
  fig, ax = plt.subplots(figsize=(4,4))
  x=theta
if __name__ == "__main__":
  main()
```

---- Output figures

(a)



(b)

