

# paper3

October 8, 2025

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[2]: # =====  
# Deterministic UC (N=3) via 3-Block ADMM  
# Block-2: MONOLITHIC QUBO per time slice (y,u,v together)  
# - Run 1: Brute Force QUBO  
# - Run 2: DVQE QUBO  
# Output: publication-quality plot comparing residuals, saved as JPG  
# =====  
  
import numpy as np  
import cvxpy as cp  
import math  
import matplotlib.pyplot as plt  
from itertools import product  
  
# Optional (only needed for the DVQE run)  
try:  
    from raiselab import DVQE  
    HAS_DVQE = True  
except Exception:  
    HAS_DVQE = False  
  
# -----  
# Global Config  
# -----  
N = 3          # units  
T = 6          # periods  
  
# Costs  
A = np.array([500, 600, 450], dtype=float)    # no-load  
B = np.array([20.0, 25.0, 18.0], dtype=float)  
C = np.array([0.002, 0.0015, 0.0025], dtype=float)  
S = np.array([200, 200, 250], dtype=float)    # startup  
H = np.array([0, 0, 0], dtype=float)         # shutdown  
  
# Capacities  
Pmin = np.array([10, 20, 15], dtype=float)  
Pmax = np.array([60, 80, 70], dtype=float)
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# Ramps (per period)
RU = np.array([30, 30, 25], dtype=float)
RD = np.array([30, 30, 25], dtype=float)
SU = np.array([40, 40, 35], dtype=float)
SD = np.array([40, 40, 35], dtype=float)

# Min up/down (periods)
Umin = np.array([2, 2, 3], dtype=int)
Dmin = np.array([2, 2, 2], dtype=int)

# Demand & reserves
L = np.array([80, 90, 100, 95, 85, 75], dtype=float)
R_up_req = np.array([8, 8, 10, 10, 8, 6], dtype=float)
R_dn_req = np.array([6, 6, 8, 8, 6, 6], dtype=float)
delta_tau = 1.0 # 1 period

# ADMM Hyperparameters
rho_y = rho_u = rho_v = 7.0e5
beta_y = beta_u = beta_v = 7.0e6
epsilon = 1e-3
max_iter = 3000

# Utility
ACCEPT_TOL = 1e-12
Y_THRESHOLD = 0.5

# DVQE (only used in the DVQE run)
dvqe_mode = "distributed" # or "monolithic"
dvqe_depth = 2
dvqe_lr = 0.1
dvqe_max_iters = 100
qpu_qubit_config = [3, 3, 3,3,3] # per-time: 3N bits -> this is ignored in
    ↪ some impls; keep for compatibility

rng = np.random.default_rng(7)

# -----
# Helper: brute-force solver (monolithic)
# -----
def solve_qubo_bruteforce(Q, q_linear):
    Q = np.asarray(Q, dtype=float)
    q = np.asarray(q_linear, dtype=float).ravel()
    n = q.size
    if Q.shape != (n, n):
        raise ValueError(f"Q must be ({n},{n}); got {Q.shape}")
    # Symmetrize

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Q = 0.5 * (Q + Q.T)
best_z, best_cost = None, float("inf")
for cand in product([0, 1], repeat=n):
    z = np.fromiter(cand, dtype=float, count=n)
    cost = z @ Q @ z + q @ z
    if cost < best_cost:
        best_cost = cost
        best_z = z.astype(int)
return best_z, best_cost

# -----
# Diagnostics (for prints if needed)
# -----
def capacity_violations(pv, yv):
    below = np.maximum(0.0, (Pmin[:, None] * yv) - pv)
    above = np.maximum(0.0, pv - (Pmax[:, None] * yv))
    return float(np.max(below)), float(np.max(above))

def power_balance_mismatch(pv):
    mis = np.abs(np.sum(pv, axis=0) - L)
    return float(np.max(mis))

# -----
# Core ADMM Runner
# solver in {"brute", "dvqe"}
# Block-2: single monolithic QUBO per time over [z_y; z_u; z_v] (length 3N)
# -----
def run_admm_monolithic(solver="brute"):
    # Initial p0 in [20,30] and y0 inferred
    p0 = np.ones(N) * 20
    y0 = (p0 > 0.0).astype(int)

    # Relaxed primals (Block-1)
    y = np.ones((N, T)) * 0.5
    u = np.zeros((N, T))
    v = np.zeros((N, T))
    p = np.tile(L / max(N, 1), (N, 1))
    r_up = np.zeros((N, T))
    r_dn = np.zeros((N, T))

    # Auxiliaries & slacks
    z_y = np.zeros((N, T), dtype=int)
    z_u = np.zeros((N, T), dtype=int)
    z_v = np.zeros((N, T), dtype=int)
    s_y = np.zeros((N, T))
    s_u = np.zeros((N, T))
    s_v = np.zeros((N, T))

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# Duals
lam_y = np.zeros((N, T))
lam_u = np.zeros((N, T))
lam_v = np.zeros((N, T))

residuals = []

for it in range(max_iter):
    # ===== Block 1: Classical QP =====
    yi = cp.Variable((N, T))
    ui = cp.Variable((N, T))
    vi = cp.Variable((N, T))
    pi = cp.Variable((N, T))
    rup = cp.Variable((N, T), nonneg=True)
    rdn = cp.Variable((N, T), nonneg=True)

    econ = (
        cp.sum(cp.multiply(A[:, None], yi)) +
        cp.sum(cp.multiply(B[:, None], pi)) +
        cp.sum(cp.multiply(C[:, None], cp.square(pi))) +
        cp.sum(cp.multiply(S[:, None], ui)) +
        cp.sum(cp.multiply(H[:, None], vi))
    )

    pen_y = cp.sum(cp.multiply(lam_y, yi - z_y + s_y)) + (rho_y / 2) * cp.
↪sum_squares(yi - z_y + s_y)
    pen_u = cp.sum(cp.multiply(lam_u, ui - z_u + s_u)) + (rho_u / 2) * cp.
↪sum_squares(ui - z_u + s_u)
    pen_v = cp.sum(cp.multiply(lam_v, vi - z_v + s_v)) + (rho_v / 2) * cp.
↪sum_squares(vi - z_v + s_v)
    objective = cp.Minimize(econ + pen_y + pen_u + pen_v)

    cons = []
    # Domains
    cons += [yi >= 0, yi <= 1, ui >= 0, ui <= 1, vi >= 0, vi <= 1]
    cons += [pi >= 0]
    # Power balance
    for t in range(T):
        cons += [cp.sum(pi[:, t]) == L[t]]
    # Capacity bounds
    cons += [pi >= cp.multiply(Pmin[:, None], yi)]
    cons += [pi <= cp.multiply(Pmax[:, None], yi)]
    # Transitions & no-simultaneous
    cons += [yi[:, 0] - y0 == ui[:, 0] - vi[:, 0]]
    cons += [ui[:, 0] + vi[:, 0] <= 1]
    for t in range(1, T):
        cons += [yi[:, t] - yi[:, t - 1] == ui[:, t] - vi[:, t]]

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        cons += [ui[:, t] + vi[:, t] <= 1]
# Min up/down windows
for i in range(N):
    Ui, Di = int(Umin[i]), int(Dmin[i])
    for t in range(T):
        k_up = max(0, t - Ui + 1)
        k_dn = max(0, t - Di + 1)
        cons += [cp.sum(ui[i, k_up:t + 1]) <= yi[i, t]]
        cons += [cp.sum(vi[i, k_dn:t + 1]) <= 1 - yi[i, t]]
# Ramping with SU/SD
for i in range(N):
    cons += [pi[i, 0] - p0[i] <= RU[i] * y0[i] + SU[i] * ui[i, 0]]
    cons += [p0[i] - pi[i, 0] <= RD[i] * yi[i, 0] + SD[i] * vi[i, 0]]
    for t in range(1, T):
        cons += [pi[i, t] - pi[i, t - 1] <= RU[i] * yi[i, t - 1] +
↳SU[i] * ui[i, t]]
        cons += [pi[i, t - 1] - pi[i, t] <= RD[i] * yi[i, t] + SD[i] *
↳vi[i, t]]
# Reserves headroom/footroom + deliverability
cons += [rup <= cp.multiply(Pmax[:, None], yi) - pi]
cons += [rdn <= pi - cp.multiply(Pmin[:, None], yi)]
cons += [rup <= RU[:, None] * delta_tau]
cons += [rdn <= RD[:, None] * delta_tau]
# System reserve requirements
for t in range(T):
    cons += [cp.sum(rup[:, t]) >= R_up_req[t]]
    cons += [cp.sum(rdn[:, t]) >= R_dn_req[t]]

# Warm-start
yi.value, ui.value, vi.value = y, u, v
pi.value, rup.value, rdn.value = p, r_up, r_dn

# Solve Block-1
prob = cp.Problem(objective, cons)
installed = set(cp.installed_solvers())
status = "unknown"
if "OSQP" in installed:
    prob.solve(solver=cp.OSQP, eps_abs=1e-7, eps_rel=1e-7,
        max_iter=800000, polish=True, warm_start=True,
↳verbose=False)
    status = prob.status
    if status not in ("optimal", "optimal_inaccurate") and "SCS" in
↳installed:
        prob.solve(solver=cp.SCS, eps=5e-7, max_iters=1_200_000,
            warm_start=True, verbose=False)
    status = prob.status

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# Extract values
y = yi.value
u = ui.value
v = vi.value
p = pi.value
r_up = rup.value
r_dn = rdn.value

# ===== Block 2: Monolithic QUBO per time =====
# z_t {0,1}^{3N} : [z_y; z_u; z_v]
z_y_prev, z_u_prev, z_v_prev = z_y.copy(), z_u.copy(), z_v.copy()
for t in range(T):
    qy = -(lam_y[:, t] + rho_y * (y[:, t] + s_y[:, t])) + 0.5 * rho_y
    qu = -(lam_u[:, t] + rho_u * (u[:, t] + s_u[:, t])) + 0.5 * rho_u
    qv = -(lam_v[:, t] + rho_v * (v[:, t] + s_v[:, t])) + 0.5 * rho_v

    q = np.concatenate([qy, qu, qv]) # 3N linear terms
    Q = np.zeros((3 * N, 3 * N), dtype=float) # monolithic (no
    ↪couplings here)

    # Current incumbent combined
    z_prev = np.concatenate([z_y_prev[:, t], z_u_prev[:, t], z_v_prev[
    ↪, t]])

    if solver == "brute":
        z_t, _ = solve_qubo_bruteforce(Q, q)
    elif solver == "dvqe":
        if not HAS_DVQE:
            raise RuntimeError("DVQE not available. Please install/
            ↪enable raiselab.DVQE.")
        z_t, _, _ = DVQE(mode=dvqe_mode, Q=Q, q_linear=q, init_type=2,
            depth=dvqe_depth, lr=dvqe_lr,
            ↪max_iters=dvqe_max_iters,
            qpu_qubit_config=qpu_qubit_config,
            ↪rel_tol=1e-6)
        else:
            raise ValueError("solver must be 'brute' or 'dvqe'.")

    z_t = (np.asarray(z_t).ravel() > 0.5).astype(int)

    # Accept-if-better w.r.t. linear objective (Q is zero here)
    if float(q @ z_t) + ACCEPT_TOL < float(q @ z_prev):
        z_y[:, t] = z_t[0:N]
        z_u[:, t] = z_t[N:2 * N]
        z_v[:, t] = z_t[2 * N:3 * N]
    else:
        z_y[:, t] = z_y_prev[:, t]

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        z_u[:, t] = z_u_prev[:, t]
        z_v[:, t] = z_v_prev[:, t]

# ===== Block 3: Prox slacks (nonnegativity projection) =====
s_y = -(lam_y + rho_y * (y - z_y)) / (beta_y + rho_y)
s_u = -(lam_u + rho_u * (u - z_u)) / (beta_u + rho_u)
s_v = -(lam_v + rho_v * (v - z_v)) / (beta_v + rho_v)
s_y = np.maximum(0.0, s_y)
s_u = np.maximum(0.0, s_u)
s_v = np.maximum(0.0, s_v)

# ===== Dual Updates =====
lam_y = lam_y + 0.5 * rho_y * (y - z_y + s_y)
lam_u = lam_u + 0.5 * rho_u * (u - z_u + s_u)
lam_v = lam_v + 0.5 * rho_v * (v - z_v + s_v)

# ===== Residual & Stop =====
res = math.sqrt(
    np.linalg.norm((y - z_y + s_y).ravel())**2 +
    np.linalg.norm((u - z_u + s_u).ravel())**2 +
    np.linalg.norm((v - z_v + s_v).ravel())**2
)
residuals.append(res)
if (it % 10) == 0:
    print(f"[{solver:5s}] it={it:4d} residual={res:.3e}")
if res < epsilon:
    break

return residuals

# -----
# Run both variants
# -----
res_brute = run_admm_monolithic(solver="brute")
res_dvqe = run_admm_monolithic(solver="dvqe") if HAS_DVQE else None

# -----
# Plot (publication style) & Save
# -----
plt.rcParams.update({
    "font.size": 12,          # base font size
    "axes.labelsize": 13,
    "axes.titlesize": 14,
    "legend.fontsize": 12,
    "xtick.labelsize": 11,
    "ytick.labelsize": 11
})

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plt.figure(figsize=(7.2, 4.6))
# Avoid markers for a clean publication curve; thicker lines
plt.semilogy(res_brute, linewidth=2.2, label="ADMM + Monolithic QUBO (Brute_
↪Force)")
if res_dvqe is not None:
    plt.semilogy(res_dvqe, linewidth=2.2, linestyle="--",
        label="ADMM + Monolithic QUBO (DVQE)")
else:
    plt.semilogy([], [], label="DVQE not available", alpha=0.0) # keep legend_
↪alignment if needed

plt.grid(True, which="both", linestyle="--", linewidth=0.7, alpha=0.7)
plt.xlabel("Iteration")
plt.ylabel("Primal residual (log scale)")
plt.title("Deterministic UC (N=3) - 3-Block ADMM with Monolithic Block-2 QUBO")
plt.tight_layout()
plt.legend(frameon=False)
plt.savefig("admm_uc_monolithic_residuals.jpg", dpi=300)
plt.show()

print("Saved figure: admm_uc_monolithic_residuals.jpg")

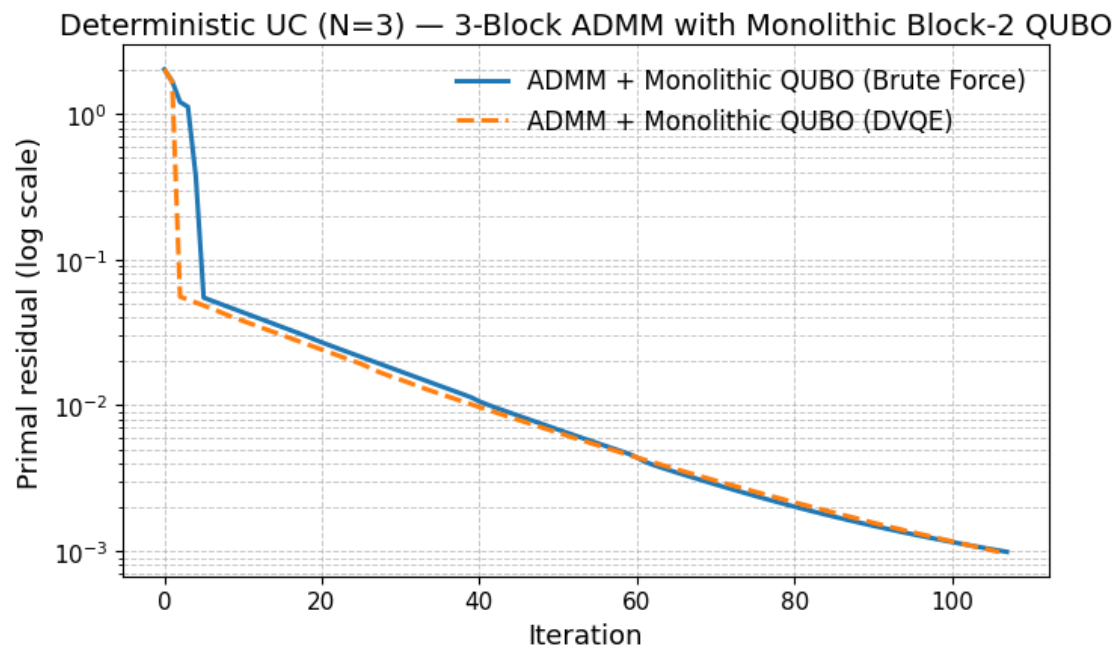
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[brute] it= 0 residual=2.016e+00
[brute] it= 10 residual=4.342e-02
[brute] it= 20 residual=2.705e-02
[brute] it= 30 residual=1.709e-02
[brute] it= 40 residual=1.065e-02
[brute] it= 50 residual=6.818e-03
[brute] it= 60 residual=4.390e-03
[brute] it= 70 residual=2.868e-03
[brute] it= 80 residual=2.020e-03
[brute] it= 90 residual=1.492e-03
[brute] it= 100 residual=1.155e-03
[dvqe ] it= 0 residual=2.034e+00
[dvqe ] it= 10 residual=3.795e-02
[dvqe ] it= 20 residual=2.412e-02
[dvqe ] it= 30 residual=1.499e-02
[dvqe ] it= 40 residual=9.740e-03
[dvqe ] it= 50 residual=6.487e-03
[dvqe ] it= 60 residual=4.395e-03
[dvqe ] it= 70 residual=3.045e-03
[dvqe ] it= 80 residual=2.162e-03
[dvqe ] it= 90 residual=1.566e-03
[dvqe ] it= 100 residual=1.167e-03

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Saved figure: admm\_uc\_monolithic\_residuals.jpg

[ ]: