

# SM

PyR@TE 3.0

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# 1 Model

## 1.1 Gauge groups

Name	Type	Abelian	Coupling constant
U1Y	$U(1)$	True	$g_1$
SU2L	$SU(2)$	False	$g_2$
SU3c	$SU(3)$	False	$g_3$

## 1.2 Fermions

Name	Generations	U1Y $\times$ SU2L $\times$ SU3c
$Q$	3	$(+\frac{1}{6}, \mathbf{2}, \mathbf{3})$
$L$	3	$(-\frac{1}{2}, \mathbf{2}, \mathbf{1})$
$u_R$	3	$(+\frac{2}{3}, \mathbf{1}, \mathbf{3})$
$d_R$	3	$(-\frac{1}{3}, \mathbf{1}, \mathbf{3})$
$e_R$	3	$(-1, \mathbf{1}, \mathbf{1})$

## 1.3 Scalars

Name	Complex	Expression	Generations	U1Y $\times$ SU2L $\times$ SU3c
$H$	True	$\frac{1}{\sqrt{2}} (\Pi + i \Sigma)$	1	$(+\frac{1}{2}, \mathbf{2}, \mathbf{1})$

# 2 Lagrangian

## 2.1 Definitions

$$\tilde{H}_i = \epsilon_{i,j} H_j^\dagger$$

## 2.2 Yukawa couplings

$$-\mathcal{L}_Y = +Y_{uf_1,f_2} \tilde{H}_i \bar{Q}_{f_1,i,a} u_{Rf_2,a} + Y_{df_1,f_2} \bar{Q}_{f_1,i,a} H_i d_{Rf_2,a} + Y_{ef_1,f_2} \bar{L}_{f_1,i} H_i e_{Rf_2} + \text{h.c.}$$

## 2.3 Quartic couplings

$$-\mathcal{L}_Q = +\lambda H_i^\dagger H_i H_{i_1}^\dagger H_{i_1}$$

## 2.4 Scalar mass couplings

$$-\mathcal{L}_{sm} = +\mu H_i^\dagger H_i$$

# 3 Renormalization Group Equations

## 3.1 Convention

$$\beta(X) \equiv \mu \frac{dX}{d\mu} \equiv \frac{1}{(4\pi)^2} \beta^{(1)}(X) + \frac{1}{(4\pi)^4} \beta^{(2)}(X)$$

## 3.2 Definitions and substitutions

$$Y_u = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & y_t \end{pmatrix}, \quad Y_d = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & y_b \end{pmatrix}, \quad Y_e = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & y_\tau \end{pmatrix}$$

## 3.3 Gauge couplings

$$\beta^{(1)}(g_1) = \frac{41}{10} g_1^3$$

$$\beta^{(2)}(g_1) = +\frac{199}{50} g_1^5 + \frac{27}{10} g_1^3 g_2^2 + \frac{44}{5} g_1^3 g_3^2 - \frac{17}{10} g_1^3 |y_t|^2 - \frac{1}{2} g_1^3 |y_b|^2 - \frac{3}{2} g_1^3 |y_\tau|^2$$

$$\beta^{(1)}(g_2) = -\frac{19}{6} g_2^3$$

$$\beta^{(2)}(g_2) = +\frac{9}{10} g_1^2 g_2^3 + \frac{35}{6} g_2^5 + 12 g_2^3 g_3^2 - \frac{3}{2} g_2^3 |y_t|^2 - \frac{3}{2} g_2^3 |y_b|^2 - \frac{1}{2} g_2^3 |y_\tau|^2$$

$$\beta^{(1)}(g_3) = -7 g_3^3$$

$$\beta^{(2)}(g_3) = +\frac{11}{10} g_1^2 g_3^3 + \frac{9}{2} g_2^2 g_3^3 - 26 g_3^5 - 2 g_3^3 |y_t|^2 - 2 g_3^3 |y_b|^2$$

### 3.4 Yukawa couplings

$$\beta^{(1)}(y_t) = +\frac{9}{2}y_t|y_t|^2 + y_t|y_\tau|^2 + \frac{3}{2}y_t|y_b|^2 - \frac{17}{20}g_1^2y_t - \frac{9}{4}g_2^2y_t - 8g_3^2y_t$$

$$\begin{aligned}\beta^{(2)}(y_t) = & -12y_t|y_t|^4 - \frac{1}{4}y_t|y_b|^4 - \frac{9}{4}y_t|y_\tau|^4 - \frac{11}{4}y_t|y_b|^2|y_t|^2 + \frac{5}{4}y_t|y_b|^2|y_\tau|^2 - \frac{9}{4}y_t|y_t|^2|y_\tau|^2 \\ & -12\lambda y_t|y_t|^2 + 6\lambda^2y_t + \frac{393}{80}g_1^2y_t|y_t|^2 + \frac{225}{16}g_2^2y_t|y_t|^2 + 36g_3^2y_t|y_t|^2 + \frac{15}{8}g_1^2y_t|y_\tau|^2 \\ & + \frac{15}{8}g_2^2y_t|y_\tau|^2 + \frac{7}{80}g_1^2y_t|y_b|^2 + \frac{99}{16}g_2^2y_t|y_b|^2 + 4g_3^2y_t|y_b|^2 + \frac{1187}{600}g_1^4y_t - \frac{9}{20}g_1^2g_2^2y_t \\ & + \frac{19}{15}g_1^2g_3^2y_t - \frac{23}{4}g_2^4y_t + 9g_2^2g_3^2y_t - 108g_3^4y_t\end{aligned}$$

$$\beta^{(1)}(y_b) = +\frac{3}{2}y_b|y_t|^2 + \frac{9}{2}y_b|y_b|^2 + y_b|y_\tau|^2 - \frac{1}{4}g_1^2y_b - \frac{9}{4}g_2^2y_b - 8g_3^2y_b$$

$$\begin{aligned}\beta^{(2)}(y_b) = & -\frac{11}{4}y_b|y_b|^2|y_t|^2 - \frac{1}{4}y_b|y_t|^4 + \frac{5}{4}y_b|y_t|^2|y_\tau|^2 - 12y_b|y_b|^4 - \frac{9}{4}y_b|y_\tau|^4 - \frac{9}{4}y_b|y_b|^2|y_\tau|^2 \\ & -12\lambda y_b|y_b|^2 + 6\lambda^2y_b + \frac{91}{80}g_1^2y_b|y_t|^2 + \frac{99}{16}g_2^2y_b|y_t|^2 + 4g_3^2y_b|y_t|^2 + \frac{237}{80}g_1^2y_b|y_b|^2 \\ & + \frac{225}{16}g_2^2y_b|y_b|^2 + 36g_3^2y_b|y_b|^2 + \frac{15}{8}g_1^2y_b|y_\tau|^2 + \frac{15}{8}g_2^2y_b|y_\tau|^2 - \frac{127}{600}g_1^4y_b - \frac{27}{20}g_1^2g_2^2y_b \\ & + \frac{31}{15}g_1^2g_3^2y_b - \frac{23}{4}g_2^4y_b + 9g_2^2g_3^2y_b - 108g_3^4y_b\end{aligned}$$

$$\beta^{(1)}(y_\tau) = +3y_\tau|y_t|^2 + 3y_\tau|y_b|^2 + \frac{5}{2}y_\tau|y_\tau|^2 - \frac{9}{4}g_1^2y_\tau - \frac{9}{4}g_2^2y_\tau$$

$$\begin{aligned}\beta^{(2)}(y_\tau) = & -\frac{27}{4}y_\tau|y_t|^2|y_\tau|^2 + \frac{3}{2}y_\tau|y_b|^2|y_t|^2 - \frac{27}{4}y_\tau|y_b|^2|y_\tau|^2 - \frac{27}{4}y_\tau|y_t|^4 - \frac{27}{4}y_\tau|y_b|^4 \\ & -3y_\tau|y_\tau|^4 - 12\lambda y_\tau|y_\tau|^2 + 6\lambda^2y_\tau + \frac{17}{8}g_1^2y_\tau|y_t|^2 + \frac{45}{8}g_2^2y_\tau|y_t|^2 + 20g_3^2y_\tau|y_t|^2 \\ & + \frac{5}{8}g_1^2y_\tau|y_b|^2 + \frac{45}{8}g_2^2y_\tau|y_b|^2 + 20g_3^2y_\tau|y_b|^2 + \frac{537}{80}g_1^2y_\tau|y_\tau|^2 + \frac{165}{16}g_2^2y_\tau|y_\tau|^2 \\ & + \frac{1371}{200}g_1^4y_\tau + \frac{27}{20}g_1^2g_2^2y_\tau - \frac{23}{4}g_2^4y_\tau\end{aligned}$$

### 3.5 Quartic couplings

$$\beta^{(1)}(\lambda) = +24\lambda^2 - \frac{9}{5}g_1^2\lambda - 9g_2^2\lambda + \frac{27}{200}g_1^4 + \frac{9}{20}g_1^2g_2^2 + \frac{9}{8}g_2^4 + 12\lambda|y_t|^2 + 12\lambda|y_b|^2 + 4\lambda|y_\tau|^2$$

$$- 6 |y_t|^4 - 6 |y_b|^4 - 2 |y_\tau|^4$$

$$\begin{aligned} \beta^{(2)}(\lambda) = & - 312\lambda^3 + \frac{108}{5}g_1^2\lambda^2 + 108g_2^2\lambda^2 + \frac{1887}{200}g_1^4\lambda + \frac{117}{20}g_1^2g_2^2\lambda - \frac{73}{8}g_2^4\lambda - \frac{3411}{2000}g_1^6 \\ & - \frac{1677}{400}g_1^4g_2^2 - \frac{289}{80}g_1^2g_2^4 + \frac{305}{16}g_2^6 - 144\lambda^2|y_t|^2 - 144\lambda^2|y_b|^2 - 48\lambda^2|y_\tau|^2 \\ & + \frac{17}{2}g_1^2\lambda|y_t|^2 + \frac{5}{2}g_1^2\lambda|y_b|^2 + \frac{15}{2}g_1^2\lambda|y_\tau|^2 + \frac{45}{2}g_2^2\lambda|y_t|^2 + \frac{45}{2}g_2^2\lambda|y_b|^2 + \frac{15}{2}g_2^2\lambda|y_\tau|^2 \\ & + 80g_3^2\lambda|y_t|^2 + 80g_3^2\lambda|y_b|^2 - \frac{171}{100}g_1^4|y_t|^2 + \frac{9}{20}g_1^4|y_b|^2 - \frac{9}{4}g_1^4|y_\tau|^2 + \frac{63}{10}g_1^2g_2^2|y_t|^2 \\ & + \frac{27}{10}g_1^2g_2^2|y_b|^2 + \frac{33}{10}g_1^2g_2^2|y_\tau|^2 - \frac{9}{4}g_2^4|y_t|^2 - \frac{9}{4}g_2^4|y_b|^2 - \frac{3}{4}g_2^4|y_\tau|^2 - 3\lambda|y_t|^4 \\ & - 42\lambda|y_b|^2|y_t|^2 - 3\lambda|y_b|^4 - \lambda|y_\tau|^4 - \frac{8}{5}g_1^2|y_t|^4 + \frac{4}{5}g_1^2|y_b|^4 - \frac{12}{5}g_1^2|y_\tau|^4 - 32g_3^2|y_t|^4 \\ & - 32g_3^2|y_b|^4 + 30|y_t|^6 - 6|y_b|^4|y_t|^2 - 6|y_b|^2|y_t|^4 + 30|y_b|^6 + 10|y_\tau|^6 \end{aligned}$$

### 3.6 Scalar mass couplings

$$\beta^{(1)}(\mu) = - \frac{9}{10}g_1^2\mu - \frac{9}{2}g_2^2\mu + 12\lambda\mu + 6\mu|y_t|^2 + 6\mu|y_b|^2 + 2\mu|y_\tau|^2$$

$$\begin{aligned} \beta^{(2)}(\mu) = & + \frac{1671}{400}g_1^4\mu + \frac{9}{8}g_1^2g_2^2\mu - \frac{145}{16}g_2^4\mu + \frac{72}{5}g_1^2\lambda\mu + 72g_2^2\lambda\mu - 60\lambda^2\mu + \frac{17}{4}g_1^2\mu|y_t|^2 \\ & + \frac{5}{4}g_1^2\mu|y_b|^2 + \frac{15}{4}g_1^2\mu|y_\tau|^2 + \frac{45}{4}g_2^2\mu|y_t|^2 + \frac{45}{4}g_2^2\mu|y_b|^2 + \frac{15}{4}g_2^2\mu|y_\tau|^2 + 40g_3^2\mu|y_t|^2 \\ & + 40g_3^2\mu|y_b|^2 - 72\lambda\mu|y_t|^2 - 72\lambda\mu|y_b|^2 - 24\lambda\mu|y_\tau|^2 - \frac{27}{2}\mu|y_t|^4 - 21\mu|y_b|^2|y_t|^2 \\ & - \frac{27}{2}\mu|y_b|^4 - \frac{9}{2}\mu|y_\tau|^4 \end{aligned}$$

### 3.7 Vacuum-expectation values

Definitions:

$$H : \frac{1}{\sqrt{2}}\Pi_2 \rightarrow \frac{1}{\sqrt{2}}(\Pi_2 + v)$$

Gauge fixing:

$$\xi \rightarrow 1$$

RGEs:

$$\beta^{(1)}(v) = + \frac{3}{5}g_1^2v + 3g_2^2v - 3v|y_t|^2 - 3v|y_b|^2 - v|y_\tau|^2$$

$$\begin{aligned}\beta^{(2)}(v) = & -\frac{1221}{800}g_1^4v + \frac{9}{16}g_1^2g_2^2v + \frac{199}{32}g_2^4v - \frac{103}{40}g_1^2v|y_t|^2 - \frac{43}{40}g_1^2v|y_b|^2 - \frac{81}{40}g_1^2v|y_\tau|^2 \\ & - \frac{63}{8}g_2^2v|y_t|^2 - \frac{63}{8}g_2^2v|y_b|^2 - \frac{21}{8}g_2^2v|y_\tau|^2 - 20g_3^2v|y_t|^2 - 20g_3^2v|y_b|^2 + \frac{27}{4}v|y_t|^4 \\ & - \frac{3}{2}v|y_b|^2|y_t|^2 + \frac{27}{4}v|y_b|^4 + \frac{9}{4}v|y_\tau|^4 - 6\lambda^2v\end{aligned}$$

# A Group theoretical information

## A.1 Gauge groups

Group	Lie algebra	Dim.	Rank	Representations		
				Name / Dim.	Dynkin labels	Type
SU2	A1	3	1	<b>2</b>	[1]	Pseudo-real
				<b><math>\bar{2}</math></b>	[1, True]	Pseudo-real
SU3	A2	8	2	<b>3</b>	[1, 0]	Complex
				<b><math>\bar{3}</math></b>	[0, 1]	Complex