


Chapter-16

Greedy Algorithms

- ⊗ Greedy algorithm can be used for many optimization problems, but not always.
- ⊗ Greedy algorithm always makes choice that looks best at the moment. Don't think about future.
 - it hope that, a locally optimal choice will lead to a globally optimal solution
 - for some problems, it works.
- ⊗ Two ingredients that need to prove to for a greedy strategy:
 - (i) Greedy-choice property  choose best choice at the moment
don't think about future sub problem.
 - (ii) Optimal substructure
- ⇒ and we need to prove that a greedy choice at each step yields a globally optimal solution.
- ⊗ Optimal Substructure: a problem exhibits optimal substructure if an optimal solution to the problem contains optimal solution to sub problem.

An activity selection problem:

Definition:

- Scheduling a resource among competing activities.

Elaboration:

$\Rightarrow S = 1, 2, 3, \dots, n$ activities

activity a_i has,

start time s_i

finish time f_i

Resource Opening time

$$0 \leq s_i \leq f_i \leq \infty$$

Resource Closing time

Compatibility:

activity $a_i \Rightarrow [s_i, f_i)$

activity $a_j \Rightarrow [s_j, f_j)$

$$s_i \geq f_j$$

or

$$s_j \geq f_i$$

Goal:

- to select a maximum size set of mutually compatible activities.



\Rightarrow

i	1	2	3	4	5	6	7	8	9	10	11
s_i	1	3	0	5	3	5	6	8	8	2	12
f_i	4	5	6	7	2	7	10	11	12	14	16

\Rightarrow finish time is sorted already.

⊗ Optimal solution can be multiple:

$\left. \begin{array}{l} \{a_1, a_4, a_3, a_{11}\} \\ \{a_2, a_4, a_3, a_{11}\} \\ \{a_2, a_4, a_3, a_{11}\} \end{array} \right\}$

Greedy algorithm will give one of them.

⊗ Property of greedy algorithm here,

- choose one of them which must finish first.
- the next selected activity is always the one with the earliest finish time.
- it is a greedy choice in the sense that it leaves as much as opportunity as possible for the remaining activities to be scheduled.
- Thus it ~~maximum~~ maximize the amount of ~~time~~ unscheduled time remaining.

⊗ Algorithm:

GREEDY-ACTIVITY-SELECTOR(s, f)

$\Theta(n)$ { $n = s.length$
 $A = \{a_1\}$
 $k = 1$
for $m = 2$ to n
 if $s[m] \geq f[k]$
 $A = A \cup \{a_m\}$
 $k = m$
return A

for sort
total time = $\Theta(n \lg n) + \Theta(n)$
 = $\Theta(n \lg n)$

* Operation!

$$A = \{a_1, a_4, a_8, a_{11}\} \quad S = \{a_1, a_2, a_3, a_4, a_5, a_6, a_7, a_8, a_9, a_{10}, a_{11}\}$$

$$A' = \{a_4, a_8, a_{11}\} \longleftarrow S' = \{a_4, a_6, a_7, a_8, a_9, a_{11}\}$$

$$A'' = \{a_8, a_{11}\} \longleftarrow S'' = \{a_8, a_9, a_{11}\}$$
$$= \{a_9, a_{11}\}$$

$$A''' = \{a_{11}\} \longleftarrow S''' = \{a_{11}\}$$
$$S^{IV} = \{\emptyset\}$$

* Why it is greedy?

- it leaves as much opportunity as possible for the remaining activities to be scheduled.
- The greedy choice is the one that maximizes the amount of unscheduled time remaining.

* Why this algorithm is optimal?

- properties
 - satisfies the greedy choice property
 - has the optimal substructure property

* Greedy choice property:

⇒ Show there is an optimal solution that start with a greedy choice. ($k=1$)

⇒ Suppose $A \subseteq S$ in an optimal solution.

- Order the activities in A by finish time. The first activity in A is k .

⇒ if $k=1$, the schedule A begins with greedy choice.

⇒ if $k \neq 1$, show that there is an optimal solution B to S that begins with the greedy choice, activity 1.

⇒

$A'' = \{a_1, a_n\}$; $S'' = \{a_1, a_2, a_n\}$
↓
activity 1
if, $A'' = \{a_1, a_n\}$ also a optimal solution,
then its greedy choice.

⇒ Let, $B = A - \{k\} \cup \{1\}$

- Because $f_1 \leq f_k \rightarrow$ activities in B are disjoint
- since B has the same number of activities as A
- Thus, B is optimal.

Optimal Substructure:

⇒ Once the greedy choice of activity 1 is made, the problem reduces to finding an optimal solution for the activity selection problem over those activities in S that are compatible with activity 1.

- if A is optimal solution to S , the $A' = A - \{1\}$ is optimal to $S' = \{i \in S : s_i \geq f_1\}$

⇒ why?

⇒ if we find another optimal B' to S' with more activities than A'

then, adding activity 1 to B' would yield a solution B to S with more activity than A , will contradict the optimality of A

$$\begin{array}{l|l} A = \{a_1, a_4, a_6, a_{11}\} \Rightarrow 4 & \text{if, } B' = \{a_4, a_6, a_{11}, \square\} \Rightarrow 4 \\ A' = \{a_4, a_6, a_{11}\} \Rightarrow 3 & \text{is possible} \\ & \text{then } B = \{a_1, a_4, a_6, a_{11}, \square\} \Rightarrow 5 \end{array}$$

And $B > A$

But B' is not possible

then A is the optimal solution. (Proved) by contradict.

⇒ After each greedy choice is made, we are left with an optimization problem of the same ~~form~~ as form as the original problem.

- By induction on the number of choice made, making the greedy choice at every step produces an optimal solution.

Next class Quiz-2

on-6,7,8

L-14 / 31.03.2024 /

Quiz-2