

Chapter - 2

Determinants

$$\begin{aligned} (1) &= 1 \cdot 2 - 3 \cdot (-4) = 2 + 12 = 14 \\ (2) &= 1 \cdot 3 - 2 \cdot (-4) = 3 + 8 = 11 \\ (3) &= 1 \cdot (-4) - 1 \cdot 3 = -4 - 3 = -7 \end{aligned}$$

2.1

$A = \begin{bmatrix} 2 & -1 \\ 3 & -4 \end{bmatrix}$ is a matrix

$$\det(A) = |A| = \begin{vmatrix} 2 & -1 \\ 3 & -4 \end{vmatrix} = -8 + 3 = -5$$

⊗ $A = \begin{bmatrix} 3 & 1 & -4 \\ 2 & 5 & 6 \\ 1 & 4 & 8 \end{bmatrix}$

Minor of 3: $M_{11} = \begin{vmatrix} 5 & 6 \\ 4 & 8 \end{vmatrix} = 40 - 24 = 16$

$$M_{23} = \begin{vmatrix} 3 & 1 \\ 1 & 4 \end{vmatrix} = 12 - 1 = 11$$

$$M_{21} = \begin{vmatrix} 1 & -4 \\ 4 & 8 \end{vmatrix} = 8 + 16 = 24$$

$$M_{22} = \begin{vmatrix} 3 & -4 \\ 1 & 8 \end{vmatrix} = 24 + 4 = 28$$

Cofactor

$$C_{11} = (-1)^{1+1} M_{11} \rightarrow 1+1=2 = \text{even} = (+)$$

$$C_{21} = (-1)^{2+1} M_{21} \rightarrow 2+1=3 = \text{odd} = (-1)$$

$$C_{22} = (-1)^{2+2} M_{22} \rightarrow 2+2=4 = \text{even} = (+)$$

$$A = \begin{bmatrix} 3 & 1 & -4 \\ 2 & 5 & 6 \\ 1 & 4 & 8 \end{bmatrix}$$

$$C_{21} = -M_{21} = -24$$

$$C_{22} = M_{22} = 28$$

$$C_{23} = -M_{23} = -11$$

$$\det(A) = 2 \cdot C_{21} + 5 \cdot C_{22} + 6 \cdot C_{23}$$

$$= 2(-24) + 5(28) + 6(-11)$$

$$= 26$$

M

• Cofactor expansion method to find $\det(A)$

⊗ We can find $\det(A)$ by any row or column.

Row \times Row cofactor

or

Column \times Column cofactor

$$\begin{vmatrix} 8 & 2 & 8 \\ 3 & 1 & 0 \\ 2 & 0 & 0 \end{vmatrix} = A$$

⊗

Cofactor of row-2 \times entry of row 1 or 3 = 0.

$$\begin{vmatrix} 1 & 2 & 3 \\ 4 & 8 & 8 \\ 8 & 1 & 0 \end{vmatrix} = \begin{vmatrix} 4 & 8 & 8 \\ 1 & 2 & 3 \\ 8 & 1 & 0 \end{vmatrix}$$

$$\begin{vmatrix} 3 & 2 & 1 \\ 1 & 2 & 2 \\ 8 & 1 & 0 \end{vmatrix} = \begin{vmatrix} 3 & 2 & 1 \\ 1 & 2 & 2 \\ 8 & 1 & 0 \end{vmatrix}$$

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2.2/

⊗ Find determinant by row reduction:

$$A = \begin{pmatrix} 2 & 5 & -2 \\ 0 & 1 & 3 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\det(A) = 2 \cdot 1 \cdot 6 = 12$$

⊗

$$\begin{vmatrix} 2 & 3 & 4 \\ 5 & c & 1 \\ 3 & -4 & 2 \end{vmatrix} = - \begin{vmatrix} 5 & c & 1 \\ 2 & 3 & 4 \\ 3 & -4 & 2 \end{vmatrix}$$

⊗

$$\begin{vmatrix} 2 & c & 4 \\ 5 & c & 1 \\ 3 & -4 & 2 \end{vmatrix} = 2 \begin{vmatrix} 1 & 3 & 2 \\ 5 & c & 1 \\ 3 & -4 & 2 \end{vmatrix}$$

$$\textcircled{8} \quad A = \begin{bmatrix} 0 & 1 & 5 \\ 3 & -6 & 9 \\ 2 & 6 & 1 \end{bmatrix}$$

$$\det(A) = ?$$

$$\underline{\begin{array}{|c|} \hline 2 \cdot 3 \\ \hline \end{array}}$$

$$\begin{bmatrix} ab & ab & ab \\ ab & ab & ab \\ ab & ab & ab \end{bmatrix} = ?$$

$$\det(A+B) \neq \det(A) + \det(B)$$

$$\det(AB) = \det(A) \cdot \det(B)$$

$$\textcircled{9} \quad A = \begin{bmatrix} 1 & 3 \\ 5 & -4 \end{bmatrix}$$

$$A^{-1} = -\frac{1}{19} \begin{bmatrix} -4 & -3 \\ -5 & 1 \end{bmatrix} = \begin{bmatrix} \frac{4}{19} & \frac{3}{19} \\ \frac{5}{19} & \frac{1}{19} \end{bmatrix}$$

$$\det(A^{-1}) = \dots$$

$$\textcircled{*} \quad AA^{-1} = I$$

$$\Rightarrow \det(AA^{-1}) = \det(I) = 1$$

$$\Rightarrow \det(A) \cdot \det(A^{-1}) = 1$$

$$\textcircled{*} \quad A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$$

$$\text{matrix of cofactors} = \begin{bmatrix} C_{11} & C_{12} & C_{13} \\ C_{21} & C_{22} & C_{23} \\ C_{31} & C_{32} & C_{33} \end{bmatrix}$$

$$\text{Transpose of the matrix} = \begin{bmatrix} C_{11} & C_{21} & C_{31} \\ C_{12} & C_{22} & C_{32} \\ C_{13} & C_{23} & C_{33} \end{bmatrix} = \text{adj}(A).$$

Now,

$$A \cdot \text{adj}(A) = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \begin{bmatrix} C_{11} & C_{21} & C_{31} \\ C_{12} & C_{22} & C_{32} \\ C_{13} & C_{23} & C_{33} \end{bmatrix}$$

$$= \begin{bmatrix} \det(A) & 0 & 0 \\ 0 & \det(A) & 0 \\ 0 & 0 & \det(A) \end{bmatrix}$$

$$= \det(A) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$= \det(A) \cdot I$$

Now,

$$A \cdot \text{adj}(A) = \det(A) \cdot I$$

$$\Rightarrow A \cdot \frac{\text{adj}(A)}{\det(A)} = I$$

$$\therefore A^{-1} = \frac{\text{adj}(A)}{\det(A)}$$

$$\textcircled{*} \quad A = \begin{bmatrix} 3 & 2 & -1 \\ 1 & 6 & 3 \\ 2 & -4 & 0 \end{bmatrix}$$

Number of cofactors =

$$\begin{bmatrix} 12 & 6 & -16 \\ 4 & 2 & 16 \\ 12 & -10 & 16 \end{bmatrix}$$

$$\text{adj}(A) = \begin{bmatrix} 12 & 4 & 12 \\ 6 & 2 & -10 \\ -16 & 16 & 16 \end{bmatrix}$$

$$\begin{aligned} \det(A) &= 3 \cdot 12 + 2 \cdot 6 + (-1)(-16) \\ &= 36 + 12 + 16 \end{aligned}$$

$$= 64$$

$$A^{-1} = \begin{bmatrix} \frac{12}{64} & \frac{4}{64} & \frac{12}{64} \\ \frac{6}{64} & \frac{2}{64} & \frac{-10}{64} \\ \frac{-16}{64} & \frac{16}{64} & \frac{16}{64} \end{bmatrix}$$

25)

$$A = \begin{bmatrix} 4 & 5 & 0 \\ 11 & 1 & 2 \\ 1 & 5 & 2 \end{bmatrix}$$

$$A_1 = \begin{bmatrix} 2 & 5 & 0 \\ 3 & 1 & 2 \\ 1 & 5 & 2 \end{bmatrix} \quad \text{Replace with constant}$$

$$A_2 = \begin{bmatrix} 4 & 2 & 0 \\ 11 & 3 & 2 \\ 1 & 1 & 2 \end{bmatrix}$$

$$A_3 = \begin{bmatrix} 4 & 5 & 2 \\ 11 & 1 & 3 \\ 1 & 5 & 1 \end{bmatrix}$$

Cramen's rule:

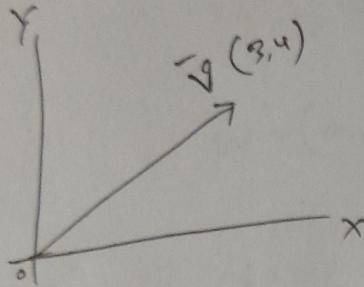
$$x = \frac{\det(A_1)}{\det(A)}$$

$$y = \frac{\det(A_2)}{\det(A)}$$

$$z = \frac{\det(A_3)}{\det(A)}$$

3.1

Chapter - 3 / Vector

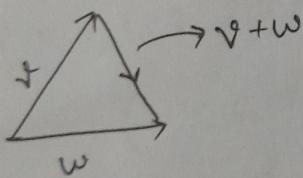


Magnitude / length / norm of the vector v : $\|v\| = \sqrt{1^2 + (-3)^2 + 4^2 + (-2)^2} = \sqrt{30}$

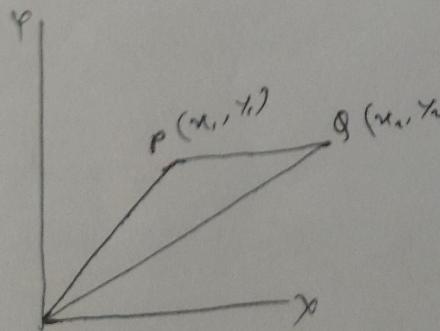
$$\bar{v} = (1, -3, 4, -2)$$

$$\|v\| = \sqrt{1^2 + (-3)^2 + 4^2 + (-2)^2}$$

$$= \sqrt{1+9+16+4} = \sqrt{30}$$



$v, 2v, \frac{1}{2}v \Rightarrow$ Parallel vector



$$\overrightarrow{OP}_1 = (x_1, y_1)$$

$$\overrightarrow{OP}_2 = (x_2, y_2)$$

$$\overrightarrow{PQ} = (x_2 - x_1, y_2 - y_1)$$

(*) $P_1(2, -1, 4)$

$P_2(7, 5, -8)$

$\vec{v} = \overrightarrow{P_1 P_2}$

$v = (7-2, 5+1, -8-4)$

$= (5, 6, -12)$

(*) \mathbb{R} : set of all real numbers.

$X = \{a, b\}$

$Y = \{1, 2, 3\}$

$X \times Y = \{(a, 1), (a, 2), (a, 3), (b, 1), (b, 2), (b, 3)\}$

$\mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}^2 \{ (a, b) : a \in \mathbb{R}, b \in \mathbb{R} \}$

Euclidean 2 space.

$\mathbb{R}^3 = \{ (a, b, c) : a \in \mathbb{R}, b \in \mathbb{R}, c \in \mathbb{R} \}$

Euclidean - 3 space

$$v = (1, 2, -3) \in \mathbb{R}^3$$

$$v = (1, -2, 3, 5) \in \mathbb{R}^4$$

$$w = (a, b, c, d) \in \mathbb{R}^4$$

$$v = w$$

$$(a, b, c, d) = (1, -2, 3, 5)$$

$$a = 1$$

$$b = -2$$

$$c = 3$$

$$d = 5$$

$$\textcircled{x} \quad v = (1, -2, 3, 5)$$

$$w = (-2, 5, 6, -2)$$

$$v + w = (-1, 3, 9, 3)$$

$$3v = (3, -6, 9, 15)$$

$$(1, 0, 0, 0) = v$$

$$3(1, 0, 0, 0) = 3v$$

3.2/

Unit vector

$$v = (5, -1, 3)$$

$$\|v\| = \sqrt{5^2 + (-1)^2 + 3^2} = \sqrt{25 + 1 + 9} = \sqrt{35}$$

\hat{v} ^{unit vector} = $\frac{v}{\|v\|} = \frac{5, -1, 3}{\sqrt{35}} = \left(\frac{5}{\sqrt{35}}, \frac{-1}{\sqrt{35}}, \frac{3}{\sqrt{35}} \right)$

Standard unit vector

In \mathbb{R}^3 , $i = (1, 0, 0)$, $j = (0, 1, 0)$, $k = (0, 0, 1)$

are standard unit vectors.

In \mathbb{R}^4 , $e_1 = (1, 0, 0, 0)$, $e_2 = (0, 1, 0, 0)$, $e_3 = (0, 0, 1, 0)$

$$e_4 = (0, 0, 0, 1)$$

are standard unit vectors

u, v

$$p\bar{p} = \text{dist } p_{\bar{p}} = \|u-v\|$$

$$\|u-v\| = d(u, v)$$

$$u = (1, 3, -2, 7)$$

$$v = (0, 7, 2, 2)$$

$$\|u-v\| = \|(1, -4, -4, 5)\|$$

$$= \sqrt{1^2 + (-4)^2 + (-4)^2 + 5^2}$$

$$= \sqrt{1 + 16 + 16 + 25}$$

Dot product / Euclidean inner product

$$u \cdot v = \|u\| \|v\| \cos \theta$$

$$= u_1 v_1 + u_2 v_2$$

$$u = (u_1, u_2)$$

$$u = (\cancel{2}, -3, 1) \quad (2, -3, 1)$$

$$v = (v_1, v_2)$$

$$v = (1, 4, -4)$$

$$\cos \theta = ?$$

$$u \cdot v = (2, -12, -4)$$

$$= 2 - 16 = -4$$

$$\|u\| = \sqrt{4+9+1} = \sqrt{14}$$

$$\|v\| = \sqrt{1^2 + (-4)^2 + 4^2} = \sqrt{37} \quad (v \cdot v) / \|v\|^2 = \|v - u\|^2$$

$$\cos \theta = \frac{u \cdot v}{\|u\| \|v\|}$$

$$(2, 3, -1) \sim u$$

$$(3, 8, (0, 0)) \sim v$$

$$u \cdot v = 0 \Rightarrow u \perp v$$

$$\|(2, 3, -1) - (3, 8, (0, 0))\| = \|v - u\|$$

u orthogonal to v : $u \perp v$

$$22 + 21 + 21 + 1 = 65$$

bilangan prima adalah faktor bilangan bulat

$$\text{Bilangan prima } \|v\| - \|u\| = v, u$$

$$v, u \in \mathbb{R}^n$$

$$(2, 3, -1) \cdot (3, 8, (0, 0)) = 0 \quad (v, u) = 0$$

$$(2, 3, -1) \cdot (2, 3, -1) = 1 \quad (v, v) = 1$$

$$(2, 3, -1) \cdot (3, 8, (0, 0)) = 65 \quad (v, u)$$

L-11 / 06.07.2022 /

3.3.1

Orthogonality $(s, i, p) \cdot n = 0, (s, i, p) \cdot l = 0$

$u \cdot v = 0 \Rightarrow$ Dot product

Euclidean inner product



$$u = (-2, 3, 1, 4)$$

in \mathbb{R}^3

$$v = (1, 2, 0, -1)$$

$$\begin{aligned} u \cdot v &= (-2 + 6 + 0 - 4) \\ &= 0 \end{aligned}$$

$\therefore u \perp v$

$$i, j, k \text{ are } \left| \begin{array}{l} i \cdot j = (0+0+0)=0 \\ j \cdot k = 0 \\ k \cdot i = 0 \end{array} \right.$$

$$i = (1, 0, 0)$$

$$j = (0, 1, 0)$$

$$k = (0, 0, 1)$$

$$i \cdot i = 1$$

$$j \cdot j = 1$$

$$k \cdot k = 1$$

vector component of u along a

$$\text{Proj}_a u = \frac{u \cdot a}{\|a\|^2} a$$

vector component of u orthogonal to u

$$u - \text{Proj}_a u$$

Example - 5 /

$$u = (2, -1, 3), a = (4, -1, 2)$$

$$\text{Proj}_a u = \frac{u \cdot a}{\|a\|^2} a$$

$$= \frac{8+1+6}{4^2 + (-1)^2 + 2^2} a$$

$$= \frac{15}{21} (4, -1, 2)$$

$$= \frac{5}{7} (4, -1, 2)$$

$$= \left(\frac{20}{7}, \frac{-5}{7}, \frac{10}{7} \right)$$

vector component of u orthogonal to a

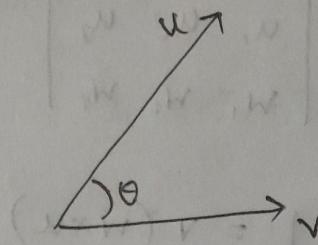
$$u - \text{Proj}_a u = (2, -1, 3) - \left(\frac{20}{7}, \frac{-5}{7}, \frac{10}{7} \right)$$

$$= \left(2 - \frac{20}{7}, -1 + \frac{5}{7}, 3 - \frac{10}{7} \right)$$

$$= \left(\frac{-6}{7}, \frac{-2}{7}, \frac{11}{7} \right)$$

3.5 /

Cross Product



$$\begin{vmatrix} u & v & w \\ u & v & w \\ u & v & w \end{vmatrix} = (w \times v) \cdot u$$

$u \times v$ is a vector

$$= \|u\| \|v\| \sin \theta \hat{n}$$

$$\boxed{u \perp (u \times v)}$$

$$\boxed{v \perp (u \times v)}$$

$$\boxed{u \cdot (u \times v) = 0}$$

$$\boxed{v \cdot (u \times v) = 0}$$

$$\begin{matrix} u \\ v \\ w \end{matrix}$$

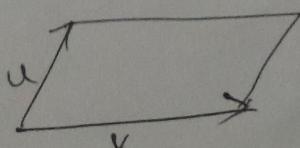
$$(w \times v) \cdot w = (w \times w) \cdot v = (w \times v) \cdot u$$

$$u = (u_1, u_2, u_3) = u_1 i + u_2 j + u_3 k$$

$$v = (v_1, v_2, v_3) = v_1 i + v_2 j + v_3 k$$

$$\bar{u} \times \bar{v} = \begin{vmatrix} i & j & k \\ u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \end{vmatrix} = i \begin{vmatrix} u_2 & u_3 \\ v_2 & v_3 \end{vmatrix} - j \begin{vmatrix} u_1 & u_3 \\ v_1 & v_3 \end{vmatrix} + k \begin{vmatrix} u_1 & u_2 \\ v_1 & v_2 \end{vmatrix}$$

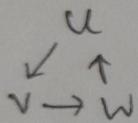
④ $\|u \times v\| = \text{area of the parallelogram determined by } u \text{ and } v$



⊗ u, v, w

$$u \cdot (v \times w) = \begin{vmatrix} u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \\ w_1 & w_2 & w_3 \end{vmatrix} = - \begin{vmatrix} v_1 & v_2 & v_3 \\ u_1 & u_2 & u_3 \\ w_1 & w_2 & w_3 \end{vmatrix}$$
$$= \begin{vmatrix} v_1 & v_2 & v_3 \\ w_1 & w_2 & w_3 \\ u_1 & u_2 & u_3 \end{vmatrix} = v \cdot (w \times u)$$

⊗ $\|u \cdot (v \times w)\| =$



$$\|u \cdot (v \times w)\| = \|u\| \cdot \|v \times w\|$$

$$(v \times w) \perp u$$
$$(v \times w) \perp v$$

$$u \cdot (v \times w) = v \cdot (w \times u) = w \cdot (u \times v)$$

$|u \cdot (v \times w)| = \text{volume of the parallelogram determined}$

by u, v, w .

$$\|u \cdot (v \times w)\| = \|u\| \cdot \|v \times w\| = \begin{vmatrix} u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \\ w_1 & w_2 & w_3 \end{vmatrix} = v \times w$$

and $v \times w$ is perpendicular to u (the normal to $u \times v \times w$)

L-12 / 18-07-2022

Electricity

For the point A,

$$I_1 = I_2 + I_3$$

$$7I_1 + 3I_2 - 30 = 0$$

$$11I_2 - 50 - 3I_3 = 0$$

1)

$$\therefore I_1 = I_2 + I_3$$

$$\Rightarrow I_1 - I_2 - I_3 = 0$$

$$\therefore 13I_2 + 5I_3 + 8 = 0$$

$$\Rightarrow 5I_1 + 13I_2 = -8$$

$$\therefore -3 + 14I_3 - 13I_2 = 0$$

$$\Rightarrow -13I_2 + 14I_3 = 3$$

∴ Augmented matrix:

$$\left[\begin{array}{cccc} 1 & -1 & -1 & 0 \\ 5 & 13 & 0 & -8 \\ 0 & -13 & 14 & 3 \end{array} \right]$$

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$$\therefore I_3 = I_2 + I_1$$

$$\Rightarrow I_1 + I_2 - I_3 = 0$$

$$\therefore 6 - 2I_1 + 2I_2 = 0$$

$$\Rightarrow -2I_1 + 2I_2 = -6$$

$$\therefore 8 - 4I_3 - 2I_2 = 0$$

$$\Rightarrow -2I_2 - 4I_3 = -8$$

$$\left| \begin{array}{cccc} 1 & 1 & -1 & 0 \\ -2 & 2 & 0 & -6 \\ 0 & -2 & -4 & -8 \end{array} \right|$$

Einheitsstufenform:

$$\left| \begin{array}{cccc} 0 & 1 & -1 & 0 \\ 0 & 0 & 2 & 3 \\ 0 & 0 & 0 & 0 \end{array} \right|$$

$$0 = 0 \cdot 1 + 0 \cdot 2 + 0 \cdot 0$$

$$0 = 0 \cdot 1 - 0 \cdot 2 + 0 \cdot 0$$

$$0 = 0 \cdot 1 + 0 \cdot 2 + 0 \cdot 0$$

(5)

4.1

Vector Space

Let V be a non-empty set of objects.

Two operations, addition and scalar multiplication, are defined in V .

$V = \mathbb{R}$ is a vector space

$V = \mathbb{R}^n$ is a vector space; $n \in \mathbb{N}$

$$V = \left\{ \begin{bmatrix} a & b \\ c & d \end{bmatrix} : a, b, c, d \in \mathbb{R} \right\}$$

$= M_{22} \rightarrow$ Notation.

Exercise:

1] a) $u = (-1, 2)$

$$v = (3, 4)$$

$$k = 3$$

$$u+v = (-1+3, 2+4) = (2, 6)$$

$$ku = (0, k u_2) = (0, 3 \cdot 4) = (0, 6)$$

e)

$$1u = (1 \cdot u_1, 1 \cdot u_2) = (0, u_2) \neq u$$

since $u_1 \neq 0$

Axiom 10 is fails and hence that V is not a vector space.

$M_{22} \Rightarrow 2 \times 2$ matrix of real numbers

$P_2 \Rightarrow$ all polynomial equation; degree ≤ 2 .



V , vector space, and $W \subset V$

$W \subset V$ is a subspace of V ,

$$\text{i) } u, v \in W \Rightarrow u+v \in W$$

$$\text{ii) } k, u \text{ scalar, } u \in W \Rightarrow ku \in W$$



x -axis is a subspace of W



$$W = \{a+bn+cn^2 : a, b, c \in \mathbb{Z}\}$$

$$u = 2 + 3n + 7n^2 \in W$$

$$\frac{1}{2}u = 1 + \left(\frac{3}{2}\right)n + \left(\frac{7}{2}\right)n^2 \notin W$$

rational

W is not subspace of P_2

\otimes V is vector in V and

$$w = k_1 u_1 + k_2 u_2 + \dots + k_n u_n$$

where,

$u_1, u_2, \dots, u_n \in V$ and k_1, k_2, \dots, k_n are scalar

\otimes $V = \mathbb{R}^2$

$$w \in V \Leftrightarrow w \in V, V \subseteq W$$

$$u = (1, -1)$$

$$v = (2, 1) \in \mathbb{R}^2$$

$$\Rightarrow 2u + 3v$$

$$= 2(1, -1) + 3(2, 1)$$

$$= (2, -2) + (6, 3)$$

$$= (8, 1) \in \mathbb{R}^3$$

\otimes

$$S = \{w_1, w_2, w_3\}$$

$$W \ni w_1 + w_2 + w_3 = w$$

w = set of all possible linear combination if the vector is S .

= spanned by S ,

$$w = \text{span}(S)$$

⊗ $V = \mathbb{R}^3$

standard unit vector in \mathbb{R}^3 : $\overset{\text{unit}}{\rightarrow} \mathbf{e}_1 = (1, 0, 0), \mathbf{e}_2 = (0, 1, 0), \mathbf{e}_3 = (0, 0, 1)$

$$S = \{ \mathbf{e}_1 = (1, 0, 0), \mathbf{e}_2 = (0, 1, 0), \mathbf{e}_3 = (0, 0, 1) \}$$

$$k_1 \mathbf{e}_1 + k_2 \mathbf{e}_2 + k_3 \mathbf{e}_3 = (k_1, k_2, k_3) = (x, y, z)$$

Let,

$$2\mathbf{e}_1 + 3\mathbf{e}_2 + 4\mathbf{e}_3 = (2, 3, 4) \in \mathbb{R}^3$$

$$(2, 3, 4) = (1, 0, 0) + (0, 1, 0) + (0, 0, 1) =$$

⊗

$$P_2 = \text{span}\{1, n, n^2\}$$

standard unit vector:

$$P_2 = \text{span}\{1, n, n^2\}$$

$$P_3 = \text{span}\{1, n, n^2, n^3\}$$

$$P_n = \text{span}\{1, n, n^2, n^3, \dots, n^n\}$$

⊗ Standard unit matrix

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = A$$

$$M_{22} = \text{span} \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}$$

4.2

$v_1 = (1, 1, 2)$, $v_2 = (1, 0, 1)$, $v_3 = (2, 1, 3)$ span \mathbb{R}^3 ?

Take any vector $(a, b, c) \in \mathbb{R}^3$

Set,

$$(a, b, c) = k_1 v_1 + k_2 v_2 + k_3 v_3$$

$$= k_1 (1, 1, 2) + k_2 (1, 0, 1) + k_3 (2, 1, 3)$$

$$= (k_1, k_1, 2k_1) + (k_2, 0, k_2) + (2k_3, k_3, 3k_3)$$

$$= (k_1 + k_2 + 2k_3, k_1 + 0 + k_2, 2k_1 + k_2 + 3k_3)$$

\Rightarrow

$$k_1 + k_2 + 2k_3 = a$$

$$k_1 + k_2 = b$$

$$2k_1 + k_2 + 3k_3 = c$$

System of linear equation

Co-efficient matrix,

$$A = \begin{bmatrix} 1 & 1 & 2 \\ 1 & 0 & 1 \\ 2 & 1 & 3 \end{bmatrix}$$

$$\det(A) = \begin{vmatrix} 1 & 1 & 2 \\ 1 & 0 & 1 \\ 2 & 1 & 3 \end{vmatrix} = 1(0-1) - 1(2-1) + 2(1-0) \\ = (1-1) - (2-1) = 0 \quad (1-1) = W, (2-1) = W \\ = -1 - 1 + 2 \\ = 0 \quad (0,0) = W \cdot 0 = W \cdot 0$$

$\det(A)$ is zero. So, system has no solution.

So, k_1, k_2, k_3 do not exist.

So, v_1, v_2, v_3 do not span \mathbb{R}^3 .

$$(1,0,0) = \underline{v_1} \quad (0,1,0) = \underline{v_2} \quad (0,0,1) = \underline{v_3}$$

4.3

Linear Independence

$$\underline{(0,0,0)} = \underline{(1,0,0)} + \underline{(0,1,0)} + \underline{(0,0,1)}$$

$$v_1 = (2,3), v_2 = (4,6)$$

$$(0,0,0) = (1,1,1)$$

Relation:

$$v_2 = 2v_1$$

$$2v_1 - v_2 = (0,0)$$

Hence, scalars,

$$2-1=1 \neq 0$$

So, vectors v_1, v_2 are dependent.

④ $w_1 = (2, 3), w_2 = (5, -1)$

$$0 \cdot w_1 + 0 \cdot w_2 = (0, 0)$$

No, other scalen can't make it zero.

So, vector w_1, w_2 are independent.

⑤ In \mathbb{R}^3

$$e_1 = (1, 0, 0) \quad e_2 = (0, 1, 0) \quad e_3 = (0, 0, 1)$$

Take $k_1 e_1 + k_2 e_2 + k_3 e_3 = 0$

$$k_1(1, 0, 0) + k_2(0, 1, 0) + k_3(0, 0, 1) = (0, 0, 0)$$

$$\Rightarrow (k_1, k_2, k_3) = (0, 0, 0)$$

$\therefore \begin{cases} k_1 = 0 \\ k_2 = 0 \\ k_3 = 0 \end{cases}$ } only one solution is zero. So, they are linearly independent.

$\therefore \{e_1, e_2, e_3\}$ is a linear independent set.

(*) In P_2

(P-P)

$\{1, x, x^2\}$ is linearly independent.

V not true?

$$k_1 + k_2x + k_3x^2 = 0$$

$$\Rightarrow k_1 = 0, k_2 = 0, k_3 = 0$$

(*) In homogenous system, if determinate is 0 then they

are dependent, else independent.

(*) Linear homogenous system having equation more than

variable, then system has only zero solution. So, they

are linearly independent.

$$\left\{ \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \right\}$$

[4.4]

S Basis for V

\Rightarrow S is linearly independent

\Rightarrow S spans V

\otimes R^3 is standard basis if every component in R

$S = \{v_1, v_2, v_3\}$ is independent

then it is spanning as well

R^3

standard unit basis for $R^3 = \{e_1, e_2, e_3\}$

standard basis for P_2 : $\{1, x, x^2\}$

$M_{22} : \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}$

(*)

Example-9/

$$S = \{ v_1 = (1, 2, 1), v_2 = (2, 1, 0), v_3 = (3, 3, 4) \}$$

is a basis for \mathbb{R}^3

$$v = (5, -1, 9) \quad (v)_S = ?$$

Take, $v = c_1 v_1 + c_2 v_2 + c_3 v_3$

$$(5, -1, 9) = c_1 (1, 2, 1) + c_2 (2, 1, 0) + c_3 (3, 3, 4)$$

$$= (c_1 + 2c_2 + 3c_3, 2c_1 + c_2 + 3c_3, c_1 + 4c_3)$$

$$\therefore c_1 + 2c_2 + 3c_3 = 5$$

$$2c_1 + c_2 + 3c_3 = -1$$

$$c_1 + 4c_3 = 9$$

Augmented matrix.

$$\left[\begin{array}{cccc} 1 & 2 & 3 & 5 \\ 2 & 1 & 3 & -1 \\ 1 & 0 & 4 & 9 \end{array} \right]$$

solve it.

by solving,

$$c_1 = 1$$

$$c_2 = -1$$

$$c_3 = 2$$

$$\therefore (\mathbf{v})_s = (1, -1, 2)$$

Q In \mathbb{R}^3

$$\mathbf{v} = (5, 2, -3)$$

$S = \{(1, 0, 0), (0, 1, 0), (0, 0, 1)\}$ basis for \mathbb{R}^3

$$(\mathbf{v})_s = ?$$

$$(5, 2, -3) = c_1(1, 0, 0) + c_2(0, 1, 0) + c_3(0, 0, 1)$$

$$= (c_1, c_2, c_3)$$

$$\therefore c_1 = 5$$

$$c_2 = 2$$

$$c_3 = -3$$

$$\therefore (\mathbf{v})_s = (5, 2, -3)$$

$$\therefore (\mathbf{v})_s = \mathbf{v} \quad (\text{Theorem})$$

(proved)

4.5Dimension of a vector space

$$\dim(\mathbb{R}^3) = 3$$

dimension = Positive integers

$$P_2 = \{1, x, x^2\}$$

$$\dim(P_2) = 3$$

$$\dim(M_{2,2}) = 4 = 2 \times 2$$

$$\dim(P_n) = n+1$$

$$= \{1, x, x^2, \dots, x^n\}$$

Theorem 4.5.2

Let V be a finite-dimensional vector space, and let

$$\{v_1, v_2, \dots, v_n\}$$
 be any basis.

- If a set has more than n vectors, then it is linearly dependent.
- If a set has fewer than n vectors, then it does not span V .

Theorem 4.5.3

Let S be a nonempty set of vectors in a vector space V .

a) If S is a linearly independent set, and if v is a vector in V that is outside of $\text{span}(S)$, then the set $S \cup \{v\}$ that results by inserting v into S is still linearly independent.

b) If v is a vector in S that is expressible as a linear combination of other vectors in S , and if $S - \{v\}$ denotes the set obtained by removing v from S , then $S - \{v\}$ span the same space; that is,

$$\text{span}(S) = \text{span}(S - \{v\})$$

* Set of non zero solution of a homogenous system then
the set is a subspace of this \mathbb{R}^n space.

Example - 3

$$x_1 = -s-t$$

$$x_2 = s$$

$$x_3 = -t$$

$$x_4 = 0$$

$$x_5 = t$$

$$(x_1, x_2, x_3, x_4, x_5) = (-s-t, s, -t, 0, t)$$

$$\leftarrow (-s, s, 0, 0, 0) + (-t, 0, -t, 0, t)$$

$$\leftarrow s(-1, 1, 0, 0, 0) + t(-1, 0, -1, 0, 1)$$

$$(x_1, x_2, x_3, x_4, x_5) = s\mathbf{v}_1 + t\mathbf{v}_2$$

$\mathbf{v}_1, \mathbf{v}_2$ is span \mathbb{R}^5

$\{\mathbf{v}_1, \mathbf{v}_2\}$ is a basis for the solution space and

dimension for the solution space 2.