ACM 模板

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目录

1. 数学

```
/*================================================================================*\
  1)    线性筛素数
\*================================================================================*/
const int N = 25600000;
bool a[N]; //判断是否为合数
int p[N/2],num;
void prime(){
   memset(a, 0, sizeof(a));
   int i, j;
    num = 0;
   for(i = 2; i < N; ++i){
      if(a[i]==0) p[num++] = i;
       for(j = 0; j<num && i*p[j]<N ; ++j){
           a[i*p[j]] = 1;
           if(i%p[j]==0) break;
       }
   }
}
/*================================================================================*\
  2)    GCD 最大公约数
\*================================================================================*/
int gcd(int a, int b) {
   return b ? gcd(b, a % b) : a;
}
/*================================================================================*\
  3)    com(n,r)%mod  和  n!快速质因数分解
\*================================================================================*/
//这里直接用a*b%c,而没有用模板中的函数product_mod 和 product_mod是为了提高效率
typedef long long lld;
const int N = 2000000;
bool a[N];
int p[N/2],num,n1[N/2],n2[N/2],n3[N/2];
void prime();
//-----------------------以上为引用模板内其他函数----------------------//
template<class Type>
Type pow(Type a,Type b,Type c){
   Type r=1;
   while(b){
      if(b & 1)r=r*a%c;
      a=a*a%c;
      b>>=1;
   }
   return r;
}
void div(int *list,int n){
   int i,tmp;
```

```
    for (i=0;i<num;i++) list[i]=0;
    for (i=0;i<num && p[i]<=n;i++){
        tmp=n;
        while (tmp/p[i]){list[i]+=tmp/p[i];tmp/=p[i];}
    }
}
lld com(lld n,lld r,int mod){
    lld res=1,temp;
    div(n1,n);  div(n2,r);  div(n3,n-r);
    for(int i=0;i<num;i++){
        n1[i]-=n2[i]+n3[i];
        if(n1[i]==0)continue;
        temp=pow(p[i],n1[i],mod);
        res=(res*temp)%mod;
    }
    return res;
}
int main(){
    prime();
    ……
}
/*=============================================================================*\
  4)   组合数(n 最大取 61)(若用 int 型 n 最大取 33)
\*=============================================================================*/
long long com(int n,int r){
    if(r > n)return 0;
    if(n-r < r)r=n-r;
    int i,j;
    long long s=1;
    for(i=0,j=1;i<r;i++){
        s*=n-i;
        for(;j<=r && s%j==0;j++)s/=j;
    } return s;
}
/*=============================================================================*\
  5)   double 型组合数(n 最大可取 1029,一般 6 位精确值)
\*=============================================================================*/
double lnc(int n,int r){ //求ln(c(n,r))
    if(r > n-r)r = n-r;
    double s1=0,s2=0;
    for(int i=0;i<r;i++) s1 += log((double)n-i);
    for(int i=2;i<=r;i++) s2 += log((double)i);
    return s1-s2;
}
double com(int n,int r){
    if(r>n)return 0;
    return exp(lnc(n,r));
}
```

```
/*================================================================================*\
  6)   a*b % c
\*================================================================================*/
template<class Type>
Type product_mod(Type a,Type b,Type c){
    Type r=0;
    while(b>0){
       if(b & 1)r=(r+a)%c;
       a=(a+a)%c;
       b>>=1;
    } return r;
}
/*================================================================================*\
  7)   a^b % c
\*================================================================================*/
template<class Type>
Type product_mod(Type a,Type b,Type c);
//----------------------以上为引用模板内其他函数----------------------//
template<class Type>
Type power_mod(Type a,Type b,Type c){
   Type r=1;
   while(b){
       if(b & 1)r=product_mod(r,a,c);
       a=product_mod(a,a,c);
       b>>=1;
   } return r;
}
/*================================================================================*\
  8)   素数测试
\*================================================================================*/
//3e+14以内100%正确，(long long型/2)之内
//也应该是正确的，不过没有找到理论依据
template<class Type>
Type product_mod(Type a,Type b,Type c);
template<class Type>
Type power_mod(Type a,Type b,Type c);
//----------------------以上为引用模板内其他函数----------------------//
bool isprime(long long n){
    if(n<2)return false;
    if(n==2)return true;
    if(n%2==0)return false;
   int i,j,k=0;
   int p[]={2,3,5,7,11,13,17,23,37,51,61};
   long long a,m=n-1;
    while(m % 2 == 0)m>>=1,k++;
    for(i=0;i<11;i++){
        if(p[i]>=n)return true;
        a = power_mod((long long)p[i],m,n);
```

```
        if(a==1)continue;
        for(j = 0; j < k; j ++){
            if(a==n-1)break;
            a = product_mod(a,a,n);
        }
        if(j==k)return false ;
    }  return true;
}
/*=============================================================================*\
  9)   整数的因子分解
\*=============================================================================*/
#intlude<cstdlib>
using namespace std;
Type gcd(Type a,Type b);
Type product_mod(Type a,Type b,Type c);
bool isprime(long long n);
//----------------------以上为引用模板内其他函数----------------------//
typedef long long lld;
lld pollard_rho(lld c,lld n){
   int i=1;
   lld x=rand()%n, y=x;
   int k=2;
   do{
      i++;
      lld d=gcd(n+y-x,n);
      if(d>1 && d<n)return d;
      if(i==k)y=x,k*=2;
      x=(product_mod(x,x,n)+n-c)%n;
   }while(y!=x);
   return n;
}
lld rho(lld n){
   if(isprime(n))return n;
   while(1){
      lld t = pollard_rho(rand()%(n-1)+1,n);
      if(t<n){
         lld a=rho(t),b=rho(n/t);
         return a<b ? a:b;
      }
   }
}
/*=============================================================================*\
  10)  所有数位相加
\*=============================================================================*/
int dig(int x){
   if(x==0)return 0;
   return (x+8)%9+1;
}
```

```
/*==========================================================================*\
  11)  统计 x 二进制表示中 1 的个数
\*==========================================================================*/
template<class Type>
int count(Type x){
    Type n=x>>1;
    while(n){x-=n;n>>=1;}
    return x;
}
/*==========================================================================*\
  12)  数值转换为 char* (十进制转换)
\*==========================================================================*/
//将十进制数v转换成2至36进制的数，结果以
//字符串形式存放入dest中，r为进制数，函数//返回字符串长度
//注意v为0时，返回字符串长度为0
template<class Type>
int my_itoa(Type v,char *dest,int r){
    if(v==0){
       dest[0]='0';dest[1]='\0';
       return 0;
    }
    int len=my_itoa(v/r,dest,r);
    int t=v%r;
    if(t<10)dest[len++]='0'+t;
    else dest[len++]='a'+t-10;
    dest[len]='\0';
    return len;
}
/*==========================================================================*\
  13)  约瑟夫环问题
   n 个人(编号 1…n)围成一圈，从第 k 个人开始，从 1 报数，报到 m 出列，下一个人继续从 1 报数
\*==========================================================================*/
//----------------------数学方法----------------------//
方法一：（可以求得每次出列者编号）
int i=0,n,m,k,p;
scanf("%d%d%d",&k,&n,&m);
while(++i<=n){//每次计算第i个出列者的编号
    p=i*m;
    while(p>n){ p=p-n+(p-n-1)/(m-1);}
    printf("%d\n",(p+n+k-2)%n+1);
}
方法二：(只能求得最后剩下那人的编号，但效率较高)
int n,m,k,p;
scanf("%d%d%d",&k,&n,&m);
p=0;//运算时是从0开始数，数到m-1
for(int i=2;i<=n;i++)p=(p+m)%i;
printf("%d\n",(p+n+k)%n+1);
```

```
/*================================================================================*\
  14)  生成下一个二进制中有 k 个 1 的数
\*================================================================================*/
int nxt(int x) {
   int b = x & -x;
   int t = x + b;
   int c = t ^ x;
   int m = (c >> 2) / b;
   int r = t | m;
   return r;
}
/*================================================================================*\
  15)  Nim 积
\*================================================================================*/
int nimpow(int x, int y) { // x=2^a;
   if (y < 2) return y ? x : 0;
   int m, b;
   for (b = 0, m = 2; x >= m; )
      m = 1 << (1 << ++b);
   m = 1 << (1 << --b);
   int p = x>>(1<<b);
   int s = y>>(1<<b), t = y&(m-1);
   int d1 = nimpow(p, s);
   int d2 = nimpow(p, t);
   return ((d1 ^ d2) << (1 << b)) ^ nimpow(m >> 1, d1);
}
int nimx(int x, int y) {
   if (x < y) return nimx(y, x);
   if (y < 2) return y ? x : 0;
   int m, b;
   for (b = 0, m = 2; x >= m; )
      m = 1 << (1 << ++b);
   m = 1 << (1 << --b);
   int p = x>>(1<<b), q = x&(m-1);
   int s = y>>(1<<b), t = y&(m-1);
   int c1 = nimx(p, s);
   int c2 = nimx(p, t) ^ nimx(q, s);
   int c3 = nimx(q, t) ^ ((c1 ^ c2) << (1 << b));
   return c3 ^ nimpow(m >> 1, c1);
}
*================================================================================*\
  16)  稳定婚姻问题
\*================================================================================*/
const int N = 1010;
int n, resm[N], resw[N];
int man[N][N], woman[N][N];
int chose[N];
```

```
void stableMatch() {
    queue<int> q;
    memset(chose, 0, sizeof(chose));
    memset(resw, -1, sizeof(resw));
    for (int i = 0; i < n; ++i) q.push(i);
    while (!q.empty()) {
        int u = q.front(); q.pop();
        int v = man[u][chose[u]++];
        if (resw[v] == -1 || woman[v][resw[v]] > woman[v][u]) {
            if (resw[v] != -1) q.push(resw[v]);
            resm[u] = v;
            resw[v] = u;
        } else {
            q.push(u);
        }
    }
}

void solve() {
    int u;
    scanf("%d", &n);
    for (int i = 0; i < n; ++i)
        for (int j = 0; j < n; ++j) {
            scanf("%d", &u); man[i][j] = u - 1; //读入男士对女士的偏好次序
        }
    for (int i = 0; i < n; ++i)
        for (int j = 0; j < n; ++j) {
            scanf("%d", &u); woman[i][u - 1] = j; //读入女士对男士的偏好次序
        }
    stableMatch();
    for (int i = 0; i < n; ++i)
        printf("%d\n", resm[i] + 1);  // 输出男士有利的稳定婚姻方案
}
/*================================================================================*\
  17)  三分法(凸性函数求极值)
\*================================================================================*/
const double EPS=1e-10;
double MIN, MAX;
double cal(double x){
    /* 根据题目的意思计算 */
}

double solve(){
    double left=MIN,right=MAX;
    double mid1,mid2;
    while(left+EPS<right){
        mid1=left+(right-left)*0.381966;
        mid2=left+(right-left)*0.618034;
```

```
        if(cal(mid1)<cal(mid2)) right=mid2; //求极小值
    // if(cal(mid1)>cal(mid2)) right=mid2; //求极大值
        else left=mid1;
    }
    return cal(left);
}

*==========================================================================*\
  18)  线性规划(watashi 的模板)
\*==========================================================================*/
const double EPS = 1e-9;
const int MAX_N = 128;
const int MAX_M = 128;
typedef double LPMAT[MAX_M + 1][MAX_M + MAX_N + 1];
typedef double LPRET[MAX_N + 1];

inline bool d_zero(double x) {
    return fabs(x) < EPS;
};
inline bool d_less(double x, double y) {
    return x + EPS < y;
};
/** 线性规划.
 * 求 b1 x1 + b2 x2 + ... + bn xn 在 x1, x2, ..., xn >= 0 时的最大值
 * m 为限制条件方程数, n 为变量数目
 * 限制条件为
 *  a_i1 x1 + a_i2 x2 + ... + a_in xn <= ci (1 <= i <= m, ci >= 0 (!!!))
 * mat 传入系数矩阵
 * mat[0] 表示目标方程, 即 mat[0][1..n] 为 b1 .. bn
 * mat[1..m]表示限制方程, mat[1..m][0] 表示 c1, c2, ... cm
 * 其余 mat[i][j] 表示 a[i][j]
 * 注意函数会改变 mat 的值
 *   i \ j 0    1    2   .... n
 *   0     0   b1   b2   .... bn
 *   1     c1  a11  a12  .... a1n
 *   ..............................
 *   m     cm  am1  am2  .... amn
 * 找到解返回 true, ans 返回最大值, ret[1..n] 分别返回 x1..xn 的取值
 * 如果不存在最大值返回 false
 * 不可能无解, 因为 x1 = x2 = ... = xn = 0 必为一组解
 */
bool lp(int m, int n, LPMAT mat, double& ans, LPRET ret) {
    static int p[MAX_M + 1], q[MAX_M + MAX_N + 1];
    static double trial[MAX_M + MAX_N + 1];
    int i, j, k, l, s, h;
    double z, zbuf;

    mat[0][0] = 0;
```

```
    for (i = 0; i <= m; i++) {
        for (j = n; j > 0; j--)
            mat[i][j + m] = (i == 0) ? -mat[i][j] : mat[i][j];

        for (j = m; j > 0; j--)
            mat[i][j] = (i == j) ? 1 : 0;

        p[i] = q[i] = i;
    }

    bool flag = true;
    while (flag) {
        flag = false;
        for (j = m + n; j > 0; j--) {
            if (!d_less(mat[0][j], 0))
                continue;
            for (i = 1, l = 0; i <= m; i++) {
                if (!d_less(0, mat[i][j]))
                    continue;
                if (l == 0) {
                    l = i, s = 0;
                } else {
                    for (h = 0; ; h++) {
                        if (h == s)
                            trial[s++] = mat[l][h] / mat[l][j];
                        z = mat[i][h] / mat[i][j];
                        if (trial[h] != z) break;
                    }
                    if (d_less(z, trial[h]))
                        l = i, trial[h] = z, s = h + 1;
                }
            }
            if (l == 0) return false;  // The maximum is infinite

            for (k = 0, z = mat[l][j]; k <= m + n; k++)
                if (!d_zero(mat[l][k]))
                    mat[l][k] = mat[l][k] / z;

            for (i = 0; i <= m; i++) {
                if (i == l)
                    continue;
                for (k = 0, z = mat[i][j]; k <= m + n; k++)
                    mat[i][k] = (k == j || d_zero(zbuf = mat[i][k] - z *
mat[l][k])) ?  0 : zbuf;
            }
            q[p[l]] = 0, p[l] = j, q[j] = l;
            flag = true;
            break;
```

```
        };
    };
    ans = mat[0][0];

    for (i = 1, j = m + 1; j <= m + n; i++, j++)
        ret[i] = (q[j]) ? mat[q[j]][0] : 0;

    /* 此处可用来计算 (u1, u2, ..., um) 其中 ui >= 0, 使得在
     * a1j u1 + a2j u2 + ... + amj um >= bj (1 <= j <= n)
     * 的限制条件下 c1 u1 + c2 u2 + ... + cm um 最大.
     * 当函数返回 false 的时候此处无解. */
    //for (j = 1; j <= m; j++)
    //    u[i] = mat[0][j];

    return true;
}
```

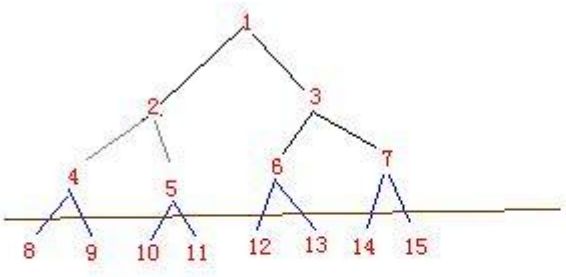
2． 数据结构

```
/*================================================================================*\
  1)    二分查找
\*================================================================================*/
//a[]已经有序(数值可以不唯一)
//在[low,high)范围内查找值v
//返回第1个匹配的下标,失败返回-1
template<class Type>
int bs(Type a[],int low,int high,Type v){
    if(low==high)return -1;
    int mid;
    while (low<high){
        mid=(low+high)>>1;
        if(a[mid]<v)low=mid+1;
    //  if(a[mid]>v)low=mid+1;  //a[]递减
        else high=mid;
    }
    if(a[low]==v)return low;
    return -1;
}
/*================================================================================*\
  2)    二分查找(大于等于 v(/大于 v)的第一个值)
\*================================================================================*/
//范围为[low,high)
//a[]递增。若 v 最大则返回 high 的值
template<class Type>
int bsh(Type a[],int low,int high,Type v){
    int mid;
    while (low<high){
        mid=(low+high)>>1;
        if(a[mid]<v)low=mid+1;  //大于等于v
    //  if(a[mid]<=v)low=mid+1; //大于v
        else high=mid;
    }
    return low;
}
/*================================================================================*\
  3)    最长有序子序列(递增/非递减)
\*================================================================================*/
const int N=30010;
Type a[N],f[N]; //题目中的序列存入a[]中
int d[N];
template<class Type>
int bsh(Type a[],int low,int high,Type v)
    //递增时bsh找大于等于v的第一个值
    //非递减时bsh找大于v的第一个值
//----------------------以上为引用模板内其他函数----------------------//
```

```
template<class Type>
int lis(Type a[],int n){//n为a序列的总数
   int i,j,size=1;
   f[0]=a[0];d[0]=1;
   for(i=1;i<n;i++){
      j=bsh(f,0,size,a[i]);
      f[j]=a[i];d[i]=j+1;
      if(j==size)size++;
   }
   return size;
}
/*================================================================================*\
  4)   Matrix
\*================================================================================*/
const int N = 300; // 300左右是极限了，否则ans什么都就要开成全局变量
const int mod = 1000000007;
typedef int type;
struct matrix {
   int n;
   type a[N][N];
   void clear() {forn (i, n) forn (j, n) a[i][j] = 0; }
   matrix(){}
   matrix(int z) { n = z; clear(); }
   matrix operator + (const matrix& u) {
      matrix ans; ans.n = n;
      forn (i, n) forn (j, n) {
         ans.a[i][j] = a[i][j] + u.a[i][j];
         if (ans.a[i][j] >= mod) ans.a[i][j] %= mod;
      } return ans;
   }
   matrix operator * (const matrix& u) {
      matrix ans(n);
      forn (i, n) forn (k, n) if (a[i][k])
         forn (j, n) if (u.a[k][j]) {
            ans.a[i][j] += a[i][k] * u.a[k][j];
            if (ans.a[i][j] >= mod) ans.a[i][j] %= mod;
         }
      return ans;
   }
   matrix pow(int k) {
      matrix r(n), t = *this;
      forn (i, n) r.a[i][i] = 1;
      while (k) {
         if (k & 1) r = t * r;
         t = t * t;
         k >>= 1;
      } return r;
   }
```

```
    matrix calc(int); // A + A^2 + A^3 + ... + A^k
}mtx;

matrix matrix::calc(int k) {
    matrix r(2 * n), t, ret(n);
    forn(i, n) forn(j, n)
        r.a[i][j] = r.a[i][j + n] = a[i][j];
    forn(i, n) r.a[i + n][i + n] = 1;
    t = r.pow(k);
    forn(i, n) forn(j, n)
        ret.a[i][j] = t.a[i][j + n];
    return ret;
}
/*================================================================================*\
  5)    树状数组 解决 RMQ 问题
\*================================================================================*/
const int N=50010;
int n,v[N],c[N];      //v[]需初始化,下标为1…n
int lowb(const int &a){ return a & (-a);}
void preprocess(){    //v[]中已有值，树状数组c[]存放区间最大值
    int i,y,k;
    for(i=1;i<=n;i++){
        y=lowb(i); c[i]=v[i];
        for(k=1;k<y;k<<=1)
            if(c[i]<c[i-k])c[i]=c[i-k];
    }
}
int search(int a,int b){//查找[a,b]中最大值
    int res=-0x7fffffff;
    a--;
    while(1){
        for(;b-lowb(b)>=a && b;b-=lowb(b))
            if(res<c[b])res=c[b];
        if(b==a)break;
        if(res<v[b])res=v[b];
        b--;
    }
    return res;
}
/*================================================================================*\
  6)    ST 算法 解决 RMQ 问题:
\*================================================================================*/
//这里查询的是最大值
//下标范围0…n-1
int mx[N][20], ln[N], val[N];//val[]置为待查询数组
void init(int n){
    int i,j,k,sk;
    ln[0] = ln[1] = 0;
```

```
    for (i = 2; i < n; ++i)
        ln[i] = ln[i >> 1] + 1;
    for(i=0;i<n;i++) mx[i][0]=val[i];
    for(i=1,k=2;k<n;i++,k<<=1)
        for(j=0,sk=k>>1;j<n;j++,sk++){
            mx[j][i]=mx[j][i-1];
            if(sk<n && mx[j][i]<mx[sk][i-1])
                mx[j][i]=mx[sk][i-1];
        }
}
int query(int a,int b){
    int bl = ln[b - a + 1];
    return max(mx[a][bl],mx[b-(1<<bl)+1][bl]);
}
/*================================================================================*\
  7)    点树
\*================================================================================*/
/*
  点树 - (线段树的一种拓展，专门针对点操作)
  实现思路:
    先画一棵完全二叉树， 为节省空间，采用数组来实现。对这棵二叉树，叶子用于存放数据，节点用于统计叶子信息。
通过下面的三种方法，进一步节省空间:
1   节点只记录左子树叶子信息，右子树叶子信息通过当前节点和父节点等节点的值计算得出。
     因而需要指定一个点，当作根节点的"父节点"，以便计算根节点右子树信息。
     可以将根节点从1开始编号，对节点i，左孩子编号为2*i，右孩子编号为2*i+1。
2   对某些应用，叶子信息可以通过节点信息计算得出，因而不保存叶子信息，
3   完全二叉树，边界要求为2^k，为了表示[0, n)这n个点，需要将n增加到2^k，实际上，
    只要第n个叶子的父节点r存在就可以了，编号大于r的节点根本不会被访问到，因而没必要分配空间
 */
```



额外增加节点0，记录所有叶子。

节点	所统计的(左子树下的)叶子
0:	8 9 10 11 12 13 14 15
1:	8 9 10 11
2:	8 9
3:	12 13
4:	8
5:	10
6:	12
7:	14

叶子8-15对应输入的数据，节点1-7记录左子树下的叶子数目
为节省空间，各节点不记录右子树的信息，且不记录叶子对应的数据

点树存储结构示意图

```
template<int N> // 表示可用区间为[0,N)，其中N必须是2的幂数;
class pointtree {
public:
    int a[2 * N];
    int size;
```

```
    void clear() {
        memset(this, 0, sizeof(*this));
    }
    void ins(int n) {
        ++size;
        for (++a[n += N]; n > 1; n >>= 1)
            if (~n & 1)
                a[n >> 1]++;
    }
    void del(int n) {
        if (!a[n += N]) return; // 没有n
        --size;
        for (--a[n]; n > 1; n >>= 1)
            if (~n & 1)
                a[n >> 1]--;
    }
    int cntls(int n) {  // 统计小于n的个数
        int c = 0; // 若统计小于等于则c=a[i];
        for (n += N; n > 1; n >>= 1)
            if (n & 1)
                c += a[n >> 1];
        return c;
    }
    int cntgt(int n) {  // 统计大于n的个数
        return size - a[N + n] - cntls(n);
    }

    /*
     * 解决：求点集中第i小的数(由0数起)
     * 注意：如果i>=size 返回N-1
     */
    int operator[](int n) {
        int i = 1;
        while (i < N) {
            if (n < a[i]) i <<= 1;
            else n -= a[i], i = i << 1 | 1;
        }
        return i - N;
    }
};
pointtree<1 << 18> t;
/*============================================================================*\
  8)   SBT
\*============================================================================*/
// 注意没有内存回收
template<typename Type>
class sbtree { // SizeBalanceTree
public:
```

```
void clear() {
   tot = 0;
   lc[0] = rc[0] = 0;
   sz[0] = 0;
   root = 0;
}
int size() {return sz[root];}
bool empty() {return root == 0;}
void Build(int s,int e) {Build(root,s,e);}
bool Find(Type val)  {return Find(root, val);}
void Insert(Type val)   {Insert(root, val);}
void Delete(Type val)   {Delete(root, val);}
Type DeleteSelect(int k) {return DeleteSelect(root, k);}
void DeleteSmall(Type val) {DeleteSmall(root, val);}
int Rank(Type val)   {return Rank(root, val);}
Type Select(int k)   {return Select(root, k);}
Type pred(Type val)  {return pred(root, val);}
Type succ(Type val) {return succ(root, val);}
Type getMin()  {
   int temp = root;
   while (lc[temp]) temp = lc[temp];
   return key[temp];
}
Type getMax()  {
   int temp = root;
   while (rc[temp]) temp = rc[temp];
   return key[temp];
}
Type DeleteMax() {
   int temp = root;
   if(rc[root] == 0) {
      root = lc[root];
      return key[temp];
   }
   while (rc[rc[temp]]) {
      sz[temp] --;
      temp = rc[temp];
   }
   sz[temp] --;
   Type ret = key[rc[temp]];
   rc[temp] = lc[rc[temp]];
   return ret;
}
Type DeleteMin() {
   int temp = root;
   if(lc[root] == 0) {
      root = rc[root];
      return key[temp];
```

```
        }
        while (lc[lc[temp]]) {
            sz[temp] --;
            temp = lc[temp];
        }
        sz[temp] --;
        Type ret = key[lc[temp]];
        lc[temp] = rc[lc[temp]];
        return ret;
    }
private:
    int sz[maxn];   //sz[i]表示以i为根的子树的大小
    Type key[maxn]; //存放val值 (左儿子 <= 根 <= 右儿子)
    int lc[maxn];   //左儿子
    int rc[maxn];   //右儿子
    int root , tot;
        // 建树之前先clear()
    void Build(int &root,int s,int e) {  //以[s, e]的连续整数建SBT
        if(s > e) return ;
        int mid = (s + e)/2;
        root = ++tot;
        key[root] = mid;
        lc[root] = 0;
        rc[root] = 0;
        sz[root] = e - s + 1;
        if(s == e) return ;
        Build(lc[root] , s , mid - 1);
        Build(rc[root] , mid + 1 , e);
    }
    bool Find(int &root,Type k) {
        if (root == 0) {
            return false;
        } else if (k < key[root]) {
            return Find(lc[root] , k);
        } else {
            return (key[root] == k || Find(rc[root] , k));
        }
    }
    void Insert(int &root,Type val) {
        if (root == 0) {
            root = ++tot;
            lc[root] = rc[root] = 0;
            sz[root] = 1;
            key[root] = val;
            return ;
        }
        sz[root] ++;
        if (val < key[root]) {
```

```
        Insert(lc[root] , val);
      } else {
        Insert(rc[root] , val);
      }
      maintain(root , !(val < key[root]));
   }
   Type Delete(int &root,Type val) {//删除一个val值(val值必须存在)(无内存回收)
      sz[root]--;
      if ((key[root] == val) || (val < key[root] && lc[root] == 0) ||
(key[root] < val && rc[root] == 0)) {
         Type ret = key[root];
         if ( lc[root] == 0 || rc[root] == 0 )
            root = lc[root] + rc[root];
         else   //从左子树中取最大的节点取代当前节点
            key[root] = Delete(lc[root] , key[root] + 1);
         return ret;
      } else {
        if ( val < key[root] )
           return Delete(lc[root] , val);
        else
           return Delete(rc[root] , val);
      }
   }
   void DeleteSmall(int &root , Type val){//删除小于val的所有数(破坏树的平衡)
      if ( root == 0 ) return ;
      if ( key[root] < val ) {
         root = rc[root];
         DeleteSmall(root , val);
      } else {
         DeleteSmall(lc[root] , val);
         sz[root] = 1 + sz[lc[root]] + sz[rc[root]];
      }
   }
   int Rank(int &root , Type val) { //查询val值rank多少(val值必须存在)
      if ( key[root] == val ) {
         return 1;
      } else if ( val < key[root] ) {
         return Rank(lc[root], val);
      } else {
         return sz[lc[root]] + 1 + Rank(rc[root] , val);
      }
   }
   Type Select(int &root , int k) { // 查询第k小元素(从1开始)
      if ( sz[lc[root]] + 1 == k ) {
         return key[root];
      } else if ( k > sz[lc[root]] ) {
         return Select(rc[root] , k - 1 - sz[lc[root]]);
      } else {
```

```
        return Select(lc[root] , k);
    }
}
Type DeleteSelect(int &root,int k) {  // 删除第k小元素
    sz[root]--;
    if ( sz[lc[root]] + 1 == k ) {
        Type ret = key[root];
        if (lc[root] == 0 || rc[root] == 0 )
            root = lc[root] + rc[root];
        else
            key[root] = Delete(lc[root] , key[root] + 1);
        return ret;
    } else if ( k > sz[lc[root]] ) {
        return DeleteSelect(rc[root] , k - 1 - sz[lc[root]]);
    } else {
        return DeleteSelect(lc[root] , k);
    }
}
Type pred(int &root , Type val) {  // 查询小于val的最大值
    if (root == 0) {
        return val;
    } else if (val > key[root]) {
        Type ret = pred(rc[root] , val);
        if(ret == val) return key[root];
        return ret;
    } else {
        return pred(lc[root] , val);
    }
}
Type succ(int &root , Type val) {  // 查询大于val的最小值
    if (root == 0) {
        return val;
    } else if (key[root] > val) {
        Type ret = succ(lc[root] , val);
        if (ret == val) return key[root];
        return ret;
    } else {
        return succ(rc[root] , val);
    }
}
void LeftRotate(int &root) {
    int temp = rc[root];
    rc[root] = lc[temp];
    lc[temp] = root;
    sz[temp] = sz[root];
    sz[root] = 1 + sz[lc[root]] + sz[rc[root]];
    root = temp;
}
```

```
    void RightRotate(int &root) {
        int temp = lc[root];
        lc[root] = rc[temp];
        rc[temp] = root;
        sz[temp] = sz[root];
        sz[root] = 1 + sz[lc[root]] + sz[rc[root]];
        root = temp;
    }
    void maintain(int &root , bool flag) {
        if (root == 0) return ;
        if ( !flag ) {  // 调整左子树
            if ( sz[lc[lc[root]]] > sz[rc[root]] ) {
                RightRotate( root );
            } else if ( sz[rc[lc[root]]] > sz[rc[root]] ) {
                LeftRotate( lc[root] );
                RightRotate( root );
            } else {
                return ;
            }
        } else {   // 调整右子树
            if ( sz[rc[rc[root]]] > sz[lc[root]] ) {
                LeftRotate( root );
            } else if ( sz[lc[rc[root]]] > sz[lc[root]] ) {
                RightRotate( rc[root] );
                LeftRotate( root );
            } else {
                return ;
            }
        }
        maintain(lc[root] , false);
        maintain(rc[root] , true);
        maintain(root , false);
        maintain(root , true);
    }
};
/*=============================================================================*\
  9)   Splay Tree
\*=============================================================================*/
/*
 * Splay Tree
 * 所处理的数组下标为1-N，为实现方便，在0和N+1的位置增加一个key为inf的结点
 * select()函数中的kth与实际下边的关系如下
 * inf - num - num - num - num - inf
 *  0     1     2     3     4     5
 * 另外用null节点替换空指针
 */
const int MAX = 200005;
#define type int
```

```
struct node {
   int size, rev;
   type key, minv, delta;
   node *ch[2], *pre;
   void add(type v) {
      if (size == 0) return;
      delta += v;
      minv += v;
      key += v;
   }
   void reverse() {
      if (size == 0) return;
      rev ^= 1;
      swap(ch[0], ch[1]);
      /* 逆序后会变化的值注意修改(比如左右连续长度) */
   }
   void update() {
      size = ch[0]->size + ch[1]->size + 1;
      minv = min(key, min(ch[0]->minv, ch[1]->minv));
   }
   void pushdown() {
      if (delta) {
         ch[0]->add(delta);
         ch[1]->add(delta);
      }
      if (rev) {
         ch[0]->reverse();
         ch[1]->reverse();
      }
      delta = rev = 0;
   }
};

type arr[MAX];
node* Hash[MAX]; // Hash[i]指向key = i的节点，方便查找其位置(key值唯一)

#define keytree root->ch[1]->ch[0]
class Splay {
   int cnt, top;
   node *stk[MAX], data[MAX];
public:
   node *root, *null;

   /*
    * 获得一个新的节点，之前删除的节点会放到stk中以便再利用
    */
   node *Newnode(type var) {
      node *p;
```

```
    if (top) p = stk[top--];
    else p = &data[cnt++];
    p->key = p->minv = var;
    p->size = 1;
    p->delta = p->rev = 0;
    p->ch[0] = p->ch[1] = p->pre = null;
    return p;
}

void init() {
    top = cnt = 0;
    null = Newnode(inf);
    null->size = 0;
    root = Newnode(inf);
    root->ch[1] = Newnode(inf);
    root->ch[1]->pre = root;
    root->update();
}

/*
 * 用arr数组中[l,r]区间内的值建树
 */
void maketree(int l, int r) {
    init();
    keytree = build(l, r);
    keytree->pre = root->ch[1];
    splay(keytree, null);
}
node *build(int l, int r) {
    if (l > r) return null;
    int mid = (l + r) >> 1;
    node *p = Newnode(arr[mid]);
    Hash[arr[mid]] = p;
    p->ch[0] = build(l, mid - 1);
    p->ch[1] = build(mid + 1, r);
    if (p->ch[0] != null)
        p->ch[0]->pre = p;
    if (p->ch[1] != null)
        p->ch[1]->pre = p;
    p->update();
    return p;
}

/*
 * 旋转操作, c=0 表示左旋, c=1 表示右旋
 */
void rotate(node *x, int c) {
    node *y = x->pre;
```

```
    y->pushdown();
    x->pushdown();
    y->ch[!c] = x->ch[c];
    if (x->ch[c] != null)
        x->ch[c]->pre = y;
    x->pre = y->pre;
    if (y->pre != null)
        y->pre->ch[ y == y->pre->ch[1] ] = x;
    x->ch[c] = y;
    y->pre = x;
    y->update();
    if (y == root) root = x;
}

/*
 * 旋转使x成为f的子节点，若f为null则x旋转为根节点
 * x会执行pushdown和update的操作
 */
void splay(node *x, node *f) {
    x->pushdown();
    while (x->pre != f) {
        if (x->pre->pre == f) {
            rotate(x, x->pre->ch[0] == x);
            break;
        }
        node *y = x->pre;
        node *z = y->pre;
        int c = (y == z->ch[0]);
        if (x == y->ch[c]) {
            rotate(x, !c); rotate(x, c); // 之字形旋转
        } else {
            rotate(y, c); rotate(x, c);  // 一字形旋转
        }
    }
    x->update();
}

/*
 * 找到位置为k的节点，并将其升至x的儿子
 * k节点会执行pushdown和update的操作
 */
void select(int kth, node *x) {
    node *cur = root;
    while (true) {
        cur->pushdown();
        int tmp = cur->ch[0]->size;
        if (tmp == kth) break;
        else if (tmp < kth) {
```

```
            kth -= tmp + 1;
            cur = cur->ch[1];
        } else {
            cur = cur->ch[0];
        }
    }
    splay(cur, x);
}

/*
 * 在x位置后插入值为y的节点。
 * "insert(2,4)" on {1, 2, 3, 4, 5} results in {1, 2, 4, 3, 4, 5}
 * 做法:将x位置的节点a升至根节点，再将x+1位置的节点b升至a的右儿子
 * 此时b的左儿子一定为空， 将新插入的节点作为b的左儿子。
 */
void insert(int x, type y) {
    select(x, null);
    select(x + 1, root);
    keytree = Newnode(y);
    keytree->pre = root->ch[1];
    root->ch[1]->update();
    splay(keytree, null);
}
/*
 * 在x位置后插入arr数组中[l,r]区间内的数
 */
void insert(int x, int l, int r) {
    select(x, null);
    select(x + 1, root);
    keytree = build(l, r);
    keytree->pre = root->ch[1];
    root->ch[1]->update();
    splay(keytree, null);
}

/*
 * 回收x为根的子树
 */
void erase(node *x) {
    if (x == null) return;
    erase(x->ch[0]);
    erase(x->ch[1]);
    stk[++top] = x;
}
/*
 * 删除区间[x, y]范围的数
 */
void dele(int x, int y) {
```

```
    select(x - 1, null);
    select(y + 1, root);
    erase(keytree);
    keytree = null;
    root->ch[1]->update();
    root->update();
}
/*
 * 删除x位置的数。
 * "DELETE(2)" on {1, 2, 3, 4, 5} results in {1, 3, 4, 5}
 * 做法：找到并将其升至根节点，调用deleroot();
 */
void dele(int x) {
    select(x, null);
    deleroot();
}
/*
 * 删除某节点
 * 做法：将其升至根节点，调用deleroot()
 */
void dele(node* t) {
    splay(t, null);
    deleroot();
}
/*
 * 删除根节点，以其右子树的最左边节点替换之
 */
void deleroot() {
    node *oldRoot = root;
    root = root->ch[1];
    root->pre = null;
    select(0, null);
    root->ch[0] = oldRoot->ch[0];
    root->ch[0]->pre = root;
    root->update();
    stk[++top] = oldRoot;
}


/*
 * 区间增加key值 "add(2, 4, 1)" on {1, 2, 3, 4, 5} results in {1, 3, 4, 5, 5}
 */
void add(int x, int y, type d) {
    select(x - 1, null);
    select(y + 1, root);
    keytree->add(d);
    splay(keytree, null);
}
```

```
    /*
     * 区间翻转 "reverse(2,4)" on {1, 2, 3, 4, 5} results in {1, 4, 3, 2, 5}
     */
    void reverse(int x, int y) {
        select(x - 1, null);
        select(y + 1, root);
        keytree->reverse();
    }
    /*
     * 区间[x, y]循环右移d，实质是交换区间[a, b]和[b + 1, c]，其中b = y-d%(y-x+1)
     * "revolve(2, 4, 2)" on {1, 2, 3, 4, 5} results in {1, 3, 4, 2, 5}
     * 做法：将b+1位置的节点x升至根节点，将c+1位置的节点y升至x的右儿子，将c位置的节点z升至y的左儿子
     * 将a-1位置的节点v升至x的左儿子，此时v的右儿子即是[a, b]，将其赋给z的右儿子。
     * 当d = 1时，节点x与节点z是同一节点，特殊处理。
     */
    void revolve(int x, int y, int d) {
        int len = y - x + 1;
        d = (d % len + len) % len;
        if (d == 0) return;
        if (d == 1) {
            dele(y);
            insert(x - 1, stk[top]->key);
        } else {
            select(y - d + 1, null);
            select(y + 1, root);
            select(x - 1, root);
            select(y, root->ch[1]);
            node *p = root->ch[0]->ch[1];
            root->ch[0]->ch[1] = null;
            root->ch[0]->update();
            root->ch[1]->ch[0]->ch[1] = p;
            p->pre = root->ch[1]->ch[0];
            splay(p, null);
        }
    }

    /*
     * 求区间最小值
     * "MIN(2,4)" on {1, 2, 3, 4, 5} is 2
     * 做法：找到X-1位置上的节点a并将其升至根节点，再找到Y+1位置上的
     * 的节点b并将其作为a的右儿子。则b的左儿子即所求区间。
     */
    type getMin(int x, int y) {
        select(x - 1, null);
        select(y + 1, root);
        return keytree->minv;
    }
```

```
    /*
     * 查找key = i的节点的位置
     * 做法：将该节点升至根节点，统计其左儿子个数
     * 注意：由于首位插入了一个无用节点，所以原序列的第i个数有i个左儿子
     */
    int query(type i) {
        splay(Hash[i], null);
        int ans = root->ch[0]->size;
    // reverse(1, ans);
    // dele(1);
        return ans;
    }

    void debug() {vis(root);}
    void vis(node* t) {
        if (t == null) return;
        vis(t->ch[0]);
        printf("node%2d:lson %2d,rson %2d,pre %2d,sz=%2d,key=%2d\n",
               t - data, t->ch[0] - data, t->ch[1] - data,
               t->pre - data, t->size, t->key);
        vis(t->ch[1]);
    }
} spt;
/*==============================================================================*\
  10)  动态树(边权)
\*==============================================================================*/
const int N = 10010;
#define type int
struct node {
    int size;
    bool isroot;
    type val, maxv;
    node *ch[2], *pre;
    void init(type v, node *null) {
        val = maxv = v;
        ch[0] = ch[1] = pre = null;
        size = isroot = 1;
    }
    void pushdown() {}
    void update() {
        size = ch[0]->size + ch[1]->size + 1;
        maxv = max(val, max(ch[0]->maxv, ch[1]->maxv));
    }
};
int n;
type cost[N * 2];
int head[N], que[N], id[N], e;
int ev[N * 2], nxt[N * 2];
```

```
void addedge(int u, int v, type c) {
   ev[e] = v; cost[e] = c; nxt[e] = head[u]; head[u] = e++;
   ev[e] = u; cost[e] = c; nxt[e] = head[v]; head[v] = e++;
}
struct LinkCutTree {
   node data[N], *null;
   void maketree() {
      null = data;
      null->init(-inf, null);
      null->size = 0;
      int bg = 0, ed = 0;
      que[ed++] = 1;
      data[1].init(-inf, null);
      while (bg < ed) {
         int u = que[bg++];
         for (int i = head[u]; ~i; i = nxt[i]) {
            int v = ev[i];
            if (data[u].pre == data + v) continue;
            que[ed++] = v;
            data[v].init(cost[i], null);
            data[v].pre = data + u;
            id[i / 2 + 1] = v;  // 记录边的权值在哪个节点上，下标均为从1开始
         }
      }
   }
   void rotate(node *x, int c) {
      node *y = x->pre;
      y->pushdown();
      x->pushdown();
      y->ch[!c] = x->ch[c];
      if (x->ch[c] != null)
         x->ch[c]->pre = y;
      x->pre = y->pre;
      if (y->isroot) y->isroot = 0, x->isroot = 1;
      else y->pre->ch[ y == y->pre->ch[1] ] = x;
      x->ch[c] = y;
      y->pre = x;
      y->update();
   }
   void splay(node *x) {
      x->pushdown();
      while (!x->isroot) {
         if (x->pre->isroot) {
            rotate(x, x->pre->ch[0] == x);
            break;
         }
         node *y = x->pre;
         node *z = y->pre;
```

```
      int c = (y == z->ch[0]);
      if (x == y->ch[c]) {
         rotate(x, !c); rotate(x, c);
      } else {
         rotate(y, c); rotate(x, c);
      }
   }
   x->update();
}

node* access(node *x) {
   node *y;
   for (y = null; x != null; y = x, x = x->pre) {
      splay(x);   x->ch[1]->isroot = 1;
      x->ch[1] = y;  y->isroot = 0;
      x->update();
   }
   return y;
}
node* findroot(node *x) {
   x = access(x);
   while (1) {
      x->pushdown();
      if (x->ch[0] == null) return x;
      else x = x->ch[0];
   }
}

void modify(int u, type val) {
   splay(data + u);
   data[u].val = val;
   data[u].update();
}
type qmax(int u, int v) {
   access(data + u);
   node *x = data + v;
   type ans;
   for (node *y = null; x != null; y = x, x = x->pre) {
      splay(x);
      if (x->pre == null)
         ans = max(x->ch[1]->maxv, y->maxv);
      x->ch[1]->isroot = 1;
      x->ch[1] = y;  y->isroot = 0;
      x->update();
   }
   return ans;
}
```

```
    void debug() {
        for (int i = 1; i <= n; ++i) {
            printf("node%2d:ls%2d,rs%2d,pre%2d,val=%2d,max=%2d\n",
                   i, data[i].ch[0] - data, data[i].ch[1] - data,
                   data[i].pre - data, data[i].val, data[i].maxv);
        }
    }
}lct;
/*================================================================================*\
  11)  动态树(点权)
\*================================================================================*/
const int N = 30010;
#define type int

int n, q;
int head[N], que[N], e;
int ev[N * 2], nxt[N * 2];
type val[N]

void addedge(int u, int v) {
    ev[e] = v; nxt[e] = head[u]; head[u] = e++;
    ev[e] = u; nxt[e] = head[v]; head[v] = e++;
}

struct node {
    int size;
    bool rev, isroot;
    type val, maxv, sum;
    node *ch[2], *pre;
    void init(type v, node *null) {
        val = maxv = sum = v;
        ch[0] = ch[1] = pre = null;
        rev = 0;
        size = isroot = 1;
    }
    void reverse() {
        if (size == 0) return;
        swap(ch[0], ch[1]);
        rev ^= 1;
    }
    void pushdown() {
        if (rev) {
            ch[0]->reverse();
            ch[1]->reverse();
        }
        rev = 0;
    }
    void update() {
```

```
        size = ch[0]->size + ch[1]->size + 1;
        sum = ch[0]->sum + ch[1]->sum + val;
        maxv = max(val, max(ch[0]->maxv, ch[1]->maxv));
    }
};

struct LinkCutTree {
    node data[N], *null;
    void maketree() {
        null = data;
        null->init(-inf, null);
        null->size = null->sum = 0;
        int bg = 0, ed = 0;
        que[ed++] = 1;
        data[1].init(val[1], null);
        while (bg < ed) {
            int u = que[bg++];
            for (int i = head[u]; ~i; i = nxt[i]) {
                int v = ev[i];
                if (data[u].pre == data + v) continue;
                que[ed++] = v;
                data[v].init(val[v], null);
                data[v].pre = data + u;
            }
        }
    }
    void rotate(node *x, int c) {
        node *y = x->pre;
        y->pushdown();
        x->pushdown();
        y->ch[!c] = x->ch[c];
        if (x->ch[c] != null)
            x->ch[c]->pre = y;
        x->pre = y->pre;
        if (y->isroot) y->isroot = 0, x->isroot = 1;
        else y->pre->ch[ y == y->pre->ch[1] ] = x;
        x->ch[c] = y;
        y->pre = x;
        y->update();
    }
    void splay(node *x) {
        x->pushdown();
        while (!x->isroot) {
            if (x->pre->isroot) {
                rotate(x, x->pre->ch[0] == x);
                break;
            }
            node *y = x->pre;
```

```
        node *z = y->pre;
        int c = (y == z->ch[0]);
        if (x == y->ch[c]) {
            rotate(x, !c); rotate(x, c);
        } else {
            rotate(y, c); rotate(x, c);
        }
    }
    x->update();
}

node* access(node *x) {
    node *y;
    for (y = null; x != null; y = x, x = x->pre) {
        splay(x);   x->ch[1]->isroot = 1;
        x->ch[1] = y;  y->isroot = 0;
        x->update();
    }
    return y;
}
node* findroot(node *x) {
    x = access(x);
    while (1) {
        x->pushdown();
        if (x->ch[0] == null) return x;
        else x = x->ch[0];
    }
}

/*
 * 把x为根的子树与原来节点断开，移动到y节点下(必须合法)
 */
void move(int x, int y) {
    access(data + x);
    splay(data + x);
    data[x].ch[0]->pre = null;
    data[x].ch[0]->isroot = 1;
    data[x].ch[0] = null;
    data[x].pre = data + y;
    access(data + x);
}

/*
 * 判断x是否在y到根节点的路径上，包括x==y的情况
 */
bool isfather(int x, int y) {
    if (findroot(data + x) !=
        findroot(data + y)) return false;
```

```
        access(data + y);
        splay(data + x);
        return data[x].pre == null;
    }

    void evert(node *x) { // 将x节点置为根,权值在边上时不能进行
        x = access(x);
        x->reverse();
    }
    void modify(int u, type val) {
        splay(data + u);
        data[u].val = val;
        data[u].update();
    }
    type qmax(int u, int v) {
        evert(data + u);
        return access(data + v)->maxv;
    }
    type qsum(int u, int v) {
        evert(data + u);
        return access(data + v)->sum;
    }

    void debug() {
        bool flag = true;
        while (flag) {
            flag = false;
            for (int i = 1; i <= n; ++i)
                if (data[i].rev) {
                    data[i].pushdown();
                    flag = true;
                }
        }
        for (int i = 1; i <= n; ++i) {
            printf("node%2d:ls%2d,rs%2d,pre%2d,val=%2d,max=%2d\n",
                   i, data[i].ch[0] - data, data[i].ch[1] - data,
                   data[i].pre - data, data[i].val, data[i].maxv);
        }
    }
}lct;
/*==========================================================================*\
  12)  块状链表
\*==========================================================================*/
const int TOT = 2 * 1024 * 1024 + 10;
const int SIZE = 3000; // size of each block
const int MAX = TOT / SIZE * 2 + 100;

#define type int
```

```
struct BlockList {
   type data[MAX][SIZE];
   int cnt[MAX];
   int next[MAX];
   int free[MAX];
   int top;

   void init() {
      for (int i = 1; i < MAX; ++i)
         free[i] = i;
      top = 1;
      next[0] = -1;
      cnt[0] = 0;
   }
   int newnode(int n, type from[], int nxt) {
      int b = free[top++];
      next[b] = nxt;
      cnt[b] = n;
      memcpy(data[b], from, sizeof(type) * n);
      return b;
   }
   void delnode(int t) {
      free[--top] = t;
   }
   /*
    * 找到p所在的块b，p置为在b中的相对位置，下标均从0开始
    * p == cnt[b]时不会跳到下一块，而是位于此块的最后一个的后面
    */
   void find(int &p, int &b) {
      for (b = 0; b != -1 && p > cnt[b]; b = next[b])
         p -= cnt[b];
   }

   /*
    * b block : [0,end] -> [0,p-1] & [p,end]
    */
   void splite(int b, int p) {
      if (b == -1 || p == cnt[b]) return;
      int t = newnode(cnt[b] - p, data[b] + p, next[b]);
      next[b] = t;
      cnt[b] = p;
   }
   void maintain(int b) {
      for (; b != -1; b = next[b])
         for (int t = next[b]; t != -1 && cnt[b] + cnt[t] <= SIZE;
               t = next[b]) {
            memcpy(data[b] + cnt[b], data[t], sizeof(type) * cnt[t]);
            cnt[b] += cnt[t];
```

```
            next[b] = next[t];
            delnode(t);
        }
    }
    /*
     * 在p位置上插入n个数，该位置上的数向后挪，下标从0开始
     */
    void insert(int p, int n, type from[]) {
        int b, t, i;
        find(p, b);
        splite(b, p);
        for (i = 0; i + SIZE <= n; i += SIZE) {
            t = newnode(SIZE, from + i, next[b]);
            next[b] = t;
            b = t;
        }
        if (n - i) {
            t = newnode(n - i, from + i, next[b]);
            next[b] = t;
        }
        maintain(b);
    }
    void erase(int p, int n) {
        int b, e;
        find(p, b);
        splite(b, p);
        for (e = next[b]; e != -1 && n > cnt[e]; e = next[e])
            n -= cnt[e];
        splite(e, n);
        e = next[e];
        for (int t = next[b]; t != e; t = next[b]) {
            next[b] = next[t];
            delnode(t);
        }
        maintain(b);
    }
    void get(int p, int n, type to[]) {
        int b, t, i;
        find(p, b);
        i = min(n, cnt[b] - p);
        memcpy(to, data[b] + p, sizeof(type) * i);
        for (t = next[b]; t != -1 && i + cnt[t] <= n;
                i += cnt[t], t = next[t])
            memcpy(to + i, data[t], sizeof(type) * cnt[t]);
        if (n - i && t != -1)
            memcpy(to + i, data[t], sizeof(type) * (n - i));
    }
}lst;
```

```
/*==========================================================================*\
  13)  左偏树
\*==========================================================================*/
const int N = 100010;
const int na = 0;
#define typec int // type of key val
struct node {
   typec key;
   int l, r, f, dist;
} tr[N];
int iroot(int i) { // find i's root
   if (i == na) return i;
   while (tr[i].f != na) i = tr[i].f;
   return i;
}
int merge(int rx, int ry) { // two root: rx, ry
   if (rx == na) return ry;
   if (ry == na) return rx;
   if (tr[rx].key > tr[ry].key) swap(rx, ry);  //最小堆变最大堆只要修改这里
   int r = merge(tr[rx].r, ry);
   tr[rx].r = r; tr[r].f = rx;
   if (tr[r].dist > tr[tr[rx].l].dist)
      swap(tr[rx].l, tr[rx].r);
   if (tr[rx].r == na) tr[rx].dist = 0;
   else tr[rx].dist = tr[tr[rx].r].dist + 1;
   return rx; // return new root
}
int ins(int i, typec key, int root) { // add a new node(i, key)
   tr[i].key = key;
   tr[i].l = tr[i].r = tr[i].f = na;
   tr[i].dist = 0;
   return root = merge(root, i); // return new root
}
int del(int i) { // delete node i
   if (i == na) return i;
   int x, y, l, r;
   l = tr[i].l;
   r = tr[i].r;
   y = tr[i].f;
   tr[i].l = tr[i].r = tr[i].f = na;
   tr[x = merge(l, r)].f = y;
   if (y != na && tr[y].l == i) tr[y].l = x;
   if (y != na && tr[y].r == i) tr[y].r = x;
   for (; y != na; x = y, y = tr[y].f) {
      if (tr[tr[y].l].dist < tr[tr[y].r].dist)
         swap(tr[y].l, tr[y].r);
      if (tr[tr[y].r].dist + 1 == tr[y].dist) break;
      tr[y].dist = tr[tr[y].r].dist + 1;
```

```
    }
    if (x != na) return iroot(x); // return new root
    else return iroot(y);
}
node top(int root) {
    return tr[root];
}
node pop(int &root) {
    node out = tr[root];
    int l = tr[root].l, r = tr[root].r;
    tr[root].l = tr[root].r = tr[root].f = na;
    tr[l].f = tr[r].f = na;
    root = merge(l, r);
    return out;
}
int change(int i, typec val) { // tr[i].key = val
    if (i == na) return i;
    if (tr[i].l == na && tr[i].r == na && tr[i].f == na) {
        tr[i].key = val;
        return i;
    }
    int rt = del(i);
    return ins(i, val, rt);
}
void init(int n) {
    tr[na].l = tr[na].r = tr[na].f = na;
    tr[na].dist = -1;
    for (int i = 1; i <= n; i++) {
        scanf("%d", &tr[i].key); //%d: type of key
        tr[i].l = tr[i].r = tr[i].f = na;
        tr[i].dist = 0;
    }
}
/*============================================================================*\
  14)  划分树
\*============================================================================*/
#define L(x) (x << 1)
#define R(x) (x << 1 | 1)
const int N = 100010;
int n;

struct node {
    int lft, rht;
    int getmid() { return (lft + rht) >> 1; }
}tree[N * 4]; // 注意"*4"
int val[20][N], sorted[N];
int toleft[20][N];
```

```
void build(int root, int lft, int rht, int d) {
   tree[root].lft = lft;
   tree[root].rht = rht;
   if (lft == rht) return;
   int mid = (lft + rht) >> 1;
   int same = mid - lft + 1; //same表示和val_mid相等且分到左边的数目
   for (int i = lft; i <= rht; ++i)
      if (val[d][i] < sorted[mid])
         same--;
   int lpos = lft;
   int rpos = mid + 1;
   for (int i = lft; i <= rht; ++i) {
      if (i == lft) toleft[d][i] = 0;
      else toleft[d][i] = toleft[d][i - 1];

      if (val[d][i] < sorted[mid]) {
         toleft[d][i]++;
         val[d + 1][lpos++] = val[d][i];
      } else if (val[d][i] > sorted[mid]) {
         val[d + 1][rpos++] = val[d][i];
      } else if (same) {
         same--;
         toleft[d][i]++;
         val[d + 1][lpos++] = val[d][i];
      } else {
         val[d + 1][rpos++] = val[d][i];
      }
   }
   build(L(root), lft, mid, d + 1);
   build(R(root), mid + 1, rht, d + 1);
}

int query(int root, int lft, int rht, int d, int k) {
   if (lft == rht) return val[d][lft];
   int s;  //s表示[lft , rht]有多少个分到左边
   int ss; //ss表示[tree[root].lft , lft - 1]有多少个分到左边
   if (lft == tree[root].lft) {
      s = toleft[d][rht];
      ss = 0;
   } else {
      s = toleft[d][rht] - toleft[d][lft - 1];
      ss = toleft[d][lft - 1];
   }
   if (k <= s) {  //有多于k个分到左边,显然去左儿子区间找第k个
      int left = tree[root].lft + ss;
      int right = left + s - 1;
      return query(L(root), left, right, d + 1, k);
   } else {
```

```
        int b = lft - tree[root].lft - ss;
              // b表示[tree[root].lft , lft - 1]有多少个分到右边
        int left = tree[root].getmid() + b + 1;
        int right = left + rht - lft - s;
        return query(R(root), left, right, d + 1, k - s);
    }
}
/*================================================================================*\
  15)  矩形面积并
\*================================================================================*/
#define L(x) (x << 1)
#define R(x) (x << 1 | 1)
const int N = 100010 * 2;
const double eps = 1e-8;
//typedef double type;
typedef ll type;
type bin[N];

struct line {
    type x, y0, y1;
    int d;
    line(){}
    line(type x, type y0, type y1, int d) :
        x(x), y0(y0), y1(y1), d(d) {}
    bool operator < (const line& u) const {
//      if (fabs(x - u.x) > eps) return x < u.x;
        if (x != u.x) return x < u.x;
        return d > u.d;
    }
}lin[N];

struct node {
    int lft, rht, c; // c 为区间被覆盖的层数
    type m;    // 区间被覆盖长度
    int getmid() { return (lft + rht) >> 1; }
    void update(int);
}tree[N * 4];

void node::update(int root) {
    if (c) m = bin[rht] - bin[lft];
    else if (lft + 1 == rht) m = 0;
    else m = tree[L(root)].m + tree[R(root)].m;
}


void build(int root, int lft, int rht) {
    tree[root].lft = lft;
    tree[root].rht = rht;
```

```
    tree[root].c = 0;
    tree[root].m = 0;
    if (lft + 1 == rht) return;
    int mid = (lft + rht) >> 1;
    build(L(root), lft, mid);
    build(R(root), mid, rht);
}

void insert(int root, int lft, int rht, int d) {
    if (lft <= tree[root].lft && tree[root].rht <= rht) {
        tree[root].c += d;
        tree[root].update(root);
        return;
    }
    int mid = tree[root].getmid();
    if (lft < mid) insert(L(root), lft, rht, d);
    if (mid < rht) insert(R(root), lft, rht, d);
    tree[root].update(root);
}

bool Equal(double a, double b) {return fabs(a - b) < eps;}

void solve() {
    type x0, x1, y0, y1;
    int n, tot = 0;
    scanf("%d", &n);
    forn (i, n) {
//      scanf("%lf%lf%lf%lf", &x0, &y0, &x1, &y1);
        scanf("%lld%lld%lld%lld", &x0, &y0, &x1, &y1);
        bin[tot] = y0;  lin[tot++] = line(x0, y0, y1, 1);
        bin[tot] = y1;  lin[tot++] = line(x1, y0, y1, -1);
    }
    sort(lin, lin + tot);
    sort(bin, bin + tot);
// tot = unique(bin, bin + tot, Equal) - bin;
    tot = unique(bin, bin + tot) - bin;
    build(1, 0, tot - 1); // 注意tot不能等于0
    type ans = 0;
    forn (i, n + n) {
//      int lft = lower_bound(bin, bin + tot, lin[i].y0 - eps) - bin;
//      int rht = lower_bound(bin, bin + tot, lin[i].y1 - eps) - bin;
        int lft = lower_bound(bin, bin + tot, lin[i].y0) - bin;
        int rht = lower_bound(bin, bin + tot, lin[i].y1) - bin;
        if (lft != rht) insert(1, lft, rht, lin[i].d);
        ans += tree[1].m * (lin[i + 1].x - lin[i].x);
    }
    printf("%lld\n", ans);
}
```

```
/*================================================================================*\
  16)  矩形周长并
\*================================================================================*/
#define L(x) (x << 1)
#define R(x) (x << 1 | 1)
const int N = 100010 * 2;
const double eps = 1e-8;
//typedef double type;
typedef int type;
type bin[N];

struct line {
   type x, y0, y1;
   int d;
   line(){}
   line(type x, type y0, type y1, int d) :
      x(x), y0(y0), y1(y1), d(d) {}
   bool operator < (const line& u) const {
//    if (fabs(x - u.x) > eps) return x < u.x;
      if (x != u.x) return x < u.x;
      return d > u.d;
   }
}lin[N];

struct node {
   int lft, rht, c; // c 为区间被覆盖的层数
   int cnt, lbd, rbd; // lbd和rbd表示边界，cnt表示需要统计几根线段
   type m;    // 区间被覆盖长度
   void init() {
      cnt = lbd = rbd = c = 0;
      m = 0;
   }
   int getmid() { return (lft + rht) >> 1; }
   void update(int);
}tree[N * 4];

void node::update(int root) {
   if (c) {
      m = bin[rht] - bin[lft];
      lbd = rbd = cnt = 1;
   } else if (lft + 1 == rht) {
      init();
   } else {
      m = tree[L(root)].m + tree[R(root)].m;
      cnt = tree[L(root)].cnt + tree[R(root)].cnt
            - (tree[L(root)].rbd & tree[R(root)].lbd);
      lbd = tree[L(root)].lbd;
      rbd = tree[R(root)].rbd;
```

```
    }
}

void build(int root, int lft, int rht) {
    tree[root].lft = lft;
    tree[root].rht = rht;
    tree[root].init();
    if (lft + 1 == rht) return;
    int mid = (lft + rht) >> 1;
    build(L(root), lft, mid);
    build(R(root), mid, rht);
}

void insert(int root, int lft, int rht, int d) {
    if (lft <= tree[root].lft && tree[root].rht <= rht) {
        tree[root].c += d;
        tree[root].update(root);
        return;
    }
    int mid = tree[root].getmid();
    if (lft < mid) insert(L(root), lft, rht, d);
    if (mid < rht) insert(R(root), lft, rht, d);
    tree[root].update(root);
}

bool Equal(double a, double b) {return fabs(a - b) < eps;}

void solve() {
    type x0, x1, y0, y1;
    int n, tot = 0;
    scanf("%d", &n);
    forn (i, n) {
//      scanf("%lf%lf%lf%lf", &x0, &y0, &x1, &y1);
        scanf("%d%d%d%d", &x0, &y0, &x1, &y1);
        bin[tot] = y0;  lin[tot++] = line(x0, y0, y1, 1);
        bin[tot] = y1;  lin[tot++] = line(x1, y0, y1, -1);
    }
    sort(lin, lin + tot);
    sort(bin, bin + tot);
// tot = unique(bin, bin + tot, Equal) - bin;
    tot = unique(bin, bin + tot) - bin;
    build(1, 0, tot - 1); // 注意tot不能等于0
    type ans = 0, len = 0;
    forn (i, n + n) {
//      int lft = lower_bound(bin, bin + tot, lin[i].y0 - eps) - bin;
//      int rht = lower_bound(bin, bin + tot, lin[i].y1 - eps) - bin;
        int lft = lower_bound(bin, bin + tot, lin[i].y0) - bin;
        int rht = lower_bound(bin, bin + tot, lin[i].y1) - bin;
```

```
        if (lft != rht) insert(1, lft, rht, lin[i].d);
        ans += tree[1].cnt * (lin[i + 1].x - lin[i].x) * 2;
//      ans += fabs(tree[1].m - len);
        ans += abs(tree[1].m - len);
        len = tree[1].m;
    }
    printf("%d\n", ans);
}
```

3. 搜索 & 动态规划

```
/*================================================================================*\
  1)   插头DP(括号匹配)
\*================================================================================*/
//这份是简单路径(4进制) 的插头DP
const int N = 10;
int n, m, maze[N][N];

const int H = 40007;
struct Hash {
   int head[H], nxt[H], size;
   int dp[H], msk[H];
   void clear() {
      size = 0; clr(head, -1);
   }
   void push(int m, int val) {
      int x = m % H;
      for (int i = head[x]; ~i; i = nxt[i]) {
         if (msk[i] == m) {
            dp[i] = max(dp[i], val);
            return;
         }
      }
      dp[size] = val;
      msk[size] = m;
      nxt[size] = head[x];
      head[x] = size++;
   }
}hp[2], *scr, *des;

int getlft(int msk, int pos) {
   int cnt = 1;
   for (int i = pos - 1; i >= 0; --i) {
      int t = (msk >> (i * 2)) & 3;
      if (t == 1) cnt--;
      if (t == 2) cnt++;
      if (cnt == 0) return 1 << (i * 2);
   } return 0;
}
int getrht(int msk, int pos) {
   int cnt = 1;
   for (int i = pos + 1; i < 32; ++i) {
      int t = (msk >> (i * 2)) & 3;
      if (t == 1) cnt++;
      if (t == 2) cnt--;
      if (cnt == 0) return 1 << (i * 2);
   } return 0;
```

```
}
int cntthree(int msk) {
   int cnt = 0;
   while (msk) {
      if ((msk & 3) == 3) cnt++;
      msk >>= 2;
   }
   return cnt;
}

int plugDP() {
   scr = hp; des = hp + 1;
   int ans = 0;
   scr->clear();
   scr->push(0, 0);
   forn (i, n) forn (j, m) {
      des->clear();
      forn (k, scr->size) {
         int msk = scr->msk[k];
         int val = scr->dp[k] + maze[i][j];

//       printf("dp[%d][%d][", i, j);
//       forn (t, m + 1) printf("%d", (msk >> (t * 2)) & 3);
//       printf("] = %d\n", val - maze[i][j]);

         int lft = (msk >> (j * 2)) & 3;
         int up = (msk >> (j * 2 + 2)) & 3;
         int now = msk & ~(15 << (j * 2));
         if (maze[i][j] == 0) {
            if (lft == 0 && up == 0)
               des->push(now, val);
         } else if (lft == 0 && up == 0) {
            des->push(now, val - maze[i][j]);
            des->push(now | 9 << (j * 2), val);
            if (cntthree(msk) > 1) continue;
            des->push(now | 3 << (j * 2), val);
            des->push(now | 3 << (j * 2 + 2), val);
         } else if (lft == 0 || up == 0) {
            des->push(now | (lft + up) << (j * 2), val);
            des->push(now | (lft + up) << (j * 2 + 2), val);
            if (cntthree(msk) > 1) continue;
            if (lft + up == 3) {
               if (now == 0) ans = max(ans, val);
            } else {
               int pos = lft == 0 ? j + 1 : j;
               if (lft + up == 1) now += getrht(msk, pos);
               if (lft + up == 2) now += getlft(msk, pos) * 2;
               des->push(now, val);
```

```
            }
         } else if (lft == 3 && up == 3) {
            if (now == 0) ans = max(ans, val);
         } else if (lft == 3 || up == 3) {
            int pos = lft == 3 ? j + 1 : j;
            if (lft + up == 4) now += getrht(msk, pos);
            if (lft + up == 5) now += getlft(msk, pos) * 2;
            des->push(now, val);
         } else if (lft == up) {
            if (lft == 1) now -= getrht(msk, j + 1);
            if (lft == 2) now += getlft(msk, j);
            des->push(now, val);
         } else if (lft == 2 && up == 1) {
            des->push(now, val);
         }
      }
      swap(scr, des);
      if (j == m - 1) {
         des->clear();
         forn (k, scr->size) if (scr->msk[k] < 1 << (m * 2))
            des->push(scr->msk[k] << 2, scr->dp[k]);
         swap(scr, des);
      }
   }
   return ans;
}

void solve() {
   scanf("%d%d", &n, &m);
   int ans = 0;
   forn (i, n) forn (j, m) {
      scanf("%d", &maze[i][j]);
      ans = max(ans, maze[i][j]);
   }
   printf("%d\n", max(ans, plugDP()));
}

int main() {
   int cas;
   scanf("%d", &cas);
   forn (i, cas) {
      solve();
   }
   return 0;
}
```

```
/*================================================================================*\
  2)    插头 DP(最小表示法)
\*================================================================================*/
/*
题目: Black and White (UVA 10572)
题目内容或思路:   插头dp(广义路径) (陈丹琪论文题)
    转移的时候,每个格子有一到两个填色方案
    以黑色为例转移如下:
不合法情况: (情况1)If 最后一格 && 左白 && 上白 && 左上黑   Then 照成不连通,非法
      (情况2)If 左黑 && 上黑 && 左上黑        Then 形成2x2的格子,非法
      (情况3)If 上白 && 轮廓线上没有和上边相连的格子
           If 轮廓线上有白色的格子     Then 照成不连通, 非法 (情况3.1)
           If 当前格不是最后两格       Then 非法           (情况3.2)
          (因为如果剩下格子有白色,照成不连通 剩下格子全黑色,必然有2x2的黑色格子)
    If 左黑 && 上黑        Then 合并两个连通块
    Else If 左白 && 上白      Then 形成新的连通块
    Else If 左黑 && 上白      Then 和左边的合并
    Else If 左白 && 上黑      Then 和上边的合并
    最后对所有状态判断一下最多只能存在两个连通块
*/
const int N = 10;
int n, m, code[N], bin[N];
char maze[N][N];
typedef int type;

const int H = 17009;
struct Hash {
   int head[H], nxt[H], size;
   int msk[H], col[H];
   type dp[H];
   void clear() { size = 0; clr(head, -1); }
   int push(int xmsk, int xcol, type val) {
      int x = xmsk % H;
      for (int i = head[x]; ~i; i = nxt[i]) {
         if (msk[i] == xmsk && col[i] == xcol) {
            dp[i] += val;
            return i;
         }
      }
      msk[size] = xmsk;
      col[size] = xcol;
      dp[size] = val;
      nxt[size] = head[x];
      return head[x] = size++;
   }
}hp[2], *scr, *des;
int pre[66][H];
```

```
void decode(int msk, int code[]) {
   forn (i, m) code[i] = (msk >> (i * 3)) & 7;
}

int encode(int code[]) {
   int msk = 0, cnt = 0; clr(bin, -1);
   forn (i, m) {
      if (bin[code[i]] == -1)
         bin[code[i]] = cnt++;
      msk |= bin[code[i]] << (i * 3);
   } return msk;
}

void trans(int i, int j, int k, int cur) {
   decode(scr->msk[k], code);
   int col = scr->col[k];
   int lft = (j == 0) ? -1 : (col >> (j - 1)) & 1;
   int up = (i == 0) ? -1 : (col >> (j + 1)) & 1;
   int p = (j == 0 || i == 0) ? -1 : (col >> j) & 1;

// printf("dp[%d][%d][", i, j);
// forn (t, m) printf("%d", code[t]);
// printf("][");
// forn (t, m + 1) printf("%d", (col >> t) & 1);
// printf("] = %lld (%d)\n", scr->dp[k], cur);

   if (i == n - 1 && j == m - 1 && lft == 1 - cur
      && up == 1 - cur && p == cur) return;  // 情况1
   if (lft == cur && up == cur && p == cur) return; // 情况2
   if (up != -1 && up != cur) {
      int cnt = 0;
      forn (u, m) if (code[u] == code[j]) cnt++;
      if (cnt == 1) {      // 情况3
         forn (u, m + 1) if (u != j && u != j + 1)
            if (((col >> u) & 1) == up) return; // 情况3.1
         if (i * m + j < n * m - 2) return; // 情况3.2
      }
   }
   if (lft == cur && up == cur) {
      int t = code[j];
      forn (u, m) if (code[u] == t)
         code[u] = code[j - 1]; // 合并
   } else if (lft != cur && up != cur) {
      code[j] = 8;    // 新连通块
   } else if (lft == cur) {
      code[j] = code[j - 1];
   }
```

```
    if (p == -1) col |= cur << j;
    else col ^= ((cur ^ p) << j);
    if (j == m - 1) col = (col << 1) & ~(1 << (m + 2));
    int id = des->push(encode(code), col, scr->dp[k]);
    pre[i * m + j][id] = k << 1 | cur;
}
ll plugDP(int &id) {
    scr = hp; des = scr + 1;
    scr->clear(); scr->push(0, 0, 1);
    forn (i, n) forn (j, m) {
        des->clear();
//      puts("");
        forn (k, scr->size) {
            if (maze[i][j] != 'o') trans(i, j, k, 1);
            if (maze[i][j] != '#') trans(i, j, k, 0);
        }
        swap(scr, des);
    }
    type ans = 0;
    forn (k, scr->size) {
        decode(scr->msk[k], code);
        int block = 0;
        forn (i, m) block = max(block, code[i]);
        if (block <= 1) {
            ans += scr->dp[k];
            id = k << 1;
        }
    } return ans;
}
void solve() {
    int id;
    scanf("%d%d", &n, &m);
    forn (i, n) scanf("%s", maze[i]);
    type ans = plugDP(id);
    printf("%d\n", ans);
    if (ans == 0) { puts(""); return;}
    ford (i, n) ford (j, m) {
        id = pre[i * m + j][id >> 1];
        maze[i][j] = id & 1 ? '#' : 'o';
    }
    forn (i, n) puts(maze[i]);
    puts("");
}
int main() {
    int cas; scanf("%d", &cas);
    forn (i, cas) solve();
    return 0;
 }
```

```
/*==========================================================================*\
  3)   重复覆盖问题(Dancing Links + IDA*)
\*==========================================================================*/
int u[M], d[M], l[M], r[M];
int col[M], s[N];
// 上面变量都需初始化
void remove(int &c){
   for(int i = d[c]; i != c ; i = d[i])
      l[r[i]] = l[i], r[l[i]] = r[i];
}
void resume(int &c){
   for(int i = u[c]; i != c ; i = u[i])
      l[r[i]] = i, r[l[i]] = i;
}
int h() {
   bool hash[51];
   memset(hash,false,sizeof(hash));
   int ret = 0;
   for(int c = r[0]; c; c = r[c]) if(!hash[c]){
      ret++;
      hash[c] = true;
      for(int i = d[c] ; i != c ; i = d[i])
         for(int j = r[i] ; j != i ; j = r[j])
            hash[col[j]] = true;
   }
   return ret;
}

bool dfs(int deep,int lim) {
   if(deep + h() > lim) return false;
   if(r[0] == 0) return true;
   int idx , i , j , minnum = 99999;
   for(i = r[0] ; i; i = r[i])
      if(s[i] < minnum)
         minnum = s[i], idx = i;
   for(i = d[idx]; i != idx; i = d[i]) {
      remove(i);
      for(j = r[i]; j != i ; j = r[j]) remove(j);
      if(dfs(deep+1,lim)) return true;
      for(j = l[i]; j != i ; j = l[j]) resume(j);
      resume(i);
   }
   return false;
}
```

4. 图论

```
/*================================================================================*\
  1)    二分图最佳匹配(kuhn munkras 算法)
    最大权匹配/最小权匹配，复杂度 O(n^3)
\*================================================================================*/
#define N 200
#define INF 0x7fffffff
int g[N][N],nx,ny;   //需要初始化
int mx[N],my[N],lx[N],ly[N]; //lx[],ly[]为KM算法中Xi与Yi的顶点标号
bool sx[N],sy[N];    //标记是否在交错树上
int prev[N],slack[N];   //prev[i]为Y中i点在交错树上的前点；slack为松弛量
int q[N*2],head,tail;
void augment(int v){ //增广
   while(v!=-1){
      int pv=mx[prev[v]];
      mx[prev[v]]=v; my[v]=prev[v];v=pv;
   }
}
bool bfs(){
   while(head!=tail){
      int p=q[head++],u=p>>1;
      if(p & 1){
         if(my[u]==-1){ augment(u);return true; }
         else { q[tail++]=my[u]<<1; sx[my[u]]=true; }
      }
      else for(int i=0;i<ny;i++)
         if(sy[i])continue;
         else if(lx[u]+ly[i]!=g[u][i]){
            int ex=lx[u]+ly[i]-g[u][i];
            if(slack[i]>ex){ slack[i]=ex; prev[i]=u; }
         }
         else { prev[i]=u; sy[i]=true; q[tail++]=i*2+1; }
   }return false;
}
int KMmatch(bool maxsum = true){    //默认为最大权匹配
   int i,j,ex,cost=0;
   if(!maxsum) for(i=0;i<nx;i++) for(j=0;j<ny;j++) g[i][j]*=-1;
   memset(mx,-1,sizeof(mx));
   memset(my,-1,sizeof(my));
   memset(ly,0,sizeof(ly));
   for(i=0;i<nx;i++)
      for(lx[i]=-INF,j=0;j<ny;j++)
         lx[i]=max(lx[i],g[i][j]);
   for(int live=0;live<nx;live++){
      memset(sx,0,sizeof(sx)); memset(sy,0,sizeof(sy));
      for(i=0;i<ny;i++)slack[i]=INF;
      head=tail=0; q[tail++]=live*2; sx[live]=true;
```

```
        while(!bfs()){
            for(ex=INF,i=0;i<ny;i++)if(!sy[i]) ex=min(ex,slack[i]);
            for(i=0;i<nx;i++) if(sx[i])lx[i]-=ex;
            for(j=0;j<ny;j++){ if(sy[j])ly[j]+=ex;slack[j]-=ex;}
            for(i=0;i<ny;i++)
                if(!sy[i] && slack[i]==0){q[tail++]=i*2+1;sy[i]=true;}
        }
    }
    if(!maxsum) for(i=0;i<nx;i++) for(j=0;j<ny;j++) g[i][j]*=-1;
    for(i=0;i<nx;i++)cost+=g[i][mx[i]];
    return cost;
}
/*============================================================================*\
  2)    二分图最佳匹配(kuhn munkras 算法)按交大模板改的
    复杂度O(n^4)(上界较宽)。比上一个模板的优点是代码短。
\*============================================================================*/
#define N 200
int mx[N], my[N], lx[N], ly[N];
bool sx[N], sy[N];
int nx, ny, g[N][N]; //需要初始化
bool path(int u) {
    sx[u] = 1;
    forn (v, ny) if (g[u][v] == lx[u] + ly[v] && !sy[v]) {
        sy[v] = 1;
        if (my[v] == -1 || path(my[v])) {
            mx[u] = v; my[v] = u; return 1;
        }
    } return 0;
}
int KMmatch(bool maxsum = true){  //默认为最大权匹配
    int j, ret = 0;
    if (!maxsum) forn (i, nx) forn (j, ny) g[i][j] *= -1;
    clr(ly, 0);  clr(mx, -1);  clr(my, -1);
    forn (i, nx) for(lx[i] = -inf, j = 0; j < ny; j++)
        lx[i] = max(lx[i], g[i][j]);
    forn (u, nx) if (mx[u] == -1) {
        clr(sx, 0);  clr(sy, 0);
        while(!path(u)){
            int ex=inf;
            forn (i, nx) if (sx[i]) forn (j, ny) if (!sy[j])
                ex = min(ex, lx[i] + ly[j] - g[i][j]);
            forn (i, nx) if (sx[i]) { lx[i] -= ex; sx[i] = 0; }
            forn (j, ny) if (sy[j]) { ly[j] += ex; sy[j] = 0; }
        }
    }
    if (!maxsum) forn (i, nx) forn (j, ny) g[i][j] *= -1;
    forn (i, nx) ret += g[i][mx[i]];
    return ret;
```

```
}
/*================================================================================*\
  3)   次小生成树
\*================================================================================*/
#define N 1010
#define inf 0x3fffffff
typedef int type;
int n, pre[N];
type cost[N][N], lowc[N], maxc[N][N];
bool vis[N];
type prim(){
   type res = 0, minc;
   clr(vis, 0);  clr(pre, 0);
   forn (i, n) forn (j, n) maxc[i][j] = -inf;
   vis[0] = 1;  pre[0] = -1;
   forn (i, n) lowc[i] = cost[0][i];
   forn (i, n - 1) {
      minc = inf; int p = -1;
      forn (j, n) if (!vis[j] && minc > lowc[j]) {
         minc = lowc[j];  p = j;
      }
      if(p == -1) return -1;
      res += minc;
      forn (j, n)
         if (vis[j]) maxc[j][p] = maxc[p][j] =
            max(maxc[j][ pre[p] ], cost[ pre[p] ][p]);
         else if(lowc[j]>cost[p][j]){lowc[j]=cost[p][j];pre[j]=p;}
      vis[p] = 1;
   } return res;
}
type secondmst(){
   type res = prim(), minc = inf;
   forn (i, n) for (int j = i + 1; j < n; ++j)
      if(pre[i] != j && pre[j] != i)
         minc = min(minc, cost[i][j] - maxc[i][j]);
   return res + minc;
}
/*================================================================================*\
  4)   BellmanFord 单源最短路（吉大模板）
\*================================================================================*/
#define typec int // type of cost
const typec inf=0x3f3f3f3f; // max of cost
int n, m, pre[V], edge[E][3]; typec dist[V];
bool relax (int u, int v, typec c){
   if (dist[v] > dist[u] + c) {
      dist[v] = dist[u] + c;
      pre[v] = u; return 1;
   }return 0;
```

```
}
int bellman (int src){
   int i, j;
   for(i=0;i<n;++i){ dist[i]=inf; pre[i]=-1;}
   dist[src] = 0; bool flag;
   for (i=1; i<n; ++i){
      flag = false; // 优化
      for (j=0; j<m; ++j)
         if(relax(edge[j][0], edge[j][1],edge[j][2]))
            flag = true;
      if ( !flag ) break;
   }
   for (j=0; j<m; ++j)
      if( relax(edge[j][0], edge[j][1], edge[j][2]) )
         return 0; // 有负圈
   return 1;
}
/*=============================================================================*\
  5)   Floyd 求最小环（吉大模板）
\*=============================================================================*/
const int N=110;
int n,m,g[N][N],dist[N][N];
int r[N][N],out[N],ct;
int solve(int i,int j,int k){
   ct=0;
   while(j!=i){ out[ct++]=j;j=r[i][j];}
   out[ct++]=i;out[ct++]=k;
   return 0;
}
int main(){
   int i,j,k;
   scanf("%d%d",&n,&m);
   for(i=0;i<n;i++)for(j=0;j<n;j++){
      g[i][j]=INF;r[i][j]=i;
   }
   for(i=0;i<m;i++){
      int x,y,l;
      scanf("%d%d%d",&x,&y,&l);
      if(l<g[--x][--y])g[x][y]=g[y][x]=l;
   }
   memmove(dist,g,sizeof(dist));
   int _min=INF;
   for(k=0;k<n;k++){
      for(i=0;i<k;i++)if(g[k][i]<INF)
         for(j=i+1;j<k;j++)
            if(dist[i][j]<INF && g[k][j]<INF &&
               _min>dist[i][j]+g[k][i]+g[k][j])
                  _min=dist[i][j]+g[k][i]+g[k][j],solve(i,j,k);
```

```
        for(i=0;i<n;i++)if(dist[i][k]<INF)
            for(j=0;j<n;j++)
                if(dist[k][j]<INF && dist[i][j]>dist[i][k]+dist[k][j])
                    dist[i][j]=dist[i][k]+dist[k][j],r[i][j]=r[k][j];
    }
    if(_min<INF){
        for(ct--;ct>=0;ct--){
            printf("%d",out[ct]+1);
            if(ct)printf(" ");
        }
    }
    else printf("No solution.");
    printf("\n");
    return 0;
}
/*============================================================================*\
  6)   Tarjan 强连通分量 O(N + M)
\*============================================================================*/
const int N = 10010;
const int M = 50010;
int e, ev[M], nxt[M], head[N];
bool instack[N];
int dfn[N], low[N], dindex, q[N], ed;
int belong[N], bcnt;  //记录连通分量
void addedge(int u, int v){
    ev[e] = v; nxt[e] = head[u]; head[u] = e++;
}
void tarjan(int u){
    int i, v;
    dfn[u] = low[u] = ++dindex;//时间戳
    instack[u] = 1;
    q[ed++] = u;
    for(i = head[u]; i != -1; i = nxt[i]){
        v = ev[i];
        if (!dfn[v]){
            tarjan(v);
            low[u] = min(low[u], low[v]);
        }else if(instack[v])
            low[u] = min(low[u], dfn[v]);
    }
    if (dfn[u] == low[u]){
        do{
            belong[v = q[--ed]] = bcnt;
            instack[v] = 0;
        }while(v != u);
        bcnt++;
    }
}
```

```
void solve(){
    int n, m, u, v;
    scanf("%d%d", &n, &m);
    e = 0;
    memset(head, -1, sizeof(head));
    while(m--){
        scanf("%d%d", &u, &v);
        addedge(--u, --v);
    }
    ed = bcnt = dindex = 0;
    memset(dfn,0,sizeof(dfn));
    memset(instack, 0, sizeof(instack));
    for(int i = 0; i < n; ++i)
        if(!dfn[i])tarjan(i);
}
/*==========================================================================*\
  7)   2-SAT + 缩点O(N + M)
\*==========================================================================*/
const int N = 8010 * 2;
const int M = 20010 * 2;
int dfn[N], low[N], q[N], ed, dindex;
int belong[N], bcnt, order[N], f[N];
bool instack[N], vis[N];
set<pii> edge;

struct graph {
    int e, head[N];
    int ev[M], nxt[M];
    void init() { e = 0; clr(head, -1); }
    void addedge(int u, int v) {
        ev[e] = v; nxt[e] = head[u]; head[u] = e++;
    }
    void input(int m) {
        int u, v;
        init();
        forn (i, m) {
            scanf("%d%d", &u, &v); // u和v不能共存
            u--; v--;
            addedge(u, v ^ 1);
            addedge(v, u ^ 1);
        }
    }
    void tarjan(int);
    void toposort(int u) {
        vis[u] = 1;
        for (int i = head[u]; ~i; i = nxt[i]) {
            int v = ev[i];
            if (!vis[v]) toposort(v);
```

```
        } order[--dindex] = u;
    }
    void dfs(int u) {
        vis[u] = 1;
        for (int i = head[u]; ~i; i = nxt[i]) {
            int v = ev[i]; if (!vis[v]) dfs(v);
        }
    }
    void build(int);
}g, s;

void graph::build(int n) { // 缩点建新图
    edge.clear();  s.init();
    for (int u = 0; u < n; ++u)
        for (int i = head[u]; ~i; i = nxt[i]) {
            int a = belong[u];
            int b = belong[ev[i]];
            if (a != b && edge.find(MP(b, a)) == edge.end()) {
                edge.insert(MP(b, a));
                s.addedge(b, a);   // 建反向边
            }
        }
}

void graph::tarjan(int u) {...} // 调用前面tarjan的模板

void solve(int n) {
    bcnt = dindex = ed = 0;
    clr(dfn, 0);  clr(instack, 0);
    forn (i, n) if (!dfn[i]) g.tarjan(i);
    forn (i, n) {
        if (belong[i] == belong[i ^ 1]) {
            puts("NIE"); return;   // 无可行解
        }
        f[belong[i]] = belong[i ^ 1];
    }
    g.build(n);
    dindex = bcnt; clr(vis, 0);
    forn (i, bcnt) if (!vis[i]) s.toposort(i);
    set<int> res;
    clr(vis, 0);
    forn (i, bcnt) {
        int u = order[i];
        if (!vis[u]) {
            res.insert(u);
            s.dfs(f[u]);
        }
    }
```

```
    forn (i, n)
        if (res.find(belong[i]) != res.end())
            printf("%d\n", i + 1);
}

int main() {
    int n, m;
    while (~scanf("%d%d", &n, &m)) {
        g.input(m);
        solve(n * 2);
    } return 0;
}
/*================================================================================*\
  8)   LCA
\*================================================================================*/
const int N = 10010;
const int M = N * 2;
const int H = 20;

struct graph {
    int e, head[N];
    int ev[M], nxt[M];
    void init() { e = 0; clr(head, -1); }
    void addedge(int u, int v) {
        ev[e] = v; nxt[e] = head[u]; head[u] = e++;
        ev[e] = u; nxt[e] = head[v]; head[v] = e++;
    }
};

int ln[N];
struct LCA {
    int pnt[N][H], depth[N], stk[N];
    void init() { // 求1-N所有log2(x)的值，只需初始化一次
        ln[0] = ln[1] = 0;
        for (int i = 2; i < N; ++i)
            ln[i] = ln[i >> 1] + 1;
    }
    int getfather(int x, int len) {
        while (len > 0) {
            x = pnt[x][ ln[len] ];
            len -= 1 << ln[len];
        } return x;
    }
    int lca(int x, int y) {
        int low = 0, high = min(depth[x], depth[y]);
        x = getfather(x, depth[x] - high);
        y = getfather(y, depth[y] - high);
        if (x == y) return x;
```

```
        while (high - low > 1) {
            int mid = ln[high - low - 1];
            int nx = pnt[x][mid];
            int ny = pnt[y][mid];
            mid = high - (1 << mid);
            if (nx == ny) low = mid;
            else { high = mid; x = nx; y = ny; }
        }
        return pnt[x][ln[high - low]];
    }

    /********下面求得depth[]和pnt[][]值，也可以通过其他方式求得********/
    void build(const graph& g, int root, int n) {
        forn (i, n) {
            depth[i] = -1;
            clr(pnt[i], -1);
        }
        int top = 1;
        depth[ stk[0] = root ] = 0;
        while (top) { // 这里默认g为一颗树，若为森林需要修改此处
            int u = stk[--top];
            for (int i = g.head[u]; ~i; i = g.nxt[i]) {
                int v = g.ev[i];
                if (depth[v] != -1) continue;
                stk[top++] = v;
                pnt[v][0] = u;
                depth[v] = depth[u] + 1;
            }
        }
        for (int i = 1; i < H; ++i)
            forn (u, n) if (pnt[u][i - 1] != -1)
                pnt[u][i] = pnt[ pnt[u][i - 1] ][i - 1];
    }
};
/*============================================================================*\
  9)   Tarjan(边双连通)
\*============================================================================*/
const int N = 10010, M = 20010 * 2;
struct graph {
    int e, head[N], ev[M], nxt[M];
    void init() { e = 0; clr(head, -1); }
    void addedge(int u, int v) {
        ev[e] = v; nxt[e] = head[u]; head[u] = e++;
        ev[e] = u; nxt[e] = head[v]; head[v] = e++;
    }
};

struct Biconnected {
```

```
int dfn[N], low[N], tim;
int bridge[M]; // 边e为桥则 bridge[e >> 1] == 1
int cut[N];  //点u为割点则 cut[u] == 1
int belong[N], bnt;  // 按桥分块，每个点属于哪个块

void tarjan(const graph& g, int u, bool isroot) {
   dfn[u] = low[u] = ++tim;
   int cnt = 0;
   for (int i = g.head[u]; ~i; i = g.nxt[i]) {
      if (bridge[i >> 1]) continue;
      bridge[i >> 1] = -1;
      int v = g.ev[i];
      if (!dfn[v]) {
         cnt++;
         tarjan(g, v, false);
         if (dfn[u] <= low[v]) cut[u] = 1;
         if (dfn[u] < low[v]) bridge[i >> 1] = 1;
         low[u] = min(low[u], low[v]);
      } else
         low[u] = min(low[u], dfn[v]);
   }
   if (isroot && cnt < 2) cut[u] = 0;
}
void dfs(const graph& g, int u, int mark) {
   belong[u] = mark;
   for (int i = g.head[u]; ~i; i = g.nxt[i]) {
      if (bridge[i >> 1] == 1) continue;
      int v = g.ev[i];
      if (belong[v] == -1) dfs(g, v, mark);
   }
}
void work(const graph& g, int n, graph& tr) {
   tim = 0; clr(cut, 0); clr(dfn, 0); clr(bridge, 0);
   forn (i, n) if (!dfn[i]) tarjan(g, i, true);

   bnt = 0; clr(belong, -1);
   forn (i, n) if (belong[i] == -1) dfs(g, i, bnt++);

   set<pii> edge;  tr.init();
   forn (i, g.e / 2) if (bridge[i] == 1) {  // 缩点建树
      int u = belong[g.ev[i * 2]];
      int v = belong[g.ev[i * 2 + 1]];
      if (edge.find(MP(u, v)) != edge.end()) continue;
      edge.insert(MP(u, v));
      edge.insert(MP(v, u));
      tr.addedge(u, v);
   }
}
```

```
};
/*==============================================================================*\
  10)  Tarjan(点双连通)
\*==============================================================================*/
const int N = 100010;
const int M = 100010 * 2;

struct graph {
   int e, head[N];
   int ev[M], nxt[M];
   void init() { e = 0; clr(head, -1); }
   void addedge(int u, int v) {
      ev[e] = v; nxt[e] = head[u]; head[u] = e++;
      ev[e] = u; nxt[e] = head[v]; head[v] = e++;
   }
};

struct Biconnected {
   int dfn[N], low[N], tim;
   int stk[M], top;
   int cut[N];  //点u为割点则 cut[u] == 1
   int belong[M], bcnt;  // 每条边属于哪个连通块

   void tarjan(const graph& g, int u, int e) {
      int v, edge, son = 0;
      dfn[u] = low[u] = ++tim;
      for (int i = g.head[u]; ~i; i = g.nxt[i]) {
         v = g.ev[i];
         if (i == (e ^ 1)) continue;
         if (dfn[v] >= dfn[u]) continue;
         stk[top++] = i >> 1;
         if (!dfn[v]) {
            son++;
            tarjan(g, v, i);
            low[u] = min(low[u], low[v]);
            if (dfn[u] <= low[v]) {
               cut[u] = true;
               do {
                  edge = stk[--top];
                  belong[edge] = bcnt;
               } while (edge != i >> 1);
               bcnt++;
            }
         } else
            low[u] = min(low[u], dfn[v]);
      }
      if (e == -1 && son < 2) cut[u] = 0;
   }
```

```
    void work(const graph& g, int &n, graph& tr) {
        bcnt = tim = top = 0;
        clr(dfn, 0); clr(cut, 0);
        forn (i, n) if (!dfn[i]) tarjan(g, i, -1);

        /*********下面缩点(割点和每个块分别缩为一点)*********/
        set<pii> edge;
        int tot = n;
        n = bcnt;  tr.init();
        forn (u, tot) if (cut[u] == 1) {
            for (int i = g.head[u]; ~i; i = g.nxt[i]) {
                int z = belong[i >> 1];
                if (edge.find(MP(n, z)) != edge.end()) continue;
                tr.addedge(n, z);
                edge.insert(MP(n, z));
                edge.insert(MP(z, n));
            }
            n++;
        }
    }
};
/*=============================================================================*\
  11)  最大团(输出方案)
\*=============================================================================*/
const int N = 110;
int n, m, g[N][N], id[N];
int list[N][N], s[N], degree[N], behide[N];
int found, curmax, curobj;


void sortdegree() {
    for (int i = 1; i <= n; ++i) id[i] = i;
    for (int j, k, l, i = 1; i <= n; ++i) {
        for (k = i, j = i + 1; j <= n; ++j)
            if (degree[j] < degree[k]) k = j;
        if (k != i) {
            swap(id[i], id[k]);
            swap(degree[i], degree[k]);
            for (l = 1; l <= n; ++l) swap(g[i][l], g[k][l]);
            for (l = 1; l <= n; ++l) swap(g[l][i], g[l][k]);
        }
    }
}

void dfs(int d, vi &t) {
    if (d - 1 > curmax) {found = 1; return ;}
    int i, j;
```

```
    for (i = 1; i < list[d - 1][0] - curmax + d; ++i)
        if (!found && d + behide[list[d - 1][i] + 1] > curmax &&
                (list[d-1][0]==i || d+behide[list[d-1][i+1]]>curmax)) {
            for (j = i + 1, list[d][0] = 0; j <= list[d - 1][0]; ++j)
                if (g[list[d - 1][j]][list[d - 1][i]])
                    list[d][++list[d][0]] = list[d - 1][j];
            t[d - 1] = list[d - 1][i];
            if (list[d][0] == 0 || d + behide[list[d][1]] > curmax)
                dfs(d + 1, t);
        }
}

void gao() {
    vi ans(1, 1);
    sortdegree(); behide[n + 1] = 0; behide[n] = 1;
    for (int j, i = n - 1; i > 0; --i) {
        curmax = behide[i + 1]; found = list[1][0] = 0;
        for (j = i + 1; j <= n; ++j)
            if (g[j][i]) list[1][++list[1][0]] = j;
        vi tmp(curmax + 1);
        tmp[0] = i;
        dfs(2, tmp); behide[i] = curmax + found;
        if (found) ans = tmp;
    }
    printf("%d\n", sz(ans));
    for (int i = 0; i < sz(ans); ++i)
        ans[i] = id[ans[i]];
    sort(ans.begin(), ans.end());
    for (int i = 0; i < sz(ans); ++i) {
        if (i) printf(" ");
        printf("%d", ans[i]);
    }
    puts("");
}

void solve() {
    int u, v;
    clr(g, 0);
    scanf("%d%d", &n, &m);
    for (int i = 0; i < m; ++i) {
        scanf("%d%d", &u, &v);
        g[u][v] = g[v][u] = 1;
    }
    for (int i = 1; i <= n; ++i)
        for (int j = 1; j <= n; ++j)
            g[i][j] ^= 1;
    gao();
}
```

```
/*================================================================================*\
  12)  Minimal Steiner Tree O(4^k*V+2^k*E*logE)
\*================================================================================*/
typedef int typec;
const int V = 1000, E = 4010, K = 8;
const typec inf = 0x3f3f3f3f;
int ev[E], nxt[E], head[V], vis[V], ch[V], e, n, k;
typec cost[E], dp[V][1 << K];
struct node {
   int v; typec c;
   node(int v = 0, typec c = 0) : v(v), c(c) {}
   bool operator < (const node &u) const {
      return c > u.c;
   }
};
void addedge(int u, int v, typec c) {
   ev[e] = v; cost[e] = c; nxt[e] = head[u]; head[u] = e++;
   ev[e] = u; cost[e] = c; nxt[e] = head[v]; head[v] = e++;
}
int steiner(int ch[], int k) {
   memset(dp, 0x3f, sizeof(dp));
   for (int i = 0; i < k; ++i) dp[ch[i]][1 << i] = 0;
   for (int i = 0; i < n; ++i) dp[i][0] = 0;
   int tot = 1 << k;
   priority_queue<node> que;
   for (int i = 0; i < tot; ++i) {
      for (int j = 0; j < n; ++j)
         for (int u = i; u > 0; u = (u - 1) & i)
            dp[j][i] = min(dp[j][i], dp[j][u] + dp[j][i ^ u]);
//权值在点上时 dp[j][i] = min(dp[j][i], dp[j][u] + dp[j][i ^ u] - cost[j]);
      memset(vis, 0, sizeof(vis));
      for (int j = 0; j < n; ++j)
         if (dp[j][i] != inf)
            que.push(node(j, dp[j][i]));
      while (!que.empty()) {
         int u = que.top().v; que.pop();
         if (vis[u]) continue;
         vis[u] = 1;
         for (int j = head[u]; ~j; j = nxt[j]) {
            int v = ev[j];
            if (dp[v][i] > dp[u][i] + cost[j]) { // 权值在点上用cost[v]
               dp[v][i] = dp[u][i] + cost[j]; // 权值在点上用cost[v]
               que.push(node(v, dp[v][i]));
            }
         }
      }
   } return dp[ch[0]][(1 << k) - 1];
}
```

```
/*==========================================================================*\
  13)  最大流 SAP(V^2 * E)(递归版)
\*==========================================================================*/
//typedef double typec;
//const typec inf = 1e100;
//const double eps = 1e-8
typedef int typec;
const typec inf = 0x3f3f3f3f;
const int N = 210, M = 410 * 2;

struct FlowNetwork {
   int n, e, head[N], d[N], vd[N], pre[N];
   int nxt[M], ev[M];
   typec c[M];
   void init() { e = 0; clr(head, -1); }
   void addedge(int u, int v, typec w) {
      ev[e]=v; c[e]=w; nxt[e]=head[u]; head[u]=e++;
      ev[e]=u; c[e]=0; nxt[e]=head[v]; head[v]=e++;//无向图c[e]=w;
   }
   typec maxflow(int u, int s, int t, typec flow){
      if(u == t)return flow;
      typec temp, ans = 0;
      for(int i = head[u]; i != -1; i = nxt[i]){
         //if(c[i] < eps || d[u] != d[ev[i]] + 1)continue;
         if(c[i] <= 0 || d[u] != d[ev[i]] + 1)continue;
         temp = maxflow(ev[i], s, t, min(c[i], flow - ans));
         c[i] -= temp; c[i ^ 1] += temp;
         ans += temp;
         if(ans == flow)return ans;
      }
      if(d[s] >= n)return ans;
      if(--vd[d[u]] == 0)d[s] = n;
      vd[++d[u]]++;
      return ans;
   }
   typec sap(int s, int t, int n) {
      clr(d, 0); clr(vd, 0);
      this->n = vd[0] = n;
      typec ans = 0;
      while(d[s] < n) ans += maxflow(s, s, t, inf);
      return ans;
   }
};
/*==========================================================================*\
  14)  最大流 SAP(V^2 * E)(非递归)
\*==========================================================================*/
//typedef double typec;
//const typec inf = 1e100;
```

```
//const double eps = 1e-8
typedef int typec;
const typec inf = 0x3f3f3f3f;
const int N = 210, M = 410 * 2;

struct FlowNetwork {
   int e, head[N], d[N], vd[N], pre[N], cur[N];
   int nxt[M], eu[M], ev[M];
   typec c[M];
   void init() { e = 0; clr(head, -1); }
   void addedge(int u, int v, typec w) {
      eu[e]=u; ev[e]=v; c[e]=w; nxt[e]=head[u]; head[u]=e++;
      eu[e]=v; ev[e]=u; c[e]=0; nxt[e]=head[v]; head[v]=e++;
            //无向图中第二个c[e]=w;
   }
   typec sap(int s, int t, int n){
      int i, u;
      clr(d, 0); clr(vd, 0);
      vd[0] = n;
      cur[u = s] = head[s];
      pre[s] = -1;
      typec temp, ans = 0;
      while (d[s] < n) {
         if(u == t){
            for(temp = inf, i = pre[u]; ~i; i = pre[eu[i]])
               temp = min(temp, c[i]);
            for(i = pre[u]; ~i; i = pre[eu[i]]){
               c[i] -= temp; c[i ^ 1] += temp;
            }
            ans += temp;  u = s;
         }
         for (i = cur[u]; ~i; i = nxt[i])
            //if (c[i] > eps && d[u] == d[ev[i]] + 1){
            if (c[i] > 0 && d[u] == d[ev[i]] + 1){
               cur[u] = i;    //当前弧优化
               pre[u = ev[i]] = i;
               break;
            }
         if(i == -1){
            cur[u] = head[u];
            if (--vd[d[u]] == 0)break;
            vd[++d[u]]++;
            if(u != s)u = eu[pre[u]];
         }
      }
      return ans;
   }
};
```

```
/*==========================================================================*\
  15)  最大流(预流推进)(watashi 代码)
\*==========================================================================*/
/* watashi的预流推进代码(ZOJ2364/SGU212) */
const int MAXN = 1515;
const int MAXM = 300300;

inline int RE(int i) { return i ^ 1; }

struct Edge { int v, c; };

struct FlowNetwork {
   int n, m, source, sink;
   vector<int> e[MAXN];
   Edge edge[MAXM * 2];

   void init(int n, int source, int sink) {
      this->n = n;
      this->m = 0;
      this->source = source;
      this->sink = sink;
      for (int i = 0; i < n; ++i) {
         e[i].clear();
      }
   }

   void addEdge(int a, int b, int c) {
      edge[m].v = b;
      edge[m].c = c;
      e[a].push_back(m++);
      edge[m].v = a;
      edge[m].c = 0;
      e[b].push_back(m++);
   }

   int c[MAXN * 2];
   int d[MAXN];
   int w[MAXN];
   int done[MAXN];

   void bfs() {
      queue<int> q;
      fill(c, c + n * 2, 0);
      c[n + 1] = n - 1;
      fill(d, d + n, n + 1);
      d[source] = n;
      d[sink] = 0;
      q.push(sink);
```

```
    while (!q.empty()) {
        int u = q.front();
        q.pop();
        --c[n + 1];
        ++c[d[u]];
        for (size_t i = 0; i < e[u].size(); ++i) {
            Edge &cra = edge[RE(e[u][i])];
            int v = edge[e[u][i]].v;
            if (d[v] == n + 1 && cra.c > 0) {
                d[v] = d[u] + 1;
                q.push(v);
            }
        }
    }
}

int hlpp() {
    vector<queue<int> > q(n * 2);
    vector<bool> mark(n, false);
    int todo = -1;

    bfs();
    mark[source] = mark[sink] = true;
    fill(w, w + n, 0);
    for (size_t i = 0; i < e[source].size(); ++i) {
        Edge &arc = edge[e[source][i]];
        Edge &cra = edge[RE(e[source][i])];
        int v = arc.v;
        w[v] += arc.c;
        cra.c += arc.c;
        arc.c = 0;
        if (!mark[v]) {
            mark[v] = true;
            q[d[v]].push(v);
            todo = max(todo, d[v]);
        }
    }
    fill(done, done + n, 0);
    while (todo >= 0) {
        if (q[todo].empty()) {
            --todo;
            continue;
        }
        int u = q[todo].front();
        mark[u] = false;
        q[todo].pop();
        while (done[u] < (int)e[u].size()) {
            Edge &arc = edge[e[u][done[u]]];
```

```
            int v = arc.v;
            if (d[u] == d[v] + 1 && arc.c > 0) {
               Edge &cra = edge[RE(e[u][done[u]])];
               int f = min(w[u], arc.c);
               w[u] -= f;
               w[v] += f;
               arc.c -= f;
               cra.c += f;
               if (!mark[v]) {
                  mark[v] = true;
                  q[d[v]].push(v);
               }
               if (w[u] == 0) {
                  break;
               }
            }
            ++done[u];
         }
         if (w[u] > 0) {
            int du = d[u];
            --c[d[u]];
            d[u] = n * 2;
            for (size_t i = 0; i < e[u].size(); ++i) {
               Edge &arc = edge[e[u][i]];
               int v = arc.v;
               if (d[u] > d[v] + 1 && arc.c > 0) {
                  d[u] = d[v] + 1;
                  done[u] = i;
               }
            }
            ++c[d[u]];
            if (c[du] == 0) {
               for (int i = 0; i < n; ++i) {
                  if (d[i] > du && d[i] < n + 1) {
                     --c[d[i]];
                     ++c[n + 1];
                     d[i] = n + 1;
                  }
               }
            }
            mark[u] = true;
            q[d[u]].push(u);
            todo = d[u];
         }
      }

      return w[sink];
   }
```

```
};

int main() {
   int re;
   int n, m, l, r, s, t;
   FlowNetwork fn;

   scanf("%d", &re);
   for (int ri = 1; ri <= re; ++ri) {
      if (ri > 1) {
         puts("");
      }
      scanf("%d%d%d", &n, &m, &l);
      for (int i = 0; i < n; ++i) {
         scanf("%d", &r);
         if (r == 1) {
            s = i;
         } else if (r == l) {
            t = i;
         }
      }
      fn.init(n, s, t);
      for (int i = 0; i < m; ++i) {
         scanf("%d%d%d", &s, &t, &r);
         fn.addEdge(s - 1, t - 1, r);
      }
      fn.hlpp();
      for (int i = 0; i < m; ++i) {
         printf("%d\n", fn.edge[RE(i << 1)].c);
      }
   }

   return 0;
}
/*============================================================================*\
  16)  最小费用流(SPFA)
\*============================================================================*/
// 注：费用不能有负环
typedef int typef;
typedef int typec;
const int N = 5100, M = 40010;
const typef inff = 0x3f3f3f3f;
const typec infc = 0x3f3f3f3f;

struct MinCostMaxFlow {
   int e, ev[M], nxt[M], head[N];
   typec cost[M], dist[N];
   typef cap[M];
```

```
    int pnt[N], road[N], q[N], bg, ed;
    bool vis[N];

    void init() { e = 0; clr(head, -1); }

    void addedge(int u, int v, typef f, typec c) { //u->v flow=f, cost=c
        ev[e]=v; cap[e]=f; cost[e]=c; nxt[e]=head[u]; head[u]=e++;
        ev[e]=u; cap[e]=0; cost[e]=-c; nxt[e]=head[v]; head[v]=e++;
    }

    bool spfa(int s, int t, int n) {
        forn (i, n) dist[i] = infc, vis[i] = 0;
        bg = ed = dist[s] = 0;
        pnt[s] = s; q[ed++] = s;
        while (bg != ed) {
            int u = q[bg++]; vis[u] = 0;
            if (bg == N) bg = 0;
            for (int i = head[u]; ~i; i = nxt[i]) {
                if (cap[i] <= 0)continue;
                int v = ev[i];
                if (dist[v] > dist[u] + cost[i]) {
                    dist[v] = dist[u] + cost[i];
                    pnt[v] = u; road[v] = i;
                    if (!vis[v]) {
                        q[ed++] = v; vis[v] = 1;
                        if(ed == N)ed = 0;
                    }
                }
            }
        }
        return dist[t] != infc;
    }

    void mincost(int s, int t, int n, typef &f, typec &c) {
        c = f = 0;
        while(spfa(s, t, n)){
            typef minf = inff;
            for(int u = t; u != s; u = pnt[u])
                minf = min(minf, cap[road[u]]);
            for(int u = t; u != s; u = pnt[u]){
                cap[road[u]] -= minf;
                cap[road[u] ^ 1] += minf;
            }
            f += minf;
            c += minf * dist[t];
        }
    }
};
```

```
/*=============================================================================*\
  17)  最小费用流(ZKW)
\*=============================================================================*/
const int V=440, E= 4010*2;

struct MinCostMaxFlow {
   struct etype {
      int t, c, f;
      etype *next, *pair;
      etype() {}
      etype(int T,int C,int F,etype* N): t(T), c(C), f(F), next(N) {}
      void* operator new(unsigned, void* p){return p;}
   } *e[V], Te[E+E], *Pe;

   int S, T, n, pis, cost;
   bool v[V];

   void init() { clr(e, 0); Pe = Te; }

   void addedge(int s, int t, int f, int c) {
      e[s] = new(Pe++) etype(t, +c, f, e[s]);
      e[t] = new(Pe++) etype(s, -c, 0, e[t]);
      e[s]->pair = e[t];
      e[t]->pair = e[s];
   }

   int aug(int u, int m) {
      if (u == T) return cost += pis * m, m;
      v[u] = true;
      int f = m;
      for (etype *i = e[u]; i; i = i->next)
         if (i->f && i->c == 0 && !v[i->t]) {
            int d = aug(i->t, min(f, i->f));
            i->f -= d, i->pair->f += d, f -= d;
            if (f == 0) return m;
         }
      return m - f;
   }

   bool modlabel() {
      static int d[V]; memset(d, 0x3f, sizeof(d)); d[T] = 0;
      static deque<int> Q; Q.push_back(T);
      while(Q.size()) {
         int dt, u = Q.front(); Q.pop_front();
         for(etype *i = e[u]; i; i = i->next)
            if(i->pair->f && (dt = d[u] - i->c) < d[i->t])
               (d[i->t] = dt) <= d[Q.size() ? Q.front() : 0]
                     ? Q.push_front(i->t) : Q.push_back(i->t);
```

```
        }
        forn (i, n) for(etype *j = e[i]; j; j = j->next)
            j->c += d[j->t] - d[i];
        pis += d[S];
        return d[S] < inf;
    }

    int mincost(int s, int t, int tot) {
        S = s; T = t; n = tot;
        pis = cost = 0;
        while(modlabel())
            do memset(v, 0, sizeof(v));
            while(aug(S, inf));
        return cost;
    }
};
/*=============================================================================*\
  18)  一般图匹配（带花树）
\*=============================================================================*/
/*  从网上摘抄的代码，不明其中细节，不过验证过其正确性
    注意：下标从1开始   */
#define MAXE 250*250*2
#define MAXN 250
deque<int> Q;
//g[i][j]存放关系图：i,j是否有边,match[i]存放i所匹配的点
bool g[MAXN][MAXN], inque[MAXN], inblossom[MAXN];
int match[MAXN], pre[MAXN], base[MAXN];

//找公共祖先
int findancestor(int u, int v) {
    bool inpath[MAXN] = { false };
    while (1) {
        u = base[u];
        inpath[u] = true;
        if (match[u] == -1) break;
        u = pre[match[u]];
    }
    while (1) {
        v = base[v];
        if (inpath[v]) return v;
        v = pre[match[v]];
    }
}

//压缩花
void reset(int u, int anc) {
    while (u != anc) {
        int v = match[u];
```

```
      inblossom[base[u]] = 1;
      inblossom[base[v]] = 1;
      v = pre[v];
      if (base[v] != anc)
         pre[v] = match[u];
      u = v;
   }
}

void contract(int u, int v, int n) {
   int anc = findancestor(u, v);
   clr(inblossom, 0);
   reset(u, anc);
   reset(v, anc);
   if (base[u] != anc) pre[u] = v;
   if (base[v] != anc) pre[v] = u;
   for (int i = 1; i <= n; i++)
      if (inblossom[base[i]]) {
         base[i] = anc;
         if (!inque[i]) {
            Q.push_back(i);
            inque[i] = 1;
         }
      }
}

bool dfs(int S, int n) {
   for (int i = 0; i <= n; i++)
      pre[i] = -1, inque[i] = 0, base[i] = i;
   Q.clear();
   Q.push_back(S);
   inque[S] = 1;
   while (!Q.empty()) {
      int u = Q.front();
      Q.pop_front();
      for (int v = 1; v <= n; v++) {
         if (g[u][v] && base[v] != base[u] && match[u] != v) {
            if (v == S || (match[v] != -1 && pre[match[v]] != -1))
               contract(u, v, n);
            else if (pre[v] == -1) {
               pre[v] = u;
               if (match[v] != -1)
                  Q.push_back(match[v]), inque[match[v]] = 1;
               else {
                  u = v;
                  while (u != -1) {
                     v = pre[u];
                     int w = match[v];
```

```
                    match[u] = v;
                    match[v] = u;
                    u = w;
                }
                return true;
            }
        }
    }
}
return false;
}

int work(int n) {
    clr(match,-1);
    int ans = 0;
    for (int i = 1; i <= n; i++)
        if (match[i] == -1 && dfs(i, n))
            ans++;
    return ans;
}
/*============================================================================*\
  19)  无根树的最小树形图
\*============================================================================*/
/*
有固定根的最小树形图求法O(VE)：交大和吉大模板上都有这里就不熬述了
对于不固定根的最小树形图，wy教主有一巧妙方法。摘录如下：
新加一个点，和每个点连权相同的边，这个权大于原图所有边权的和，这样这个图固定跟的最小树形图和
原图不固定跟的最小树形图就是对应的了。
*/
```

5. 字符串

```
/*==========================================================================*\
  1)   AC 自动机
\*==========================================================================*/
const int N = 1000010;
const int M = 10001 * 50;
const int ch = 26;
int sw[128];//string swap每个字符对应的Index，方便模板化
int trie[M][ch + 1], top, n, q[M], bg, ed, fail[M];
bool vis[M];
char str[N];
void init(){
   top = 1;
   memset(trie[0], 0, sizeof(trie[0]));
   for(char i = 'a', j = 0; i <= 'z'; ++i, ++j)
      sw[i] = j;
}
void ins(char *s, int rank = 1){//rank的值随题目要求而变
   int rt, nxt;
   for(rt = 0; *s; rt = nxt, ++s){
      nxt = trie[rt][sw[*s]];
      if(nxt == 0){
         memset(trie[top], 0, sizeof(trie[top]));
         trie[rt][sw[*s]] = nxt = top++;
      }
   }
// trie[rt][ch] = rank;
   trie[rt][ch]++;
}
void makefail(){
   int u, v;
   fail[0] = bg = ed = 0;
   for(int i = 0; i < ch; ++i)
      if(q[ed] = trie[0][i])
         fail[q[ed++]] = 0;
   while(bg < ed){
      u = q[bg++];
      for(int i = 0; i < ch; ++i){
         if(v = trie[u][i]){
            q[ed++] = v;
            fail[v] = trie[fail[u]][i];
            //对trie[v][ch]按trie[fail[v]][ch]里的内容进行处理
         }else
            trie[u][i] = trie[fail[u]][i];
      }
   }
}
```

```
int ac(char *s){
   int res = 0; memset(vis, 0, sizeof(vis));
   for(int i = 0; *s; ++s){
      i = trie[i][sw[*s]];
      for(int j = i; j && !vis[j]; j = fail[j]){
         vis[j] = 1;
         if(trie[j][ch])
            res += trie[j][ch];
      }
   } return res;
}
void input(){
   init(); char tmp[55];
   scanf("%d", &n);
   for(int i = 1; i <= n; ++i){
      scanf("%s", tmp); ins(tmp);
   } scanf("%s", str);
}
void solve(){
   makefail();
   printf("%d\n", ac(str));
}
/*================================================================================*\
  2)   后缀数组O(N*log(N)) + RMQ O(N*log(N))
\*================================================================================*/
/*
rank[0...7]: 4 6 8 1 2 3 5 7
string:      a a b a a a a b
-----------------------------------------
 sa[1] = 3 : a a a a b       height[1] = 0
 sa[2] = 4 : a a a b         height[2] = 3
 sa[3] = 5 : a a b           height[3] = 2
 sa[4] = 0 : a a b a a a a b height[4] = 3
 sa[5] = 6 : a b             height[5] = 1
 sa[6] = 1 : a b a a a a b   height[6] = 2
 sa[7] = 7 : b               height[7] = 0
 sa[8] = 2 : b a a a a b     height[8] = 1
*/
const int N = 1000010;
int ua[N], ub[N], us[N];
int cmp(int *r,int a,int b,int l){
   return r[a]==r[b]&&r[a+l]==r[b+l];
}
void da(int *r,int *sa,int n,int m){ //da(r, sa, n + 1, 256);(r[n] = 0)
   int i,j,p,*x=ua,*y=ub,*t;        //r[]存放原字符串，且从char变为int
   for(i=0;i<m;i++) us[i]=0;  //sa[i]表示排名为i的后缀起始下标(i>=1,sa[i]>=0)
   for(i=0;i<n;i++) us[x[i]=r[i]]++;
   for(i=1;i<m;i++) us[i]+=us[i-1];
```

```
    for(i=n-1;i>=0;i--) sa[--us[x[i]]]=i;
    for(j=1,p=1;p<n;j*=2,m=p){
      for(p=0,i=n-j;i<n;i++) y[p++]=i;
      for(i=0;i<n;i++) if(sa[i]>=j) y[p++]=sa[i]-j;
      for(i=0;i<m;i++) us[i]=0;
      for(i=0;i<n;i++) us[x[i]]++;
      for(i=1;i<m;i++) us[i]+=us[i-1];
      for(i=n-1;i>=0;i--) sa[--us[x[y[i]]]]=y[i];
      for(t=x,x=y,y=t,p=1,x[sa[0]]=0,i=1;i<n;i++)
        x[sa[i]]=cmp(y,sa[i-1],sa[i],j)?p-1:p++;
    }
}
int rank[N],height[N]; //height[i]为排第i-1和第i的后缀的公共前缀长度
void calheight(int *r,int *sa,int n){
    int i,j,k=0;
    for(i=1;i<=n;i++) rank[sa[i]]=i;
    for(i=0;i<n;height[rank[i++]]=k)
      for(k?k--:0,j=sa[rank[i]-1];r[i+k]==r[j+k];k++);
}
int *RMQ = height; // RMQ为查询的数组,这里RMQ=height
//int RMQ[N];
int mm[N];
int best[20][N]; //best[i][j]表示[j, j + 2^i)区间中的最小值
void initRMQ(int n){
    int i,j,a,b;
    for(mm[0]=-1,i=1;i<=n;i++)
      mm[i]=((i&(i-1))==0)?mm[i-1]+1:mm[i-1];
    for(i=1;i<=n;i++) best[0][i]=i;
    for(i=1;i<=mm[n];i++)
    for(j=1;j<=n+1-(1<<i);j++){
      a=best[i-1][j];
      b=best[i-1][j+(1<<(i-1))];
      if(RMQ[a]<RMQ[b]) best[i][j]=a;
      else best[i][j]=b;
    }
}
int askRMQ(int a,int b){
    int t;
    t=mm[b-a+1];b-=(1<<t)-1;
    a=best[t][a];b=best[t][b];
    return RMQ[a]<RMQ[b]?a:b;
}
int lcp(int a,int b){ //后缀r[a]和r[b]的公共前缀长度
    int t;
    a=rank[a];b=rank[b];
    if(a>b) {t=a;a=b;b=t;}
    return(height[askRMQ(a+1,b)]);
}
```

```
/*=============================================================================*\
  3)   KMP
\*=============================================================================*/
int fail[M];

void makefail(char *t, int lt){
   t--;
   for(int i = 1, j = 0; i <= lt + 1; ++i, ++j){
      fail[i] = j;
      while(j > 0 && t[i] != t[j]) j = fail[j];
   }
}
int kmp(char *s, int ls, char *t, int lt){
   --s; --t; int cnt = 0;
   for(int i = 1, j = 1; i <= ls; ++i, ++j){
      while(j > 0 && s[i] != t[j])j = fail[j];
      if(j == lt){
         cnt++;
         j = fail[lt + 1] - 1;
      }
   } return cnt; // 返回出现了几次
}
/*=============================================================================*\
  4)   字符串最小表示
\*=============================================================================*/
// flag = 1 为最小表示；flag = 0 为最大表示
int mpres(char *s, int len, bool flag) {
   int i = 0, j = 1, k = 0, t;
   while (i < len && j < len && k < len) {
      t = s[(i + k) % len] - s[(j + k) % len];
      if (t == 0) { ++k; continue; }
      if ((t > 0) == flag)
         i = max(i + k + 1, j);
      else
         j = max(j + k + 1, i);
      if (i == j) ++i;
      k = 0;
   } return min(i, j);
}
/*=============================================================================*\
  5)   扩展 KMP
\*=============================================================================*/
const int N = 100010;
char a[N], b[N];
int lcp1[N], lcp2[N];

void SelfLcp(char *t, int lt, int *lcp) {
```

```
    int j = 0, k;
    while (j + 1 < lt && t[j] == t[j + 1]) ++j;
    lcp[1] = j; k = 1;
    for (int i = 2; i < lt; ++i) {
        int len = k + lcp[k] - 1, l = lcp[i - k];
        if (l < len - i + 1) lcp[i] = l;
        else {
            j = max(0, len - i + 1);
            while (i + j < lt && t[j] == t[i + j]) ++j;
            lcp[i] = j; k = i;
        }
    }
}

//lcp1[i]为s[i,|s|]和t的公共前缀长，lcp2[i]为t[i,|t|]和t的公共前缀长
void ExtKmp(char *s, int ls, int *lcp1, char *t, int lt, int *lcp2){
    SelfLcp(t, lt, lcp2);
    int j = 0, k;
    while (j < ls && j < lt && s[j] == t[j]) ++j;
    lcp1[0] = j; k = 0;
    for (int i = 1; i < ls; ++i) {
        int len = k + lcp1[k] - 1, l = lcp2[i - k];
        if (l < len - i + 1) lcp1[i] = l;
        else {
            j = max(0, len - i + 1);
            while (i + j < ls && j < lt && s[i + j] == t[j]) ++j;
            lcp1[i] = j; k = i;
        }
    }
}
/*============================================================================*\
  6)   O(n)回文子串算法
\*============================================================================*/
/*
   原串:  w a a b w s w f d
新串r[]:  $ # w # a # a # b # w # s # w # f # d #
辅助数组P:  1 2 1 2 3 2 1 2 1 2 1 4 1 2 1 2 1 2 1
p[id]- 1 就是该回文子串在原串中的长度
*/
const int N = 110010 * 2;
char str[N];
int r[N], p[N];

void pk(int *r, int n, int *p) {
   int i, id, mx = 0;
   for (i = 1; i < n; ++i) {
      if (mx > i) p[i] = min(p[2 * id - i], mx - i);
      else p[i] = 1;
```

```
        for (; r[i + p[i]] == r[i - p[i]]; p[i]++);
        if (p[i] + i > mx) {
            mx = p[i] + i;
            id = i;
        }
    }
}

void solve() {
    scanf("%s", str);
    int len = strlen(str);
    int n = 0;
    r[n++] = '$'; r[n++] = '#';
    forn (i, len) {
        r[n++] = str[i];
        r[n++] = '#';
    }
    r[n] = 0;
    pk(r, n, p);
    int ans = 0;
    for (int i = 1; i < n; ++i)
        ans = max(ans, p[i] - 1);
    printf("%d\n", ans);
}
```

6. 计算几何

```
/*==========================================================================*\
  1)    二维几何基本操作
\*==========================================================================*/
#define sqr(x) ((x)*(x))
const double eps = 1e-8;
const double pi = acos(-1.0);

int dcmp(double x) {
   if (x < -eps) return -1; else return x > eps;
}
struct cpoint {
   double x, y;
   cpoint(){}
   cpoint(double x, double y) : x(x), y(y) {}
   cpoint operator + (const cpoint &u) const {
      return cpoint(x + u.x, y + u.y);
   }
   cpoint operator - (const cpoint &u) const {
      return cpoint(x - u.x, y - u.y);
   }
   cpoint operator * (const double &s) const {
      return cpoint(x * s, y * s);
   }
   cpoint operator / (const double &s) const {
      return cpoint(x / s, y / s);
   }
   double operator * (const cpoint &u) const { // 叉积
      return x * u.y - y * u.x;
   }
   double operator ^ (const cpoint &u) const { // 点积
      return x * u.x + y * u.y;
   }

   cpoint turnleft() const { // 左转90度
      return cpoint(-y, x);
   }
   cpoint turnleft(double ang) const {
      double c = cos(ang), s = sin(ang);
      return cpoint(x * c - y * s, y * c + x * s);
   }
   cpoint turnright() const { // 右转90度
      return cpoint(y, -x);
   }
   cpoint turnright(double ang) const {
      double c = cos(ang), s = sin(ang);
      return cpoint(x * c + y * s, y * c - x * s);
```

```
    }
    cpoint trunc(double s) { // 向量长度变为s
        double r = s / len();
        return cpoint(x * r, y * r);
    }
    double len() { return sqrt(x * x + y * y); }
    void get() { scanf("%lf%lf", &x, &y); }

    bool operator == (const cpoint& u) const {
        return dcmp(x - u.x) == 0 && dcmp(y - u.y) == 0;
    }
    bool operator < (const cpoint& u) const {
        if (dcmp(x - u.x)) return x < u.x;
        else return dcmp(y - u.y) < 0;
    }
};

double cross(cpoint o, cpoint p, cpoint q) { // 叉积
    return (p - o) * (q - o);
}
double dot(cpoint o, cpoint p, cpoint q) { // 点积
    return (p - o) ^ (q - o);
}
double dis(cpoint p, cpoint q) { // 两点距离
    return sqrt(sqr(p.x - q.x) + sqr(p.y - q.y));
}
double dissqr(cpoint p, cpoint q) {    // 距离平方
    return sqr(p.x - q.x) + sqr(p.y - q.y);
}
double angle(cpoint p0,cpoint p1,cpoint p2) {//计算角p1p0p2,范围在(-pi, pi]
    double cr = cross(p0, p1, p2);
    double dt = dot(p0, p1, p2);
    if (dcmp(cr) == 0) cr = 0.0;
    if (dcmp(dt) == 0) dt = 0.0;
    return atan2(cr, dt); //p0p1到p0p2逆时针为正
}
bool PointOnLine(cpoint p0, cpoint p1, cpoint p2) { // 判点p0在直线上p1p2
    return dcmp(cross(p0, p1, p2)) == 0;
}
bool PointOnSegment(cpoint p0, cpoint p1, cpoint p2){//判点p0在线段上p1p2
    return dcmp(cross(p0, p1, p2)) == 0 && dcmp(dot(p0, p1, p2)) <= 0;
}
//  判断直线相对位置 1=相交, 0=平行, -1=重合,  cp返回交点
int LineInter(cpoint p1, cpoint p2, cpoint p3, cpoint p4, cpoint &cp){
    double u = cross(p1, p2, p3), v = cross(p2, p1, p4);
    if (dcmp(u + v)) {
        cp = (p3 * v + p4 * u) / (u + v);
        return 1;
```

```
    }
    if (dcmp(u)) return 0;
    if (dcmp(cross(p3, p4, p1))) return 0;
    return -1;
}
// 判断线段相交，cp返回交点
int SegmentInter(cpoint p1,cpoint p2,cpoint p3,cpoint p4,cpoint &cp){
    int ret = LineInter(p1, p2, p3, p4, cp);
    if (ret == 1)
        return PointOnSegment(cp, p1, p2) && PointOnSegment(cp, p3, p4);
    if (ret==-1&&(PointOnSegment(p1,p3,p4)||PointOnSegment(p2,p3,p4)
            || PointOnSegment(p3, p1, p2) || PointOnSegment(p4, p1, p2) ))
        return -1;
    return 0;
}

// 判线段和直线相交：线段的两个端点和直线上任意两点的叉积异号即相交(叉积为0则点在直线上)

// 判断线段相交
int SegmentInterTest(cpoint p1, cpoint p2, cpoint p3, cpoint p4) {
    if (max(p1.x, p2.x) + eps < min(p3.x, p4.x) ||
        max(p3.x, p4.x) + eps < min(p1.x, p2.x) ||
        max(p1.y, p2.y) + eps < min(p3.y, p4.y) ||
        max(p3.y, p4.y) + eps < min(p1.y, p2.y)) return 0 ;
    int d1 = dcmp(cross(p3, p4, p2));
    int d2 = dcmp(cross(p3, p4, p1));
    int d3 = dcmp(cross(p1, p2, p4));
    int d4 = dcmp(cross(p1, p2, p3));
    if (d1 * d2 == 1 || d3 * d4 == 1) return 0 ;
    if (d1 == 0 && d2 == 0 && d3 == 0 && d4 == 0) return -1;
    return 1 ;
}
// 判点在多边形内 0 = outside; 1 = inside; 2 = boundary
int PointInPolygon(cpoint cp, cpoint p[], int n) {
    int i, k, d1, d2, wn = 0;
    p[n] = p[0];
    for (i = 0; i < n; i++) {
        if (PointOnSegment(cp, p[i], p[i + 1])) return 2 ;
        k = dcmp(cross(p[i], p[i + 1], cp));
        d1 = dcmp(p[i + 0].y - cp.y);
        d2 = dcmp(p[i + 1].y - cp.y);
        if (k > 0 && d1 <= 0 && d2 > 0) wn++;
        if (k < 0 && d2 <= 0 && d1 > 0) wn--;
    }
    return wn != 0;
}
// 点到直线的距离，cp为点p0在直线上的射影
double PointToLine(cpoint p0, cpoint p1, cpoint p2, cpoint &cp) {
```

```
    double d = dis(p1, p2);
    double s = cross(p1, p2, p0) / d ;
    cp.x = p0.x + s * (p2.y - p1.y) / d;
    cp.y = p0.y - s * (p2.x - p1.x) / d;
    return fabs(s);  // s为有向距离
}
// 点在直线上的射影(可以拓展到三维)
cpoint PointProjLine(cpoint p0, cpoint p1, cpoint p2) {
    double t = dot(p1, p2, p0) / dot(p1, p2, p2);
    return p1 + (p2 - p1) * t;
}
// 求多边形面积(凸凹都可)
double PolygonArea(cpoint p[], int n) {
    p[n] = p[0]; double s = 0;
    for (int i = 0; i < n; ++i) s += p[i] * p[i + 1];
    return s; // 顺时针方向s为负
}
/*==========================================================================*\
  2)   二维凸包
\*==========================================================================*/
cpoint bp;
int PolarCmp(const cpoint &p1, const cpoint &p2) {
    int u = dcmp(cross(bp, p1, p2));
    return u > 0 || (u == 0 && dcmp(dissqr(bp, p1)-dissqr(bp, p2)) < 0);
}
// ch中的点为逆时针顺序，边界无三点共线
void graham(cpoint pin[], int n, cpoint ch[], int &m) {
    int i, j, k, u, v;
    memcpy(ch, pin, n * sizeof(cpoint));
    for (i = k = 0; i < n; ++i) {
        u = dcmp(ch[i].x - ch[k].x);
        v = dcmp(ch[i].y - ch[k].y);
        if (v < 0 || (v == 0 && u < 0)) k = i;
    }
    bp = ch[k];
    sort(ch, ch + n, PolarCmp);
    n =  unique(ch, ch + n) - ch; // 注意重载"=="
    if (n <= 1) { m = n; return ;}
    if (dcmp(cross(ch[0], ch[1], ch[n - 1])) == 0) {
        m = 2; ch[1] = ch[n - 1]; return;
    }
    ch[n++] = ch[0];
    for (i = 1, j = 2; j < n; ++j) {
        while (i > 0 && dcmp(cross(ch[i - 1], ch[i], ch[j])) <= 0) i--;
        ch[++i] = ch[j];
    }
    m = i;
}
```

```
/*================================================================================*\
  3)   Pick 公式（网格）
\*================================================================================*/
/*给定顶点坐标均是整点（或正方形格点）的简单多边形，其面积S和内部格点数目a、边上格点数目b的关系： S = a + b/2 - 1 */
/*================================================================================*\
  4)   三角形的费马点
\*================================================================================*/
//到三顶点的距离和最短，费马点
/*当三角形最大的顶角小于120度的时候，三角形内一点到三顶点之间的距离最小是与三顶点夹角都成120度的点P；当最到顶点大于等于120度，该顶点取最小值
补充一下，当三角形的最大角小于120度时，费尔码点在三角形内，作法有多种，可以从任二边向外作等边三角形，联接正三角形的顶点和原三角形的对角，两者联线交点即所求。*/
/*================================================================================*\
  5)   旋转卡壳求凸包直径 O(N)
\*================================================================================*/
//返回值凸包直径的平方（最远两点距离的平方）
double rotating(cpoint cp[], int n){
   int i = 1; double res = 0.0;
   cp[n] = cp[0];
   for(int j = 0; j < n; j ++) {
      while(dcmp( fabs(cross(cp[i + 1], cp[j], cp[j + 1])) -
         fabs(cross(cp[i], cp[j], cp[j + 1])) ) > 0)
         i = (i + 1) % n;
      //cp[i]和cp[j],cp[i + 1]和cp[j + 1]可能是对踵点
      res = max(res, max(dissqr(cp[i], cp[j]),
         dissqr(cp[i + 1], cp[j + 1])));
   }
   return res;
}
/*================================================================================*\
  6)   旋转卡壳求两凸包最短距离 O(N)
\*================================================================================*/
double PointToSeg(cpoint p0, cpoint p1, cpoint p2) {//点到线段距离
   cpoint cp;
   double d = PointToLine(p0, p1, p2, cp);
   if (PointOnSegment(cp, p1, p2)) return d;
   else return min(dis(p0, p1), dis(p0, p2));
}
//两平行线段距离
double DisPallSeg(cpoint p0,cpoint p1,cpoint p2, cpoint p3) {
   return min( min(PointToSeg(p0, p2, p3),PointToSeg(p1, p2, p3)),
               min(PointToSeg (p2, p0, p1), PointToSeg(p3, p0, p1)) );
}
void anticlockwise(cpoint cp[], int n) {
   for (int i = 0; i < n - 2; ++i) {
      double t = cross(cp[i], cp[i + 1], cp[i + 2]);
      if (dcmp(t) > 0) return ;
```

```
            if (dcmp(t) < 0) {
                reverse(cp, cp + n);
                return;
            }
        }
    }
// 旋转卡壳，两凸包必须逆时针，并且需要把两凸包交换再做一遍
double rotating(cpoint ch1[], int n, cpoint ch2[], int m) {
    int p = 0, q = 0;
    for (int i = 0; i < n; ++i)
        if (dcmp(ch1[i].y - ch1[p].y) < 0)
            p = i;
    for (int i = 0; i < m; ++i)
        if (dcmp(ch2[i].y - ch2[q].y) > 0)
            q = i;
    ch1[n] = ch1[0];
    ch2[m] = ch2[0];
    double tmp, res = 1e99;
    for (int i = 0; i < n; ++i) {
        while ((tmp = cross(ch1[p], ch1[p + 1], ch2[q + 1]) -
            cross(ch1[p], ch1[p + 1], ch2[q])) > eps)
            q = (q + 1) % m;
        if (dcmp(tmp) < 0)
            res = min(res, PointToSeg(ch2[q], ch1[p], ch1[p + 1]));
        else
            res = min(res,DisPallSeg(ch1[p],ch1[p+1],ch2[q],ch2[q+1]));
        p = (p + 1) % n;
    }
    return res;
}
double solve() {
    anticlockwise(ch1, n);
    anticlockwise(ch2, m);
    return min(rotating(ch1, n, ch2, m), rotating(ch2, m, ch1, n));
}
/*================================================================================*\
  7)   半平面交O(N * log(N))
\*================================================================================*/
struct cvector {
    cpoint s, e;
    double ang, d;
};
void setline(double x1,double y1,double x2,double y2,cvector &v) {
    v.s.x = x1; v.s.y = y1;
    v.e.x = x2; v.e.y = y2;
    v.ang = atan2(y2 - y1, x2 - x1);
    if (dcmp(x1 - x2))v.d = (x1 * y2 - x2 * y1) / fabs(x1 - x2);
    else              v.d = (x1 * y2 - x2 * y1) / fabs(y1 - y2);
```

```
}
bool parallel(const cvector &a, const cvector &b) { //判向量平行
   double u = (a.e.x - a.s.x) * (b.e.y - b.s.y)
         - (a.e.y - a.s.y) * (b.e.x - b.s.x);
   return dcmp(u) == 0;
}

//求两向量(直线)交点(两向量不能平行或重合)
cpoint CrossPoint(const cvector &a, const cvector &b) {
   cpoint res;
   double u = cross(a.s, a.e, b.s), v = cross(a.e, a.s, b.e);
   res.x = (b.s.x * v + b.e.x * u) / (u + v);
   res.y = (b.s.y * v + b.e.y * u) / (u + v);
   return res;
}
//半平面交排序函数[优先顺序: 1.极角2.前面的直线在后面的左边]
bool VecCmp(const cvector &l, const cvector &r) {
   if (dcmp(l.ang - r.ang)) return l.ang < r.ang;
   return l.d < r.d;
}

cvector deq[N]; //用于计算的双端队列

//     获取半平面交的多边形（多边形的核）
//     注意:1.半平面在向量左边, 2.函数会改变vec[]中的值
//函数运行后如果n[即返回多边形的点数量]为0则
//不存在半平面交的多边形（不存在区域或区域面积无穷大）
void HalfPanelCross(cvector vec[], int n, cpoint cp[], int &m) {
   int i, tn; m = 0;
   sort(vec, vec + n, VecCmp);
   for (i = tn = 1; i < n; ++i) //平面在向量左边的筛选
      if(dcmp(vec[i].ang - vec[i - 1].ang))
         vec[tn++] = vec[i];
   n = tn;
   int bot = 0, top = 1;
   deq[0] = vec[0];
   deq[1] = vec[1]; // vec[]大小不可小于2
   for (i = 2; i < n; ++i) {
      if (parallel(deq[top], deq[top - 1]) ||
         parallel(deq[bot], deq[bot + 1]) ) return ;
      while ( bot < top && dcmp( cross(vec[i].s, vec[i].e,
         CrossPoint(deq[top], deq[top - 1])) ) < 0 )
         top--;
      while ( bot < top && dcmp( cross(vec[i].s, vec[i].e,
         CrossPoint(deq[bot], deq[bot + 1])) ) < 0 )
         bot++;
      deq[++top] = vec[i];
   }
```

```
    while ( bot < top && dcmp( cross(deq[bot].s, deq[bot].e,
        CrossPoint(deq[top], deq[top - 1])) ) < 0 )
        top--;
    while ( bot < top && dcmp( cross(deq[top].s, deq[top].e,
        CrossPoint(deq[bot], deq[bot + 1])) ) < 0 )
        bot++;
    if (top <= bot + 1) return ; // 两条或两条以下的直线，面积无穷大
    for (i = bot; i < top; ++i)
        cp[m++] = CrossPoint(deq[i], deq[i + 1]);
    if (bot < top + 1)
        cp[m++] = CrossPoint(deq[bot], deq[top]);
    for (i = 0; i < m; ++i) {
        if (dcmp(cp[i].x) == 0) cp[i].x = 0;
        if (dcmp(cp[i].y) == 0) cp[i].y = 0;
    }
}

/***********************传入的半平面为方程时需要***************************/
// 1 = 构造向量成功， 0 = 无解，2 = 有无穷解
int makevec(double a,double b,double c,cvector &v) {//ax + by + c>=0
    if (dcmp(b) > 0)
        setline(0, -c / b, 1, -(a + c) / b, v);
    else if (dcmp(b) < 0)
        setline(1, -(a + c) / b, 0, -c / b, v);
    else if (dcmp(a) > 0)
        setline(-c / a, 0, -c / a, -1, v);
    else if (dcmp(a) < 0)
        setline(-c / a, 0, -c / a, 1, v);
    else if (dcmp(c) >= 0)
        return 2;
    else
        return 0;
    return 1;
}
/***********************传入的半平面为方程时需要***************************/

int n, m;
cvector v[N];
cpoint cp[N];
void solve() {
    scanf("%d", &n);
    double x1, x2, y1, y2;
    for (int i = 0; i < n; ++i) {
        scanf("%lf%lf%lf%lf", &x1, &y1, &x2, &y2);
        setline(x1, y1, x2, y2, v[i]);
    }
    double high = 10000.0;
    double low = 0.0;
```

```
    setline(low, low, high, low, v[n++]);
    setline(high, low, high, high, v[n++]);
    setline(high, high, low, high, v[n++]);
    setline(low, high, low, low, v[n++]);

    HalfPanelCross(v, n, cp, m);
    if (m < 3)
        printf("0.0\n");
    else {
        cp[m] = cp[0];
        double area = 0;
        for (int i = 0; i < m; ++i)
            area += cp[i].x * cp[i + 1].y - cp[i].y * cp[i + 1].x;
        printf("%.1lf\n", area / 2);
    }
}
/*================================================================================*\
  8)   最小圆覆盖 (随机增量法O(N))
\*================================================================================*/
void center(cpoint p0, cpoint p1, cpoint p2, cpoint &cp) {//三角形外心
    double a1=p1.x-p0.x, b1=p1.y-p0.y, c1=(sqr(a1)+sqr(b1))/2;
    double a2=p2.x-p0.x, b2=p2.y-p0.y, c2=(sqr(a2)+sqr(b2))/2;
    double d = a1 * b2 - a2 * b1;
    cp.x = p0.x + (c1 * b2 - c2 * b1) / d;
    cp.y = p0.y + (a1 * c2 - a2 * c1) / d;
}
void MinCir(cpoint cp[], int n, cpoint &c, double &r) {
    random_shuffle(cp, cp + n);
    c = cp[0]; r = 0;
    for (int i = 1; i < n; ++i) {
        if (dcmp(dis(cp[i], c) - r) <= 0) continue;
        c = cp[i]; r = 0;
        for (int j = 0; j < i; ++j) {
            if (dcmp(dis(cp[j], c) - r) <= 0) continue;
            c.x = (cp[i].x + cp[j].x) / 2;
            c.y = (cp[i].y + cp[j].y) / 2;
            r = dis(c, cp[j]);
            for (int k = 0; k < j; ++k) {
                if (dcmp(dis(cp[k], c) - r) <= 0) continue;
                center(cp[i], cp[j], cp[k], c);
                r = dis(c, cp[k]);
            }
        }
    }
}
/*================================================================================*\
  9)   最近圆对(二分 + 扫描线)
\*================================================================================*/
```

```
const int N = 50010;
const double eps = 1e-8;
int n, lft[N], rht[N];  set<int> s;
struct circle {  double x, y, r; }cir[N];

int dcmp(double x) {if (x < -eps) return -1; else return x > eps;}
bool cmp(circle a, circle b) { return a.y < b.y; }
bool cmp2(int i, int j){return cir[i].x-cir[i].r < cir[j].x-cir[j].r;}
bool cmp3(int i, int j) {return cir[i].x+cir[i].r < cir[j].x+cir[j].r;}

double dis(circle a, circle b) {
    return sqrt(sqr(a.x - b.x) + sqr(a.y - b.y)) - a.r - b.r;
}
bool inter(circle a, circle b, double delta) {
    return dcmp(dis(a, b) - delta * 2) < 0;
}
bool insert(int i, double mid) {
   set<int>::iterator it = s.insert(lft[i]).first;
   if (it != s.begin()) {
      if (inter(cir[*--it], cir[lft[i]], mid))
         return false;
      ++it;
   }
   if (++it != s.end() && inter(cir[*it], cir[lft[i]], mid))
      return false;
   return true;
}
bool remove(int j, double mid) {
   set<int>::iterator it = s.find(rht[j]);
   if (it != s.begin() && it != --s.end()) {
      int a = *--it;  ++it;
      int b = *++it;
      if (inter(cir[a], cir[b], mid))
         return false;
   }
   s.erase(rht[j]);
   return true;
}
bool check(double mid) {
    s.clear();
    for (int i = 0, j = 0; i < n || j < n;) {
      if (j == n) {
         if (!insert(i++, mid)) return false;
      } else if (i == n) {
         if (!remove(j++, mid)) return false;
      } else if (dcmp(cir[lft[i]].x - cir[lft[i]].r - mid
         - cir[rht[j]].x - cir[rht[j]].r - mid) <= 0) {
            if (!insert(i++, mid)) return false;
```

```
        } else {
            if (!remove(j++, mid)) return false;
        }
    } return true;
}

void solve() {
    scanf("%d", &n);
    for (int i = 0; i < n; ++i) {
        scanf("%lf%lf%lf", &cir[i].x, &cir[i].y, &cir[i].r);
        lft[i] = rht[i] = i;
    }
    sort(cir, cir + n, cmp);
    sort(lft, lft + n, cmp2);
    sort(rht, rht + n, cmp3);
    double mid, low = 0, high = dis(cir[0], cir[1]) / 2;
    while (dcmp(high - low)) {
        mid = (high + low) / 2;
        if (check(mid)) low = mid;
        else high = mid;
    }
    printf("%lf\n", low + high);
}
/*================================================================================*\
  10)  圆和多边形面积的交
\*================================================================================*/
double r;   int n; //多边形点数

struct cpoint {
   double x, y;
   cpoint(){}
   cpoint(double x, double y) : x(x), y(y) {}
}pin[N]; //需要初始化多边形

int dcmp(double x) {
   if (x < -eps) return -1; else return x > eps;
}

void gao(cpoint u, cpoint v, double r, vector<cpoint>& ret) {
   ret.push_back(u);
   double a = sqr(v.x - u.x) + sqr(v.y - u.y);
   double b = 2 * ((v.x - u.x) * u.x + (v.y - u.y) * u.y);
   double c = sqr(u.x) + sqr(u.y) - r * r;
   double d = b * b - 4 * a * c;
   if (d < 0) return;   d = sqrt(d);
   double t1 = (-b + d) / (2 * a);
   double t2 = (-b - d) / (2 * a);
   if (t1 > t2) swap(t1, t2);
```

```
    if (dcmp(t1) > 0 && dcmp(1 - t1) > 0)
        ret.push_back( cpoint(u.x+(v.x-u.x)*t1, u.y+(v.y-u.y)*t1));
    if (dcmp(t2) > 0 && dcmp(1 - t2) > 0 && dcmp(t2 - t1) > 0)
        ret.push_back( cpoint(u.x+(v.x-u.x)*t2, u.y+(v.y-u.y)*t2));
}

double tri(const cpoint& u, const cpoint& v) {
    return u.x * v.y - u.y * v.x;
}

double arc(const cpoint& u, const cpoint& v, double r) {
    double t = atan2(v.y, v.x) - atan2(u.y, u.x);
    while (t > pi) t -= 2 * pi;
    while (t < -pi) t += 2 * pi;
    return r * r * t;
}

// 圆和多边形的公共面积(圆心在原点)
double area(double r, cpoint pin[], int n) {
    double ans = 0; pin[n] = pin[0];
    vector<cpoint> v;
    for (int i = 0; i < n; ++i)
        gao(pin[i], pin[i + 1], r, v);
    v.push_back(v.front());
    for (int i = 1; i < (int)v.size(); ++i) {
        if (sqrt( sqr((v[i - 1].x + v[i].x) / 2)
                + sqr((v[i - 1].y + v[i].y) / 2) ) < r)
            ans += tri(v[i - 1], v[i]);
        else
            ans += arc(v[i - 1], v[i], r);
    } return fabs(ans / 2);
}
/*=============================================================================*\
  11)  圆的面积并和交 O(N^2*log(N))
\*=============================================================================*/
const int N = 1010;
const double eps = 1e-8;
const double pi = acos(-1.0);
double area[N]; // area[i]记录了覆盖i层的面积
int n;
int dcmp(double x) {
    if (x < -eps) return -1; else return x > eps;
}
struct cp {
    double x, y, r, angle; int d; // d表示层数
    cp(){}
    cp(double xx, double yy, double ang = 0, int t = 0) {
        x = xx;  y = yy;  angle = ang;  d = t;
```

```
    }
    void get() {
        scanf("%lf%lf%lf", &x, &y, &r);
        d = 1; // 注意每个圆的层数要初始化为1
    }
}cir[N], tp[N * 2];
double dis(cp a, cp b) {
    return sqrt(sqr(a.x - b.x) + sqr(a.y - b.y));
}
double cross(cp p0, cp p1, cp p2) {
    return (p1.x - p0.x) * (p2.y - p0.y) - (p1.y - p0.y) * (p2.x - p0.x);
}
int CirCrossCir(cp p1,double r1, cp p2,double r2, cp &cp1, cp &cp2){
    double mx = p2.x - p1.x, sx = p2.x + p1.x, mx2 = mx * mx;
    double my = p2.y - p1.y, sy = p2.y + p1.y, my2 = my * my;
    double sq = mx2 + my2, d = -(sq - sqr(r1 - r2)) * (sq - sqr(r1 + r2));
    if (d + eps < 0) return 0; if (d < eps) d = 0; else d = sqrt(d);
    double x = mx * ((r1 + r2) * (r1 - r2) + mx * sx) + sx * my2;
    double y = my * ((r1 + r2) * (r1 - r2) + my * sy) + sy * mx2;
    double dx = mx * d, dy = my * d; sq *= 2;
    cp1.x = (x - dy) / sq; cp1.y = (y + dx) / sq;
    cp2.x = (x + dy) / sq; cp2.y = (y - dx) / sq;
    if (d > eps) return 2; else return 1;
}

bool circmp(const cp& u, const cp& v) {
    return dcmp(u.r - v.r) < 0;
}

bool cmp(const cp& u, const cp& v) {
    if (dcmp(u.angle - v.angle)) return u.angle < v.angle;
    return u.d > v.d;
}

double calc(cp cir, cp cp1, cp cp2) {
    double ans = (cp2.angle - cp1.angle) * sqr(cir.r)
        - cross(cir, cp1, cp2) + cross(cp(0, 0), cp1, cp2);
    return ans / 2;
}

void CirUnion(cp cir[], int n, double area[]) {
    memset(area + 1, 0, sizeof(double) * n);
    cp cp1, cp2;
    sort(cir, cir + n, circmp);
    for (int i = 0; i < n; ++i)
        for (int j = i + 1; j < n; ++j)
            if (dcmp(dis(cir[i], cir[j]) + cir[i].r - cir[j].r) <= 0)
                cir[i].d++;
```

```
    for (int i = 0; i < n; ++i) {
        int tn = 0, cnt = 0;
        for (int j = 0; j < n; ++j) {
            if (i == j) continue;
            if (CirCrossCir(cir[i], cir[i].r, cir[j], cir[j].r,
                cp2, cp1) < 2) continue;
            cp1.angle = atan2(cp1.y - cir[i].y, cp1.x - cir[i].x);
            cp2.angle = atan2(cp2.y - cir[i].y, cp2.x - cir[i].x);
            cp1.d = 1;    tp[tn++] = cp1;
            cp2.d = -1;   tp[tn++] = cp2;
            if (dcmp(cp1.angle - cp2.angle) > 0) cnt++;
        }
        tp[tn++] = cp(cir[i].x - cir[i].r, cir[i].y, pi, -cnt);
        tp[tn++] = cp(cir[i].x - cir[i].r, cir[i].y, -pi, cnt);
        sort(tp, tp + tn, cmp);
        int s = cir[i].d + tp[0].d;
        for (int j = 1; j < tn; ++j) {
            area[s] += calc(cir[i], tp[j - 1], tp[j]);
            s += tp[j].d;
        }
    }
}

void solve() {
    for (int i = 0; i < n; ++i)
        cir[i].get();
    CirUnion(cir, n, area);
    for (int i = 1; i <= n; ++i) {
        area[i] -= area[i + 1];
        printf("[%d] = %.3lf\n", i, area[i]);
    }
}

/*============================================================================*\
  12)  凸多边形面积并O(N^2*log(N))
\*============================================================================*/
// 注意 cpoint 重载 "==" 和 "<"
#define forn(i, n) for(int i = 0; i < (int)(n); ++i)
#define MP make_pair
#define SZ(a) (int)(a.size())

const int N = 510;
const int M = 6;

struct poly {
    int n;
    cpoint cp[M];
```

```
   void get() {
//    scanf("%d", &n);
      n = 4;
      forn (i, n) cp[i].get();
   }
   bool check() {
      cp[n] = cp[0];
      double area = 0;
      forn (i, n) area += cp[i] * cp[i + 1];
      if (dcmp(area) == 0) return false;
      if (area < 0) reverse(cp, cp + n);
      cp[n] = cp[0];
      return true;
   }
}ply[N];

int n;
typedef pair<cpoint, cpoint> segment;
#define line cpoint
segment seg1[N * M], seg2[N * M];
line lin[N * M]; //line借用cpoint结构分别用x,y表示直线y = kx + b中的k,b

line getline(cpoint u, cpoint v) {
   double k;
   if (dcmp(u.x - v.x) == 0) k = 1e200;
   else k = (u.y - v.y) / (u.x - v.x);
   return line(k, u.y - k * u.x);
}

bool getcut(line lin, cpoint a, cpoint b, cpoint& cp) {
   double t = lin.x * (a.x - b.x) - (a.y - b.y);
   if (dcmp(t) == 0) return false;
   double x = ((a * b) - (a.x - b.x) * lin.y) / t;
   cp = cpoint(x, lin.x * x + lin.y);
   return true;
}

double calc(segment seg[], int m) {
   int ln = 0; double ans = 0;
   cpoint A, B, cp;
   forn (i, m) lin[ln++] = getline(seg[i].first, seg[i].second);
   sort(lin, lin + ln);
   ln = unique(lin, lin + ln) - lin;

   forn (i, ln) {
      vector<pair<double, int> > mark;
      forn (j, n) {
         bool touch = 0;
```

```
            forn (k, ply[j].n)
               if (lin[i] == getline(ply[j].cp[k], ply[j].cp[k + 1])) {
                  touch = 1; break;
               }
            if (touch) continue; // 共线
            vector<cpoint> cut;
            forn (k, ply[j].n) {
               A = ply[j].cp[k];
               B = ply[j].cp[k + 1];
               if (!getcut(lin[i], A, B, cp)) continue;
               if (dcmp((A - cp) ^ (B - cp)) <= 0)
                  cut.push_back(cp);
            }
            sort(cut.begin(), cut.end());
            cut.resize(unique(cut.begin(), cut.end()) - cut.begin());
            if (SZ(cut) == 2) {
               mark.push_back(MP(cut[0].x, 0));
               mark.push_back(MP(cut[1].x, 1));
            }
         }

         forn (j, m)
            if (lin[i] == getline(seg[j].first, seg[j].second)) {
               double mn = min(seg[j].first.x, seg[j].second.x);
               double mx = max(seg[j].first.x, seg[j].second.x);
               mark.push_back(MP(mn, 2));
               mark.push_back(MP(mx, 3));
            }

         sort(mark.begin(), mark.end());

         double last = mark[0].first;
         int in = 0, ct = 0;
         forn (j, SZ(mark)) {
            double y0 = lin[i].x * last + lin[i].y;
            double y1 = lin[i].x * mark[j].first + lin[i].y;
            if (!in && ct)
               ans += (y0 + y1) * (mark[j].first - last) / 2;
            last = mark[j].first;
            if (mark[j].second == 0) in++;
            if (mark[j].second == 1) in--;
            if (mark[j].second == 2) ct++;
            if (mark[j].second == 3) ct--;
         }
      }
      return ans;
   }
```

```
double PolyUnion(poly ply[], int n) {
   int n1, n2, tot = n;
   n1 = n2 = n = 0;
   forn (i, tot) if (ply[i].check())
      ply[n++] = ply[i]; // 去除共线多边形
   forn (i, n) forn (j, ply[i].n) {
      cpoint A = ply[i].cp[j];
      cpoint B = ply[i].cp[j + 1];
      if (dcmp(A.x - B.x) > 0) seg1[n1++] = MP(A, B);
      if (dcmp(A.x - B.x) < 0) seg2[n2++] = MP(A, B);
   }
   return calc(seg1, n1) - calc(seg2, n2);
}
/*==============================================================================*\
  13)  三维几何基本操作
\*==============================================================================*/
struct vpoint {
   double x, y, z;
   vpoint(){}
   vpoint(double x, double y, double z) : x(x), y(y), z(z) {}
   vpoint operator + (const vpoint &u) const {
      return vpoint(x + u.x, y + u.y, z + u.z);
   }
   vpoint operator - (const vpoint &u) const {
      return vpoint(x - u.x, y - u.y, z - u.z);
   }
   vpoint operator * (const double &s) const {
      return vpoint(x * s, y * s, z * s);
   }
   vpoint operator / (const double &s) const {
      return vpoint(x / s, y / s, z / s);
   }
   vpoint operator * (const vpoint &u) const { // 叉积
      return vpoint(
            y * u.z - z * u.y,
            z * u.x - x * u.z,
            x * u.y - y * u.x  );
   }
   double operator ^ (const vpoint &u) const { // 点积
      return x * u.x + y * u.y + z * u.z;
   }

   vpoint trunc(double s) { // 向量长度变为s
      double r = s / len();
      return vpoint(x * r, y * r, z * r);
   }
   double len() { return sqrt(x * x + y * y + z * z); }
   void get() { scanf("%lf%lf%lf", &x, &y, &z); }
```

```
    double angle(vpoint v) { // 计算转到v向量的夹角
        return acos((*this ^ v) / (len() * v.len()));
    }

    bool operator == (const vpoint &u) const {
        return dcmp(x - u.x) == 0 && dcmp(y - u.y) == 0
               && dcmp(z - u.z) == 0;
    }
    bool operator < (const vpoint &u) const {
        if (dcmp(x - u.x)) return x < u.x;
        if (dcmp(y - u.y)) return y < u.y;
        return dcmp(z - u.z) < 0;
    }
};

// 三角形面积*2
double area(vpoint a, vpoint b, vpoint c) {
    return ((b - a) * (c - a)).len();
}
// 四面体有向体积*6 ( a在平面bcd的正向时为正(右手定则) )
double volume(vpoint a, vpoint b, vpoint c, vpoint d) {
    return (b - a) * (c - a) ^ (d - a);
}
// 判四点共面
bool onplane(vpoint a, vpoint b, vpoint c, vpoint d) {
    return dcmp((b - a) * (c - a) ^ (d - a)) == 0;
}



/**********************点线关系**********************/

// 判点p在直线AB上 (没用过但比较可靠)
bool PointOnLine(vpoint p, vpoint A, vpoint B) {
    return dcmp( ((A - p) * (B - p)).len() ) == 0;
}
// 判点p在线段AB上 (没用过但比较可靠)
bool PointOnSeg(vpoint p, vpoint A, vpoint B) {
    return dcmp( ((A - p) * (B - p)).len() ) == 0
           && dcmp( (A - p) ^ (B - p) ) <= 0;
}
// 点p在直线AB上的射影
vpoint PointProjLine(vpoint p, vpoint A, vpoint B) {
    double t = ((p - A) ^ (B - A)) / ((B - A) ^ (B - A));
    return A + (B - A) * t;
}
```

```
/**********************线线关系**********************/

// 异面直线AB和CD的距离 (没用过但比较可靠)
double dist(vpoint A, vpoint B, vpoint C, vpoint D) {
    vpoint n = (B - A) * (D - C);
    return fabs(n ^ (C - A)) / n.len();
}

// 判定直线AB和CD位置关系，并求交点 (没用过)
// -2:异面  -1:重合  0:平行  1:相交
int LineInter(vpoint A, vpoint B, vpoint C, vpoint D, vpoint& tp) {
    if (dcmp( (B - A) * (C - A) ^ (D - A) )) return -2;
    vpoint v = (B - A) * (D - C);
    vpoint u = (C - A) * (D - C);
    double t;
    if (dcmp(v.z))      t = u.z / v.z;
    else if (dcmp(v.x)) t = u.x / v.x;
    else if (dcmp(v.y)) t = u.y / v.y;
    else if (dcmp( ((C - A) * (C - B)).len() )) return 0;
    else return -1;
    tp = A + (B - A) * t;
    return 1;
}

// 判定线段AB和CD位置关系，并求交点 (没用过)
// -2:异面  -1:共线且有重叠  0:不相交  1:相交
int SegmentInter(vpoint A, vpoint B, vpoint C, vpoint D, vpoint& tp)
{
    int ret = LineInter(A, B, C, D, tp);
    if (ret == -2 || ret == 0) return ret;
    if (ret == 1)
        return PointOnSeg(tp, A, B) && PointOnSeg(tp, C, D);
    if (ret == -1 && (PointOnSeg(A, C, D) || PointOnSeg(B, C, D)
            || PointOnSeg(C, A, B) || PointOnSeg(D, A, B) ))
        return -1;
    return 0;
}




/**********************点面关系**********************/

// 点A到平面n.x * x + n.y * y + n.z * z + d = 0的距离
double PointToPlane(vpoint A, vpoint n, double d) {
    return fabs((A ^ n) + d) / n.len();
}
```

```
// 点A在平面n.x*(x-o.x)+n.y*(y-o.y)+n.z*(z-o.z) = 0上的射影(点法式)
vpoint PointProjPlane(vpoint A, vpoint n, vpoint o) {
   double t = ((A - o) ^ n) / (n ^ n);
   return A - n * t;
}
```

```
/**********************线面关系**********************/

// 直线AB和平面n.x*x+n.y*y+n.z*z+d=0的交点(n为法向量)
// -1:直线在平面上   0:没有交点(平行)    1:有交点
int LineInterPlane(vpoint A, vpoint B, vpoint n,
      double d, vpoint &vp) {
   B = B - A;
   double s = (A ^ n) + d;
   double t = n ^ B;
   if (dcmp(t) == 0)  // 法向量和直线垂直
      return dcmp(s) ? 0 : -1;
   vp = A - B * (s / t);
   return 1;
}
```

```
/**********************面面关系**********************/

// 求平面 n1.x*x+n1.y*y+n1.z*z+d1=0 和
// 平面 n2.x*x+n2.y*y+n2.z*z+d2=0 的 交线AB (没用过)
// -1:重合    0:平行    1:相交
int PlaneInter(vpoint n1, double d1, vpoint n2, double d2,
      vpoint& A, vpoint& B) {
   vpoint v = n1 * n2;
   vpoint n = n1 * d2 - n2 * d1;
   if (dcmp(v.z))      A = vpoint(n.y/v.z, -n.x/v.z, 0);
   else if (dcmp(v.x)) A = vpoint(0, n.z/v.x, -n.y/v.x);
   else if (dcmp(v.y)) A = vpoint(-n.z/v.y, 0, n.x/v.y);
   else if (dcmp( n.len() )) return 0;
   else return -1;
   B = A + v.trunc(10.0); // 改变v值以免B点坐标过大
   return 1;
}
```

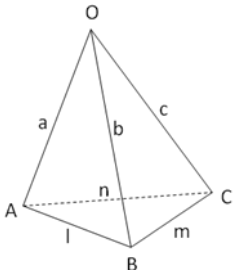
```
/**********************旋转**********************/
// 点p绕向量AB旋转ang角度后的坐标(旋转按照右手定则)
vpoint rotate(vpoint p, vpoint A, vpoint B, double ang) {
    vpoint o = PointProjLine(p, A, B);
    vpoint r = p - o;
    vpoint e = (B - A).trunc(1.0) * r;
    return r * cos(ang) + e * sin(ang) + o;
}
/*============================================================================*\
  14)  三维凸包O(N^2)
\*============================================================================*/
/**************************************
  Name: 3D Convex Hull
  Author: Isun
  Date: 1-10-10 17:20
  Description: 求三维空间点集凸包—增量法O(n^2)
**************************************/
#define eps 1e-7
#define MAXV 305

struct pt{ //三维点
    double x, y, z;
    pt(){}
    pt(double _x, double _y, double _z): x(_x), y(_y), z(_z){}
    pt operator - (const pt p1){return pt(x - p1.x, y - p1.y, z - p1.z);}
    pt operator * (pt p) {     //叉乘
        return pt(y*p.z-z*p.y, z*p.x-x*p.z, x*p.y-y*p.x);
    }
    double operator ^ (pt p){return x*p.x+y*p.y+z*p.z;}  //点乘
};

struct _3DCH{
    struct fac{
        int a, b, c;    //表示凸包一个面上三个点的编号
        bool ok;     //表示该面是否属于最终凸包中的面
    };
    int n;    //初始点数
    pt P[MAXV]; //初始点
    int cnt; //凸包表面的三角形数
    fac F[MAXV*8]; //凸包表面的三角形
    int to[MAXV][MAXV];

    double vlen(pt a){return sqrt(a.x*a.x+a.y*a.y+a.z*a.z);}//向量长度
    double area(pt a,pt b,pt c){return vlen((b-a)*(c-a));}//三角形面积*2
    double volume(pt a, pt b, pt c, pt d) {  //四面体有向体积*6
        return (b-a)*(c-a)^(d-a);
    }
```

```
double ptof(pt &p, fac &f){ //正：点在面同向
   pt m = P[f.b]-P[f.a], n = P[f.c]-P[f.a], t = p-P[f.a];
   return (m * n) ^ t;
}

void deal(int p, int a, int b){
   int f = to[a][b];
   fac add;
   if (F[f].ok){
      if (ptof(P[p], F[f]) > eps)
         dfs(p, f);
      else{
         add.a = b, add.b = a, add.c = p, add.ok = 1;
         to[p][b] = to[a][p] = to[b][a] = cnt;
         F[cnt++] = add;
      }
   }
}

void dfs(int p, int cur){
   F[cur].ok = 0;
   deal(p, F[cur].b, F[cur].a);
   deal(p, F[cur].c, F[cur].b);
   deal(p, F[cur].a, F[cur].c);
}

bool same(int s, int t){
   pt &a = P[F[s].a], &b = P[F[s].b], &c = P[F[s].c];
   return fabs(volume(a, b, c, P[F[t].a])) < eps
      && fabs(volume(a, b, c, P[F[t].b])) < eps
      && fabs(volume(a, b, c, P[F[t].c])) < eps;
}

//构建三维凸包
void construct(){
   cnt = 0;
   if (n < 4) return;

/*********此段是为了保证前四个点不公面，若已保证，可去掉********/
   bool sb = 1;
   for (int i = 1; i < n; i++){ //使前两点不公点
      if (vlen(P[0] - P[i]) > eps){
         swap(P[1], P[i]);
         sb = 0;   break;
      }
   }  if (sb)return;

   sb = 1;
```

```
    for (int i = 2; i < n; i++){ //使前三点不公线
        if (vlen((P[0] - P[1]) * (P[1] - P[i])) > eps){
            swap(P[2], P[i]);
            sb = 0;  break;
        }
    }  if (sb)return;

    sb = 1;
    for (int i = 3; i < n; i++){ //使前四点不共面
        if (fabs((P[0]-P[1]) * (P[1]-P[2]) ^ (P[0]-P[i])) > eps){
            swap(P[3], P[i]);
            sb = 0;   break;
        }
    }  if (sb) return;
    /*********此段是为了保证前四个点不公面********/

    fac add;
    for (int i = 0; i < 4; i++){
        add.a=(i+1)%4, add.b=(i+2)%4, add.c=(i+3)%4, add.ok=1;
        if (ptof(P[i], add) > 0)
            swap(add.b, add.c);
        to[add.a][add.b] = to[add.b][add.c] = to[add.c][add.a] = cnt;
        F[cnt++] = add;
    }
    for (int i = 4; i < n; i++){
        for (int j = 0; j < cnt; j++){
            if (F[j].ok && ptof(P[i], F[j]) > eps){
                dfs(i, j);  break;
            }
        }
    }
    int tmp = cnt;   cnt = 0;
    for (int i = 0; i < tmp; i++)
        if (F[i].ok)
            F[cnt++] = F[i];
}
double area(){ //表面积
    double ret = 0.0;
    for (int i = 0; i < cnt; i++)
        ret += area(P[F[i].a], P[F[i].b], P[F[i].c]);
    return ret / 2.0;
}
double volume(){ //体积
    pt O(0, 0, 0);
    double ret = 0.0;
    for (int i = 0; i < cnt; i++)
        ret += volume(O, P[F[i].a], P[F[i].b], P[F[i].c]);
    return fabs(ret / 6.0);
```

```
    }
    //表面三角形数
    int facetCnt_tri() { return cnt; }

    int facetCnt(){ //表面多边形数
        int ans = 0;
        for (int i = 0; i < cnt; i++){
            bool nb = 1;
            for (int j = 0; j < i; j++) if (same(i, j)){
                nb = 0;  break;
            }  ans += nb;
        }  return ans;
    }
};
_3DCH hull; //内有大数组，不易放在函数内
int main() {
    while (~scanf("%d", &hull.n)){
        for (int i = 0; i < hull.n; i++)
            scanf("%lf%lf%lf", &hull.P[i].x, &hull.P[i].y,
&hull.P[i].z);
        hull.construct();
        printf("%d\n", hull.facetCnt());
    } return 0;
}
/*============================================================================*\
  15)  欧拉四面体公式
\*============================================================================*/
```

已知四面体的六条棱长，求体积：



$$V^2=\frac{1}{36}\begin{vmatrix} a^2 & \frac{a^2+b^2-n^2}{2} & \frac{a^2+c^2-m^2}{2} \\ \frac{a^2+b^2-n^2}{2} & b^2 & \frac{b^2+c^2-l^2}{2} \\ \frac{a^2+c^2-m^2}{2} & \frac{b^2+c^2-l^2}{2} & c^2 \end{vmatrix}$$

```
#define sqr(x) ((x)*(x))
double V(double a,double b,double c,double l,double m,double n) {
    double abl = a*a + b*b - l*l;
    double bcm = b*b + c*c - m*m;
    double can = c*c + a*a - n*n;
    return sqrt(sqr(2*a*b*c) + abl*bcm*can
        - sqr(a*bcm) - sqr(b*can) - sqr(c*abl)) / 12;
}
```

7. 其他

```
/*================================================================================*\
  1)   读入输出优化
\*================================================================================*/
int readint(){  //用于整数
    char c;
    while (c = getchar(), '-' != c && !isdigit(c))
      if(c == EOF)return EOF;
    int f = 1;
    if ('-' == c) {
        f = -1;
        c = getchar();
    }
    int x = c - '0';
    while (isdigit(c = getchar())) {
        x = x * 10 + c - '0';
    }
    return x * f;
}
void write(int a){   //用于正整数
   if(a>9)write(a/10);
   putchar(a%10+'0');
}
double readdouble() {  //用于double型的读入
   char c;
   while (c = getchar(), c != '-' && c != '.' && !isdigit(c));
   int f = 1;
   if (c == '-') {
      f = -1;
      c = getchar();
   }
   double p = 1, res = 0;
   if (c != '.') {
      res = c - '0';
      while (isdigit(c = getchar())) {
         res = res * 10 + c - '0';
      }
   }
   if (c != '.') return res * f;
   while (isdigit(c = getchar())) {
      res = res * 10 + c - '0';
      p *= 10;
   }
   return res * f / p;
}
```