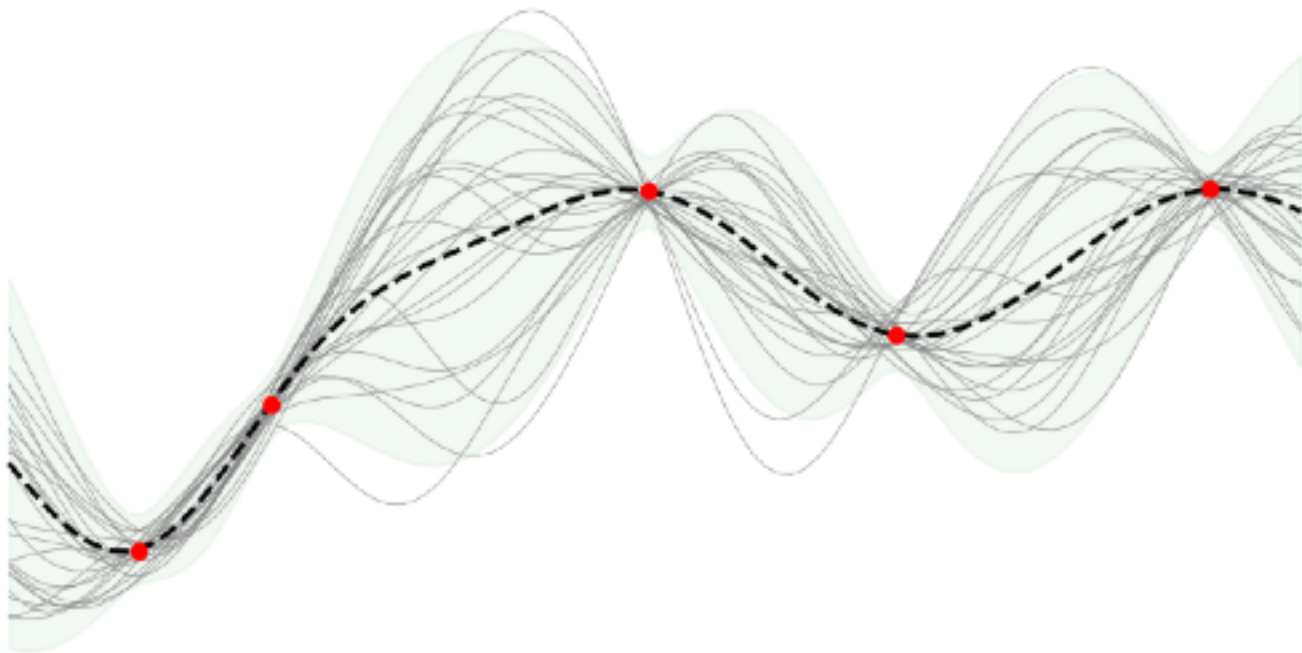




Lancaster
University



Williams, G.K. and Rasmussen, G.E. (2006). *Gaussian Processes for Machine Learning*, MIT press, Cambridge, MA.



f ~ GRW, K)

Weight-Space View

$$f(x) = \phi(x)^T w, \quad w \sim N(0, \Sigma_p)$$

Function-Space View

$$f(x) \sim N(\mu(x), k(x, x))$$

Posterior Predictive

$$y_* | x_*, \mathcal{D}, f \sim N(\mu_{y_*|\mathcal{D}}, K_{y_*|\mathcal{D}})$$

$$\mu_{y_*|\mathcal{D}} = \mu(X_*) + K_*^T (K + \sigma^2 I)^{-1} (y - \mu(X))$$

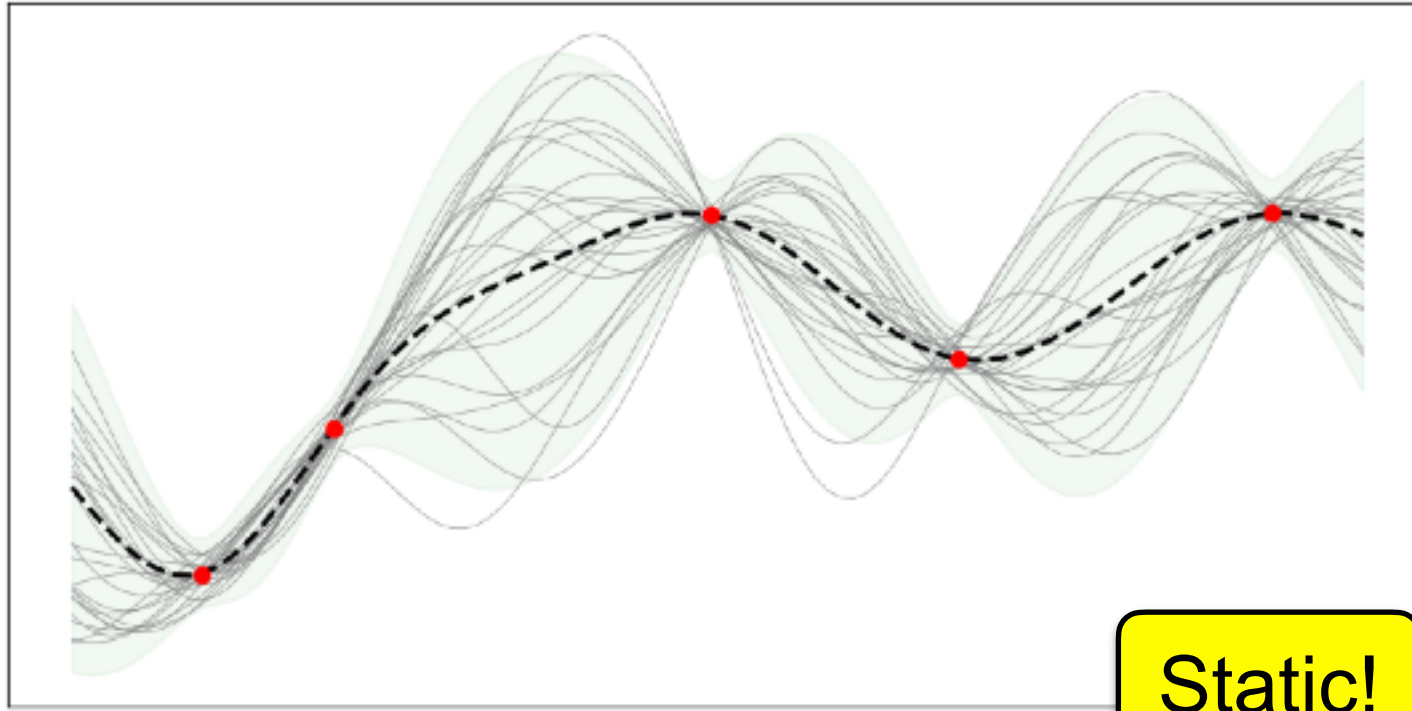
$$K_{y_*|\mathcal{D}} = K_*^T (K + \sigma^2 I)^{-1} K_*$$

Static!

Gaussian Processes [Static]

Gaussian Processes [Static]

$$f \sim GP(\mu, k)$$



Static!

Weight-Space View

$$f(x) = \phi(x)^T w, \quad w \sim N(0, \Sigma_p)$$

Function-Space View

$$f(x) \sim N(\mu(x), k(x, x))$$

Posterior Predictive

$$y_* | x_*, \mathcal{D}, f \sim N(\mu_{y_* | \mathcal{D}}, K_{y_* | \mathcal{D}})$$

$$\mu_{y_* | \mathcal{D}} = \mu(X_*) + K_*^T (K + \sigma^2 I)^{-1} (y - \mu(X))$$

$$K_{y_* | \mathcal{D}} = K_*^T (K + \sigma^2 I)^{-1} K_*$$

Gaussian Processes [Dynamic]

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ON STATIONARY PROCESSES IN THE PLANE

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Biometrika, Volume 41, Issue 3-4, 3 December 1954, Pages 434–449,

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