Modèles Linéaires Appliqués

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Automne 2020

Rappels #5 (optimization)



Calculus

Given a smooth function $f : \mathbb{R}^n \to \mathbb{R}$ Its gradient, $\nabla f : \mathbb{R}^n \to \mathbb{R}^n$ is

$$\nabla f(\mathbf{x}) = \frac{\partial f(\mathbf{x})}{\partial \mathbf{x}} = \left(\frac{\partial f(\mathbf{x})}{\partial x_1}, \frac{\partial f(\mathbf{x})}{\partial x_2}, \cdots, \frac{\partial f(\mathbf{x})}{\partial x_n}\right)$$

Its Hessian matrix is $H = \nabla^2 f : \mathbb{R}^n \to \mathbb{R}^{n \times n}$

$$H(\mathbf{x}) = \frac{\partial^2 f(\mathbf{x})}{\partial \mathbf{x} \mathbf{x}^{\top}} = \begin{pmatrix} \frac{\partial^2 f(\mathbf{x})}{\partial x_1^2} & \frac{\partial^2 f(\mathbf{x})}{\partial x_1 \partial x_2} & \cdots & \frac{\partial^2 f(\mathbf{x})}{\partial x_1 \partial x_n} \\ \frac{\partial^2 f(\mathbf{x})}{\partial x_2 \partial x_1} & \frac{\partial^2 f(\mathbf{x})}{\partial x_2^2} & \cdots & \frac{\partial^2 f(\mathbf{x})}{\partial x_2 \partial x_n} \\ \vdots & \vdots & & \vdots \\ \frac{\partial^2 f(\mathbf{x})}{\partial x_n \partial x_1} & \frac{\partial^2 f(\mathbf{x})}{\partial x_n \partial x_2} & \cdots & \frac{\partial^2 f(\mathbf{x})}{\partial x_n^2} \end{pmatrix}$$

Differential Calculus

Classical rules for differentiable $\mathbb{R} \to \mathbb{R}$ functions

$$h(x) = \alpha f(x) + \beta g(x), \ h'(x) = \alpha f'(x) + \beta g'(x),$$

$$h(x) = f(x)g(x), \ h'(x) = f'(x)g(x) + f(x)g'(x)$$

•
$$h(x) = f(g(x)), h'(x) = f'(g(x))g'(x)$$

$$h = f^{-1}, \ h'(y) = \frac{1}{f'(h^{-1}(y))}$$

$$h(x) = f(x)^n, h'(x) = nf'(x)f(x)^{n-1}$$

$$h(x) = \frac{f(x)}{g(x)}, \ h'(x) = \frac{f'(x)g(x) - f(x)g'(x)}{g(x)}^{2},$$

▶
$$h(x) = \log[f(x)], h'(x) = \frac{f'(x)}{f(x)}$$



Differential Calculus

Let
$$\mathbf{a} \in \mathbb{R}^n$$
, $\mathbf{a}^{\mathsf{T}} \mathbf{x} = \sum_{i=1}^n a_i x_i$, $\frac{\partial \mathbf{a}^{\mathsf{T}} \mathbf{x}}{\partial x_i} = a_i$

$$\frac{\partial \mathbf{a}^{\mathsf{T}} \mathbf{x}}{\partial \mathbf{x}} = \left(\frac{\partial \mathbf{a}^{\mathsf{T}} \mathbf{x}}{\partial x_1}, \frac{\partial \mathbf{a}^{\mathsf{T}} \mathbf{x}}{\partial x_2}, \cdots, \frac{\partial \mathbf{a}^{\mathsf{T}} \mathbf{x}}{\partial x_n}\right) = (a_1, a_2, \cdots, a_n) = \mathbf{a}^{\mathsf{T}}$$

More generally, for multivariate linear or quadratic functions,

$$ightharpoonup \frac{\partial \mathbf{A} \mathbf{x}}{\partial \mathbf{x}} = \mathbf{A}$$
 analogous of: if $f(x) = ax$, $f'(x) = a$

▶
$$\frac{\partial^2 \mathbf{x}^\mathsf{T} \mathbf{A} \mathbf{x}}{\partial \mathbf{x} \partial \mathbf{x}^\mathsf{T}} = \mathbf{A} + \mathbf{A}^\mathsf{T}$$
 analogous of: if $f(x) = ax^2$, $f''(x) = 2a$

$$\frac{\partial \langle \mathbf{x}, \mathbf{x} \rangle}{\partial \mathbf{x}} = \frac{\partial \mathbf{x}^{\mathsf{T}} \mathbf{x}}{\partial \mathbf{x}} = \frac{\partial \|\mathbf{x}\|^2}{\partial \mathbf{x}} = 2\mathbf{x}^{\mathsf{T}}$$

The problem is to solve $\min_{y \in \mathbb{R}} \{f(y)\}\$

Note:
$$\min_{y \in \mathbb{R}} \{f(y)\} = \max_{y \in \mathbb{R}} \{-f(y)\}\$$

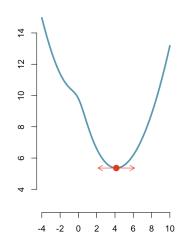
Note:
$$y^* \in \underset{y \in \mathbb{R}}{\operatorname{argmin}} \{f(y)\}\$$

and $\underset{y \in \mathbb{R}}{\min} \{f(y)\} = f(y^*).$

First order condition

$$f'(y^*) = \frac{\partial f(y)}{\partial y}\bigg|_{y=y^*} = 0$$

(necessary condition)



First order condition

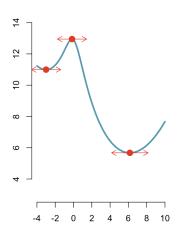
$$f'(y^*) = \frac{\partial f(y)}{\partial y}\bigg|_{y=y^*} = 0$$

might be not sufficient

$$f''(y^*) = \frac{\partial^2 f}{\partial y^2}\Big|_{y=y^*} > 0$$
: minimum

$$f''(y^*) = \frac{\partial^2 f}{\partial y^2}\Big|_{y=y^*} < 0$$
: maximum

can be a local minimum...



Example: $\{y_1, \dots, y_n\}$ in \mathbb{R} , let

$$f(y) = \sum_{i=1}^{n} (y_i - y)^2$$

$$\frac{\partial f(y)}{\partial y} = \frac{\partial}{\partial y} \sum_{i=1}^{n} (y_i - y)^2 = \sum_{i=1}^{n} \frac{\partial (y_i - y)^2}{\partial y} = \sum_{i=1}^{n} -2(y_i - y)$$

SO

$$\frac{\partial f(y)}{\partial y}\Big|_{y=y^*} = 0$$
 if and only if $\sum_{i=1}^n (y_i - y^*) = 0$ or $\sum_{i=1}^n y_i = ny^*$

i.e.
$$y^* = \frac{1}{n} \sum_{i=1}^{n} y_i = \overline{y}$$
.



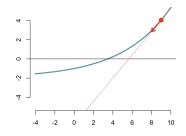
Solving $f'(y^*) = 0$ numerically Newton's method: solve $g(y^*) = 0$

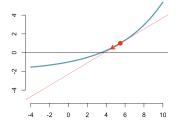
$$g(y) \simeq g(y_0) + g'(y_0)(y - y_0)$$

If
$$g(y) \simeq 0$$
, $g(y_0) + g'(y_0)(y - y_0) \simeq 0$

Start from y_0 , then

$$y_{k+1} = y_k - \frac{g(y_k)}{g'(y_k)}$$



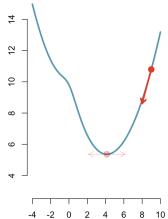




To solve $f'(y^*) = 0$ numerically Start from y_0 , then

$$y_{k+1} = y_k - \frac{f'(y_k)}{f''(y_k)}$$

 $f'(y_k)$ gives the direction $f''(y_k)$ gives the speed of convergence (close to the minimum $f''(y_k) > 0$)



```
v = c(0.89367, -1.04729, 1.97133, -0.38363, 1.65414)
2 > mean(v)
3 [1] 0.617644
4 > f = function(x) sum((v-x)^2)
5 > optim(0, f)
6 $par
7 [1] 0.6175781
8 $value
9 [1] 6.757535
```



The problem is $\min_{\mathbf{y} \in \mathbb{R}^p} \{f(\mathbf{y})\}\$

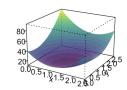
or
$$\min_{(y_1,\dots,y_p)\in\mathbb{R}^p}\{f(y_1,\dots,y_p)\}$$

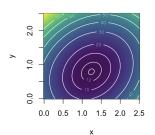
First order conditions: $\nabla f(\mathbf{y}^*) = \mathbf{0}$,

$$\left. \frac{\partial f(y_1, y_2, \cdots, y_p)}{\partial y_1} \right|_{\mathbf{v} = \mathbf{v}^*} = 0$$

$$\left. \frac{\partial f(y_1, y_2, \cdots, y_p)}{\partial y_2} \right|_{\mathbf{y} = \mathbf{y}^*} = 0$$

$$\frac{\partial f(y_1, y_2, \cdots, y_p)}{\partial y_p}\bigg|_{\mathbf{y}=\mathbf{y}^*} = 0$$





Example: $\{(x_1, y_1), \cdots, (x_n, y_n)\}$ in \mathbb{R}^2 , let

$$f(a,b) = \sum_{i=1}^{n} (y_i - [a + bx_i])^2$$

$$\frac{\partial f(a,b)}{\partial a} = -2 \sum_{i=1}^{n} (y_i - [a + bx_i]) = -2(n\overline{y} - [a + bn\overline{y}])$$

$$\frac{\partial f(a,b)}{\partial b} = -2 \sum_{i=1}^{n} (y_i - [a + bx_i])x_i$$

$$\frac{\partial f(a,b)}{\partial a} \Big|_{(a,b)=(a^*,b^*)} = 0 \text{ means that } \overline{y} = a^* + b^*\overline{x},$$

$$\frac{\partial f(a,b)}{\partial b} \Big|_{(a,b)=(a^*,b^*)} = 0 \text{ means that } \widehat{\varepsilon} \perp \mathbf{x}, \ \widehat{\varepsilon}_i = y_i - [a^* + b^*x_i],$$

