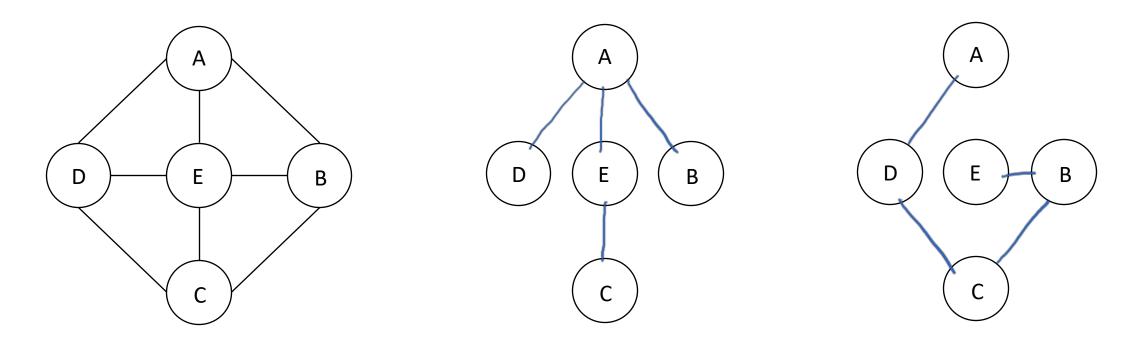
Spanning Trees

Definition

(A Why is it inportant: It since us the nin imm set of edges we need in the graph, so that we could reach all the hales in the graph.)

For an undirected graph G with V nodes: If T is a subgraph of G and T contains all nodes of G, is connected, and has exactly (V-1) edges, then T is a spanning tree of G.



Depth First Spanning Trees

DFT(v):

mark v as visited

for each unvisited successor u of v:

DFT(u)

A Notice that the 2 trivisal aborithms

can also be used for finding the spaning tree.

(Each time befole we visit a node, we add that edge to the spaning tree. Since every node is visited exactly once, there will be V-1 edges created also)

Breadth First Spanning Trees

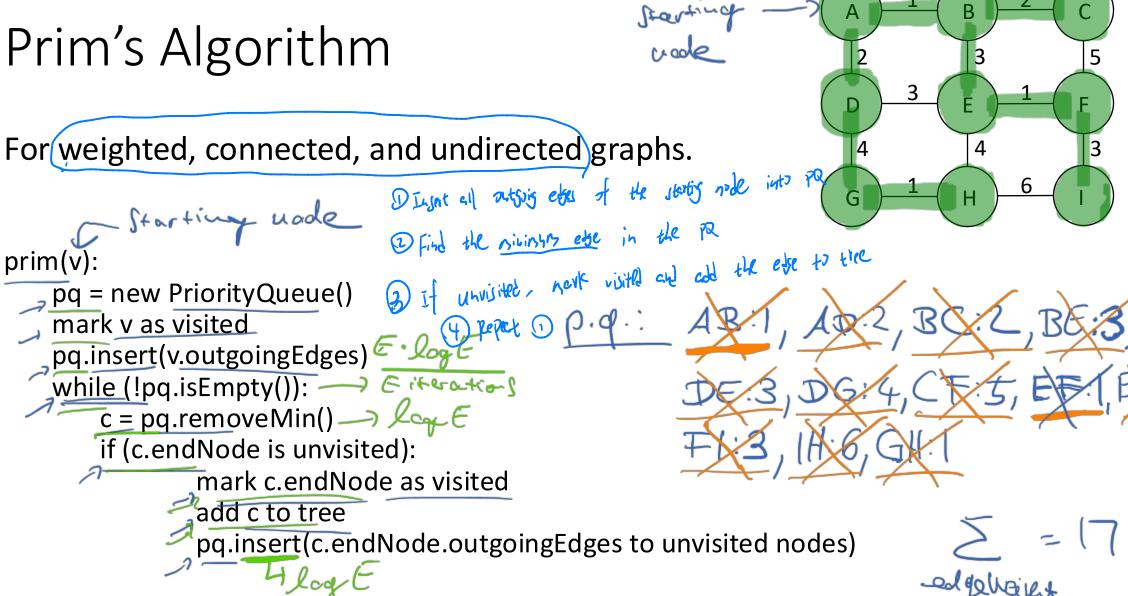
```
BFT(v):
      q = new Queue()
      mark v as visited
      q.enqueue(v)
      while (!q.isEmpty()):
            c = q.dequeue()
             for each unvisited successor u of c:
                   add edge C-u to specuring tree
                   mark u as visited
                   q.enqueue(u)
```

Minimum Spanning Trees

In a weighted graph:

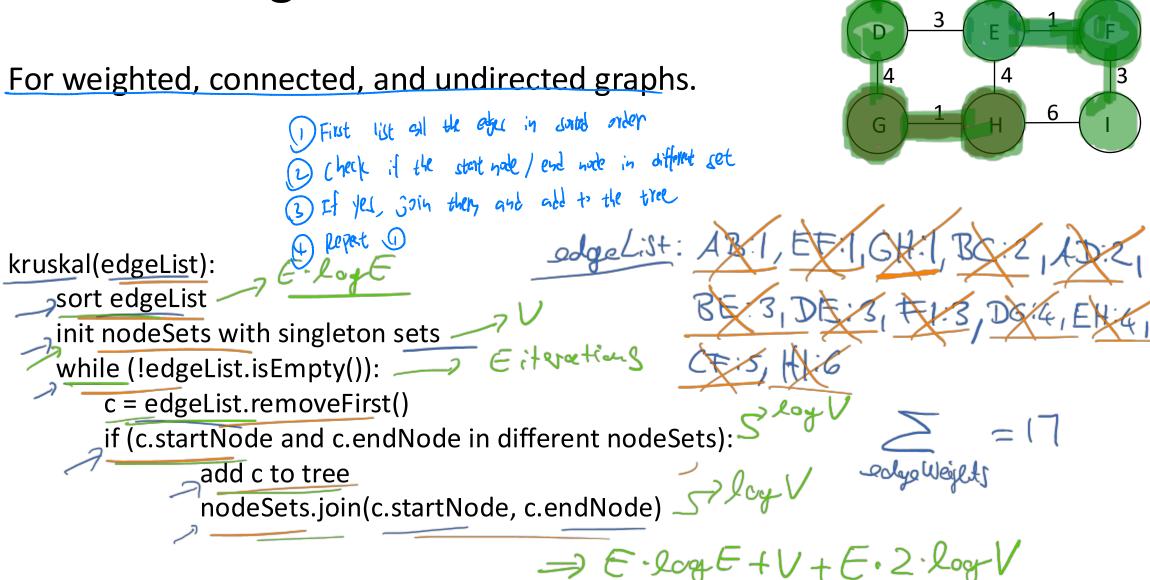
Minimum spanning trees are the spanning trees with the lowest sum of edge weights.

Subset of the spanning tree



=> E.logE+E.2.logE

Kruskal's Algorithm



Complexities

V: # nodes in graph

E: # edges in graph

Prim:
$$O(X-E \cdot log E)$$
 $O(E \cdot log V^2)$
 $O(E \cdot X log V)$

Kruskal:

 $O(E \cdot log E + X + 2 \cdot E \cdot log V)$
 $O(E \cdot log V^X + 2 \cdot E \cdot log V)$
 $O(E \cdot log V^X)$