

Milestone Report – Dartboard Calibration Module

Project: Dart Detection and Classification

Milestone: Prototype for image processor was completed

Date: July 10, 2025

Objective

Develop a calibration system for a steel-tip dartboard using webcam input and **ArUco markers** to geometrically define the dartboard's rings and sectors. The goal is to handle distortion and perspective skew from camera placement and enable precise field classification.

Key Features Achieved

1. ArUco Marker-Based Detection

- **Usage:** Four ArUco markers are placed around the dartboard to define a reference quadrilateral.
- **Purpose:**
 - Provides **accurate spatial reference** for the dartboard.
 - Enables **automatic center estimation** and initial scaling.
 - Compensates for **camera tilt and distortion**.
- **Library:** OpenCV's `cv2.aruco` module used for detection and pose estimation.

2. Concentric Ring Calibration

- **Input:** User manually adjusts outermost ring to match dartboard boundary.
- **Automatic generation:**
 - The five inner rings (Triple, Inner Single, Outer Bull, Bullseye) are created using standardized **dartboard ratios**.

3. Sector (Line) Calibration

- **Sectors:** 20 radial lines divide the board into scoring areas.
- **Adjustable parameters:**
 - `line_rotation`: Aligns sectors correctly (between 20 and 1).
 - `line_scale`: Controls line length based on outer ring.
 - `offset_x`, `offset_y`: Shift center from marker-based estimate if needed.
 - `stretch_x`, `stretch_y`: Handle elliptical distortion (e.g. camera tilt).

4. Data Structure

- All calibration results are stored in structured format:
 - `rings`: List of ellipses.
 - `line_rotation`, `line_scale`: Sector info.
 - `offset_x`, `offset_y`: Center shift.
 - `stretch_x`, `stretch_y`: Aspect ratio correction.
-

Accuracy Notes

- Visual inspection confirms:
 - Radial lines match dartboard sectors.
 - Ring sizes correspond well to true regions even with elliptical distortion.
 - Click-test diagnostics reveal correct (though still being fine-tuned) ring and sector classifications.
-

In Progress / Next Steps

- Refine ring classification logic (currently drifting into adjacent regions slightly).
 - Integrate with dart detection phase.
-

Screenshots

