Data acquisition with the ADS1115 on the raspberry PI

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Chapter 1

rpi_ads1115

Raspberry PI C++ library for the ADS1115

github: https://github.com/berndporr/rpi_ads1115

Chapter 2

Class Index

2.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

Chapter 3

Class Documentation

3.1 ADS1115rpi Class Reference

This class reads data from the ADS1115 in the background (separate thread) and calls a callback function whenever data is available.

`#include <ads1115rpi.h>`

Public Member Functions

- ~ADS1115rpi ()

  Destructor which makes sure the data acquisition has stopped.
- virtual void hasSample (float sample)=0

  Called when a new sample is available.
- void setChannel (ADS1115settings::Input channel)

  Selects a different channel at the multiplexer while running.
- void start (ADS1115settings settings=ADS1115settings())

  Starts the data acquisition in the background and the callback is called with new samples.
- void stop ()

  Stops the data acquistion.

3.1.1 Detailed Description

This class reads data from the ADS1115 in the background (separate thread) and calls a callback function whenever data is available.

3.1.2 Member Function Documentation

3.1.2.1 hasSample()

```
virtual void ADS1115rpi::hasSample (
            float sample )  [pure virtual]
```

Called when a new sample is available.

This needs to be implemented in a derived class by the client. Defined as abstract.

Parameters

sample	Voltage from the selected channel

3.1.2.2 setChannel()

```
void ADS1115rpi::setChannel (
            ADS1115settings::Input channel )
```

Selects a different channel at the multiplexer while running.

Call this in the callback handler hasSample() to cycle through different channels.

Parameters

channel	Sets the channel from A0..A3.

3.1.2.3 start()

```
void ADS1115rpi::start (
            ADS1115settings settings = ADS1115settings() )
```

Starts the data acquisition in the background and the callback is called with new samples.

Parameters

settings	A struct with the settings.

The documentation for this class was generated from the following file:

- ads1115rpi.h

3.2 ADS1115settings Struct Reference

ADS1115 initial settings when starting the device.

```
#include <ads1115rpi.h>
```

Public Types

- enum SamplingRates {
  FS8HZ = 0, **FS16HZ** = 1, **FS32HZ** = 2, **FS64HZ** = 3,
  FS128HZ = 4, **FS250HZ** = 5, **FS475HZ** = 6, **FS860HZ** = 7 }

  Sampling rates.
- enum PGA { **FSR2_048** = 2, **FSR1_024** = 3, **FSR0_512** = 4, **FSR0_256** = 5 }

  Full scale range: 2.048V, 1.024V, 0.512V or 0.256V.
- enum Input { **AIN0** = 0, **AIN1** = 1, **AIN2** = 2, **AIN3** = 3 }

  Channel indices.

Public Attributes

- int i2c_bus = 1

  I2C bus used (99% always set to one)
- uint8_t address = DEFAULT_ADS1115_ADDRESS

  I2C address of the ads1115.
- SamplingRates samplingRate = FS8HZ

  Sampling rate requested.
- PGA pgaGain = FSR2_048

  Requested full scale range.
- Input channel = AIN0

  Requested input channel (AIN0..AIN3)
- bool initPIGPIO = true

  If set to true the pigpio will be initialised.
- int drdy_gpio = DEFAULT_ALERT_RDY_TO_GPIO

  GPIO pin connected to ALERT/RDY.

3.2.1 Detailed Description

ADS1115 initial settings when starting the device.

The documentation for this struct was generated from the following file:

- ads1115rpi.h

Index