

Data acquisition with the ADS1115 on the raspberry PI

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1 rpi_ads1115	1
2 Class Index	3
2.1 Class List	3
3 Class Documentation	5
3.1 ADS1115callback Class Reference	5
3.1.1 Detailed Description	5
3.2 ADS1115rpi Class Reference	5
3.2.1 Detailed Description	6
3.2.2 Constructor & Destructor Documentation	6
3.2.2.1 ADS1115rpi()	6
3.2.3 Member Function Documentation	6
3.2.3.1 setCallback()	6
3.2.3.2 start()	7
3.3 ADS1115settings Struct Reference	7
3.3.1 Detailed Description	8
Index	9

Chapter 1

rpi_ads1115

Raspberry PI C++ library for the ADS1115

Chapter 2

Class Index

2.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

ADS1115callback	Callback for new samples which needs to be implemented by the main program	5
ADS1115rpi	This class reads data from the AD7705 in the background (separate thread) and calls a callback function whenever data is available	5
ADS1115settings	ADS1115 initial settings when starting the device	7

Chapter 3

Class Documentation

3.1 ADS1115callback Class Reference

Callback for new samples which needs to be implemented by the main program.

```
#include <ads1115rpi.h>
```

Public Member Functions

- virtual void [hasSample](#) (float sample)=0
Called after a sample has arrived.

3.1.1 Detailed Description

Callback for new samples which needs to be implemented by the main program.

The function `hasSample` needs to be overloaded in the main program.

The documentation for this class was generated from the following file:

- `ads1115rpi.h`

3.2 ADS1115rpi Class Reference

This class reads data from the AD7705 in the background (separate thread) and calls a callback function whenever data is available.

```
#include <ads1115rpi.h>
```

Public Member Functions

- [ADS1115rpi](#) ()
Constructor with the spiDevice.
- [~ADS1115rpi](#) ()
Destructor which makes sure the data acquisition has stopped.
- void [setCallback](#) ([ADS1115callback](#) *cb)
Sets the callback which is called whenever there is a sample.
- void [start](#) ([ADS1115settings](#) settings=[ADS1115settings](#)())
Starts the data acquisition in the background and the callback is called with new samples.
- void [stop](#) ()
Stops the data acquisition.

3.2.1 Detailed Description

This class reads data from the AD7705 in the background (separate thread) and calls a callback function whenever data is available.

3.2.2 Constructor & Destructor Documentation

3.2.2.1 ADS1115rpi()

```
ADS1115rpi::ADS1115rpi ( )
```

Constructor with the spiDevice.

The default device is /dev/spidev0.0.

Parameters

<i>spiDevice</i>	The raw /dev spi device.
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3.2.3 Member Function Documentation

3.2.3.1 setCallback()

```
void ADS1115rpi::setCallback (
    ADS1115callback * cb )
```

Sets the callback which is called whenever there is a sample.

Parameters

<i>cb</i>	Pointer to the callback interface.
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3.2.3.2 start()

```
void ADS1115rpi::start (
    ADS1115settings settings = ADS1115settings() )
```

Starts the data acquisition in the background and the callback is called with new samples.

Parameters

<i>samplingRate</i>	The sampling rate of the ADC.
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The documentation for this class was generated from the following file:

- ads1115rpi.h

3.3 ADS1115settings Struct Reference

ADS1115 initial settings when starting the device.

```
#include <ads1115rpi.h>
```

Public Types

- enum [SamplingRates](#) {
FS8HZ = 0, **FS16HZ** = 1, **FS32HZ** = 2, **FS64HZ** = 3,
FS128HZ = 4, **FS250HZ** = 5, **FS475HZ** = 6, **FS860HZ** = 7 }
Sampling rates.
- enum [PGA](#) { **FSR2_048** = 2, **FSR1_024** = 3, **FSR0_512** = 4, **FSR0_256** = 5 }
Gains of the PGA.
- enum [Input](#) { **AIN0** = 0, **AIN1** = 1, **AIN2** = 2, **AIN3** = 3 }
Channel indices.

Public Attributes

- int [i2c_bus](#) = 1
I2C bus used (99% always one)
- uint8_t [address](#) = DEFAULT_ADS1115_ADDRESS
I2C address of the ads1115.
- [SamplingRates](#) [samplingRate](#) = FS8HZ
Sampling rate requested.

- `PGA pgaGain = FSR2_048`
Requested gain.
- `Input channel = AIN0`
Requested input channel (0 or 1)
- `bool initPIGPIO = true`
If set to true the pigpio is initialised.
- `int drdy_gpio = DEFAULT_DATA_READY_GPIO`
Default GPIO pin for data ready.

3.3.1 Detailed Description

ADS1115 initial settings when starting the device.

The documentation for this struct was generated from the following file:

- `ads1115rpi.h`

Index

ADS1115callback, [5](#)

ADS1115rpi, [5](#)

 ADS1115rpi, [6](#)

 setCallback, [6](#)

 start, [7](#)

ADS1115settings, [7](#)

setCallback

 ADS1115rpi, [6](#)

start

 ADS1115rpi, [7](#)