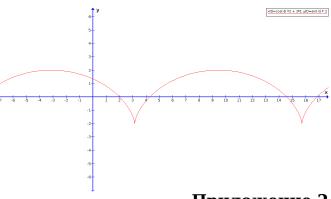
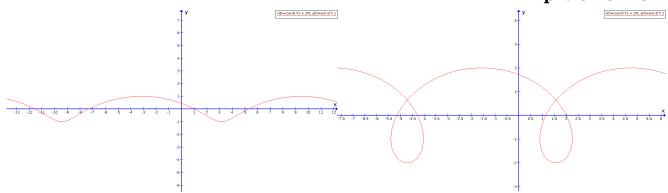
Приложение

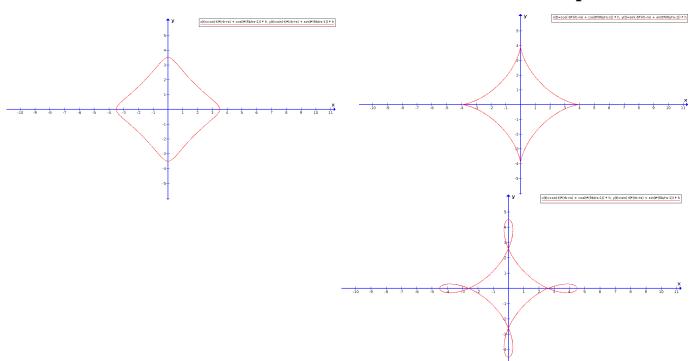
Приложение 1

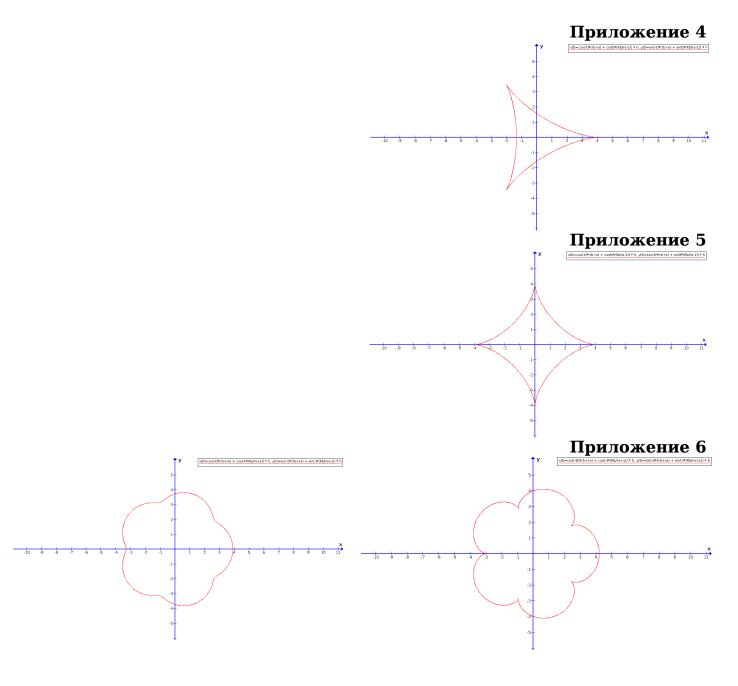


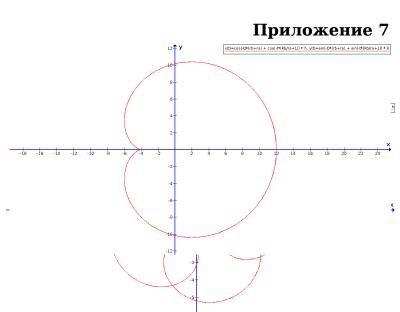
Приложение 2

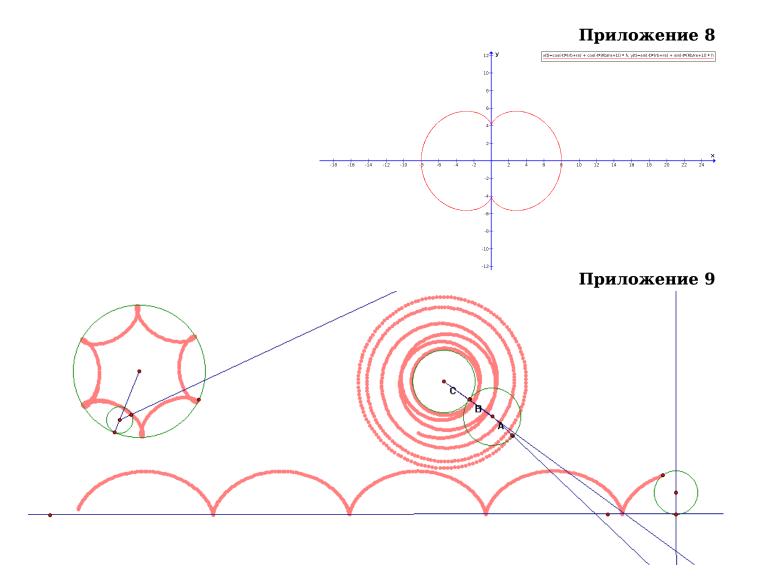


Приложение 3

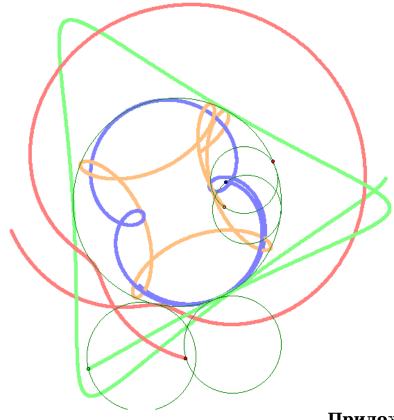




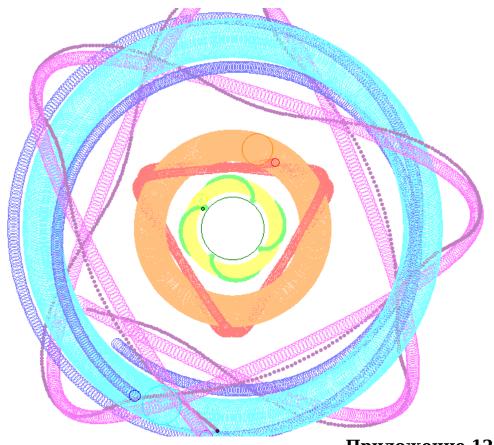




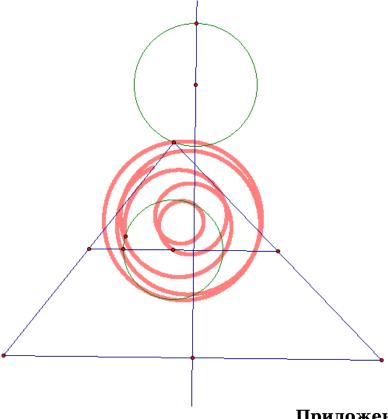
Приложение 10



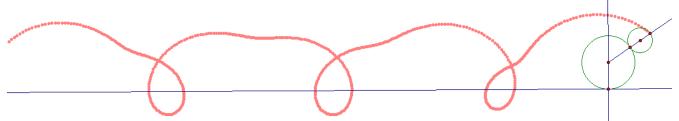
Приложение 11



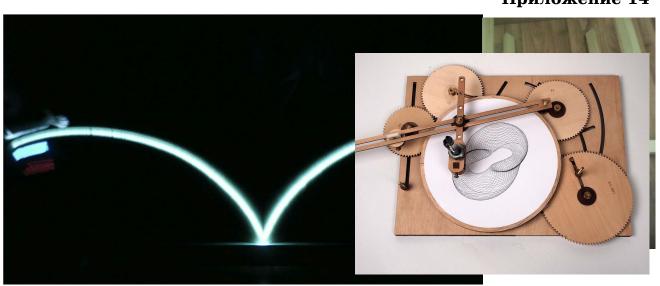
Приложение 12



Приложение 13



Приложение 14



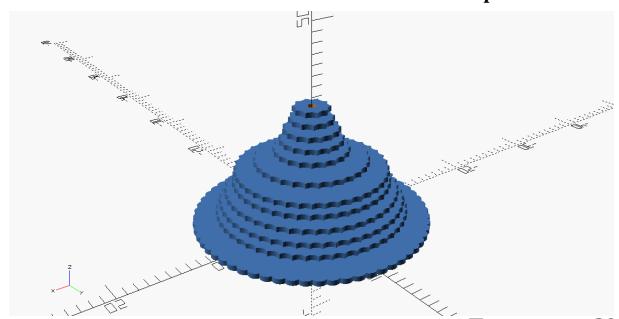
Приложение 15 Приложение 16

```
/*count=100;
             R=100;
             d=R/(1+1/count*0.3);
             r=d/count:
             h=r*0.7;
             m=r/d:
             pol1 = 0.3;
             pol2=20;*/
             //gear(100,true,0.8);
             module gear(count, bul=true,hd=1,dc=1,R=10,pol1=0.09,pol2=4){
             k=0.7;
             r=R/(1+1/60*(1-k))/60;
             d=r*count:
             echo(r);
             h=r*k:
             m=r/d;
             //pol1=0.1;
             //pol2=4;
             difference(){
             linear extrude(height=hd,center=true,slices=1,convexity=10)
             if(bul){
             polygon([
             for(t=[0:360*d/r*pol1])
             [d*(m+1)*cos(t/pol1*m)-h*cos((m+1)*t/pol1),d*(m+1)*sin(t/pol1*m)-h*cos((m+1)*t/pol1),d*(m+1)*sin(t/pol1*m)-h*cos((m+1)*t/pol1),d*(m+1)*sin(t/pol1*m)-h*cos((m+1)*t/pol1),d*(m+1)*sin(t/pol1*m)-h*cos((m+1)*t/pol1),d*(m+1)*sin(t/pol1*m)-h*cos((m+1)*t/pol1),d*(m+1)*sin(t/pol1*m)-h*cos((m+1)*t/pol1),d*(m+1)*sin(t/pol1*m)-h*cos((m+1)*t/pol1),d*(m+1)*sin(t/pol1*m)-h*cos((m+1)*t/pol1),d*(m+1)*sin(t/pol1*m)-h*cos((m+1)*t/pol1),d*(m+1)*sin(t/pol1*m)-h*cos((m+1)*t/pol1),d*(m+1)*sin(t/pol1*m)-h*cos((m+1)*t/pol1),d*(m+1)*sin(t/pol1*m)-h*cos((m+1)*t/pol1),d*(m+1)*sin(t/pol1*m)-h*cos((m+1)*t/pol1),d*(m+1)*sin(t/pol1*m)-h*cos((m+1)*t/pol1),d*(m+1)*sin(t/pol1*m)-h*cos((m+1)*t/pol1),d*(m+1)*sin(t/pol1*m)-h*cos((m+1)*t/pol1),d*(m+1)*sin(t/pol1*m)-h*cos((m+1)*t/pol1),d*(m+1)*sin(t/pol1*m)-h*cos((m+1)*t/pol1),d*(m+1)*sin(t/pol1*m)-h*cos((m+1)*t/pol1),d*(m+1)*sin(t/pol1*m)-h*cos((m+1)*t/pol1),d*(m+1)*sin(t/pol1*m)-h*cos((m+1)*t/pol1),d*(m+1)*sin(t/pol1*m)-h*cos((m+1)*t/pol1),d*(m+1)*sin(t/pol1*m)-h*cos((m+1)*t/pol1),d*(m+1)*sin(t/pol1*m)-h*cos((m+1)*t/pol1*m)-h*cos((m+1)*t/pol1*m)-h*cos((m+1)*t/pol1*m)-h*cos((m+1)*t/pol1*m)-h*cos((m+1)*t/pol1*m)-h*cos((m+1)*t/pol1*m)-h*cos((m+1)*t/pol1*m)-h*cos((m+1)*t/pol1*m)-h*cos((m+1)*t/pol1*m)-h*cos((m+1)*t/pol1*m)-h*cos((m+1)*t/pol1*m)-h*cos((m+1)*t/pol1*m)-h*cos((m+1)*t/pol1*m)-h*cos((m+1)*t/pol1*m)-h*cos((m+1)*t/pol1*m)-h*cos((m+1)*t/pol1*m)-h*cos((m+1)*t/pol1*m)-h*cos((m+1)*t/pol1*m)-h*cos((m+1)*t/pol1*m)-h*cos((m+1)*t/pol1*m)-h*cos((m+1)*t/pol1*m)-h*cos((m+1)*t/pol1*m)-h*cos((m+1)*t/pol1*m)-h*cos((m+1)*t/pol1*m)-h*cos((m+1)*t/pol1*m)-h*cos((m+1)*t/pol1*m)-h*cos((m+1)*t/pol1*m)-h*cos((m+1)*t/pol1*m)-h*cos((m+1)*t/pol1*m)-h*cos((m+1)*t/pol1*m)-h*cos((m+1)*t/pol1*m)-h*cos((m+1)*t/pol1*m)-h*cos((m+1)*t/pol1*m)-h*cos((m+1)*t/pol1*m)-h*cos((m+1)*t/pol1*m)-h*cos((m+1)*t/pol1*m)-h*cos((m+1)*t/pol1*m)-h*cos((m+1)*t/pol1*m)-h*cos((m+1)*t/pol1*m)-h*cos((m+1)*t/pol1*m)-h*cos((m+1)*t/pol1*m)-h*cos((m+1)*t/pol1*m)-h*cos((m+1)*t/pol1*m)-h*cos((m+1)*t/pol1*m)-h*cos((m+1)*t/pol1*m)-h*cos((m+1)*t/pol1*m)-h
h*sin((m+1)*t/pol1)
              1):
              }else{
             polygon([
             for(t=[0:1:360*pol2])
             [(d-r)*\cos(t/pol2)+h*\cos((d-r)/r*t/pol2),(d-r)*\sin(t/pol2)-h*\sin((d-r)/r*t/pol2)]
             1);}
             cylinder(h=hd+2,d1=dc,d2=dc,$fn=100,center=true);}}
                                                                                                                                                                                          Приложение 17
include < cicloid test gear.scad >
             //gear(count, bul=true,hd=1,dc=1,R=15,pol1=0.1,pol2=4)
             Rbgear=22;
             sizes=22:
             r bolt=sizes*0.8/Rbgear;
             gears=[10,12,15,17,20,30,40,41,45,48,50,60];
             pols = [0.09, 0.09, 0.09, 0.09, 0.09, 0.09, 0.09]:
             luchs=[6,7,10,17,13,12,13,13,7];
             //projection(){
             gears();
             board():
              *gears for board();
              translate([0,-50,0])planka(50);
```

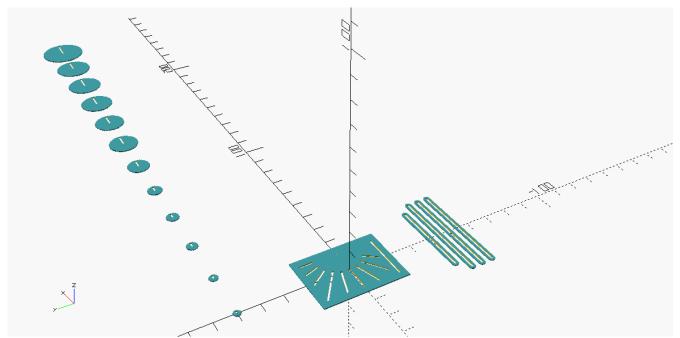
```
translate([0,-45,0])planka(50);
                      translate([0,-55,0])planka(50);
                      translate([0,-40,0])planka(40);
                      //}
                      module gears(){
                      for(a=[0:11]){
                     translate([a*23,50,0])
                      difference(){
                      gear(gears[a],(a==11))? true:false,sizes/22/2,r bolt,sizes/2,0.19,a*10/11+2);
                      translate([(22*gears[a]/60/2-0.8)/2,0,0])cube([\overline{2}2*gears[a]/60/2-0.8)/2,0,0])cube([\overline{2}2*gears[a]/60/2-0.8)/2,0,0])cube([\overline{2}2*gears[a]/60/2-0.8)/2,0,0])cube([\overline{2}2*gears[a]/60/2-0.8)/2,0,0])cube([\overline{2}2*gears[a]/60/2-0.8)/2,0,0])cube([\overline{2}2*gears[a]/60/2-0.8)/2,0,0])cube([\overline{2}2*gears[a]/60/2-0.8)/2,0,0])cube([\overline{2}2*gears[a]/60/2-0.8)/2,0,0])cube([\overline{2}2*gears[a]/60/2-0.8)/2,0,0])cube([\overline{2}2*gears[a]/60/2-0.8)/2,0,0])cube([\overline{2}2*gears[a]/60/2-0.8)/2,0,0])cube([\overline{2}2*gears[a]/60/2-0.8)/2,0,0])cube([\overline{2}2*gears[a]/60/2-0.8)/2,0,0])cube([\overline{2}2*gears[a]/60/2-0.8)/2,0,0])cube([\overline{2}2*gears[a]/60/2-0.8)/2,0))cube([\overline{2}2*gears[a]/60/2-0.8)/2,0))cube([\overline{2}2*gears[a]/60/2-0.8)/2,0))cube([\overline{2}2*gears[a]/60/2-0.8)/2,0))cube([\overline{2}2*gears[a]/60/2-0.8)/2,0))cube([\overline{2}2*gears[a]/60/2-0.8)/2,0))cube([\overline{2}2*gears[a]/60/2-0.8)/2,0))cube([\overline{2}2*gears[a]/60/2-0.8)/2,0))cube([\overline{2}2*gears[a]/60/2-0.8)/2,0))cube([\overline{2}2*gears[a]/60/2-0.8)/2,0))cube([\overline{2}2*gears[a]/60/2-0.8)/2,0))cube([\overline{2}2*gears[a]/60/2-0.8)/2,0))cube([\overline{2}2*gears[a]/60/2-0.8)/2,0))cube([\overline{2}2*gears[a]/60/2-0.8)/2,0))cube([\overline{2}2*gears[a]/60/2-0.8)/2,0))cube([\overline{2}2*gears[a]/60/2-0.8)/2,0))cube([\overline{2}2*gears[a]/60/2-0.8)/2,0))cube([\overline{2}2*gears[a]/60/2-0.8)/2,0))cube([\overline{2}2*gears[a]/60/2-0.8)/2,0))cube([\overline{2}2*gears[a]/60/2-0.8)/2,0))cube([\overline{2}2*gears[a]/60/2-0.8)/2,0))cube([\overline{2}2*gears[a]/60/2-0.8)/2,0))cube([\overline{2}2*gears[a]/60/2-0.8)/2,0))cube([\overline{2}2*gears[a]/60/2-0.8)/2,0))cube([\overline{2}2*gears[a]/60/2-0.8)/2,0))cube([\overline{2}2*gears[a]/60/2-0.8)/2,0))cube([\overline{2}2*gears[a]/60/2-0.8)/2,0))cube([\overline{2}2*gears[a]/60/2-0.8)/2,0))cube([\overline{2}2*gears[a]/60/2-0.8)/2,0))cube([\overline{2}2*gears[a]/60/2-0.8)/2,0))cube([\overline{2}2*gears[a]/60/2-0.8)/2,0))cube([\overline{2}2*gears[a]/60/2-0.8)/2,0))cube([\overline{2}2*gears[a]/60/2-0.8)/2,0))cube([\overline{2}2*gears[a]/60/2-0.8)/2))cube([\overline{2}2*gears[a]/60/2-0.8)/2))cube([\overline{2}2*gears[a]/60/2-0.8)/2))cube([\overline{2}2*gears[a]/60/2-0.8)/2))cube([\overline{2}2*gears[a]/60/2-0.8)/2)
0.8,r bolt, 0.6], true); } } }
                      module board(){
                      difference(){
                      cube([sizes*30/Rbgear,sizes*40/Rbgear,sizes*0.5/Rbgear],true);
                      translate([sizes*(30/2-4)/Rbgear,sizes*(40/2-Rbgear/2-Rbgear/2/2-4)/
Rbgear,0])cylinder(sizes/22,r bolt/2,r bolt/2,true,$fn=100);
                                   translate([sizes*(30/2-4)/Rbgear,sizes*(40/2-4)/Rbgear,0])cylinder(sizes/
22,r bolt/2,r bolt/2,true,fn=100);
                      translate([sizes*(-0.5)/Rbgear,-sizes*(40/2-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([sizes*(30-4-3)/Rbgear,0])cube([size*(30-4-3)/Rbgear,0])cube([size*(30-4-3)/Rbgear,0])cube([size*(30-4-3)/Rbgear,0])cube([size*(30-4-3)/Rbgear,0])cube([size*(30-4-3)/Rbgear,0])cube([si
Rbgear,r bolt, sizes/Rbgear], true);
                      for(i=[-5:3])
translate([sizes*(30/2-4)/Rbgear,0,0])rotate([0,0,360/20*i+180])translate([sizes*(30/2-4)/Rbgear,0,0])rotate([0,0,360/20*i+180])translate([sizes*(30/2-4)/Rbgear,0,0])rotate([0,0,360/20*i+180])translate([sizes*(30/2-4)/Rbgear,0,0])rotate([0,0,360/20*i+180])translate([sizes*(30/2-4)/Rbgear,0,0])rotate([0,0,360/20*i+180])translate([sizes*(30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0,0])rotate([30/2-4)/Rbgear,0)rotate([30/2-4)/Rbgear,0)rotate([30/2-4)/Rbgear,0)rotate([30/2-4)/Rbgear,0)rotate([30/2-4)/Rb
Rbgear/2+(luchs[i+5])/2)/Rbgear,0,0])cube([sizes*(luchs[i+5])/2)/Rbgear,0,0])cube([sizes*(luchs[i+5])/2)/Rbgear,0,0])cube([sizes*(luchs[i+5])/2)/Rbgear,0,0])cube([sizes*(luchs[i+5])/2)/Rbgear,0,0])cube([sizes*(luchs[i+5])/2)/Rbgear,0,0])cube([sizes*(luchs[i+5])/2)/Rbgear,0,0])cube([sizes*(luchs[i+5])/2)/Rbgear,0,0])cube([sizes*(luchs[i+5])/2)/Rbgear,0,0])cube([sizes*(luchs[i+5])/2)/Rbgear,0,0])cube([sizes*(luchs[i+5])/2)/Rbgear,0,0])cube([sizes*(luchs[i+5])/2)/Rbgear,0,0])cube([sizes*(luchs[i+5])/2)/Rbgear,0,0])cube([sizes*(luchs[i+5])/2)/Rbgear,0,0])cube([sizes*(luchs[i+5])/2)/Rbgear,0,0])cube([sizes*(luchs[i+5])/2)/Rbgear,0,0])cube([sizes*(luchs[i+5])/2)/Rbgear,0,0])cube([sizes*(luchs[i+5])/2)/Rbgear,0,0])cube([sizes*(luchs[i+5])/2)/Rbgear,0,0])cube([sizes*(luchs[i+5])/2)/Rbgear,0,0])cube([sizes*(luchs[i+5])/2)/Rbgear,0,0])cube([sizes*(luchs[i+5])/2)/Rbgear,0,0])cube([sizes*(luchs[i+5])/2)/Rbgear,0,0])cube([sizes*(luchs[i+5])/2)/Rbgear,0,0)/Rbgear,0,0)
Rbgear,r bolt,sizes/Rbgear],true);}}}
                      modulegears for board(){
                      translate([sizes*(30/2-4)/Rbgear,sizes*(40/2-Rbgear/2-Rbgear/2/2-4)/
Rbgear, sizes*0.5/Rbgear])gear(60,true, sizes*0.5/Rbgear,rbolt, sizes/2,0.09);
translate([sizes*(30/2-4)/Rbgear,sizes*(40/2-4)/Rbgear,sizes*0.5/
Rbgear])rotate(360/60)gear(30,false,sizes*0.5/Rbgear,r bolt,sizes/2,0.09,4);
translate([-sizes*(Rbgear/2/60*54)/Rbgear,0,sizes*0.5/
Rbgear])rotate([0,0,360/56/2])gear(54,false,sizes*0.5/Rbgear,r bolt,sizes/
2,0.09,4);
                      moduleplanka(leny){
                      difference(){
                      union(){
                      cube([leny-3,3,0.5], true);
                                  translate([(leny-3)/2,0,0])cylinder(d1=3,d2=3,h=0.5,center=true,
fn=100;
                                   translate([(leny-3)/-2,0,0])cylinder(d1=3,d2=3,h=0.5,center=true,
fn=100;
                      cube([leny-3,1,0.6],true);
                                   translate([(leny-3)/-2,0,0])cylinder(d1=1,d2=1,h=1,center=true,
fn=100:
                                   translate([(leny-3)/2,0,0])cylinder(d1=1,d2=1,h=1,center=true,
fn=100;}
```

Приложение 18

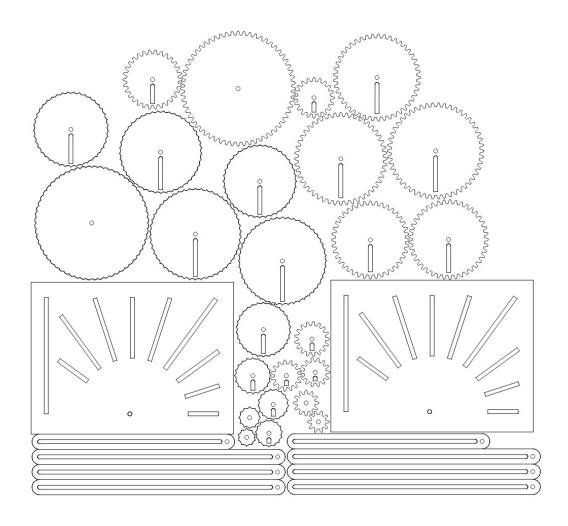
Приложение 19



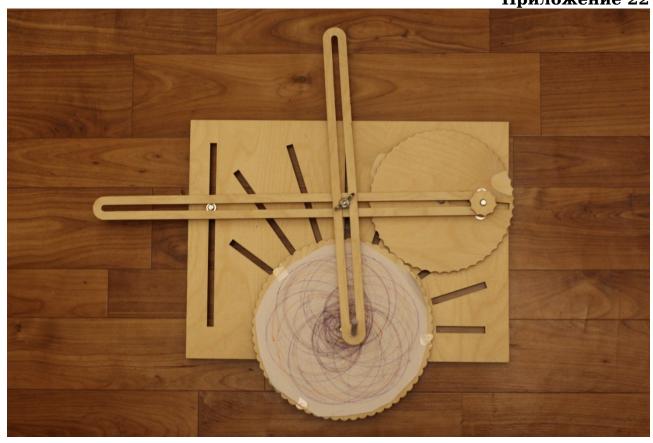
Приложение 20



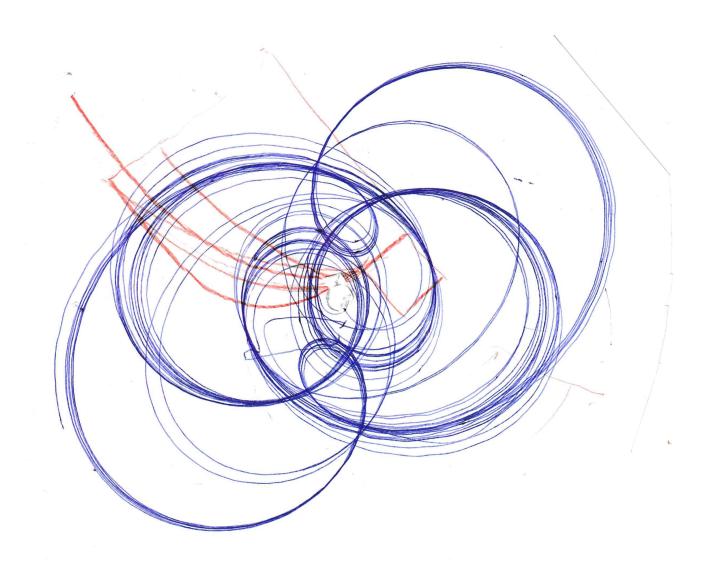
Приложение 21

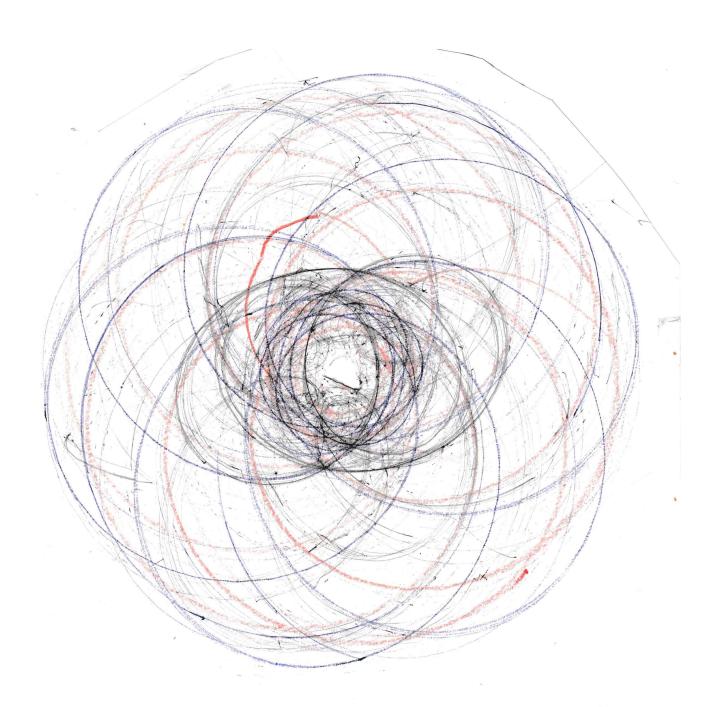


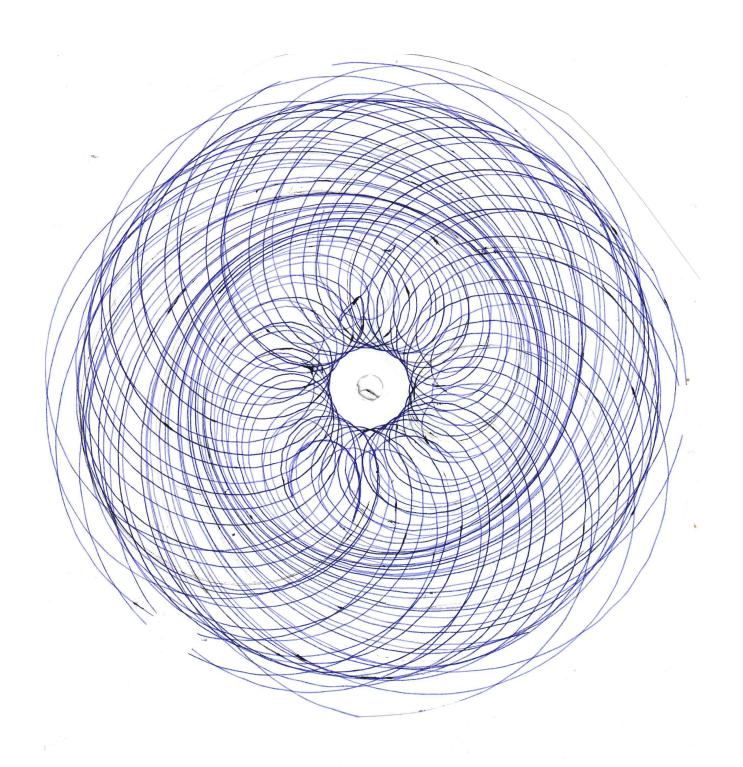
Приложение 22





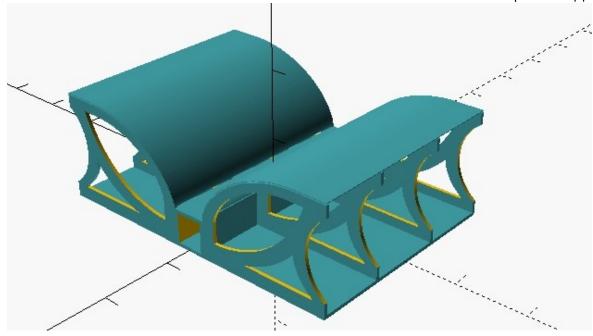






Приложение 23 Сдесь заметки...

Я одновременно работал ещё над одним проектом, и внём требовалось создания макета парковки для умного города. Привожу не законченную модель в которой форма навеса выполнена по Циклоиде.



Появилась идея изучения аэродинамических свойств кривых. И рассмотрения геометрии на искривлённой плоскости, порождаемой вращением кривой(Циклоиды, Гипотрохоиды...) пример — гиперболоид Приложение 24

