

$$\mathbb{A}^3, \quad TA^3 = \mathbb{R}^3 \quad (\mathbb{R}^3, \langle \cdot, \cdot \rangle_{st})$$

- rette affini : sottospazi affini di dim 1
- piani affini : sottospazi affini di dim 2

Fissiamo un sistema di riferimento affine ortogonale $(O; \{\underline{e}_1, \underline{e}_2, \underline{e}_3\})$

- **rette affini**: r retta, $P_0 \in r$

$$\underline{v} \in \mathbb{R}^3 \quad \text{span}\{\underline{v}\} = T_r$$

eq. parametrica $P \in r \Leftrightarrow P - P_0 = \lambda \underline{v}$
 $\lambda \in \mathbb{R}$

$$\text{se } P = \begin{pmatrix} x \\ y \\ z \end{pmatrix} \quad P_0 = \begin{pmatrix} a_0 \\ b_0 \\ c_0 \end{pmatrix}$$

$$\underline{v} = \begin{pmatrix} \alpha \\ \beta \\ \gamma \end{pmatrix}$$

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} \in r \Leftrightarrow \begin{pmatrix} x \\ y \\ z \end{pmatrix} - \begin{pmatrix} a_0 \\ b_0 \\ c_0 \end{pmatrix} = \lambda \begin{pmatrix} \alpha \\ \beta \\ \gamma \end{pmatrix} \quad \lambda \in \mathbb{R}$$

$$r: \begin{cases} x = a_0 + \lambda \alpha \\ y = b_0 + \lambda \beta \\ z = c_0 + \lambda \gamma \end{cases} \quad \lambda \in \mathbb{R}$$

eq. cartesiana: $P \in r \Leftrightarrow \langle P - P_0, \underline{u} \rangle = 0$
per ogni $\underline{u} \in (Tr)^\perp$

Oss: $\dim Tr = 1 \Rightarrow \dim (Tr)^\perp = 2$

perché $\mathbb{R}^3 = Tr \oplus (Tr)^\perp$

de Grassmann $3 = 1 + 2$

se $(Tr)^\perp = \text{span}\{\underline{u}_1, \underline{u}_2\}$ allora

$P \in r \Leftrightarrow \langle P - P_0, \underline{u}_1 \rangle = \langle P - P_0, \underline{u}_2 \rangle = 0$

se $\underline{u}_1 = \begin{pmatrix} l \\ m \\ n \end{pmatrix}$ $\underline{u}_2 = \begin{pmatrix} p \\ q \\ r \end{pmatrix}$ allora

$$P \in r \Leftrightarrow \begin{cases} \langle \begin{pmatrix} x \\ y \\ z \end{pmatrix} - \begin{pmatrix} a_0 \\ b_0 \\ c_0 \end{pmatrix}, \begin{pmatrix} l \\ m \\ n \end{pmatrix} \rangle = 0 \\ \langle \begin{pmatrix} x \\ y \\ z \end{pmatrix} - \begin{pmatrix} a_0 \\ b_0 \\ c_0 \end{pmatrix}, \begin{pmatrix} p \\ q \\ r \end{pmatrix} \rangle = 0 \end{cases}$$

$$r: \begin{cases} (x-a_0)l + (y-b_0)m + (z-c_0)n = 0 \\ (x-a_0)p + (y-b_0)q + (z-c_0)r = 0 \end{cases}$$

\Leftrightarrow

$$\begin{cases} lx + my + nz + d = 0 \\ px + qy + rz + k = 0 \end{cases}$$

piani affini

π

$$\dim T\pi = 2$$

$$P_0 = \begin{pmatrix} a_0 \\ b_0 \\ c_0 \end{pmatrix} \in \pi$$

$$\underline{v}_1, \underline{v}_2 \in \mathbb{R}^3$$

$$T\pi = \text{span} \{ \underline{v}_1, \underline{v}_2 \}$$

$$\underline{v}_1 = \begin{pmatrix} \alpha \\ \beta \\ \gamma \end{pmatrix}$$

$$\underline{v}_2 = \begin{pmatrix} \tilde{\alpha} \\ \tilde{\beta} \\ \tilde{\gamma} \end{pmatrix}$$

equazione parametrica:

$$P \in \pi \Leftrightarrow P - P_0 \in T\pi$$

$$\Leftrightarrow P - P_0 = \lambda \underline{v}_1 + \mu \underline{v}_2 \quad \lambda, \mu \in \mathbb{R}$$

in coordinate

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} - \begin{pmatrix} a_0 \\ b_0 \\ c_0 \end{pmatrix} = \lambda \begin{pmatrix} \alpha \\ \beta \\ \gamma \end{pmatrix} + \mu \begin{pmatrix} \tilde{\alpha} \\ \tilde{\beta} \\ \tilde{\gamma} \end{pmatrix} \quad \lambda, \mu \in \mathbb{R}$$

$$\pi : \begin{cases} x = a_0 + \lambda \alpha + \mu \tilde{\alpha} \\ y = b_0 + \lambda \beta + \mu \tilde{\beta} \\ z = c_0 + \lambda \gamma + \mu \tilde{\gamma} \end{cases} \quad \lambda, \mu \in \mathbb{R}$$

$\begin{matrix} \parallel \\ \rho_0 \\ \cap \\ \pi \end{matrix}$
 $\begin{matrix} \underline{v_1} & \underline{v_2} \end{matrix}$

eq. conteniente:

$$\underline{OSS} : \dim (T\pi)^\perp = 1$$

$$\mathbb{R}^3 = T\pi \oplus (T\pi)^\perp$$

$\begin{matrix} 3 & 2 & 1 \end{matrix}$

$$P \in \pi \Leftrightarrow \langle P - P_0, \underline{u} \rangle = 0 \quad \text{per ogni} \\ \underline{u} \in (T\pi)^\perp$$

$$\text{se } \underline{u}_1 = \begin{pmatrix} m \\ n \\ \ell \end{pmatrix} \quad \text{span}\{\underline{u}_1\} = (\overrightarrow{T\pi})^\perp$$

allow

$$P \in \pi \Leftrightarrow \langle P - P_0, \underline{u}_1 \rangle = 0$$

in coordinate

$$\left\langle \begin{pmatrix} x \\ y \\ z \end{pmatrix} - \begin{pmatrix} a_0 \\ b_0 \\ c_0 \end{pmatrix}, \begin{pmatrix} m \\ n \\ \ell \end{pmatrix} \right\rangle = 0$$

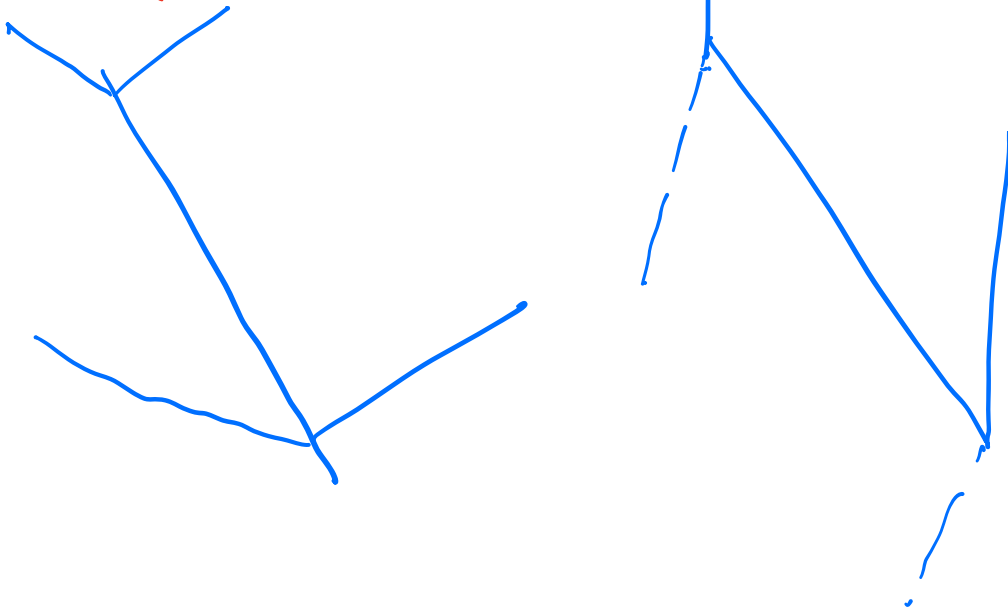
$$\pi: (x - a_0) \cdot m + (y - b_0) \cdot n + (z - c_0) \cdot \ell = 0$$

\downarrow

$$\pi: \boxed{m}x + \boxed{n}y + \boxed{\ell}z + \delta = 0$$

$$\downarrow \begin{pmatrix} m \\ n \\ \ell \end{pmatrix} = \underline{u}_1$$

oss: comparando le eq. cartesiane di rette piane si vede che ogni retta affine è l'intersezione di due piani affini (ma non in modo unico)



PRODOTTO VETTORIALE IN \mathbb{R}^3

Fissiamo la base canonica $\{\underline{e}_1, \underline{e}_2, \underline{e}_3\}$

siano $\underline{v}, \underline{w} \in \mathbb{R}^3$

$$\underline{v} = \begin{pmatrix} a \\ b \\ c \end{pmatrix} \quad \underline{w} = \begin{pmatrix} \alpha \\ \beta \\ \gamma \end{pmatrix}$$

$$\underline{v} \wedge \underline{w} := \det \begin{pmatrix} \underline{e}_1 & \underline{e}_2 & \underline{e}_3 \\ a & b & c \\ \alpha & \beta & \gamma \end{pmatrix} :=$$

\uparrow
 wedge
 prodotto esterno
 prodotto vettoriale

$$= b\gamma \underline{e}_1 + \alpha c \underline{e}_2 + a\beta \underline{e}_3 - \alpha b \underline{e}_3 - \beta c \underline{e}_1 - a\gamma \underline{e}_2 =$$

$$(b\gamma - \beta c) \underline{e}_1 + (\alpha c - a\gamma) \underline{e}_2 + (a\beta - \alpha b) \underline{e}_3$$

$$\underline{v} \wedge \underline{w} = \begin{pmatrix} b\gamma - \beta c \\ \alpha c - a\gamma \\ a\beta - \alpha b \end{pmatrix}$$

OSS: $\underline{u} = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$

$$\langle \underline{v} \wedge \underline{w}, \underline{u} \rangle =$$

$$= \left\langle \begin{pmatrix} by - \beta c \\ \alpha c - ay \\ a\beta - \alpha b \end{pmatrix}, \begin{pmatrix} x \\ y \\ z \end{pmatrix} \right\rangle =$$

$$= \underbrace{byx}_{\text{red}} - \underbrace{\beta cx}_{\text{red}} + \underbrace{\alpha cy}_{\text{red}} - \underbrace{ayy}_{\text{red}} + \underbrace{a\beta z}_{\text{red}} - \underbrace{\alpha bz}_{\text{red}}$$

$$\det \begin{pmatrix} x & y & z \\ a & b & c \\ \alpha & \beta & \gamma \end{pmatrix} = \underbrace{xb}_{\text{red}}\gamma + \underbrace{yc}_{\text{red}}\alpha + \underbrace{z\beta}_{\text{red}}a - \underbrace{\alpha bz}_{\text{red}} - \underbrace{\beta cx}_{\text{red}} - \underbrace{\gamma ya}_{\text{red}}$$

$$\langle \underline{v} \wedge \underline{w}, \underline{u} \rangle = \det \begin{pmatrix} x & y & z \\ a & b & c \\ \alpha & \beta & \gamma \end{pmatrix} \begin{matrix} \rightarrow \underline{u} \\ \rightarrow \underline{v} \\ \rightarrow \underline{w} \end{matrix}$$

da questa formula segue immediatamente:

Corollario:

$$\langle \underline{v} \wedge \underline{w}, \underline{v} \rangle = 0$$

$$\langle \underline{v} \wedge \underline{w}, \underline{w} \rangle = 0$$

quindi

$\underline{v} \wedge \underline{w}$ è ortogonale a $\text{span}\{\underline{v}, \underline{w}\}$

OSS:

- $\underline{v} \wedge \underline{w} = - \underline{w} \wedge \underline{v}$

- se $\{\underline{v}, \underline{w}\}$ sono lin. dip.

$$\underline{v} \wedge \underline{w} = 0$$

- $\underline{\tilde{v}} \in \mathbb{R}^3$

$$(\underline{v} + \underline{\tilde{v}}) \wedge \underline{w} = \underline{v} \wedge \underline{w} + \underline{\tilde{v}} \wedge \underline{w}$$

- $\lambda \in \mathbb{R}$

$$(\lambda \underline{v}) \wedge \underline{w} = \lambda (\underline{v} \wedge \underline{w}) = \underline{v} \wedge (\lambda \underline{w})$$

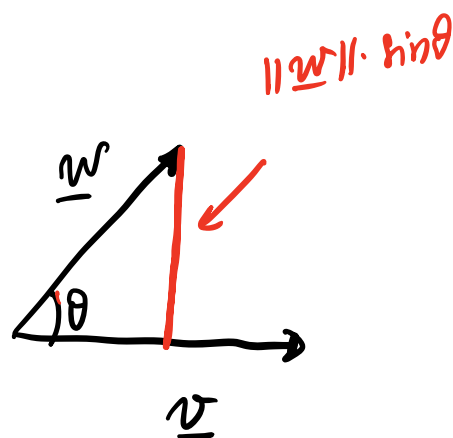
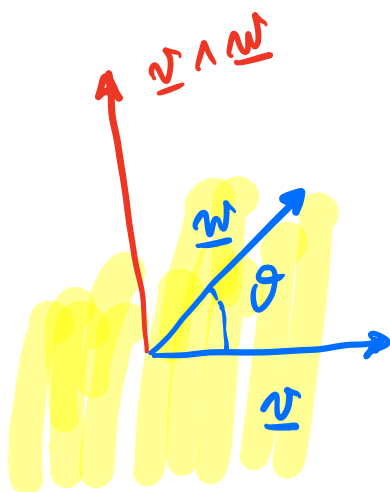
- $\underline{v} \wedge (\underline{w} + \underline{\tilde{w}}) = \underline{v} \wedge \underline{w} + \underline{v} \wedge \underline{\tilde{w}}$

FATTO: $\underline{v}, \underline{w} \neq 0$

$$\|\underline{v} \wedge \underline{w}\| = \|\underline{v}\| \cdot \|\underline{w}\| \sin \theta$$

θ è l'angolo tra \underline{v} e \underline{w}

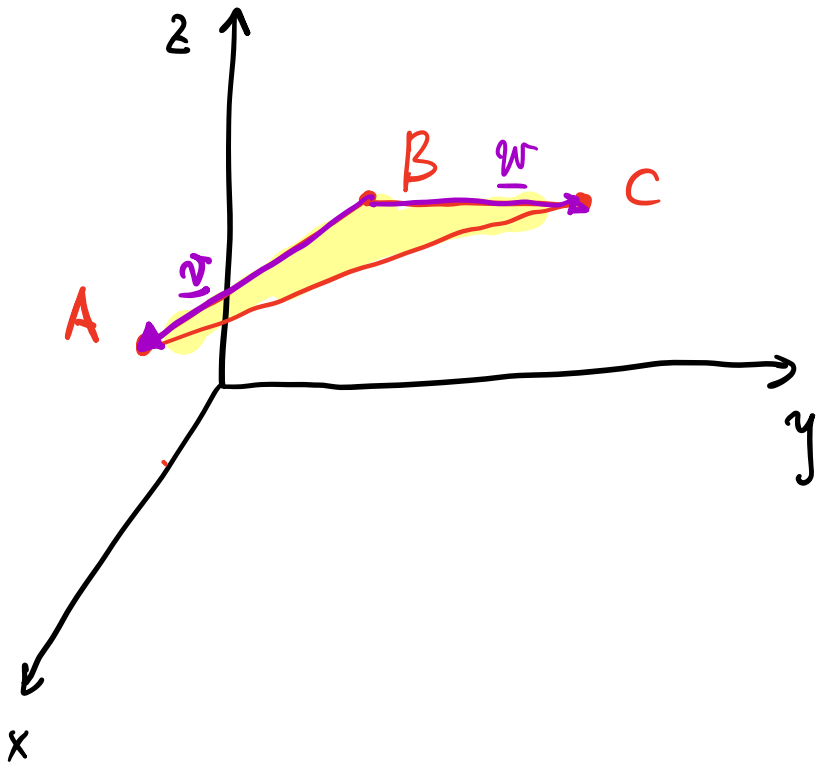
$$\left(\text{cioè} \quad \cos \theta = \frac{\langle \underline{v}, \underline{w} \rangle}{\|\underline{v}\| \cdot \|\underline{w}\|} \quad \text{se } \underline{v}, \underline{w} \neq 0 \right)$$



Esempio: Siano $A = (1, 0, 1)$

$$B = (-1, 1, 1) \quad C = (0, 2, 1)$$

in \mathbb{A}^3 (in cui abbiamo fissato
un sistema di rf. affine ortogonale)
trovare l'area del triangolo con
vertici A, B, C



$$\text{Sea } \underline{v} = A - B \quad \underline{w} = C - B$$

$$\text{Area del triángulo} = \frac{1}{2} \|\underline{v} \wedge \underline{w}\|$$

$$\underline{v} = \begin{pmatrix} 2 \\ -1 \\ 0 \end{pmatrix} \quad \underline{w} = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$$

$$\underline{v} \wedge \underline{w} = \det \begin{pmatrix} \underline{e}_1 & \underline{e}_2 & \underline{e}_3 \\ 2 & -1 & 0 \\ 1 & 1 & 0 \end{pmatrix} =$$

$$= 2\underline{e}_3 + \underline{e}_3 = 3\underline{e}_3 = \begin{pmatrix} 0 \\ 0 \\ 3 \end{pmatrix}$$

$$\|\underline{v} \wedge \underline{w}\| = \sqrt{0^2 + 0^2 + 3^2} = 3$$

$$\text{Area} = \frac{3}{2}.$$

Esempio: Sia r la retta in A^3

$$\begin{cases} x + y = 1 \\ x - z = 0 \end{cases}$$

determinare l'eq. parametrica di r

$$\begin{cases} 1 \cdot x + 1 \cdot y + 0 \cdot z = 1 \\ 1 \cdot x + 0 \cdot y - 1 \cdot z = 0 \end{cases}$$

i vettori $\begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$ e $\begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}$ sono una

basi di $(Tr)^\perp$

$\begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} \wedge \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}$ è tangente a r

ovvero $\text{span} \left\{ \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} \wedge \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} \right\} = Tr$

$$\begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} \wedge \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} = \det \begin{vmatrix} \underline{e}_1 & \underline{e}_2 & \underline{e}_3 \\ 1 & 1 & 0 \\ 1 & 0 & -1 \end{vmatrix} =$$

$$= -\underline{e}_1 - \underline{e}_3 + \underline{e}_2 = \begin{pmatrix} -1 \\ 1 \\ -1 \end{pmatrix}$$

prendiamo un qualunque punto di r :
 ed esempio $(0, 1, 0)$ [ponendo
 nel sistema $x=0$]

eq. parametriche:

$$\begin{cases} x = 0 + \lambda \cdot (-1) \\ y = 1 + \lambda \cdot 1 \\ z = 0 + \lambda \cdot (-1) \end{cases} \quad \lambda \in \mathbb{R}$$

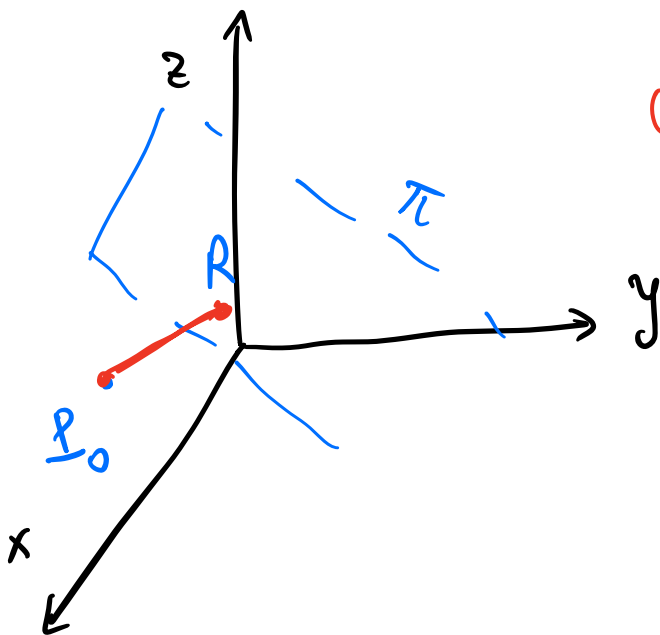
$$\begin{cases} x = -\lambda \\ y = 1 + \lambda \\ z = -\lambda \end{cases} \quad \lambda \in \mathbb{R}$$

Esempio: Sia π il piano

$$x + y + z = -1$$

e sia $P_0 = (1, 0, 1)$

Calcolare la distanza tra P_0 e π



$$\begin{aligned} \text{dist}(P_0, \pi) &= \\ \min \{ \text{dist}(P_0, P) & \\ P \in \pi \} \end{aligned}$$

1°) troviamo la retta r ortogonale
a π e passante per P_0 .

Poi determiniamo $R = \pi \cap r$

$$\text{dist}(P_0, \pi) = \|R - P_0\|$$

$$\pi: x + y + z = -1$$

$$\underline{v} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \quad \text{span}\{\underline{v}\} = (\perp \pi)^\perp$$

\underline{v} è un vettore tangente a r

$$r: \begin{cases} x = 1 + \lambda \cdot 1 \\ y = 0 + \lambda \cdot 1 \\ z = 1 + \lambda \cdot 1 \end{cases} \quad \lambda \in \mathbb{R}$$

P_0

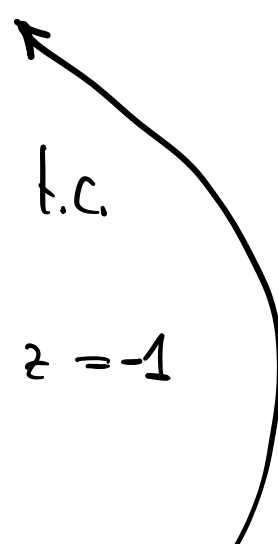
$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} \in r \iff \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 1 + \lambda \\ \lambda \\ 1 + \lambda \end{pmatrix} \quad \lambda \in \mathbb{R}$$

$$R = \pi \cap r$$

$\{$

$$\pi: \begin{pmatrix} x \\ y \\ z \end{pmatrix} \text{ t.c.}$$

$$x + y + z = -1$$



↓
sostituisco x, y, z con

$$(1+\lambda) + \lambda + (1+\lambda) = -1$$

$$(x + y + z = -1)$$

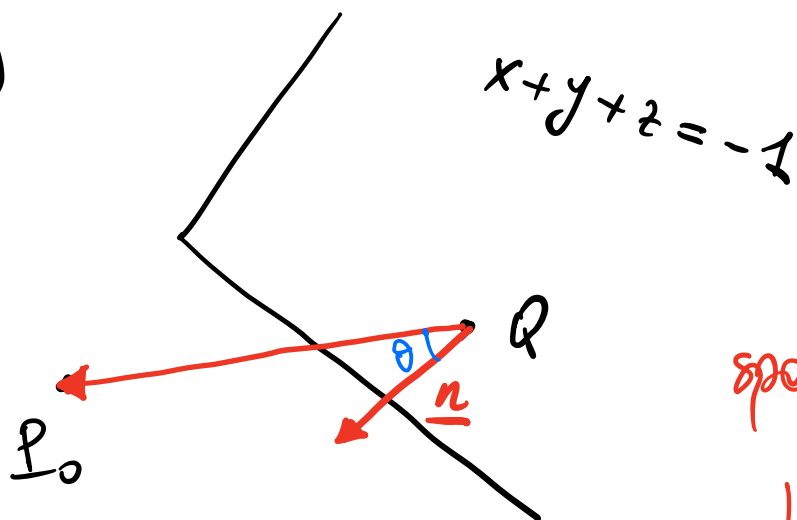
$$2 + 3\lambda = -1 \quad \lambda = -1$$

$$R = \begin{pmatrix} 1 + (-1) \\ -1 \\ 1 + (-1) \end{pmatrix} = \begin{pmatrix} 0 \\ -1 \\ 0 \end{pmatrix}$$

$$\|P_0 - R\| = \left\| \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} - \begin{pmatrix} 0 \\ -1 \\ 0 \end{pmatrix} \right\| =$$

$$\|R - P_0\| = \left\| \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \right\| = \sqrt{1^2 + 1^2 + 1^2} = \sqrt{3}$$

2°)

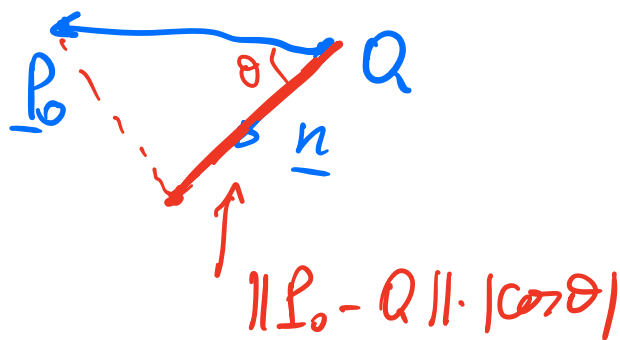


$$\text{span}\{\underline{n}\} = (\Gamma\pi)^\perp$$

$$\|\underline{n}\| = 1$$

$$|\langle P_0 - Q, \underline{n} \rangle| = \|P_0 - Q\| \cdot \underbrace{\|\underline{n}\|}_{1} |\cos\theta|$$

$$= \|P_0 - Q\| |\cos\theta|$$



$$\text{Quindi } \text{dist}(P_0, \pi) = |\langle P_0 - Q, \underline{n} \rangle|$$

$$P_0 = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$$

$$\pi: x + y + z = -1$$

$$Q = (-1, 0, 0)$$

$$\underline{v} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \perp T\pi$$

$$\|\underline{v}\| = \sqrt{3}$$

$$\underline{u} = \frac{\underline{v}}{\|\underline{v}\|} = \begin{pmatrix} 1/\sqrt{3} \\ 1/\sqrt{3} \\ 1/\sqrt{3} \end{pmatrix}$$

$$P_0 - Q = \begin{pmatrix} 2 \\ 0 \\ 1 \end{pmatrix}$$

$$\left| \left\langle \begin{pmatrix} 2 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1/\sqrt{3} \\ 1/\sqrt{3} \\ 1/\sqrt{3} \end{pmatrix} \right\rangle \right| = \frac{2}{\sqrt{3}} + \frac{1}{\sqrt{3}} = \sqrt{3}$$