

oss: se $d(\underline{v}, \underline{w}) := \|\underline{v} - \underline{w}\|$
 allora $P_U(\underline{v})$ è il punto di minima
 distanza di \underline{v} da U .

Prodotti scalari e metrici

$(V, \langle \cdot, \cdot \rangle)$ spazio metrico

$\{\underline{v}_1, \dots, \underline{v}_n\}$ base di V

$$a_{ij} := \langle \underline{v}_i, \underline{v}_j \rangle \quad i, j = 1, \dots, n$$

oss: poiché il prodotto scalare è
 simmetrico $\langle \underline{v}_i, \underline{v}_j \rangle = \langle \underline{v}_j, \underline{v}_i \rangle$

e quindi $\boxed{a_{ij} = a_{ji}} \quad (*)$

Sia

$$A := \begin{pmatrix} a_{11} & \dots & a_{1n} \\ \vdots & & \vdots \\ a_{n1} & \dots & a_{nn} \end{pmatrix}$$

OSS: (*) \Rightarrow A è simmetrica, ovvero

$$\boxed{A = A^t}$$

$$\underline{v} = \alpha_1 \underline{v}_1 + \dots + \alpha_n \underline{v}_n$$

$$\underline{w} = \beta_1 \underline{v}_1 + \dots + \beta_n \underline{v}_n$$

$$\langle \underline{v}, \underline{w} \rangle = \langle \alpha_1 \underline{v}_1 + \dots + \alpha_n \underline{v}_n, \beta_1 \underline{v}_1 + \dots + \beta_n \underline{v}_n \rangle$$

$$= \alpha_1 \langle \underline{v}_1, \beta_1 \underline{v}_1 + \dots + \beta_n \underline{v}_n \rangle + \dots + \alpha_n \langle \underline{v}_n, \beta_1 \underline{v}_1 + \dots + \beta_n \underline{v}_n \rangle$$

$$= \alpha_1 \beta_1 \langle \underline{v}_1, \underline{v}_1 \rangle + \dots + \alpha_1 \beta_n \langle \underline{v}_1, \underline{v}_n \rangle + \dots$$

$$+ \alpha_n \beta_1 \langle \underline{v}_n, \underline{v}_1 \rangle + \dots + \alpha_n \beta_n \langle \underline{v}_n, \underline{v}_n \rangle$$

$$= \alpha_1 \beta_1 Q_{11} + \dots + \alpha_1 \beta_n Q_{1n} + \dots + \alpha_n \beta_1 Q_{n1} + \dots$$

$$\dots + \alpha_n \beta_n Q_{nn} =$$

$$= (\alpha_1, \dots, \alpha_n) \begin{pmatrix} Q_{11} & \dots & Q_{1n} \\ \vdots & & \vdots \\ Q_{n1} & \dots & Q_{nn} \end{pmatrix} \begin{pmatrix} \beta_1 \\ \vdots \\ \beta_n \end{pmatrix}$$

Goal:

$$\underline{v} \mapsto \underline{x} := \begin{pmatrix} \alpha_1 \\ \vdots \\ \alpha_n \end{pmatrix} \quad \text{coordinate in } \{\underline{v}_1, \dots, \underline{v}_n\}$$

$$\underline{w} \mapsto \underline{y} := \begin{pmatrix} \beta_1 \\ \vdots \\ \beta_n \end{pmatrix} \quad \text{coordinate in } \{\underline{v}_1, \dots, \underline{v}_n\}$$

allow

$$\langle \underline{v}, \underline{w} \rangle = \underline{x}^t \cdot A \cdot \underline{y}$$

OSS:

$$\langle \underline{v}, \underline{w} \rangle = \underline{x}^t A \underline{y}$$

"

$$\langle \underline{w}, \underline{v} \rangle = \underline{y}^t \cdot A \cdot \underline{x}$$

$$\left[\begin{aligned} (\underline{x}^t A \underline{y})^t &= \underline{x}^t A \underline{y} \\ &= \underline{y}^t A^t \underline{x} \\ &= \underline{y}^t \cdot A \cdot \underline{x} \end{aligned} \right. \quad \begin{aligned} & \\ & \\ & A = A^t \end{aligned}$$

Lemma: A, B matrici $n \times n$. Se
 $\underline{x}^t A \underline{y} = \underline{x}^t B \underline{y}$ per ogni $\underline{x}, \underline{y} \in \mathbb{R}^n$
 allora $A = B$

Dim:

$$\underline{e}_i^t A \underline{e}_j =$$

$$\underline{e}_i^t \cdot A = (0, \dots, \underset{\substack{\uparrow \\ i}}{1}, 0, \dots, 0) \begin{pmatrix} a_{11} & \dots & a_{1n} \\ \vdots & & \vdots \\ a_{n1} & \dots & a_{nn} \end{pmatrix}$$

$$= (a_{i1} \dots a_{in}) \quad \begin{array}{l} i\text{-ma riga} \\ \text{della matrice} \end{array}$$

$$(A \cdot \underline{e}_j = \begin{pmatrix} a_{1j} \\ \vdots \\ a_{nj} \end{pmatrix} \quad j\text{-ma colonna})$$

$$\underline{e}_i^t A \cdot \underline{e}_j = (e_{i1} \dots e_{in}) \begin{pmatrix} 0 \\ \vdots \\ 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix} \leftarrow j = a_{ij}$$

se $\underline{x}^t A \underline{y} = \underline{x}^t B \underline{y}$ per ogni $\underline{x}, \underline{y}$

in particolare

$$\underline{e}_i^t A \underline{e}_j = \underline{e}_i^t B \underline{e}_j \text{ per ogni } i, j$$

$$\Rightarrow a_{ij} = b_{ij}$$



Assumiamo che $\{\underline{v}_1, \dots, \underline{v}_n\}$ sia base
ortogonale di V

$$\Rightarrow A = I$$

OSS: se $A = I \Rightarrow \{\underline{v}_1, \dots, \underline{v}_n\}$ è
base ortogonale perché:

$$\underline{v}_1 \mapsto \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix} \quad \text{nelle base } \{ \underline{v}_1, \dots, \underline{v}_n \}$$

$$\vdots$$

$$\underline{v}_n \mapsto \begin{pmatrix} 0 \\ \vdots \\ 1 \end{pmatrix} \quad \text{coord. nelle base } \{ \underline{v}_1, \dots, \underline{v}_n \}$$

$$\langle \underline{v}_i, \underline{v}_j \rangle = \begin{pmatrix} 0 \\ \vdots \\ 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix}^t \cdot I \begin{pmatrix} 0 \\ \vdots \\ 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix} \leftarrow j =$$

$$= \underline{e}_i^t \cdot I \cdot \underline{e}_j = \begin{cases} 0 & \text{se } i \neq j \\ 1 & \text{se } i = j \end{cases}$$

Sia $\{ \underline{w}_1, \dots, \underline{w}_n \}$ un'altra base
ortonormale di V

$\mathcal{P} := \{ \underline{v}_1, \dots, \underline{v}_n \}$ ortonormale

$\mathcal{W} := \{ \underline{w}_1, \dots, \underline{w}_n \}$ ortonormale

Sia C la matrice di cambiamento di base da V a W

ovvero se $\underline{v} \in V$ $\underline{v} \rightarrow \underline{x} = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}_P$

$$\underline{v} \rightarrow \underline{\tilde{x}} = \begin{pmatrix} \tilde{x}_1 \\ \vdots \\ \tilde{x}_n \end{pmatrix}_{W^P}$$

$$\underline{\tilde{x}} = C \underline{x}$$

$\underline{w} \in V$ $\underline{w} \rightarrow \underline{y} = \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix}_P$, $\underline{\tilde{y}} = \begin{pmatrix} \tilde{y}_1 \\ \vdots \\ \tilde{y}_n \end{pmatrix}_{W^P}$

$$\underline{\tilde{y}} = C \underline{y}$$

P ortogonale

$$\langle \underline{v}, \underline{w} \rangle \stackrel{P}{=} \underline{x}^t \cdot I \cdot \underline{y} = \underline{x}^t \cdot \underline{y}$$

W ortogonale

$$\underline{\tilde{x}}^t \cdot I \cdot \underline{\tilde{y}} = \underline{\tilde{x}}^t \cdot \underline{\tilde{y}}$$

$$\Rightarrow \underline{\tilde{x}}^t \underline{\tilde{y}} = \underline{x}^t \underline{y}$$

$$\begin{aligned} (C\underline{x})^t \cdot (C\underline{y}) &= (\underline{x}^t \cdot C^t) (C\underline{y}) = \\ &= \underline{x}^t (C^t \cdot C) \underline{y} \end{aligned}$$

per tanto per ogni $\underline{x}, \underline{y} \in \mathbb{R}^n$

$$\underline{x}^t \cdot \underline{I} \cdot \underline{y} = \underline{x}^t \underline{y} = \underline{x}^t (C^t \cdot C) \underline{y}$$

$$\Rightarrow \boxed{C^t C = I}$$

In altri termini $\boxed{C^{-1} = C^t}$

Def: Una matrice A $n \times n$ si dice
ortogonale se $A^{-1} = A^t$ (cioè
 se $AA^t = I$)

l'argomento precedente implica:

[Prop: $(V, \langle \cdot, \cdot \rangle)$ spazio metrico.
Siano $P = \{\underline{v}_1, \dots, \underline{v}_n\}$, $W = \{\underline{w}_1, \dots, \underline{w}_n\}$
due basi ortonormali di V .
Allora la matrice di cambiamento
di coordinate da P a W (e
quella da W a P) è una matrice
ortogonale]

OSS: A è una matrice ortogonale
se e solo se A^t è ortogonale.
 $\overset{''}{A^{-1}}$

A è ortogonale se e solo se i
vettori colonne di A formano una

base ortonormale di $(\mathbb{R}^n, \langle \cdot, \cdot \rangle_{st})$

$$A^t A = I$$

$$A = (\underbrace{\underline{a}_1 \dots \underline{a}_n}_{\substack{\uparrow \\ \text{vettori colonna}}}) \quad A^t = \begin{pmatrix} \underline{a}_1^t \\ \vdots \\ \underline{a}_n^t \end{pmatrix}$$

$$A^t \cdot A = \begin{pmatrix} \underline{a}_1^t \\ \vdots \\ \underline{a}_n^t \end{pmatrix} \cdot (\underline{a}_1 \dots \underline{a}_n) = \begin{pmatrix} \langle \underline{a}_1, \underline{a}_1 \rangle & \dots & \langle \underline{a}_1, \underline{a}_n \rangle \\ \vdots & & \vdots \\ \langle \underline{a}_n, \underline{a}_1 \rangle & \dots & \langle \underline{a}_n, \underline{a}_n \rangle \end{pmatrix}$$

$$A^t \cdot A = I \Leftrightarrow \langle \underline{a}_i, \underline{a}_j \rangle = \begin{cases} 0 & \text{se } i \neq j \\ 1 & \text{se } i = j \end{cases}$$