

## **SAM4S** User Peripherals

#### **Presentation Outline**

#### User Peripherals Initialization

- Product Mapping
- Peripheral Identifiers
- Product Dependencies
- USARTO Peripheral Initialization Example

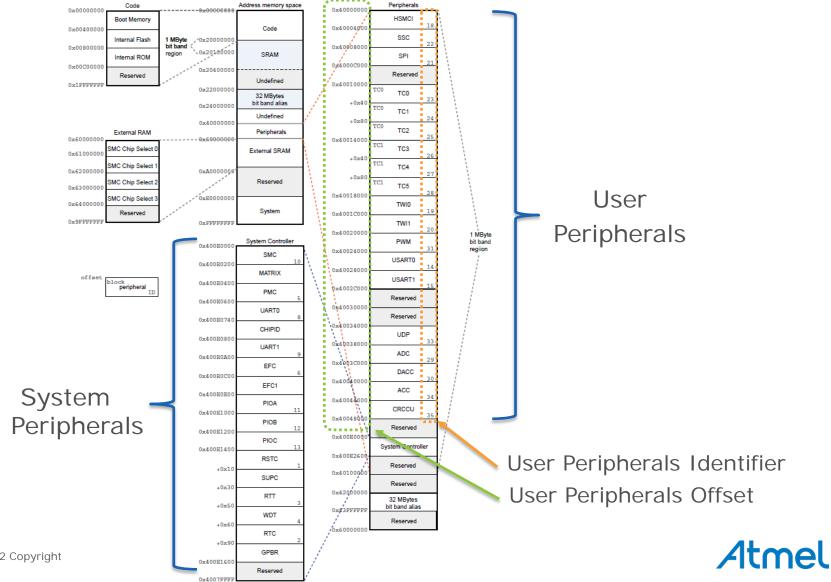
#### User Peripherals Highlights

- Serial Peripheral Interface (SPI)
- Two-wire Interface (TWI)
- Universal Asynchronous Receiver Transmitter (UART)
- Universal Synchronous Asynchronous Receiver Transmitter (USART)
- Synchronous Serial Controller (SSC)
- High Speed Multimedia Card Interface (HSMCI)
- Full Speed USB Device Port (UDP)
- Timer Counter (TC)
- Pulse Width Modulation Controller (PWM)
- Analog Comparator Controller (ACC)
- Analog-to-Digital Converter (ADC)
- Digital-to-Analog Converter Controller (DACC)
- CRC Unit (CRCCU)





## **Product Mapping**



## Peripheral Identifiers

- A Peripheral Identifier is required for:
  - Peripheral Interrupt Control using the NVIC.
  - Peripheral Clock Control using the PMC.

User Peripherals ID

System Peripherals ID

			PMC	Instance Description	
Instance ID	Instance Name	NVIC Interrupt	Clock Control		
0	SUPC	X		Supply Controller	
1	RSTC	X		Reset Controller	
2	RTC	Х		Real Time Clock	
3	RTT	Х		Real Time Timer	
4	WDT	X		Watchdog Timer	
5	PMC	Х		Power Management Controller	
6	EEFC0	Х		Enhanced Embedded Flash Controller 0	
7	EEFC1	-		Enhanced Embedded Flash Controller 1	
8	UART0	Х	Х	UART 0	
9	UART1	Х	х	UART 1	
10	SMC	-	х	Static Memory Controller	
11	PIOA	Х	х	Parallel I/O Controller A	
12	PIOB	Х	Х	Parallel I/O Controller B	
13	PIOC	Х	х	Parallel I/O Controller C	
14	USART0	Х	Х	USART 0	
15	USART1	Х	Х	USART 1	
16	-	-	-	Reserved	
17	-	-	-	Reserved	
18	HSMCI	Х	х	Multimedia Card Interface	
19	TWI0	Х	х	Two Wire Interface 0	
20	TWI1	Х	х	Two Wire Interface 1	
21	SPI	Х	х	Serial Peripheral Interface	
22	SSC	Х	Х	Synchronous Serial Controller	
23	TC0	Х	Х	Timer/Counter 0	
24	TC1	Х	Х	Timer/Counter 1	
25	TC2	Х	х	Timer/Counter 2	
26	TC3	Х	х	Timer/Counter 3	
27	TC4	Х	Х	Timer/Counter 4	
28	TC5	Х	Х	Timer/Counter 5	
29	ADC	х	х	Analog To Digital Converter	
30	DACC	Х	х	Digital To Analog Converter	
31	PWM	Х	Х	Pulse Width Modulation	
32	CRCCU	х	Х	CRC Calculation Unit	
33	ACC	х	Х	Analog Comparator	
34	UDP	Х	Х	USB Device Port	



## Product Dependencies

#### • I/O Lines (PIO)

- User Peripheral pins may be multiplexed with PIO lines.
- The programmer must first program the PIO controllers to assign the User Peripheral pins to their peripheral functions.
- Other I/Os features such as pull-up/down or multi drive may be configured too.

#### Power Management (PMC)

- The User Peripheral may be clocked through the Power Management Controller.
- The programmer must first configure the PMC to enable the User Peripheral clock.

#### Interrupt (NVIC)

- The User Peripheral interface has an interrupt line connected to the NVIC Interrupt Controller.
- Handling the User Peripheral interrupt requires programming the interrupt controller before configuring the User Peripheral.

#### Peripheral DMA (PDC) – (if available for the User Peripheral)

 The User Peripheral interface may be used in conjunction with the PDC in order to reduce processor overhead.



## **USARTO** Peripheral Initialization Example

#### 1. I/O Lines (PIO)

The PIO Controller provides multiplexing of up to four peripheral functions on a single pin.

• The selection is performed by writing PIO\_ABCDSR1 / PIO\_ABCDSR2 (ABCD Select Registers).

I/O Line	Peripheral A	Peripheral B	Peripheral C	Extra Function	System Function	Comments
PA5	RXD0	NPCS3		WKUP4		
PA6	TXD0	PCK0				

```
// PIOA Controller Base Address defined in SAM4S.h  
#define PIOA  
((Pio *)0x400E0E00U)

// Clear PA5/PA6 bits in PIO_ABCDSR1 to assign I/O lines to Peripheral A PIOA->PIO_ABCDSR[0] &= \sim((1 << 5)|(1 << 6)); 
// Clear PA5/PA6 bits in PIO_ABCDSR2 to assign I/O lines to Peripheral A PIOA->PIO_ABCDSR[1] &= \sim((1 << 5)|(1 << 6)); 
// Enable USART0 RXD0 (PA5) & TXD0 (PA6) 
PIOA->PIO_PDR = (1 << 5)|(1 << 6);
```



USARTO Peripheral Initialization Example (cont.)

2. Power Management (PMC)

```
// PMC Controller Base Address defined in SAM4S.h

#define PMC ((Pmc *)0x400E0400U)

0x400E0400

0x400E0600

PMC

0x400E0600

Ox400E0600

USARTO

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```



USARTO Peripheral Initialization Example (cont.)

- 3. User Peripheral Configuration
  - Asynchronous
  - 115200 8bits No Parity 1 Stop bit

```
0x40024000
// USART 0 Base Address defined in SAM4S.h
                                                                 USART0
                   ((Usart *)0x40024000U
#define USART0
                                                0x40028000
// Reset and disable receiver & transmitter
USARTO->US_CR= US_CR_RSTRX | US_CR_RSTTX | US_CR_RXDIS | US_CR_TXDIS;
// Configure USARTO Mode Register
USARTO->US MR = US MR USART MODE NORMAL US MR CHRL 8 BIT US MR PAR NO
  US MR NBSTOP 1 BIT;
// Configure USARTO Baudrate
USARTO->US BRGR = MCK/115200;
// Enable TX and RX
USARTO->US_CR = US_CR_TXEN
                             US CR RXEN;
```



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USARTO Peripheral Initialization Example (cont.)

# 4. Interrupt (NVIC) // Enable IRQn (CMSIS function) NVIC\_EnableIRQ(14); 0x40024000 USARTO 14

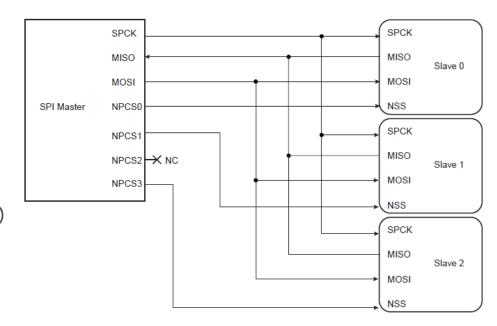
#### 5. Peripheral DMA (PDC)





## Serial Peripheral Interface (SPI)

- Supports communication with serial external devices
  - 4 hardware chip selects
  - Up to 15 peripherals using external decoder
  - Serial memories (DataFlash...)
  - Serial peripherals (ADC, DAC...)

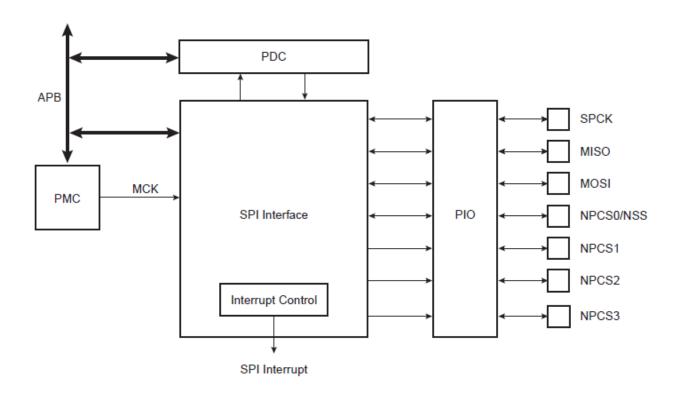


- Master / Slave
  - 8- to 16-bit programmable data length per chip select
  - SPI modes 0, 1, 2 and 3
    - Programmable phase and polarity per chip select
  - Programmable delays between:
    - Chip selects
    - Consecutive transfers
    - Clock and data per chip select



Serial Peripheral Interface (SPI)

Master Mode can run SPI Clock (SPCK) up to MCK



- PDC Support
  - One Transmit PDC channel + One Receive PDC channel



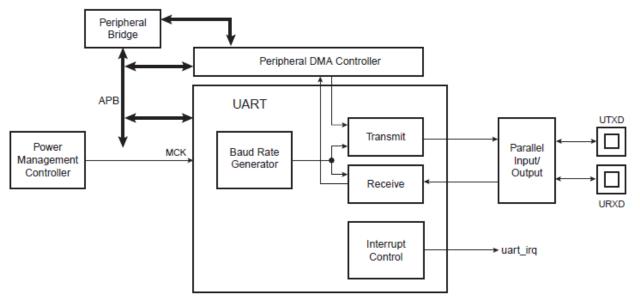
Two-Wire Interface (TWI)

- Master, Multi-Master and Slave Mode Operation
- Compatibility with I2C compatible devices
- One, two or three bytes for slave address
- Fast Mode Speed (Up to 400 kbit/s)
- VDD General Call Supported in Slave Mode TWD Host with TWI TWCK Interface Atmel TWI I C LCD I C Temp. I C RTC Serial EEPROM Controller Sensor Slave 1 Slave 2 Slave 3 Slave 4
- PDC Support
  - One Transmit PDC channel + One Receive PDC channel



Universal Asynchronous Receiver Transmitter (UART)

- Two-pin UART
  - Independent receiver and transmitter with a Baud Rate Generator
  - Even, Odd, Mark or Space Parity Generation
  - Automatic Echo, Local Loopback and Remote Loopback Channel Modes



- PDC Support
  - One Transmit PDC channel + One Receive PDC channel



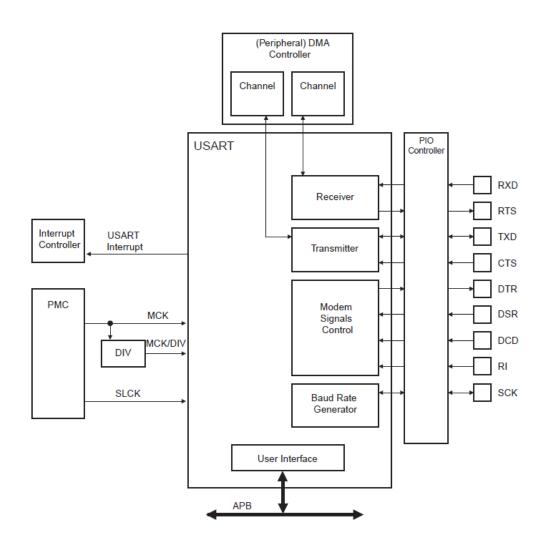
Universal Synchronous Asynchronous Receiver Transmitter (USART)

- 5- to 9-bit full-duplex synchronous/asynchronous serial com
  - Hardware handshaking RTS-CTS
  - Optional Manchester Encoding
  - Full modem line support on USART1 (DCD-DSR-DTR-RI)
- RS485 with driver control signal
- ISO7816, T = 0 or T = 1 Protocols for interfacing with smart cards
- SPI Mode
  - Master or Slave
  - Serial Clock programmable Phase and Polarity
  - SPI Serial Clock (SCK) Frequency up to MCK/4
- IrDA modulation and demodulation
  - Communication at up to 115.2 Kbps



Universal Synchronous Asynchronous Receiver Transmitter (USART)

- Common USART Signals:
  - SCK Serial Clock
  - RXD Receive Data
  - RTS Request To send
  - TXD Transmit Data
  - CTS Clear To Send
- Modem Signals:
  - DTR Data Terminal Ready
  - DSR Data Set Ready
  - DCD Data Carrier Detect
  - RI Ring Indicator
- PDC Support
  - One Transmit PDC channel
  - One Receive PDC channel

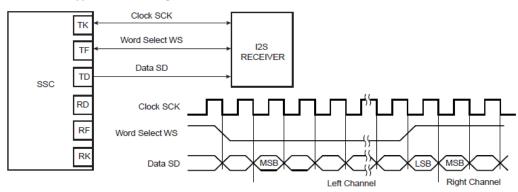




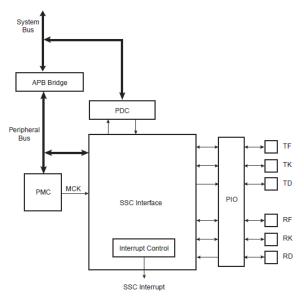
## Synchronous Serial Controller (SSC)

- Provides serial synchronous communication links with external devices
  - CODECs, I2S, TDM Buses...

Figure 31-17. Audio Application Block Diagram



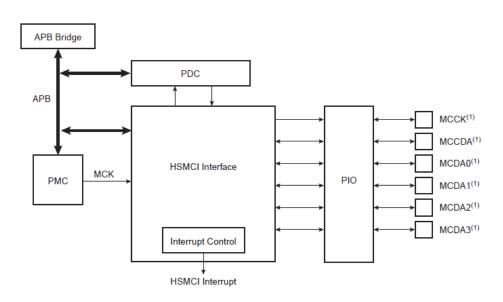
- Receiver and transmitter include:
  - a data signal
  - a clock signal
  - a frame synchronization signal
- PDC Support
  - One Transmit PDC channel
  - One Receive PDC channel





High Speed MultiMedia Card Interface (HSMCI)

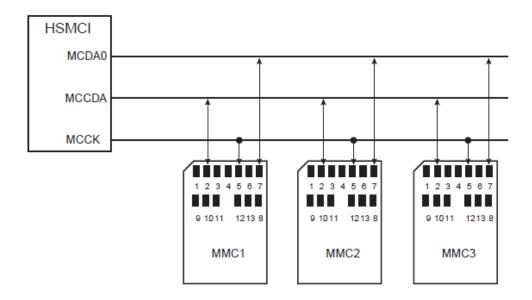
- 1-bit or 4-bit Interface
- Compatibility with:
  - MultiMedia Card Specification Version 4.3
  - SD and SDHC Memory Card Specification Version 2.0
  - SDIO Specification Version V1.1.
- High Speed mode support
- Cards clock rate up to MCK/2
- PDC Support
  - 1 Common PDC channel for transmit/receive (half duplex)



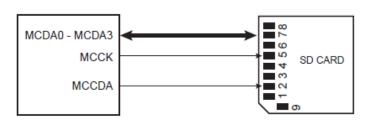


High Speed MultiMedia Card Interface (HSMCI)

- MCI has one slot supporting
  - One MultiMediaCard bus (up to 30 cards)



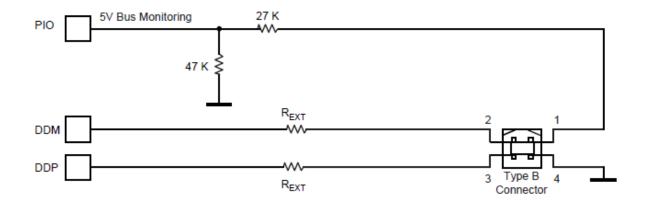
- Or one SD Memory Card
- Or one SDIO Card





USB Device Port (UDP)

- USB V2.0 full-speed compliant, 12 Mbits per second.
  - Eight endpoints
  - Embedded 2688-byte Dual-Port RAM for endpoints
  - Suspend/resume logic
- Embedded USB V2.0 full-speed transceiver



- Integrated Pull-up on DDP
- Pull-down resistors on DDM and DDP when disabled



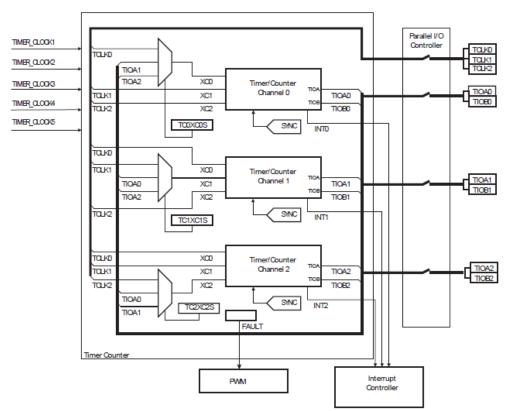
## Timer Counter (TC)

- Six 16-bit Timer Counter Channels
  - Two Timer Counters / Three 16-bit TC Channels per Timer Counter
- Wide range of functions including:
  - Frequency Measurement
  - Event Counting
  - Interval Measurement
  - Pulse Generation
  - Delay Timing
  - Pulse Width Modulation
  - Up/down Capabilities
- Quadrature decoder
  - Position / revolution / speed
- 2-bit Gray Up/Down Counter for Stepper Motor



## Timer Counter (TC)

- Each channel is user-configurable and contains:
  - Three external clock inputs: TCLKx
  - Five internal clock inputs: TIMER\_CLOCKx
  - Two multi-purpose input/output signals: TIOA/TIOB





Pulse Width Modulation Controller (PWM)

- One Four-channel 16-bit PWM Controller
  - 16-bit counter per channel
- Common clock generator, providing Thirteen Different Clocks
  - A Modulo n counter providing eleven clocks
  - Two independent Linear Dividers working on modulo n counter outputs
- Independent channel programming
  - Independent Enable Disable Commands
  - Independent Clock Selection
  - Independent Period and Duty Cycle, with Double Buffering
  - Programmable selection of the output waveform polarity
  - Programmable center or left aligned output waveform
  - Independent complementary Outputs with 12-bit dead time generator



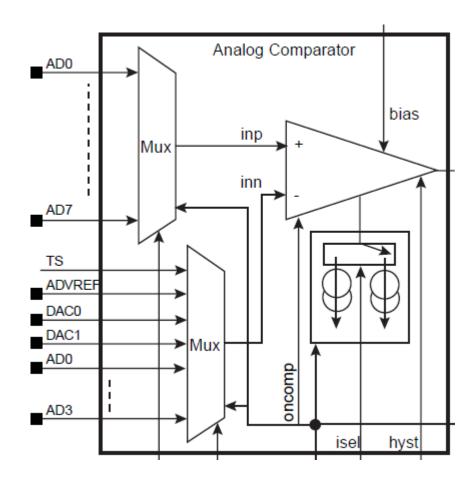
Pulse Width Modulation Controller (PWM)

- Synchronous Channel mode
  - Synchronous Channels share the same counter
  - Mode to update the synchronous channels registers after a programmable number of periods
- Two independent event lines which can send up to 4 triggers on ADC within a period
- One programmable Fault Input providing an asynchronous protection of outputs
- Stepper motor control (2 Channels)
- PDC Support
  - 1 Transmit PDC channel
  - Update duty cycle of synchronous channels



Analog Comparator Controller (ACC)

- 8 User Analog Inputs Selectable for Comparison
  - AD0 to AD7
- 4 Voltage References Selectable for Comparison:
  - Temperature Sensor
  - ADVREF
  - DACO and DAC1
- Compare Event Fault Generation for PWM





Analog-to-Digital Converter (ADC)

- Up to 16 Channels, 12-bit ADC
  - 10/12-bit resolution
  - Up to 1 MSample/s
- Programmable conversion sequence conversion on each channel
- Integrated temperature sensor (Analog Channel 15)
- Automatic calibration mode
- Single ended/differential conversion
- Programmable gain: 1, 2, 4
- PDC Support
  - 1 Receive PDC channel



Digital-to-Analog Converter Controller (DACC)

- Up to Two Independent Analog Outputs, 12-bit Resolution
- Individual Enable and Disable of Each Analog Channel
- Hardware Trigger or External Trigger Pins
- Sleep Mode
- Automatic Wake-up on Trigger and Back-to-Sleep Mode after Conversions of all Enabled Channels
- PDC Support
  - 1 Transmit PDC channel



Cyclic Redundancy Check Calculation Unit (CRCCU)

- 32-bit cyclic redundancy check automatic calculation
- Three different polynomials are available:
  - CCITT802.3
  - CASTAGNOLI
  - CCITT16.
- CRC comparison between two addresses of the memory
- One Master on the AHB with its own DMA Controller
  - Computes CRC on the fly





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