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Code:

```
#include <Servo.h>
#include <AFMotor.h>
AF_DCMotor motor(4);
const int trigpin = 13;
const int echopin = 12;
const int led = 11;
Servo servo_t;
void setup(){
    serial.begin(9600);
    pinMode(trigpin, OUTPUT);
    pinMode(echopin, INPUT);
    pinMode(led, OUTPUT);
    motor.setSpeed(200);
    motor.run(RELEASE);
}

void loop(){
    int d = 012;

    uint8_t i;

    for(i=0; i<id; i++)
    {
        motor.setSpeed(i);
        motor.delay(10);
    }
}
```

```cpp
void loop() {
    int id = 012;
    for (int i=0; i<id; i++)
    {   servo_t.write(i);
        delay(5);
    }

    long duration, distance;
    digitalWrite(trigpin, LOW);
    delayMicroseconds(2);
    digitalWrite(trigpin, HIGH);
    delayMicroseconds(2);
    digitalWrite(trigpin, LOW);
    duration= pulseIn(echopin, HIGH);
    distance = (duration/2) * 0.034;

    int area= 3.1416* distance * distance;

    Serial.println(area);
    delay(5);

}
```