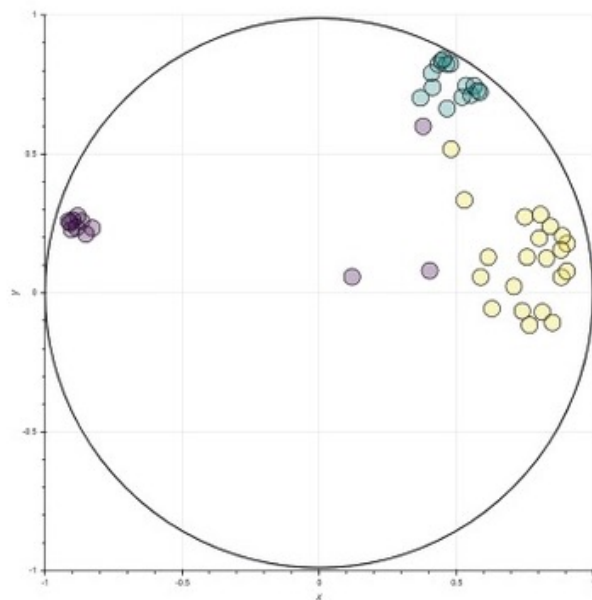
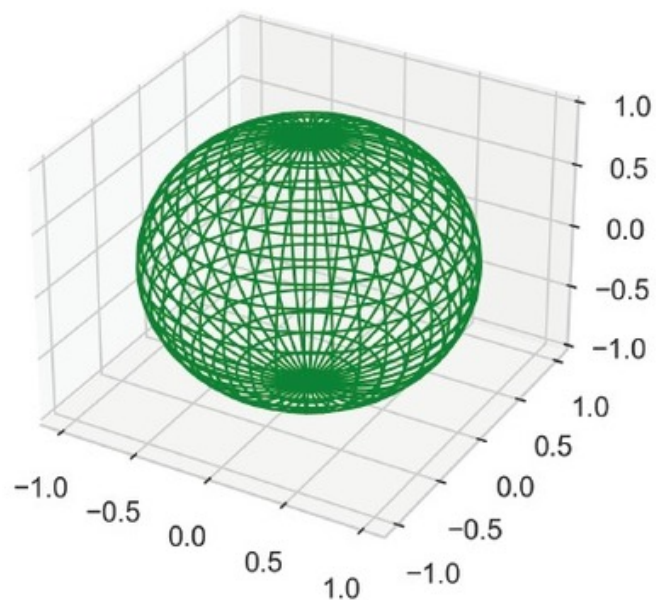


① UMAP



② Projections



③ Clustering and noise identification

