

# Riemannian Manifolds

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**Abstract**

## Contents

# 1 Riemannian Metrics

## 1.1 The Riemannian Metric

### Definition 1.1.1: Riemannian Metric

Let  $M$  be a smooth manifold. A Riemannian metric on  $M$  is a function  $g : TM \times TM \rightarrow \mathbb{R}$  such that for each  $p \in M$ , the restriction of  $g$  to  $T_p M \times T_p M$ , denoted  $g_p$  has the following properties.

- Symmetric:  $g_p(X_p, Y_p) = g_p(Y_p, X_p)$  for all  $X_p, Y_p \in T_p M$
- Positive Definite:  $g_p(X_p, X_p) > 0$  for all  $X_p \in T_p M$  with  $X_p \neq 0$
- Bilinearity:  $g_p(aX_p + bY_p, Z_p) = ag_p(X_p, Z_p) + bg_p(Y_p, Z_p)$  and  $g_p(X_p, aY_p + bZ_p) = ag_p(X_p, Y_p) + bg_p(X_p, Z_p)$

### Definition 1.1.2: Riemannian Manifold

A Riemannian manifold  $(M, g)$  is a manifold  $M$  together with a Riemannian metric  $g$  on  $M$ .

## 1.2 Bundle Metric

### Definition 1.2.1: Bundle Metric

Let  $M$  be a topological manifold and  $p : E \rightarrow M$  a vector bundle on  $M$ . Then a bundle metric on  $E$  is a section of  $E^* \otimes E^*$  such that it is nondegenerate and symmetric.

In other words, a bundle metric is an assignment to each fibre, an inner product. Bilinearity is seen from  $E^* \otimes E^*$ , which is exactly the set of all bilinear forms  $E \times E \rightarrow \mathbb{R}$ .

### Proposition 1.2.2

Let  $M$  be a smooth manifold. Then a Riemannian metric give rise to a bundle metric on  $TM$ . A bundle metric on  $TM$  gives rise to a Riemannian metric.

## 2 Levi-Civita Connection

### 3 Geodesics

**Definition 3.0.1: Geodesics**

A curve  $\gamma : (a, b) \rightarrow M$  is called a geodesic if  $D_t(\gamma'(t)) = 0$  for all  $t \in (a, b)$ .