CS 4400 - Problem Set 6 Rob Johansen

u0531837

}

```
1. Problem 3.67:
      A. el.p is at byte offset 0
         el.y is at byte offset 4
         e2.x
                is at byte offset 0
         e2.next is at byte offset 4
      B. The total bytes required for this union would be 8.
      C. Here is the missing code for the proc() function:
               void proc(union ele *up)
               {
                   up \rightarrow next.y = *(up \rightarrow next.p) - up \rightarrow x;
2. Problem 5.16. This is a version that uses four-way loop unrolling. Code
   that is new or modified has been highlighted in red:
         void inner4(vec ptr u, vec ptr v, data t *dest)
         {
               long int i;
               int length = vec length(u);
               int limit = length - 3;
               data t *udata = get vec start(u);
               data t *vdata = get vec start(v);
               data t sum = (data) 0;
               for (i = 0; i < limit; i += 4) {
                     sum = (((sum + udata[i] * vdata[i])
                                  + udata[i+1] * vdata[i+1])
                                  + udata[i+2] * vdata[i+2])
                                  + udata[i+3] * vdata[i+3];
               for (; i < length; i++) {
                     sum = sum + udata[i] * vdata[i];
               *dest = sum;
```

- A. No version can achieve a CPE less than 2.00 because of the datadependency chain between loop registers.
- B. Performance did not improve for loop unrolling because there are still n multiply operations. It's true that there are now 1/4 as many iterations, but each iteration now has 4 multiplications in sequence.
- 3. Problem 5.17. This is a version that uses four-way loop unrolling with four parallel accumulator. Code that is new or modified has been highlighted in red:

```
void inner4(vec ptr u, vec ptr v, data t *dest)
     long int i;
     int length = vec length(u);
     int limit = length - 3;
     data t *udata = get vec start(u);
     data t *vdata = get vec start(v);
     data t sum0 = (data) 0;
     data t sum1 = (data) 0;
     data t sum2 = (data) 0;
     data t sum3 = (data) 0;
     for (i = 0; i < limit; i += 4) {
           sum0 = sum0 + udata[i] * vdata[i];
           sum1 = sum1 + udata[i+1] * vdata[i+1];
           sum2 = sum2 + udata[i+2] * vdata[i+2];
           sum3 = sum3 + udata[i+3] * vdata[i+3];
     }
     for (; i < length; i++) {
           sum0 = sum0 + udata[i] * vdata[i];
     *dest = sum0 + sum1 + sum2 + sum3;
}
```

- A. The performance is limited to a CPE of 2.00 because of the datadependency chain between loop registers.
- B. The version with integer data on IA32 is worse because a new datadependency chain between loop registers is introduced.

4. Problem 5.18. This is a version that uses four-way loop unrolling along with reassociation. Code that is new or modified has been highlighted in red:

```
void inner4(vec ptr u, vec ptr v, data t *dest)
     long int i;
     int length = vec length(u);
     int limit = length - 3;
     data t *udata = get vec start(u);
     data t *vdata = get vec start(v);
     data t sum = (data) 0;
     for (i = 0; i < limit; i += 4) {
           sum = sum + ((((udata[i] * vdata[i]))
                         + udata[i+1] * vdata[i+1])
                         + udata[i+2] * vdata[i+2])
                         + udata[i+3] * vdata[i+3]);
     }
     for (; i < length; i++) {</pre>
           sum = sum + udata[i] * vdata[i];
     *dest = sum;
}
```