

Mathematical methods

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0.1 The purpose

This document was written to be used as a summary to help revise the content covered mathematical methods. For any inquiries, feedback, and further explanations, contact lachlanprivate@duck.com or through the discord server: <https://discord.gg/6P8rddkXFr>. I encourage you to let me know of any topic I missed, how I could explain it better, or how it could be reworded or formatted to be more helpful in its purpose. The goal of this document is to be a comprehensive summary of everything you need to know.

Mathematical Methods v1.2



Mensuration			
circumference of a circle	$C = 2\pi r$	area of a circle	$A = \pi r^2$
area of a parallelogram	$A = bh$	area of a trapezium	$A = \frac{1}{2}(a+b)h$
area of a triangle	$A = \frac{1}{2}bh$	total surface area of a cone	$S = \pi rs + \pi r^2$
total surface area of a cylinder	$S = 2\pi rh + 2\pi r^2$	surface area of a sphere	$S = 4\pi r^2$
volume of a cone	$V = \frac{1}{3}\pi r^2 h$	volume of a cylinder	$V = \pi r^2 h$
volume of a prism	$V = Ah$	volume of a pyramid	$V = \frac{1}{3}Ah$
volume of a sphere	$V = \frac{4}{3}\pi r^3$		

Sequences and series	
arithmetic sequence	$t_n = t_1 + (n-1)d$ $S_n = \frac{n}{2}(2t_1 + (n-1)d) = \frac{n}{2}(t_1 + t_n)$
geometric sequence	$t_n = t_1 r^{(n-1)}$ $S_n = t_1 \frac{(r^n - 1)}{(r - 1)}$ $S_\infty = \frac{t_1}{(1 - r)}, r < 1$

Logarithms	
exponents and logarithms	$a^x = b \Leftrightarrow x = \log_a(b)$
logarithmic laws	$\log_a(x) + \log_a(y) = \log_a(xy)$ $\log_a(x) - \log_a(y) = \log_a\left(\frac{x}{y}\right)$ $\log_a(x^n) = n\log_a(x)$ $\log_a(x) = \frac{\log_b(x)}{\log_b(a)}$

Calculus		
$\frac{d}{dx} x^n = n x^{n-1}$	$\int x^n dx = \frac{x^{n+1}}{n+1} + c$	
$\frac{d}{dx} e^x = e^x$	$\int e^x dx = e^x + c$	
$\frac{d}{dx} \ln(x) = \frac{1}{x}$	$\int \frac{1}{x} dx = \ln(x) + c$	
$\frac{d}{dx} \sin(x) = \cos(x)$	$\int \sin(x) dx = -\cos(x) + c$	
$\frac{d}{dx} \cos(x) = -\sin(x)$	$\int \cos(x) dx = \sin(x) + c$	
chain rule	If $h(x) = f(g(x))$ then $h'(x) = f'(g(x))g'(x)$	If $y = f(u)$ and $u = g(x)$ then $\frac{dy}{dx} = \frac{dy}{du} \times \frac{du}{dx}$
product rule	If $h(x) = f(x)g(x)$ then $h'(x) = f(x)g'(x) + f'(x)g(x)$	$\frac{d}{dx}(uv) = u \frac{dv}{dx} + v \frac{du}{dx}$
quotient rule	If $h(x) = \frac{f(x)}{g(x)}$ then $h'(x) = \frac{f'(x)g(x) - f(x)g'(x)}{(g(x))^2}$	$\frac{d}{dx}\left(\frac{u}{v}\right) = \frac{v \frac{du}{dx} - u \frac{dv}{dx}}{v^2}$

Trigonometry	
cosine rule	$c^2 = a^2 + b^2 - 2ab \cos(C)$
sine rule	$\frac{a}{\sin(A)} = \frac{b}{\sin(B)} = \frac{c}{\sin(C)}$
area of a triangle	$\text{area} = \frac{1}{2} bc \sin(A)$
Pythagorean identity	$\sin^2(A) + \cos^2(A) = 1$

Statistics		
binomial theorem	$(x + y)^n = x^n + \binom{n}{1} x^{n-1} y + \dots + \binom{n}{r} x^{n-r} y^r + \dots + y^n$	
binomial probability	$P(X = r) = \binom{n}{r} p^r (1 - p)^{n-r}$	
discrete random variable X	mean	$E(X) = \mu = \sum p_i x_i$
	variance	$Var(X) = \sum p_i (x_i - \mu)^2$
continuous random variable X	mean	$E(X) = \mu = \int_{-\infty}^{\infty} x p(x) dx$
	variance	$Var(X) = \int_{-\infty}^{\infty} (x - \mu)^2 p(x) dx$
binomial distribution	mean	np
	variance	$np(1 - p)$
sample proportion	mean	p
	standard deviation	$\sqrt{\frac{p(1 - p)}{n}}$
approximate confidence interval for p	$\left(\hat{p} - z \sqrt{\frac{\hat{p}(1 - \hat{p})}{n}}, \hat{p} + z \sqrt{\frac{\hat{p}(1 - \hat{p})}{n}} \right)$	
general addition rule for probability	$P(A \cup B) = P(A) + P(B) - P(A \cap B)$	
probability of independent events	$P(A \cap B) = P(A) \times P(B)$	
conditional probability	$P(A B) = \frac{P(A \cap B)}{P(B)}$	

Chapter 1

Sequences

1.1 Arithmetic sequences

An arithmetic sequence is a sequence of numbers where the terms are increasing or decreasing at a constant rate.

1.1.1 Recursive definition

The recursive definition of an arithmetic sequence is:

$$t_{n+1} = t_n + d$$

Where t_{n+1} is the next term, t_n is the current term, and d is the common difference or “by how much the sequence goes up by”.

1.1.2 General equation

The general equation for finding the n^{th} term of the sequence is:

$$t_n = t_1 + (n - 1)d$$

Where t_n is the n^{th} term of the sequence, t_1 is the first term of the sequence, and d is the common difference.

1.1.3 Sum of all prior arithmetic sequence

The sum of all arithmetic sequence is given by:

$$S_n = \frac{n}{2}(2t_1 + (n - 1)d) = \frac{n}{2}(t_1 + t_n)$$

Where S_n is the sum of the prior sequences up to the n^{th} term, n is the number of sequences, d is the common difference, t_1 is the first term, and t_n is the n^{th} term.

1.2 Geometric sequences

1.2.1 General equation

Geometric sequences are similar to arithmetic sequences, however, it multiplies instead of add the common difference. The equation for the n^{th} term is:

$$t_n = t_1 \times r^{n-1}$$

Where r is the common ratio, n is the term number, t_n is the n^{th} term, and t_1 is the first term.

1.2.2 Recursive definition

The recursive definition is:

$$t_{n+1} = r \times t_n$$

1.2.3 Sum

Sum of n geometric sequence

The sum of the first n^{th} terms of a geometric sequence is:

$$S_n = t_1 \times \frac{r^n - 1}{r - 1}$$

Sum of all geometric sequence

And the sum of an infinite geometric sequence is:

$$S_\infty = \frac{t_1}{1 - r}$$

NOTE:

This equation only provides a non-infinite solution where $-1 < r < 1$

Compound interest is:

$$A = (1 + r)^n \times P$$

Where A is the total amount of the investment, P is the principle, (i.e. the initial investment), r is the percentage interest, and n is the number of compounding periods (i.e. how many times the interest has been taken)

Chapter 2

Functions and relations

2.1 Functions

Functions is a mathematical concept where if given an input, it performs some operations, and returns an output. They have the mathematical notation of $f(x)$ where f can be seen as the name of the function and the values within the parenthesis as inputs to the function. A function must be defined for it to be used. A simple function which calculates the y-values along a parabola with the x-coordinates as input could be:

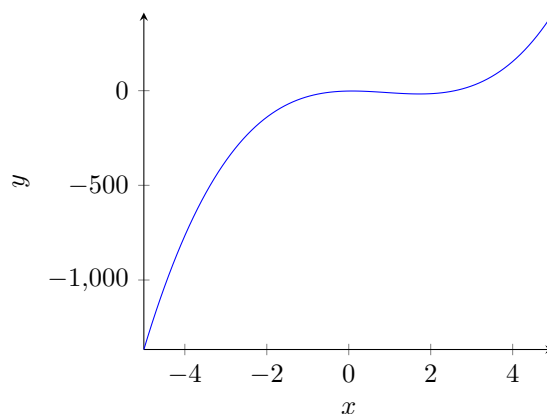
$$M(x) := x^2$$

$$\begin{aligned} M(x) &= x^2 \\ M(3) &= (3)^2 \\ M(3) &= 9 \end{aligned}$$

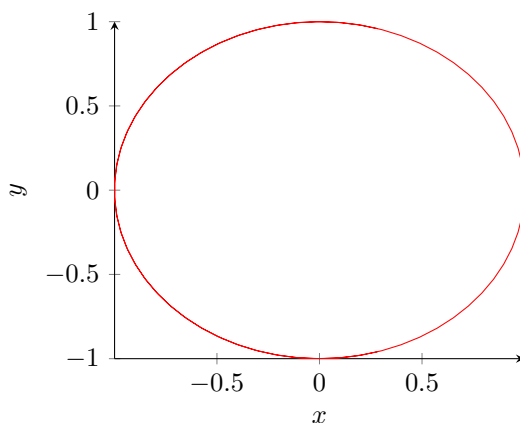
Functions can only give a one-to-one relation or a many-to-one relation since there is a clear defined input and output values with the concept of a function. To check if a graph is a function a *vertical line test* can be performed:

If the graph intersects any vertical line more than once, it cannot be a function, and is instead a relation.

This is a function:



This is not a function:



2.2 Interval notation

Interval notation are used to define the range of a function or a relation. For example, if given a function where the y-values start at 0 and approach but never reach 1, to define the range of the function, it would be $0 \leq y < 1$. However, this can be rewritten using interval notation as: $[0, 1)$. The square bracket meaning that it is $=$, \geq , and \leq , and the parenthesis meaning that it is $<$, or $>$ where it will never reach the value.

NOTE:

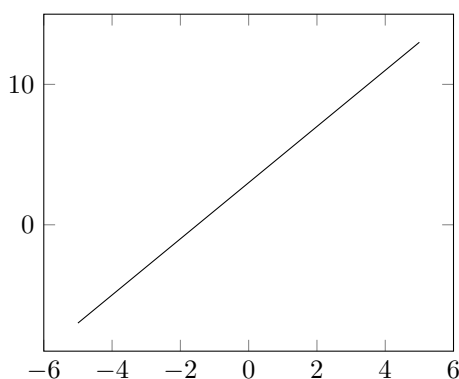
It is called a “range” when it is the y-value, and a “domain” when it is the x-value.

2.3 Relations

There are four types of relations, relations meaning for any x-value, how many valid y-values there are. The four are: one-to-one, many-to-one, one-to-many, and many-to-many.

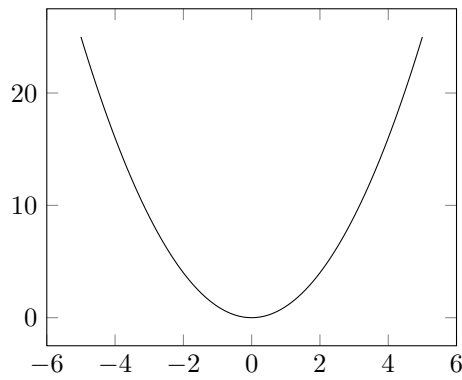
The first, (one-to-one) relation means that for any x-values, there is only one y-value. An example would be a straight line:

$$f(x) := 2x + 3$$

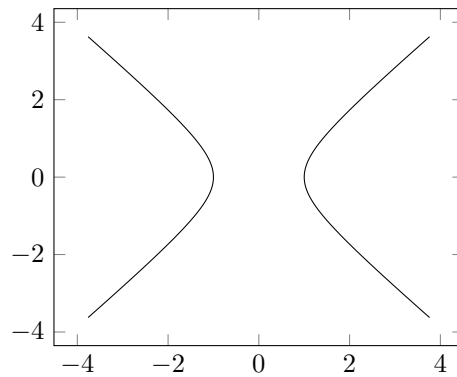


The second, (many-to-one) relation means that for any y-values, there are more than one x-value. An example would be a parabola:

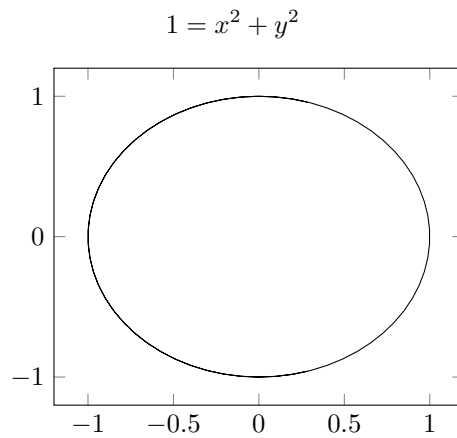
$$f(x) := x^2$$



The previous are examples of functions, the next two are not. The third, (one-to-many) relations means that for any x-value, there are more than one y-value, such as a hyperbola:



And for the last, (many-to-many) relations means that for any x-value, there are more than one y-value, and the reverse is also true, such as a circle:



Chapter 3

Transformations

The ways a function can be transformed by some units are:

$$y = a \times f(b(x - c)) + d$$

Where a is the dilation from the x-axis, b is the dilation from the y-axis, c is the translation along the x-axis, and d is the translation along the y-axis.

3.1 Dilations

A dilation transformation means that the function has been either stretched or compressed. These transformations occur when an output has been multiplied by a dilation factor. Dilations can either occur in the x-axis or the y-axis.

Let $y = f(x)$

When dilated from the x-axis by a :

$$y = a \times f(x)$$

When dilated from the y-axis by b :

$$y = f(x \times b)$$

NOTE:

values less than 1 compresses the function and greater than 1 stretch it

3.2 Reflections

A reflection transformation means that the function has been flipped along an axis.

To reflect a function along the x-axis:

$$y = -f(x)$$

To reflect a function along the y-axis:

$$y = f(-x)$$

3.3 Translations

A translation transformation means that the function has been shifted along an axis.

To move the function along the x-axis by c units:

$$y = f(x - c)$$

To move the function along the y-axis by d units:

$$y = f(x) + d$$

Chapter 4

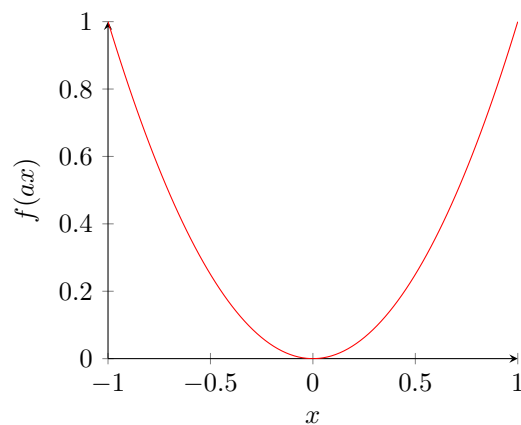
Quadratics

4.1 General or polynomial form

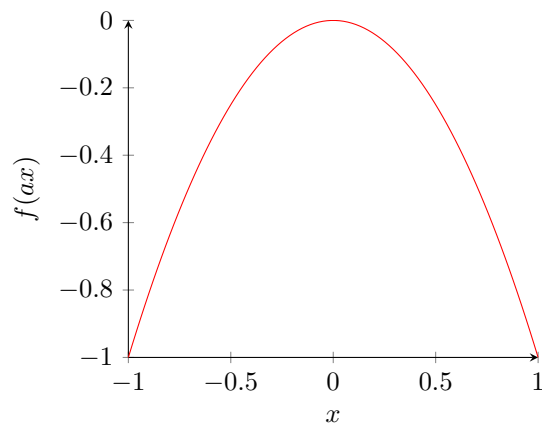
The general or polynomial form of a quadratic is:

$$y = ax^2 + bx + c$$

*NOTE:
if $a > 0$ it looks like:*



And $a < 0$ it looks like:



The axis of symmetry or the turning point is found by:

$$x = -\frac{b}{2a}$$

4.2 Turning point form

The turning point form is:

$$y = a(x - b)^2 + c$$

Where b is the translation along the x-axis and c is the translation along the y-axis.

4.3 Factorized or x-intercept form

The factorized or x-intercept form is:

$$y = a(x - b)(x - c)$$

Where it intercepts the x-axis at points $x = b$ and $x = c$

And the axis of symmetry for this form is:

$$x = \frac{b + c}{2}$$

4.4 The discriminant

The discriminant is:

$$\Delta = b^2 - 4ac$$

From a part of the quadratic equation.

If $\Delta < 0$, the quadratic has no real factors, $\Delta \geq 0$, the quadratic has 2 real factors, and if $\Delta = 0$, the quadratic is a perfect square and has only 1 real factor. The number of x-intercepts is equal to the number of factors.

4.5 Equations from graphs

If given the turning point, use the turning point form and substitute the coordinates into b and c . And if given the x-intercepts, use the x-intercept form and substitute the values b and c . While if given 3 points along the curve, use the general form by:

Given 3 points: $(0, 11), (1, 5), (2, 3)$
Substitute x and y values into general form

$$11 = a(0)^2 + b(0) + c$$

$$5 = a(1)^2 + b(1) + c$$

$$3 = a(2)^2 + b(2) + c$$

Solve for unknowns

$$11 = \cancel{a(0)^2}^0 + \cancel{b(0)}^0 + c$$

$$c = 11$$

$$5 = \cancel{a(1)^2}^a + \cancel{b(1)}^b + c$$

$$5 = a + b + c$$

$$3 = \cancel{a(2)^2}^{4a} + \cancel{b(2)}^{2b} + c$$

$$5 = a + b + 11$$

$$3 = 4a + 2b + 11$$

$$a + b = -6$$

$$4a + 2b = -8$$

$$2 \times (a + b = -6)$$

$$= -2a + -2b = 12$$

Using simultaneous equations:

$$\begin{aligned}(4a + 2b &= -8) \\ +(-2a + -2b &= 12) \\ 2a &= 4 \\ a &= 2\end{aligned}$$

$$\begin{aligned}2 + b &= -6 \\ b &= -8\end{aligned}$$

$$\therefore a = 2, b = -8, c = 11$$

4.6 Solving quadratic equations

4.6.1 Null factor law

The null factor law means that if $A \times B = 0$ at least A or B must equal 0. To use the null factor law to calculate the unknowns, factorize the quadratic:

$$\begin{aligned}\text{If given: } x^2 + 3x - 10 &= 0 \\ ax^2 + bx + c &= \\ \text{Find values which add to } b \text{ and multiply to } c \\ b = 3 = 5 + -2 \text{ and } c = -10 = 5 \times -2 \text{ fit these conditions}\end{aligned}$$

$$\begin{aligned}x^2 + 5x + -2x + -10 &= 0 \\ x(x + 5) + -2(x + 5) &= 0 \\ (x - 2)(x + 5) &= 0 \\ x &= 2, -5\end{aligned}$$

If the leading coefficient is not 1:

$$\begin{aligned}2x^2 + 7x + 3 &= 0 \\ \text{find values which multiply to } a \times c, \text{ and add to } b \\ a \times c = 2 \times 3 = 6, b = 7 + 1 \\ 2x^2 + 1x + 6x + 3 &= 0 \\ x(2x + 1) + 3(2x + 1) &= 0 \\ (x + 3)(2x + 1) &= 0 \\ x &= -3, -\frac{1}{2}\end{aligned}$$

4.6.2 Quadratic equation

To solve using the quadratic equation, substitute a , b , and c of the general form into the equation:

$$x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

4.6.3 Completing the square

To solve using completing the square, rearrange the equation so that it is in the form:

$$x^2 - 2ax + a^2 = (x - a)^2$$

Example:

$$\begin{array}{r}
 10x^2 - 30x - 8 = 0 \\
 \hline
 \frac{10x^2}{2} - \frac{30x}{2} - \frac{8}{2} = 0 \\
 \hline
 5x^2 - 15x - 4 = 0 \\
 \hline
 x^2 - 3x - \frac{4}{5} = 0
 \end{array}$$

Remember: $x^2 - 2ax + a^2$

$$a = \frac{-3}{2}$$

$a^2 = \frac{9}{4}$ (In case you forgot, $\frac{a}{b} \times \frac{c}{d} = \frac{ac}{bd}$)

$$\begin{array}{l}
 x^2 - 3x + \frac{9}{4} = \frac{4}{5} + \frac{9}{4} \\
 x^2 - 3x + \frac{9}{4} = \frac{16}{20} + \frac{45}{20} \\
 x^2 - 3x + \frac{9}{4} = \frac{61}{20}
 \end{array}$$

Remember: $(x - a)^2$

$$\left(x - \frac{3}{2}\right)^2 = \frac{61}{20}$$

$$x - \frac{3}{2} = \pm \sqrt{\frac{61}{20}}$$

$$x = \frac{3}{2} \pm \sqrt{\frac{61}{20}}$$

Chapter 5

Factorizing

5.1 Perfect squares

A perfect square follows the formula:

$$(a + b)^2 = a^2 + 2ab + b^2$$

And

$$(a - b)^2 = a^2 - 2ab + b^2$$

5.2 Difference of squares

A difference of squares follows the formula:

$$a^2 - b^2 = (a + b)(a - b)$$

5.3 Equations that reduce to quadratic form

If given: $ax^4 + bx^2 + c = 0$, x^2 could be substituted for u , therefore: $au^2 + bu + c = 0$ then solve for u .

Chapter 6

Hyperbolas

The basic equation of a hyperbola is:

$$y = \frac{1}{x}$$

The lines $x = 0$ and $y = 0$ are asymptotes, which is a line that the function will approach but never reach.

The general equation of a hyperbola is:

$$y = \frac{a}{x - c} + d$$

Where c is the vertical asymptote, d is the horizontal asymptote, and a is the dilation factor.

6.1 Transformations

6.1.1 Dilation

A dilation transformation of a hyperbola is:

$$y = \frac{a}{x}$$

Where a is the dilation factor.

6.1.2 Translations

To translate the hyperbola in the y-axis:

$$y = \frac{1}{x} + d$$

Where b is the translation along the y-axis.

To translate the hyperbola in the x-axis:

$$y = \frac{1}{x - c}$$

Where c is the translation along the x-axis.

To reflect the hyperbola it is:

$$y = -\frac{1}{x}$$

6.2 Inverse proportion

An inversely proportional graph follows a hyperbolic relationship and is represented as:

$$y = \frac{k}{x}$$

Where k is the constant of proportionality.

Chapter 7

Circles

Circles are a relation as opposed to a function as it fails the vertical line test, and the equation of a circle is:

$$(x - a)^2 + (y - b)^2 = r^2$$

Where a is the x-component of the centre point, b is the y-component, and r is the radius.

The general form of a circle is the expanded form of the above, and is:

$$x^2 + y^2 - 2ax - 2by + a^2 + b^2 - r^2 = 0$$

Chapter 8

Polynomials

Polynomials are an algebraic expression with a positive integer power, such as:

$$\begin{aligned} &2x^2 - 7x + 2, \\ &12x^4 + 2x^3 - 16x^2 + x + 8 \\ &\text{or} \\ &3x^3 + 4 \end{aligned}$$

The degree of a polynomial is the highest power, as an example, the above would be a 2nd degree, 4th degree, and 3rd degree polynomials. The leading term is the term containing the highest power, again: $2x^2$, $12x^4$, and $3x^3$. And the constant term is the term that does not contain a variable: 2, 8, and 4. Polynomials are often shown in function notation:

$$P(x) := 2x^3 + 5x - 6$$

8.1 Division

To divide polynomials by hand, use the long division method shown here:

$$\begin{array}{r} x^2 - 9x - 27 \\ x - 3 \overline{) x^3 - 12x^2 - 42} \\ \underline{-x^3 + 3x^2} \\ -9x^2 \\ \underline{9x^2 - 27x} \\ -27x - 42 \\ \underline{27x - 81} \\ -123 \end{array}$$

The product of the division would be in the form:

$$\frac{\text{dividend}}{\text{divisor}} = \text{quotient} + \frac{\text{remainder}}{\text{divisor}}$$

As an overview of what the terms mean:

Term	Meaning
Dividend	The number being divided
Divisor	Dividing by
Quotient	How many times the divisor can go into the dividend
Remainder	After you divide, how much is left over

8.2 Remainder theorem

The remainder theorem is:

If a polynomial $P(x)$ is divided by $(x - a)$, then the remainder is $P(a)$.
 And If a polynomial $P(x)$ is divided by $(ax - b)$, then the remainder is $P(-\frac{b}{a})$.

To derive this theorem, consider:

$$\frac{P(x)}{x-a} = \text{quotient} + \frac{\text{remainder}}{x-a}$$

$$\frac{P(x)}{\cancel{x-a}} \times \cancel{(x-a)} \rightarrow P(x) \quad \frac{(x-a) \times \text{quotient}}{\cancel{x-a}} \times \cancel{(x-a)} \rightarrow \text{remainder}$$

$$\frac{P(x)}{\cancel{x-a}} \times \cancel{(x-a)} = \text{quotient} \times \cancel{(x-a)} + \frac{\text{remainder}}{\cancel{x-a}} \times \cancel{(x-a)}$$

If we let $x = a$:

$$P(a) = 0 \times \text{quotient} + \text{remainder}$$

$$P(a) = \text{remainder}$$

8.3 Factor theorem

A factor of a value means that when the dividend is divided by the divisor, if the result does not produce a remainder, the divisor is a factor of the dividend. As an example:

We know that 4 is a factor of 12 because it divides 12 exactly into 3 with no remainders, likewise, if $\frac{P(x)}{x-a}$ leaves no remainder, it is a factor of the polynomial:

$$P(x) = (x-a) \times \text{quotient}$$

Or:

If $P(x)$ is a polynomial and $P(a) = 0$ then $(x-a)$ is a factor of $P(x)$
 And if $P(x)$ is a polynomial and $P(-\frac{b}{a}) = 0$ then $(ax-b)$ is a factor of $P(x)$

8.4 Factorizing polynomials

To factorize a polynomial as a product of linear factors using polynomial division, divide the polynomial by the given factor to get a polynomial of a smaller degree, and factorize the quadratic.

Let $P(x) = 4x^3 + 19x^2 + 19x + 6$, and a known factor of $(x+2)$

$$\frac{4x^3 + 19x^2 + 19x + 6}{(x+2)} = 4x^2 + 11x - 3$$

$$P(x) = (x+2)(4x^2 + 11x - 3)$$

(factorize $4x^2 + 11x - 3$)

$$4x^2 + 11x - 3 = (x+3)(4x-1)$$

$$\therefore P(x) = (x+2)(x+3)(4x-1)$$

NOTE:

if there is a missing factor such as: $ax^3 + cx + d$, just insert a bx^2 factor with $b = 0$

Chapter 9

Probabilities

9.1 Terms

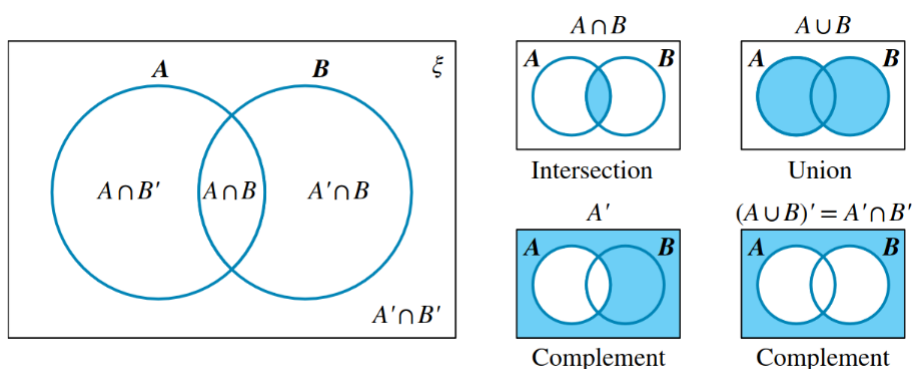
The key terms of probability are:

Name	Meaning
Trial	a result from something happening
Outcome	a result of a trial
Sample space: \mathcal{E}	the set of all outcomes: $\mathcal{E} = \{1, 2, 3, 4, 5\}$
Event	an outcome that we are looking for
Probability	the relative frequency of an event from the set of all outcomes. Probabilities begin at 0 and end at 1, 0 being impossible and 1 being certain.

NOTE:

in a deck of cards, there are 52 cards, there are 4 suits of a heart or a diamond (which are red), and clubs and spades (which are black). These suits all have an ace, 2, 3, 4 ... 10, a jack, a queen, and a king

9.2 Venn diagrams



9.3 Addition

To add probabilities, use the formula:

$$P(A \cup B) = P(A) + P(B) - P(A \cap B)$$

NOTE:

if the events A and B are mutually exclusive, i.e. if A occurs, B cannot possibly happen and vice versa, the addition formula becomes: $P(A \cup B) = P(A) + P(B)$

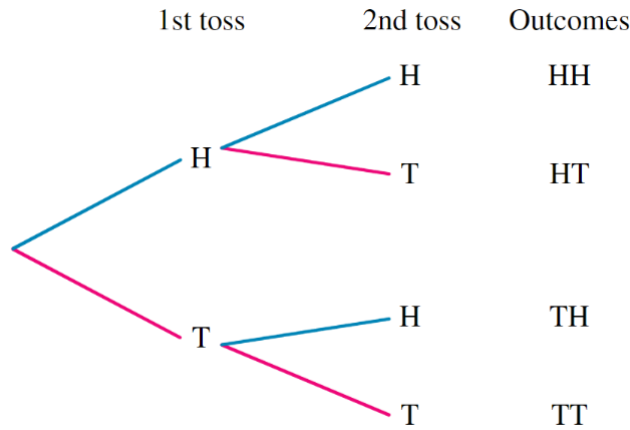
9.4 Probability tables

Probability tables are a way to represent Venn diagrams in a different format.

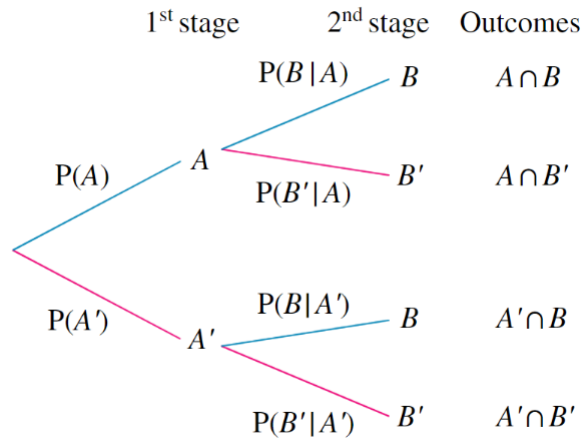
	B	B'	sum
A	$P(A \cap B)$	$P(A \cap B')$	$P(A)$
A'	$P(A' \cap B)$	$P(A' \cap B')$	$P(A')$
sum	$P(B)$	$P(B')$	$P(\mathcal{E})$

9.5 Tree diagrams

Tree diagrams are used to show the tree of possible outcomes after each trial, as in, if a coin is flipped, it can either be heads or tails, and then a next trial, which could also be heads or tails:



Tree diagrams can also be used to calculate probability by multiplying along the branch:



9.6 Conditional probability

The notation of writing conditional probability is:

$$P(A|B)$$

Where it means that the probability of A given that $(|)$ B has occurred.

To calculate the probability of an event, divide the sum of the events occurred over the sum of the sample space:

$$P(A) = \frac{n(A)}{n(\mathcal{E})}$$

And

$$P(A \cap B) = \frac{n(A \cap B)}{N(\mathcal{E})}$$

Similarly, to calculate the probability of an event given another event, change the sum of the sample space to be the sum of the first event:

$$\begin{aligned} P(A|B) &= \frac{n(A \cap B)}{n(B)} \\ &= n(A \cap B)/n(B) \\ &= \frac{n(A \cap B)}{n(\mathcal{E})} / \frac{n(B)}{n(\mathcal{E})} \\ &= P(A \cap B)/P(B) \\ P(A|B) &= \frac{P(A \cap B)}{P(B)} \end{aligned}$$

9.7 Multiplication

By rearranging the conditional probability formula, the \cap probability formula can be found:

$$P(A \cap B) = P(A) \times P(B|A)$$

9.8 Independence

An independent event is a event which does not change on another event occurring. Independent events pass these tests:

$$\begin{aligned} P(A|B) &= P(A) \\ P(A \cap B) &= P(A) \times P(B) \end{aligned}$$

9.9 Addition principle

If there are n ways of performing operation A , and m ways of performing operation B , there are $n + m$ ways of performing operation $A \cup B$.

As in, let there be 2 ways to perform task A , and 3 ways to perform task B . If there is an option to perform A or B , there is a total of $2 + 3 = 5$ ways to perform an operation.

9.10 Multiplication principle

If there are n ways of performing operation A , and m ways of performing operation B , there are $n \times m$ ways of performing operation $A \cup B$.

As in, let there be 4 ways to perform task A , and 5 ways to perform task B . With considering 1 way to perform A , there are 5 ways to perform B , repeat the process through the number of ways to perform A .

	$B, 1$	$B, 2$	$B, 3$	$B, 4$	$B, 5$
$A, 1$	(1, 1)	(1, 2)	(1, 3)	(1, 4)	(1, 5)
$A, 2$	(2, 1)	(2, 2)	(2, 3)	(2, 4)	(2, 5)
$A, 3$	(3, 1)	(3, 2)	(3, 3)	(3, 4)	(3, 5)
$A, 4$	(4, 1)	(4, 2)	(4, 3)	(4, 4)	(4, 5)

Where there are $4 \times 5 = 20$ ways to perform the operations.

Chapter 10

Factorials

Factorials is the result of multiplying all of the integers between the given integer and 1. This is given the notation and formula:

$$n! = n \times (n - 1) \times (n - 2) \times (n - 3) \dots \times 3 \times 2 \times 1$$

Example:

$$\begin{aligned} 5! &= 5 \times 4 \times 3 \times 2 \times 1 \\ &= 120 \end{aligned}$$

10.1 Dividing factorials

When given some factorial over another factorial in such cases as:

$$\begin{aligned} &\frac{4!}{2!} \\ &\frac{4 \times 3 \times 2 \times 1}{2 \times 1} \\ &\frac{4 \times 3 \times \cancel{2 \times 1}}{\cancel{2 \times 1}} \\ &4 \times 3 \\ &12 \end{aligned}$$

10.2 Special cases

$$0! = 1$$

Chapter 11

Permutations

Permutations is the number of ways of choosing r things from n distinct things where *order matters*. This is given the notation and formula:

$${}_nP_r = \frac{n!}{(n-r)!}$$

Example:

$$\begin{aligned} {}^6P_4 &= \frac{6!}{(6-4)!} \\ &= \frac{6!}{2!} \\ &= \frac{6 \times 5 \times 4 \times 3 \times 2 \times 1}{2 \times 1} \\ &= \frac{6 \times 5 \times 4 \times 3 \times \cancel{2} \times \cancel{1}}{\cancel{2} \times \cancel{1}} \\ &= 6 \times 5 \times 4 \times 3 \\ &= 360 \end{aligned}$$

11.1 Permutations in a circle

In cases where the positions being concerned is a circle such as the permutations of a circular seating arrangement, if the standard permutations formula is applied, there are several over-counting of the like arrangement in a different perspective. In these cases apply the formula:

$$\frac{{}_nP_r}{r} = \frac{\frac{n!}{(n-r)!}}{r}$$

11.2 Like objects repetitions

The number of ways of arranging n objects made up of indistinguishable objects, n_1 in the first group, n_2 in the second group and so on, is:

$$\frac{n!}{n_1!n_2!n_3!\dots n_r!}$$

Example:

Find the number of permutations of the letters in the word WOOLLOOMOOLOO.

There are 8 'O's and 3 'L's

Permutations:

$$\frac{13!}{8!3!}$$

$$\frac{13 \times 12 \times 11 \times 10 \times 9 \times 8 \times 7 \times 6 \times 5 \times 4 \times 3 \times 2 \times 1}{(8 \times 7 \times 6 \times 5 \times 4 \times 3 \times 2 \times 1) \times (3 \times 2 \times 1)}$$

$$\begin{array}{r}
13 \times 12 \times 11 \times 10 \times 9 \times 8 \times 7 \times 6 \times 5 \times 4 \times 3 \times 2 \times 1 \\
\hline
(8 \times 7 \times 6 \times 5 \times 4 \times 3 \times 2 \times 1) \times (3 \times 2 \times 1) \\
\hline
13 \times 12 \times 11 \times 10 \times 9 \\
\hline
3 \times 2 \\
\hline
13 \times \cancel{12}^{6 \times 2} \times 11 \times 10 \times \cancel{9}^{3 \times 3} \\
\hline
3 \times 2 \\
\hline
13 \times 6 \times 11 \times 10 \times 3 \\
\hline
25,740
\end{array}$$

11.3 Restrictions

When considering restrictions, deal with the restrictions first. Example:

Find the number of arrangements of the letters of the word DARWIN beginning and ending with a vowel.
 Number of letters = 6 Number of positions = 6 Beginning and end must be a vowel, so the available positions are decreased by 2: number of positions - 2 = 4 Since 2 vowels must be used: number of letters - 2 = 4
 Permutations:

$$\begin{array}{c}
{}^4P_4 \\
4! \\
4 \times 3 \times 2 \times 1 \\
24
\end{array}$$

11.4 Grouped items

When items are grouped together, treat each group as a single object. Find the number of arrangements of the groups, then multiply by the number of arrangement within each group. Example:

Find the number of arrangement of the letters of the word EQUALS if the vowels are kept together. Number of vowels = 3 Number of letters = 6 Number of positions = 6 As the 3 vowels are grouped together, the number of positions decreases: number of positions - 3_{for the members of the group} + 1_{for the group} = 4
 Permutations within vowel group:

$${}^3P_3 = 3! = 3 \times 2 = 6$$

Permutations of all positions:

$${}^4P_4 = 4! = 4 \times 3 \times 2 = 24$$

Multiply together:

$$6 \times 24 = 144$$

11.5 Special cases

$${}^nP_n = n!$$

$${}^nP_0 = 1$$

Chapter 12

Combinations

Combinations is the number of ways of choosing or selecting r objects from n distinct objects where *order does not matter*. This is given the notation and formula:

$${}^nC_r = \frac{{}^nP_r}{r!}$$

$${}^nC_r = \frac{\frac{n!}{(n-r)!}}{r!}$$

Or

$$\binom{n}{r}$$

Example:

$$\begin{aligned} {}^4C_2 &= \frac{{}^4P_2}{2!} \\ &= \frac{\frac{4!}{(4-2)!}}{2!} \\ &= \frac{\frac{4!}{2!}}{2!} \\ &= \frac{\frac{4 \times 3 \times 2}{2}}{2} \\ &= \frac{\cancel{4} \times 3 \times \cancel{2}}{2} \\ &= \frac{4 \times 3}{2} \\ &= \frac{12}{2} \\ &= 6 \end{aligned}$$

12.1 Pascal's triangle

The Pascal's triangle is a pattern formed by adding the top 2 adjacent numbers and a 1 is placed on either side of the bottom row to resemble a triangle:

Chapter 13

Index laws

Name	Meaning
Multiplication	$a^m \times a^n = a^{m+n}$
Division	$\frac{a^m}{a^n} = a^{m-n}$
Raising to a power	$(a^n)^m = a^{n \times m}$
To the power of zero	$a^0 = 1$
Negative indices	$a^{-n} = \frac{1}{a^n}, a \neq 0$
Fractional indices	$a^{\frac{m}{n}} = (\sqrt[n]{a})^m = \sqrt[n]{a^m}$

Chapter 14

Exponential functions

An exponential function increases or decreases at an accelerating rate, they have an asymptote, a line which it approaches but never reach, and intersect the y-axis at point $(0, 1)$. The general form of an exponential function equation is:

$$y = a^x$$

Where positive a values increases exponentially, and negative a approaches the asymptote as the x-value increases.

14.1 Translations

14.1.1 x-axis

To translate the exponential function along the x-axis, use the formula:

$$y = a^{x-c}$$

Where c is the translation along the x-axis.

14.1.2 y-axis

To translate the exponential function along the y-axis, use the formula:

$$y = a^x + d$$

Where d is the translation along the y-axis.

14.2 Dilations

14.2.1 x-axis

To dilate the exponential function from the x-axis, use the formula:

$$y = b \times a^x$$

Where b is the dilation factor from the y-axis. This dilation affects the y-intercept, but the asymptote stays at $y = 0$

14.2.2 y-axis

To dilate the exponential function from the y-axis, use the formula:

$$y = a^{kx}$$

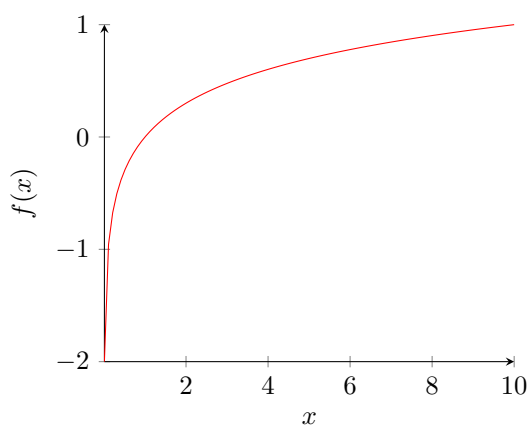
Where k is the dilation factor from the y-axis. This dilation affects the steepness of the graph, but does not affect the y-intercept or the asymptote.

Chapter 15

Logarithms

A logarithm is defined as:

$$(y = a^x) = (x = \log_a y)$$



Where y is the base numeral, a is the base, and x is the logarithm for $a > 0$ and $a \neq 1$.

15.1 Laws

Name	Rule	Restrictions
Logarithms of a product	$\log_a(mn) = \log_a m + \log_a n$	$[m, n > 0], [a > 0], [a \neq 1]$
Logarithms of a quotient	$\log_a\left(\frac{m}{n}\right) = \log_a m - \log_a n$	$[m, n > 0], [a > 0], [a \neq 1]$
Logarithms of a power	$\log_a m^n = n \log_a m$	$[m > 0], [a > 0], [a \neq 1]$
Logarithms of the base	$\log_a a = 1$	$[a > 0], [a \neq 1]$
Logarithm of one	$\log_a 1 = 0$	$[a > 0], [a \neq 1]$

15.2 The change of base theorem

To change the base, apply the formula:

$$\log_a(x) = \frac{\log_b(x)}{\log_b(a)}$$

As an example:

$$\begin{aligned} \log_5 25 &= \frac{\log_{10} 25}{\log_{10} 5} = \frac{1.39794}{0.69897} \approx 2 \\ \log_2 8 &= \frac{\ln 8}{\ln 2} = \frac{2.07944}{0.69315} \approx 3 \\ \log_3 81 &= \frac{\log_{10} 81}{\log_{10} 3} = \frac{1.90849}{0.47712} \approx 4 \end{aligned}$$

Chapter 16

Trigonometry

16.1 Radians and Degrees

Radians and degrees are two units used to measure angles. One radian is defined as the angle formed when the length of an arc on a circle is equal to the radius of the circle. There are 2π radians in a full circle, where π is approximately equal to 3.14159.

Degrees, on the other hand, are based on the idea that a full circle contains 360° . This means that one degree is equal to $\frac{1}{360}$ of a full circle.

16.2 Converting between radians and degrees

To convert between radians and degrees, we can use the following relationships:

$$1^c = \left(\frac{180}{\pi}\right)^\circ$$

and

$$1^\circ = \left(\frac{\pi}{180}\right)^c$$

To convert 45° to radians, use the second relationship:

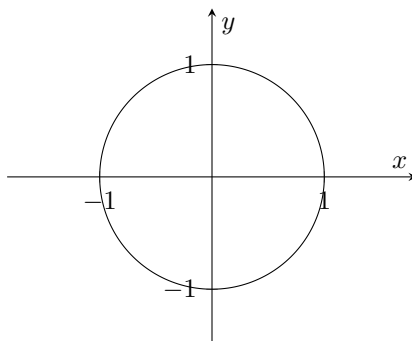
$$\begin{aligned} 45^\circ &= 45 \cdot \left(\frac{\pi}{180}\right)^c \\ &= \frac{1}{4}\pi^c \end{aligned}$$

To convert $\frac{1}{3}\pi$ radians to degrees, use the first relationship:

$$\begin{aligned} \frac{1}{3}\pi^c &= \frac{1}{3}\pi \cdot \left(\frac{180}{\pi}\right)^\circ \\ &= 60^\circ \end{aligned}$$

16.3 The unit circle

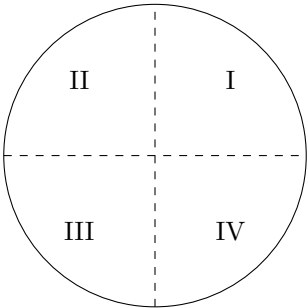
The unit circle is a circle with the centre point at origin, and has a radius of 1:



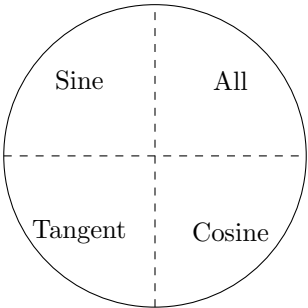
The equation of this circle is $x^2 + y^2 = 1$.

16.4 Quadrants

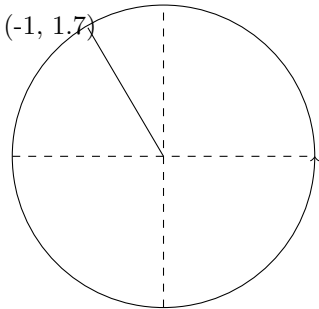
The four sections of a circle is separated into quadrants, the top right being the first quadrant, the top left being the second, the bottom left being the third, and the bottom right being the fourth.



In the first quadrant, the value of all trigonometric functions are positive, however, in the second quadrant, only the sine is, and in the third, only the tangent, and in the fourth, only the cosine.



This is true as sine is the y-axis value of the point along the unit circle which is intersected by the angle:

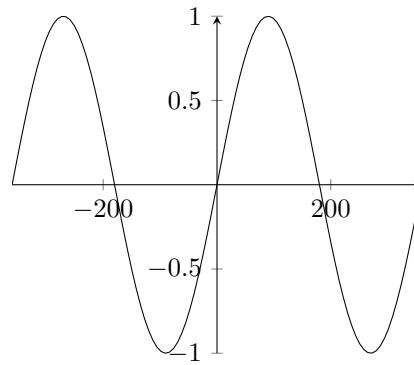


16.5 Exact values

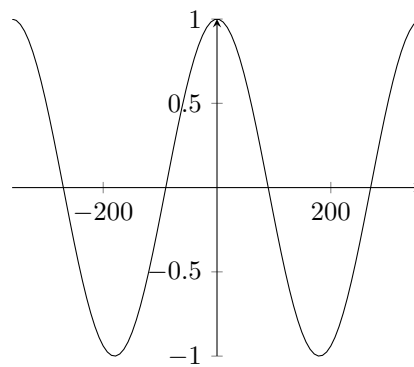
The exact values are as follows:

Angles (θ)		$\sin(\theta)$	$\cos(\theta)$	$\tan(\theta)$
Degrees ($^{\circ}$)	Radians ($^{\circ}$)			
0	0	0	1	0
30	$\frac{1}{6}\pi$	$\frac{1}{2}$	$\frac{\sqrt{3}}{2}$	$\frac{1}{\sqrt{3}}$
45	$\frac{1}{4}\pi$	$\frac{1}{\sqrt{2}}$	$\frac{1}{\sqrt{2}}$	1
60	$\frac{1}{3}\pi$	$\frac{\sqrt{3}}{2}$	$\frac{1}{2}$	$\sqrt{3}$
90	$\frac{1}{2}\pi$	1	0	n.a.

16.6 Sine



16.7 Cosine



16.8 Transformations

16.8.1 Amplitude

16.8.2 Period

16.8.3 Equilibrium

16.8.4 Phase

Chapter 17

Derivatives

17.1 Rate of change

17.1.1 Constant

17.1.2 Average

17.1.3 Instantaneous

17.2 Limits

17.3 First principles

17.4 Derivatives

17.4.1 Velocity and acceleration

17.4.2 Stationary points

17.4.3 Product rule

17.4.4 Chain rule

17.4.5 Quotient rule

17.4.6 Power rule

Chapter 18

Probability distributions

18.1 Variables

18.2 Calculating probability distributions

18.3 Expected values

18.4 Standard distribution

18.5 Variance